# INTEGRATED CIRCUITS

# DATA SHEET



# **PCA9559**

5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

Product data Supersedes data of 2002 May 24





# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

**PCA9559** 



### **FEATURES**

- 5-bit 2-to-1 multiplexer, 1-bit latch DIP switch
- 6-bit internal non-volatile register
- Internal non-volatile register programmable and readable via I<sup>2</sup>C-bus
- Override input forces all outputs to logic 0
- 5 open drain multiplexed outputs
- 1 open drain non-multiplexed (latched) output
- 5 V and 2.5 V tolerant inputs
- Useful for 'jumperless' configuration of PC motherboards
- 2 address pins, allowing up to 4 devices on the I<sup>2</sup>C-bus
- ESD protection exceeds 2000 V HBM per JESD22-A114,
   200 V MM per JESD22-A115 and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JESDEC Standard JESD78 which exceeds 100 mA

### **DESCRIPTION**

The PCA9559 is a 20-pin CMOS device consisting of one 6-bit non-volatile EEPROM registers, 5 hardware pin inputs and a 5-bit multiplexed output with one latched EEPROM bit. It is used for DIP switch-free or jumper-less system configuration and supports Mobile and Desktop VID Configuration, where 2 preset values (1 set of internal non-volatile registers and 1 set of external hardware pins) set processor voltage for operation in either performance or deep sleep modes. The PCA9559 is also useful in server and telecom/networking applications when used to replace DIP switches or jumpers, since the settings can be easily changed via I<sup>2</sup>C/SMBus without having to power down the equipment to open the cabinet. The non-volatile memory retains the most current setting selected before the power is turned off.

The PCA9559 typically resides between the CPU and Voltage Regulator Module (VRM) when used for CPU VID (Voltage IDentification code) configuration. It is used to bypass the CPU-defined VID values and provide a different set of VID values to the VRM, if an increase in the CPU voltage is desired. An increase in CPU voltage combined with an increase in CPU frequency leads to a performance boost of up to 7.5%. Lower CPU voltage reduces power consumption.

The PCA9559 has 2 address pins allowing up to 4 devices to be placed on the same  $I^2C$ -bus or SMBus.

### **PIN CONFIGURATION**

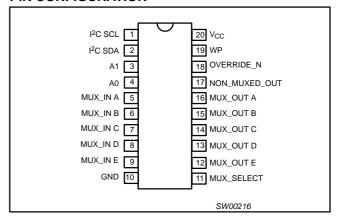


Figure 1. Pin configuration

### PIN DESCRIPTION

FIN DESCRIPTION								
PIN NUM- BER	SYMBOL	FUNCTION						
1	I <sup>2</sup> C SCL	Serial I <sup>2</sup> C-bus clock						
2	I <sup>2</sup> C SDA	Serial bi-directional I <sup>2</sup> C-bus data						
3	A1 Address	A1						
4	A0 Address	A0						
5-9	MUX_IN A-E	External inputs to multiplexer						
10	GND	Ground						
11	MUX_SELECT	Selects MUX_IN inputs or register contents for MUX_OUT outputs						
12-16	MUX_OUT E-A	Open drain multiplexed outputs						
17	NON_MUXED_ OUT	Open drain outputs from non-volatile memory						
18	OVERRIDE_N	Forces all outputs to logic 0						
19	WP	Non-volatile register write-protect						
20	$V_{CC}$	Power supply: +3.0 to +3.6 V						

## ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	TOPSIDE MARK	DRAWING NUMBER	
20-Pin Plastic TSSOP	0 to +70 °C	PCA9559PW	PCA9559	SOT360-1	

Standard packing quantities and other packaging data is available at www.philipslogic.com/packaging.

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### **FUNCTIONAL DESCRIPTION**

When the MUX\_SELECT signal is logic 0, the multiplexer will select the data from the non-volatile register to drive on the MUX\_OUT pins. When the MUX\_SELECT signal is logic 1, the multiplexer will select the MUX\_IN lines to drive on the MUX\_OUT pins. The MUX\_SELECT signal is also used to latch the NON\_MUXED\_OUT signal which outputs data from the non-volatile register. The NON\_MUXED\_OUT signal latch is transparent when MUX\_SELECT is in a logic 0 state, and will latch data when MUX\_SELECT is in a logic 1 state. When the active-LOW OVERRIDE\_N signal is set to logic 0 and the MUX\_SELECT signal is at a logic 0, all outputs will be driven to logic 0. This information is summarized in Table 1.

The Write Protect (WP) input is used to control the ability to write the contents of the 6-bit non-volatile register. If the WP signal is logic 0, the I<sup>2</sup>C-bus will be able to write the contents of the non-volatile register. If the WP signal is logic 1, data will not be allowed to be written into the non-volatile register.

The factory default for the contents of the non-volatile register are all logic 0. These stored values can be read or written using the  $I^2C$ -bus (described in the next section).

The OVERRIDE\_N, WP, MUX\_IN, and MUX\_SELECT signals have internal pull-up resistors. See the DC and AC Characteristics for hysteresis and signal spike suppression figures.

### **FUNCTION TABLE**

OVERRIDE_N	MUX_SELECT	MUX_OUT OUTPUTS	NON_MUXED_OUT OUTPUT
0	0	All 0's	All 0's
0	1	MUX_IN inputs	Latched NON_MUXED_OUT <sup>1</sup>
1	0	From non- volatile register	From non-volatile register
1	1	MUX_IN inputs	From non-volatile register

#### NOTE:

 NON\_MUXED\_OUT state will be the value present on the output at the time of the MUX\_SELECT input transitioned from a logic 0 to a logic 1 state.

### I<sup>2</sup>C INTERFACE

Communicating with this device is initiated by sending a valid address on the I<sup>2</sup>C-bus. The address format (see Flgure 1) has 5 fixed bits and two user-programmable bits followed by a 1-bit read/write value which determines the direction of the data transfer.

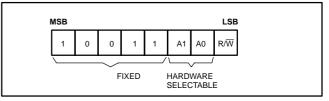


Figure 2. I<sup>2</sup>C Address Byte

Following the address and acknowledge bit are 8 data bits which, depending on the read/write bit in the address, will read data from or write data to the non-volatile register. Data will be written to the register if the read/write bit is logic 0 and the WP input is logic 0. Data will be read from the register if the bit is logic 1. The four high-order bits are latched outputs, while the four low order bits are multiplexed outputs (Figure 3).

#### NOTE:

 To ensure data integrity, the non-volatile register must be internally write protected when V<sub>CC</sub> to the I<sup>2</sup>C-bus is powered down or V<sub>CC</sub> to the component is dropped below normal operating levels.

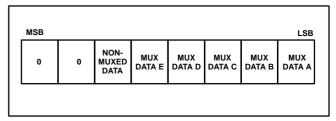


Figure 3. I<sup>2</sup>C Data Byte

## **POWER-ON RESET (POR)**

When power is applied to  $V_{CC}$ , an internal power-on reset holds the PCA9559 in a reset state until  $V_{CC}$  has reached  $V_{POR}$ . At that point, the reset condition is released and the PCA9559 volatile registers and  $I^2C/SMBus$  state machine will initialize to their default states.

The MUX\_OUT and NON\_MUXED\_OUT pin values depend on:

- the OVERRIDE # and MUX\_SELECT logic levels
- the previously stored values in the EEPROM register/current MUX\_IN pin values as shown in the Function Table.

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### **BLOCK DIAGRAM**

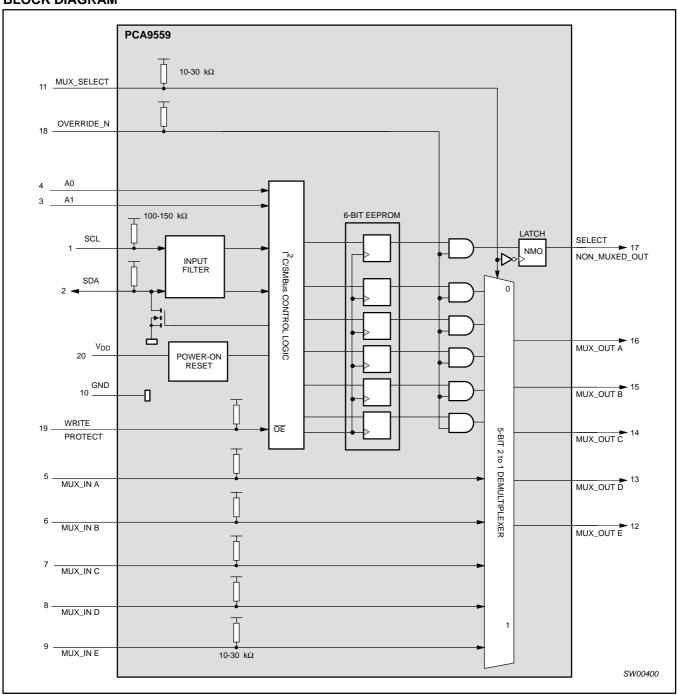


Figure 4. Block diagram

# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

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## ABSOLUTE MAXIMUM RATINGS1, 2

In accordance with the Absolute Maximum Rating System (IEC 134)

Voltages are referenced to GND (ground = 0 V)

SYMBOL	PARAMETER	RATING	UNIT	
V <sub>CC</sub>	DC supply voltage		-0.5 to +4.6	V
VI	DC input voltage	Note 3	-1.5 to V <sub>CC</sub> +1.5	V
V <sub>OUT</sub>	DC output voltage	Note 3	-0.5 to V <sub>CC</sub> +0.5	V
T <sub>stg</sub>	Storage temperature range		-60 to +150	°C

### NOTES:

- 1. Stresses beyond those listed may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- 2. The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150°C.
- 3. The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

### **RECOMMENDED OPERATING CONDITIONS**

CVMDOL	DADAMET	-n	CONDITIONS	LIN	LINUT	
SYMBOL	PARAMETI	=K	CONDITIONS	MIN	MAX	UNIT
V <sub>CC</sub>	DC supply voltage			3.0	3.6	V
$V_{IL}$	LOW-level input voltage	SCL, SDA	I <sub>OL</sub> = 3 mA	-0.5	0.9	V
$V_{IH}$	HIGH-level input voltage	SCL, SDA	I <sub>OL</sub> = 3 mA	2.7	4.0	V
M	LOW level cutrut voltage	CCL CDA	I <sub>OL</sub> = 3 mA	_	0.4	V
$V_{OL}$	LOW-level output voltage	SCL, SDA	I <sub>OL</sub> = 6 mA	_	0.6	]
V <sub>IL</sub>	LOW-level input voltage	OVERRIDE_N, MUX_IN, MUX_SELECT		-0.5	0.8	V
V <sub>IH</sub>	HIGH-level input voltage	OVERRIDE_N, MUX_IN, MUX_SELECT		2.0	4.0	V
I <sub>OL</sub>	LOW-level output current	MUX_OUT, NON_MUXED_OUT		_	8	mA
I <sub>OH</sub>	HIGH-level output current	MUX_OUT, NON_MUXED_OUT		_	100	μА
dt/dv	Input transition rise or fall time			0	10	ns/V
T <sub>amb</sub>	Operating temperature			0	70	°C

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### **DC CHARACTERISTICS**

0)////	D. D. M. T. T. D.	TEST SOURIEIS		LIMITS				
SYMBOL PARAMETER		TEST CONDITION	MIN.	TYP.	MAX.	UNIT		
Supply			•	•	<u>'</u>			
V <sub>CC</sub>	Supply voltage		3	_	3.8	V		
I <sub>CCL</sub>	Supply current	Operating mode ALL inputs = 0 V	_	_	10	mA		
I <sub>CCH</sub>	Supply current	Operating mode ALL inputs = V <sub>CC</sub>	_	_	600	μΑ		
V <sub>POR</sub>	Power-on reset voltage	no load; V <sub>I</sub> = V <sub>CC</sub> or GND	_	1.9	2.6	V		
Input SCL:	Input/Output SDA							
$V_{IL}$	LOW-level input voltage		-0.5	_	0.8	V		
V <sub>IH</sub>	HIGH-level input voltage		2	_	V <sub>CC</sub> + 0.5	V		
I <sub>OL</sub>	LOW-level output curret	V <sub>OL</sub> = 0.4 V	3	_	_	mA		
I <sub>OL</sub>	LOW-level output curret	V <sub>OL</sub> = 0.6 V	6	_	_	mA		
I <sub>IH</sub>	Leakage current HIGH	$V_I = V_{CC}$	-1.5	_	-12	μΑ		
I <sub>IL</sub>	Leakage current LOW	V <sub>I</sub> = GND	-7	_	-32	μΑ		
C <sub>I</sub>	Input capacitance		_	_	10	pF		
OVERRIDE	_N, WP, MUX_SELECT							
I <sub>IH</sub>	Leakage current HIGH	$V_I = V_{CC}$	-20	_	-100	μΑ		
I <sub>IL</sub>	Leakage current LOW	V <sub>I</sub> = GND	-86	_	-267	μΑ		
C <sub>I</sub>	Input capacitance		_	_	10	pF		
MUX_IN A	⇒ E							
I <sub>IH</sub>	Leakage current HIGH	$V_I = V_{CC}$	-0.166	_	-0.75	mA		
I <sub>IL</sub>	Leakage current LOW	V <sub>I</sub> = GND	-0.72	_	-2	mA		
C <sub>I</sub>	Input capacitance		_	_	10	pF		
A0, A1 Inpu	ıts							
I <sub>IH</sub>	Leakage current HIGH	$V_I = V_{CC}$	-1	_	1	μΑ		
I <sub>IL</sub>	Leakage current LOW	V <sub>I</sub> = GND	-1	_	1	μΑ		
C <sub>I</sub>	Input capacitance		_	_	10	pF		
MUX_OUT	E ⇒ A							
V <sub>OL</sub>	LOW-level output curret	I <sub>OL</sub> = 100 μA	_	_	0.4	V		
V <sub>OL</sub>	LOW-level output curret	I <sub>OL</sub> = 2 mA	_		0.7	V		
NON_MUXI	ED_OUT							
$V_{OL}$	LOW-level output curret	I <sub>OL</sub> = 100 μA			0.4	V		
V <sub>OL</sub>	LOW-level output curret	I <sub>OL</sub> = 2 mA	_	_	0.7	V		

### NOTES:

### NON-VOLATILE STORAGE SPECIFICATIONS

PARAMETER	SPECIFICATION
Memory cell data retention	10 years min
Number of memory cell write cycles	100,00 cycles min

Application Note AN250 I<sup>2</sup>C DIP Switch provides additional information on memory cell data retention and the minimum number of write cycles.

<sup>1.</sup>  $V_{\mbox{\scriptsize HYS}}$  is the hysteresis of Schmitt-Trigger inputs

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### **AC CHARACTERISTICS**

SYMBOL	PARAMETER		UNIT		
STWIBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT
MUX_IN ⇒ MUX	C_OUT				
t <sub>PLH</sub>	LOW-to-HIGH transition time	_	28	37	ns
t <sub>PHL</sub>	HIGH-to-LOW transition time	_	16	21	ns
$Select \Rightarrow MUX_{-}$	OUT				
tPLH	LOW-to-HIGH transition time	_	30	39	ns
tPHL	HIGH-to-LOW transition time	_	17	22	ns
OVERRIDE_N =	⇒ NON-MUXED_OUT				
t <sub>PLH</sub>	LOW-to-HIGH transition time	_	34	43	ns
t <sub>PHL</sub>	HIGH-to-LOW transition time	_	19	25	ns
OVERRIDE_N =	⇒ MUX_OUT				
t <sub>PLH</sub>	LOW-to-HIGH transition time	_	31	41	ns
t <sub>PHL</sub>	HIGH-to-LOW transition time	_	21	27	ns
t <sub>R</sub>	Output rise time	1.0	_	3	ns/V
t <sub>F</sub>	Output fall time	1.0	_	3	ns/V
P <sub>F</sub>	Pull-up resistor for outputs	1.0	_	_	ns/V
C <sub>L</sub>	Test load capacitance on outputs	_	_	_	pF
<sup>2</sup> C-bus	•				
t <sub>SCL</sub>	SCL clock frequency	10	_	400	kHz
t <sub>BUF</sub>	Bus free time between a STOP and a START condition	1.3	_	_	μs
t <sub>HD:STA</sub>	Hold time (repeated) START condition. After this period, the first clock pulse is generated	600	_	_	ns
t <sub>LOW</sub>	LOW period of SCL clock	1.3	_	_	μs
t <sub>HIGH</sub>	HIGH period of SCL clock	600	_	-12	ns
t <sub>SU:STA</sub>	Set-up time for a repeated START condition	600	_	-32	ns
t <sub>HD:DAT</sub>	Data hold time	0	_	10	ns
t <sub>SU:DAT</sub>	Data set-up time	100	_	-100	ns
t <sub>SP</sub>	Data spike time	0	_	50	ns
t <sub>SU:STO</sub>	Set-up time for STOP condition	600	_	10	ns
t <sub>R</sub>	Rise time for both SDA and SCL signals (10 - 400 pF bus)	20	_	300	ns
tį	Fall time for both SDA and SCL signals (10 - 400 pF bus)	20	_	300	ns
C <sub>L</sub>	Capacitive load for each bus line	<u> </u>	_	400	pF
T <sub>W</sub>	Write cycle time <sup>1</sup>	_	15	_	ms

## NOTE:

<sup>1.</sup> WRITE CYCLE time can only be measured indirectly during the write cycle. During this time, the device will not acknowledge its I<sup>2</sup>C Address.

# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

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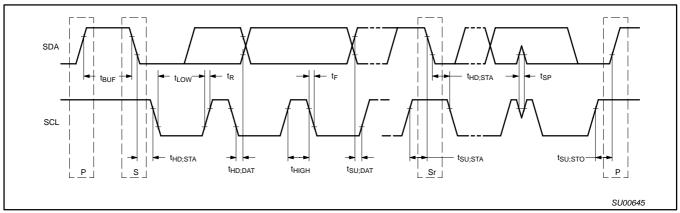


Figure 5. Definition of timing

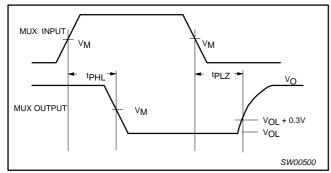


Figure 6. Open drain output enable and disable times

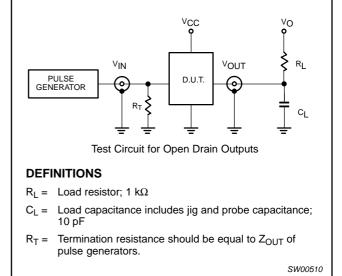


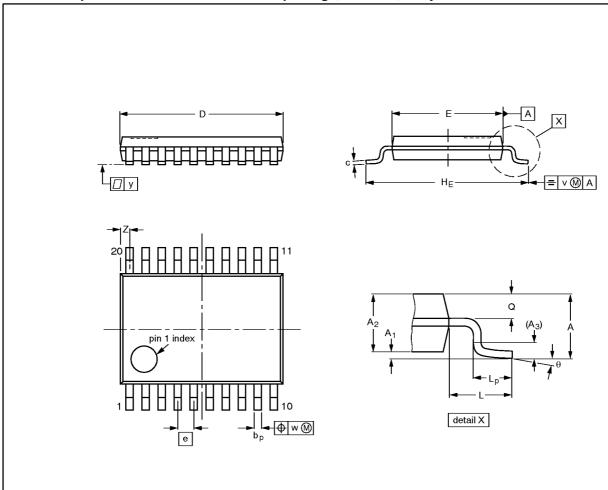
Figure 7. Test circuit

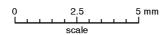
# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

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## TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm

SOT360-1





### DIMENSIONS (mm are the original dimensions)

UNI	. A max.	A <sub>1</sub>	A <sub>2</sub>	А3	рb	O	D <sup>(1)</sup>	E <sup>(2)</sup>	e	HE	L	Lρ	ø	v	8	у	Z <sup>(1)</sup>	θ
mm	1.10	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	6.6 6.4	4.5 4.3	0.65	6.6 6.2	1.0	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.5 0.2	8° 0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	IEC JEDEC EIAJ			PROJECTION	ISSUE DATE
SOT360-1		MO-153AC				<del>93-06-16</del> 95-02-04

# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM DIP switch

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## **REVISION HISTORY**

Rev	Date	Description
_4	20030627	Product data (9397 750 11675); ECN 853-2181 29936 dated 19 May 2003. Supersedes data of 2002 May 24 (9397 750 09891).
		Modifications:
		Update marketing information.
		<ul> <li>Increase number of write cycles from 3K to 100K.</li> </ul>
_3	20020524	Product data (9397 750 09891); ECN 853-2181 28310 of 24 May 2002.

# 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C FEPROM DIP switch

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Purchase of Philips I<sup>2</sup>C components conveys a license under the Philips' I<sup>2</sup>C patent to use the components in the I<sup>2</sup>C system provided the system conforms to the I<sup>2</sup>C specifications defined by Philips. This specification can be ordered using the code 9398 393 40011.

#### Data sheet status

Level	Data sheet status <sup>[1]</sup>	Product status <sup>[2] [3]</sup>	Definitions
I	Objective data	Development	This data sheet contains data from the objective specification for product development.  Philips Semiconductors reserves the right to change the specification in any manner without notice.
II	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
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- [2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.
- [3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

#### **Definitions**

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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9397 750 11675

Date of release: 06-03

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