



# 16-BIT, 4-MSPS, PSEUDO-BIPOLAR, FULLY DIFFERENTIAL INPUT, MICROPOWER SAMPLING ANALOG-TO-DIGITAL CONVERTER WITH PARALLEL INTERFACE, REFERENCE

#### **FEATURES**

- Fully Differential Input with Pseudo-Bipolar Input Range -4 V to +4 V
- 16-Bit NMC at 4 MSPS
- 1 LSB INL Typ
- 92dB SNR, -102dB THD Typ with 100-kHz Input
- Internal 4.096-V Reference and Reference Buffer
- REFIN/2 Available for Setting Analog Input Common-Mode Voltage
- Zero Latency
- High-Speed Parallel Interface
- Single Supply Operation Capability
- Low Power: 155 mW at 4 MHz Typ, Flexible Power-Down Scheme
- Pin-Out Similar to ADS8412/8402
- 48-Pin 9×9 TQFP Package

#### **APPLICATIONS**

- DWDM
- Instrumentation
- High-Speed, High-Resolution, Zero Latency Data Acquisition Systems
- Transducer Interface
- Medical Instruments
- Spectrum Analysis
- ATE

#### DESCRIPTION

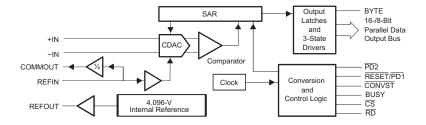
The ADS8422 is a 16-bit, 4-MHz A/D converter with an internal 4.096-V reference. The device includes a 16-bit capacitor-based multi-bit SAR A/D converter with inherent sample and hold. This converter includes a full 16-bit interface and an 8-bit option where data is read using two 8-bit read cycles if necessary.

The ADS8422 has a fully differential, pseudo-bipolar input. It is available in a 48-lead TQFP package and is characterized over the industrial -40°C to +85°C temperature range.

## HIGH-SPEED SAR CONVERTER FAMILY(1)

TYPE/SPEED	500 kHz	~600 kHz	750 kHz	1 MHz	1.25 MHz	2 MHz	3 MHz	4MHz
18-Bit Pseudo-Diff	ADS8383	ADS8381		ADS8481				
10-Bit FSeudo-Dill		ADS8380 (s)						
18-Bit Pseudo-Bipolar, Fully Diff		ADS8382 (s)		ADS8482				
16-Bit Pseudo-Diff		ADS8370 (s)	ADS8371	ADS8471	ADS8401	ADS8411		
то-ык Pseudo-ыш	ADS8327/28 (s)	ADS8372 (s)		ADS8329/30 (s)	ADS8405	ADS8410 (s)		
4C Dit Decude Dineles Fully Diff				ADS8472	ADS8402	ADS8412		ADS8422
16-Bit Pseudo-Bipolar, Fully Diff					ADS8406	ADS8413 (s)		
14-Bit Pseudo-Diff					ADS7890 (s)		ADS7891	
12-Bit Pseudo-Diff				ADS7886		ADS7883		ADS7881

(1) S: Serial





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## ORDERING INFORMATION(1)

MODEL	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES RESOLUTION (BIT)	PACKAGE TYPE	PACKAGE DESIGNATOR	TEMPERATURE RANGE	ORDERING INFORMATION	TRANSPORT MEDIA QTY.
ADS8422I	±6	±2	15	9×9 48-Pin	PFB	–40°C to 85°C	ADS8422IPFBT	Small tape and reel 250
AD304221	±0	± <b>z</b>	13	TQFP		-40 C to 65 C	ADS8422IPFBR	Tape and reel 1000
ADS8422IB	±2	+1.5/-1	16	9×9 48-Pin	PFB	–40°C to 85°C	ADS8422IBPFBT	Small tape and reel 250
AD30422IB	±Ζ	+1.5/-1	10	TQFP	FFB	-40 C to 65 C	ADS8422IBPFBR	Tape and reel 1000

<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

## **ABSOLUTE MAXIMUM RATINGS**(1)

over operating free-air temperature range (unless otherwise noted)

			VALUE	UNIT
		+IN to AGND	-0.4 to +VA + 0.1	V
Valtaria		-IN to AGND	-0.4 to +VA + 0.1	V
Voltage	+VA to AGND		-0.3 to 7	V
	-IN to AGND +VA to AGND +VBD to BDGND  oltage to BDGND voltage to BDGND e-air temperature range erature range perature (T <sub>J</sub> max)  package  Power dissipation θ <sub>JA</sub> thermal imped vapor phase (60 s	+VBD to BDGND	-0.3 to 7	V
Digital input v	oltage to BDGND	)	-0.3 to +VBD + 0.3	V
Digital output	Digital output voltage to BDGND		-0.3 to +VBD + 0.3	V
T <sub>A</sub> Operating free	e-air temperature	range	-40 to 85	°C
T <sub>stg</sub> Storage temp	erature range		-65 to 150	°C
Junction temp	perature (T <sub>J</sub> max)		150	°C
TOED 40 nin	naakaaa	Power dissipation	$(T_{J}Max - T_{A})/\theta_{JA}$	
TQFP 46-pin	раскаде	$\theta_{JA}$ thermal impedance	86	°C/W
		Vapor phase (60 sec)	215	°C
Lead tempera	d temperature, soldering Infrared (15 sec)		220	°C

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.



## **SPECIFICATIONS**

 $T_A = -40^{\circ}\text{C}$  to 85°C, +VA = 5 V, +VAREG = 5 V to 3 V, +VBD = 5 V to 2.7 V,  $f_{SAMPLE} = 4$  MSPS,  $V_{ref} = 4.096$  V (measured with internal reference buffer) (unless otherwise noted)

PARAMETE	R	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
ANALOG INPUT							
Full-scale input voltage <sup>(1)</sup>		+IN - (-IN)	-V <sub>ref</sub>		$V_{ref}$	V	
Abaduta input valtaga		+IN	-0.2		V <sub>ref</sub> + 0.2	V	
Absolute input voltage		-IN	-0.2		V <sub>ref</sub> + 0.2	V	
Common-mode input range			(V <sub>ref</sub> )/2 - 0.2	(V <sub>ref</sub> )/2	$(V_{ref})/2 + 0.2$	V	
Input capacitance				30		pF	
Input leakage current					1	nA	
SYSTEM PERFORMANCE							
Resolution				16		Bits	
No missing codes	ADS8422I		15			Bits	
no missing codes	ADS8422IB		16			DIIS	
Integral linearity (2)(3)	ADS8422I		-6	±2	6	LSB	
Integral linearity (2)(3)	ADS8422IB		-2	±1	2	(16 bit) <sup>(2)</sup>	
Differential linearity	ADS8422I		-2	±0.7	2	LSB	
Differential linearity ADS8422I			-1	±0.7	1.5	(16 bit)	
Offset error			-0.5	±0.25	0.5	mV	
Offset error drift				±0.2		ppm/°C	
Gain error <sup>(4)(5)</sup>		V <sub>ref</sub> = 4.096 V	-0.1	±0.05	0.1	%FS	
Gain error drift		V <sub>ref</sub> = 4.096 V		±2		ppm/°C	
		At dc		81			
Common-mode rejection ratio		At code 0000h with $[+IN + (-IN)]/2 =$ 512 mV <sub>pp</sub> at 500 kHz,		78		dB	
Noise		At 0000h output code		40		μV RMS	
Power supply rejection ratio		At 8000h output code		78		dB	
SAMPLING DYNAMICS							
Conversion time					0.180	μs	
Acquisition time			0.070			μs	
Throughput rate					4	MHz	
Aperture delay				3		ns	
Aperture jitter				7		ps RMS	
Step response				70		ns	
Overvoltage recovery				140		ns	

- (1) Ideal input span, does not include gain or offset error.
  (2) LSB means least significant bit and is equal to 2V<sub>REF</sub>/65536.
- (3) This is endpoint INL, not best fit.
- (4) Measured relative to an ideal full-scale input [+IN (–IN)] of 8.192 V.
- (5) This specification does not include the internal reference voltage error and drift.



# **SPECIFICATIONS (Continued)**

 $T_A = -40^{\circ}\text{C}$  to 85°C, +VA = 5 V, +VAREG = 5.25 V to 3 V, +VBD = 5 V to 2.7 V,  $f_{SAMPLE} = 4$  MSPS,  $V_{ref} = 4.096$  V (measured with internal reference buffer) (unless otherwise noted)

PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT	
DYNAMIC CHARACTERISTICS							
		10 kHz		-114			
Total harmonic distortion (THD) <sup>(1)</sup>	$V_{IN} = 8 V_{pp}$	100 kHz		-102		dB	
		500 kHz		-100			
		10 kHz		93			
Signal to noise ratio (SNR)	$V_{IN} = 8 V_{pp}$	100 kHz		92		dB	
		500 kHz		90			
		10 kHz		92.5			
Signal to noise + distortion (SINAD)	$V_{IN} = 8 V_{pp}$	100 kHz		91.5		dB	
		500 kHz		89.5			
		10 kHz		116			
Spurious free dynamic range (SFDR)	$V_{IN} = 8 V_{pp}$	100 kHz		109		dB	
		500 kHz		106			
-3dB Small signal bandwidth				30		MHz	
Maximum input frequency, f <sub>i(max)</sub> (2)	$V_{IN} = 8 V_{pp}$		2			MHz	
VOLTAGE REFERENCE INPUT							
Reference voltage at REFIN, V <sub>ref</sub>			3.9	4.096	4.15	V	
Reference resistance				1000		$M\Omega$	
INTERNAL REFERENCE OUTPUT							
Internal reference start-up time	From 95% (+VA), with	h 1-μF capacitor on REFOUT			25	ms	
Reference voltage range, V <sub>ref</sub>	I <sub>O</sub> = 0, T <sub>A</sub> = 25°C		4.088	4.096	4.104	V	
Source current	Static load				10	μΑ	
Line regulation	+VA = 4.75 V to 5.25	V		±1		mV	
Drift	I <sub>O</sub> = 0			±6		PPM/°C	
ANALOG COMMON-MODE, PIN 3							
Output voltage range	I <sub>O</sub> = 0		V <sub>REF</sub> /2 - 0.016	V <sub>REF</sub> /2	V <sub>REF</sub> /2 + 0.016	V	
Source current	Static load			200		μΑ	

<sup>(1)</sup> Calculated on the first nine harmonics of the input frequency.

<sup>(2)</sup> ADC Sampling circuit is optimized to accept inputs until Nyquist frequency. Dynamic performance may degrade rapidly above f<sub>i(max)</sub>.



# **SPECIFICATIONS (Continued)**

 $T_A = -40^{\circ}\text{C}$  to 85°C, +VA = 5 V, +VAREG = 5 V to 3 V, +VBD = 5 V to 2.7 V,  $f_{SAMPLE} = 4$  MSPS,  $V_{ref} = 4.096$  V (measured with internal reference buffer) (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
DIGITAL INPUT/OUTPUT		·					
Logic family – CMOS							
	V <sub>IH</sub>	I <sub>IH</sub> = 5 μA	0.75×(+VBD)		+VBD + 0.3		
Lagia laval	V <sub>IL</sub>	I <sub>IL</sub> = 5 μA	-0.3		0.8	V	
Logic level	V <sub>OH</sub>	I <sub>OH</sub> = 2 TTL loads	+VBD - 0.6			V	
	V <sub>OL</sub>	I <sub>OL</sub> = 2 TTL loads			0.4		
Data format – Twos compler	ment						
POWER SUPPLY REQUIRE	MENTS		·		·		
	+VA		4.75	5	5.25		
Power supply voltage	+VAREG		2.85	3.0	5.25	V	
	+VBD		2.7	3.0	5.25		
	+VA	+VA = 5 V, <u>PD1</u> = 1, <u>PD2</u> = 1		24	27	mA	
Supply current	+VAREG	+VAREG = 5 V, PD1 = 1, PD2 = 1		12	14	mA	
	TVAREG	+VAREG = 3 V, <u>PD1</u> = 1, <u>PD2</u> = 1		12 14		IIIA	
	+VBD <sup>(1)</sup>	+VBD = 3 V, 10 pF/pin	0.55			mA	
	TVBD(1)	+VBD = 5 V, 20 pF/pin	1			IIIA	
POWER DOWN <sup>(2)</sup>							
Supply current	+VA	PD1 = 0. PD2 = 1. +VA = 5 V		2.5	3.4	mA	
Опры синен	+VAREG	1 D1 = 0, 1 D2 = 1, +VA = 3 V		5		μΑ	
Power					17	mW	
Power-up time		$(\overline{\text{PD1}}, \overline{\text{PD2}}) : (0,1) \rightarrow (1,1)$			5	μs	
Supply current	+VA	PD1 = 0, PD2 = 0		5		^	
+VAREG		FB1 = 0, FB2 = 0		5		μΑ	
Power				40		μW	
Power-up time		$(\overline{PD1},\overline{PD2}):(0,\!0)\to(1,\!1)$ , 1- $\!\mu F$ Storage capacitor from REFOUT to AGND			25	ms	
TEMPERATURE RANGE							
Operating free-air			-40		85	°C	

This includes the current required for charging the external load capacitance on the digital outputs and is measured with four digital outputs toggling at the same time.  $(\overline{PD}_1$ ,  $\overline{PD}_2$ ) = (1,0) is reserved. Do not use this power-down pins combination.



## TIMING CHARACTERISTICS FROM DIGITAL INPUTS

All specifications typical at  $-40^{\circ}$ C to  $85^{\circ}$ C, +VBD = 2.7 V to 5.25 V (1)(2)

		PARAMETER	MIN	TYP MAX	UNIT		
CONV	ERSION AND AC	QUISITION					
t <sub>(ACQ)</sub>	Acquisition time	, internal to device, not externally visible	70		ns		
t <sub>w1</sub>	Pulse duration,	CONVST low	20		ns		
t <sub>w2</sub>	Pulse duration,	CONVST high	100		ns		
t <sub>p1</sub>	Period, CONVS	Ī	250		ns		
t <sub>q1</sub>	Quiet time, last	30		ns			
t <sub>q2</sub>	Quiet time, CON	IVST falling to first toggle of interface input signals (3)	10		ns		
POWE	R DOWN				<u> </u>		
		PD1 low for only ADC reset (no powerdown)	20	500	)		
t <sub>w3</sub>	Pulse duration	PD1 low for ADC reset and also ADC powerdown	1500		ns		
	PD2 low pulse duration for REFOUT and COMMOUT buffers powerdown 1500						
	Pulse duration,	all others unspecified	10		ns		

- (1) All input signals are specified with t<sub>r</sub> = t<sub>f</sub> = 5 ns (10% to 90% of V<sub>DD</sub>) and timed from after 90% of transition.
   (2) All digital output signals loaded with 10-pF capacitors at +VBD = 2.7 V and 20-pF capacitor at +VBD = 5.25 V and timed to reaching 90% of transition.
- Quiet time zones are for meeting performance and not functionality.

## TIMING CHARACTERISTICS OF DIGITAL OUTPUTS

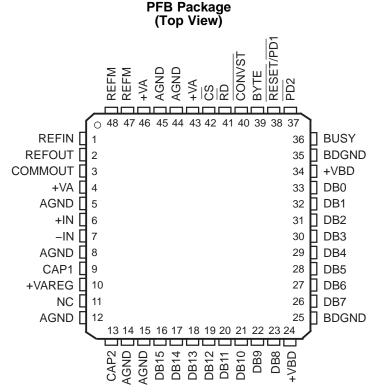
All specifications typical at  $-40^{\circ}$ C to  $85^{\circ}$ C, +VBD = 2.7 V to 5.25 V (1)(2)

	PARAMETER	MIN TYP	MAX	UNIT
CONVE	RSION AND ACQUISITION			
t <sub>(CONV)</sub>	Conversion time, internal to device, not externally visible		180	ns
t <sub>d1</sub>	Delay time, CONVST fall to conversion start (aperture delay)	3		ns
DATA R	EAD OPERATION			
t <sub>d2</sub>	Delay time, $\overline{CONVST}$ low to data valid if $\overline{CS} = \overline{RD} = 0$		225	ns
t <sub>d3</sub>	Delay time, data valid to BUSY low if $\overline{CS} = \overline{RD} = 0$	5		ns
t <sub>d4</sub>	Delay time, RD (or CS) low to data valid		17	ns
t <sub>d5</sub>	Delay time, BYTE toggle to data valid		20	ns
t <sub>d6</sub>	Delay time, data three-state after $\overline{RD}$ (or $\overline{CS}$ ) high		12	ns
POWER	DOWN			
t <sub>d7</sub>	Delay time, PD1 low to BUSY rising		20	ns
	Delay time, PD1 high to device operational (with PD2 held high)		5	μs
t <sub>d8</sub>	Delay time, PD2 high to REFOUT/COMMOUT valid		25	ms
	Delay time, power up (after AV <sub>DD</sub> = 4.75 V)		25	ms
t <sub>d9</sub>	Delay time, data three-state after PD1 low		1.5	μs

- (1) All input signals are specified with t<sub>r</sub> = t<sub>f</sub> = 5 ns (10% to 90% of V<sub>DD</sub>) and timed from after 90% of transition.
   (2) All digital output signals loaded with 10-pF capacitors at +VBD = 2.7 V and 20-pF capacitor at +VBD = 5.25 V and timed to reaching 90% of transition.



## **PIN ASSIGNMENTS**



- A. NC No connection
- B. Pins 9 and 13 are internally regulated 3-V outputs and are externally to be connected to decoupling capacitors only.
- C. +VAREG can be connected to a 3-V to 5-V supply.
- D. Pin 3 outputs REFIN/2
- E. Pin 38 can be used for ADC powerdown and pin 37 for analog output powerdown.

#### **TERMINAL FUNCTIONS**

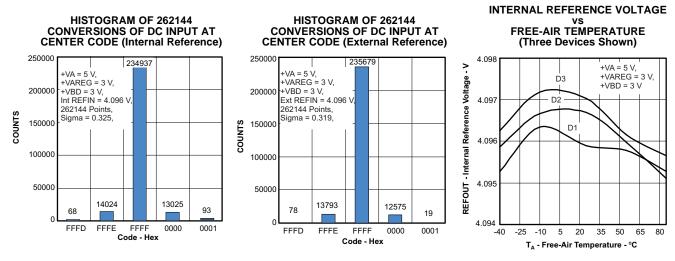
NAME	NO	I/O			DESCRIPTION			
AGND	5, 8, 12, 14, 15, 44, 45	-	Analog ground	Analog ground				
BDGND	25, 35	-	Digital ground for bus	interface digital supply				
BUSY	36	0	Status output. High wh	en a conversion is in progr	ess.			
BYTE	39	I	Byte select input. Used 0: No fold back 1: Low byte D[7:0] of t	· ·	s folded back to high byte of the 16 most significant pins DB[15:8].			
COMMOUT	3	0	This pin outputs REFII –IN)/2.	N/2 and can be used to set	the common-mode voltage of the differential analog input, (+IN +			
CONVST	40	I	Convert start. This inp	ut is low true and can act in	dependent of the CS input.			
CS	42	I	Chip select.					
CAP1, CAP2	9, 13	0	Decoupling of internall	y generated 3-V supply. Ad	d 1-μF capacitor from these pins to AGND.			
Dete Due			8-E	BIT BUS	16-BIT BUS			
Data Bus			BYTE = 0	BYTE = 1	BYTE = 0			
DB15	16	0	D15 (MSB)	D7	D15 (MSB)			
DB14	17	0	D14	D6	D14			
DB13	18	0	D13	D5	D13			
DB12	19	0	D12	D12 D4 D12				
DB11	20	0	D11	D3 D11				
DB10	21	0	D10	D2	D10			



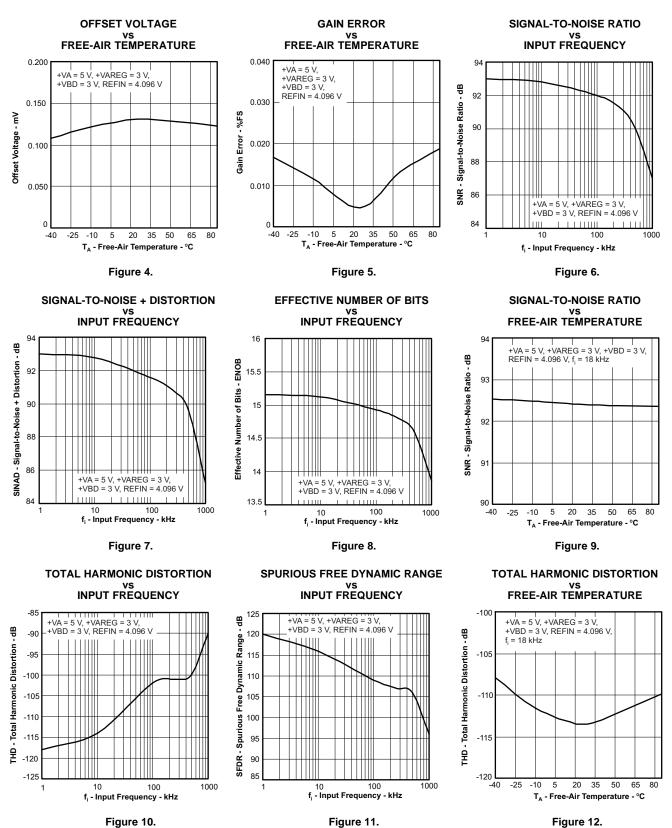
## **TERMINAL FUNCTIONS (continued)**

NAME	NO	I/O			DESCRIPTION			
DB9	22	0	D9	D1	D9			
DB8	23	0	D8	D0 (LSB) D8				
DB7	26	0	D7	All ones	D7			
DB6	27	0	D6	All ones	D6			
DB5	28	0	D5	All ones	D5			
DB4	29	0	D4	All ones	D4			
DB3	30	0	D3	All ones	D3			
DB2	31	0	D2	All ones	D2			
DB1	32	0	D1	All ones	D1			
DB0	33	0	D0 (LSB)	O (LSB) All ones D0 (LSB)				
-IN	7	- 1	Inverting input channel					
+IN	6	1	Noninverting input char	nnel				
NC	11	-	No connection					
PD2	37	I	Low true signal. A logic REFOUT and COMMO	low longer than 1.5 μs ap UT. (NOTE: The combinat	olied to this pin powers down only the analog outputs that include on PD1 = 1, PD2 = 0 is reserved. Do not use this combination.)			
REFIN	1	- 1	Reference input. Add 0	.1-μF decoupling capacitor	between REFIN and REFM.			
REFOUT	2	0	Reference output. Add	1-μF capacitor between the	e REFOUT pin and REFM pin when internal reference is used.			
REFM	47, 48	- 1	Reference ground					
RESET/PD1	38	I	than 0.5 µs only resets,		sets the ADC; the ongoing conversion is aborted. A low pulse shorter is resets and also powers down the ADC. Note that analog outputs by $\overline{\text{PD2}}$ , if necessary.			
RD	41	- 1	Synchronization pulse f	Synchronization pulse for the parallel output.				
+VA	4, 46	-	Analog power supplies,	Analog power supplies, 4.75 V to 5.25 VDC				
+VAREG	10	-	Regulator supply, 2.85	V to 5.25 VDC				
+VBD	24, 34	-	Digital power supply for	bus				

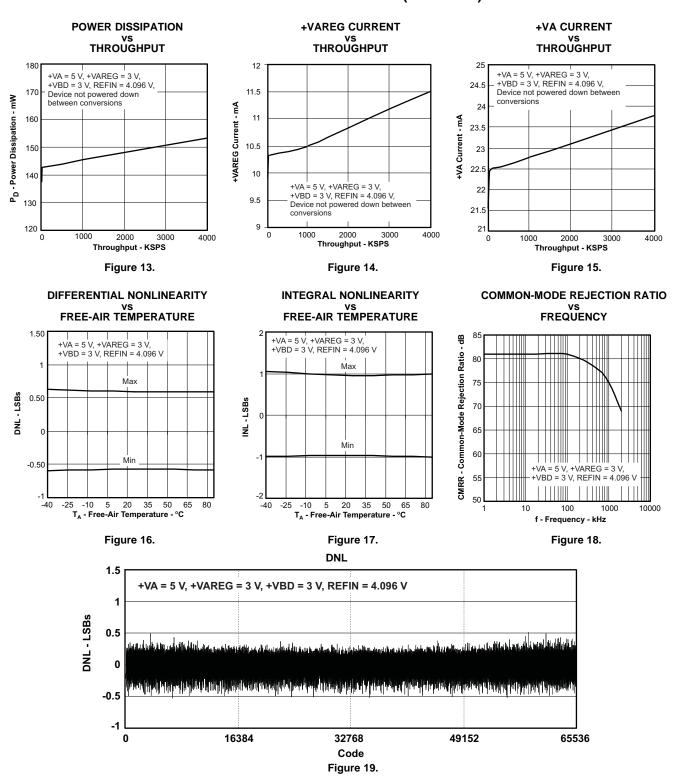
## **TYPICAL CHARACTERISTICS**



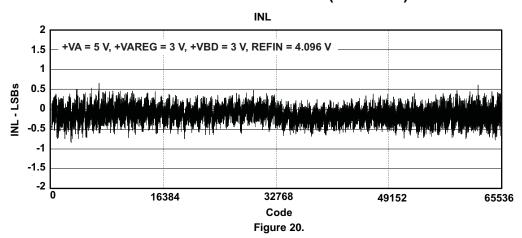


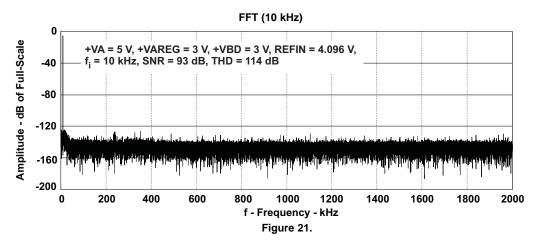


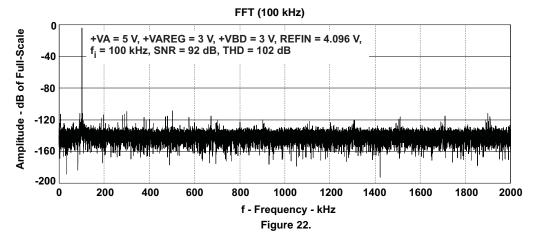




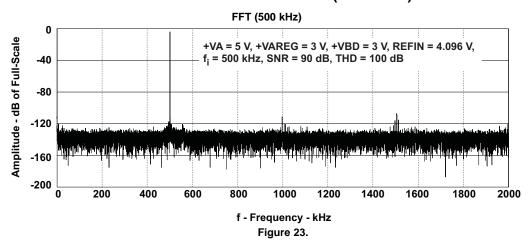




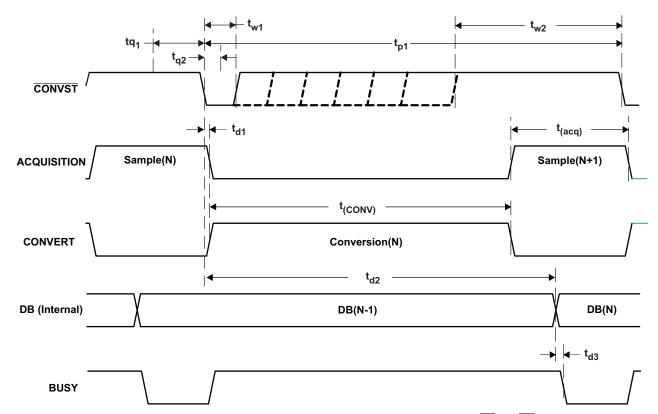








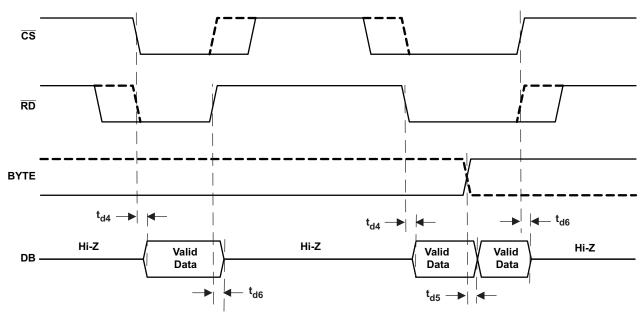
## **TIMING DIAGRAMS**



Note: The DB shown here is internal to the device and output on the pins only if and when  $\overline{CS}$  and  $\overline{RD}$  are both low (after  $t_{d4}$  ns). This is shown in Figure 25.

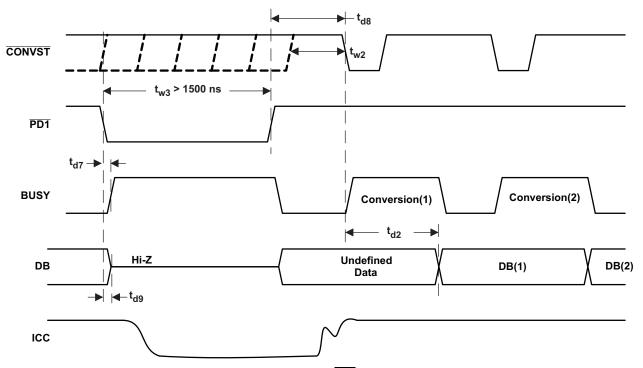
Figure 24. Conversion Control Timing





Note: Data is output on the pins only if  $\overline{\text{CS}}$  and  $\overline{\text{RD}}$  are both low,  $t_{\text{d4}}$  ns after this condition is satisfied.

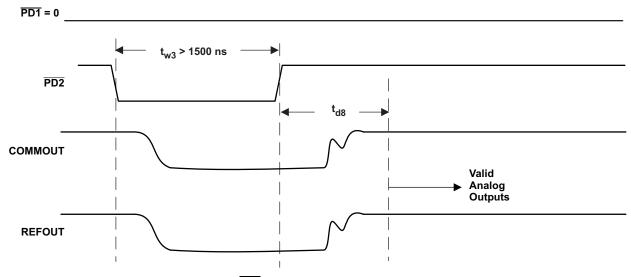
Figure 25. Data Read Timing



Note: Data is valid from the first conversion initiated 5  $\mu s$  after  $\overline{PD1}$  is pulled high.

Figure 26. ADC Power-Down Timing

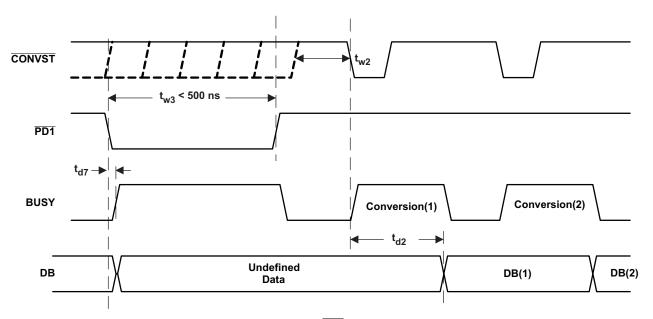




Note: Analog outputs are valid 25 ms after  $\overline{\text{PD2}}$  is pulled high.

Figure 27. Analog Output Power-Down Timing

## **RESET TIMING**



Note: Data valid from first conversion initiated 100 ns after PD1 is pulled high.

Figure 28. ADC Reset



#### PRINCIPLES OF OPERATION

The ADS8422 is a member of a family of high-speed multi-bit successive approximation register (SAR) analog-to-digital converters (ADC). The architecture is based on charge redistribution, which inherently includes a sample/hold function. See Figure 34 for the application circuit for the ADS8422.

The conversion clock is generated internally. The conversion time is a maximum of 180 ns that is capable of sustaining a 4-MHz throughput.

The analog input is provided to two input pins: +IN and -IN. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both inputs are disconnected from any internal function.

#### **REFERENCE**

The ADS8422 has a built-in 4.096-V reference but can operate with an external 4.096-V reference. When internal reference is used, pin 2 (REFOUT) should be connected to pin 1 (REFIN) with a 0.1- $\mu$ F decoupling capacitor and a 1- $\mu$ F storage capacitor between pin 2 (REFOUT) and pins 47 and 48 (REFM). The internal reference of the converter is double buffered. If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of the CDAC during conversion. Pin 2 (REFOUT) can be left unconnected (floating) if an external reference is used.

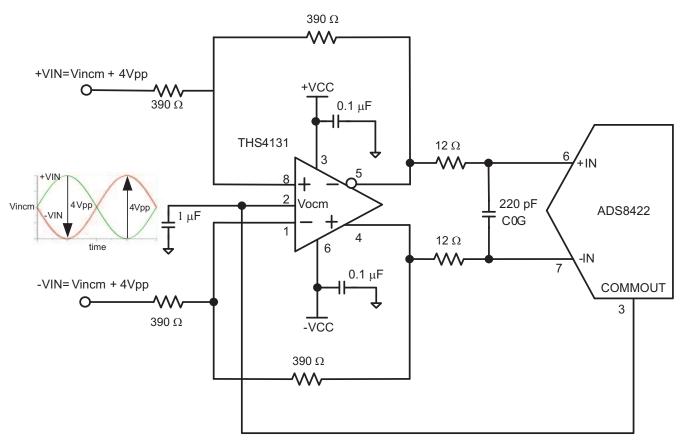
#### **ANALOG INPUT**

The ADS8422 has a pseudo-bipolar, fully differential input. When the input is differential, the amplitude of the input equals the difference between +IN and -IN. The peak-to-peak amplitude of each input is  $V_{REF}$ . However since the two inputs are  $180^{\circ}$  out of phase, the peak-to-peak amplitude of the difference voltage [+IN - (-IN)] is equal to  $2V_{REF}$ . The common-mode input range is from  $V_{REF}/2 - 0.2 \text{ V}$  to  $V_{REF}/2 + 0.2 \text{ V}$ .

In order to avoid additional external circuitry on the board, the ADS8422 outputs reference input on REFIN divided by 2 on pin 3 (COMMOUT). This voltage can be used to set the common-mode of the output from the input driver.

Figure 29, Figure 30, Figure 31, Figure 32, and Figure 33 show the recommended circuits to interface an analog input signal to the ADS8422.

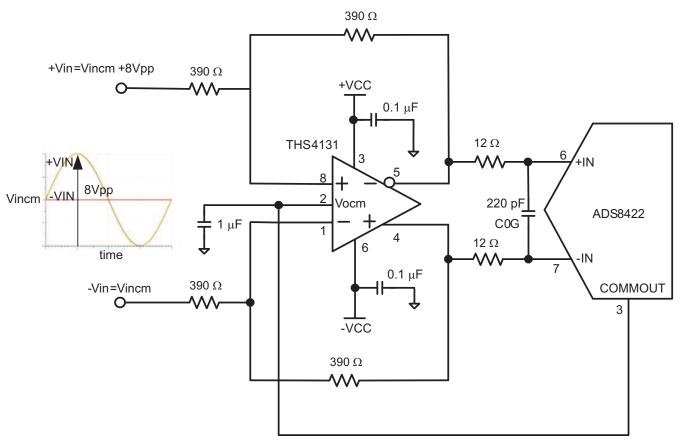




A. Input common-mode voltage (Vincm) range is restricted by the amplifier. Refer to the amplifier data sheet for more information. Output common mode of the THS4131 is set by the voltage at pin 2. The COMMOUT pin of the ADS8422 is designed to source pin 2 of the THS4131. However to use this feature both the positive supply and negative supply rails must equal (|-VCC| = |+VCC|), absolutely.

Figure 29. Fully Differential Input Driver Circuit for Unipolar or Bipolar Signals





A. Input common-mode voltage (Vincm) range is restricted by the amplifier. Refer to the amplifier data sheet for more information. Output common mode of the THS4131 is set by the voltage at pin 2. The COMMOUT pin of the ADS8422 is designed to source pin 2 of the THS4131. However to use this feature both the positive supply and negative supply rails must equal (|-VCC| = |+VCC|), absolutely.

Figure 30. Single-Ended Input Driving Circuit for When Input is Unipolar or Bipolar



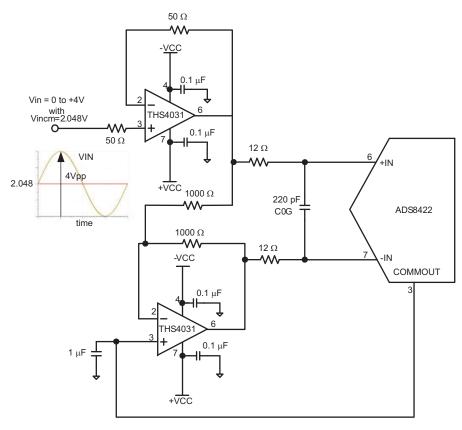
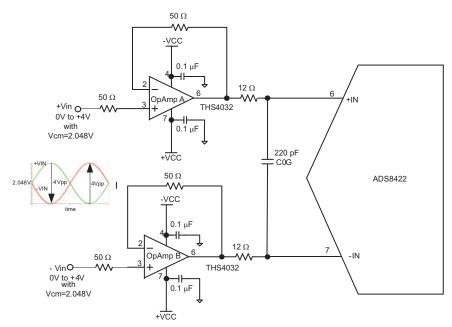


Figure 31. Single-Ended Driving Circuit for When Input is Single-Ended Unipolar and has Common-Mode of 2.048 V



A. This circuit is used to specify ADS8422 performance parameters listed in the data sheet.

Figure 32. Driver Circuit for When Input is Fully Differential Riding on Common-Mode of 2.048 V



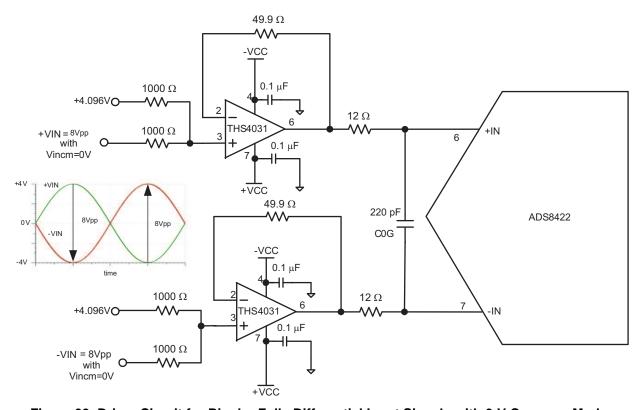


Figure 33. Driver Circuit for Bipolar Fully Differential Input Signals with 0-V Common-Mode

The input current on the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8422 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input voltage must be able to charge the input capacitance (30 pF) to a 16-bit settling level within the 70 ns acquisition time of the device. When the converter goes into hold mode, the input impedance is greater than 1  $G\Omega$ .

Care must be taken regarding the absolute analog input voltage. To maintain the linearity of the converter, both -IN and +IN inputs should be within the limits specified. Outside of these ranges, the converter linearity may not meet specifications. To minimize noise, low bandwidth input signals with low pass filters should be used.

Care should be taken to ensure that the output impedances of the sources driving the +IN and -IN inputs are matched. If this is not observed, the two inputs could have different settling times. This may result in offset error, gain error, and linearity error which change with temperature and input voltage.

When the converter enters hold mode, the voltage difference between the +IN and -IN inputs is captured on the internal capacitor array.

#### **DIGITAL INTERFACE**

## **Timing and Control**

See the timing diagrams for detailed information on timing signals and their requirements.

The ADS8422 uses an internal oscillator generated clock which controls the conversion rate and in turn the throughput of the converter. No external clock input is required.



Conversions are initiated by bringing the  $\overline{CONVST}$  pin low for a minimum of 20 ns (after the 20 ns minimum requirement has been met, the  $\overline{CONVST}$  pin can be brought high). The converter switches from sample to hold mode on the falling edge of the  $\overline{CONVST}$  command. A clean and low jitter falling edge of this signal is important to the performance of the converter. The BUSY pin is brought high immediately following  $\overline{CONVST}$  going low. BUSY stays high through the conversion process and returns low when the conversion has ended and data is available on the DB pins. Once the conversion is started, it cannot be stopped except with an asynchronous  $\overline{RESET}$  (or a logical  $\overline{PD1}$ ).

If  $\overline{\text{CONVST}}$  is detected high at the end of conversion, the device immediately enters sampling mode and the analog input is connected to the CDAC. Otherwise, the CDAC is connected to the analog input only when  $\overline{\text{CONVST}}$  goes high. The high duration of  $\overline{\text{CONVST}}$  should be at least 100 ns. There is no maximum high pulse duration specification for  $\overline{\text{CONVST}}$ .

## **Reading Data**

The ADS8422 outputs full parallel data in 2's complement format as shown in Table 1. The parallel output is active when  $\overline{CS}$  and  $\overline{RD}$  are both low. There is a minimal quiet zone requirement around the falling edge of  $\overline{CONVST}$ . This is 30 ns prior to the falling edge of  $\overline{CONVST}$  and 10 ns after the falling edge. No data read should be attempted within this zone. Any other combination of  $\overline{CS}$  and  $\overline{RD}$  three-states the parallel output. BYTE is used for multi-word read operation. BYTE is used whenever lower bits on the bus are output on the higher byte of the bus. Refer to Table 1 for ideal output codes.

**ANALOG VALUE** DESCRIPTION **DIGITAL OUTPUT 2'S COMPLIMENT** Full scale range  $2V_{ref}$ 2V<sub>ref</sub>)/65536 Least significant bit (LSB) **BINARY CODE HEX CODE** +Full scale  $(+V_{ref})$  -0111 1111 1111 1111 7FFF Midscale 0000 0000 0000 0000 0000 0 V 0 V – Midscale - 1 LSB 1111 1111 1111 1111 **FFFF** -Full scale  $-V_{ref}+$ 1000 0000 0000 0000 8000

Table 1. Ideal Input Voltages and Output Codes

The output data can be read as a full 16-bit word on pins DB15 - DB0 (MSB-LSB) if BYTE is low.

The result may also be read on an 8-bit bus for convenience. This is done by using only pins DB15-DB8. In this case two reads are necessary: the first as before, leaving BYTE low and reading the 8 most significant bits on pins DB15-DB8, then bringing BYTE high. When BYTE is high, the low bits (D7-D0) appear on pins DB15-DB8.

These multi-word read operations can be performed with a multiple active (toggling)  $\overline{RD}$  signal or with the  $\overline{RD}$  signal tied low for simplicity.

 DATA READ OUT

 BYTE
 PINS DB15-DB8
 PINS DB7-DB0

 High
 D7 - D0
 All One's

 Low
 D15 - D8
 D7 - D0

Table 2. Conversion Data Read Out

#### RESET

RESET/PD1 is an asynchronous active low input signal. Maximum RESET/PD1 low time is 0.5 μs to avoid ADC powerdown. Current conversion is aborted no later than 20 ns after the converter is in reset mode. The converter returns to normal operation mode no later than 20 ns after the RESET/PD1 input is brought high (see Figure 28).

The converter provides two power saving options: ADC powerdown (using pin 38, PD1) and analog output powerdown (PD2).



ADC powerdown is activated by asserting  $\overline{PD1}$  to 0 for longer than 1.5  $\mu$ s. If the signal  $\overline{PD1}$  is asserted 0 for less than 0.5  $\mu$ s, the ADC is only reset and any ongoing conversion aborted. See Figure 26. ADC operation can be resumed from ADC powerdown by de-asserting the  $\overline{PD1}$  pin. In ADC power-down mode, the analog outputs from the ADC(COMMOUT, REFOUT) are not powered down thereby reducing the power-on time.

Full chip power-down is activated by turning off the power supply or by asserting both,  $\overline{PD1} = 0$  and  $\overline{PD2} = 0$  for longer than 1.5 µs (see Figure 27). In this mode, even the analog outputs of the ADC (COMMOUT, REFOUT) are powered down thereby giving maximum power saving. Device operation can be resumed from full chip power-down by turning on the power supply or by deasserting both,  $\overline{PD1} = 1$  and  $\overline{PD2} = 1$ .

COMMAND **APPLICATION TIME POWER WHEN APPLIED RESUME TIME**  $\overline{RESET/PD1} = 0$ 20 ns No change 20 ns  $\overline{PD1} = 0, \overline{PD2} = 1$ 1.5 µs 17mW 5 μs  $\overline{PD1} = \overline{PD2} = 0$  $1.5 \, \mu s$  $40 \mu W$ 25 ms  $\overline{PD1} = 1, \overline{PD2} = 0$ Reserved - Do not use this combination

Table 3. Effects of RESET, PD1, and PD2

#### LAYOUT

For optimum performance, care should be taken with the physical layout of the ADS8422 circuitry.

As the ADS8422 offers single-supply operation, it is often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to achieve good performance from the converter.

The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections, and digital inputs that occur just prior to latching the output of the analog comparator. Thus, driving any single conversion for an n-clock SAR converter, there are n *windows* in which large external transient voltages can affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, or high power devices. The 50 ns period before BUSY falls should be kept free of supply glitches.

The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event.

On average, the ADS8422 draws very little current from an external reference as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A 0.1- $\mu$ F bypass capacitor is recommended from pin 1 directly to REFM (pin 48). REFM and AGND should be shorted on the same ground plane underneath the device.

The AGND, BDGND, and AGND pins should be connected to a clean ground point. In all cases, this should be the *analog* ground. Avoid connections which are too close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout consists of an analog ground plane dedicated to the converter and associated analog circuitry.

As with the AGND connections, +VA and +VAREG should be connected to their respective power supply planes or traces that are separate from the connection for digital logic, until they are connected at the power entry point. Power to the ADS8422 should be clean and well bypassed. A 0.1- $\mu$ F ceramic bypass capacitor should be placed as close to the device as possible. See Table 4 for capacitor placement. In addition, a 1- $\mu$ F to 10- $\mu$ F capacitor is recommended. In some situations, additional bypassing may be required, such as a 100- $\mu$ F electrolytic capacitor or even a Pi filter made up of inductors and capacitors — all designed to essentially low-pass filter the +5-V supply, thus removing the high frequency noise.

**Table 4. Power Supply Decoupling Capacitor Placement** 

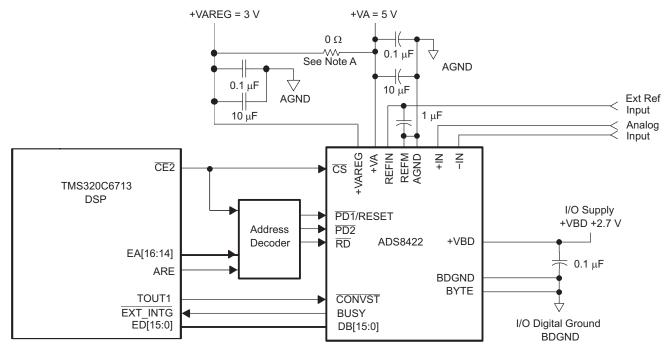
POWER SUPPLY PLANE	CONVERTER ANALOG SIDE	CONVERTER
SUPPLY PINS	CONVENTER ANALOG SIDE	DIGITAL SIDE
Pin pairs that require shortest path to decoupling capacitors	(4,5), (9,8), (10,12), (13,15), (43,44), (46,45)	(24,25), (34,35)



#### **APPLICATION INFORMATION**

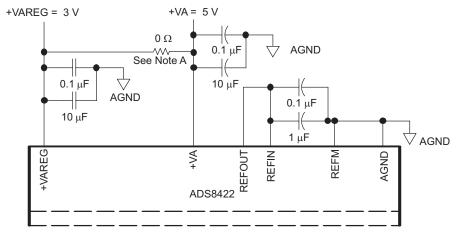
#### ADS8422 TO A HIGH PERFORMANCE DSP INTERFACE

Figure 34 shows a parallel interface between the ADS8422 and a Texas instruments high performance DSP such as the TMS320C6713 using the full 16-bit bus. The ADS8422 is mapped onto the CE2 memory space of the TMS320C6713 DSP. The read and reset signals are generated by using a 3-to-8 decoder. A read operation from the address 0xA000C000 generates a pulse on the RD pin of the data converter, wheras a read operation form word address 0xA0014000 generates a pulse on the RESET/PD1 pin. The CE2 signal of the DSP acts as CS (chip select) for the converter. As the TMS320C6713 features a 32-bit external memory interface, the BYTE input of the converter can be tied permanently low, disabling the foldback of the data bus. The BUSY signal of the ADS8422 is applied to the EXT\_INT6 interrupt input of the DSP, enabling the EDMA controller to react on the falling edge of this signal and to collect the conversion result. The TOUT1 (timer out 1) pin of the TMS320C6713 is used to source the CONVST signal of the converter.



A. This resistor (0  $\Omega$ ) can be installed to use the same 5-V supply.

Figure 34. ADS8422 Application Circuitry



A. This resistor (0  $\Omega$ ) can be installed to use the same 5-V supply.

Figure 35. ADS8422 Using Internal Reference

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#### PACKAGING INFORMATION

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
ADS8422IBPFBR	Active	Production	TQFP (PFB)   48	1000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B
ADS8422IBPFBR.A	Active	Production	TQFP (PFB)   48	1000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B
ADS8422IBPFBT	Active	Production	TQFP (PFB)   48	250   SMALL T&R	Yes	Call TI	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B
ADS8422IBPFBT.A	Active	Production	TQFP (PFB)   48	250   SMALL T&R	Yes	Call TI	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I B
ADS8422IPFBR	Active	Production	TQFP (PFB)   48	1000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I
ADS8422IPFBR.A	Active	Production	TQFP (PFB)   48	1000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS 8422I

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



# **PACKAGE OPTION ADDENDUM**

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Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

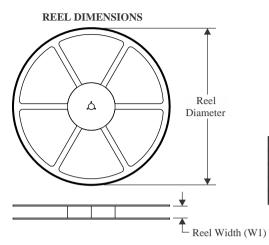
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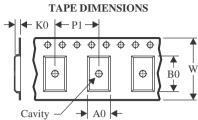
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# **PACKAGE MATERIALS INFORMATION**

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## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS8422IBPFBR	TQFP	PFB	48	1000	330.0	16.4	9.6	9.6	1.5	12.0	16.0	Q2
ADS8422IPFBR	TQFP	PFB	48	1000	330.0	16.4	9.6	9.6	1.5	12.0	16.0	Q2



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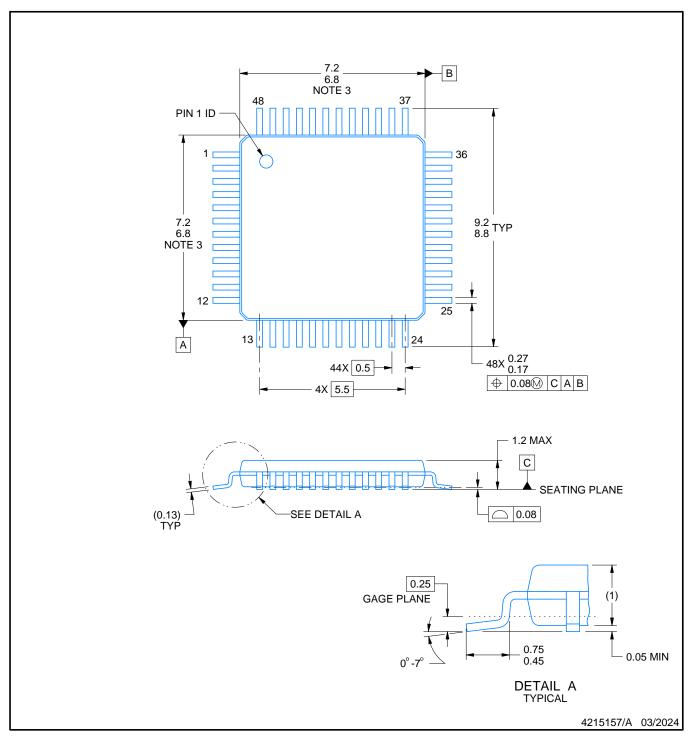


## \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS8422IBPFBR	TQFP	PFB	48	1000	350.0	350.0	43.0
ADS8422IPFBR	TQFP	PFB	48	1000	350.0	350.0	43.0



PLASTIC QUAD FLATPACK

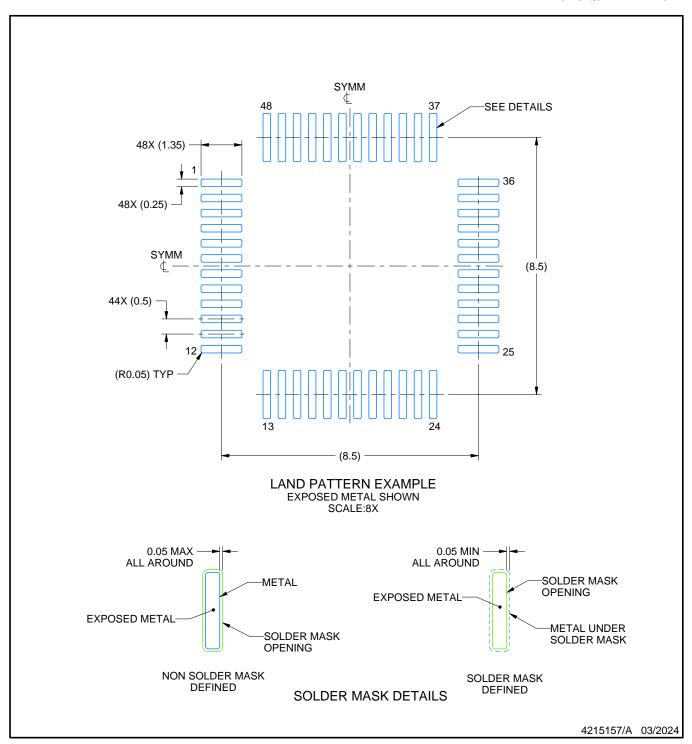


#### NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
   This drawing is subject to change without notice.
   Reference JEDEC registration MS-026.



PLASTIC QUAD FLATPACK

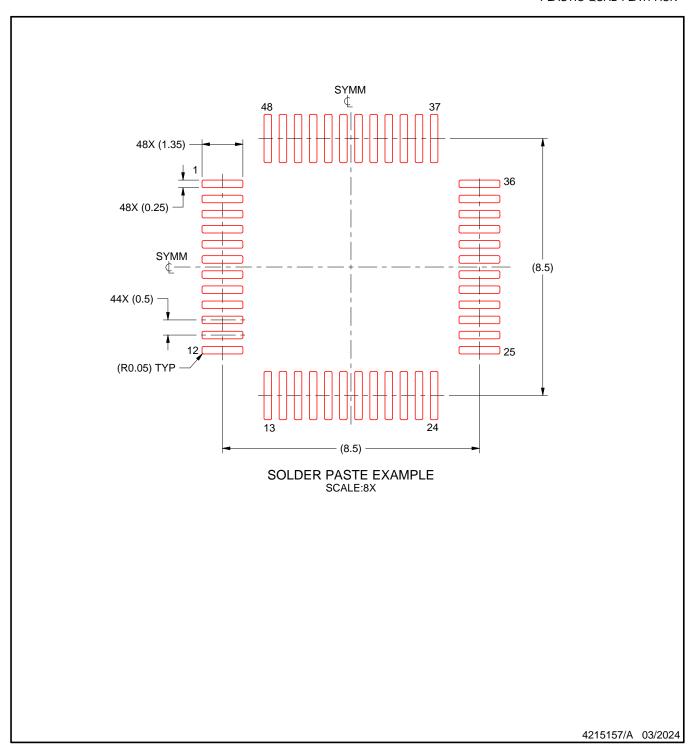


NOTES: (continued)

- 4. Publication IPC-7351 may have alternate designs.
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



PLASTIC QUAD FLATPACK



NOTES: (continued)



<sup>6.</sup> Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

<sup>7.</sup> Board assembly site may have different recommendations for stencil design.

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