HEF4013B-Q100

Dual D-type flip-flop Rev. 2 — 20 February 2013

Product data sheet

General description 1.

The HEF4013B-Q100 is a dual D-type flip-flop that features independent set-direct input (SD), clear-direct input (CD), clock input (CP) and outputs (Q, Q). Data is accepted when CP is LOW and is transferred to the output on the positive-going edge of the clock. The active HIGH asynchronous CD and SD inputs are independent and override the D or CP inputs. The outputs are buffered for best system performance. The Schmitt trigger action of the clock inputs, makes the circuit highly tolerant of slower clock rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Connect unused inputs to V_{DD}, V_{SS}, or another input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

Features and benefits 2.

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
 - ◆ Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
 - MIL-STD-883, method 3015 exceeds 2000 V
 - HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Complies with JEDEC standard JESD 13-B

3. **Applications**

- Counters and dividers
- Registers
- Toggle flip-flops



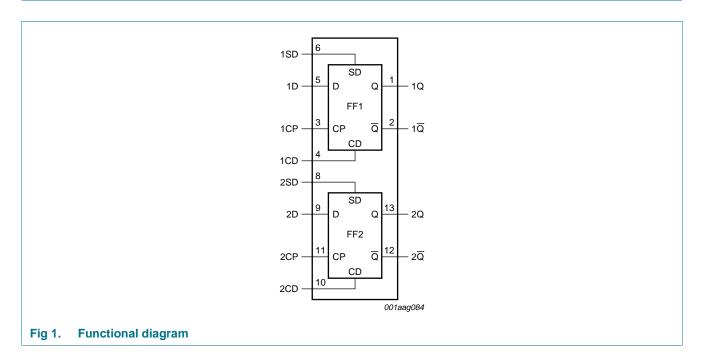
4. Ordering information

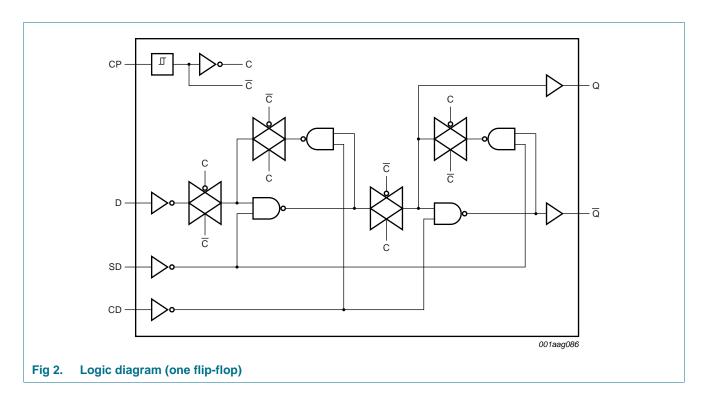
Table 1. Ordering information

All types operate from −40 °C to +125 °C

Type number	Package							
	Name	Description	Version					
HEF4013BP-Q100	DIP14	plastic dual in-line package; 14 leads (300 mil)	SOT27-1					
HEF4013BT-Q100	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1					
HEF4013BTT-Q100	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1					

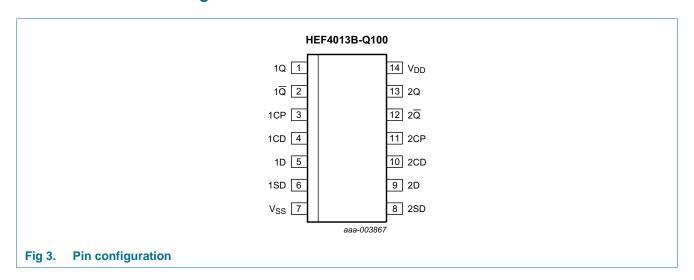
5. Functional diagram





6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description	
1Q, 2Q	1, 13	true output	
1 Q , 2 Q	2, 12	complement output	
1CP, 2CP	3, 11	clock input (LOW to HIGH edge-triggered)	
HEF4013B_Q100		All information provided in this document is subject to legal disclaimers.	© NXP B.V. 2013. All rights reserved.

Table 2. Pin description ...continued

Symbol	Pin	Description
1CD, 2CD	4, 10	asynchronous clear-direct input (active HIGH)
1D, 2D	5, 9	data input
1SD, 2SD	6, 8	asynchronous set-direct input (active HIGH)
V_{SS}	7	ground (0 V)
V_{DD}	14	supply voltage

7. Functional description

Table 3. Function table[1]

Control			Input	Output	
nSD	nCD	nCP	nD	nQ	nQ
Н	L	X	X	Н	L
L	Н	X	X	L	Н
Н	Н	X	X	Н	Н
L	L	↑	L	L	Н
L	L	↑	Н	Н	L

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; ↑ = LOW-to-HIGH clock transition.

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to $V_{SS} = 0 \text{ V}$ (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	$V_{DD} + 0.5$	V
I _{OK}	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}$			
		DIP14	[1] -	750	mW
		SO14	[2] _	500	mW
		TSSOP14	[3] _	500	mW
Р	power dissipation	per output	-	100	mW

^[1] For DIP14 packages: above T_{amb} = 70 °C, P_{tot} derates linearly with 12 mW/K.

^[2] For SO14 packages: above T_{amb} = 70 °C, P_{tot} derates linearly with 8 mW/K.

^[3] For TSSOP14 packages: above $T_{amb} = 60 \, ^{\circ}\text{C}$, P_{tot} derates linearly with 5.5 mW/K.

9. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		3	15	V
VI	input voltage		0	V_{DD}	V
T _{amb}	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{DD} = 5 V$	-	3.75	μs/V
		V _{DD} = 10 V	-	0.5	μs/V
		V _{DD} = 15 V	-	0.08	μs/V

10. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} ; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	–40 °C	T _{amb} =	+25 °C	T _{amb} =	+85 °C	T _{amb} = -	⊦125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V_{IH}	HIGH-level	$ I_{O} < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V_{IL}	LOW-level	$ I_O < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V_{OH}	HIGH-level	$ I_O < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V_{OL}	LOW-level	$ I_O < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level	$V_0 = 2.5 \text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mΑ
	output current	$V_{O} = 4.6 \text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mΑ
		$V_0 = 9.5 \text{ V}$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mΑ
		$V_0 = 13.5 \text{ V}$	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mΑ
I _{OL}	LOW-level	$V_0 = 0.4 \text{ V}$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mΑ
	output current	$V_0 = 0.5 \text{ V}$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mΑ
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mΑ
I _I	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I _{DD}	supply current	all valid input	5 V	-	1.0	-	1.0	-	30	-	30	μΑ
		combinations;	10 V	-	2.0	-	2.0	-	60	-	60	μΑ
		$ I_O = 0 A$	15 V	-	4.0	-	4.0	-	120	-	120	μΑ
C _I	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

11. Dynamic characteristics

Table 7. Dynamic characteristics

 $T_{amb} = 25$ °C; unless otherwise specified. For test circuit see <u>Figure 6</u>.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
=	HIGH to LOW	nCP to nQ, $n\overline{Q}$;	5 V	[1] $83 + 0.55 \times C_L$	-	110	220	ns
	propagation delay	see Figure 4	10 V	$34 + 0.23 \times C_L$	-	45	90	ns
			15 V	$22 + 0.16 \times C_{L}$	-	30	60	ns
		nSD to nQ	5 V	11 73 + $0.55 \times C_L$	-	100	200	ns
			10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_{L}$	-	30	60	ns
		nCD to nQ	5 V	11 73 + 0.55 × C _L	-	100	200	ns
			10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
t _{PLH}	LOW to HIGH	nCP to nQ, $n\overline{Q}$;	5 V	11 68 + 0.55 × C _L	-	95	190	ns
	propagation delay	see Figure 4	10 V	$29 + 0.23 \times C_L$	-	40	80	ns
			15 V	$22 + 0.16 \times C_L$	-	30	60	ns
		nSD to nQ	5 V	[1] 48 + 0.55 × C _L	-	75	150	ns
			10 V	$24 + 0.23 \times C_L$	-	35	70	ns
			15 V	17 + 0.16 × C _L	-	25	50	ns
		nCD to nQ	5 V	[1] 33 + 0.55 × C _L	-	60	120	ns
			10 V	19 + 0.23 × C _L	-	30	60	ns
			15 V	12 + 0.16 × C _L	-	20	40	ns
t _t	transition time	see Figure 4	5 V	[1] 10 + 1.00 × C _L	-	60	120	ns
			10 V	9 + 0.42 × C _L	-	30	60	ns
			15 V	$6 + 0.28 \times C_L$	-	20	40	ns
t _{su}	set-up time	nD to nCP;	5 V		40	20	-	ns
		see Figure 4	10 V		25	10	-	ns
			15 V		15	5	-	ns
t _h	hold time	nD to nCP;	5 V		20	0	-	ns
		see Figure 4	10 V		20	0	-	ns
			15 V		15	0	-	ns
t _W	pulse width	nCP input LOW;	5 V		60	30	-	ns
		see Figure 4	10 V		30	15	-	ns
			15 V		20	10	-	ns
		nSD input HIGH;	5 V		50	25	-	ns
		see Figure 5	10 V		24	12	-	ns
			15 V		20	10	-	ns
		nCD input HIGH;	5 V		50	25	-	ns
		see Figure 5	10 V		24	12	-	ns
			15 V		20	10	-	ns

Table 7. Dynamic characteristics ... continued

 $T_{amb} = 25$ °C; unless otherwise specified. For test circuit see <u>Figure 6</u>.

Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
recovery time	nSD input;	5 V		+15	-5	-	ns
	see <u>Figure 5</u>	10 V		15	0	-	ns
		15 V		15	0	-	ns
	nCD input; see <u>Figure 5</u>	5 V		40	25	-	ns
		10 V		25	10	-	ns
		15 V		25	10	-	ns
maximum clock	requency 10	5 V		7	14	-	MHz
frequency		10 V		14	28	-	MHz
		15 V		20	40	-	MHz
	recovery time	recovery time nSD input; see Figure 5 nCD input; see Figure 5 maximum clock see Figure 4	recovery time $ \begin{array}{c} \text{nSD input;} \\ \text{see } \underline{\text{Figure 5}} \\ \hline 10 \text{ V} \\ \hline 15 \text{ V} \\ \hline \text{nCD input;} \\ \text{see } \underline{\text{Figure 5}} \\ \hline 10 \text{ V} \\ \hline 15 \text{ V} \\ \hline \\ \text{maximum clock} \\ \text{frequency} \\ \end{array} $	recovery time $ \begin{array}{c} \text{nSD input;} \\ \text{see } \overline{\text{Figure 5}} \\ \hline \\ \text{nCD input;} \\ \text{see } \overline{\text{Figure 5}} \\ \hline \\ \text{nCD input;} \\ \text{see } \overline{\text{Figure 5}} \\ \hline \\ \text{10 V} \\ \hline \\ \text{15 V} \\ \hline \\ \text{maximum clock} \\ \text{frequency} \end{array} $ see $ \overline{\text{Figure 4}} \\ \hline \\ \text{frequency} \\ \hline $	recovery time $ \begin{array}{c} \text{nSD input;} \\ \text{see } \overline{\text{Figure 5}} \\ \hline 10 \text{ V} \\ \hline 15 \text{ V} \\ \hline 25 \text{ Input;} \\ \hline 10 \text{ V} \\ \hline 25 \text{ Input;} \\ \hline 10 \text{ V} \\ \hline 25 \text{ Input;} \\ \hline 10 \text{ V} \\ \hline 25 \text{ Input;} \\ \hline 10 \text{ V} \\ $	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

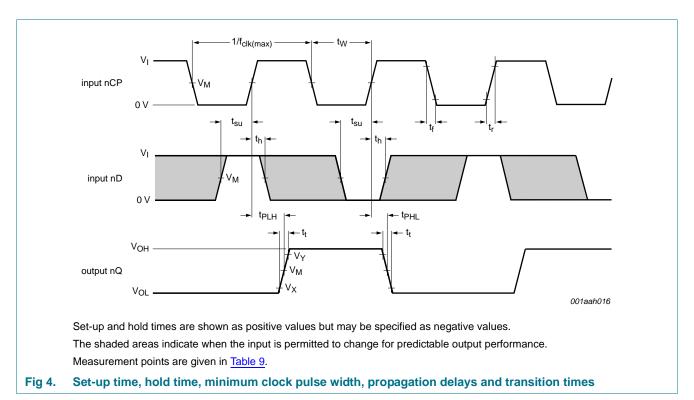
^[1] Typical values of the propagation delays and output transition times can be calculated with the extrapolation formulas. C_L is given in pF.

Table 8. Dynamic power dissipation

 $V_{SS} = 0 \ V; \ t_r = t_f \le 20 \ ns; \ T_{amb} = 25 \ ^{\circ}C.$

-	· · · · · · · · · · · · · · · · · · · ·			
Symbol	Parameter	V_{DD}	Typical formula	Where
P_D	dynamic power dissipation	5 V	$P_D = 850 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 \ \mu W$	f_i = input frequency in MHz;
		10 V	$P_D = 3600 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 \mu W$	fo = output frequency in MHz;
		15 V	$P_D = 9000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 \mu W$	C_L = output load capacitance in pF;
				$\Sigma(f_0 \times C_L)$ = sum of the outputs;
				V _{DD} = supply voltage in V.

12. Waveforms



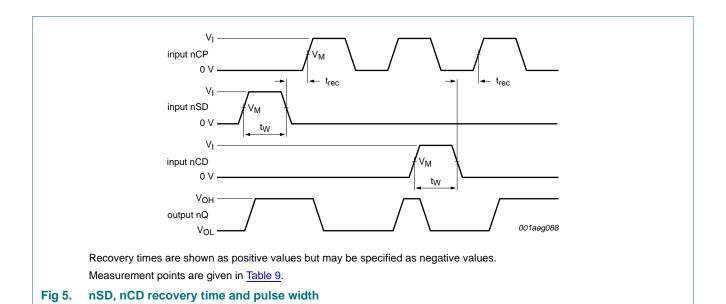
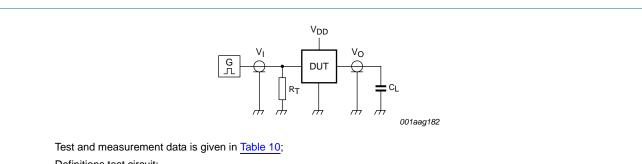


Table 9. **Measurement points**

Supply voltage	Input	Output		
V_{DD}	V _M	V _M	V _X	V _Y
5 V to 15 V	0.5V _{DD}	0.5V _{DD}	0.1V _{DD}	0.9V _{DD}



Definitions test circuit:

DUT = Device Under Test.

 R_T = Termination resistance should be equal to output impedance Z_o of the pulse generator.

 C_L = Load capacitance including jig and probe capacitance.

Test circuit for measuring switching times Fig 6.

Table 10. Test data

Supply voltage	Input	Load	
V_{DD}	VI	C _L	
5 V to 15 V	V _{SS} or V _{DD}	≤ 20 ns	50 pF

13. Application information

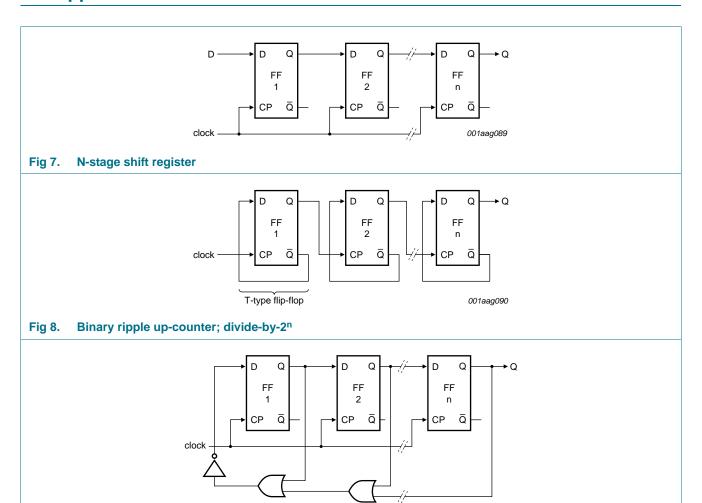


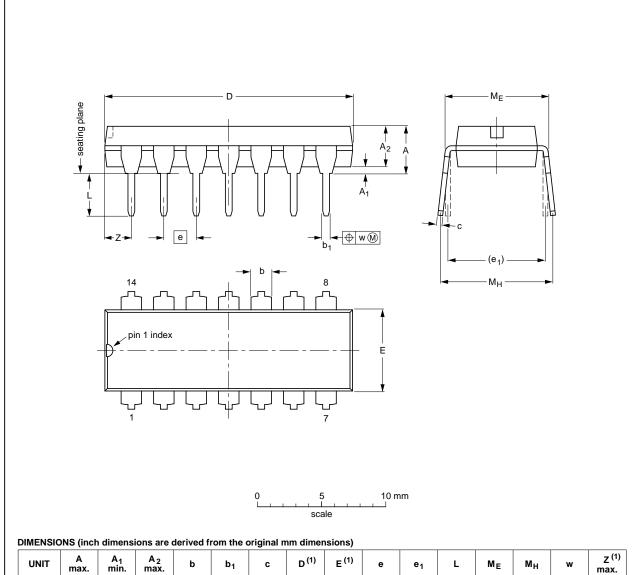
Fig 9.

Modified ring counter; divide-by-(n + 1)

14. Package outline

DIP14: plastic dual in-line package; 14 leads (300 mil)

SOT27-1



UNIT	A max.	A ₁ min.	A ₂ max.	b	b ₁	С	D ⁽¹⁾	E ⁽¹⁾	е	e ₁	L	ME	M _H	w	Z ⁽¹⁾ max.
mm	4.2	0.51	3.2	1.73 1.13	0.53 0.38	0.36 0.23	19.50 18.55	6.48 6.20	2.54	7.62	3.60 3.05	8.25 7.80	10.0 8.3	0.254	2.2
inches	0.17	0.02	0.13	0.068 0.044	0.021 0.015	0.014 0.009	0.77 0.73	0.26 0.24	0.1	0.3	0.14 0.12	0.32 0.31	0.39 0.33	0.01	0.087

Note

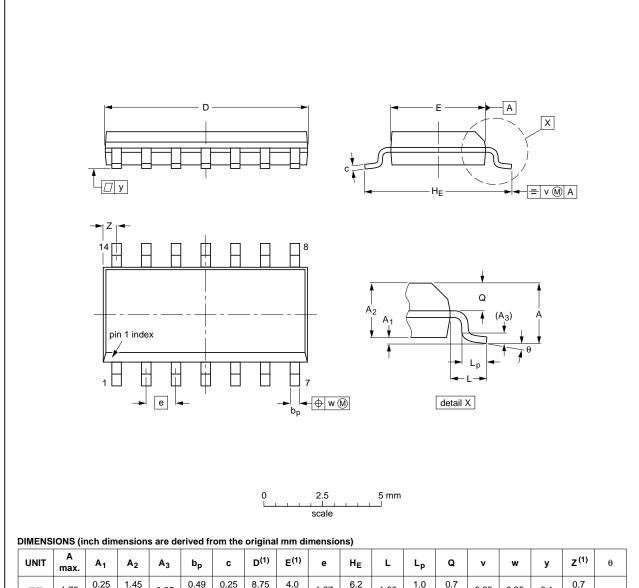
1. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT27-1	050G04	MO-001	SC-501-14			99-12-27 03-02-13	

Fig 10. Package outline SOT27-1 (DIP14)

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1



UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽¹⁾	е	HE	L	Lp	Q	v	w	у	z ⁽¹⁾	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	8.75 8.55	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.35 0.34	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	0°

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

	REFER	EUROPEAN	ISSUE DATE			
IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
076E06	MS-012				99-12-27 03-02-19	
_	-	IEC JEDEC		IEC JEDEC JEITA	IEC JEDEC JEITA PROJECTION	

Fig 11. Package outline SOT108-1 (SO14)

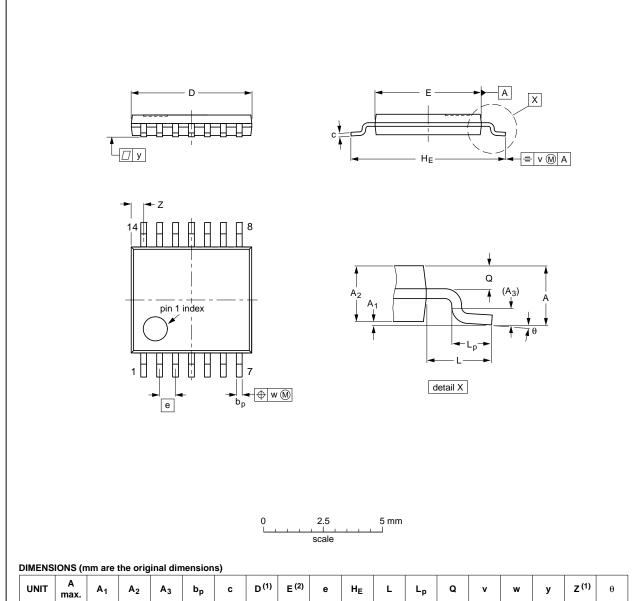
HEF4013B_Q100

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TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1



Ξ							-,												
	UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	Z ⁽¹⁾	θ
	mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.72 0.38	8° 0°

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE				
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE		
SOT402-1		MO-153				99-12-27 03-02-18		
				•				

Fig 12. Package outline SOT402-1 (TSSOP14)

15. Abbreviations

Table 11. Abbreviations

Acronym	Description
НВМ	Human Body Model
ESD	ElectroStatic Discharge
MM	Machine Model
MIL	Military

16. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4013B_Q100 v.2	20130220	Product data sheet	-	HEF4013B_Q100
Modifications:	 HEF4013BI 	P-Q100 (DIP14) added.		
HEF4013B_Q100 v.1	20120807	Product data sheet	-	-

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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Dual D-type flip-flop

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