

To all our customers

---

## **Regarding the change of names mentioned in the document, such as Hitachi Electric and Hitachi XX, to Renesas Technology Corp.**

---

The semiconductor operations of Mitsubishi Electric and Hitachi were transferred to Renesas Technology Corporation on April 1st 2003. These operations include microcomputer, logic, analog and discrete devices, and memory chips other than DRAMs (flash memory, SRAMs etc.) Accordingly, although Hitachi, Hitachi, Ltd., Hitachi Semiconductors, and other Hitachi brand names are mentioned in the document, these names have in fact all been changed to Renesas Technology Corp. Thank you for your understanding. Except for our corporate trademark, logo and corporate statement, no changes whatsoever have been made to the contents of the document, and these changes do not constitute any alteration to the contents of the document itself.

Renesas Technology Home Page: <http://www.renesas.com>

Renesas Technology Corp.  
Customer Support Dept.  
April 1, 2003

## Cautions

Keep safety first in your circuit designs!

1. Renesas Technology Corporation puts the maximum effort into making semiconductor products better and more reliable, but there is always the possibility that trouble may occur with them. Trouble with semiconductors may lead to personal injury, fire or property damage.

Remember to give due consideration to safety when making your circuit designs, with appropriate measures such as (i) placement of substitutive, auxiliary circuits, (ii) use of nonflammable material or (iii) prevention against any malfunction or mishap.

Notes regarding these materials

1. These materials are intended as a reference to assist our customers in the selection of the Renesas Technology Corporation product best suited to the customer's application; they do not convey any license under any intellectual property rights, or any other rights, belonging to Renesas Technology Corporation or a third party.
2. Renesas Technology Corporation assumes no responsibility for any damage, or infringement of any third-party's rights, originating in the use of any product data, diagrams, charts, programs, algorithms, or circuit application examples contained in these materials.
3. All information contained in these materials, including product data, diagrams, charts, programs and algorithms represents information on products at the time of publication of these materials, and are subject to change by Renesas Technology Corporation without notice due to product improvements or other reasons. It is therefore recommended that customers contact Renesas Technology Corporation or an authorized Renesas Technology Corporation product distributor for the latest product information before purchasing a product listed herein.  
The information described here may contain technical inaccuracies or typographical errors.  
Renesas Technology Corporation assumes no responsibility for any damage, liability, or other loss rising from these inaccuracies or errors.  
Please also pay attention to information published by Renesas Technology Corporation by various means, including the Renesas Technology Corporation Semiconductor home page (<http://www.renesas.com>).
4. When using any or all of the information contained in these materials, including product data, diagrams, charts, programs, and algorithms, please be sure to evaluate all information as a total system before making a final decision on the applicability of the information and products. Renesas Technology Corporation assumes no responsibility for any damage, liability or other loss resulting from the information contained herein.
5. Renesas Technology Corporation semiconductors are not designed or manufactured for use in a device or system that is used under circumstances in which human life is potentially at stake. Please contact Renesas Technology Corporation or an authorized Renesas Technology Corporation product distributor when considering the use of a product contained herein for any specific purposes, such as apparatus or systems for transportation, vehicular, medical, aerospace, nuclear, or undersea repeater use.
6. The prior written approval of Renesas Technology Corporation is necessary to reprint or reproduce in whole or in part these materials.
7. If these products or technologies are subject to the Japanese export control restrictions, they must be exported under a license from the Japanese government and cannot be imported into a country other than the approved destination.  
Any diversion or reexport contrary to the export control laws and regulations of Japan and/or the country of destination is prohibited.
8. Please contact Renesas Technology Corporation for further details on these materials or the products contained therein.

---

# HD404369 Series



Rev. 6.0  
Sept. 1998

---

## Description

The HD404369 Series is a 4-bit HMCS400-Series microcomputer designed to increase program productivity and also incorporate large-capacity memory. Each microcomputer has an A/D converter, input capture timer, 32-kHz oscillator for clock, and four low-power dissipation modes.

The HD404369 Series includes nine chips: the HD404364, HD40A4364 with 4-kword ROM; the HD404368, HD40A4368 with 8-kword ROM; the HD4043612, HD40A43612 with 12-kword ROM; the HD404369, HD40A4369 with 16-kword ROM; the HD407A4369 with 16-kword PROM.

The HD40A4364, HD40A4368, HD40A43612, HD40A4369, and HD407A4369 are high speed versions (minimum instruction cycle time: 0.47  $\mu$ s).

The HD407A4369 is a PROM version (ZTAT™ microcomputer). A program can be written to the PROM by a PROM writer, which can dramatically shorten system development periods and smooth the process from debugging to mass production. (The ZTAT™ version is 27256-compatible.)

## Features

- 512-digit  $\times$  4-bit RAM
- 54 I/O pins
  - One input-only pin
  - 53 input/output pins: 8 pins are intermediate-voltage NMOS open drain with high-current pins (15 mA, max.)
- On-chip A/D converter (8-bit  $\times$  12-channel)
  - Low power voltage 2.7 V to 6.0 V
- Three timers
  - One event counter input
  - One timer output
  - One input capture timer
- Eight-bit clock-synchronous serial interface (1 channel)
- Alarm output

---

## HD404369 Series

---

- Built-in oscillators
  - Ceramic oscillator or crystal
  - External clock drive is also possible
  - Subclock: 32.768-kHz crystal oscillator
- Seven interrupt sources
  - Two by external sources
  - Three by timers
  - One by A/D converter
  - One by serial interface
- Four low-power dissipation modes
  - Standby mode
  - Stop mode
  - Watch mode
  - Subactive mode
- Instruction cycle time
  - 0.47  $\mu\text{s}$  ( $f_{\text{OSC}} = 8.5 \text{ MHz}$ , 1/4 division ratio):  
HD40A4364, HD40A4368, HD40A43612, HD40A4369, HD407A4369
  - 0.8  $\mu\text{s}$  ( $f_{\text{OSC}} = 5 \text{ MHz}$ , 1/4 division ratio):  
HD404364, HD404368, HD4043612, HD404369
  - 1/4, 1/8, 1/16, 1/32 system clock division ratio can be selecte

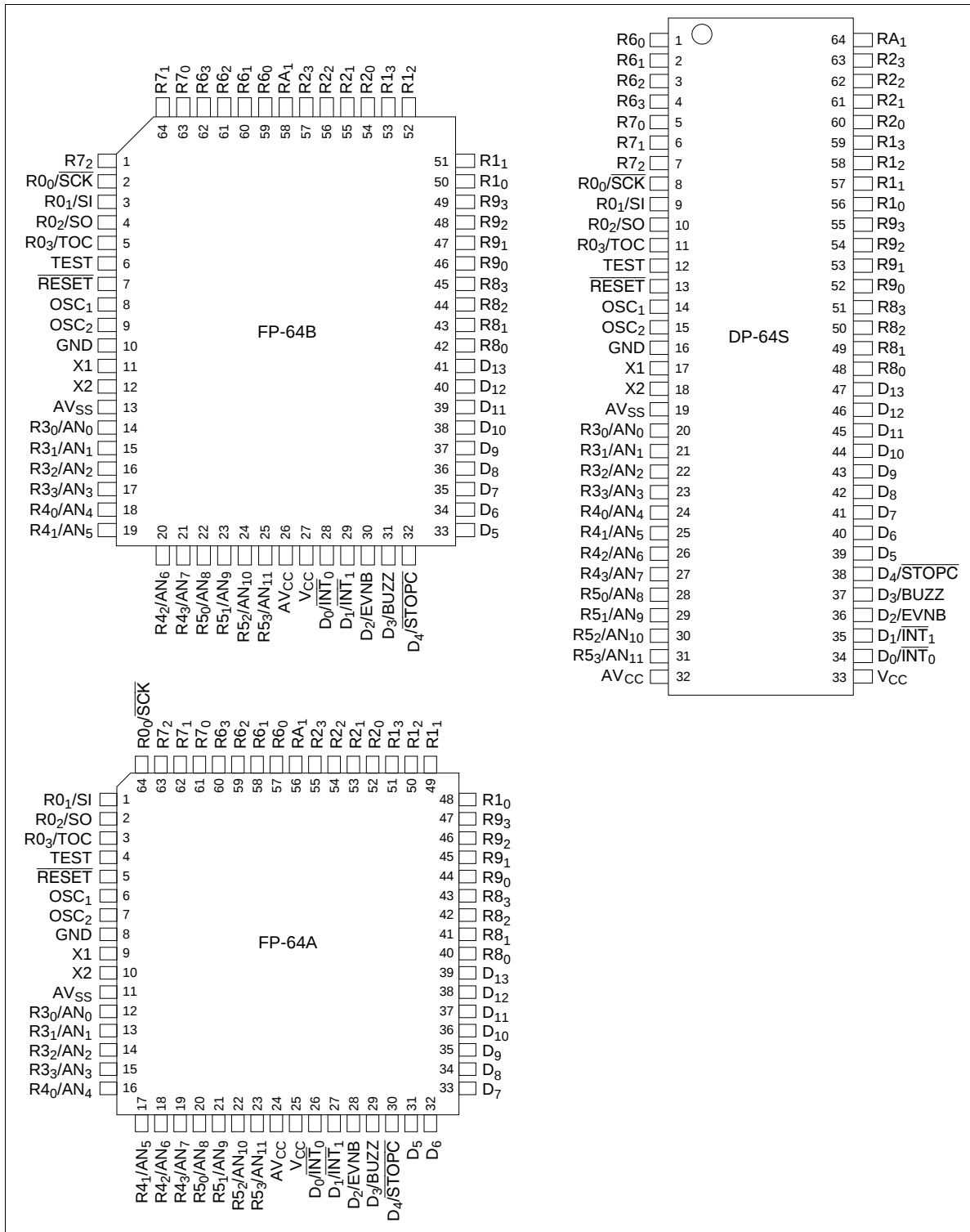
## HD404369 Series

### Ordering Information

| Type     | Instruction Cycle Time                                 | Product Name | Model Name  | ROM (Words) | Package |
|----------|--------------------------------------------------------|--------------|-------------|-------------|---------|
| Mask ROM | Standard version ( $f_{osc} = 5 \text{ MHz}$ )         | HD404364     | HD404364S   | 4,096       | DP-64S  |
|          |                                                        |              | HD404364F   |             | FP-64B  |
|          |                                                        |              | HD404364H   |             | FP-64A  |
|          |                                                        | HD404368     | HD404368S   | 8,192       | DP-64S  |
|          |                                                        |              | HD404368F   |             | FP-64B  |
|          |                                                        |              | HD404368H   |             | FP-64A  |
|          |                                                        | HD4043612    | HD4043612S  | 12,288      | DP-64S  |
|          |                                                        |              | HD4043612F  |             | FP-64B  |
|          |                                                        |              | HD4043612H  |             | FP-64A  |
|          |                                                        | HD404369     | HD404369S   | 16,384      | DP-64S  |
|          |                                                        |              | HD404369F   |             | FP-64B  |
|          |                                                        |              | HD404369H   |             | FP-64A  |
|          | High speed versions<br>( $f_{osc} = 8.5 \text{ MHz}$ ) | HD40A4364    | HD40A4364S  | 4,096       | DP-64S  |
|          |                                                        |              | HD40A4364F  |             | FP-64B  |
|          |                                                        |              | HD40A4364H  |             | FP-64A  |
|          |                                                        | HD40A4368    | HD40A4368S  | 8,192       | DP-64S  |
|          |                                                        |              | HD40A4368F  |             | FP-64B  |
|          |                                                        |              | HD40A4368H  |             | FP-64A  |
|          |                                                        | HD40A43612   | HD40A43612S | 12,288      | DP-64S  |
|          |                                                        |              | HD40A43612F |             | FP-64B  |
|          |                                                        |              | HD40A43612H |             | FP-64A  |
|          |                                                        | HD40A4369    | HD40A4369S  | 16,384      | DP-64S  |
|          |                                                        |              | HD40A4369F  |             | FP-64B  |
|          |                                                        |              | HD40A4369H  |             | FP-64A  |
| ZTAT™    | $(f_{osc} = 8.5 \text{ MHz})$                          | HD407A4369   | HD407A4369S | 16,384      | DP-64S  |
|          |                                                        |              | HD407A4369F |             | FP-64B  |
|          |                                                        |              | HD407A4369H |             | FP-64A  |

# HD404369 Series

## Pin Arrangement



**Pin Description**

| Item       | Symbol                                                                 | Pin Number               |                                   |                                   | I/O | Function                                                                                                                                                                 |
|------------|------------------------------------------------------------------------|--------------------------|-----------------------------------|-----------------------------------|-----|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|            |                                                                        | DP-64S                   | FP-64B                            | FP-64A                            |     |                                                                                                                                                                          |
| Power      | $V_{CC}$                                                               | 33                       | 27                                | 25                                |     | Applies power voltage                                                                                                                                                    |
| Supply     | GND                                                                    | 16                       | 10                                | 8                                 |     | Connected to ground                                                                                                                                                      |
| Test       | TEST                                                                   | 12                       | 6                                 | 4                                 | I   | Cannot be used in user applications. Connect this pin to GND.                                                                                                            |
| Reset      | $\overline{RESET}$                                                     | 13                       | 7                                 | 5                                 | I   | Resets the MCU                                                                                                                                                           |
| Oscillator | OSC <sub>1</sub>                                                       | 14                       | 8                                 | 6                                 | I   | Input/output pin for the internal oscillator. Connect these pins to the ceramic oscillator or crystal oscillator, or OSC <sub>1</sub> to an external oscillator circuit. |
|            | OSC <sub>2</sub>                                                       | 15                       | 9                                 | 7                                 | O   |                                                                                                                                                                          |
|            | X1                                                                     | 17                       | 11                                | 9                                 | I   | Used with a 32.768-kHz crystal oscillator for clock purposes                                                                                                             |
|            | X2                                                                     | 18                       | 12                                | 10                                | O   |                                                                                                                                                                          |
|            |                                                                        |                          |                                   |                                   |     |                                                                                                                                                                          |
| Port       | D <sub>0</sub> –D <sub>13</sub>                                        | 34–47                    | 28–41                             | 26–39                             | I/O | Input/output pins consisting of standard voltage pins addressed individually by bits                                                                                     |
|            | RA <sub>1</sub>                                                        | 64                       | 58                                | 56                                | I   | One-bit standard-voltage input port pin                                                                                                                                  |
|            | R0 <sub>0</sub> –R0 <sub>3</sub> ,<br>R3 <sub>0</sub> –R9 <sub>3</sub> | 1–11,<br>20–31,<br>48–55 | 1–5,<br>14–25,<br>42–49,<br>59–64 | 1–3,<br>12–23,<br>40–47,<br>57–64 | I/O | Four-bit input/output pins consisting of standard voltage pins                                                                                                           |
|            | R1 <sub>0</sub> –R2 <sub>3</sub>                                       | 56–63                    | 50–57                             | 48–55                             | I/O | Four-bit input/output pins consisting of intermediate voltage pins                                                                                                       |
|            |                                                                        |                          |                                   |                                   |     |                                                                                                                                                                          |
| Interrupt  | $\overline{INT_0}$ , $\overline{INT_1}$                                | 34, 35                   | 28, 29                            | 26, 27                            | I   | Input pins for external interrupts                                                                                                                                       |
| Stop clear | $\overline{STOPC}$                                                     | 38                       | 32                                | 30                                | I   | Input pin for transition from stop mode to active mode                                                                                                                   |
| Serial     | $\overline{SCK}$                                                       | 8                        | 2                                 | 64                                | I/O | Serial interface clock input/output pin                                                                                                                                  |
| Interface  | SI                                                                     | 9                        | 3                                 | 1                                 | I   | Serial interface receive data input pin                                                                                                                                  |
|            | SO                                                                     | 10                       | 4                                 | 2                                 | O   | Serial interface transmit data output pin                                                                                                                                |
| Timer      | TOC                                                                    | 11                       | 5                                 | 3                                 | O   | Timer output pin                                                                                                                                                         |
|            | EVNB                                                                   | 36                       | 30                                | 28                                | I   | Event count input pin                                                                                                                                                    |
| Alarm      | BUZZ                                                                   | 37                       | 31                                | 29                                | O   | Square waveform output pin                                                                                                                                               |

---

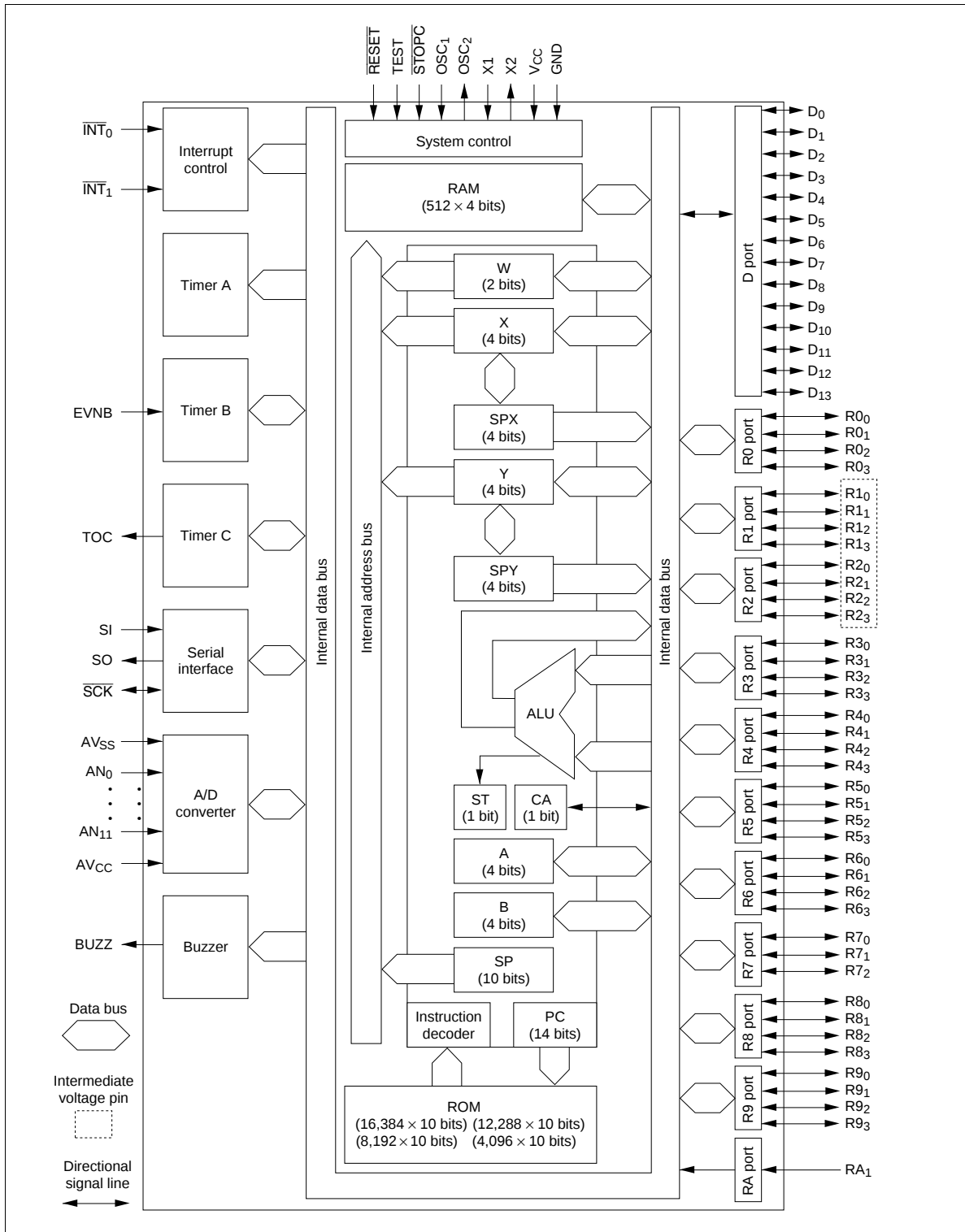
## HD404369 Series

---

### Pin Description (cont)

| Item          | Symbol             | Pin Number |        |        | I/O | Function                                                                                                                                                                                                                                                                                                                                                                                                         |
|---------------|--------------------|------------|--------|--------|-----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|               |                    | DP-64S     | FP-64B | FP-64A |     |                                                                                                                                                                                                                                                                                                                                                                                                                  |
| A/D converter | $AV_{CC}$          | 32         | 26     | 24     |     | Power supply for the A/D converter. Connect this pin as close as possible to the $V_{CC}$ pin and at the same voltage as $V_{CC}$ . If the power supply voltage to be used for the A/D converter is not equal to $V_{CC}$ , connect a 0.1- $\mu$ F bypass capacitor between the $AV_{CC}$ and $AV_{SS}$ pins. (However, this is not necessary when the $AV_{CC}$ pin is directly connected to the $V_{CC}$ pin.) |
|               | $AV_{SS}$          | 19         | 13     | 11     |     | Ground for the A/D converter. Connect this pin as close as possible to GND at the same voltage as GND.                                                                                                                                                                                                                                                                                                           |
|               | $AN_0$ – $AN_{11}$ | 20–31      | 14–25  | 12–23  | I   | Analog input pins for the A/D converter                                                                                                                                                                                                                                                                                                                                                                          |

# Block Diagram



## HD404369 Series

### Memory Map

#### ROM Memory Map

The ROM memory map is shown in figure 1 and described below.

**Vector Address Area (\$0000–\$000F):** Reserved for JMPL instructions that branch to the start addresses of the reset and interrupt routines. After MCU reset or an interrupt, program execution continues from the vector address.

**Zero-Page Subroutine Area (\$0000–\$003F):** Reserved for subroutines. The program branches to a subroutine in this area in response to the CAL instruction.

**Pattern Area (\$0000–\$0FFF):** Contains ROM data that can be referenced with the P instruction.

**Program Area (\$0000–\$0FFF (HD404364, HD40A4364), \$0000–\$1FFF (HD404368, HD40A4368), \$0000–\$2FFF (HD4043612, HD40A43612), \$0000–\$3FFF (HD404369, HD40A4369, HD407A4369)):** The entire ROM area can be used for program coding.

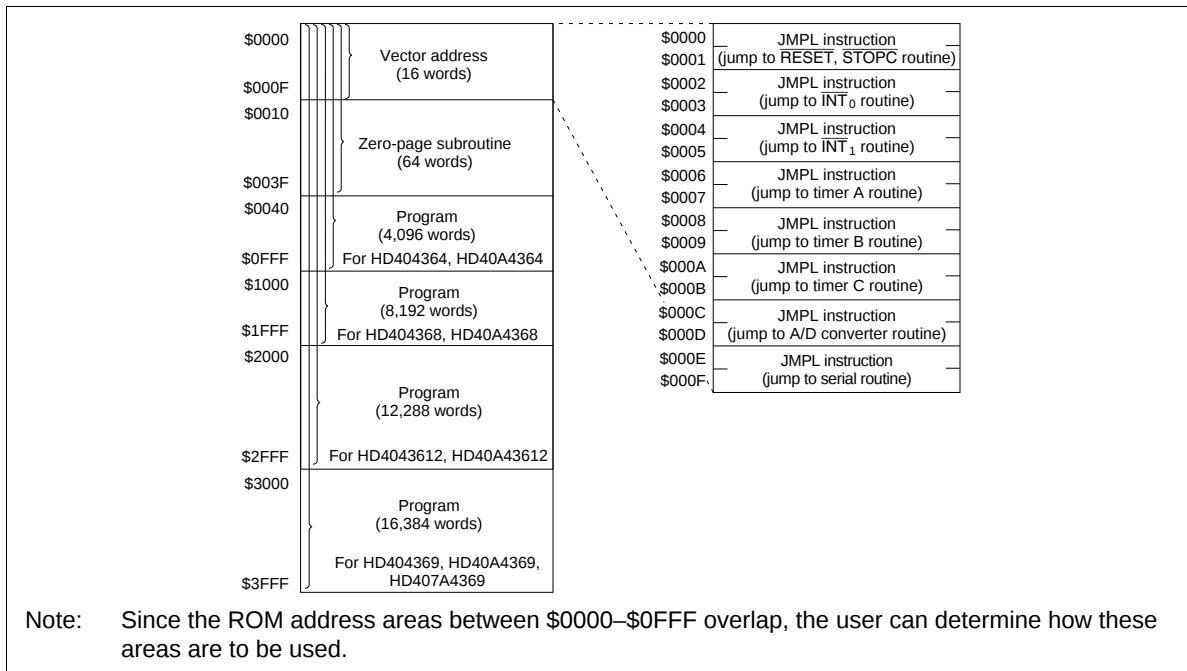


Figure 1 ROM Memory Map

#### RAM Memory Map

The MCU contains 512-digit  $\times$  4 bit RAM areas. These RAM areas consist of a memory register area, a data area, and a stack area. In addition, an interrupt control bits area, special function register area, and register flag area are mapped onto the same RAM memory space labeled as a RAM-mapped register area. The RAM memory map is shown in figure 2 and described below.

## RAM Memory Map

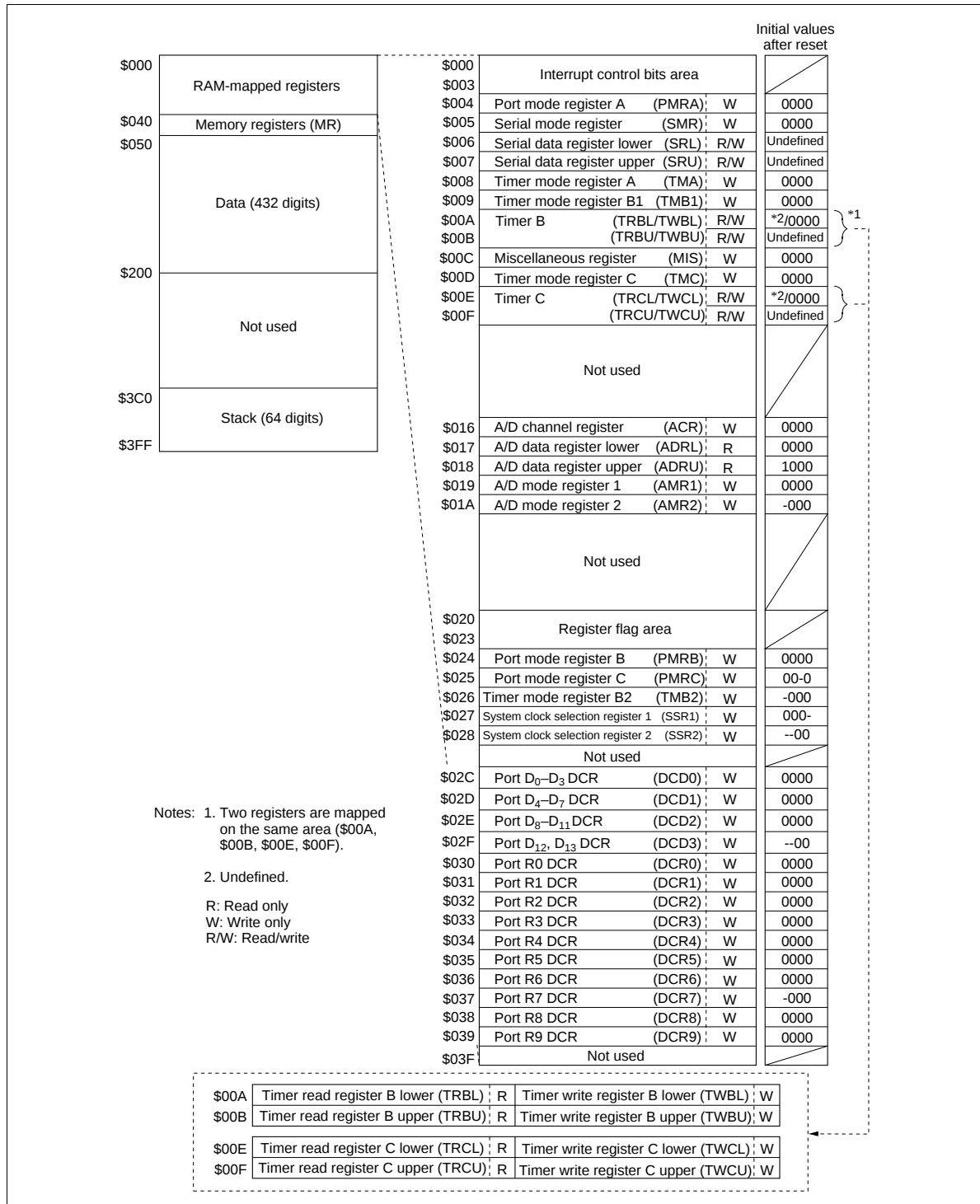


Figure 2 RAM Memory Map

---

## HD404369 Series

---

### RAM-Mapped Register Area (\$000–\$03F):

- Interrupt Control Bits Area (\$000–\$003)

This area is used for interrupt control bits (figure 3). These bits can be accessed only by RAM bit manipulation instructions (SEM/SEMD, REM/REMD, and TM/TMD). However, note that not all the instructions can be used for each bit. Limitations on using the instructions are shown in figure 4.

- Special Function Register Area (\$004–\$01F, \$024–\$03F)

This area is used as mode registers and data registers for external interrupts, serial interface, timer/counters, A/D converter, and as data control registers for I/O ports. The structure is shown in figures 2 and 5. These registers can be classified into three types: write-only (W), read-only (R), and read/write (R/W). RAM bit manipulation instructions cannot be used for these registers.

- Register Flag Area (\$020–\$023)

This area is used for the DTON, WDON, and other register flags and interrupt control bits (figure 3). These bits can be accessed only by RAM bit manipulation instructions (SEM/SEMD, REM/REMD, and TM/TMD). However, note that not all the instructions can be used for each bit. Limitations on using the instructions are shown in figure 4.

**Memory Register (MR) Area (\$040–\$04F):** Consisting of 16 addresses, this area (MR0–MR15) can be accessed by register-register instructions (LAMR and XMRA). The structure is shown in figure 6.

### Data Area (\$050–\$1FF)

**Stack Area (\$3C0–\$3FF):** Used for saving the contents of the program counter (PC), status flag (ST), and carry flag (CA) at subroutine call (CAL or CALL instruction) and for interrupts. This area can be used as a 16-level nesting subroutine stack in which one level requires four digits. The data to be saved and the save conditions are shown in figure 6.

The program counter is restored by either the RTN or RTNI instruction, but the status and carry flags can only be restored by the RTNI instruction. Any unused space in this area is used for data storage.

|       | Bit 3                              | Bit 2                              | Bit 1                              | Bit 0                              |
|-------|------------------------------------|------------------------------------|------------------------------------|------------------------------------|
| \$000 | IM0<br>(IM of $\overline{INT_0}$ ) | IF0<br>(IF of $\overline{INT_0}$ ) | RSP<br>(Reset SP bit)              | IE<br>(Interrupt enable flag)      |
| \$001 | IMTA<br>(IM of timer A)            | IFTA<br>(IF of timer A)            | IM1<br>(IM of $\overline{INT_1}$ ) | IF1<br>(IF of $\overline{INT_1}$ ) |
| \$002 | IMTC<br>(IM of timer C)            | IFTC<br>(IF of timer C)            | IMTB<br>(IM of timer B)            | IFTB<br>(IF of timer B)            |
| \$003 | IMS<br>(IM of serial)              | IFS<br>(IF of serial)              | IMAD<br>(IM of A/D)                | IFAD<br>(IF of A/D)                |

Interrupt control bits area

|       | Bit 3                             | Bit 2                              | Bit 1                              | Bit 0                               |
|-------|-----------------------------------|------------------------------------|------------------------------------|-------------------------------------|
| \$020 | DTON<br>(Direct transfer on flag) | ADSF<br>(A/D start flag)           | WDON<br>(Watchdog on flag)         | LSON<br>(Low speed on flag)         |
| \$021 | RAME<br>(RAM enable flag)         | IAOF<br>(I <sub>AD</sub> off flag) | ICEF<br>(Input capture error flag) | ICSF<br>(Input capture status flag) |
| \$022 | Not used                          |                                    |                                    |                                     |
| \$023 |                                   |                                    |                                    |                                     |

Register flag area

IF: Interrupt request flag  
IM: Interrupt mask  
IE: Interrupt enable flag  
SP: Stack pointer

**Figure 3 Configuration of Interrupt Control Bits and Register Flag Areas**

|          | SEM/SEMD                    | REM/REMD     | TM/TMD    |
|----------|-----------------------------|--------------|-----------|
| IE       | Allowed                     | Allowed      | Allowed   |
| IM       |                             |              |           |
| LSON     |                             |              |           |
| IAOF     |                             |              |           |
| IF       | Not executed                | Allowed      | Allowed   |
| ICSF     |                             |              |           |
| ICEF     |                             |              |           |
| RAME     |                             |              |           |
| RSP      | Not executed                | Allowed      | Inhibited |
| WDON     | Allowed                     | Not executed | Inhibited |
| ADSF     | Allowed                     | Inhibited    | Allowed   |
| DTON     | Not executed in active mode | Allowed      | Allowed   |
|          | Used in subactive mode      |              |           |
| Not used | Not executed                | Not executed | Inhibited |

Note: WDON is reset by MCU reset or by  $\overline{STOPC}$  enable for stop mode cancellation.  
The REM or REMD instruction must not be executed for ADSF during A/D conversion.  
DTON is always reset in active mode.  
If the TM or TMD instruction is executed for the inhibited bits or non-existing bits, the value in ST becomes invalid.

**Figure 4 Usage Limitations of RAM Bit Manipulation Instructions**

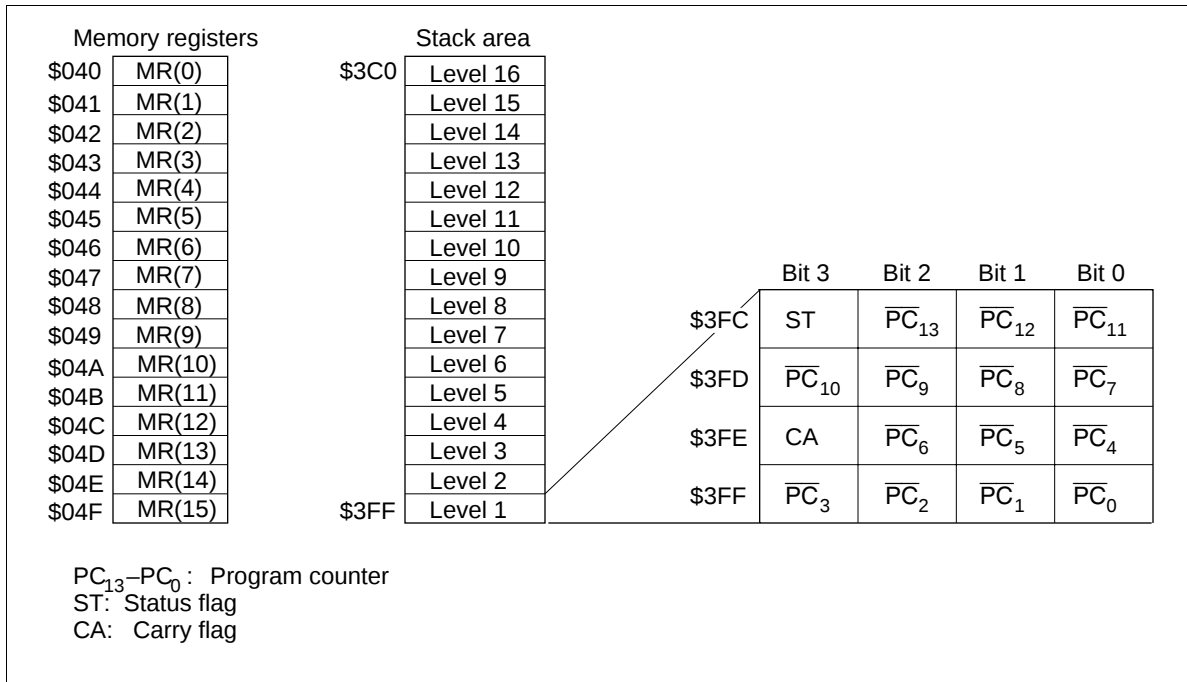
## HD404369 Series

|                 | Bit 3                              | Bit 2                                 | Bit 1                               | Bit 0                            |
|-----------------|------------------------------------|---------------------------------------|-------------------------------------|----------------------------------|
| \$000           | Interrupt control bits area        |                                       |                                     |                                  |
| \$003           |                                    |                                       |                                     |                                  |
| PMRA \$004      | D <sub>3</sub> /BUZZ               | R0 <sub>3</sub> /TOC                  | R0 <sub>1</sub> /SI                 | R0 <sub>2</sub> /SO              |
| SMR \$005       | R0 <sub>0</sub> /SCK               | Serial transmit clock speed selection |                                     |                                  |
| SRL \$006       | Serial data register (lower digit) |                                       |                                     |                                  |
| SRU \$007       | Serial data register (upper digit) |                                       |                                     |                                  |
| TMA \$008       | *1                                 | Clock source selection (timer A)      |                                     |                                  |
| TMB1 \$009      | *2                                 | Clock source selection (timer B)      |                                     |                                  |
| TRBL/TWBL \$00A | Timer B register (lower digit)     |                                       |                                     |                                  |
| TRBU/TWBU \$00B | Timer B register (upper digit)     |                                       |                                     |                                  |
| MIS \$00C       | *3                                 | SO PMOS control                       | Interrupt frame period selection    |                                  |
| TMC \$00D       | *2                                 | Clock source selection (timer C)      |                                     |                                  |
| TRCL/TWCL \$00E | Timer C register (lower digit)     |                                       |                                     |                                  |
| TRCU/TWCU \$00F | Timer C register (upper digit)     |                                       |                                     |                                  |
|                 | Not used                           |                                       |                                     |                                  |
| ACR \$016       | Analog channel selection           |                                       |                                     |                                  |
| ADRL \$017      | A/D data register (lower digit)    |                                       |                                     |                                  |
| ADRU \$018      | A/D data register (upper digit)    |                                       |                                     |                                  |
| AMR1\$019       | R3 <sub>3</sub> /AN <sub>3</sub>   | R3 <sub>2</sub> /AN <sub>2</sub>      | R3 <sub>1</sub> /AN <sub>1</sub>    | R3 <sub>0</sub> /AN <sub>0</sub> |
| AMR2 \$01A      | Not used                           | R5/AN <sub>8</sub> –AN <sub>11</sub>  | R4/AN <sub>4</sub> –AN <sub>7</sub> | *4                               |
|                 | Not used                           |                                       |                                     |                                  |
| \$020           | Register flag area                 |                                       |                                     |                                  |
| \$023           |                                    |                                       |                                     |                                  |
| PMRB \$024      | D <sub>4</sub> /STOPC              | D <sub>2</sub> /EVNB                  | D <sub>1</sub> /INT <sub>1</sub>    | D <sub>0</sub> /INT <sub>0</sub> |
| PMRC \$025      | Buzzer output                      |                                       | *5                                  | *6                               |
| TMB2 \$026      | Not used                           | *7                                    | EVNB detection edge selection       |                                  |
| SSR1 \$027      | *8                                 | *9                                    | Clock select                        | Not used                         |
| SSR2 \$028      | Not used                           |                                       | Clock division ratio selection      |                                  |
|                 | Not used                           |                                       |                                     |                                  |
| DCD0 \$02C      | Port D <sub>3</sub> DCD            | Port D <sub>2</sub> DCD               | Port D <sub>1</sub> DCD             | Port D <sub>0</sub> DCD          |
| DCD1 \$02D      | Port D <sub>7</sub> DCD            | Port D <sub>6</sub> DCD               | Port D <sub>5</sub> DCD             | Port D <sub>4</sub> DCD          |
| DCD2 \$02E      | Port D <sub>11</sub> DCD           | Port D <sub>10</sub> DCD              | Port D <sub>9</sub> DCD             | Port D <sub>8</sub> DCD          |
| DCD3 \$02F      | Not used                           |                                       | Port D <sub>13</sub> DCD            | Port D <sub>12</sub> DCD         |
| DCR0 \$030      | Port R0 <sub>3</sub> DCR           | Port R0 <sub>2</sub> DCR              | Port R0 <sub>1</sub> DCR            | Port R0 <sub>0</sub> DCR         |
| DCR1 \$031      | Port R1 <sub>3</sub> DCR           | Port R1 <sub>2</sub> DCR              | Port R1 <sub>1</sub> DCR            | Port R1 <sub>0</sub> DCR         |
| DCR2 \$032      | Port R2 <sub>3</sub> DCR           | Port R2 <sub>2</sub> DCR              | Port R2 <sub>1</sub> DCR            | Port R2 <sub>0</sub> DCR         |
| DCR3 \$033      | Port R3 <sub>3</sub> DCR           | Port R3 <sub>2</sub> DCR              | Port R3 <sub>1</sub> DCR            | Port R3 <sub>0</sub> DCR         |
| DCR4 \$034      | Port R4 <sub>3</sub> DCR           | Port R4 <sub>2</sub> DCR              | Port R4 <sub>1</sub> DCR            | Port R4 <sub>0</sub> DCR         |
| DCR5 \$035      | Port R5 <sub>3</sub> DCR           | Port R5 <sub>2</sub> DCR              | Port R5 <sub>1</sub> DCR            | Port R5 <sub>0</sub> DCR         |
| DCR6 \$036      | Port R6 <sub>3</sub> DCR           | Port R6 <sub>2</sub> DCR              | Port R6 <sub>1</sub> DCR            | Port R6 <sub>0</sub> DCR         |
| DCR7 \$037      | Not used                           | Port R7 <sub>2</sub> DCR              | Port R7 <sub>1</sub> DCR            | Port R7 <sub>0</sub> DCR         |
| DCR8 \$038      | Port R8 <sub>3</sub> DCR           | Port R8 <sub>2</sub> DCR              | Port R8 <sub>1</sub> DCR            | Port R8 <sub>0</sub> DCR         |
| DCR9 \$039      | Port R9 <sub>3</sub> DCR           | Port R9 <sub>2</sub> DCR              | Port R9 <sub>1</sub> DCR            | Port R9 <sub>0</sub> DCR         |
|                 | Not used                           |                                       |                                     |                                  |
| \$03F           |                                    |                                       |                                     |                                  |

Notes:

1. Timer-A/time-base
2. Auto-reload on/off
3. Pull-up MOS control
4. A/D conversion time
5. SO output level control in idle states
6. Serial clock source selection
7. Input capture selection
8. 32-kHz oscillation stop
9. 32-kHz oscillation division ratio

Figure 5 Special Function Register Area



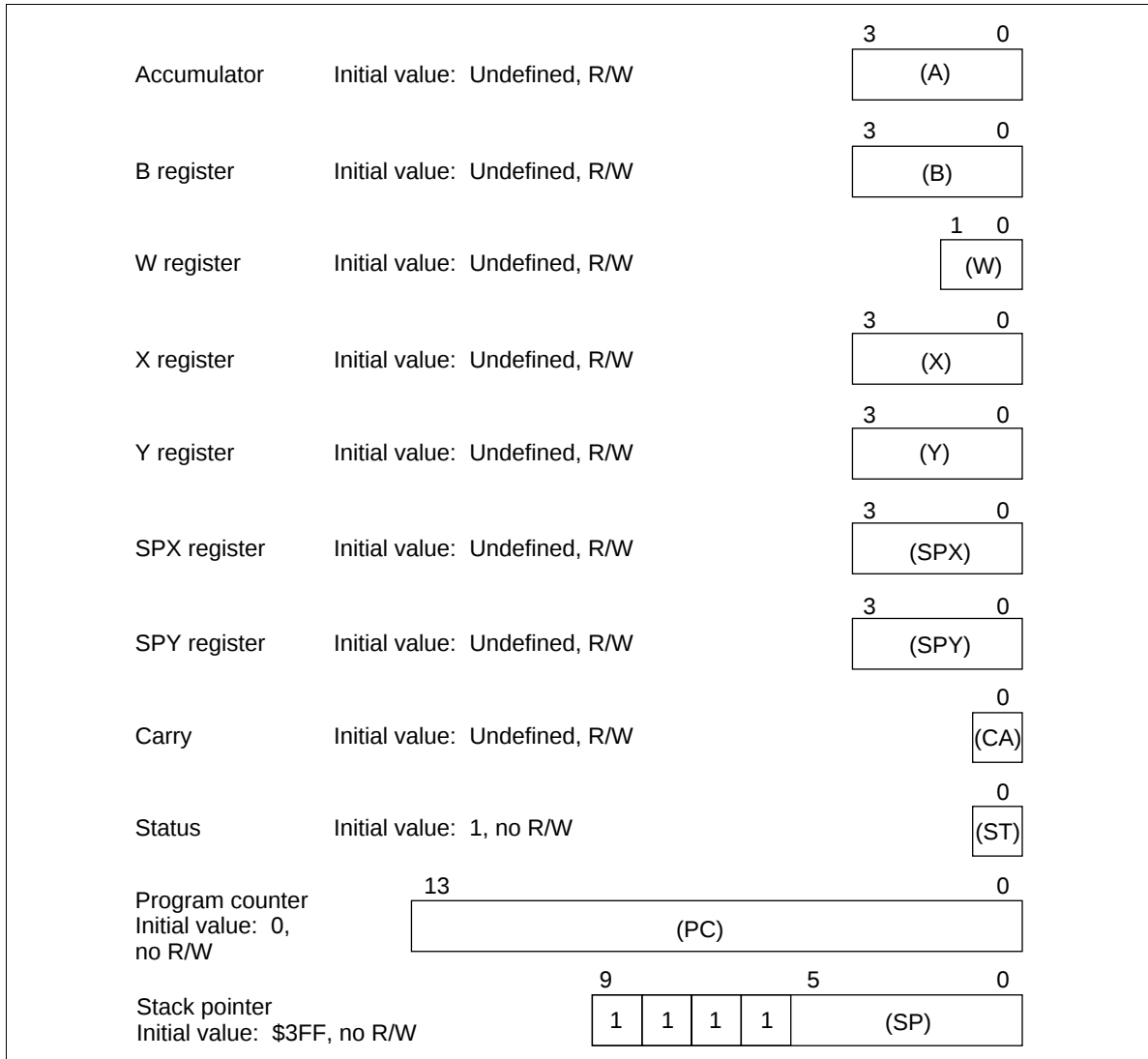
**Figure 6 Configuration of Memory Registers and Stack Area, and Stack Position**

## HD404369 Series

### Functional Description

#### Registers and Flags

The MCU has nine registers and two flags for CPU operations. They are shown in figure 7 and described below.



**Figure 7 Registers and Flags**

**Accumulator (A), B Register (B):** Four-bit registers used to hold the results from the arithmetic logic unit (ALU) and transfer data between memory, I/O, and other registers.

**W Register (W), X Register (X), Y Register (Y):** Two-bit (W) and four-bit (X and Y) registers used for indirect RAM addressing. The Y register is also used for D-port addressing.

**SPX Register (SPX), SPY Register (SPY):** Four-bit registers used to supplement the X and Y registers.

**Carry Flag (CA):** One-bit flag that stores any ALU overflow generated by an arithmetic operation. CA is affected by the SEC, REC, ROTL, and ROTR instructions. A carry is pushed onto the stack during an interrupt and popped from the stack by the RTNI instruction—but not by the RTN instruction.

**Status Flag (ST):** One-bit flag that latches any overflow generated by an arithmetic or compare instruction, not-zero decision from the ALU, or result of a bit test. ST is used as a branch condition of the BR, BRL, CAL, and CALL instructions. The contents of ST remain unchanged until the next arithmetic, compare, or bit test instruction is executed, but become 1 after the BR, BRL, CAL, or CALL instruction is read, regardless of whether the instruction is executed or skipped. The contents of ST are pushed onto the stack during an interrupt and popped from the stack by the RTNI instruction—but not by the RTN instruction.

**Program Counter (PC):** 14-bit binary counter that points to the ROM address of the instruction being executed.

**Stack Pointer (SP):** Ten-bit pointer that contains the address of the stack area to be used next. The SP is initialized to \$3FF by MCU reset. It is decremented by 4 when data is pushed onto the stack, and incremented by 4 when data is popped from the stack. The top four bits of the SP are fixed at 1111, so a stack can be used up to 16 levels.

The SP can be initialized to \$3FF in another way: by resetting the RSP bit with the REM or REMD instruction.

## **Reset**

The MCU is reset by inputting a low-level voltage to the  $\overline{\text{RESET}}$  pin. At power-on or when stop mode is cancelled,  $\overline{\text{RESET}}$  must be low for at least one  $t_{\text{RC}}$  to enable the oscillator to stabilize. During operation,  $\overline{\text{RESET}}$  must be low for at least two instruction cycles.

Initial values after MCU reset are listed in table 1.

## **Interrupts**

The MCU has 7 interrupt sources: two external signals ( $\overline{\text{INT}}_0$  and  $\overline{\text{INT}}_1$ ), three timer/counters (timers A, B, and C), serial interface, and A/D converter.

An interrupt request flag (IF), interrupt mask (IM), and vector address are provided for each interrupt source, and an interrupt enable flag (IE) controls the entire interrupt process.

**Interrupt Control Bits and Interrupt Processing:** Locations \$000 to \$003 in RAM are reserved for the interrupt control bits which can be accessed by RAM bit manipulation instructions.

The interrupt request flag (IF) cannot be set by software. MCU reset initializes the interrupt enable flag (IE) and the IF to 0 and the interrupt mask (IM) to 1.

A block diagram of the interrupt control circuit is shown in figure 8, interrupt priorities and vector addresses are listed in table 2, and interrupt processing conditions for the 7 interrupt sources are listed in table 3.

---

## HD404369 Series

---

An interrupt request occurs when the IF is set to 1 and the IM is set to 0. If the IE is 1 at that point, the interrupt is processed. A priority programmable logic array (PLA) generates the vector address assigned to that interrupt source.

The interrupt processing sequence is shown in figure 9 and an interrupt processing flowchart is shown in figure 10. After an interrupt is acknowledged, the previous instruction is completed in the first cycle. The IE is reset in the second cycle, the carry, status, and program counter values are pushed onto the stack during the second and third cycles, and the program jumps to the vector address to execute the instruction in the third cycle.

Program the JMPL instruction at each vector address, to branch the program to the start address of the interrupt program, and reset the IF by a software instruction within the interrupt program.

**Table 1 Initial Values After MCU Reset**

| Item                             | Abbr.                                       | Initial Value           | Contents                                                         |
|----------------------------------|---------------------------------------------|-------------------------|------------------------------------------------------------------|
| Program counter                  | (PC)                                        | \$0000                  | Indicates program execution point from start address of ROM area |
| Status flag                      | (ST)                                        | 1                       | Enables conditional branching                                    |
| Stack pointer                    | (SP)                                        | \$3FF                   | Stack level 0                                                    |
| Interrupt flags/mask             | Interrupt enable flag (IE)                  | 0                       | Inhibits all interrupts                                          |
|                                  | Interrupt request flag (IF)                 | 0                       | Indicates there is no interrupt request                          |
|                                  | Interrupt mask (IM)                         | 1                       | Prevents (masks) interrupt requests                              |
| I/O                              | Port data register (PDR)                    | All bits 1              | Enables output at level 1                                        |
|                                  | Data control register (DCD0-DCD2)           | All bits 0              | Turns output buffer off (to high impedance)                      |
|                                  |                                             | (DCD3) - - 00           |                                                                  |
|                                  |                                             | (DCR0-DCR6, DCR8, DCR9) |                                                                  |
|                                  |                                             | (DCR7) - 000            |                                                                  |
|                                  | Port mode register A (PMRA)                 | 0000                    | Refer to description of port mode register A                     |
|                                  | Port mode register B bits 2-0 (PMRB2-PMRB0) | 000                     | Refer to description of port mode register B                     |
|                                  | Port mode register C (PMRC)                 | 00 - 0                  | Refer to description of port mode register C                     |
|                                  | Timer mode register A (TMA)                 | 0000                    | Refer to description of timer mode register A                    |
|                                  | Timer mode register B1 (TMB1)               | 0000                    | Refer to description of timer mode register B1                   |
| Timer/counters, serial interface | Timer mode register B2 (TMB2)               | - 000                   | Refer to description of timer mode register B2                   |
|                                  | Timer mode register C (TMC)                 | 0000                    | Refer to description of timer mode register C                    |
|                                  | Serial mode register (SMR)                  | 0000                    | Refer to description of serial mode register                     |
|                                  | Prescaler S (PSS)                           | \$000                   | —                                                                |
|                                  | Prescaler W (PSW)                           | \$00                    | —                                                                |
|                                  | Timer counter A (TCA)                       | \$00                    | —                                                                |
|                                  | Timer counter B (TCB)                       | \$00                    | —                                                                |
|                                  | Timer counter C (TCC)                       | \$00                    | —                                                                |
|                                  | Timer write register B (TWBU, TWBL)         | \$X0                    | —                                                                |
|                                  | Timer write register C (TWCU, TWCL)         | \$X0                    | —                                                                |
|                                  | Octal counter                               | 000                     | —                                                                |

## HD404369 Series

| Item          |                                | Abbr.  | Initial Value | Contents                                                           |
|---------------|--------------------------------|--------|---------------|--------------------------------------------------------------------|
| A/D           | A/D mode register 1            | (AMR1) | 0000          | Refer to description of A/D mode register                          |
|               | A/D mode register 2            | (AMR2) | - 000         |                                                                    |
|               | A/D channel register           | (ACR)  | 0000          | Refer to description of A/D channel register                       |
|               | A/D data register              | (ADRL) | 0000          | Refer to description of A/D data register                          |
|               |                                | (ADRU) | 1000          |                                                                    |
| Bit registers | Low speed on flag              | (LSON) | 0             | Refer to description of operating modes                            |
|               | Watchdog timer on flag         | (WDON) | 0             | Refer to description of timer C                                    |
|               | A/D start flag                 | (ADSF) | 0             | Refer to description of A/D converter                              |
|               | I <sub>AD</sub> off flag       | (IAOF) | 0             | Refer to the description of A/D converter                          |
|               | Direct transfer on flag        | (DTON) | 0             | Refer to description of operating modes                            |
|               | Input capture status flag      | (ICSF) | 0             | Refer to description of timer B                                    |
|               | Input capture error flag       | (ICEF) | 0             | Refer to description of timer B                                    |
| Others        | Miscellaneous register         | (MIS)  | 0000          | Refer to description of operating modes, I/O, and serial interface |
|               | System clock select register 1 | (SSR1) | 000 -         | Refer to description of operating modes, and oscillation circuits  |
|               | System clock select register 2 | (SSR2) | - - 00        | Refer to description of oscillation circuits                       |

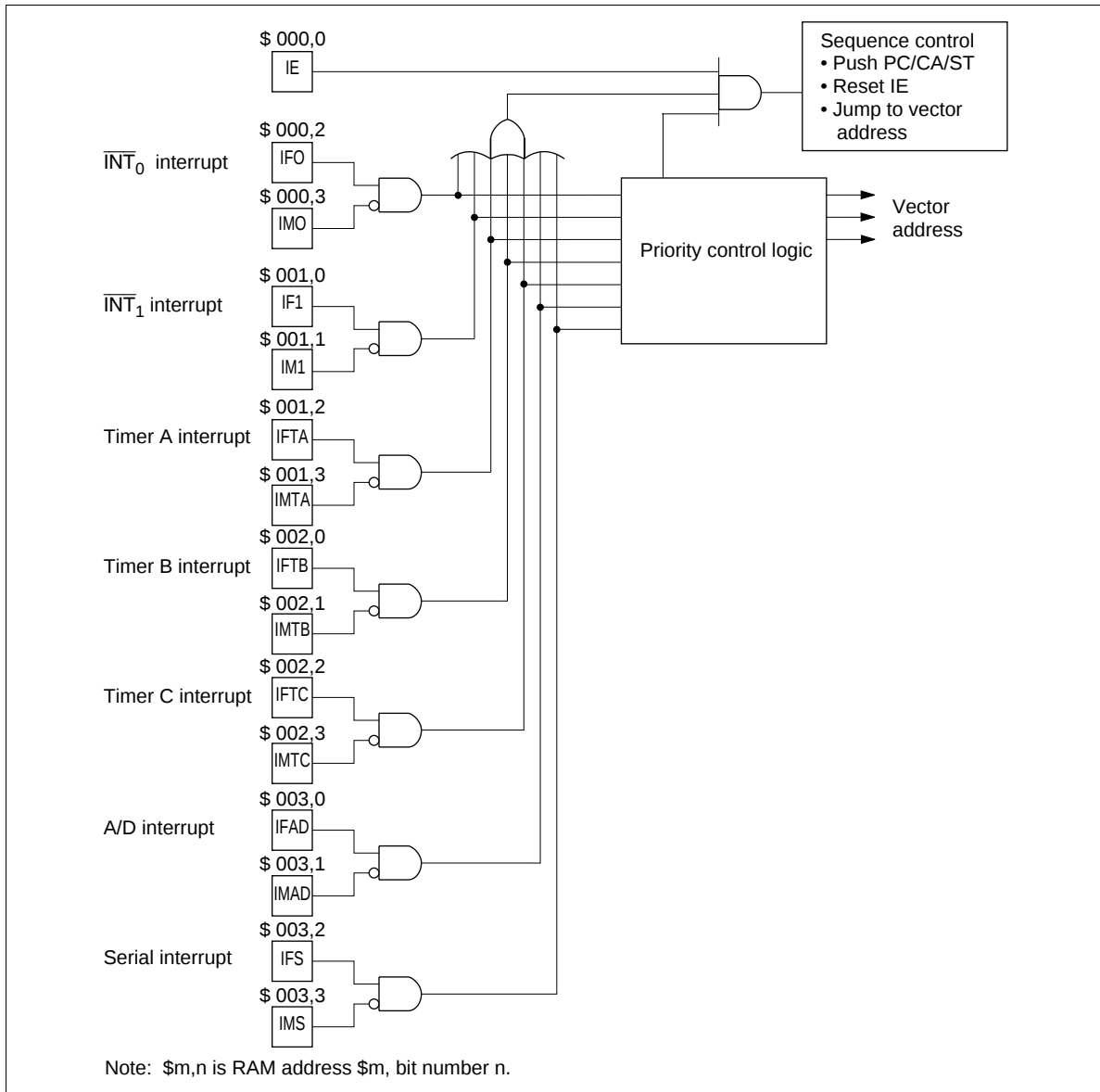
- Notes: 1. The statuses of other registers and flags after MCU reset are shown in the following table.  
2. X indicates invalid value. – indicates that the bit does not exist.

| Item                                 | Abbr.      | Status After Cancellation of Stop Mode by $\overline{\text{STOPC}}$ Input      | Status After all Other Types of Reset                                          |
|--------------------------------------|------------|--------------------------------------------------------------------------------|--------------------------------------------------------------------------------|
| Carry flag                           | (CA)       | Pre-stop-mode values are not guaranteed; values must be initialized by program | Pre-mcu-reset values are not guaranteed; values must be initialized by program |
| Accumulator                          | (A)        |                                                                                |                                                                                |
| B register                           | (B)        |                                                                                |                                                                                |
| W register                           | (W)        |                                                                                |                                                                                |
| X/SPX register                       | (X/SPX)    |                                                                                |                                                                                |
| Y/SPY register                       | (Y/SPY)    |                                                                                |                                                                                |
| Serial data register                 | (SRL, SRU) |                                                                                |                                                                                |
| RAM                                  |            | Pre-stop-mode values are retained                                              |                                                                                |
| RAM enable flag                      | (RAME)     | 1                                                                              | 0                                                                              |
| Port mode register B bit 3           | (PMRB3)    | Pre-stop-mode values are retained                                              | 0                                                                              |
| System clock select register 1 bit 3 | (SSR13)    |                                                                                |                                                                                |

**Table 2 Vector Addresses and Interrupt Priorities**

| Reset/Interrupt  | Priority | Vector Address |
|------------------|----------|----------------|
| RESET, STOPC*    | —        | \$0000         |
| INT <sub>0</sub> | 1        | \$0002         |
| INT <sub>1</sub> | 2        | \$0004         |
| Timer A          | 3        | \$0006         |
| Timer B          | 4        | \$0008         |
| Timer C          | 5        | \$000A         |
| A/D              | 6        | \$000C         |
| Serial           | 7        | \$000E         |

Note: \* The STOPC interrupt request is valid only in stop mode.

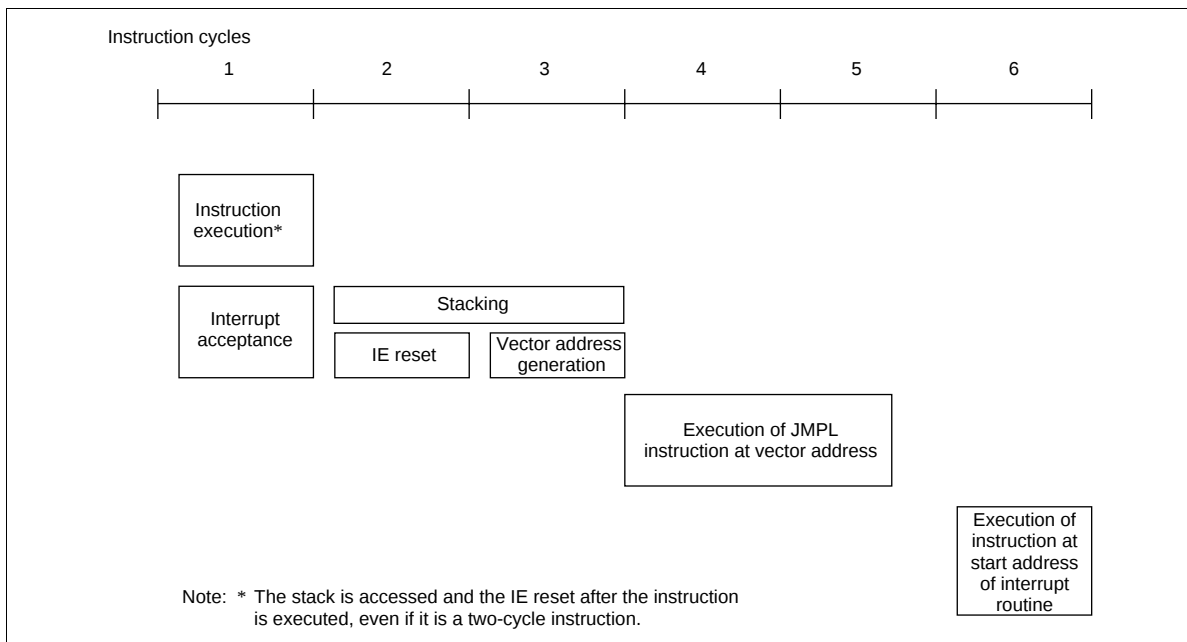


**Figure 8 Interrupt Control Circuit**

**Table 3 Interrupt Processing and Activation Conditions**

|                        | Interrupt Source   |                    |         |         |         |     |        |
|------------------------|--------------------|--------------------|---------|---------|---------|-----|--------|
|                        | $\overline{INT}_0$ | $\overline{INT}_1$ | Timer A | Timer B | Timer C | A/D | Serial |
| IE                     | 1                  | 1                  | 1       | 1       | 1       | 1   | 1      |
| IF0 $\overline{IM0}$   | 1                  | 0                  | 0       | 0       | 0       | 0   | 0      |
| IF1 $\overline{IM1}$   | *                  | 1                  | 0       | 0       | 0       | 0   | 0      |
| IFTA $\overline{IMTA}$ | *                  | *                  | 1       | 0       | 0       | 0   | 0      |
| IFTB $\overline{IMTB}$ | *                  | *                  | *       | 1       | 0       | 0   | 0      |
| IFTC $\overline{IMTC}$ | *                  | *                  | *       | *       | 1       | 0   | 0      |
| IFAD $\overline{IMAD}$ | *                  | *                  | *       | *       | *       | 1   | 0      |
| IFS $\overline{IMS}$   | *                  | *                  | *       | *       | *       | *   | 1      |

Note: Bits marked \* can be either 0 or 1. Their values have no effect on operation.



**Figure 9 Interrupt Processing Sequence**

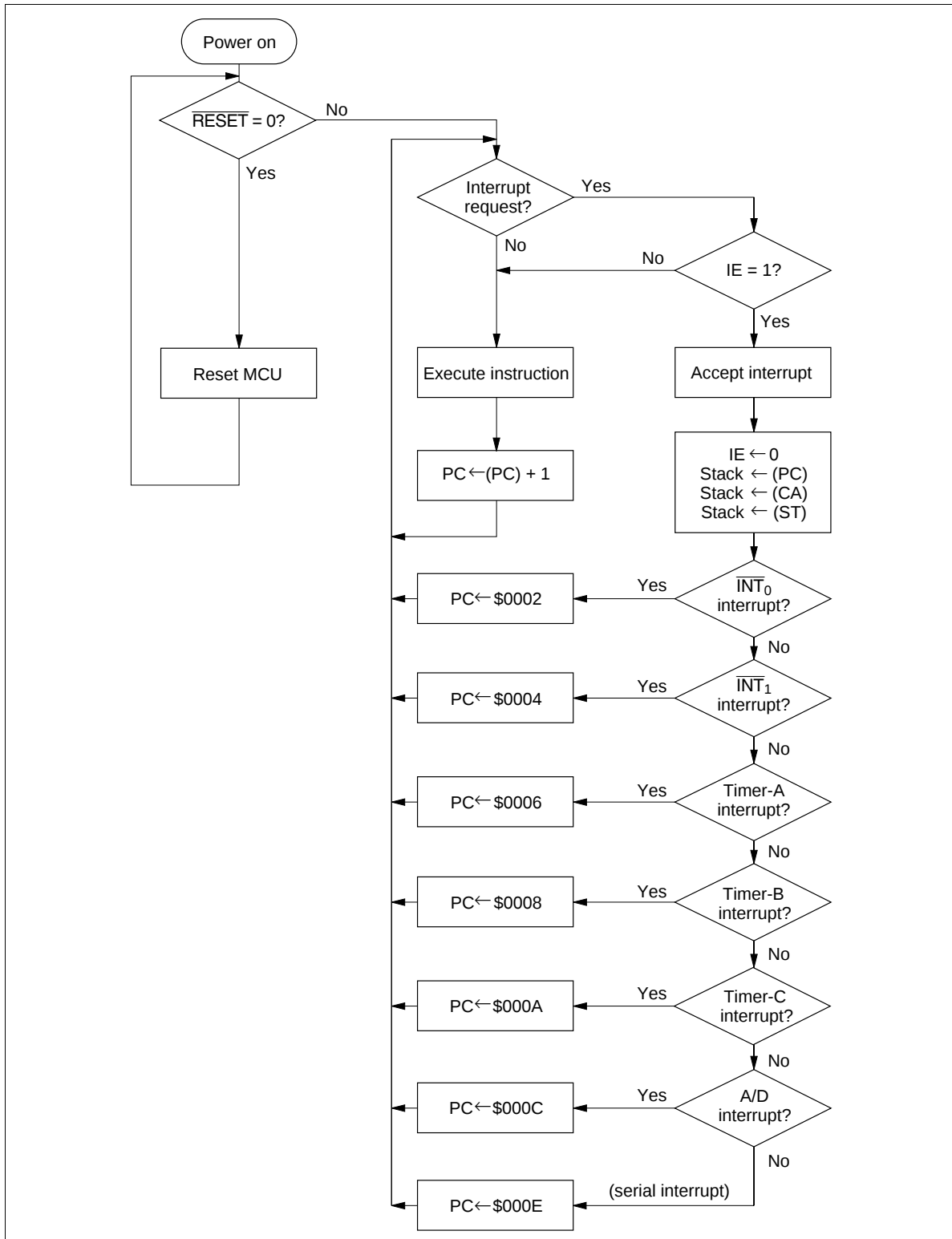


Figure 10 Interrupt Processing Flowchart

**Interrupt Enable Flag (IE: \$000, Bit 0):** Controls the entire interrupt process. It is reset by the interrupt processing and set by the RTNI instruction, as listed in table 4.

**Table 4      Interrupt Enable Flag (IE: \$000, Bit 0)**

| IE | Interrupt Enabled/Disabled |
|----|----------------------------|
| 0  | Disabled                   |
| 1  | Enabled                    |

**External Interrupts ( $\overline{INT}_0$ ,  $\overline{INT}_1$ ):** Two external interrupt signals.

**External Interrupt Request Flags (IF0: \$000, Bit 2; IF1: \$001, Bit 0):** IF0 and IF1 are set at the rising edge of signals input to  $\overline{INT}_0$  and  $\overline{INT}_1$ , as listed in table 5.

**Table 5      External Interrupt Request Flags (IF0: \$000, Bit2; IF1: \$001, Bit 0)**

| IF0, IF1 | Interrupt Request |
|----------|-------------------|
| 0        | No                |
| 1        | Yes               |

**External Interrupt Masks (IM0: \$000, Bit 3; IM1: \$001, Bit 1):** Prevent (mask) interrupt requests caused by the corresponding external interrupt request flags, as listed in table 6.

**Table 6      External Interrupt Masks (IM0: \$000, Bit 3; IM1: \$001, Bit 1)**

| IM0, IM1 | Interrupt Request |
|----------|-------------------|
| 0        | Enabled           |
| 1        | Disabled (masked) |

**Timer A Interrupt Request Flag (IFTA: \$001, Bit 2):** Set by overflow output from timer A, as listed in table 7.

**Table 7      Timer A Interrupt Request Flag (IFTA: \$001, Bit 2)**

| IFTA | Interrupt Request |
|------|-------------------|
| 0    | No                |
| 1    | Yes               |

**Timer A Interrupt Mask (IMTA: \$001, Bit 3):** Prevents (masks) an interrupt request caused by the timer A interrupt request flag, as listed in table 8.

---

## HD404369 Series

---

**Table 8      Timer A Interrupt Mask (IMTA: 001, Bit 3)**

| IMTA | Interrupt Request |
|------|-------------------|
| 0    | Enabled           |
| 1    | Disabled (masked) |

---

**Timer B Interrupt Request Flag (IFTB: \$002, Bit 0):** Set by overflow output from timer B, as listed in table 9.

**Table 9      Timer B Interrupt Request Flag (IFTB: \$002, Bit 0)**

| IFTB | Interrupt Request |
|------|-------------------|
| 0    | No                |
| 1    | Yes               |

---

**Timer B Interrupt Mask (IMTB: \$002, Bit 1):** Prevents (masks) an interrupt request caused by the timer B interrupt request flag, as listed in table 10.

**Table 10     Timer B Interrupt Mask (IMTB: \$002, Bit 1)**

| IMTB | Interrupt Request |
|------|-------------------|
| 0    | Enabled           |
| 1    | Disabled (masked) |

---

**Timer C Interrupt Request Flag (IFTC: \$002, Bit 2):** Set by overflow output from timer C, as listed in table 11.

**Table 11     Timer C Interrupt Request Flag (IFTC: \$002, Bit 2)**

| IFTC | Interrupt Request |
|------|-------------------|
| 0    | No                |
| 1    | Yes               |

---

**Timer C Interrupt Mask (IMTC: \$002, Bit 3):** Prevents (masks) an interrupt request caused by the timer C interrupt request flag, as listed in table 12.

**Table 12     Timer C Interrupt Mask (IMTC: \$002, Bit 3)**

| IMTC | Interrupt Request |
|------|-------------------|
| 0    | Enabled           |
| 1    | Disabled (masked) |

---

**Serial Interrupt Request Flag (IFS: \$003, Bit 2):** Set when data transfer is completed or when data transfer is suspended, as listed in table 13.

**Table 13     Serial Interrupt Request Flag (IFS: \$003, Bit 2)**

| IFS | Interrupt Request |
|-----|-------------------|
| 0   | No                |
| 1   | Yes               |

**Serial Interrupt Mask (IMS: \$003, Bit 3):** Prevents (masks) an interrupt request caused by the serial interrupt request flag, as listed in table 14.

**Table 14     Serial Interrupt Mask (IMS: \$003, Bit 3)**

| Mask IMS | Interrupt Request |
|----------|-------------------|
| 0        | Enabled           |
| 1        | Disabled (masked) |

**A/D Interrupt Request Flag (IFAD: \$003, Bit 0):** Set at the completion of A/D conversion, as listed in table 15.

**Table 15     A/D Interrupt Request Flag (IFAD: \$003, Bit 0)**

| IFAD | Interrupt Request |
|------|-------------------|
| 0    | No                |
| 1    | Yes               |

**A/D Interrupt Mask (IMAD: \$003, Bit 1):** Prevents (masks) an interrupt request caused by the A/D interrupt request flag, as listed in table 16.

**Table 16     A/D Interrupt Mask (IMAD: \$003, Bit 1)**

| IMAD | Interrupt Request |
|------|-------------------|
| 0    | Enabled           |
| 1    | Disabled (masked) |

## HD404369 Series

### Operating Modes

The MCU has five operating modes as shown in table 17. The operations in each mode are listed in tables 18 and 19. Transitions between operating modes are shown in figure 11.

**Active Mode:** All MCU functions operate according to the clock generated by the system oscillator OSC<sub>1</sub> and OSC<sub>2</sub>.

**Table 17 Operating Modes and Clock Status**

|                     |                      | Mode Name                                                                                                                                                                        |                                                    |                                                                               |                                                                                         |                                                                        |
|---------------------|----------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------|-------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------|------------------------------------------------------------------------|
|                     |                      | Active                                                                                                                                                                           | Standby                                            | Stop                                                                          | Watch                                                                                   | Subactive* <sup>2</sup>                                                |
| Activation method   |                      | $\overline{\text{RESET}}$ cancellation, interrupt $\overline{\text{STOPC}}$ cancellation in stop mode, STOP/SBY instruction in subactive mode (when direct transfer is selected) | SBY instruction                                    | STOP instruction when TMA3 = 0                                                | STOP instruction when TMA3 = 1                                                          | $\overline{\text{INT}}_0$ or timer A interrupt request from watch mode |
| Status              | System oscillator    | OP                                                                                                                                                                               | OP                                                 | Stopped                                                                       | Stopped                                                                                 | Stopped                                                                |
|                     | Subsystem oscillator | OP                                                                                                                                                                               | OP                                                 | * <sup>1</sup> OP                                                             | OP                                                                                      | OP                                                                     |
| Cancellation method |                      | $\overline{\text{RESET}}$ input, STOP/SBY instruction                                                                                                                            | $\overline{\text{RESET}}$ input, interrupt request | $\overline{\text{RESET}}$ input, $\overline{\text{STOPC}}$ input in stop mode | $\overline{\text{RESET}}$ input, $\overline{\text{INT}}_0$ or timer A interrupt request | $\overline{\text{RESET}}$ input, STOP/SBY instruction                  |

Notes: OP implies in operation

1. Operating or stopping the oscillator can be selected by setting bit 3 of the system clock select register 1 (SSR1: \$027).
2. Subactive mode is an optional function; specify it on the function option list.

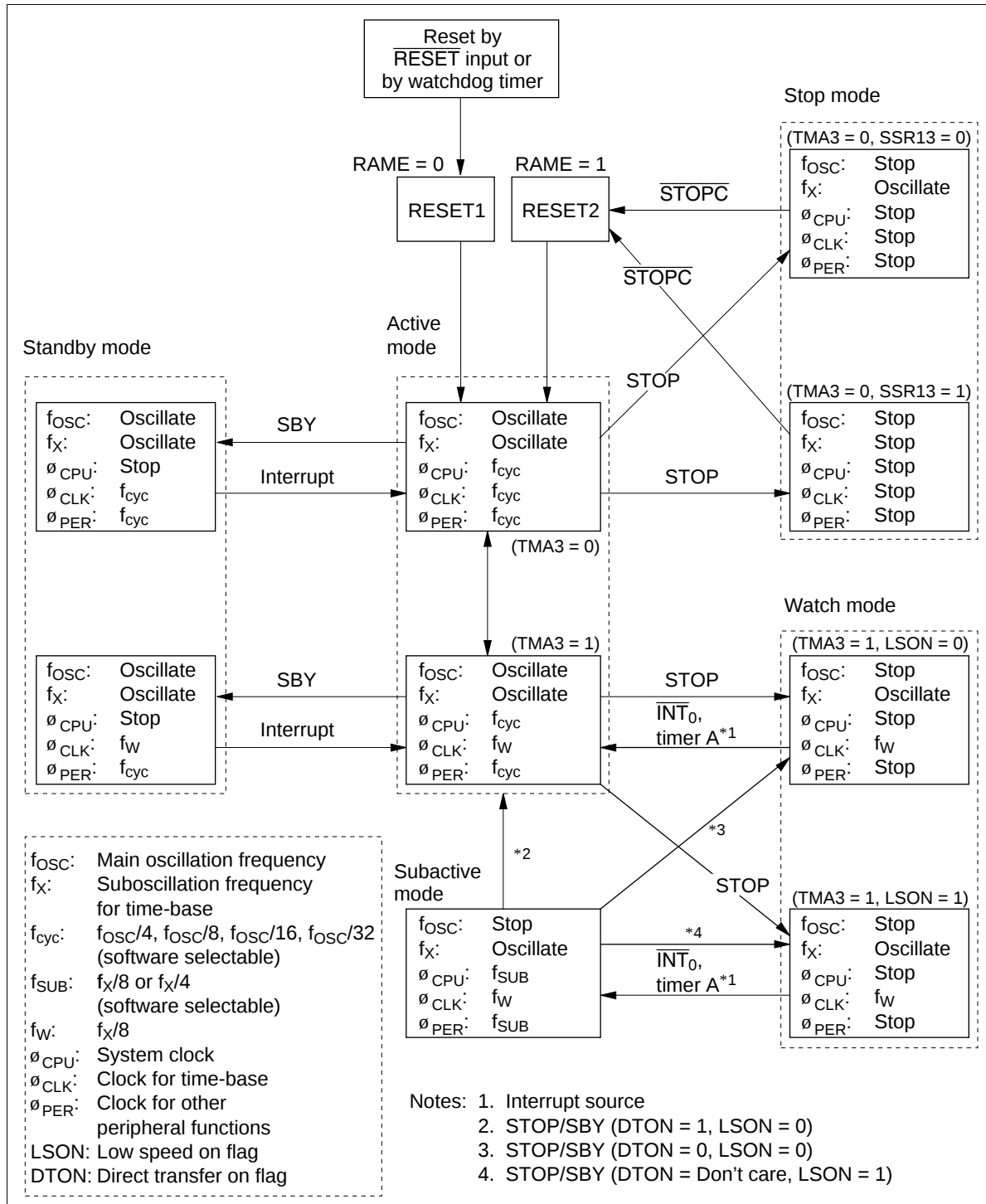
**Table 18 Operations in Low-Power Dissipation Modes**

| Function | Stop Mode | Watch Mode | Standby Mode | Subactive Mode |
|----------|-----------|------------|--------------|----------------|
| CPU      | Reset     | Retained   | Retained     | OP             |
| RAM      | Retained  | Retained   | Retained     | OP             |
| Timer A  | Reset     | OP         | OP           | OP             |
| Timer B  | Reset     | Stopped    | OP           | OP             |
| Timer C  | Reset     | Stopped    | OP           | OP             |
| Serial   | Reset     | Stopped    | OP           | OP             |
| A/D      | Reset     | Stopped    | OP           | Stopped        |
| I/O      | Reset     | Retained   | Retained     | OP             |

Note: OP implies in operation

**Table 19 I/O Status in Low-Power Dissipation Modes**

|                                         | Output                                        |                | Input                          |
|-----------------------------------------|-----------------------------------------------|----------------|--------------------------------|
|                                         | Standby Mode,<br>Watch mode                   | Stop Mode      | Active Mode,<br>Subactive mode |
| RA <sub>1</sub>                         | —                                             | —              | Input enabled                  |
| D <sub>0</sub> –D <sub>13</sub> , R0–R9 | Retained or output of<br>peripheral functions | High impedance | Input enabled                  |

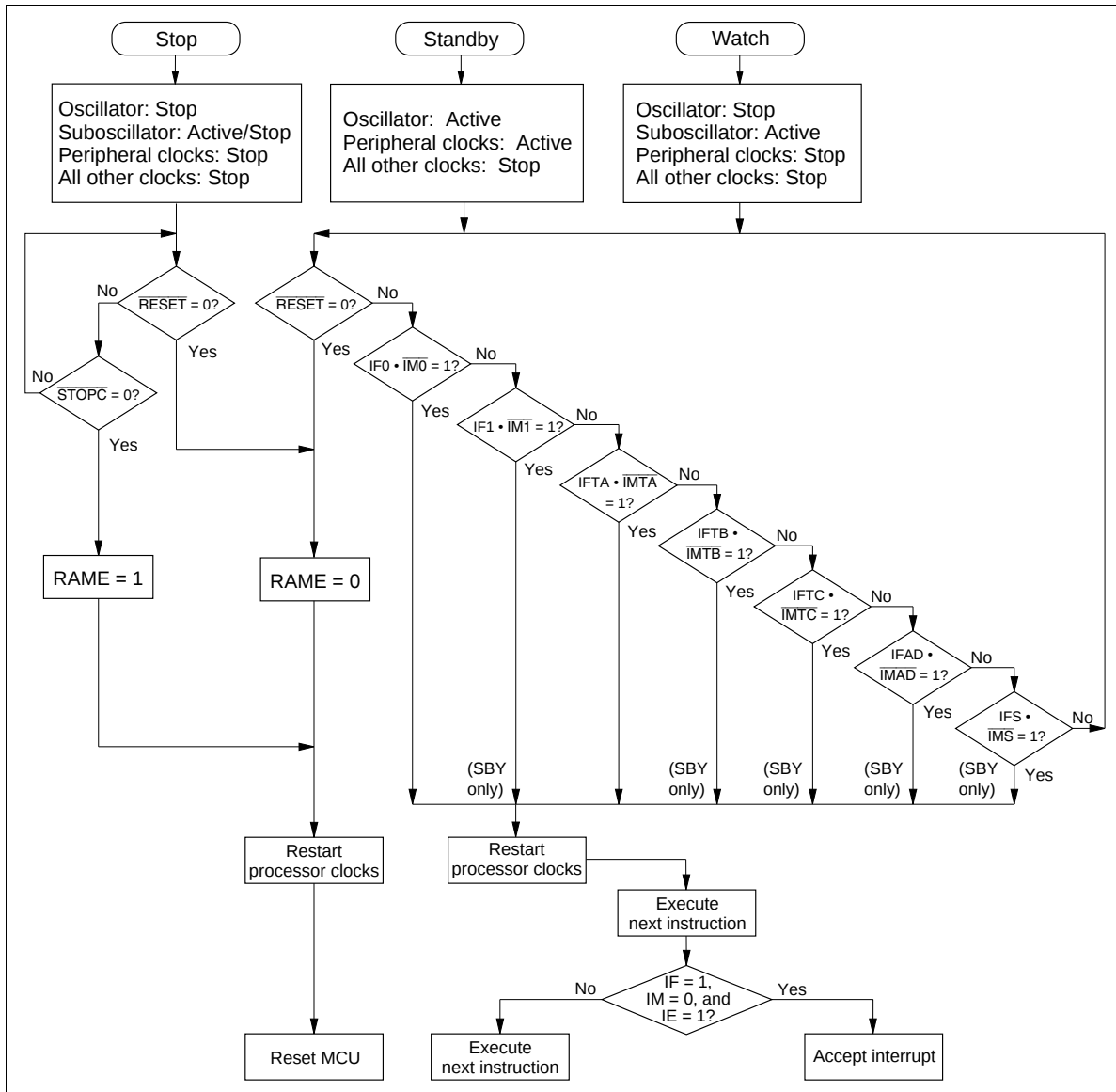


**Figure 11 MCU Status Transitions**

**Standby Mode:** In standby mode, the oscillators continue to operate, but the clocks related to instruction execution stop. Therefore, the CPU operation stops, but all RAM and register contents are retained, and the D or R port status, when set to output, is maintained. Peripheral functions such as interrupts, timers, and serial interface continue to operate. The power dissipation in this mode is lower than in active mode because the CPU stops.

The MCU enters standby mode when the SBY instruction is executed in active mode.

Standby mode is terminated by a  $\overline{\text{RESET}}$  input or an interrupt request. If it is terminated by  $\overline{\text{RESET}}$  input, the MCU is reset as well. After an interrupt request, the MCU enters active mode and executes the next instruction after the SBY instruction. If the interrupt enable flag is 1, the interrupt is then processed; if it is 0, the interrupt request is left pending and normal instruction execution continues. A flowchart of operation in standby mode is shown in figure 12.



**Figure 12 MCU Operation Flowchart**

**Stop Mode:** In stop mode, all MCU operations stop and RAM data is retained. Therefore, the power dissipation in this mode is the least of all modes. The  $OSC_1$  and  $OSC_2$  oscillator stops. For the X1 and X2 oscillator to operate or stop can be selected by setting bit 3 of the system clock select register 1 (SSR1: \$027; operating: SSR13 = 0, stop: SSR13 = 1) (figure 23). The MCU enters stop mode if the STOP instruction is executed in active mode when bit 3 of timer mode register A (TMA: \$008) is set to 0 (TMA3 = 0) (figure 37).

Stop mode is terminated by a  $\overline{RESET}$  input or a  $\overline{STOPC}$  input as shown in figure 13.  $\overline{RESET}$  or  $\overline{STOPC}$  must be applied for at least one  $t_{RC}$  to stabilize oscillation (refer to the AC Characteristics section). When the MCU restarts after stop mode is cancelled, all RAM contents before entering stop mode are retained,

but the accuracy of the contents of the accumulator, B register, W register, X/SPX register, Y/SPY register, carry flag, and serial data register cannot be guaranteed.

**Watch Mode:** In watch mode, the clock function (timer A) using the X1 and X2 oscillator operates, but other function operations stop. Therefore, the power dissipation in this mode is the second least to stop mode, and this mode is convenient when only clock display is used. In this mode, the OSC<sub>1</sub> and OSC<sub>2</sub> oscillator stops, but the X1 and X2 oscillator operates. The MCU enters watch mode if the STOP instruction is executed in active mode when TMA3 = 1, or if the STOP or SBY instruction is executed in subactive mode.

Watch mode is terminated by a  $\overline{\text{RESET}}$  input or a timer-A/ $\overline{\text{INT}}_0$  interrupt request. For details of  $\overline{\text{RESET}}$  input, refer to the Stop Mode section. When terminated by a timer-A/ $\overline{\text{INT}}_0$  interrupt request, the MCU enters active mode if LSON = 0, or subactive mode if LSON = 1. After an interrupt request is generated, the time required to enter active mode is  $t_{\text{RC}}$  for a timer A interrupt, and  $T_x$  (where  $T + t_{\text{RC}} < T_x < 2T + t_{\text{RC}}$ ) for an  $\overline{\text{INT}}_0$  interrupt, as shown in figures 14 and 15.

Operation during mode transition is the same as that at standby mode cancellation (figure 12).

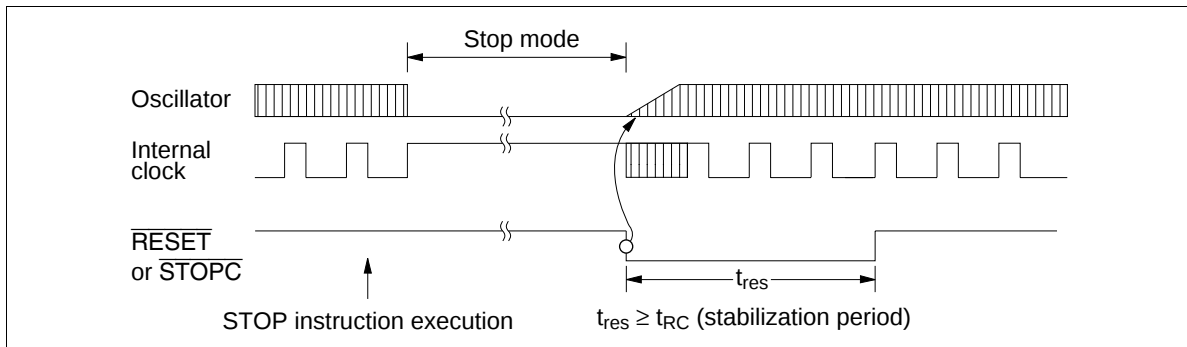


Figure 13 Timing of Stop Mode Cancellation

**Subactive Mode:** The OSC<sub>1</sub> and OSC<sub>2</sub> oscillator stops and the MCU operates with a clock generated by the X1 and X2 oscillator. In this mode, functions except the A/D conversion operate. However, because the operating clock is slow, the power dissipation becomes low, next to watch mode.

The CPU instruction execution speed can be selected as 244  $\mu\text{s}$  or 122  $\mu\text{s}$  by setting bit 2 (SSR12) of the system clock select register 1 (SSR1: \$027). Note that the SSR12 value must be changed in active mode. If the value is changed in subactive mode, the MCU may malfunction.

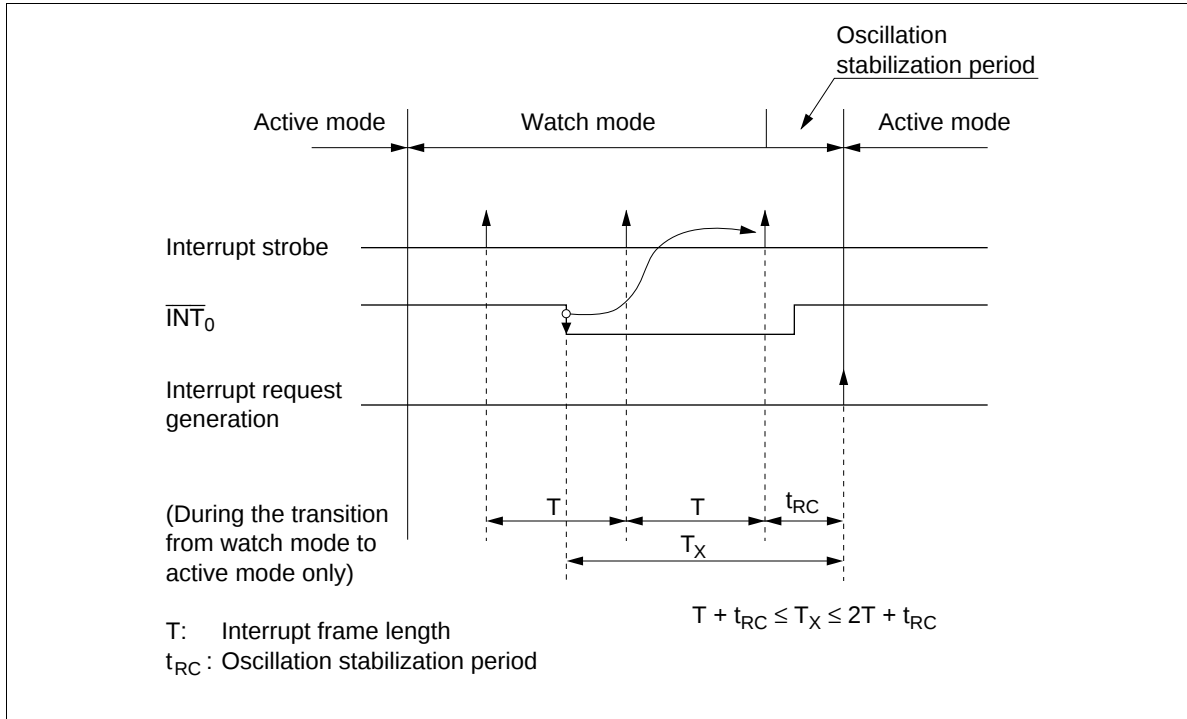
When the STOP or SBY instruction is executed in subactive mode, the MCU enters either watch or active mode, depending on the statuses of the low speed on flag (LSON: \$020, bit 0) and the direct transfer on flag (DTON: \$020, bit 3).

**Interrupt Frame:** In watch and subactive modes,  $\phi_{\text{CLK}}$  is applied to timer A and the  $\overline{\text{INT}}_0$  circuit. Prescaler W and timer A operate as the time-base and generate the timing clock for the interrupt frame. Three interrupt frame lengths (T) can be selected by setting the miscellaneous register (MIS: \$00C) (figure 15).

In watch and subactive modes, the timer-A/ $\overline{\text{INT}}_0$  interrupt is generated synchronously with the interrupt frame. The interrupt request is generated synchronously with the interrupt strobe timing except during transition to active mode. The falling edge of the  $\overline{\text{INT}}_0$  signal is input asynchronously with the interrupt

## HD404369 Series

frame timing, but it is regarded as input synchronously with the second interrupt strobe clock after the falling edge. An overflow and interrupt request in timer A is generated synchronously with the interrupt strobe timing.



**Figure 14 Interrupt Frame**

**Direct Transition from Subactive Mode to Active Mode:** Available by controlling the direct transfer on flag (DTON: \$020, bit 3) and the low speed on flag (LSON: \$020, bit 0). The procedures are described below:

- Set LSON to 0 and DTON to 1 in subactive mode.
- Execute the STOP or SBY instruction.
- The MCU automatically enters active mode from subactive mode after waiting for the MCU internal processing time and oscillation stabilization time (figure 16).

Notes: 1. The DTON flag (\$020, bit 3) can be set only in subactive mode. It is always reset in active mode.

2. The transition time ( $T_D$ ) from subactive mode to active mode:

$$t_{RC} < T_D < T + t_{RC}$$

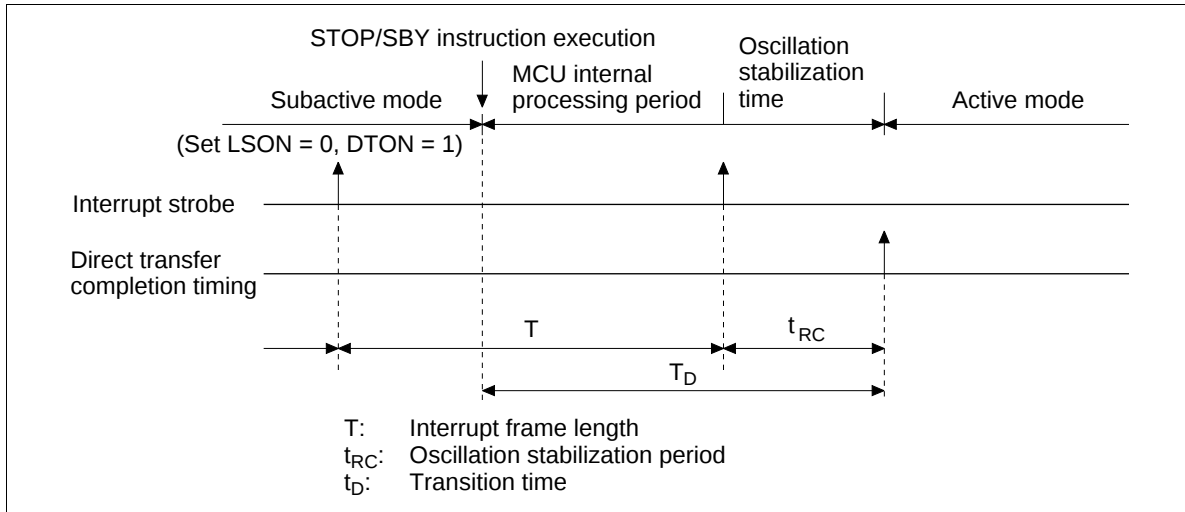
**Miscellaneous register (MIS: \$00C)**

|               |      |      |      |      |
|---------------|------|------|------|------|
| Bit           | 3    | 2    | 1    | 0    |
| Initial value | 0    | 0    | 0    | 0    |
| Read/Write    | W    | W    | W    | W    |
| Bit name      | MIS3 | MIS2 | MIS1 | MIS0 |

| MIS3                                   | MIS2 | MIS1 | MIS0 | $T^{*1}$   | $t_{RC}^{*1}$            | Oscillation Circuit Conditions |
|----------------------------------------|------|------|------|------------|--------------------------|--------------------------------|
| Buffer control.<br>Refer to figure 34. |      | 0    | 0    | 0.24414 ms | 0.12207 ms               | External clock input           |
|                                        |      |      |      |            | 0.24414 ms <sup>*2</sup> |                                |
|                                        |      | 0    | 1    | 15.625 ms  | 7.8125 ms                | Ceramic oscillator             |
|                                        |      | 1    | 0    | 125 ms     | 62.5 ms                  | Crystal oscillator             |
|                                        |      | 1    | 1    | Not used   |                          | —                              |

Notes: 1. The values of  $T$  and  $t_{RC}$  are applied when a 32.768-kHz crystal oscillator is used.  
2. The value is applied only when direct transfer operation is used.

**Figure 15 Miscellaneous Register (MIS)**



**Figure 16 Direct Transition Timing**

**Stop Mode Cancellation by  $\overline{STOPC}$ :** The MCU enters active mode from stop mode by inputting  $\overline{STOPC}$  as well as by  $\overline{RESET}$ . In either case, the MCU starts instruction execution from the starting address (address 0) of the program. However, the value of the RAM enable flag (RAME: \$021, bit 3) differs between cancellation by  $\overline{STOPC}$  and by  $\overline{RESET}$ . When stop mode is cancelled by  $\overline{RESET}$ , RAME = 0; when cancelled by  $\overline{STOPC}$ , RAME = 1.  $\overline{RESET}$  can cancel all modes, but  $\overline{STOPC}$  is valid only in stop mode;  $\overline{STOPC}$  input is ignored in other modes. Therefore, when the program requires to confirm that stop mode has been cancelled by  $\overline{STOPC}$  (for example, when the RAM contents before entering stop mode is

---

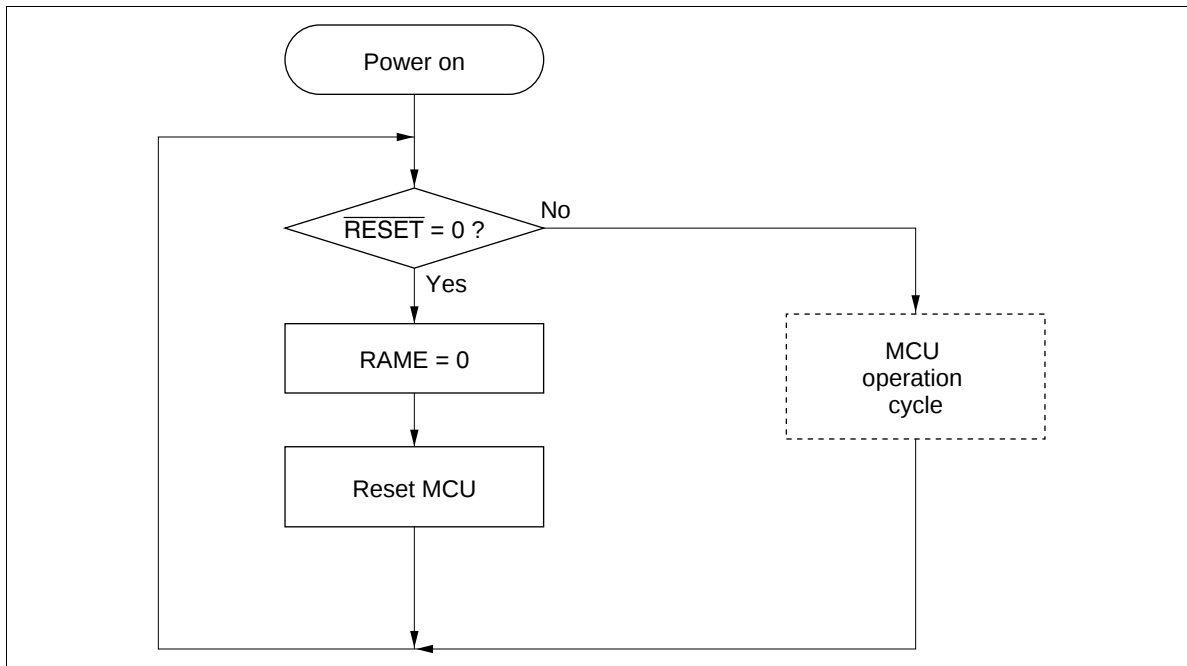
## HD404369 Series

---

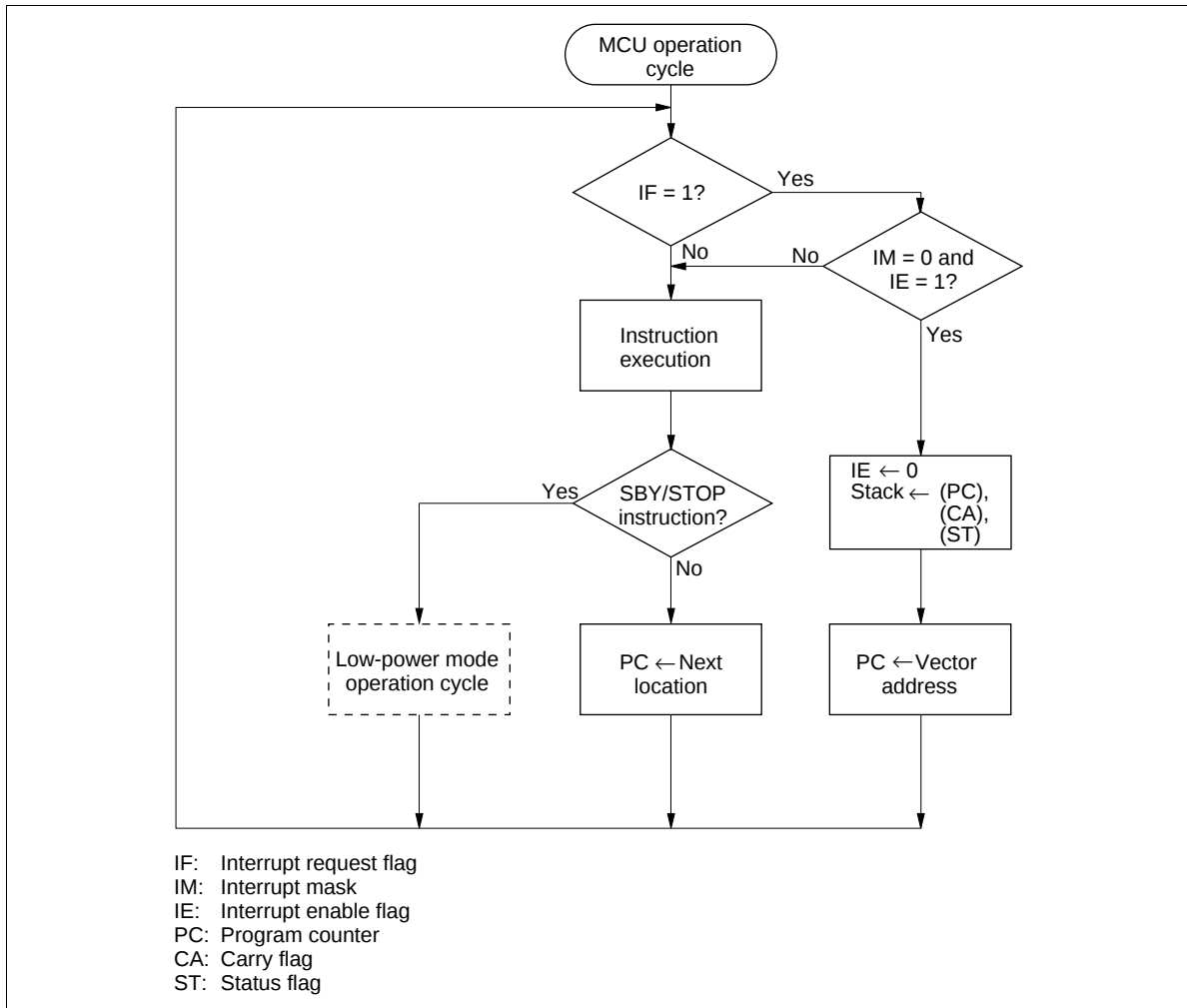
used after transition to active mode), execute the TEST instruction to the RAM enable flag (RAME) at the beginning of the program.

**MCU Operation Sequence:** The MCU operates in the sequence shown in figures 17 to 19. It is reset by an asynchronous  $\overline{\text{RESET}}$  input, regardless of its status.

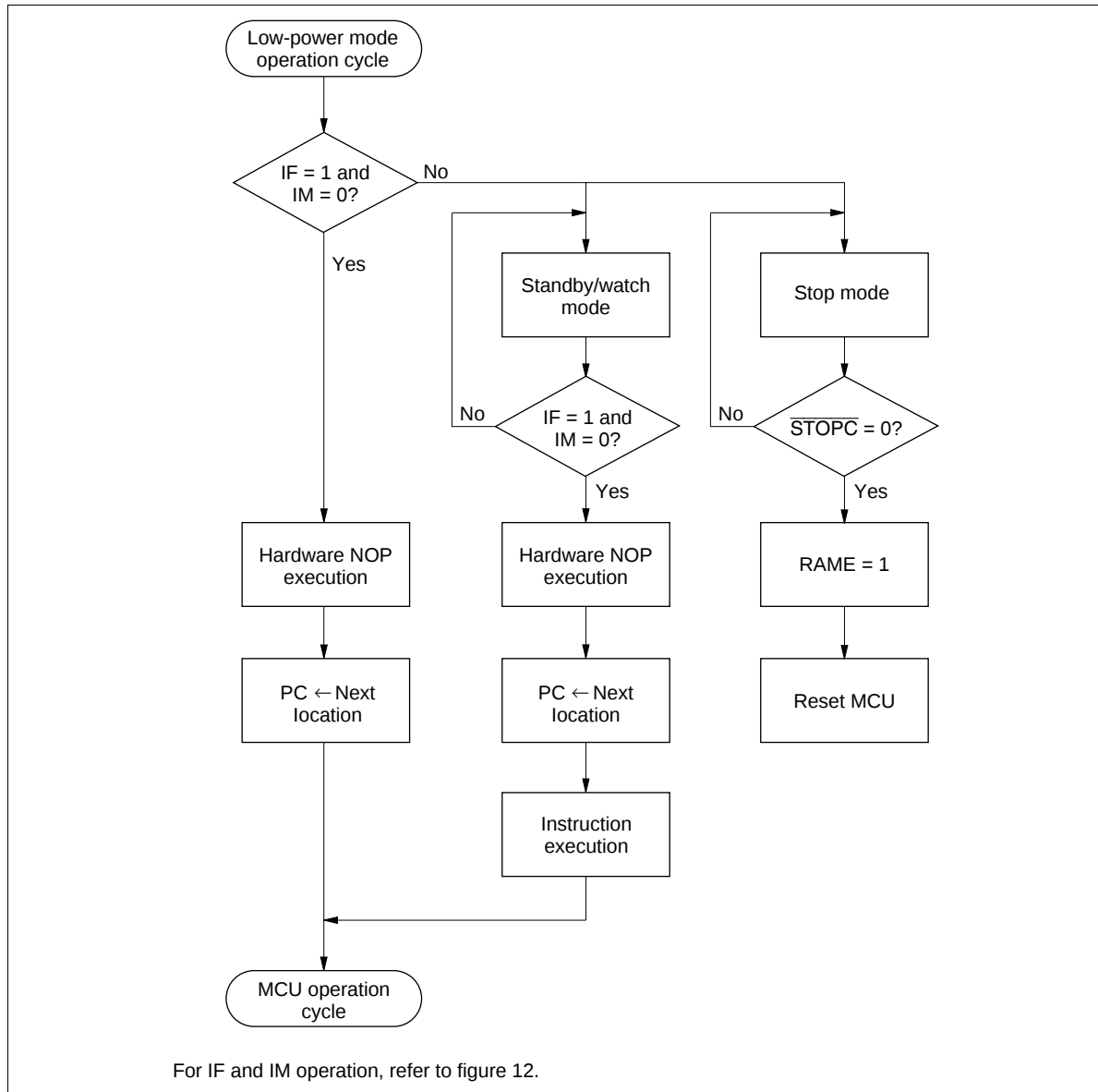
The low-power mode operation sequence is shown in figure 19. With the IE flag cleared and an interrupt flag set together with its interrupt mask cleared, if a STOP/SBY instruction is executed, the instruction is cancelled (regarded as an NOP) and the following instruction is executed. Before executing a STOP/SBY instruction, make sure all interrupt flags are cleared or all interrupts are masked.



**Figure 17 MCU Operating Sequence (Power On)**

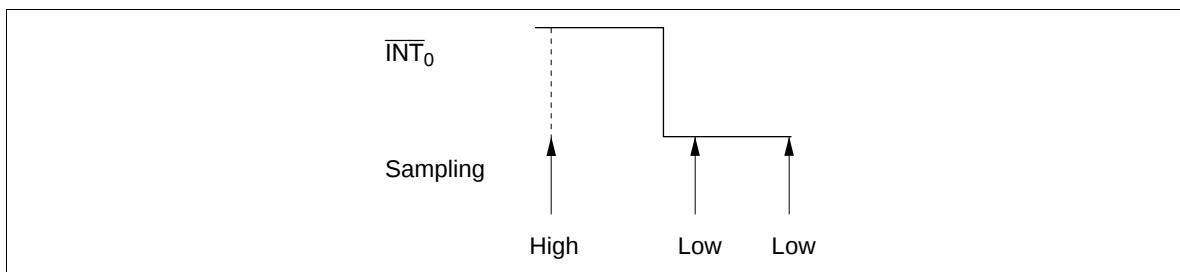


**Figure 18 MCU Operating Sequence (MCU Operation Cycle)**

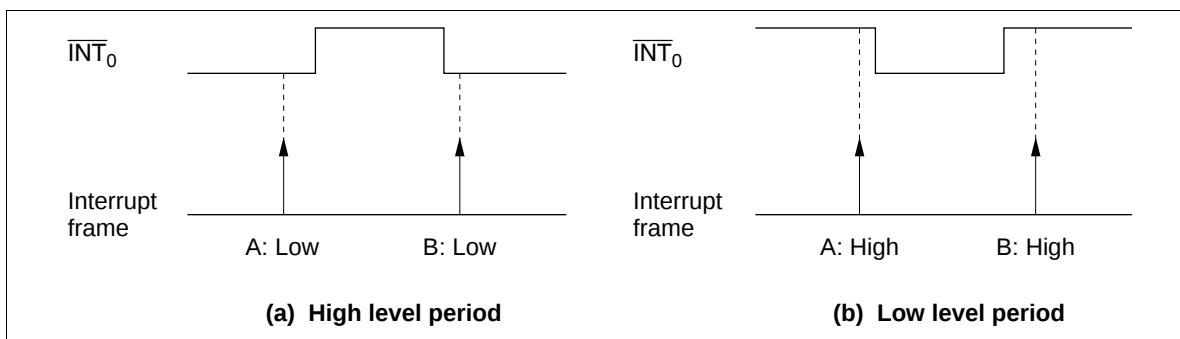


**Figure 19 MCU Operating Sequence (Low-Power Mode Operation)**

Note: When the MCU is in watch mode or subactive mode, if the high level period before the falling edge of  $\overline{INT}_0$  is shorter than the interrupt frame,  $\overline{INT}_0$  is not detected. Also, if the low level period after the falling edge of  $\overline{INT}_0$  is shorter than the interrupt frame,  $\overline{INT}_0$  is not detected. Edge detection is shown in figure 20. The level of the  $\overline{INT}_0$  signal is sampled by a sampling clock. When this sampled value changes to low from high, a falling edge is detected. In figure 21, the level of the  $\overline{INT}_0$  signal is sampled by an interrupt frame. In (a) the sampled value is low at point A, and also low at point B. Therefore, a falling edge is not detected. In (b), the sampled value is high at point A, and also high at point B. A falling edge is not detected in this case either. When the MCU is in watch mode or subactive mode, keep the high level and low level period of  $\overline{INT}_0$  longer than the interrupt frame



**Figure 20 Edge Detection**



**Figure 21 Sampling Example**

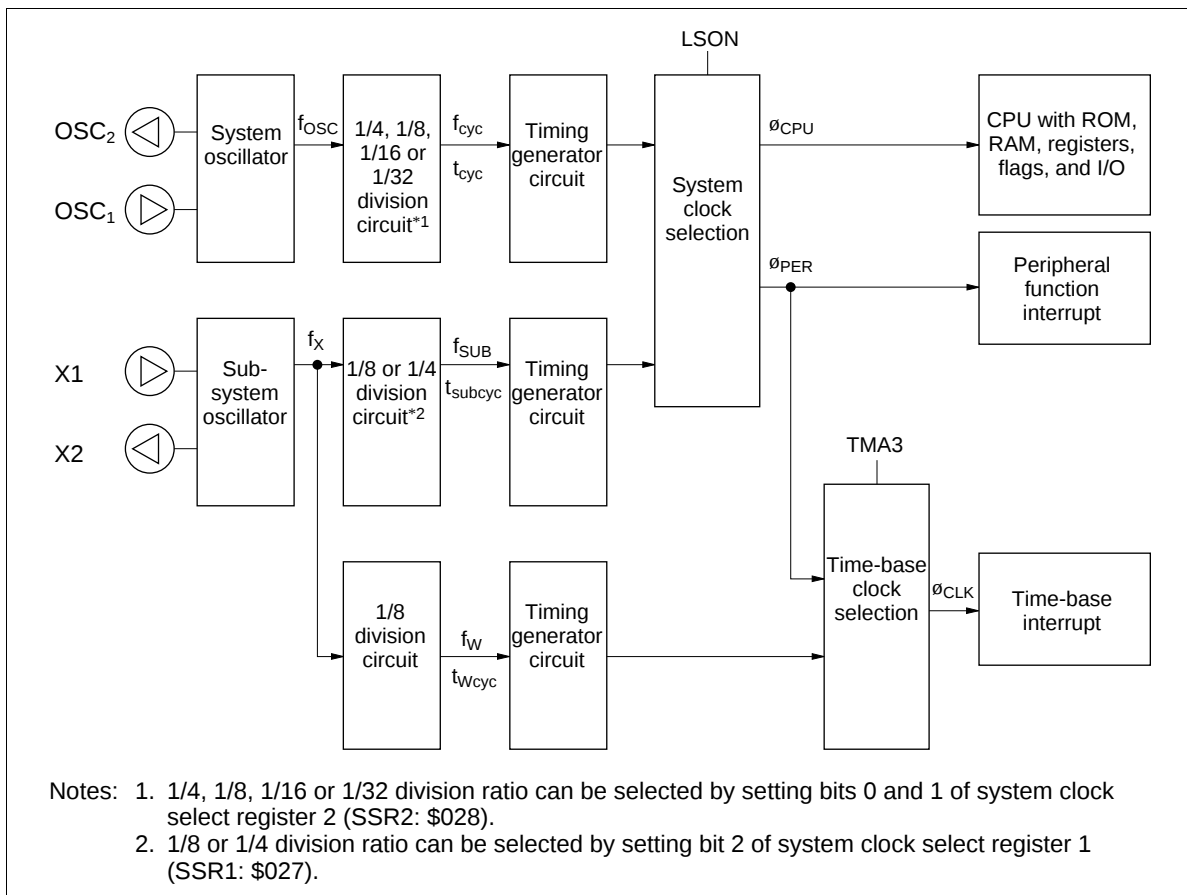
### Oscillator Circuit

A block diagram of the clock generation circuit is shown in figure 22. As shown in table 20, a ceramic oscillator or crystal oscillator can be connected to OSC<sub>1</sub> and OSC<sub>2</sub>, and a 32.768-kHz oscillator can be connected to X1 and X2. The system oscillator can also be operated by an external clock.

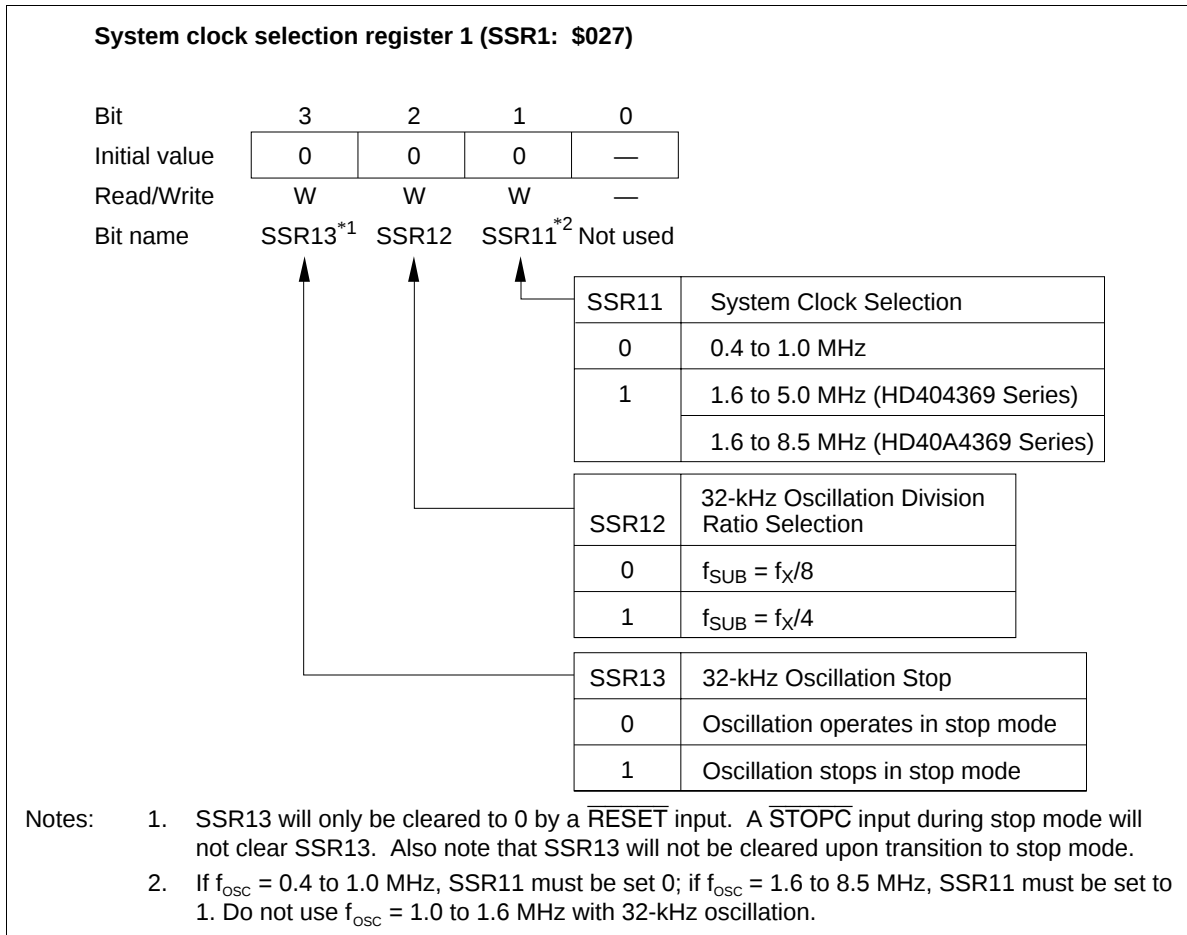
### Registers for Oscillator Circuit Operation

**System Clock Selection Register 1 (SSR1: \$027):** Four bit write-only register which sets the subsystem clock frequency ( $f_{SUB}$ ) division ratio, and sets the subsystem clock oscillation in stop mode. Bit 1 (SSR11) of system clock select register 1 must be set according to the frequency of the oscillator connected to OSC<sub>1</sub> and OSC<sub>2</sub> (figure 23).

Bit 1 (SSR11) and bit 2 (SSR12) are initialized to 0 on reset and in stop mode. Bit 3 (SSR13) is initialized to 0 only on reset.



**Figure 22 Clock Generation Circuit**



**Figure 23 System Clock Selection Register 1 (SSR1)**

**System Clock Selection Register 2 (SSR2: \$028):** Four bit write-only register which is used to select the system clock divisor (figure 24).

The division ratio of the system clock can be selected as 1/4, 1/8, 1/16, or 1/32 by setting bits 0 and 1 (SSR20, SSR21) of system clock select register 2 (SSR2).

The values of SSR20 and SSR21 are valid after the MCU enters watch mode. The system clock must be stopped when the division ratio is to be changed.

There are two methods for changing the system clock divisor, as follows.

- In active mode, set the divisor by writing to SSR20 and SSR21. At this point, the prior divisor setting will remain in effect. Now, switch to watch mode, and then return to active mode. When active mode resumes, the system clock divisor will have switched to the new value.
- In subactive mode, set the divisor by writing to SSR20 and SSR21. Then return to active mode through watch mode. When active mode resumes, the system clock divisor will have switched to the new value. (The change will also take effect for direct transition to active mode.)

# HD404369 Series

SSR2 is initialized to \$0 on reset or in stop mode.

## Notes on Usage

If the system clock select register 1 (SSR1: \$027) setting does not match the oscillator frequency, the subsystem using the 32.768-kHz oscillation will malfunction.

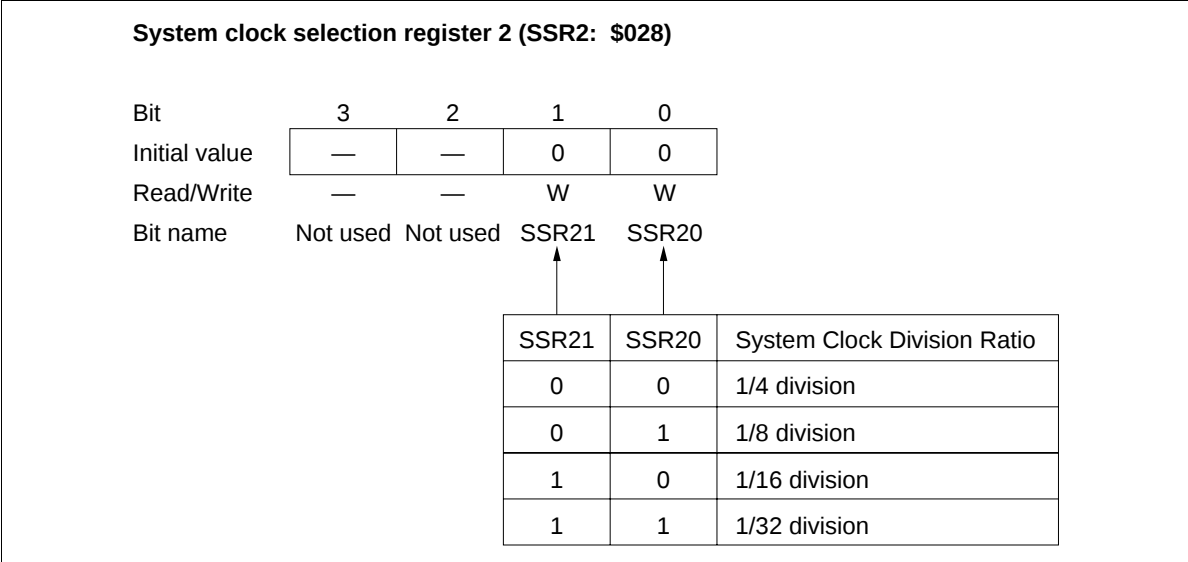
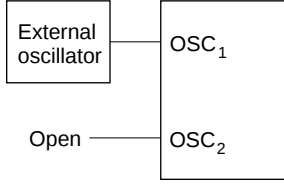
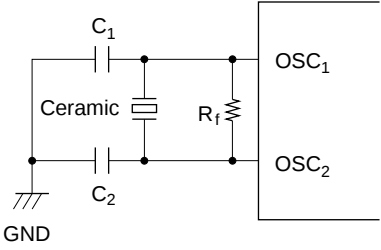
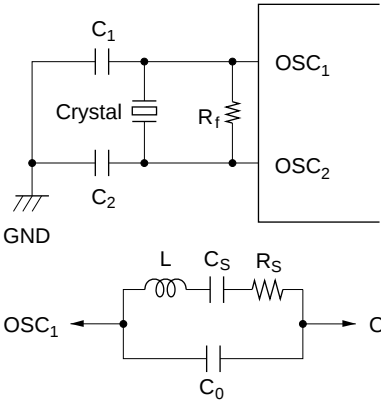
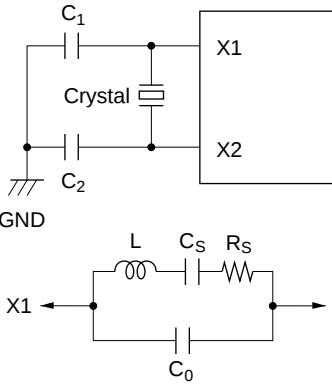
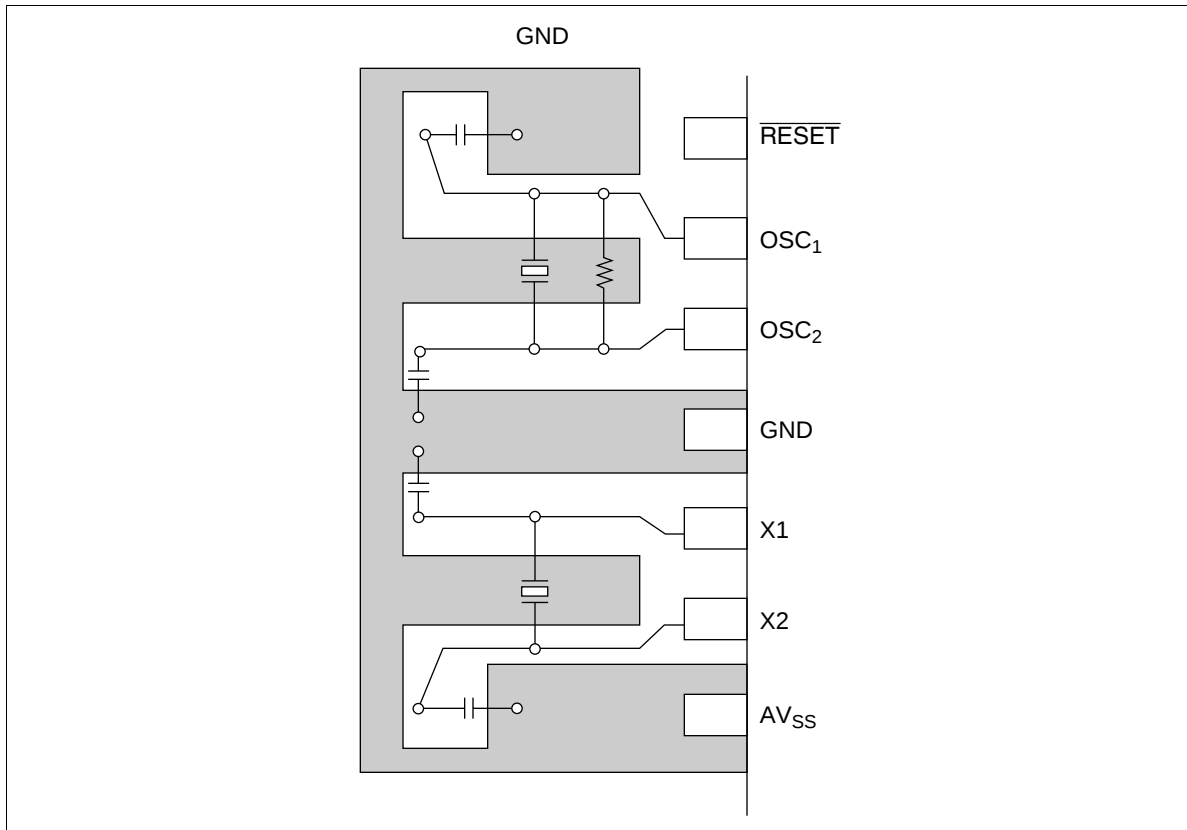


Figure 24 System Clock Selection Register 2 (SSR2)

Table 20 Oscillator Circuit Examples

| Circuit Configuration                                                                                                                           | Circuit Constants                                                                                                                                                                                                                                                           |
|-------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <p>External clock operation</p>                                |                                                                                                                                                                                                                                                                             |
| <p>Ceramic oscillator (OSC<sub>1</sub>, OSC<sub>2</sub>)</p>   | <p>Ceramic oscillator: CSA4.00MG (Murata)</p> <p><math>R_f = 1\text{ M}\Omega \pm 20\%</math></p> <p><math>C_1 = C_2 = 30\text{ pF} \pm 20\%</math></p>                                                                                                                     |
| <p>Crystal oscillator (OSC<sub>1</sub>, OSC<sub>2</sub>)</p>  | <p><math>R_f = 1\text{ M}\Omega \pm 20\%</math></p> <p><math>C_1 = C_2 = 10\text{ to }22\text{ pF} \pm 20\%</math></p> <p>Crystal: Equivalent to circuit shown below</p> <p><math>C_0 = 7\text{ pF max.}</math></p> <p><math>R_s = 100\text{ }\Omega\text{ max.}</math></p> |
| <p>Crystal oscillator (X1, X2)</p>                           | <p>Crystal: 32.768 kHz: MX38T (Nippon Denpa)</p> <p><math>C_1 = C_2 = 20\text{ pF} \pm 20\%</math></p> <p><math>R_s = 14\text{ k}\Omega</math></p> <p><math>C_0 = 1.5\text{ pF}</math></p>                                                                                  |

- Notes:
1. Since the circuit constants change depending on the crystal or ceramic oscillator and stray capacitance of the board, the user should consult with the crystal or ceramic oscillator manufacturer to determine the circuit parameters.
  2. Wiring among OSC<sub>1</sub>, OSC<sub>2</sub>, X1, X2 and elements should be as short as possible, and must not cross other wiring (see figure 25).
  3. When a 32.768-kHz crystal oscillator is not used, fix pin X1 to GND and leave pin X2 open.



**Figure 25 Typical Layout of Crystal and Ceramic Oscillators**

## **Input/Output**

The MCU has 53 input/output pins ( $D_0$ – $D_{13}$ ,  $R0$ – $R9$ ) and an input pin ( $RA_1$ ). The features are described below.

- Eight pins ( $R1$ – $R2$ ) are high-current (15 mA max) input/output with intermediate voltage NMOS open drain pins.
- The  $D_0$ – $D_4$ ,  $R0$ ,  $R3$ – $R5$  input/output pins are multiplexed with peripheral function pins such as for the timers or serial interface. For these pins, the peripheral function setting is done prior to the D or R port setting. Therefore, when a peripheral function is selected for a pin, the pin function and input/output selection are automatically switched according to the setting.
- Input or output selection for input/output pins and port or peripheral function selection for multiplexed pins are set by software.
- Peripheral function output pins are CMOS output pins. Only the  $R0_2/SO$  pin can be set to NMOS open-drain output by software.
- In stop mode, the MCU is reset, and therefore peripheral function selection is cancelled. Input/output pins are in high-impedance state.
- Each input/output pin except for  $R1$  and  $R2$  has a built-in pull-up MOS, which can be individually turned on or off by software.

I/O buffer configuration is shown in figure 26, programmable I/O circuits are listed in table 21, and I/O pin circuit types are shown in table 22.

# HD404369 Series

Table 21 Programmable I/O Circuits

| MIS3 (bit 3 of MIS) |      | 0 |   | 1  |    | 0 |    | 1  |    |
|---------------------|------|---|---|----|----|---|----|----|----|
| DCD, DCR            |      | 0 |   | 1  |    | 0 |    | 1  |    |
| PDR                 |      | 0 | 1 | 0  | 1  | 0 | 1  | 0  | 1  |
| CMOS buffer         | PMOS | — | — | —  | On | — | —  | —  | On |
|                     | NMOS | — | — | On | —  | — | —  | On | —  |
| Pull-up MOS         |      | — | — | —  | —  | — | On | —  | On |

Note: — indicates off status.

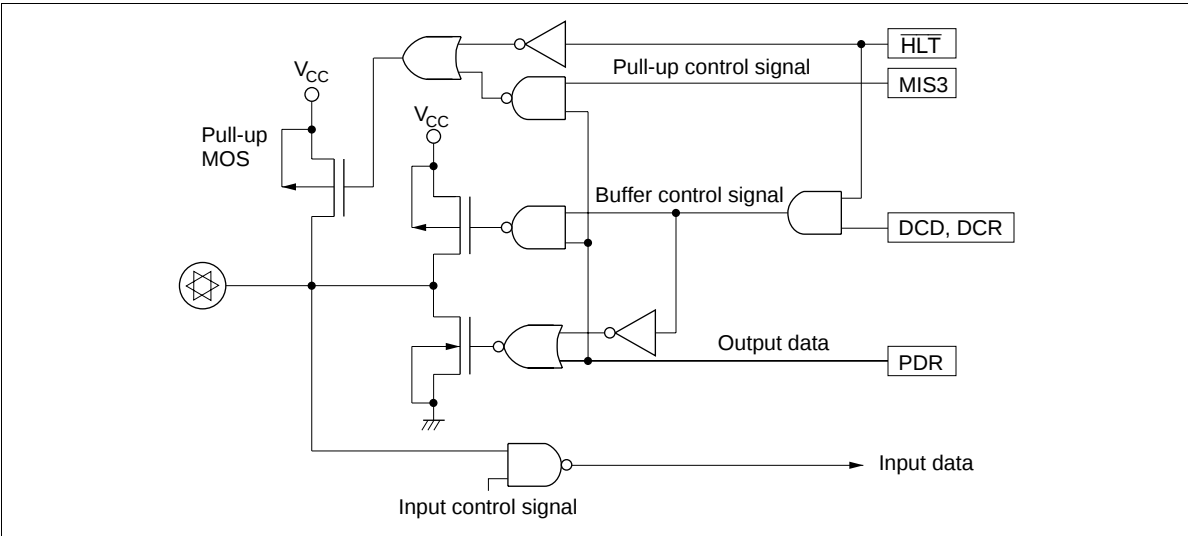


Figure 26 I/O Buffer Configuration

Table 22 Circuit Configuration of I/O Pins

| I/O Pin Type      | Circuit | Pins                                                |
|-------------------|---------|-----------------------------------------------------|
| Input/output pins |         | $D_0-D_{13}$ ,<br>$R0_0, R0_1, R0_3$<br>$R3_0-R9_3$ |
|                   |         | $R0_2$                                              |
|                   |         | $R1_0-R2_3$                                         |
| Input pins        |         | $RA_1$                                              |

Notes on next page.

## HD404369 Series

| I/O Pin Type             |                   | Circuit | Pins                                                                                                 |
|--------------------------|-------------------|---------|------------------------------------------------------------------------------------------------------|
| Peripheral function pins | Input/output pins |         | SCK                                                                                                  |
| Output pins              |                   |         | SO                                                                                                   |
|                          |                   |         | TOC, BUZZ                                                                                            |
| Input pins               |                   |         | SI,<br>$\overline{\text{INT}}_0$ , $\overline{\text{INT}}_1$ ,<br>EVNB,<br>$\overline{\text{STOPC}}$ |
|                          |                   |         | AN <sub>0</sub> -AN <sub>11</sub>                                                                    |

- Notes: 1. In stop mode, the MCU is reset and the peripheral function selection is cancelled. The  $\overline{\text{HLT}}$  signal goes low, and input/output pins enter the high-impedance state.
2. The  $\overline{\text{HLT}}$  signal is 1 in active, standby, watch, and subactive modes.

### Evaluation Chip Set and ZTAT™/Mask ROM Product Differences

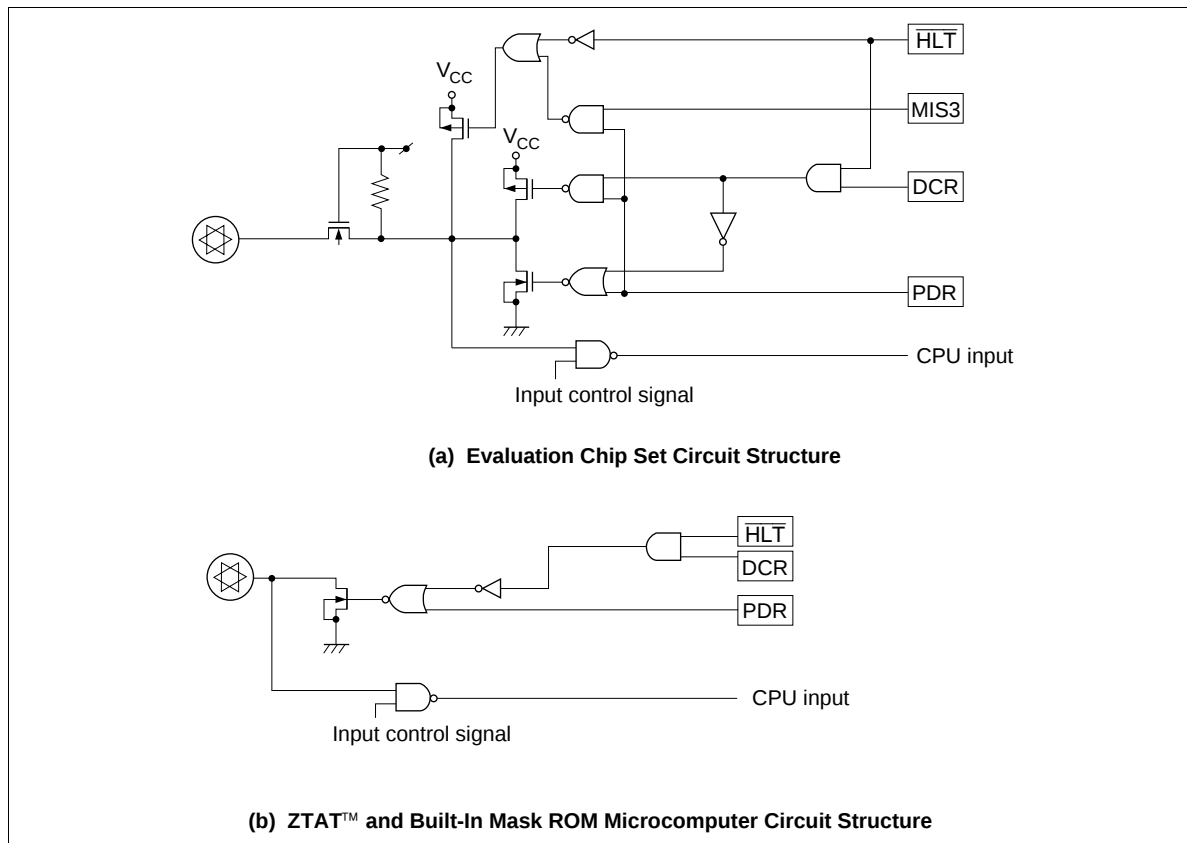
As shown in figure 27, the NMOS intermediate-voltage open drain pin circuit in the evaluation chip set differs from that used in the ZTAT™ microcomputer and built-in mask ROM microcomputer products.

Please note that although these outputs in the ZTAT™ microcomputer and built-in mask ROM microcomputer products can be set to high impedance by the combinations shown in table 23, these outputs cannot be set to high impedance in the evaluation chip set.

**Table 23 Program Control of High Impedance States**

| Register | Set Value |   |
|----------|-----------|---|
| DCR      | 0         | 1 |
| PDR      | *         | 1 |

Notes: \* An asterisk indicates that the value may be either 0 or 1 and has no influence on circuit operation. This applies to the ZTAT™ and built-in mask ROM microcomputer NMOS open drain pins.



**Figure 27 NMOS Intermediate-Voltage Open Drain Pin Circuits**

---

## HD404369 Series

---

**D Port (D<sub>0</sub>–D<sub>13</sub>):** Consist of 14 input/output pins addressed by one bit.

Pins D<sub>0</sub>–D<sub>13</sub> are set by the SED and SEDD instructions, and reset by the RED and REDD instructions. Output data is stored in the port data register (PDR) for each pin. All pins D<sub>0</sub>–D<sub>13</sub> are tested by the TD and TDD instructions.

The on/off statuses of the output buffers are controlled by D-port data control registers (DCD0–DCD3: \$02C–\$02F) that are mapped to memory addresses (figure 28).

Pins D<sub>0</sub>–D<sub>2</sub>, D<sub>4</sub> are multiplexed with peripheral function pins  $\overline{\text{INT}}_0$ ,  $\overline{\text{INT}}_1$ , EVNB, and  $\overline{\text{STOPC}}$ , respectively. The peripheral function modes of these pins are selected by bits 0–3 (PMRB0–PMRB3) of port mode register B (PMRB: \$024) (figure 29).

Pin D<sub>3</sub> is multiplexed with peripheral function pin BUZZ. The peripheral function mode of this pin is selected by bit 3 (PMRA3) of port mode register A (PMRA: \$004) (figure 30).

**R Ports (R<sub>0</sub>–R<sub>9</sub>):** 39 input/output pins addressed in 4-bit units. Data is input to these ports by the LAR and LBR instructions, and output from them by the LRA and LRB instructions. Output data is stored in the port data register (PDR) for each pin. The on/off statuses of the output buffers of the R ports are controlled by R-port data control registers (DCR0–DCR9: \$030–\$039) that are mapped to memory addresses (figure 28).

Pin R<sub>0</sub> is multiplexed with peripheral function pin  $\overline{\text{SCK}}$ . The peripheral function mode of this pin is selected by bit 3 (SMR3) of serial mode register (SMR: \$005) (figure 31).

Pins R<sub>0</sub>–R<sub>3</sub> are multiplexed with peripheral pins SI, SO and TOC, respectively. The peripheral function modes of these pins are selected by bits 0–2 (PMRA0–PMRA2) of port mode register A (PMRA: \$004), as shown in figure 30.

Port R3 is multiplexed with peripheral function pins AN<sub>0</sub>–AN<sub>3</sub>, respectively. The peripheral function modes of these pins can be selected by individual pins, by setting A/D mode register 1 (AMR1: \$019) (figure 32).

Ports R4 and R5 are multiplexed with peripheral function pins AN<sub>4</sub>–AN<sub>11</sub>, respectively. The peripheral function modes of these pins can be selected in 4-pin units by setting bits 1 and 2 (AMR21, AMR22) of A/D mode register 2 (AMR2: \$01A) (figure 33).

**Pull-Up MOS Transistor Control:** A program-controlled pull-up MOS transistor is provided for each input/output pin. The on/off status of all these transistors is controlled by bit 3 (MIS3) of the miscellaneous register (MIS: \$00C), and the on/off status of an individual transistor can also be controlled by the port data register (PDR) of the corresponding pin—enabling on/off control of that pin alone (table 21 and figure 34).

The on/off status of each transistor and the peripheral function mode of each pin can be set independently.

**How to Deal with Unused I/O Pins:** I/O pins that are not needed by the user system (floating) must be connected to V<sub>CC</sub> to prevent LSI malfunctions due to noise. These pins must either be pulled up to V<sub>CC</sub> by their pull-up MOS transistors or by resistors of about 100 k $\Omega$ .

**Data control register (DCD0 to 3: \$02C to \$02F)  
(DCR0 to 9: \$030 to \$039)**

**DCD0 to DCD3, DCR0 to DCR9**

|               |                                                         |                                     |                                     |                                     |
|---------------|---------------------------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| Bit           | 3                                                       | 2                                   | 1                                   | 0                                   |
| Initial value | 0                                                       | 0                                   | 0                                   | 0                                   |
| Read/Write    | W                                                       | W                                   | W                                   | W                                   |
| Bit name      | DCD03–<br>DCD23,<br>DCR03–<br>DCR63,<br>DCR83–<br>DCR93 | DCD02–<br>DCD22,<br>DCR02–<br>DCR92 | DCD01–<br>DCD31,<br>DCR01–<br>DCR91 | DCD00–<br>DCD30,<br>DCR00–<br>DCR90 |

**Bits 0 to 3 CMOS Buffer On/Off Selection**

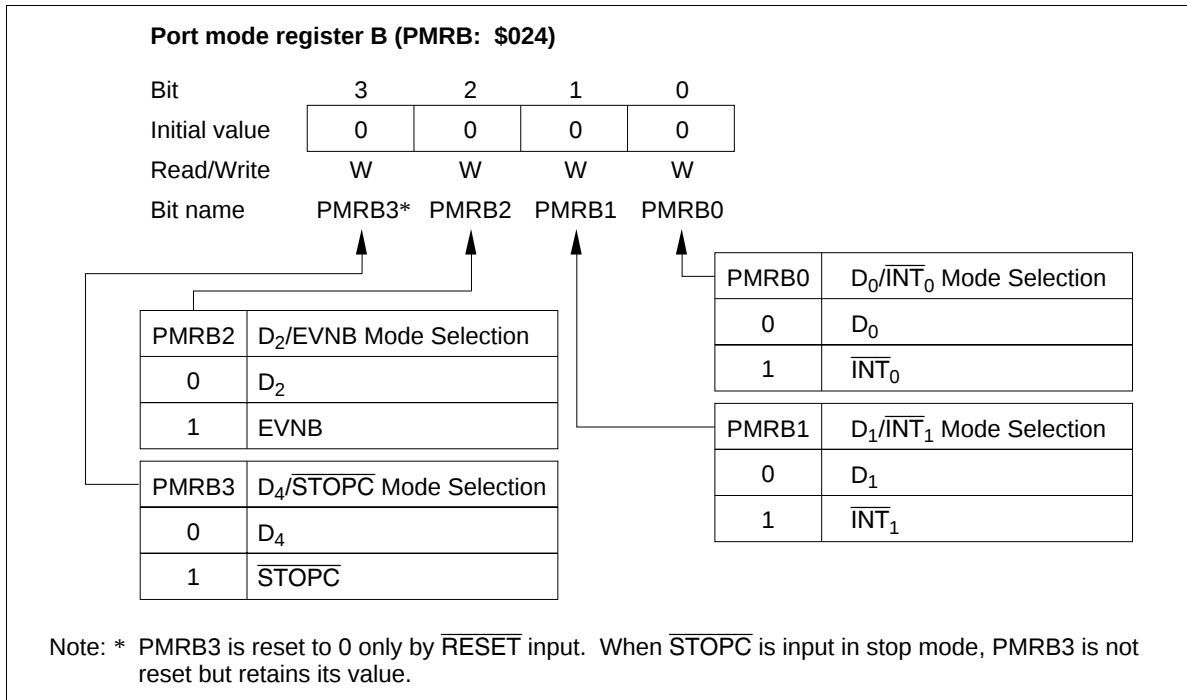
|   |                      |
|---|----------------------|
| 0 | Off (high-impedance) |
| 1 | On                   |

Correspondence between ports and DCD/DCR bits

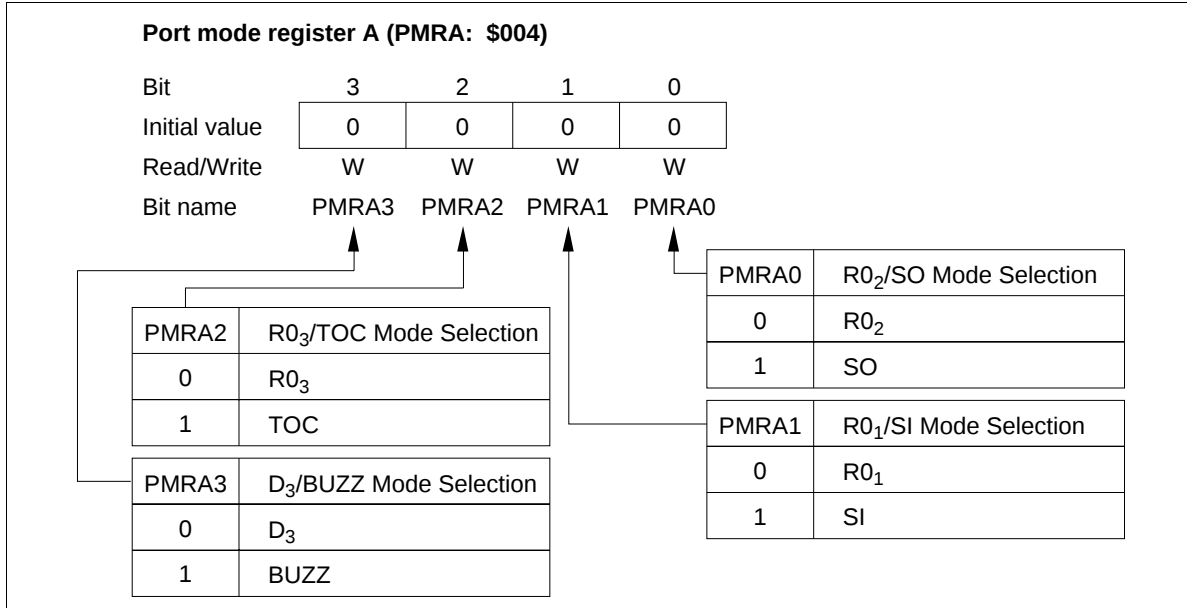
| Register Name | Bit 3           | Bit 2           | Bit 1           | Bit 0           |
|---------------|-----------------|-----------------|-----------------|-----------------|
| DCD0          | D <sub>3</sub>  | D <sub>2</sub>  | D <sub>1</sub>  | D <sub>0</sub>  |
| DCD1          | D <sub>7</sub>  | D <sub>6</sub>  | D <sub>5</sub>  | D <sub>4</sub>  |
| DCD2          | D <sub>11</sub> | D <sub>10</sub> | D <sub>9</sub>  | D <sub>8</sub>  |
| DCD3          | Not used        | Not used        | D <sub>13</sub> | D <sub>12</sub> |
| DCR0          | R <sub>03</sub> | R <sub>02</sub> | R <sub>01</sub> | R <sub>00</sub> |
| DCR1          | R <sub>13</sub> | R <sub>12</sub> | R <sub>11</sub> | R <sub>10</sub> |
| DCR2          | R <sub>23</sub> | R <sub>22</sub> | R <sub>21</sub> | R <sub>20</sub> |
| DCR3          | R <sub>33</sub> | R <sub>32</sub> | R <sub>31</sub> | R <sub>30</sub> |
| DCR4          | R <sub>43</sub> | R <sub>42</sub> | R <sub>41</sub> | R <sub>40</sub> |
| DCR5          | R <sub>53</sub> | R <sub>52</sub> | R <sub>51</sub> | R <sub>50</sub> |
| DCR6          | R <sub>63</sub> | R <sub>62</sub> | R <sub>61</sub> | R <sub>60</sub> |
| DCR7          | Not used        | R <sub>72</sub> | R <sub>71</sub> | R <sub>70</sub> |
| DCR8          | R <sub>83</sub> | R <sub>82</sub> | R <sub>81</sub> | R <sub>80</sub> |
| DCR9          | R <sub>93</sub> | R <sub>92</sub> | R <sub>91</sub> | R <sub>90</sub> |

**Figure 28 Data Control Registers (DCD, DCR)**

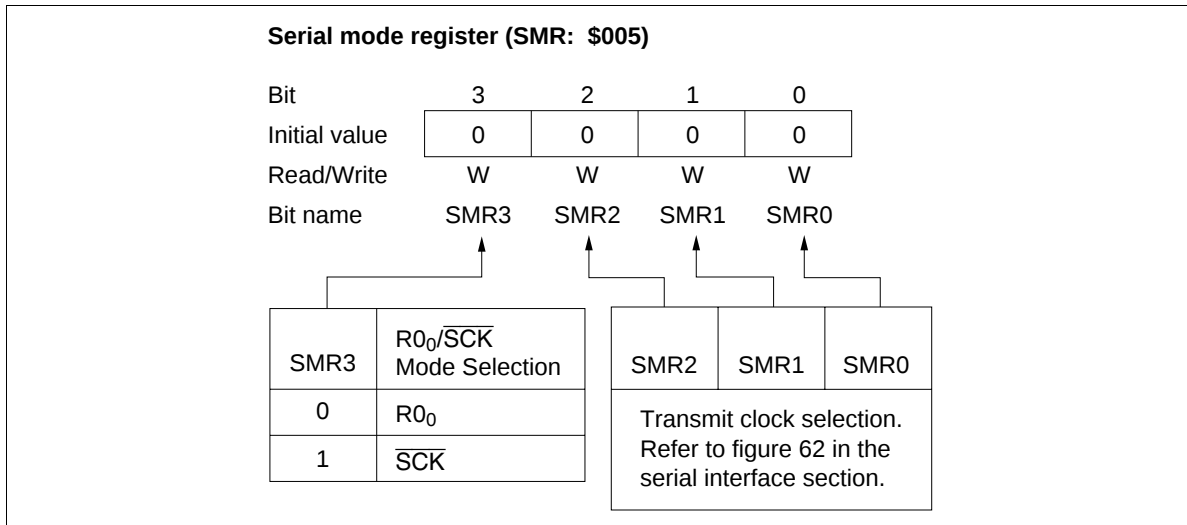
## HD404369 Series



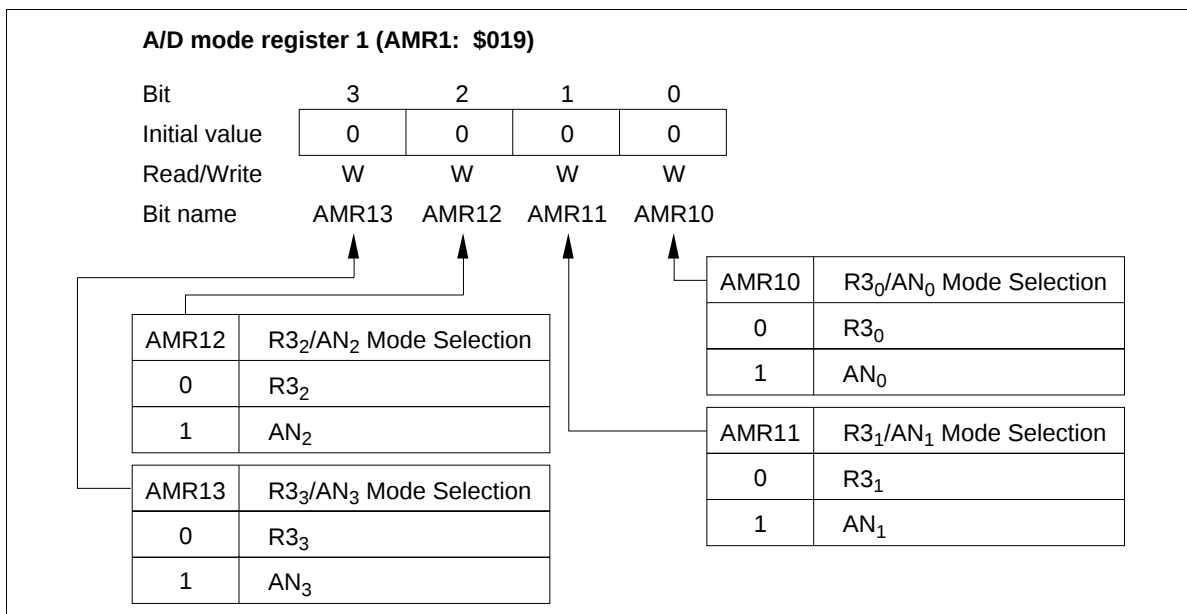
**Figure 29 Port Mode Register B (PMRB)**



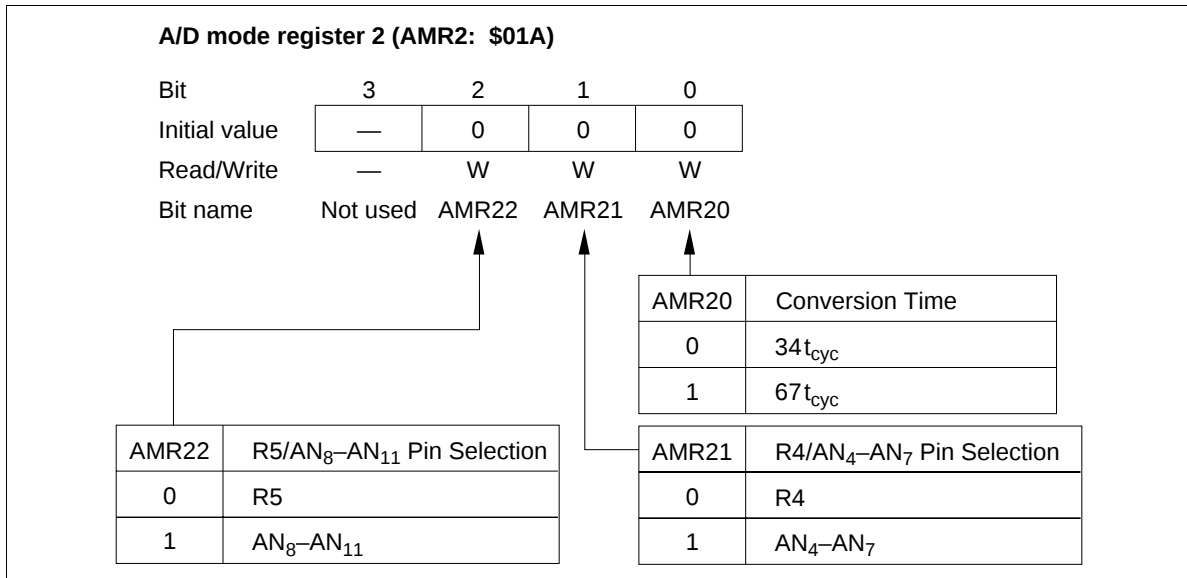
**Figure 30 Port Mode Register A (PMRA)**



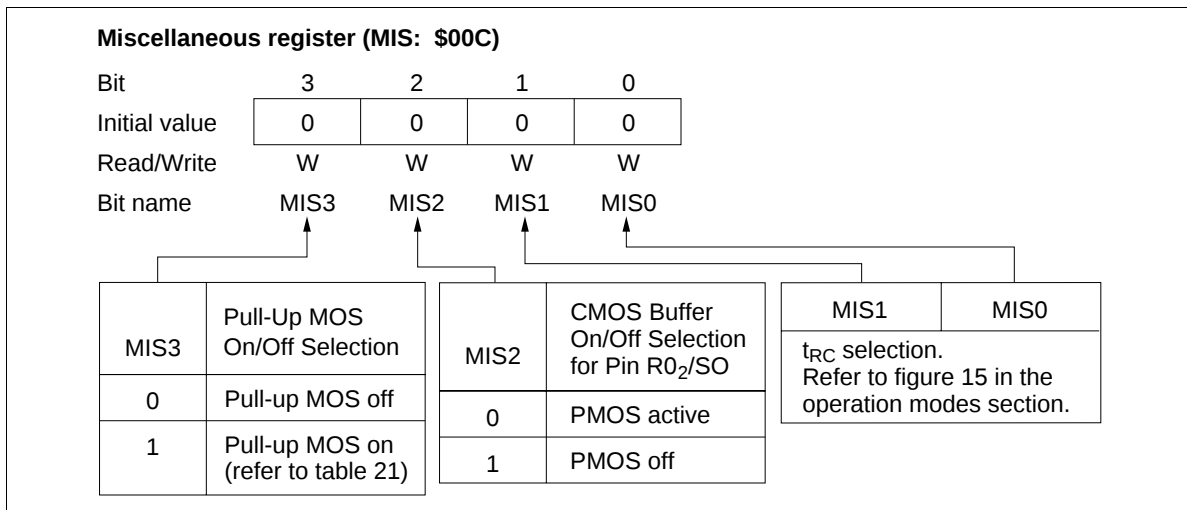
**Figure 31 Serial Mode Register (SMR)**



**Figure 32 A/D Mode Register 1 (AMR1)**



**Figure 33 A/D Mode Register 2 (AMR2)**



**Figure 34 Miscellaneous Register (MIS)**

## Prescalers

The MCU has the following two prescalers, S and W.

The prescaler operating conditions are listed in table 24, and the prescaler output supply is shown in figure 35. The timer A–C input clocks except external events and the serial transmit clock except the external clock are selected from the prescaler outputs, depending on corresponding mode registers.

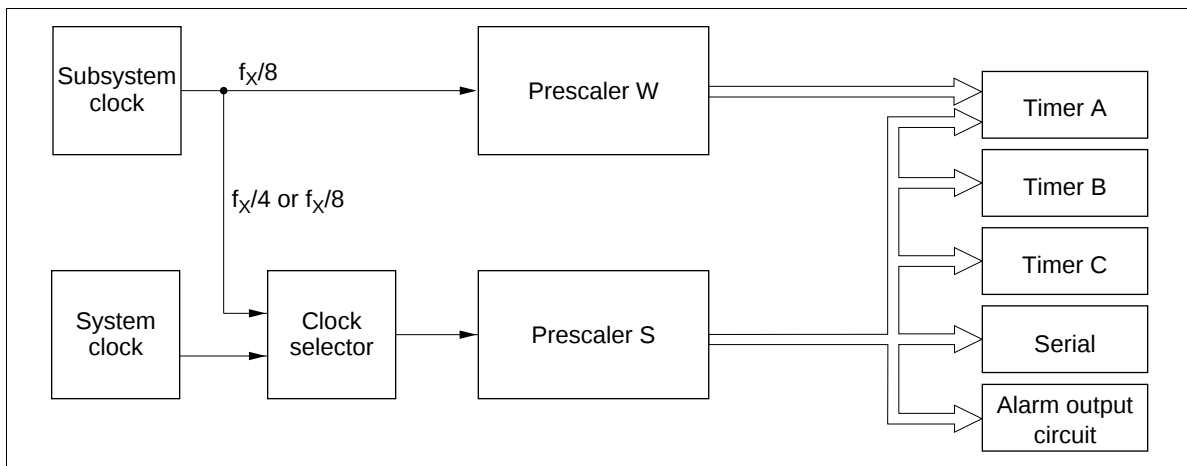
### Prescaler Operation

**Prescaler S:** 11-bit counter that inputs the system clock signal. After being reset to \$000 by MCU reset, prescaler S divides the system clock. Prescaler S keeps counting, except in watch and subactive modes and at MCU reset.

**Prescaler W:** Five-bit counter that inputs the X1 input clock signal (32-kHz crystal oscillation) divided by eight. After being reset to \$00 by MCU reset, prescaler W divides the input clock. Prescaler W can be reset by software.

**Table 24 Prescaler Operating Conditions**

| Prescaler   | Input Clock                                                                          | Reset Conditions    | Stop Conditions                     |
|-------------|--------------------------------------------------------------------------------------|---------------------|-------------------------------------|
| Prescaler S | System clock<br>(in active and standby mode), subsystem clock<br>(in subactive mode) | MCU reset           | MCU reset, stop mode,<br>watch mode |
| Prescaler W | 32-kHz crystal oscillation                                                           | MCU reset, software | MCU reset, stop mode                |



**Figure 35 Prescaler Output Supply**

### Timers

The MCU has four timer/counters (A to C).

- Timer A: Free-running timer
- Timer B: Multifunction timer
- Timer C: Multifunction timer

Timer A is an 8-bit free-running timer. Timers B and C are 8-bit multifunction timers, whose functions are listed in table 25. The operating modes are selected by software.

### Timer A

**Timer A Functions:** Timer A has the following functions.

- Free-running timer
- Clock time-base

The block diagram of timer A is shown in figure 36.

### Timer A Operations:

- Free-running timer operation: The input clock for timer A is selected by timer mode register A (TMA: \$008).

Timer A is reset to \$00 by MCU reset and incremented at each input clock. If an input clock is applied to timer A after it has reached \$FF, an overflow is generated, and timer A is reset to \$00. The overflow sets the timer A interrupt request flag (IFTA: \$001, bit 2). Timer A continues to be incremented after reset to \$00, and therefore it generates regular interrupts every 256 clocks.

- Clock time-base operation: Timer A is used as a clock time-base by setting bit 3 (TMA3) of timer mode register A (TMA: \$008) to 1. The prescaler W output is applied to timer A, and timer A generates interrupts at the correct timing based on the 32.768-kHz crystal oscillation. In this case, prescaler W and timer A can be reset to \$00 by software.

**Registers for Timer A Operation:** Timer A operating modes are set by the following registers.

- Timer mode register A (TMA: \$008): Four-bit write-only register that selects timer A's operating mode and input clock source as shown in figure 37.

Table 25 Timer Functions

| Functions       |                | Timer A   | Timer B   | Timer C   |
|-----------------|----------------|-----------|-----------|-----------|
| Clock source    | Prescaler S    | Available | Available | Available |
|                 | Prescaler W    | Available | —         | —         |
|                 | External event | —         | Available | —         |
| Timer functions | Free-running   | Available | Available | Available |
|                 | Time-base      | Available | —         | —         |
|                 | Event counter  | —         | Available | —         |
|                 | Reload         | —         | Available | Available |
|                 | Watchdog       | —         | —         | Available |
|                 | Input capture  | —         | Available | —         |
| Timer output    | PWM            | —         | —         | Available |

Note: — implies not available.

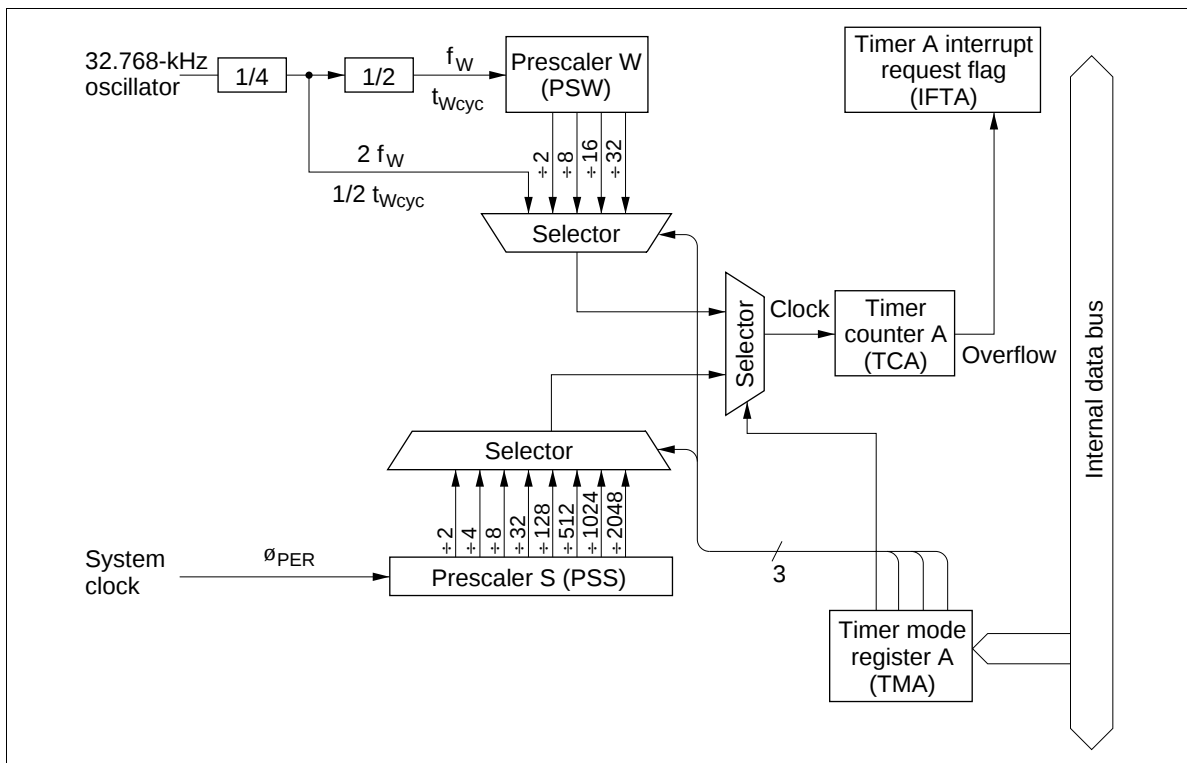


Figure 36 Timer A Block Diagram

## HD404369 Series

### Timer mode register A (TMA: \$008)

|               |      |      |      |      |
|---------------|------|------|------|------|
| Bit           | 3    | 2    | 1    | 0    |
| Initial value | 0    | 0    | 0    | 0    |
| Read/Write    | W    | W    | W    | W    |
| Bit name      | TMA3 | TMA2 | TMA1 | TMA0 |

| TMA3 | TMA2 | TMA1 | TMA0       | Source Prescaler  | Input Clock Frequency | Operating Mode |
|------|------|------|------------|-------------------|-----------------------|----------------|
| 0    | 0    | 0    | 0          | PSS               | 2048t <sub>cyc</sub>  | Timer A mode   |
|      |      |      | 1          | PSS               | 1024t <sub>cyc</sub>  |                |
|      |      | 1    | 0          | PSS               | 512t <sub>cyc</sub>   |                |
|      |      |      | 1          | PSS               | 128t <sub>cyc</sub>   |                |
|      | 1    | 0    | 0          | PSS               | 32t <sub>cyc</sub>    |                |
|      |      |      | 1          | PSS               | 8t <sub>cyc</sub>     |                |
|      |      | 1    | 0          | PSS               | 4t <sub>cyc</sub>     |                |
|      |      |      | 1          | PSS               | 2t <sub>cyc</sub>     |                |
| 1    | 0    | 0    | 0          | PSW               | 32t <sub>wcyc</sub>   | Time-base mode |
|      |      |      | 1          | PSW               | 16t <sub>wcyc</sub>   |                |
|      |      | 1    | 0          | PSW               | 8t <sub>wcyc</sub>    |                |
|      |      |      | 1          | PSW               | 2t <sub>wcyc</sub>    |                |
|      | 1    | 0    | 0          | PSW               | 1/2t <sub>wcyc</sub>  |                |
|      |      |      | 1          | Inhibited         |                       |                |
|      |      | 1    | Don't care | PSW and TCA reset |                       |                |

- Notes:
- $t_{wcyc} = 244.14 \mu s$  (when a 32.768-kHz crystal oscillator is used)
  - Timer counter overflow output period (seconds) = input clock period (seconds)  $\times$  256.
  - The division ratio must not be modified during time-base mode operation, otherwise an overflow cycle error will occur.

**Figure 37 Timer Mode Register A (TMA)**

## **Timer B**

**Timer B Functions:** Timer B has the following functions.

- Free-running/reload timer
- External event counter
- Input capture timer

The block diagram for each operation mode of timer B is shown in figures 38 and 39.

### **Timer B Operations:**

- **Free-running/reload timer operation:** The free-running/reload operation, input clock source, and prescaler division ratio are selected by timer mode register B1 (TMB1: \$009).  
Timer B is initialized to the value set in timer write register B (TWBL: \$00A, TWBU: \$00B) by software and incremented by one at each clock input. If an input clock is applied to timer B after it has reached \$FF, an overflow is generated. In this case, if the reload timer function is enabled, timer B is initialized to its initial value set in timer write register B; if the free-running timer function is enabled, the timer is initialized to \$00 and then incremented again.  
The overflow sets the timer B interrupt request flag (IFTB: \$002, bit 0). IFTB is reset by software or MCU reset. Refer to figure 3 and table 1 for details.
- **External event counter operation:** Timer B is used as an external event counter by selecting the external event input as an input clock source. In this case, pin D<sub>2</sub>/EVNB must be set to EVNB by port mode register B (PMRB: \$024).  
Either falling or rising edge, or both falling and rising edges of input signals can be selected as the external event detection edge by timer mode register 2 (TMB2: \$026). When both rising and falling edges detection is selected, the time between the falling edge and rising edge of input signals must be  $2t_{\text{cyc}}$  or longer.  
Timer B is incremented by one at each detection edge selected by timer mode register 2 (TMB2: \$026). The other operation is basically the same as the free-running/reload timer operation.
- **Input capture timer operation:** The input capture timer counts the clock cycles between trigger edges input to pin EVNB.  
Either falling or rising edge, or both falling and rising edges of input signals can be selected as the trigger input edge by timer mode register 2 (TMB2: \$026).  
When a trigger edge is input to EVNB, the count of timer B is written to timer read register B (TRBL: \$00A, TRBU: \$00B), and the timer B interrupt request flag (IFTB: \$002, bit 0) and the input capture status flag (ICSF: \$021, bit 0) are set. Timer B is reset to \$00, and then incremented again. While ICSF is set, if a trigger input edge is applied to timer B, or if timer B generates an overflow, the input capture error flag (ICEF: \$021, bit 1) is set. ICSF and ICEF are reset to 0 by MCU reset or by writing 0.

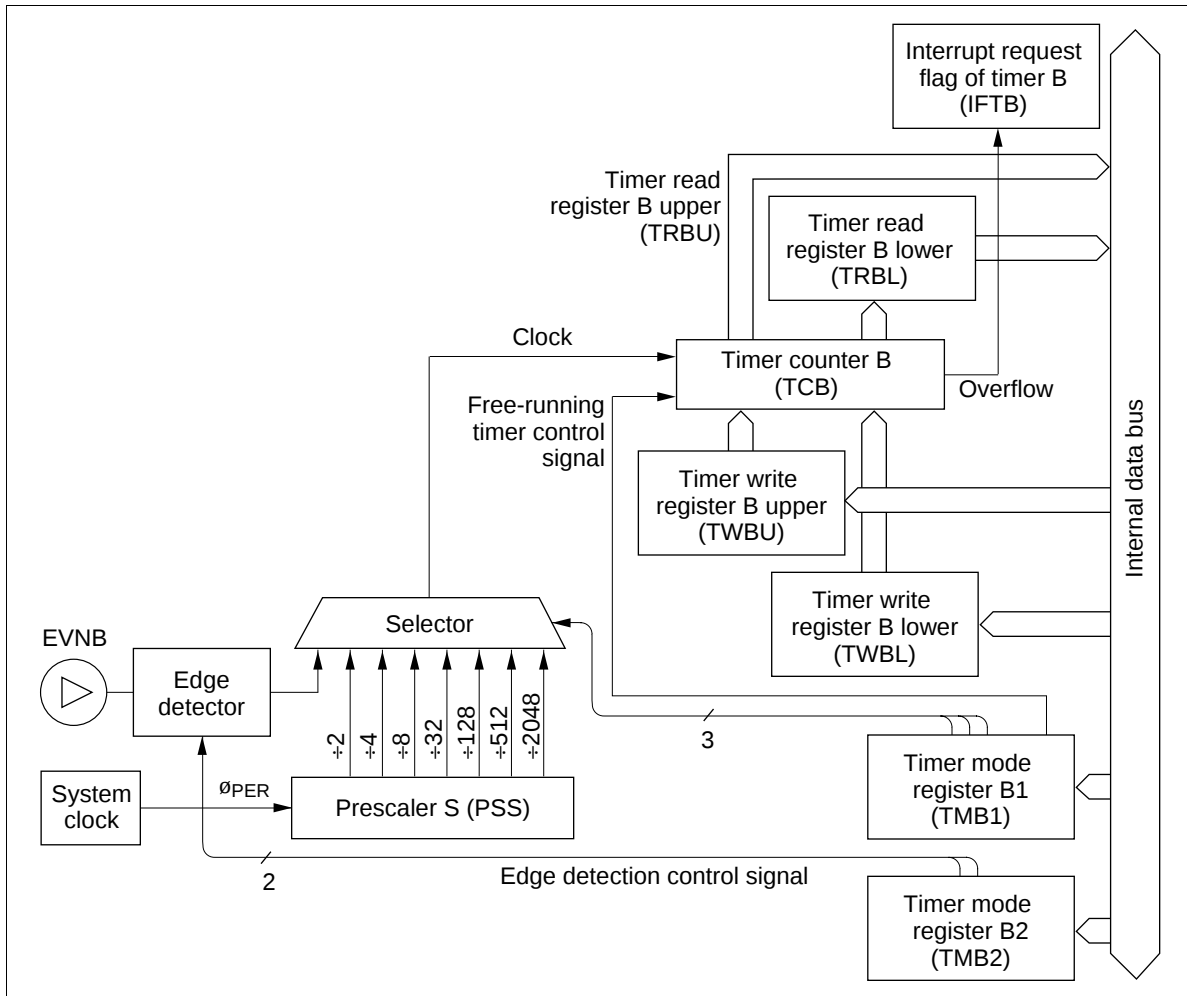


Figure 38 Timer B Free-Running and Reload Operation Block Diagram

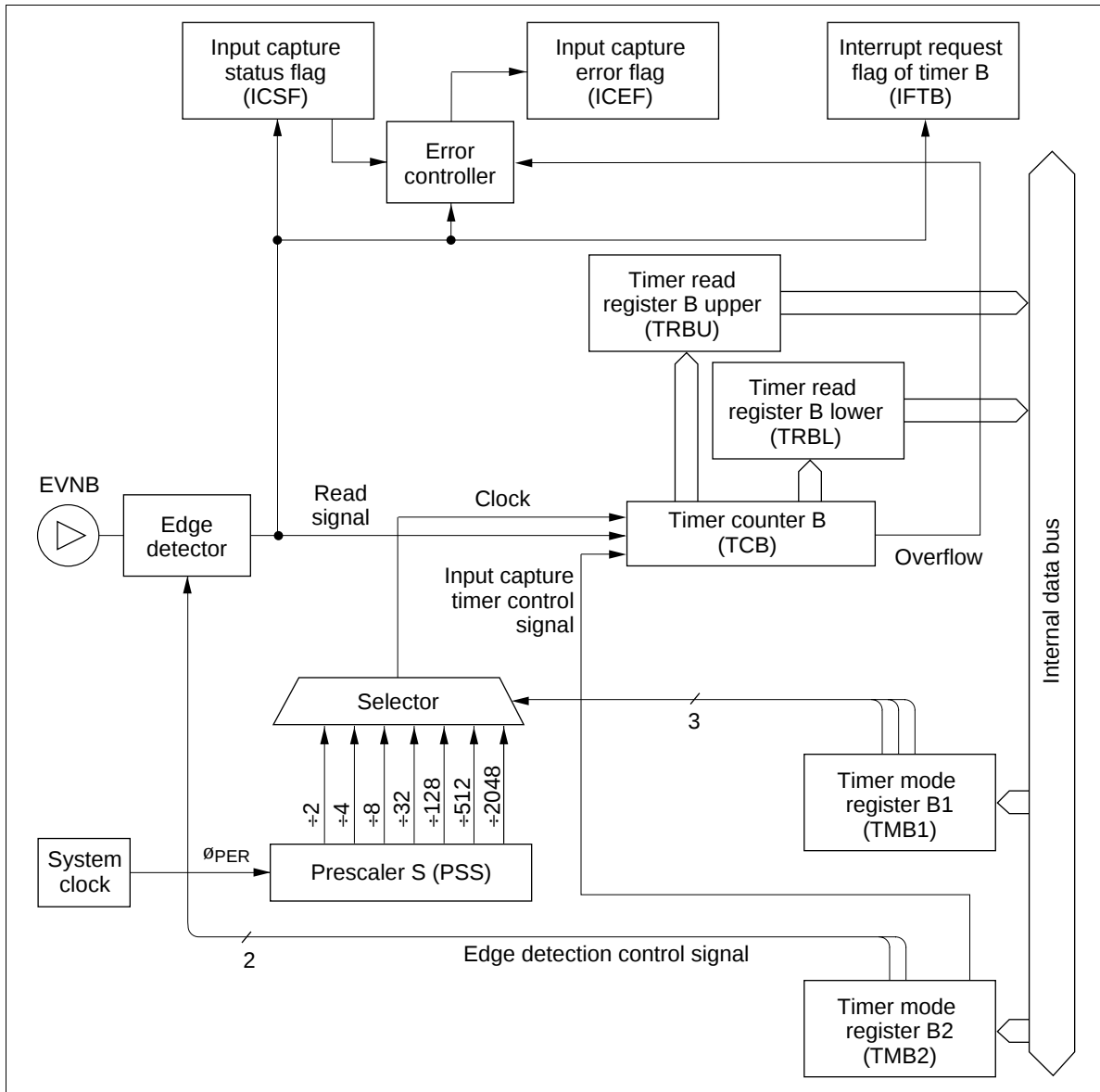


Figure 39 Timer B Input Capture Operation Block Diagram

**Registers for Timer B Operation:** By using the following registers, timer B operation modes are selected and the timer B count is read and written.

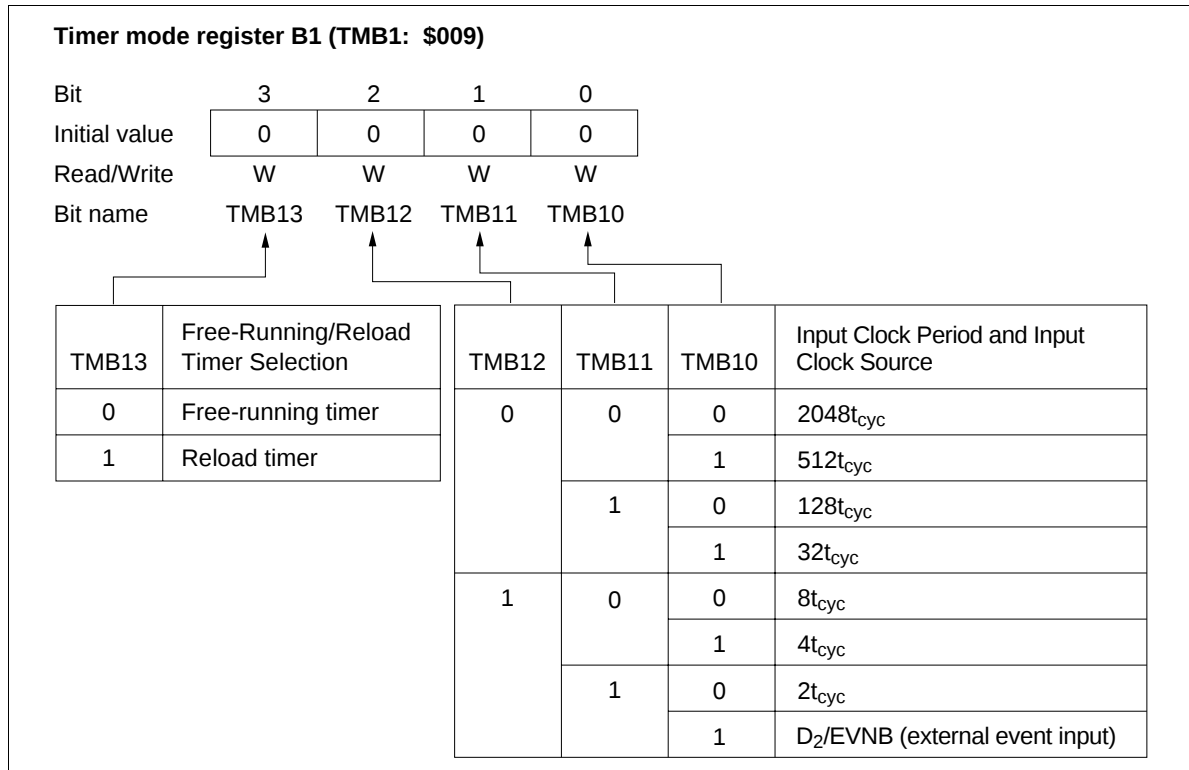
- Timer mode register B1 (TMB1: \$009)
- Timer mode register B2 (TMB2: \$026)
- Timer write register B (TWBL: \$00A, TWBU: \$00B)
- Timer read register B (TRBL: \$00A, TRBU: \$00B)
- Port mode register B (PMRB: \$024)

## HD404369 Series

- Timer mode register B1 (TMB1: \$009): Four-bit write-only register that selects the free-running/reload timer function, input clock source, and the prescaler division ratio as shown in figure 40. It is reset to \$0 by MCU reset.

Writing to this register is valid from the second instruction execution cycle after the execution of the previous timer mode register B1 write instruction. Setting timer B's initialization by writing to timer write register B (TWBL: \$00A, TWBU: \$00B) must be done after a mode change becomes valid.

When selecting the input capture timer operation, select the internal clock as the input clock source.

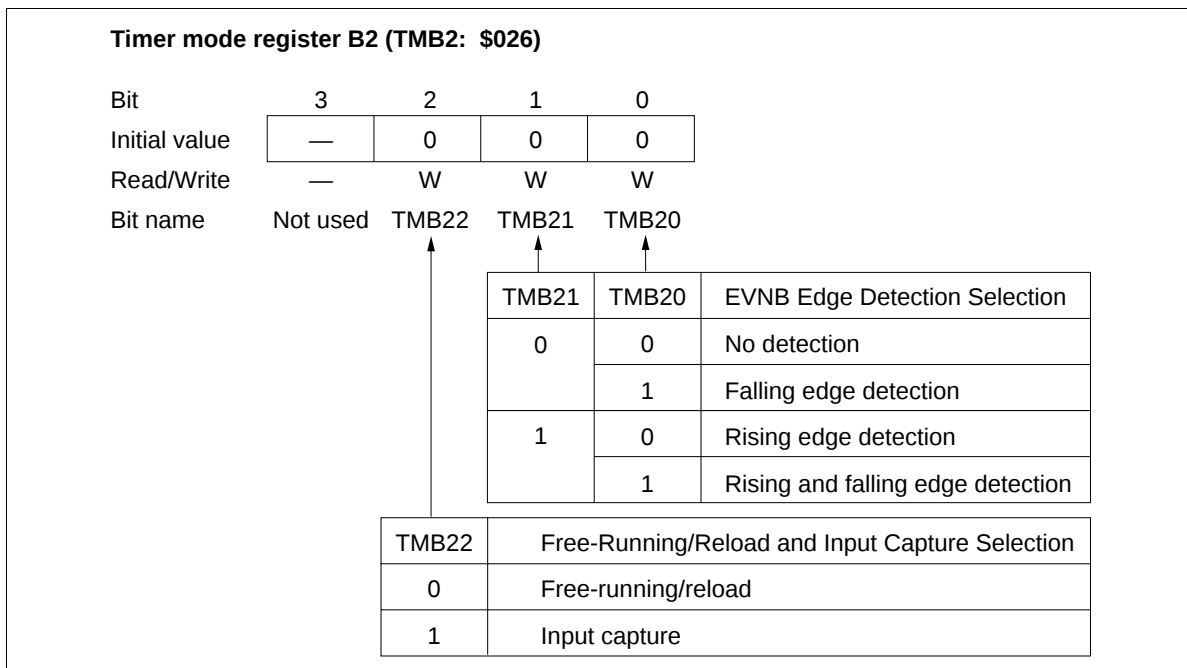


**Figure 40 Timer Mode Register B1 (TMB1)**

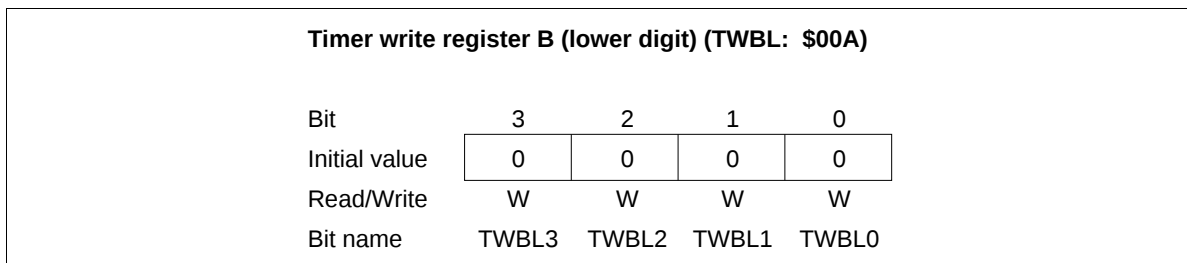
- Timer mode register B2 (TMB2: \$026): Three-bit write-only register that selects the detection edge of signals input to pin EVNB and input capture operation as shown in figure 41. It is reset to \$0 by MCU reset.
- Timer write register B (TWBL: \$00A, TWBU: \$00B): Write-only register consisting of the lower digit (TWBL) and the upper digit (TWBU). The lower digit is reset to \$0 by MCU reset, but the upper digit value is invalid (figures 42 and 43).

Timer B is initialized by writing to timer write register B (TWBL: \$00A, TWBU: \$00B). In this case, the lower digit (TWBL) must be written to first, but writing only to the lower digit does not change the timer B value. Timer B is initialized to the value in timer write register B at the same time the upper digit (TWBU) is written to. When timer write register B is written to again and if the lower digit value needs no change, writing only to the upper digit initializes timer B.

- **Timer read register B (TRBL: \$00A, TRBU: \$00B):** Read-only register consisting of the lower digit (TRBL) and the upper digit (TRBU) that holds the count of the timer B upper digit (figures 44 and 45). The upper digit (TRBU) must be read first. At this time, the count of the timer B upper digit is obtained, and the count of the timer B lower digit is latched to the lower digit (TRBL). After this, by reading TRBL, the count of timer B when TRBU is read can be obtained.  
When the input capture timer operation is selected and if the count of timer B is read after a trigger is input, either the lower or upper digit can be read first.
- **Port mode register B (PMRB: \$024):** Write-only register that selects D<sub>2</sub>/EVNB pin function as shown in figure 46. It is reset to \$0 by MCU reset.



**Figure 41 Timer Mode Register B2 (TMB2)**



**Figure 42 Timer Write Register B Lower Digit (TWBL)**

## HD404369 Series

### Timer write register B (upper digit) (TWBU: \$00B)

| Bit           | 3         | 2         | 1         | 0         |
|---------------|-----------|-----------|-----------|-----------|
| Initial value | Undefined | Undefined | Undefined | Undefined |
| Read/Write    | W         | W         | W         | W         |
| Bit name      | TWBU3     | TWBU2     | TWBU1     | TWBU0     |

**Figure 43 Timer Write Register B Upper Digit (TWBU)**

### Timer read register B (lower digit) (TRBL: \$00A)

| Bit           | 3         | 2         | 1         | 0         |
|---------------|-----------|-----------|-----------|-----------|
| Initial value | Undefined | Undefined | Undefined | Undefined |
| Read/Write    | R         | R         | R         | R         |
| Bit name      | TRBL3     | TRBL2     | TRBL1     | TRBL0     |

**Figure 44 Timer Read Register B Lower Digit (TRBL)**

### Timer read register B (upper digit) (TRBU: \$00B)

| Bit           | 3         | 2         | 1         | 0         |
|---------------|-----------|-----------|-----------|-----------|
| Initial value | Undefined | Undefined | Undefined | Undefined |
| Read/Write    | R         | R         | R         | R         |
| Bit name      | TRBU3     | TRBU2     | TRBU1     | TRBU0     |

**Figure 45 Timer Read Register B Upper Digit (TRBU)**

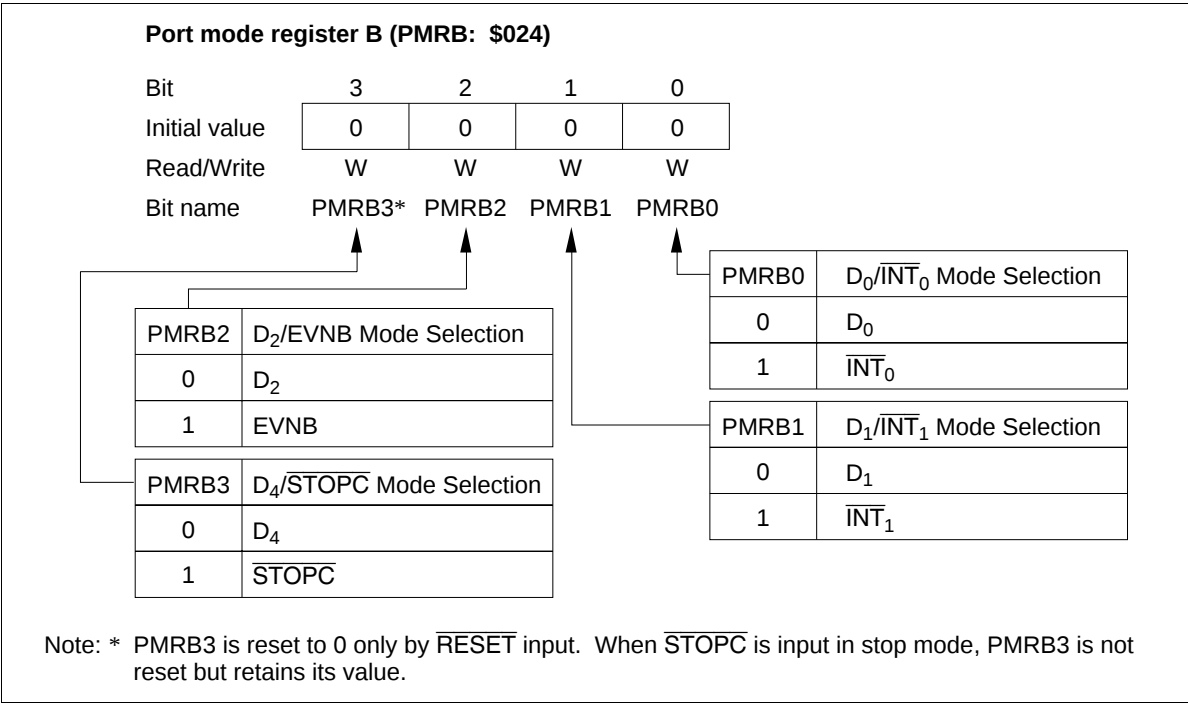


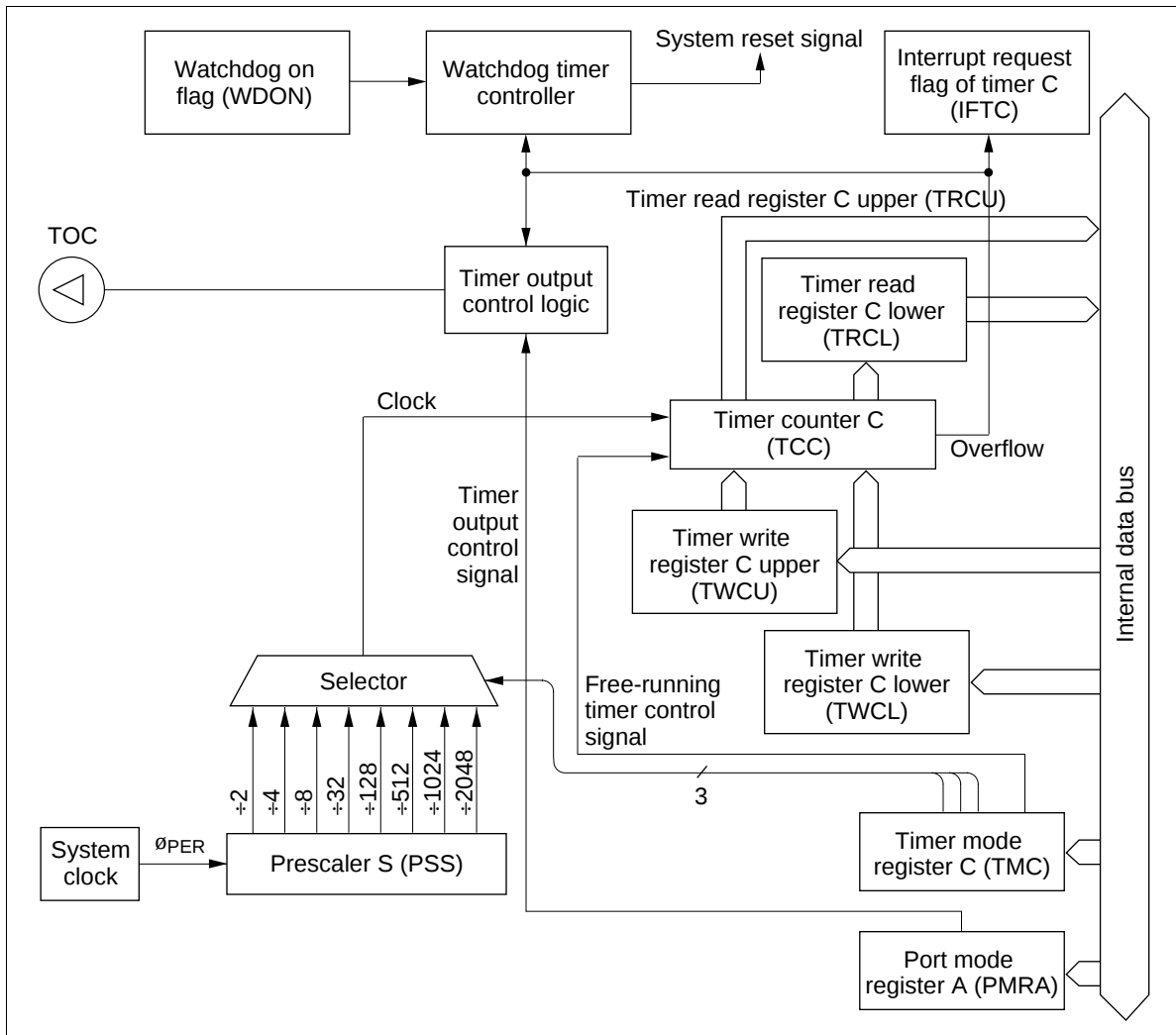
Figure 46 Port Mode Register B (PMRB)

### Timer C

**Timer C Functions:** Timer C has the following functions.

- Free-running/reload timer
- Watchdog timer
- Timer output operation (PWM output)

The block diagram of timer C is shown in figure 47.



**Figure 47 Timer C Block Diagram**

### Timer C Operations:

- Free-running/reload timer operation:** The free-running/reload operation, input clock source, and prescaler division ratio are selected by timer mode register C (TMC: \$00D).

Timer C is initialized to the value set in timer write register C (TWCL: \$00E, TWCU: \$00F) by software and incremented by one at each clock input. If an input clock is applied to timer C after it has reached \$FF, an overflow is generated. In this case, if the reload timer function is enabled, timer C is initialized to its initial value set in timer write register C; if the free-running timer function is enabled, the timer is initialized to \$00 and then incremented again.

The overflow sets the timer C interrupt request flag (IFTC: \$002, bit 2). IFTC is reset by software or MCU reset. Refer to figure 3 and table 1 for details.
- Watchdog timer operation:** Timer C is used as a watchdog timer for detecting out-of-control program routines by setting the watchdog on flag (WDON: \$020, bit 1) to 1. If a program routine runs out of control and an overflow is generated, the MCU is reset. The watchdog timer operation flowchart is shown in figure 48. Program run can be controlled by initializing timer C by software before it reaches \$FF.
- Timer output operation:** The PWM output modes can be selected for timer C by setting port mode register A (PMRA: \$004).

By selecting the timer output mode, pin R0<sub>3</sub>/TOC is set to TOC. The output from TOC is reset low by MCU reset.

**PWM output:** When PWM output mode is selected, timer C provides the variable-duty pulse output function. The output waveform differs depending on the contents of timer mode register C (TMC: \$00D) and timer write register C (TWCL: \$00E, TWCU: \$00F). The output waveform is shown in figure 49.

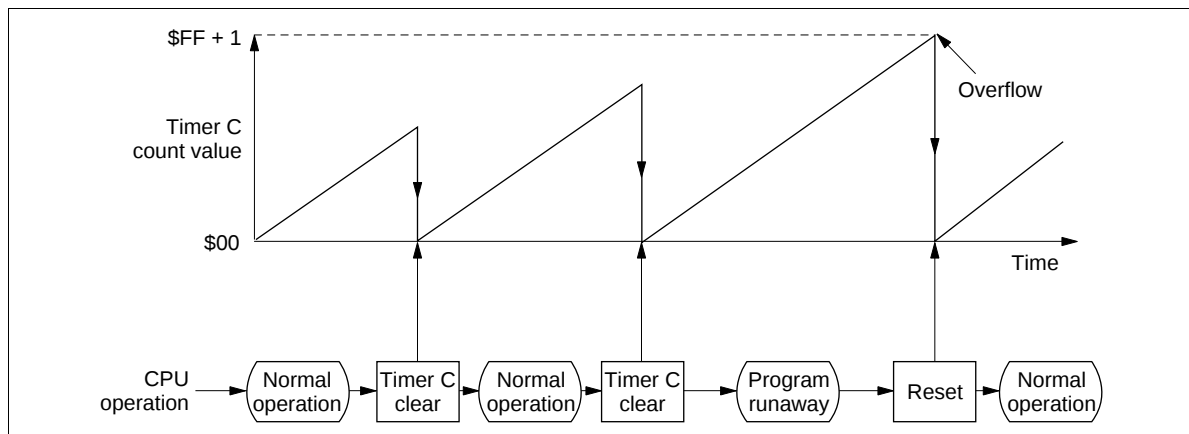
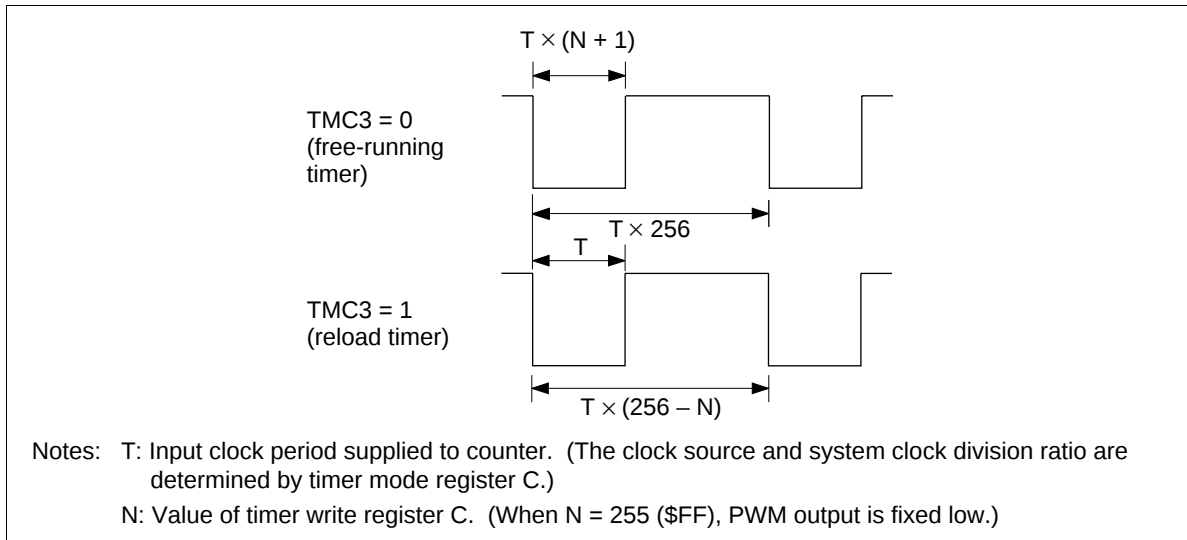


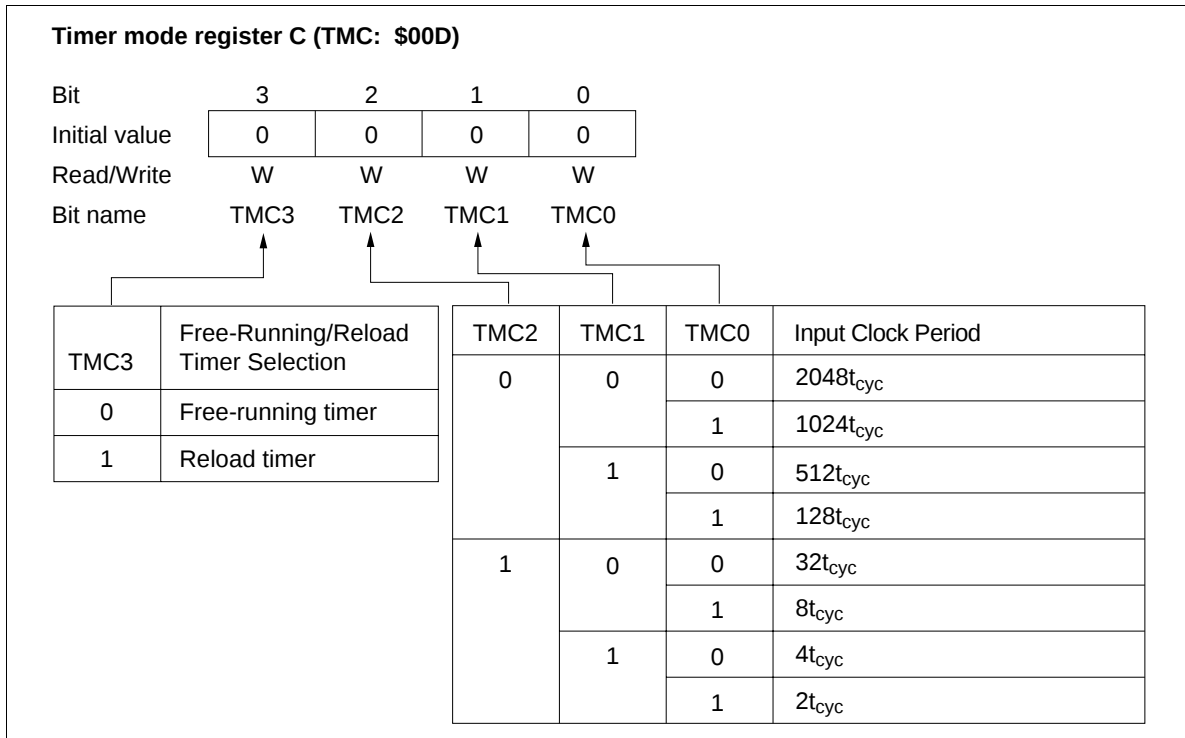
Figure 48 Watchdog Timer Operation Flowchart



**Figure 49 PWM Output Waveform**

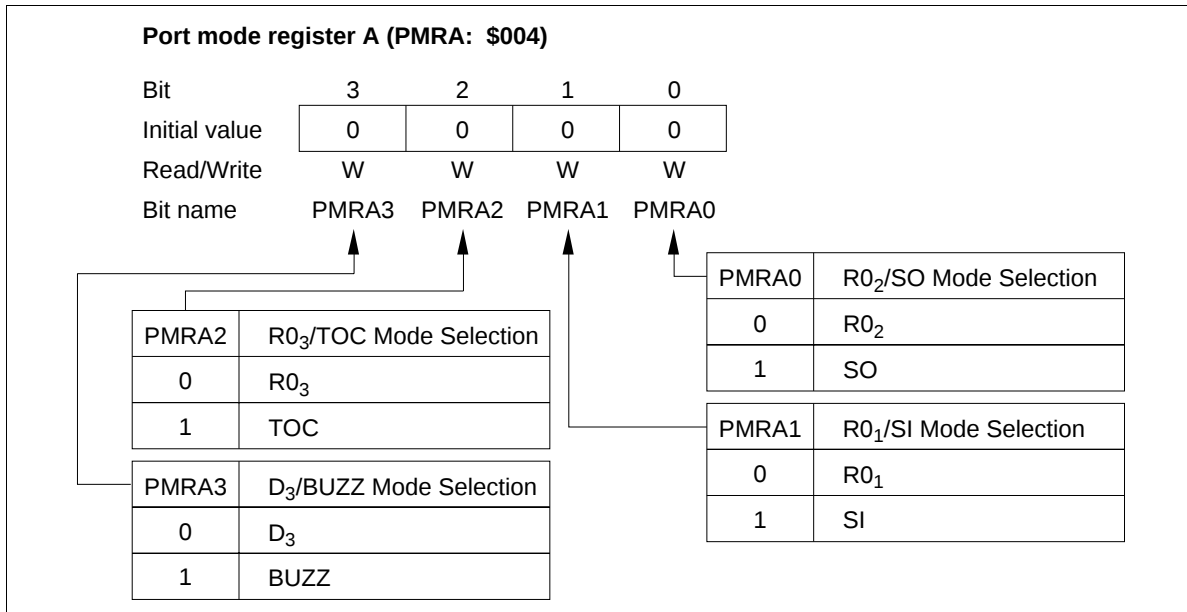
**Registers for Timer C Operation:** By using the following registers, timer C operation modes are selected and the timer C count is read and written.

- Timer mode register C (TMC: \$00D)
  - Port mode register A (PMRA: \$004)
  - Timer write register C (TWCL: \$00E, TWCU: \$00F)
  - Timer read register C (TRCL: \$00E, TRCU: \$00F)
- Timer mode register C (TMC: \$00D): Four-bit write-only register that selects the free-running/reload timer function, input clock source, and the prescaler division ratio as shown in figure 50. It is reset to \$0 by MCU reset.
- Writing to this register is valid from the second instruction execution cycle after the execution of the previous timer mode register C write instruction. Setting timer C's initialization by writing to timer write register C (TWCL: \$00E, TWCU: \$00F) must be done after a mode change becomes valid.

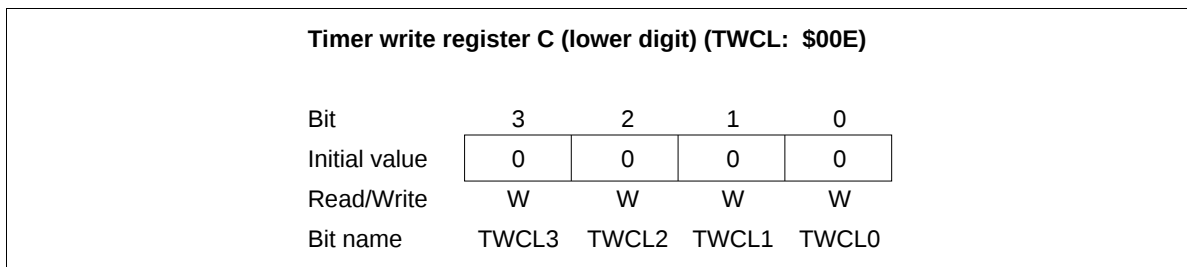


**Figure 50 Timer Mode Register C (TMC)**

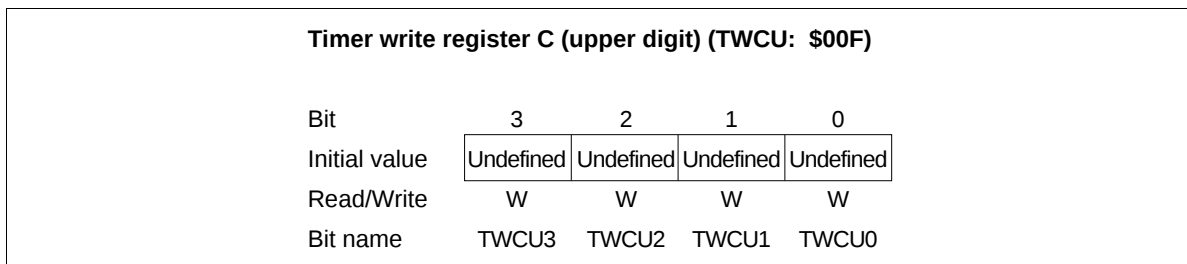
- Port mode register A (PMRA: \$004): Write-only register that selects R0<sub>3</sub>/TOC pin function as shown in figure 51. It is reset to \$0 by MCU reset.
- Timer write register C (TWCL: \$00E, TWCU: \$00F): Write-only register consisting of the lower digit (TWCL) and the upper digit (TWCU) as shown in figures 52 and 53. The operation of timer write register C is basically the same as that of timer write register B (TWBL: \$00A, TWBU: \$00B).
- Timer read register C (TRCL: \$00E, TRCU: \$00F): Read-only register consisting of the lower digit (TRCL) and the upper digit (TRCU) that holds the count of the timer C upper digit (figures 54 and 55). The operation of timer read register C is basically the same as that of timer read register B (TRBL: \$00A, TRBU: \$00B).



**Figure 51 Port Mode Register A (PMRA)**



**Figure 52 Timer Write Register C Lower Digit (TWCL)**



**Figure 53 Timer Write Register C Upper Digit (TWCU)**

**Timer read register C (lower digit) (TRCL: \$00E)**

|               |           |           |           |           |
|---------------|-----------|-----------|-----------|-----------|
| Bit           | 3         | 2         | 1         | 0         |
| Initial value | Undefined | Undefined | Undefined | Undefined |
| Read/Write    | R         | R         | R         | R         |
| Bit name      | TRCL3     | TRCL2     | TRCL1     | TRCL0     |

**Figure 54 Timer Read Register C Lower Digit (TRCL)**
**Timer read register C (upper digit) (TRCU: \$00F)**

|               |           |           |           |           |
|---------------|-----------|-----------|-----------|-----------|
| Bit           | 3         | 2         | 1         | 0         |
| Initial value | Undefined | Undefined | Undefined | Undefined |
| Read/Write    | R         | R         | R         | R         |
| Bit name      | TRCU3     | TRCU2     | TRCU1     | TRCU0     |

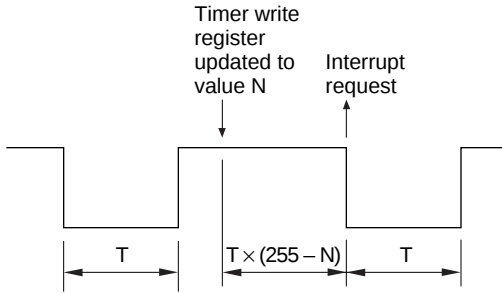
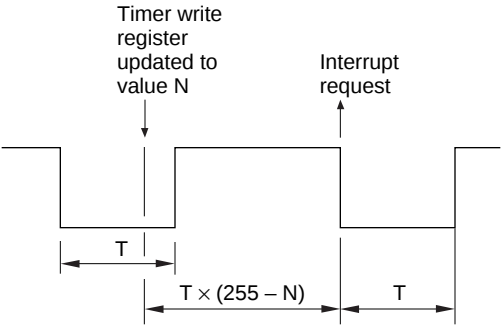
**Figure 55 Timer Read Register C Upper Digit (TRCU)**
**Notes on Use**

When using the timer output as PWM output, note the following point. From the update of the timer write register until the occurrence of the overflow interrupt, the PWM output differs from the period and duty settings, as shown in table 26. The PWM output should therefore not be used until after the overflow interrupt following the update of the timer write register. After the overflow, the PWM output will have the set period and duty cycle.

In this case, the lower digit (TWCL) must be written to first, bit writing only to the lower digit does not change the timer C value. Timer C is changed to the value in timer write register B at the same time the upper digit (TWCU) is written to.

HD404369 Series

Table 26    PWM Output Following Update of Timer Write Register

| Mode   | PWM Output                                                                        |                                                                                    |
|--------|-----------------------------------------------------------------------------------|------------------------------------------------------------------------------------|
|        | Timer Write Register is Updated during High PWM Output                            | Timer Write Register is Updated during Low PWM Output                              |
| Reload |  |  |

## Alarm Output Function

The MCU has a built-in pulse output function called BUZZ. The pulse frequency can be selected from the prescaler S's outputs, and the output frequency depends on the state of port mode register C (PMRC: \$025). The duty cycle of the pulse output is fixed at 50%.

**Port Mode Register C (PMRC: \$025):** Four-bit write-only register that selects the alarm frequencies as shown in figure 57. It is reset to \$0 by MCU reset.

**Port Mode Register A (PMRA: \$004):** Four-bit write-only register that selects  $D_3$ /BUZZ pin function as shown in figure 51. It is reset to \$0 by MCU reset.

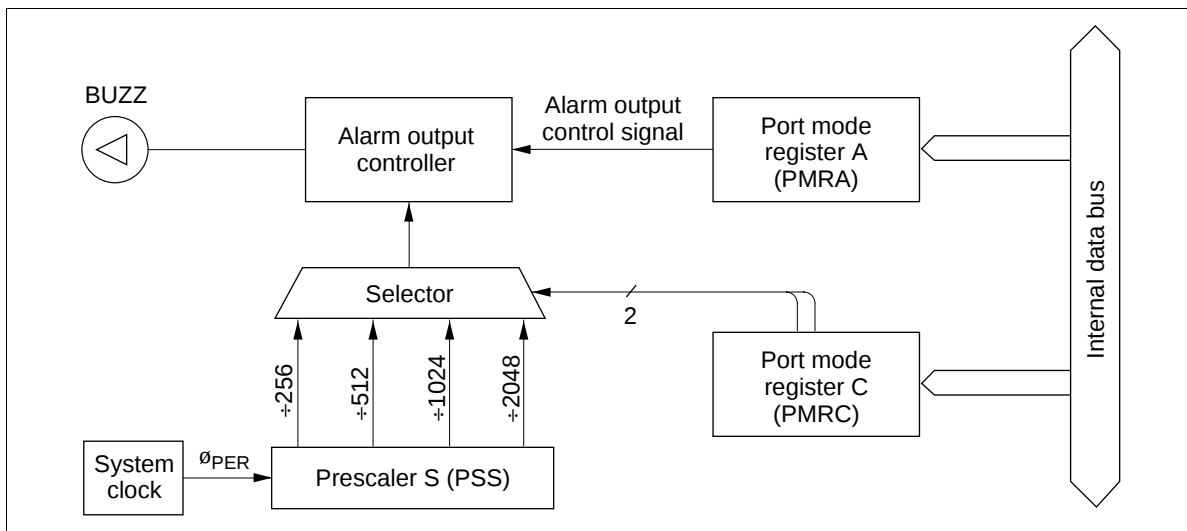


Figure 56 Alarm Output Function Block Diagram

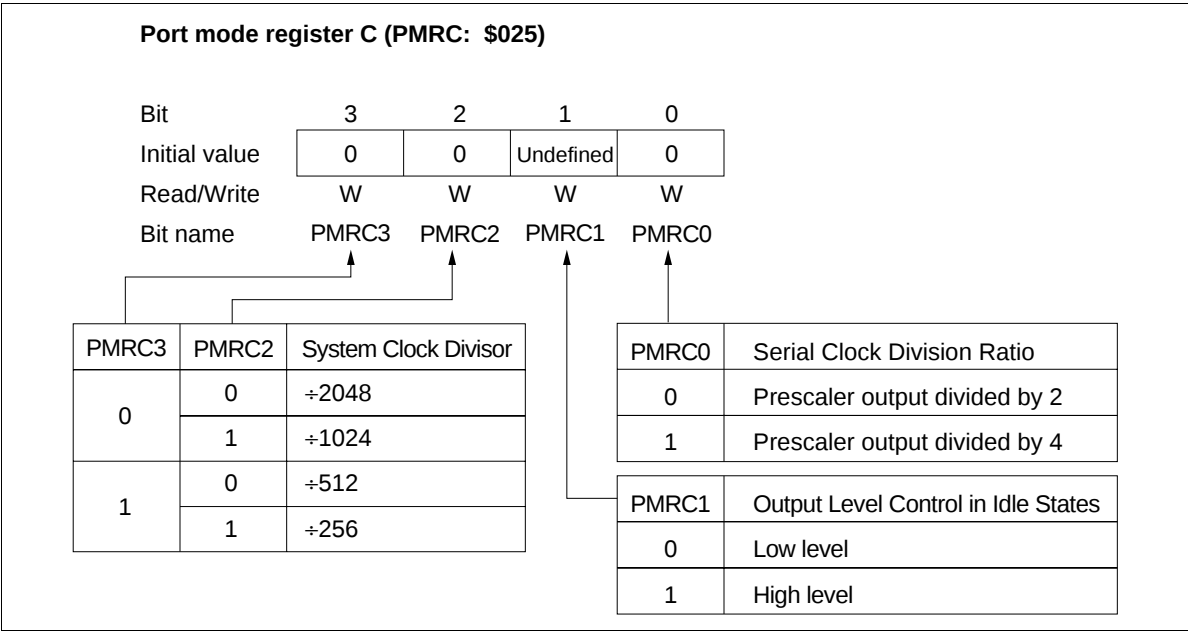


Figure 57 Port Mode Register C (PMRC)

## **Serial Interface**

The serial interface serially transfers and receives 8-bit data, and includes the following features.

- Multiple transmit clock sources
  - External clock
  - Internal prescaler output clock
  - System clock
- Output level control in idle states

Four registers, an octal counter, and a selector are also configured for the serial interface as follows.

- Serial data register (SRL: \$006, SRU: \$007)
- Serial mode register (SMR: \$005)
- Port mode register A (PMRA: \$004)
- Port mode register C (PMRC: \$025)
- Miscellaneous register (MIS: \$00C)
- Octal counter (OC)
- Selector

The block diagram of the serial interface is shown in figure 58.

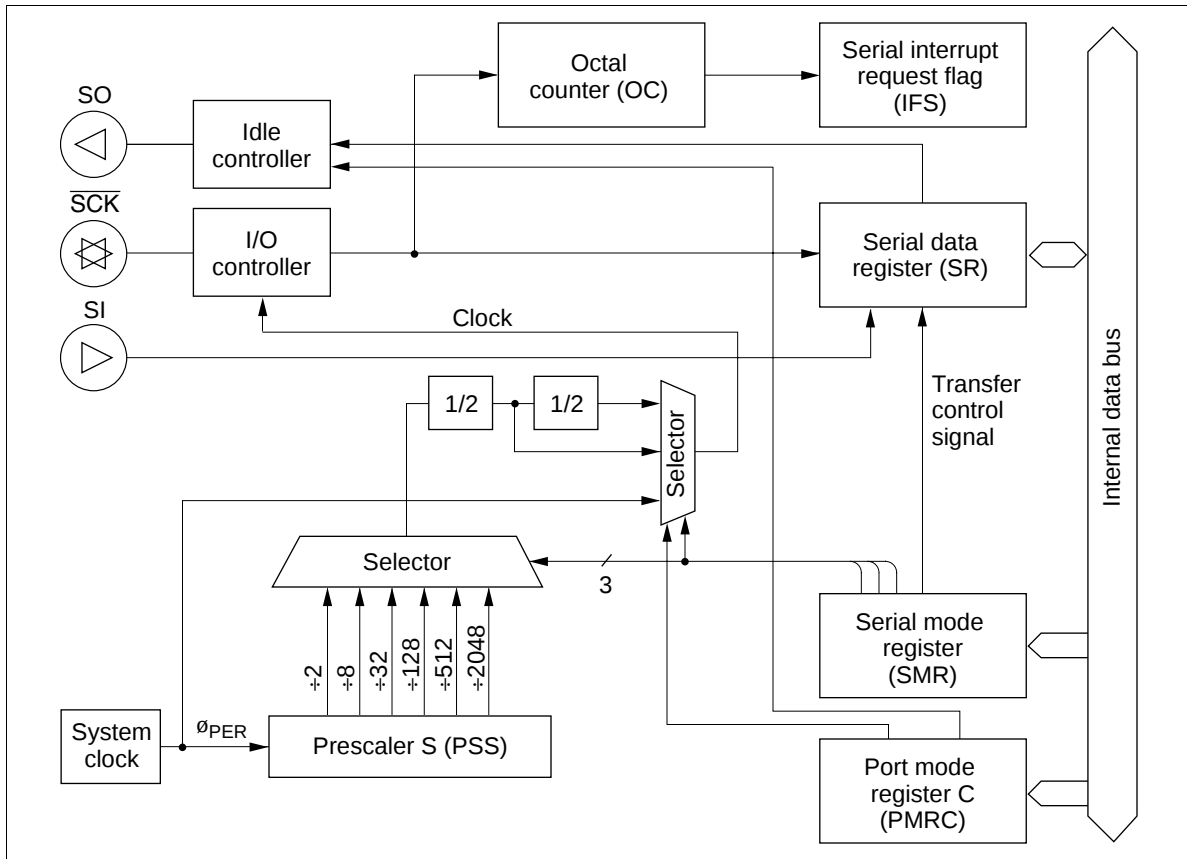


Figure 58 Serial Interface Block Diagram

### Serial Interface Operation

**Selecting and Changing the Operating Mode:** Table 27 lists the serial interface's operating modes. To select an operating mode, use one of these combinations of port mode register A (PMRA: \$004) and the serial mode register (SMR: \$005) settings; to change the operating mode, always initialize the serial interface internally by writing data to the serial mode register. Note that the serial interface is initialized by writing data to the serial mode register. Refer to the following Serial Mode Register section for details.

**Pin Setting:** The  $R0_0/\overline{SCK}$  pin is controlled by writing data to the serial mode register (SMR: \$005). The  $R0_1/SI$  and  $R0_2/SO$  pins are controlled by writing data to port mode register A (PMRA: \$004). Refer to the following Registers for Serial Interface section for details.

**Transmit Clock Source Setting:** The transmit clock source is set by writing data to the serial mode register (SMR: \$005) and port mode register C (PMRC: \$025). Refer to the following Registers for Serial Interface section for details.

**Data Setting:** Transmit data is set by writing data to the serial data register (SRL: \$006, SRU, \$007). Receive data is obtained by reading the contents of the serial data register. The serial data is shifted by the transmit clock and is input from or output to an external system.

The output level of the SO pin is invalid until the first data is output after MCU reset, or until the output level control in idle states is performed.

**Transfer Control:** The serial interface is activated by the STS instruction. The octal counter is reset to 000 by this instruction, and it increments at the rising edge of the transmit clock. When the eighth transmit clock signal is input or when serial transmission/receive is discontinued, the octal counter is reset to 000, the serial interrupt request flag (IFS: \$003, bit 2) is set, and the transfer stops.

When the prescaler output is selected as the transmit clock, the transmit clock frequency is selected as  $4t_{cyc}$  to  $8192t_{cyc}$  by setting bits 0 to 2 (SMR0–SMR2) of serial mode register (SMR: \$005) and bit 0 (PMRC0) of port mode register C (PMRC: \$025) as listed in table 28.

**Operating States:** The serial interface has the following operating states; transitions between them are shown in figure 59.

- STS wait state
  - Transmit clock wait state
  - Transfer state
  - Continuous clock output state (only in internal clock mode)
- STS wait state: The serial interface enters STS wait state by MCU reset (00, 10 in figure 59). In STS wait state, the serial interface is initialized and the transmit clock is ignored. If the STS instruction is then executed (01, 11), the serial interface enters transmit clock wait state.
  - Transmit clock wait state: Transmit clock wait state is the period between the STS execution and the falling edge of the first transmit clock. In transmit clock wait state, input of the transmit clock (02, 12) increments the octal counter, shifts the serial data register, and puts the serial interface in transfer state. However, note that if continuous clock output mode is selected in internal clock mode, the serial interface does not enter transfer state but enters continuous clock output state (17).  
The serial interface enters STS wait state by writing data to the serial mode register (SMR: \$005) (04, 14) in transmit clock wait state.
  - Transfer state: Transfer state is the period between the falling edge of the first clock and the rising edge of the eighth clock. In transfer state, the input of eight clocks or the execution of the STS instruction sets the octal counter to 000, and the serial interface enters another state. When the STS instruction is executed (05, 15), transmit clock wait state is entered. When eight clocks are input, transmit clock wait state is entered (03) in external clock mode, and STS wait state is entered (13) in internal clock mode. In internal clock mode, the transmit clock stops after outputting eight clocks.  
In transfer state, writing data to the serial mode register (SMR: \$005) (06, 16) initializes the serial interface, and STS wait state is entered.  
If the state changes from transfer to another state, the serial interrupt request flag (IFS: \$003, bit 2) is set by the octal counter that is reset to 000.
  - Continuous clock output state (only in internal clock mode): Continuous clock output state is entered only in internal clock mode. In this state, the serial interface does not transmit/receive data but only outputs the transmit clock from the  $\overline{SCK}$  pin.

## HD404369 Series

When bits 0 and 1 (PMRA0, PMRA1) of port mode register A (PMRA: \$004) are 00 in transmit clock wait state and if the transmit clock is input (17), the serial interface enters continuous clock output state. If the serial mode register (SMR: \$005) is written to in continuous clock output mode (18), STS wait state is entered.

**Output Level Control in Idle States:** In idle states, that is, STS wait state and transmit clock wait state, the output level of the SO pin can be controlled by setting bit 1 (PMRC1) of port mode register C (PMRC: \$025) to 0 or 1. The output level control example is shown in figure 60. Note that the output level cannot be controlled in transfer state.

**Transmit Clock Error Detection (In External Clock Mode):** The serial interface will malfunction if a spurious pulse caused by external noise conflicts with a normal transmit clock during transfer. A transmit clock error of this type can be detected as shown in figure 61.

**Table 27 Serial Interface Operating Modes**

| SMR   | PMRA  |       | Operating Mode               |
|-------|-------|-------|------------------------------|
| Bit 3 | Bit 1 | Bit 0 |                              |
| 1     | 0     | 0     | Continuous clock output mode |
|       |       | 1     | Transmit mode                |
|       | 1     | 0     | Receive mode                 |
|       |       | 1     | Transmit/receive mode        |

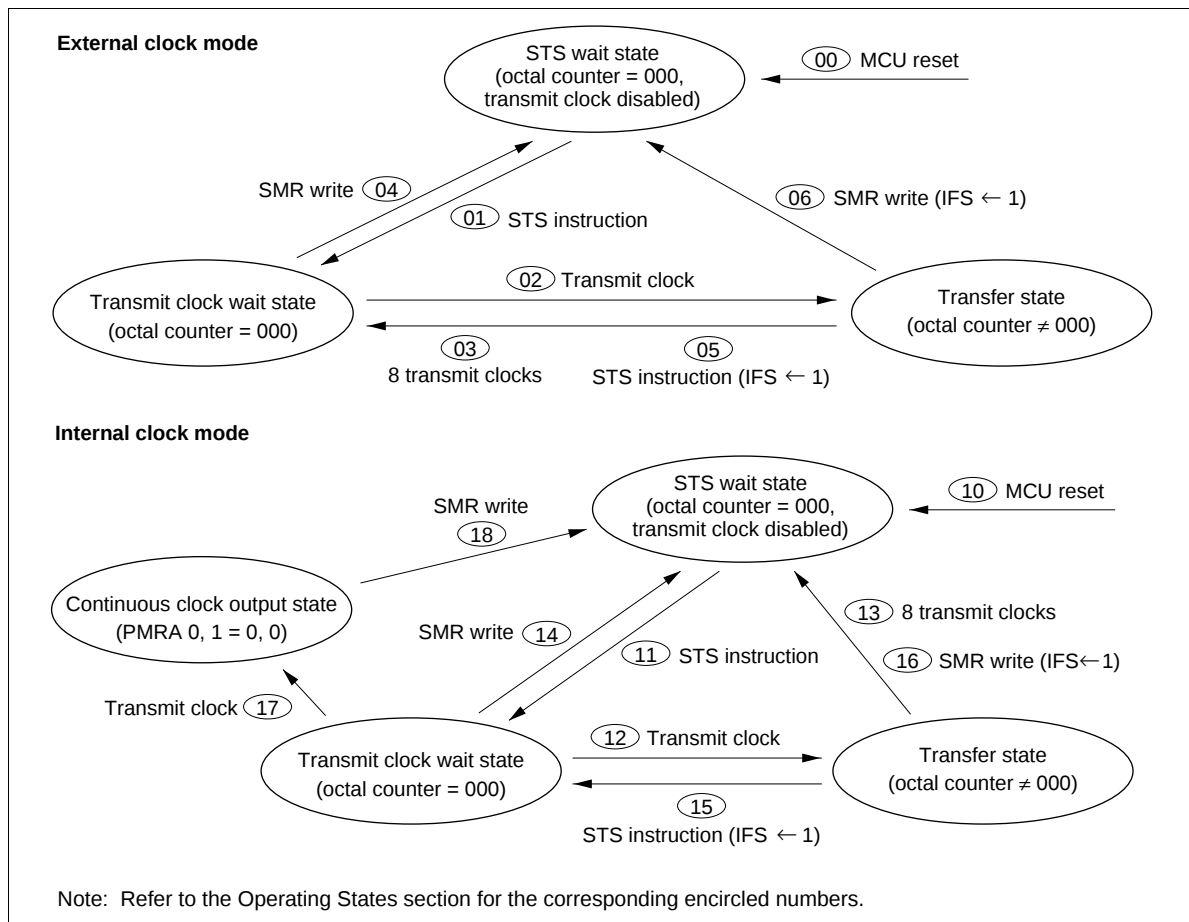
**Table 28 Serial Transmit Clock (Prescaler Output)**

| PMRC  | SMR   |       |       | Prescaler Division Ratio | Transmit Clock Frequency |
|-------|-------|-------|-------|--------------------------|--------------------------|
| Bit 0 | Bit 2 | Bit 1 | Bit 0 |                          |                          |
| 0     | 0     | 0     | 0     | $\div 2048$              | $4096t_{cyc}$            |
|       |       |       | 1     | $\div 512$               | $1024t_{cyc}$            |
|       |       | 1     | 0     | $\div 128$               | $256t_{cyc}$             |
|       |       |       | 1     | $\div 32$                | $64t_{cyc}$              |
|       | 1     | 0     | 0     | $\div 8$                 | $16t_{cyc}$              |
|       |       |       | 1     | $\div 2$                 | $4t_{cyc}$               |
|       |       | 1     | 0     | $\div 4096$              | $8192t_{cyc}$            |
|       |       |       | 1     | $\div 1024$              | $2048t_{cyc}$            |
| 1     | 0     | 0     | 0     | $\div 256$               | $512t_{cyc}$             |
|       |       |       | 1     | $\div 64$                | $128t_{cyc}$             |
|       |       | 1     | 0     | $\div 16$                | $32t_{cyc}$              |
|       |       |       | 1     | $\div 4$                 | $8t_{cyc}$               |

If more than eight transmit clocks are input in transfer state, at the eighth clock including a spurious pulse by noise, the octal counter reaches 000, the serial interrupt request flag (IFS: \$003, bit 2) is set, and transmit clock wait state is entered. At the falling edge of the next normal clock signal, the transfer state is entered. After the transfer completion processing is performed and IFS is reset, writing to the serial mode register (SMR: \$005) changes the state from transfer to STS wait. At this time IFS is set again, and therefore the error can be detected.

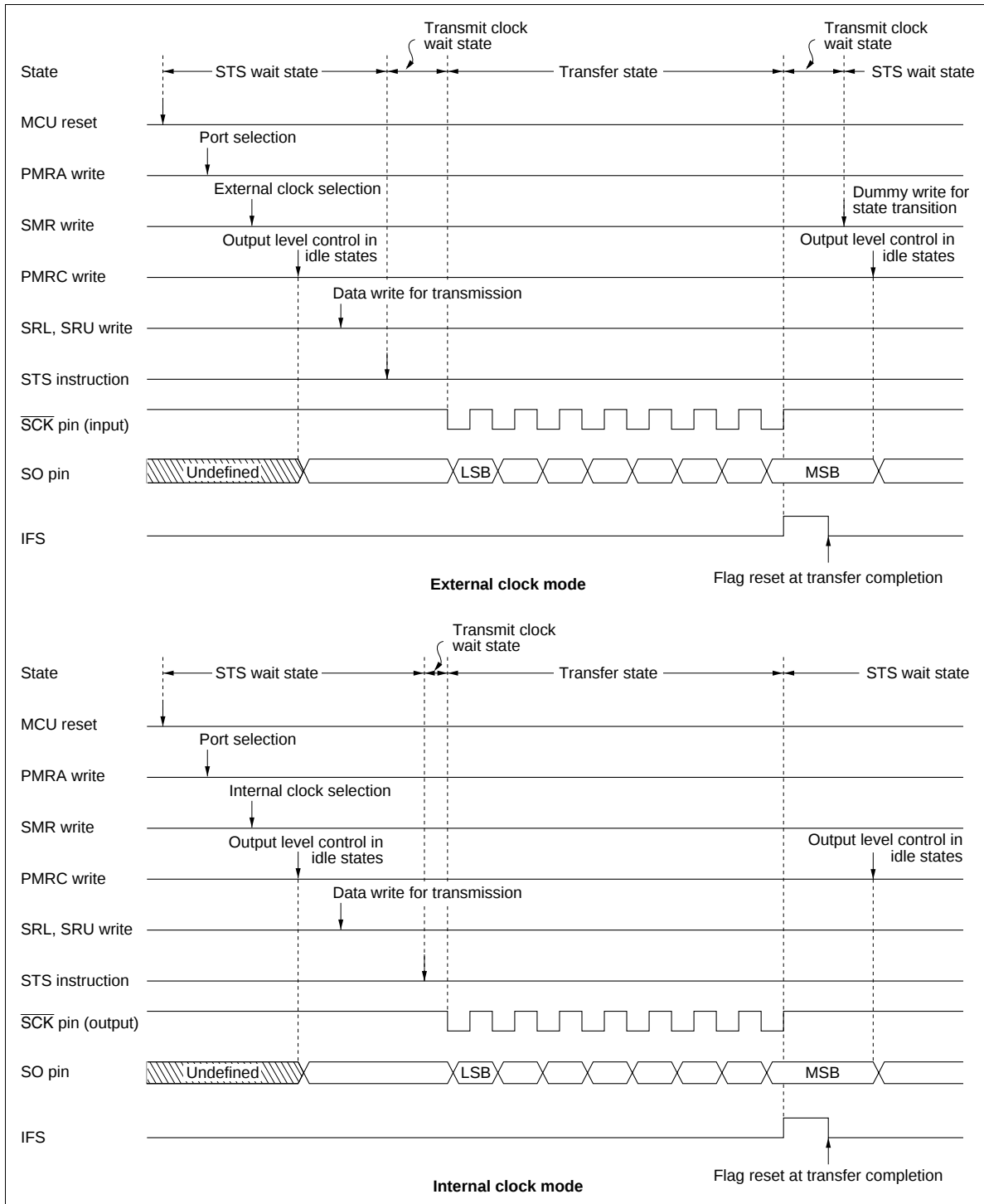
**Notes on Use:**

- Initialization after writing to registers: If port mode register A (PMRA: \$004) is written to in transmit clock wait state or in transfer state, the serial interface must be initialized by writing to the serial mode register (SMR: \$005) again.
- Serial interrupt request flag (IFS: \$003, bit 2) set: If the state is changed from transfer to another by writing to the serial mode register (SMR: \$005) or executing the STS instruction during the first low pulse of the transmit clock, the serial interrupt request flag is not set. To set the serial interrupt request flag, serial mode register write or STS instruction execution must be programmed to be executed after confirming that the  $\overline{SCK}$  pin is at 1, that is, after executing the input instruction to port R0.

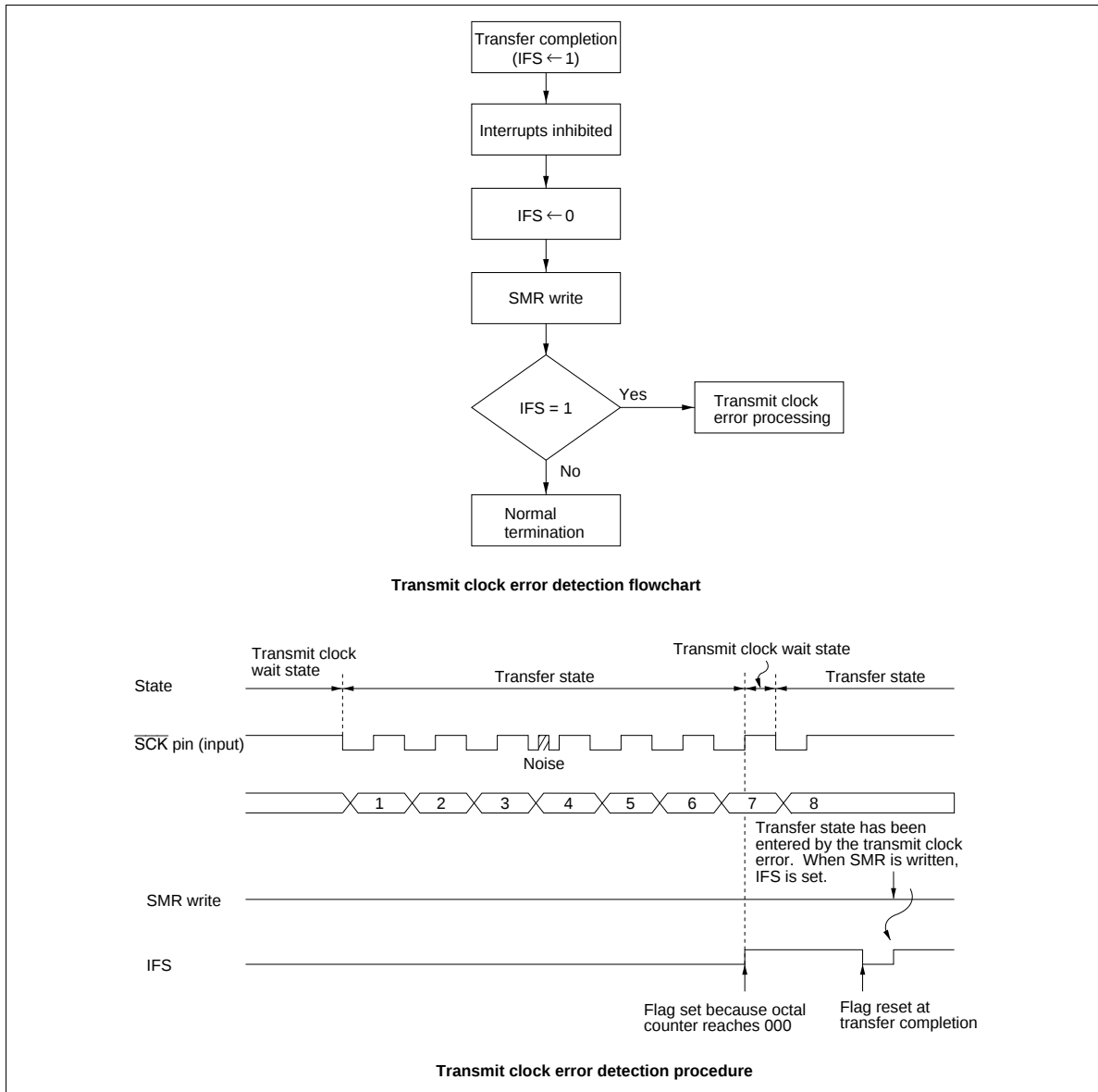


**Figure 59 Serial Interface State Transitions**

## HD404369 Series



**Figure 60 Example of Serial Interface Operation Sequence**



**Figure 61 Transmit Clock Error Detection**

### Registers for Serial Interface

The serial interface operation is selected, and serial data is read and written by the following registers.

- Serial Mode Register (SMR: \$005)
- Serial Data Register (SRL: \$006, SRU: \$007)
- Port Mode Register A (PMRA: \$004)
- Port Mode Register C (PMRC: \$025)
- Miscellaneous Register (MIS: \$00C)

## HD404369 Series

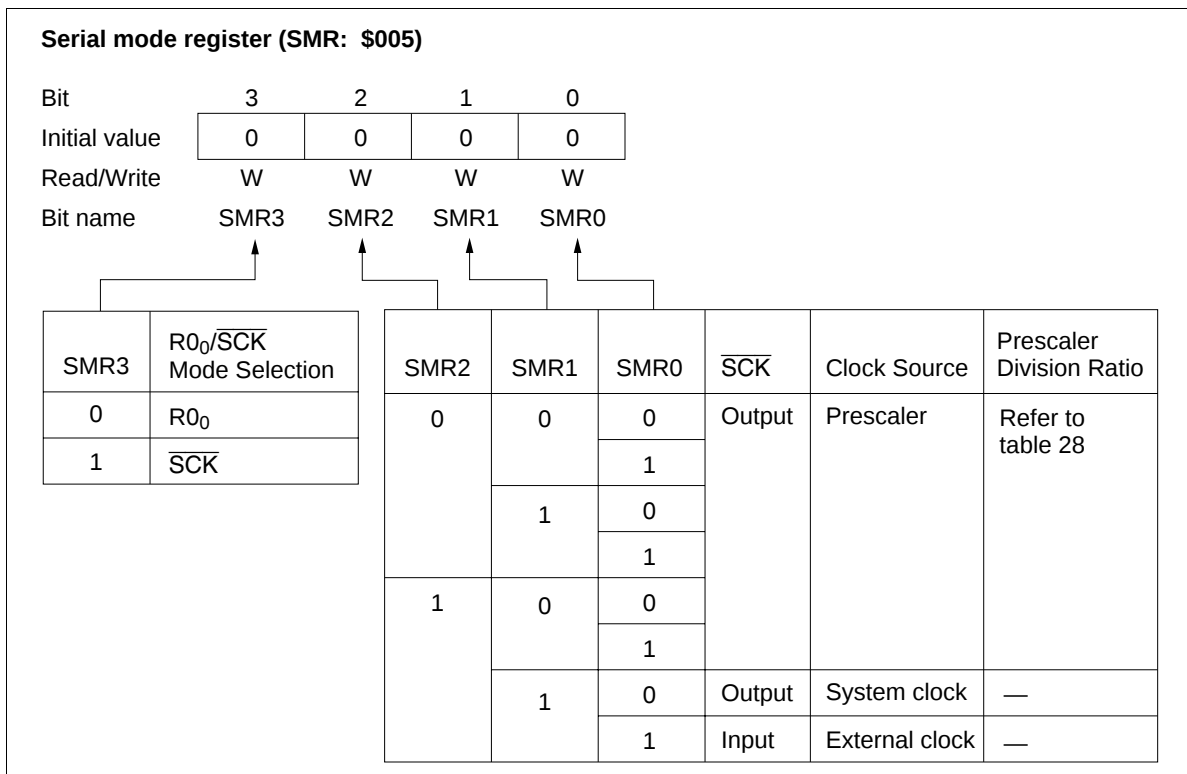
**Serial Mode Register (SMR: \$005):** This register has the following functions (figure 62).

- $R0_0/\overline{SCK}$  pin function selection
- Transmit clock selection
- Prescaler division ratio selection
- Serial interface initialization

Serial mode register (SMR: \$005) is a 4-bit write-only register. It is reset to \$0 by MCU reset.

A write signal input to serial mode register (SMR: \$005) discontinues the input of the transmit clock to the serial data register and octal counter, and the octal counter is reset to 000. Therefore, if a write is performed during data transfer, the serial interrupt request flag (IFS: \$003, bit 2) is set.

Written data is valid from the second instruction execution cycle after the write operation, so the STS instruction must be executed at least two cycles after that.



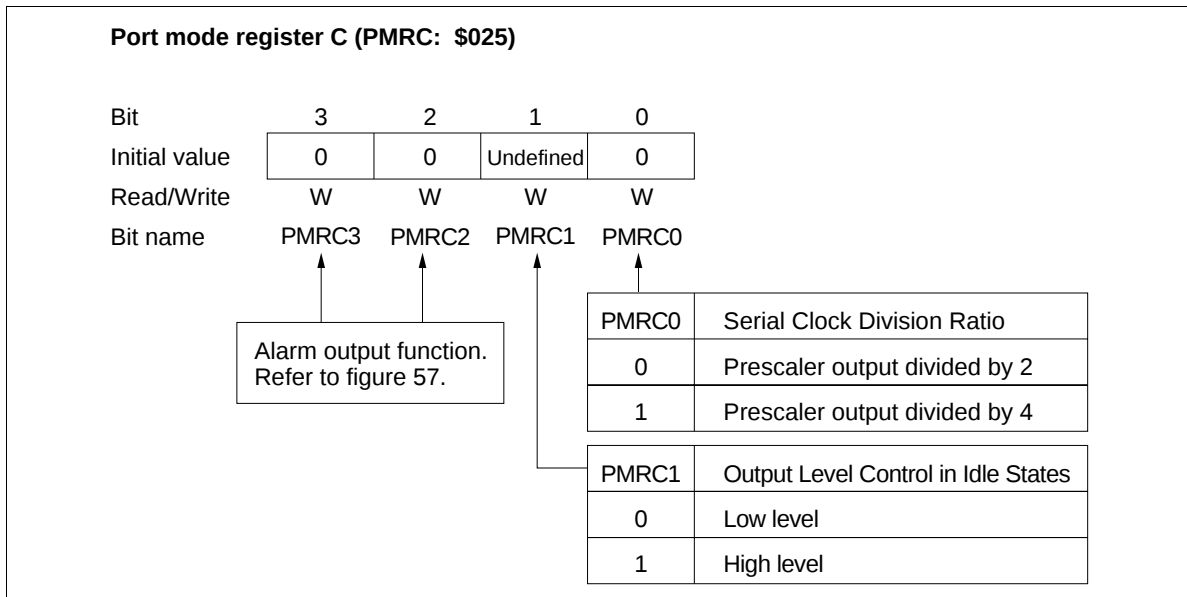
**Figure 62 Serial Mode Register (SMR)**

**Port Mode Register C (PMRC: \$025):** This register has the following functions (figure 63).

- Prescaler division ratio selection
- Output level control in idle states

Port mode register C (PMRC: \$025) is a 4-bit write-only register. It cannot be written during data transfer.

By setting bit 0 (PMRC0) of this register, the prescaler division ratio is selected. Bit 0 (PMRC0) can be reset to 0 by MCU reset. By setting bit 1 (PMRC1), the output level of the SO pin is controlled in idle states. The output level changes at the same time that PMRC1 is written to.



**Figure 63 Port Mode Register C (PMRC)**

---

# HD404369 Series

---

**Serial Data Register (SRL: \$006, SRU: \$007):** This register has the following functions (figures 64 and 65).

- Transmission data write and shift
- Receive data shift and read

Writing data in this register is output from the SO pin, LSB first, synchronously with the falling edge of the transmit clock; data is input, LSB first, through the SI pin at the rising edge of the transmit clock. Input/output timing is shown in figure 66.

Data cannot be read or written during serial data transfer. If a read/write occurs during transfer, the accuracy of the resultant data cannot be guaranteed.

| Serial data register (lower digit) (SRL: \$006) |           |           |           |           |
|-------------------------------------------------|-----------|-----------|-----------|-----------|
| Bit                                             | 3         | 2         | 1         | 0         |
| Initial value                                   | Undefined | Undefined | Undefined | Undefined |
| Read/Write                                      | R/W       | R/W       | R/W       | R/W       |
| Bit name                                        | SR3       | SR2       | SR1       | SR0       |

Figure 64 Serial Data Register (SRL)

| Serial data register (upper digit) (SRU: \$007) |           |           |           |           |
|-------------------------------------------------|-----------|-----------|-----------|-----------|
| Bit                                             | 3         | 2         | 1         | 0         |
| Initial value                                   | Undefined | Undefined | Undefined | Undefined |
| Read/Write                                      | R/W       | R/W       | R/W       | R/W       |
| Bit name                                        | SR7       | SR6       | SR5       | SR4       |

Figure 65 Serial Data Register (SRU)

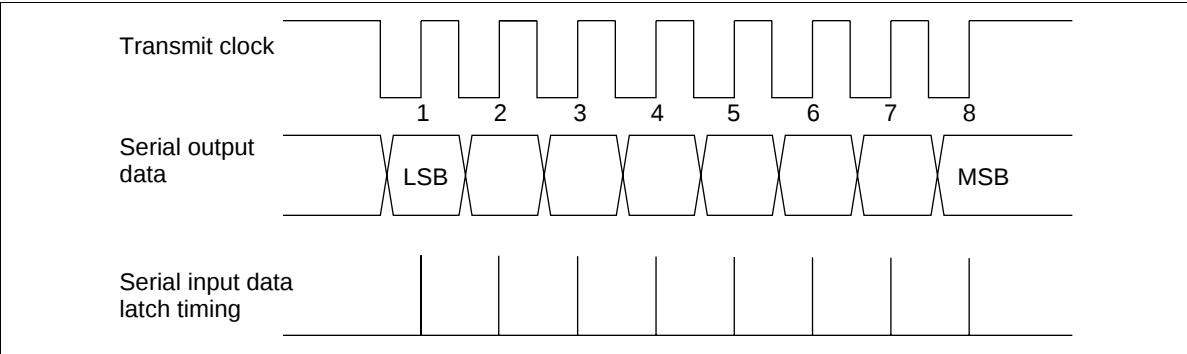
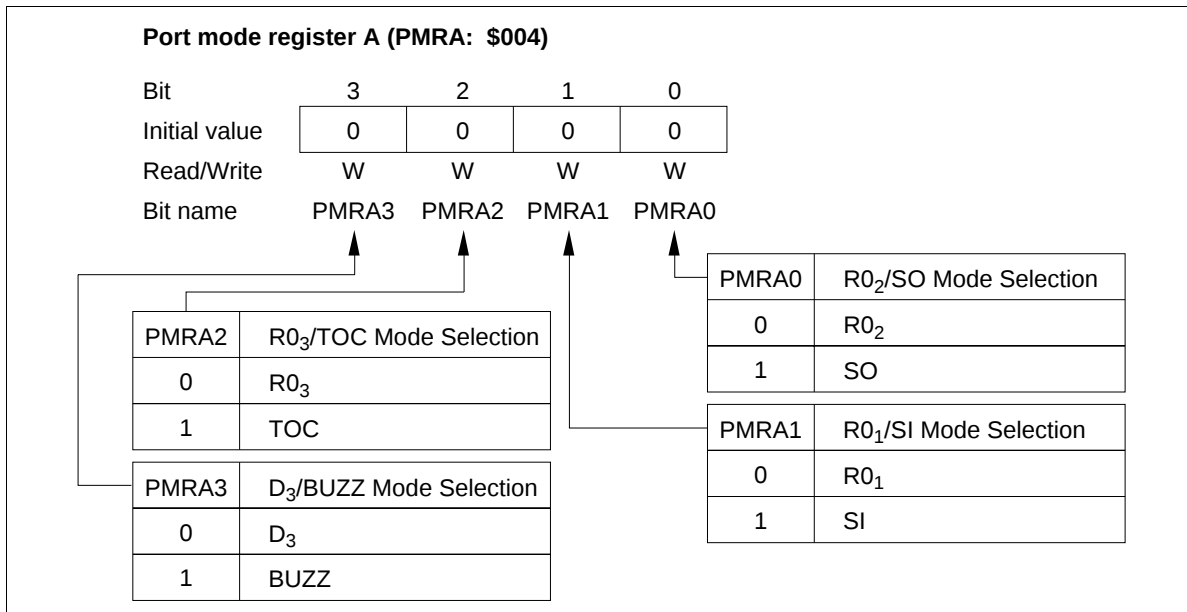


Figure 66 Serial Interface Output Timing

**Port Mode Register A (PMRA: \$004):** This register has the following functions (figure 67).

- R0<sub>1</sub>/SI pin function selection
- R0<sub>2</sub>/SO pin function selection

Port mode register A (PMRA: \$004) is a 4-bit write-only register, and is reset to \$0 by MCU reset.



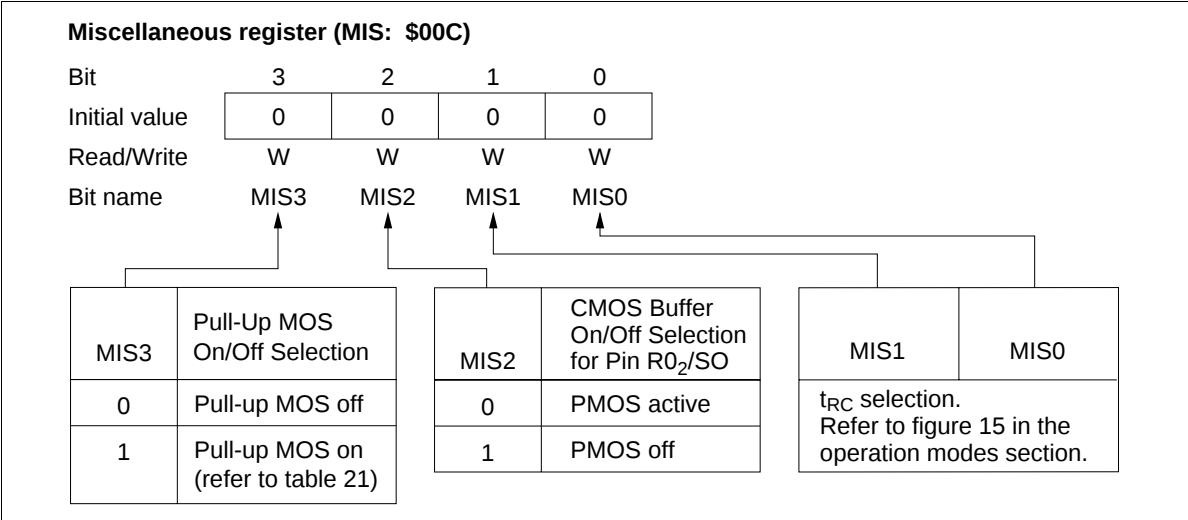
**Figure 67 Port Mode Register A (PMRA)**

# HD404369 Series

**Miscellaneous Register (MIS: \$00C):** This register has the following functions (figure 68).

- R0<sub>2</sub>/SO pin PMOS control

Miscellaneous register (MIS: \$00C) is a 4-bit write-only register and is reset to \$0 by MCU reset.



**Figure 68 Miscellaneous Register (MIS)**

## A/D Converter

The MCU has a built-in A/D converter that uses a sequential comparison method with a resistor ladder. It can measure twelve analog inputs with 8-bit resolution. The block diagram of the A/D converter is shown in figure 69.

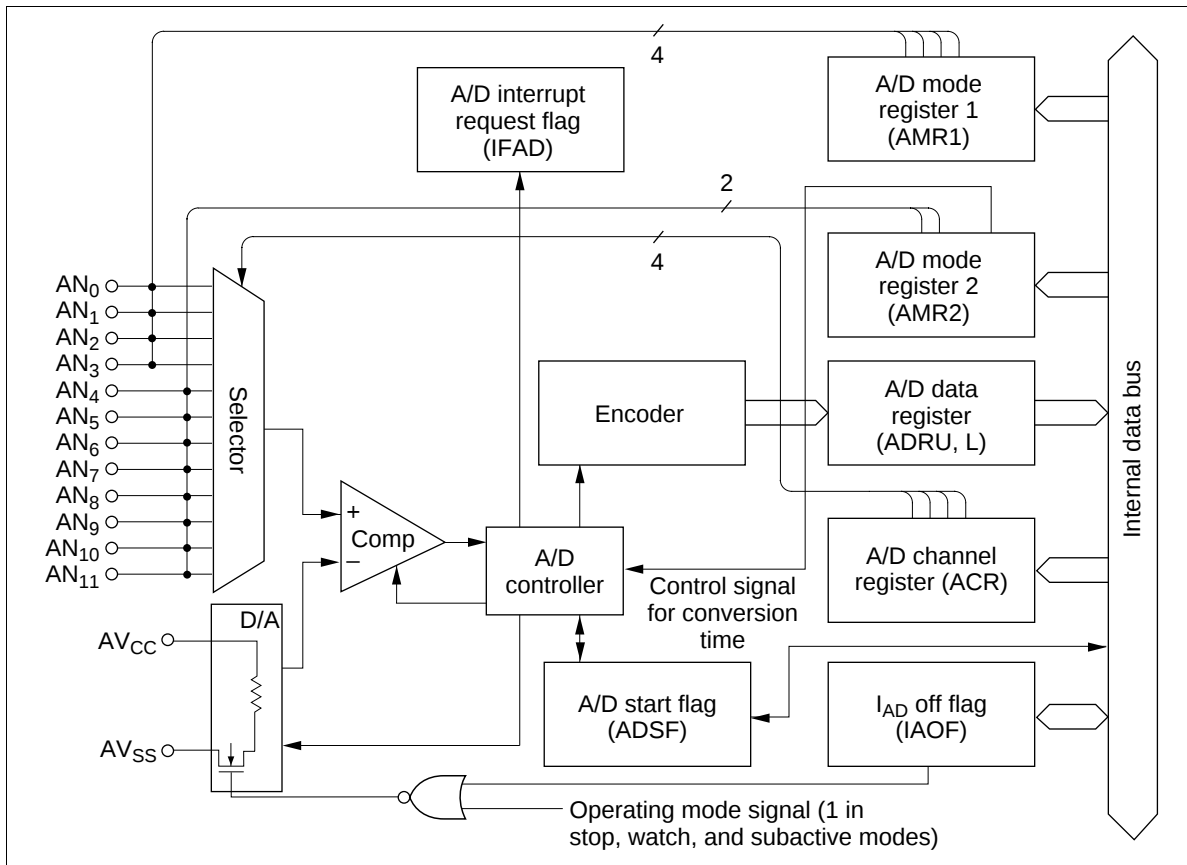
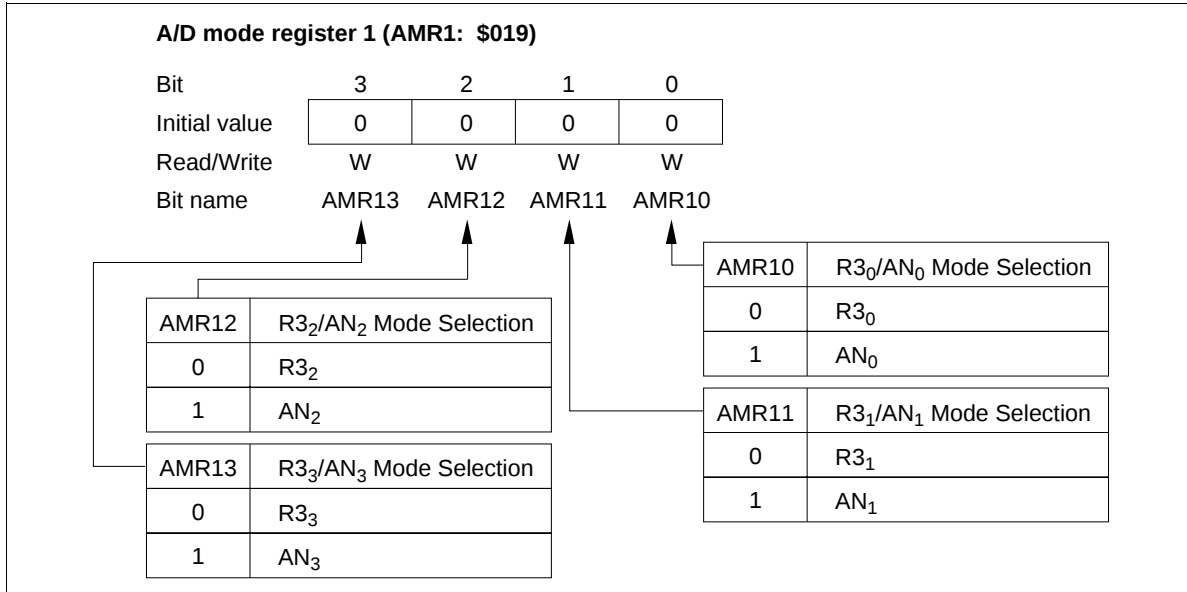


Figure 69 A/D Converter Block Diagram

## HD404369 Series

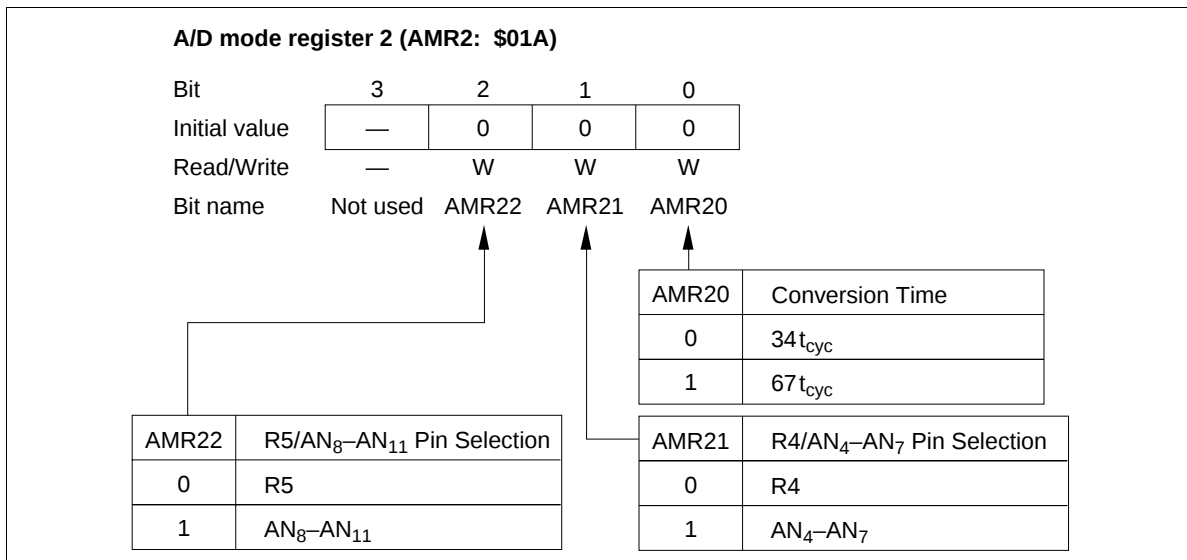
### Registers for A/D Converter Operation

**A/D Mode Register 1 (AMR1: \$019):** Four-bit write-only register which selects digital or analog ports, as shown in figure 70.



**Figure 70 A/D Mode Register 1 (AMR1)**

**A/D Mode register 2 (AMR2: \$01A):** Three-bit write-only register which is used to set the A/D conversion period and to select digital or analog ports. Bit 0 of the A/D mode register selects the A/D conversion period, and bits 1 and 2 select ports R4–R5 as pins AN<sub>4</sub>–AN<sub>11</sub> in 4-pin units (figure 71).



**Figure 71 A/D Mode Register 2 (AMR2)**

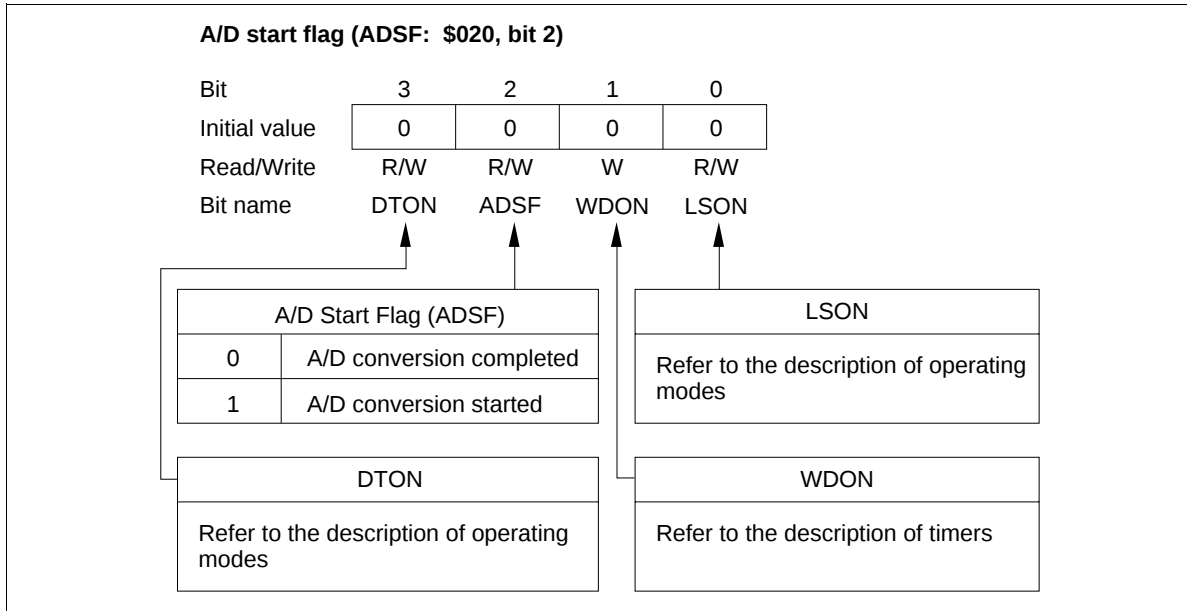
**A/D Channel Register (ACR: \$016):** Four-bit write-only register which indicates analog input pin information, as shown in figure 72.

| A/D channel register (ACR: \$016) |      |             |             |                        |
|-----------------------------------|------|-------------|-------------|------------------------|
| Bit                               | 3    | 2           | 1           | 0                      |
| Initial value                     | 0    | 0           | 0           | 0                      |
| Read/Write                        | W    | W           | W           | W                      |
| Bit name                          | ACR3 | ACR2        | ACR1        | ACR0                   |
|                                   |      |             |             |                        |
| ACR3                              | ACR2 | ACR1        | ACR0        | Analog Input Selection |
| 0                                 | 0    | 0           | 0           | AN <sub>0</sub>        |
|                                   |      |             | 1           | AN <sub>1</sub>        |
|                                   |      | 1           | 0           | AN <sub>2</sub>        |
|                                   |      |             | 1           | AN <sub>3</sub>        |
|                                   | 1    | 0           | 0           | AN <sub>4</sub>        |
|                                   |      |             | 1           | AN <sub>5</sub>        |
|                                   |      | 1           | 0           | AN <sub>6</sub>        |
|                                   |      |             | 1           | AN <sub>7</sub>        |
| 1                                 | 0    | 0           | 0           | AN <sub>8</sub>        |
|                                   |      |             | 1           | AN <sub>9</sub>        |
|                                   |      | 1           | 0           | AN <sub>10</sub>       |
|                                   |      |             | 1           | AN <sub>11</sub>       |
|                                   | 1    | Don't care. | Don't care. | Not used               |

**Figure 72 A/D Channel Register (ACR)**

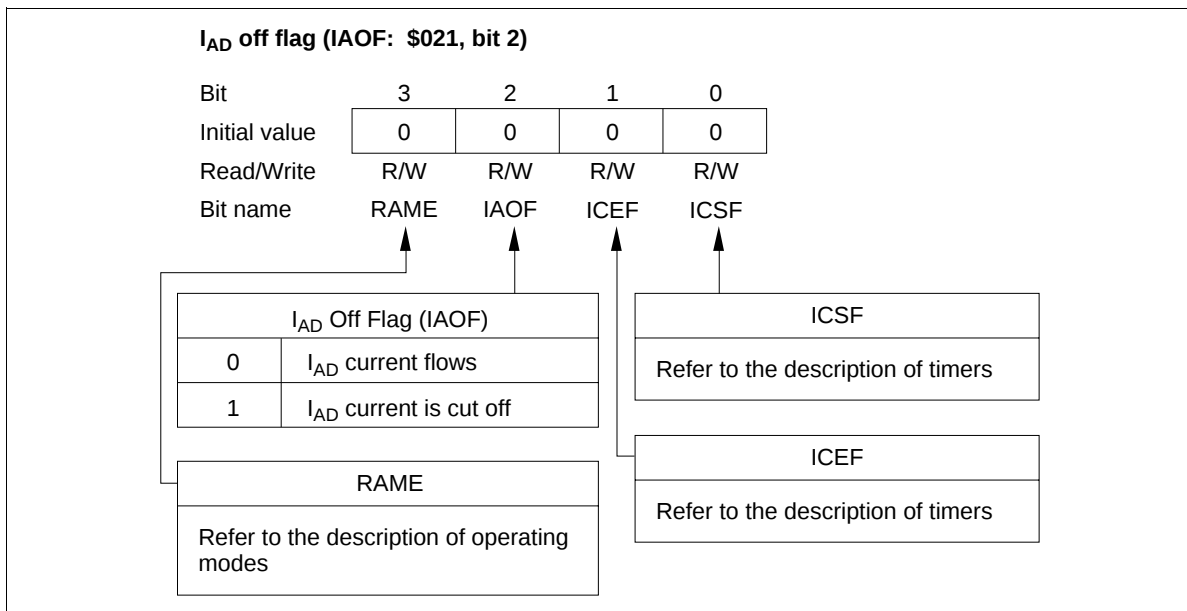
## HD404369 Series

**A/D Start Flag (ADSF: \$02C, Bit 2):** One-bit flag that initiates A/D conversion when set to 1. At the completion of A/D conversion, the converted data is stored in the A/D data register and the A/D start flag is cleared. Refer to figure 73.



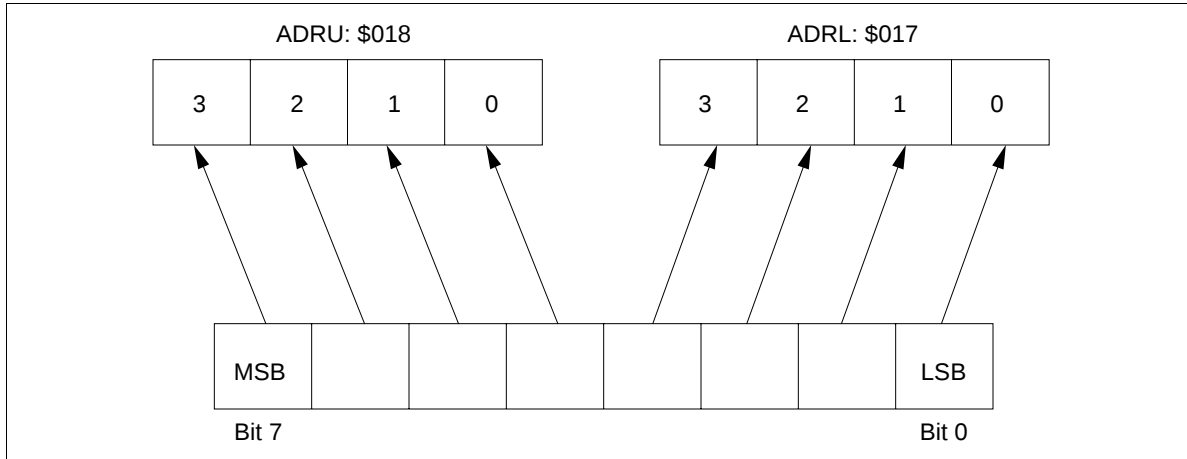
**Figure 73 A/D Start Flag (ADSF)**

**I<sub>AD</sub> Off Flag (IAOF: \$021, Bit 2):** By setting the I<sub>AD</sub> off flag to 1, the current flowing through the resistance ladder can be cut off even while operating in standby or active mode, as shown in figure 74.



**Figure 74 I<sub>AD</sub> Off Flag (IAOF)**

**A/D Data Register (ADRL: \$017, ADRU: \$018):** Eight-bit read-only register consisting of a 4-bit lower digit and 4-bit upper digit. This register is not cleared by reset. After the completion of A/D conversion, the resultant eight-bit data is held in this register until the start of the next conversion (figures 75, 76, and 77).



**Figure 75 A/D Data Registers (ADRU, ADRL)**

**A/D data register (lower digit) (ADRL: \$017)**

|               |       |       |       |       |
|---------------|-------|-------|-------|-------|
| Bit           | 3     | 2     | 1     | 0     |
| Initial value | 0     | 0     | 0     | 0     |
| Read/Write    | R     | R     | R     | R     |
| Bit name      | ADRL3 | ADRL2 | ADRL1 | ADRL0 |

**Figure 76 A/D Data Register Lower Digit (ADRL)**

**A/D data register (upper digit) (ADRU: \$018)**

|               |       |       |       |       |
|---------------|-------|-------|-------|-------|
| Bit           | 3     | 2     | 1     | 0     |
| Initial value | 1     | 0     | 0     | 0     |
| Read/Write    | R     | R     | R     | R     |
| Bit name      | ADRU3 | ADRU2 | ADRU1 | ADRU0 |

**Figure 77 A/D Data Register Upper Digit (ADRU)**

## HD404369 Series

### Notes on Usage

- Use the SEM or SEMD instruction for writing to the A/D start flag (ADSF)
- Do not write to the A/D start flag during A/D conversion
- Data in the A/D data register during A/D conversion is undefined
- Since the operation of the A/D converter is based on the clock from the system oscillator, the A/D converter does not operate in stop, watch, or subactive mode. In addition, to save power while in these modes, all current flowing through the converter's resistance ladder is cut off.
- If the power supply for the A/D converter is to be different from  $V_{CC}$ , connect a 0.1- $\mu$ F bypass capacitor between the  $AV_{CC}$  and  $AV_{SS}$  pins. (However, this is not necessary when the  $AV_{CC}$  pin is directly connected to the  $V_{CC}$  pin.)
- The contents of the A/D data register are not guaranteed during A/D conversion. To ensure that the A/D converter operates stably, do not execute port output instructions during A/D conversion.
- The port data register (PDR) is initialized to 1 by an MCU reset. At this time, if pull-up MOS is selected as active by bit 3 of the miscellaneous register (MIS3), the port will be pulled up to  $V_{CC}$ . When using a shared R port/analog input pin as an input pin, clear PDR to 0. Otherwise, if pull-up MOS is selected by MIS3 and PDR is set to 1, a pin selected by A/D mode register 1 or 2 (AMR1 or AMR2) as an analog pin will remain pulled up (figure 78).

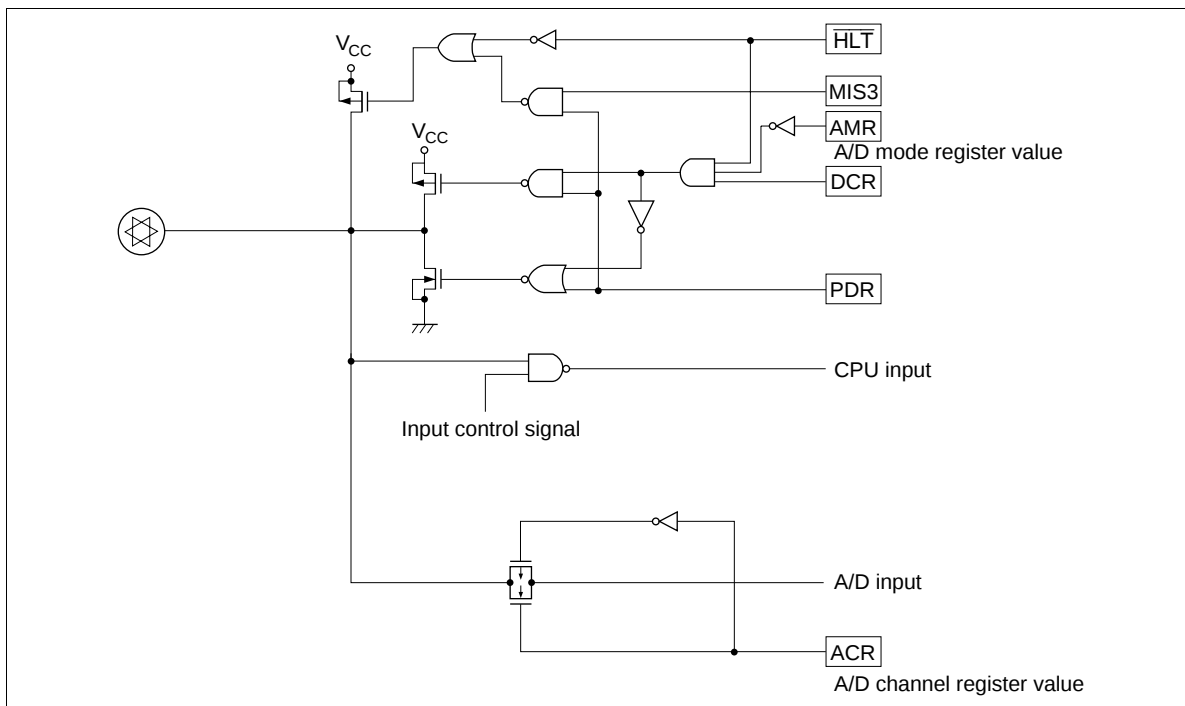


Figure 78 R Port/Analog Multiplexed Pin Circuit

### Pin Description in PROM Mode

The HD407A4369 is a PROM version of a ZTAT™ microcomputer. In PROM mode, the MCU stops operating, thus allowing the user to program the on-chip PROM.

| Pin Number |        |        | MCU Mode                          |     | PROM Mode       |     |
|------------|--------|--------|-----------------------------------|-----|-----------------|-----|
| DP-64S     | FP-64B | FP-64A | Pin                               | I/O | Pin             | I/O |
| 1          | 59     | 57     | R6 <sub>0</sub>                   | I/O |                 |     |
| 2          | 60     | 58     | R6 <sub>1</sub>                   | I/O |                 |     |
| 3          | 61     | 59     | R6 <sub>2</sub>                   | I/O |                 |     |
| 4          | 62     | 60     | R6 <sub>3</sub>                   | I/O |                 |     |
| 5          | 63     | 61     | R7 <sub>0</sub>                   | I/O |                 |     |
| 6          | 64     | 62     | R7 <sub>1</sub>                   | I/O |                 |     |
| 7          | 1      | 63     | R7 <sub>2</sub>                   | I/O |                 |     |
| 8          | 2      | 64     | R0 <sub>0</sub> /SCK              | I/O | V <sub>CC</sub> |     |
| 9          | 3      | 1      | R0 <sub>1</sub> /SI               | I/O | V <sub>CC</sub> |     |
| 10         | 4      | 2      | R0 <sub>2</sub> /SO               | I/O | O <sub>1</sub>  | I/O |
| 11         | 5      | 3      | R0 <sub>3</sub> /TOC              | I/O | O <sub>2</sub>  | I/O |
| 12         | 6      | 4      | TEST                              | I   | V <sub>PP</sub> |     |
| 13         | 7      | 5      | RESET                             | I   | RESET           | I   |
| 14         | 8      | 6      | OSC <sub>1</sub>                  | I   | V <sub>CC</sub> |     |
| 15         | 9      | 7      | OSC <sub>2</sub>                  | O   |                 |     |
| 16         | 10     | 8      | GND                               | —   | GND             |     |
| 17         | 11     | 9      | X1                                | I   | GND             |     |
| 18         | 12     | 10     | X2                                | O   |                 |     |
| 19         | 13     | 11     | AV <sub>SS</sub>                  | —   | GND             |     |
| 20         | 14     | 12     | R3 <sub>0</sub> /AN <sub>0</sub>  | I/O | O <sub>0</sub>  | I/O |
| 21         | 15     | 13     | R3 <sub>1</sub> /AN <sub>1</sub>  | I/O | O <sub>1</sub>  | I/O |
| 22         | 16     | 14     | R3 <sub>2</sub> /AN <sub>2</sub>  | I/O | O <sub>2</sub>  | I/O |
| 23         | 17     | 15     | R3 <sub>3</sub> /AN <sub>3</sub>  | I/O | O <sub>3</sub>  | I/O |
| 24         | 18     | 16     | R4 <sub>0</sub> /AN <sub>4</sub>  | I/O | O <sub>4</sub>  | I/O |
| 25         | 19     | 17     | R4 <sub>1</sub> /AN <sub>5</sub>  | I/O | M <sub>0</sub>  | I   |
| 26         | 20     | 18     | R4 <sub>2</sub> /AN <sub>6</sub>  | I/O | M <sub>1</sub>  | I   |
| 27         | 21     | 19     | R4 <sub>3</sub> /AN <sub>7</sub>  | I/O |                 |     |
| 28         | 22     | 20     | R5 <sub>0</sub> /AN <sub>8</sub>  | I/O |                 |     |
| 29         | 23     | 21     | R5 <sub>1</sub> /AN <sub>9</sub>  | I/O |                 |     |
| 30         | 24     | 22     | R5 <sub>2</sub> /AN <sub>10</sub> | I/O |                 |     |

## HD404369 Series

| Pin Number |        |        | MCU Mode                          |     | PROM Mode              |     |
|------------|--------|--------|-----------------------------------|-----|------------------------|-----|
| DP-64S     | FP-64B | FP-64A | Pin                               | I/O | Pin                    | I/O |
| 31         | 25     | 23     | R5 <sub>3</sub> /AN <sub>11</sub> | I/O |                        |     |
| 32         | 26     | 24     | AV <sub>CC</sub>                  | —   | V <sub>CC</sub>        |     |
| 33         | 27     | 25     | V <sub>CC</sub>                   | —   | V <sub>CC</sub>        |     |
| 34         | 28     | 26     | D <sub>0</sub> /INT <sub>0</sub>  | I/O | O <sub>3</sub>         | I/O |
| 35         | 29     | 27     | D <sub>1</sub> /INT <sub>1</sub>  | I/O | O <sub>4</sub>         | I/O |
| 36         | 30     | 28     | D <sub>2</sub> /EVNB              | I/O | A <sub>1</sub>         | I   |
| 37         | 31     | 29     | D <sub>3</sub> /BUZZ              | I/O | A <sub>2</sub>         | I   |
| 38         | 32     | 30     | D <sub>4</sub> /STOPC             | I/O |                        |     |
| 39         | 33     | 31     | D <sub>5</sub>                    | I/O | A <sub>3</sub>         | I   |
| 40         | 34     | 32     | D <sub>6</sub>                    | I/O | A <sub>4</sub>         | I   |
| 41         | 35     | 33     | D <sub>7</sub>                    | I/O | A <sub>9</sub>         | I   |
| 42         | 36     | 34     | D <sub>8</sub>                    | I/O | V <sub>CC</sub>        |     |
| 43         | 37     | 35     | D <sub>9</sub>                    | I/O |                        |     |
| 44         | 38     | 36     | D <sub>10</sub>                   | I/O |                        |     |
| 45         | 39     | 37     | D <sub>11</sub>                   | I/O |                        |     |
| 46         | 40     | 38     | D <sub>12</sub>                   | I/O |                        |     |
| 47         | 41     | 39     | D <sub>13</sub>                   | I/O |                        |     |
| 48         | 42     | 40     | R8 <sub>0</sub>                   | I/O | $\overline{\text{CE}}$ | I   |
| 49         | 43     | 41     | R8 <sub>1</sub>                   | I/O | $\overline{\text{OE}}$ | I   |
| 50         | 44     | 42     | R8 <sub>2</sub>                   | I/O | A <sub>13</sub>        | I   |
| 51         | 45     | 43     | R8 <sub>3</sub>                   | I/O | A <sub>14</sub>        | I   |
| 52         | 46     | 44     | R9 <sub>0</sub>                   | I/O |                        |     |
| 53         | 47     | 45     | R9 <sub>1</sub>                   | I/O |                        |     |
| 54         | 48     | 46     | R9 <sub>2</sub>                   | I/O |                        |     |
| 55         | 49     | 47     | R9 <sub>3</sub>                   | I/O |                        |     |
| 56         | 50     | 48     | R1 <sub>0</sub>                   | I/O | A <sub>5</sub>         | I   |
| 57         | 51     | 49     | R1 <sub>1</sub>                   | I/O | A <sub>6</sub>         | I   |
| 58         | 52     | 50     | R1 <sub>2</sub>                   | I/O | A <sub>7</sub>         | I   |
| 59         | 53     | 51     | R1 <sub>3</sub>                   | I/O | A <sub>8</sub>         | I   |
| 60         | 54     | 52     | R2 <sub>0</sub>                   | I/O | A <sub>0</sub>         | I   |
| 61         | 55     | 53     | R2 <sub>1</sub>                   | I/O | A <sub>10</sub>        | I   |
| 62         | 56     | 54     | R2 <sub>2</sub>                   | I/O | A <sub>11</sub>        | I   |
| 63         | 57     | 55     | R2 <sub>3</sub>                   | I/O | A <sub>12</sub>        | I   |
| 64         | 58     | 56     | RA <sub>1</sub>                   | I   | O <sub>0</sub>         | I/O |

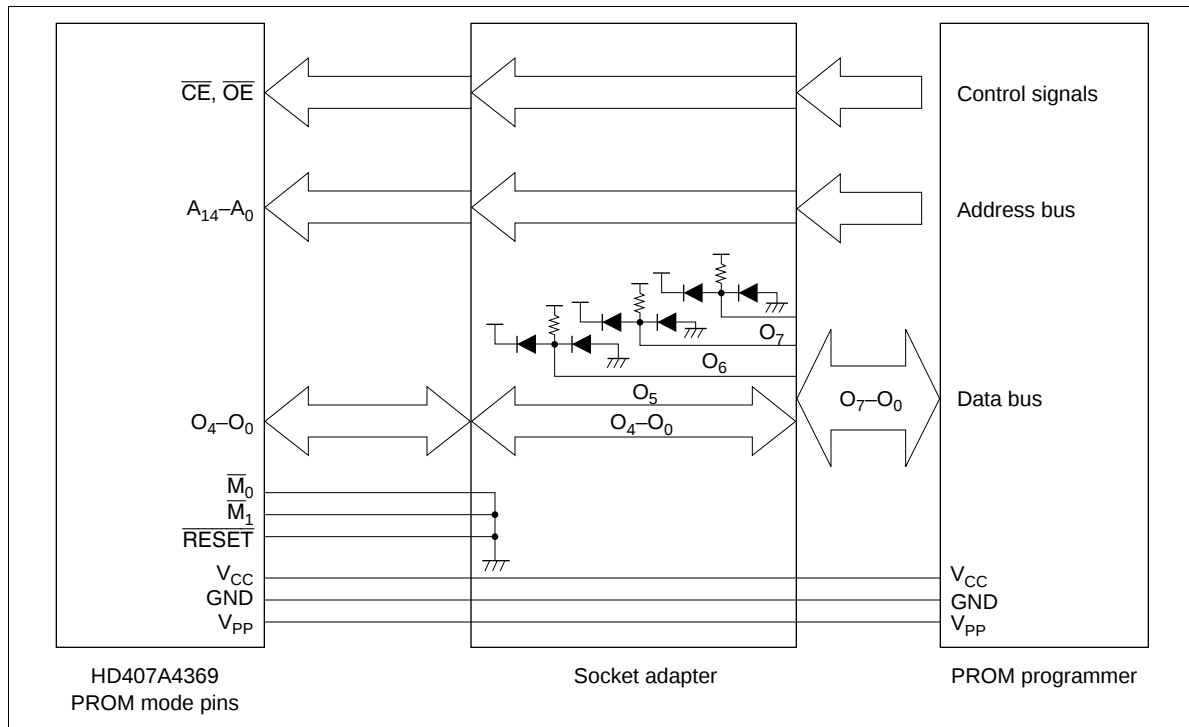
Notes: 1. I/O: Input/output pin; I: Input pin; O: Output pin

2. O<sub>0</sub> to O<sub>4</sub> consist of two pins each. Tie each pair together before using them.

## Programming the Built-In PROM

The MCU's built-in PROM is programmed in PROM mode. PROM mode is set by pulling  $\overline{\text{RESET}}$ ,  $\overline{\text{M}}_0$ , and  $\overline{\text{M}}_1$  low, as shown in figure 79. In PROM mode, the MCU does not operate, but it can be programmed in the same way as any other commercial 27256-type EPROM using a standard PROM programmer and a 100-to-28-pin socket adapter. Recommended PROM programmers and socket adapters are listed in table 29.

Since an HMCS400-series instruction is ten bits long, the HMCS400-series MCU has a built-in conversion circuit to enable the use of a general-purpose PROM programmer. This circuit splits each instruction into five lower bits and five upper bits that are read from or written to consecutive addresses. This means that if, for example, 16 kwords of built-in PROM are to be programmed by a general-purpose PROM programmer, a 32-kbyte address space (\$0000–\$7FFF) must be specified.



**Figure 79 PROM Mode Connections**

## HD404369 Series

**Table 29 Recommended PROM Programmers and Socket Adapters**

| PROM Programmer |            | Socket Adapter |             |              |
|-----------------|------------|----------------|-------------|--------------|
| Manufacture     | Model Name | Package        | Manufacture | Model Name   |
| DATA I/O corp   | 121 B      | DP-64S         | Hitachi     | HS4369ESS01H |
|                 |            | FP-64B         |             | HS4369ESF01H |
|                 |            | FP-64A         |             | HS4369ESH01H |
| AVAL corp       | PKW-1000   | DP-64S         | Hitachi     | HS4369ESS01H |
|                 |            | FP-64B         |             | HS4369ESF01H |
|                 |            | FP-64A         |             | HS4369ESH01H |

### Warnings

1. Always specify addresses \$0000 to \$7FFF when programming with a PROM programmer. If address \$8000 or higher is accessed, the PROM may not be programmed or verified correctly. Set all data in unused addresses to \$FF.  
Note that the plastic-package version cannot be erased and reprogrammed.
2. Make sure that the PROM programmer, socket adapter, and LSI are aligned correctly (their pin 1 positions match), otherwise overcurrents may damage the LSI. Before starting programming, make sure that the LSI is firmly fixed in the socket adapter and the socket adapter is firmly fixed onto the programmer.
3. PROM programmers have two voltages ( $V_{pp}$ ): 12.5 V and 21 V. Remember that ZTAT™ devices require a  $V_{pp}$  of 12.5 V—the 21-V setting will damage them. 12.5 V is the Intel 27256 setting.

### Programming and Verification

The built-in PROM of the MCU can be programmed at high speed without risk of voltage stress or damage to data reliability.

Programming and verification modes are selected as listed in table 30.

For details of PROM programming, refer to the following Notes on PROM Programming section.

**Table 30 PROM Mode Selection**

| Mode                  | Pin  |      |          |                |
|-----------------------|------|------|----------|----------------|
|                       | CE   | OE   | $V_{pp}$ | $O_0-O_4$      |
| Programming           | Low  | High | $V_{pp}$ | Data input     |
| Verification          | High | Low  | $V_{pp}$ | Data output    |
| Programming inhibited | High | High | $V_{pp}$ | High impedance |

## Addressing Modes

### RAM Addressing Modes

The MCU has three RAM addressing modes, as shown in figure 80 and described below.

**Register Indirect Addressing Mode:** The contents of the W, X, and Y registers (10 bits in total) are used as a RAM address.

**Direct Addressing Mode:** A direct addressing instruction consists of two words. The first word contains the opcode, and the contents of the second word (10 bits) are used as a RAM address.

**Memory Register Addressing Mode:** The memory registers (MR), which are located in 16 addresses from \$040 to \$04F, are accessed with the LAMR and XMRA instructions.

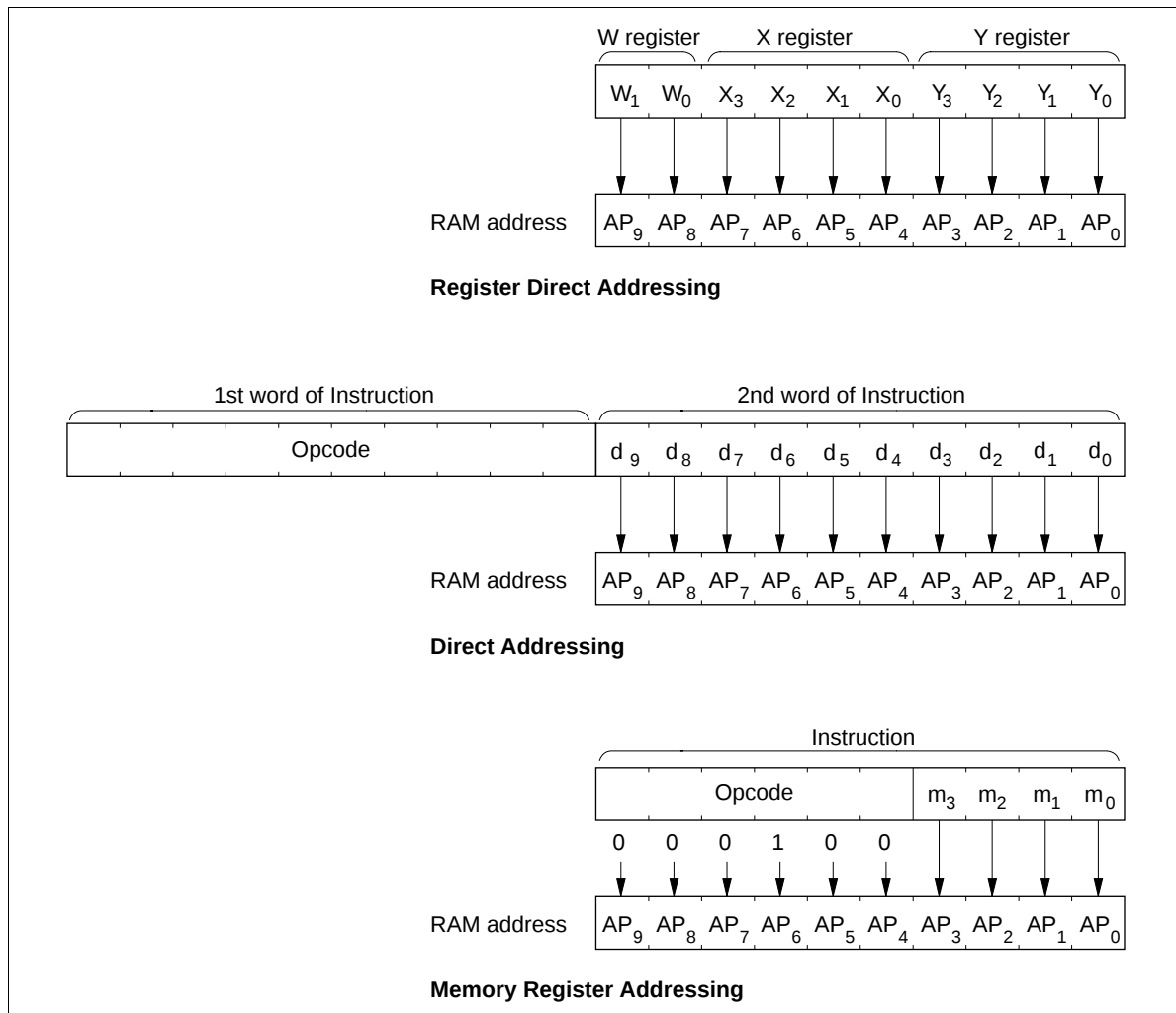


Figure 80 RAM Addressing Modes

---

## HD404369 Series

---

### ROM Addressing Modes and the P Instruction

The MCU has four ROM addressing modes, as shown in figure 81 and described below.

**Direct Addressing Mode:** A program can branch to any address in the ROM memory space by executing the JMPL, BRL, or CALL instruction. Each of these instructions replaces the 14 program counter bits ( $PC_{13}$ – $PC_0$ ) with 14-bit immediate data.

**Current Page Addressing Mode:** The MCU has 64 pages of ROM with 256 words per page. A program can branch to any address in the current page by executing the BR instruction. This instruction replaces the eight low-order bits of the program counter ( $PC_7$ – $PC_0$ ) with eight-bit immediate data. If the BR instruction is on a page boundary (address  $256n + 255$ ), executing that instruction transfers the PC contents to the next physical page, as shown in figure 83. This means that the execution of the BR instruction on a page boundary will make the program branch to the next page.

Note that the HMCS400-series cross macroassembler has an automatic paging feature for ROM pages.

**Zero-Page Addressing Mode:** A program can branch to the zero-page subroutine area located at \$0000–\$003F by executing the CAL instruction. When the CAL instruction is executed, 6 bits of immediate data are placed in the six low-order bits of the program counter ( $PC_5$ – $PC_0$ ), and 0s are placed in the eight high-order bits ( $PC_{13}$ – $PC_6$ ).

**Table Data Addressing Mode:** A program can branch to an address determined by the contents of four-bit immediate data, the accumulator, and the B register by executing the TBR instruction.

**P Instruction:** ROM data addressed in table data addressing mode can be referenced with the P instruction as shown in figure 82. If bit 8 of the ROM data is 1, eight bits of ROM data are written to the accumulator and the B register. If bit 9 is 1, eight bits of ROM data are written to the R1 and R2 port output registers. If both bits 8 and 9 are 1, ROM data is written to the accumulator and the B register, and also to the R1 and R2 port output registers at the same time.

The P instruction has no effect on the program counter.

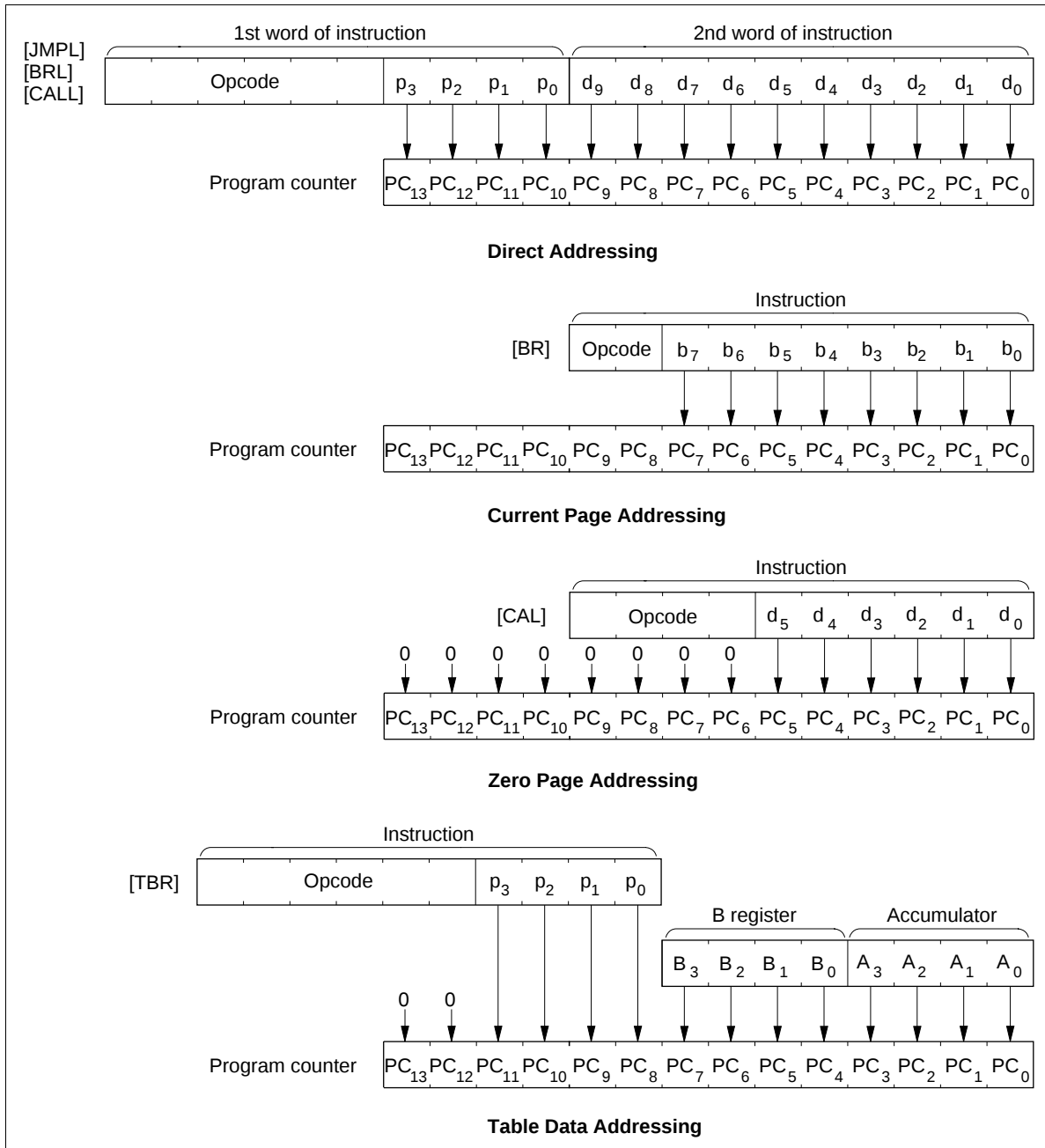
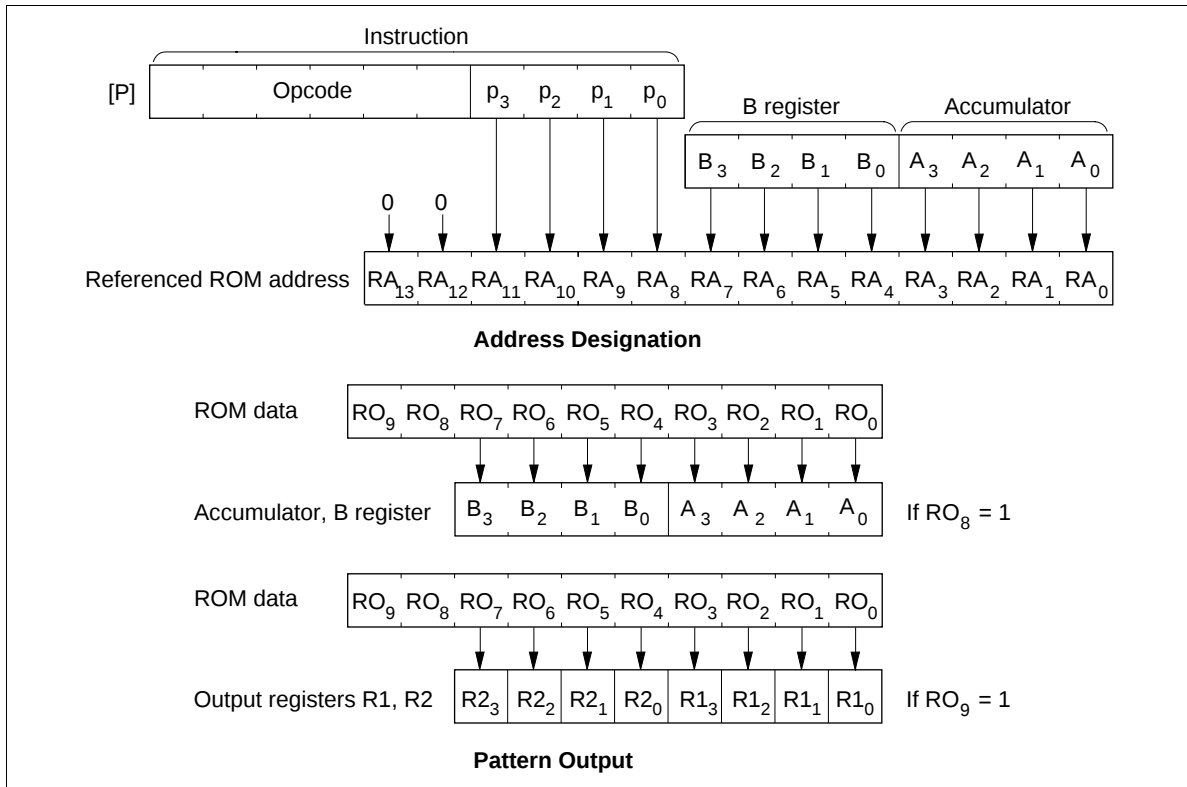
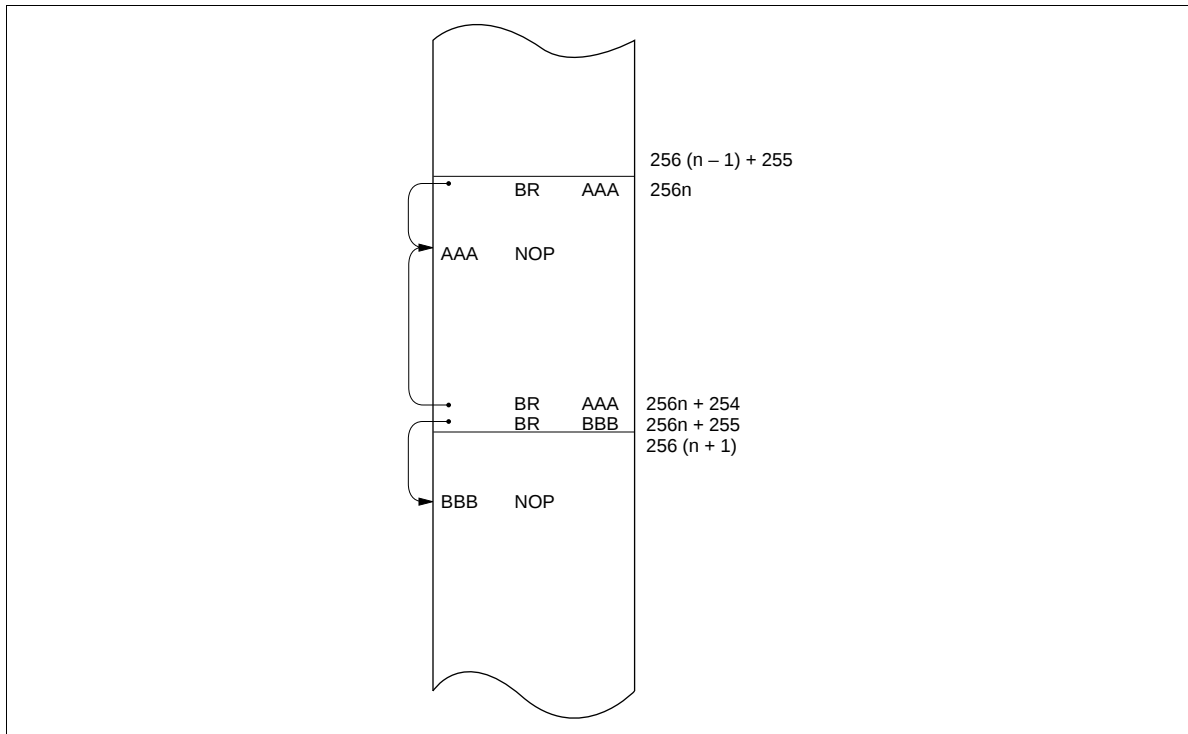


Figure 81 ROM Addressing Modes



**Figure 82 P Instruction**



**Figure 83 Branching when the Branch Destination is on a Page Boundary**

---

## HD404369 Series

---

### Instruction Set

The HD404369 Series has 101 instructions, classified into the following 10 groups:

- Immediate instructions
- Register-to-register instructions
- RAM address instructions
- RAM register instructions
- Arithmetic instructions
- Compare instructions
- RAM bit manipulation instructions
- ROM address instructions
- Input/output instructions
- Control instructions

**Absolute Maximum Ratings**

| Item                             | Symbol        | Value                  | Unit | Notes |
|----------------------------------|---------------|------------------------|------|-------|
| Supply voltage                   | $V_{CC}$      | −0.3 to +7.0           | V    |       |
| Programming voltage              | $V_{PP}$      | −0.3 to +14.0          | V    | 1     |
| Pin voltage                      | $V_T$         | −0.3 to $V_{CC} + 0.3$ | V    | 2     |
|                                  |               | −0.3 to +15.0          | V    | 3     |
| Total permissible input current  | $\Sigma I_O$  | 105                    | mA   | 4     |
| Total permissible output current | $-\Sigma I_O$ | 50                     | mA   | 5     |
| Maximum input current            | $I_O$         | 4                      | mA   | 6, 7  |
|                                  |               | 30                     | mA   | 6, 8  |
| Maximum output current           | $-I_O$        | 4                      | mA   | 7, 9  |
| Operating temperature            | $T_{opr}$     | −20 to +75             | °C   |       |
| Storage temperature              | $T_{stg}$     | −55 to +125            | °C   |       |

Notes: Permanent damage may occur if these absolute maximum ratings are exceeded. Normal operation must be under the conditions stated in the electrical characteristics tables. If these conditions are exceeded, the LSI may malfunction or its reliability may be affected.

1. Applies to pin TEST ( $V_{PP}$ ) of HD407A4369.
2. Applies to all standard voltage pins.
3. Applies to intermediate-voltage pins.
4. The total permissible input current is the total of input currents simultaneously flowing in from all the I/O pins to GND.
5. The total permissible output current is the total of output currents simultaneously flowing out from  $V_{CC}$  to all I/O pins.
6. The maximum input current is the maximum current flowing from each I/O pin to GND.
7. Applies to ports  $D_0$  to  $D_{13}$ , R0, R3 to R9.
8. Applies to ports R1 and R2.
9. The maximum output current is the maximum current flowing from  $V_{CC}$  to each I/O pin

## HD404369 Series

### Electrical Characteristics

DC Characteristics (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ , unless otherwise specified)

| Item                                  | Symbol     | Pins                                                                                                                                                    | Min            | Typ | Max            | Unit | Test Condition                       | Notes |
|---------------------------------------|------------|---------------------------------------------------------------------------------------------------------------------------------------------------------|----------------|-----|----------------|------|--------------------------------------|-------|
| Input high voltage                    | $V_{IH}$   | $\overline{RESET}$ , $\overline{SCK}$ ,<br>$\overline{INT}_0$ , $\overline{INT}_1$ ,<br>$\overline{STOPC}$ , EVNB                                       | $0.8V_{CC}$    | —   | $V_{CC} + 0.3$ | V    |                                      |       |
|                                       |            | SI                                                                                                                                                      | $0.7V_{CC}$    | —   | $V_{CC} + 0.3$ | V    |                                      |       |
|                                       |            | OSC <sub>1</sub>                                                                                                                                        | $V_{CC} - 0.5$ | —   | $V_{CC} + 0.3$ | V    |                                      |       |
| Input low voltage                     | $V_{IL}$   | $\overline{RESET}$ , $\overline{SCK}$ ,<br>$\overline{INT}_0$ , $\overline{INT}_1$ ,<br>$\overline{STOPC}$ , EVNB                                       | $-0.3$         | —   | $0.2V_{CC}$    | V    |                                      |       |
|                                       |            | SI                                                                                                                                                      | $-0.3$         | —   | $0.3V_{CC}$    | V    |                                      |       |
|                                       |            | OSC <sub>1</sub>                                                                                                                                        | $-0.3$         | —   | 0.5            | V    |                                      |       |
| Output high voltage                   | $V_{OH}$   | $\overline{SCK}$ , SO, TOC                                                                                                                              | $V_{CC} - 0.5$ | —   | —              | V    | $-I_{OH} = 0.5$ mA                   |       |
| Output low voltage                    | $V_{OL}$   | $\overline{SCK}$ , SO, TOC                                                                                                                              | —              | —   | 0.4            | V    | $I_{OL} = 0.4$ mA                    |       |
| I/O leakage current                   | $ I_{IL} $ | $\overline{RESET}$ , $\overline{SCK}$ ,<br>SI, SO, TOC,<br>OSC <sub>1</sub> , $\overline{INT}_0$ ,<br>$\overline{INT}_1$ , $\overline{STOPC}$ ,<br>EVNB | —              | —   | 1              | μA   | $V_{in} = 0$ V to $V_{CC}$           | 1     |
| Current dissipation in active mode    | $I_{CC}$   | $V_{CC}$                                                                                                                                                | —              | —   | 5.0            | mA   | $V_{CC} = 5$ V,<br>$f_{OSC} = 4$ MHz | 2     |
| Current dissipation in standby mode   | $I_{SBY}$  | $V_{CC}$                                                                                                                                                | —              | —   | 2.0            | mA   | $V_{CC} = 5$ V,<br>$f_{OSC} = 4$ MHz | 3     |
| Current dissipation in subactive mode | $I_{SUB}$  | $V_{CC}$                                                                                                                                                | —              | —   | 100            | μA   | $V_{CC} = 5$ V,<br>32 kHz oscillator | 4     |
| Current dissipation in watch mode     | $I_{WTC}$  | $V_{CC}$                                                                                                                                                | —              | —   | 20             | μA   | $V_{CC} = 5$ V,<br>32 kHz oscillator | 4     |

## HD404369 Series

| Item                             | Symbol     | Pins     | Min | Typ | Max | Unit    | Test Condition                            | Notes |
|----------------------------------|------------|----------|-----|-----|-----|---------|-------------------------------------------|-------|
| Current dissipation in stop mode | $I_{STOP}$ | $V_{CC}$ | —   | —   | 10  | $\mu A$ | $V_{CC} = 5V$ ,<br>X1 = GND,<br>X2 = Open | 4     |
| Stop mode retaining voltage      | $V_{STOP}$ | $V_{CC}$ | 2   | —   | —   | V       |                                           |       |

- Notes:
- Excludes current flowing through pull-up MOS and output buffers.
  - $I_{CC}$  is the source current when no I/O current is flowing while the MCU is in reset state.  
Test conditions: MCU: Reset  
Pins:  $\overline{RESET}$ , TEST at GND
  - $I_{SBY}$  is the source current when no I/O current is flowing while the MCU timer is operating.  
Test conditions: MCU: I/O reset  
Standby mode  
Pins:  $\overline{RESET}$  at  $V_{CC}$   
TEST at GND  
 $D_0$ – $D_{13}$ , R0–R9, RA<sub>1</sub> at  $V_{CC}$
  - This is the source current when no I/O current is flowing.  
Test conditions: Pins:  $\overline{RESET}$  at  $V_{CC}$   
TEST at GND  
 $D_0$ – $D_{13}$ , R0–R9, RA<sub>1</sub> at  $V_{CC}$

## HD404369 Series

**I/O Characteristics for Standard Pins (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ , unless otherwise specified)**

| Item                  | Symbol     | Pins                                                 | Min            | Typ | Max            | Unit          | Test Condition                    | Note |
|-----------------------|------------|------------------------------------------------------|----------------|-----|----------------|---------------|-----------------------------------|------|
| Input high voltage    | $V_{IH}$   | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$ , $RA_1$ | $0.7V_{CC}$    | —   | $V_{CC} + 0.3$ | V             |                                   |      |
| Input low voltage     | $V_{IL}$   | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$ , $RA_1$ | $-0.3$         | —   | $0.3V_{CC}$    | V             |                                   |      |
| Output high voltage   | $V_{OH}$   | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$          | $V_{CC} - 0.5$ | —   | —              | V             | $-I_{OH} = 0.5$ mA                |      |
| Output low voltage    | $V_{OL}$   | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$          | —              | —   | 0.4            | V             | $I_{OL} = 1.6$ mA                 |      |
| Input leakage current | $ I_{IL} $ | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$ , $RA_1$ | —              | —   | 1              | $\mu\text{A}$ | $V_{in} = 0$ V to $V_{CC}$        | 1    |
| Pull-up MOS current   | $-I_{PU}$  | $D_0$ – $D_{13}$ ,<br>$R_0$ , $R_3$ – $R_9$          | 30             | 150 | 300            | $\mu\text{A}$ | $V_{CC} = 5$ V,<br>$V_{in} = 0$ V |      |

Note: 1. Output buffer current is excluded.

**I/O Characteristics for Intermediate-Voltage Pins (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ , unless otherwise specified)**

| Item                | Symbol     | Pins          | Min         | Typ | Max         | Unit          | Test Condition                                 | Note |
|---------------------|------------|---------------|-------------|-----|-------------|---------------|------------------------------------------------|------|
| Input high voltage  | $V_{IH}$   | $R_1$ , $R_2$ | $0.7V_{CC}$ | —   | 12          | V             |                                                |      |
| Input low voltage   | $V_{IL}$   | $R_1$ , $R_2$ | $-0.3$      | —   | $0.3V_{CC}$ | V             |                                                |      |
| Output high voltage | $V_{OH}$   | $R_1$ , $R_2$ | 11.5        | —   | —           | V             | 500 k $\Omega$ at 12 V                         |      |
| Output low voltage  | $V_{OL}$   | $R_1$ , $R_2$ | —           | —   | 0.4         | V             | $I_{OL} = 0.4$ mA                              |      |
|                     |            |               | —           | —   | 2.0         | V             | $I_{OL} = 15$ mA,<br>$V_{CC} = 4.5$ to $5.5$ V |      |
| I/O leakage current | $ I_{IL} $ | $R_1$ , $R_2$ | —           | —   | 20          | $\mu\text{A}$ | $V_{in} = 0$ V to 12 V                         | 1    |

Note: 1. Excludes output buffer current.

## HD404369 Series

**A/D Converter Characteristics (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ , unless otherwise specified)**

| Item                                            | Symbol    | Pins           | Min            | Typ      | Max            | Unit          | Test Condition             | Notes |
|-------------------------------------------------|-----------|----------------|----------------|----------|----------------|---------------|----------------------------|-------|
| Analog supply voltage                           | $AV_{CC}$ | $AV_{CC}$      | $V_{CC} - 0.3$ | $V_{CC}$ | $V_{CC} + 0.3$ | V             |                            | 1     |
| Analog input voltage                            | $AV_{in}$ | $AN_0-AN_{11}$ | $AV_{SS}$      | —        | $AV_{CC}$      | V             |                            |       |
| Current flowing between $AV_{CC}$ and $AV_{SS}$ | $I_{AD}$  |                | —              | —        | 200            | $\mu\text{A}$ | $V_{CC} = AV_{CC} = 5.0$ V |       |
| Analog input capacitance                        | $CA_{in}$ | $AN_0-AN_{11}$ | —              | —        | 30             | pF            |                            |       |
| Resolution                                      |           |                | 8              | 8        | 8              | Bit           |                            |       |
| Number of input channels                        |           |                | 0              | —        | 12             | Channel       |                            |       |
| Absolute accuracy                               |           |                | —              | —        | $\pm 2.0$      | LSB           |                            |       |
| Conversion time                                 |           |                | 34             | —        | 67             | $t_{cyc}$     |                            |       |
| Input impedance                                 |           | $AN_0-AN_{11}$ | 1              | —        | —              | $M\Omega$     |                            |       |

Note: 1. Connect this to  $V_{CC}$  if the A/D converter is not used.

## HD404369 Series

Standard  $f_{OSC} = 5 \text{ MHz}$  Version AC Characteristics (HD404364/HD404368/HD4043612/HD404369:  
 $V_{CC} = 2.7 \text{ to } 6.0 \text{ V}$ ,  $GND = 0 \text{ V}$ ,  $T_a = -20 \text{ to } +75^\circ\text{C}$ )

| Item                                                       | Symbol       | Pins                                           | Min | Typ    | Max | Unit                 | Test Condition                                     | Notes |
|------------------------------------------------------------|--------------|------------------------------------------------|-----|--------|-----|----------------------|----------------------------------------------------|-------|
| Clock oscillation frequency                                | $f_{OSC}$    | OSC <sub>1</sub> , OSC <sub>2</sub>            | 0.4 | 4      | 5.0 | MHz                  | 1/4 system clock division ratio                    | 1     |
|                                                            |              | X1, X2                                         | —   | 32.768 | —   | kHz                  |                                                    |       |
| Instruction cycle time                                     | $t_{cyc}$    |                                                | 0.8 | 1      | 10  | μs                   |                                                    | 1     |
|                                                            | $t_{subcyc}$ |                                                | —   | 244.14 | —   | μs                   | 32-kHz oscillator, 1/8 system clock division ratio |       |
|                                                            |              |                                                | —   | 122.07 | —   | μs                   | 32-kHz oscillator, 1/4 system clock division ratio |       |
| Oscillation stabilization time (ceramic oscillator)        | $t_{RC}$     | OSC <sub>1</sub> , OSC <sub>2</sub>            | —   | —      | 7.5 | ms                   |                                                    | 2     |
| Oscillation stabilization time (crystal oscillator)        | $t_{RC}$     | OSC <sub>1</sub> , OSC <sub>2</sub>            | —   | —      | 40  | ms                   |                                                    | 2     |
|                                                            |              | X1, X2                                         | —   | —      | 2   | s                    |                                                    | 2     |
| External clock high width                                  | $t_{CPH}$    | OSC <sub>1</sub>                               | 80  | —      | —   | ns                   |                                                    | 3     |
| External clock low width                                   | $t_{CPL}$    | OSC <sub>1</sub>                               | 80  | —      | —   | ns                   |                                                    | 3     |
| External clock rise time                                   | $t_{CPr}$    | OSC <sub>1</sub>                               | —   | —      | 20  | ns                   |                                                    | 3     |
| External clock fall time                                   | $t_{CPf}$    | OSC <sub>1</sub>                               | —   | —      | 20  | ns                   |                                                    | 3     |
| $\overline{INT_0}$ , $\overline{INT_1}$ , EVNB high widths | $t_{IH}$     | $\overline{INT_0}$ , $\overline{INT_1}$ , EVNB | 2   | —      | —   | $t_{cyc}/t_{subcyc}$ |                                                    | 4     |
| $\overline{INT_0}$ , $\overline{INT_1}$ , EVNB low widths  | $t_{IL}$     | $\overline{INT_0}$ , $\overline{INT_1}$ , EVNB | 2   | —      | —   | $t_{cyc}/t_{subcyc}$ |                                                    | 4     |
| $\overline{RESET}$ low width                               | $t_{RSTL}$   | $\overline{RESET}$                             | 2   | —      | —   | $t_{cyc}$            |                                                    | 5     |
| $\overline{STOPC}$ low width                               | $t_{STPL}$   | $\overline{STOPC}$                             | 1   | —      | —   | $t_{RC}$             |                                                    | 6     |
| $\overline{RESET}$ rise time                               | $t_{RSTr}$   | $\overline{RESET}$                             | —   | —      | 20  | ms                   |                                                    | 5     |
| $\overline{STOPC}$ rise time                               | $t_{STPr}$   | $\overline{STOPC}$                             | —   | —      | 20  | ms                   |                                                    | 6     |
| Input capacitance                                          | $C_{in}$     | All input pins except R1 and R2                | —   | —      | 15  | pF                   | $f = 1 \text{ MHz}$ ,<br>$V_{in} = 0 \text{ V}$    |       |
|                                                            |              | R1, R2                                         | —   | —      | 30  | pF                   | $f = 1 \text{ MHz}$ ,<br>$V_{in} = 0 \text{ V}$    |       |

- Notes:
1. When using the subsystem oscillator (32.768 kHz), one of the following relationships for  $f_{OSC}$  must be applied.  
 $0.4 \text{ MHz} \leq f_{OSC} \leq 1.0 \text{ MHz}$  or  $1.6 \text{ MHz} \leq f_{OSC} \leq 5.0 \text{ MHz}$   
The operating range for  $f_{OSC}$  can be set with bit 1 of system clock selection register 1 (SSR1: \$027).
  2. The oscillation stabilization time is the period required for the oscillator to stabilize in the following situations:
    - a. After  $V_{CC}$  reaches 2.7 V at power-on.
    - b. After  $\overline{\text{RESET}}$  input goes low when stop mode is cancelled.
    - c. After  $\overline{\text{STOPC}}$  input goes low when stop mode is cancelled.To ensure the oscillation stabilization time at power-on or when stop mode is cancelled,  $\overline{\text{RESET}}$  or  $\overline{\text{STOPC}}$  must be input for at least a duration of  $t_{RC}$ .  
When using a crystal or ceramic oscillator, consult with the manufacturer to determine what stabilization time is required, since it will depend on the circuit constants and stray capacitance.
  3. Refer to figure 84.
  4. Refer to figure 85.
  5. Refer to figure 86.
  6. Refer to figure 87.

## HD404369 Series

**High-Speed  $f_{OSC} = 8.5$  MHz Version AC Characteristics (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ )**

| Item                                                       | Symbol       | Pins                                           | Min  | Typ    | Max | Unit                 | Test Condition                                     | Notes |
|------------------------------------------------------------|--------------|------------------------------------------------|------|--------|-----|----------------------|----------------------------------------------------|-------|
| Clock oscillation frequency                                | $f_{OSC}$    | OSC <sub>1</sub> , OSC <sub>2</sub>            | 0.4  | 4      | 5.0 | MHz                  | 1/4 system clock division ratio                    | 1     |
|                                                            |              |                                                | 0.4  | 4      | 8.5 | MHz                  |                                                    | 2, 3  |
|                                                            |              | X1, X2                                         | —    | 32.768 | —   | kHz                  |                                                    |       |
| Instruction cycle time                                     | $t_{cyc}$    |                                                | 0.8  | 1      | 10  | $\mu\text{s}$        |                                                    | 1     |
|                                                            |              |                                                | 0.47 | 1      | 10  | $\mu\text{s}$        |                                                    | 2, 3  |
|                                                            | $t_{subcyc}$ |                                                | —    | 244.14 | —   | $\mu\text{s}$        | 32-kHz oscillator, 1/8 system clock division ratio |       |
|                                                            |              |                                                | —    | 122.07 | —   | $\mu\text{s}$        | 32-kHz oscillator, 1/4 system clock division ratio |       |
| Oscillation stabilization time (ceramic oscillator)        | $t_{RC}$     | OSC <sub>1</sub> , OSC <sub>2</sub>            | —    | —      | 7.5 | ms                   |                                                    | 4     |
| Oscillation stabilization time (ceramic oscillator)        | $t_{RC}$     | OSC <sub>1</sub> , OSC <sub>2</sub>            | —    | —      | 40  | ms                   |                                                    | 4     |
|                                                            |              | X1, X2                                         | —    | —      | 2   | s                    |                                                    | 4     |
| External clock high width                                  | $t_{CPH}$    | OSC <sub>1</sub>                               | 80   | —      | —   | ns                   |                                                    | 5     |
|                                                            |              |                                                | 47   | —      | —   | ns                   |                                                    | 3, 5  |
| External clock low width                                   | $t_{CPL}$    | OSC <sub>1</sub>                               | 80   | —      | —   | ns                   |                                                    | 5     |
|                                                            |              |                                                | 47   | —      | —   | ns                   |                                                    | 3, 5  |
| External clock rise time                                   | $t_{CPr}$    | OSC <sub>1</sub>                               | —    | —      | 20  | ns                   |                                                    | 5     |
|                                                            |              |                                                | —    | —      | 15  | ns                   |                                                    | 3, 5  |
| External clock fall time                                   | $t_{CPf}$    | OSC <sub>1</sub>                               | —    | —      | 20  | ns                   |                                                    | 5     |
|                                                            |              |                                                | —    | —      | 15  | ns                   |                                                    | 3, 5  |
| $\overline{INT}_0$ , $\overline{INT}_1$ , EVNB high widths | $t_{IH}$     | $\overline{INT}_0$ , $\overline{INT}_1$ , EVNB | 2    | —      | —   | $t_{cyc}/t_{subcyc}$ |                                                    | 6     |
| $\overline{INT}_0$ , $\overline{INT}_1$ , EVNB low widths  | $t_{IL}$     | $\overline{INT}_0$ , $\overline{INT}_1$ , EVNB | 2    | —      | —   | $t_{cyc}/t_{subcyc}$ |                                                    | 6     |

## HD404369 Series

| Item              | Symbol     | Pins                                  | Min | Typ | Max | Unit      | Test Condition                            | Notes |
|-------------------|------------|---------------------------------------|-----|-----|-----|-----------|-------------------------------------------|-------|
| RESET low width   | $t_{RSTL}$ | RESET                                 | 2   | —   | —   | $t_{cyc}$ |                                           | 7     |
| STOPC low width   | $t_{STPL}$ | STOPC                                 | 1   | —   | —   | $t_{RC}$  |                                           | 8     |
| RESET rise time   | $t_{RSTr}$ | RESET                                 | —   | —   | 20  | ms        |                                           | 7     |
| STOPC rise time   | $t_{STPr}$ | STOPC                                 | —   | —   | 20  | ms        |                                           | 8     |
| Input capacitance | $C_{in}$   | All input pins except TEST, R1 and R2 | —   | —   | 15  | pF        | $f = 1 \text{ MHz}, V_{in} = 0 \text{ V}$ |       |
|                   |            | TEST                                  | —   | —   | 15  | pF        | $f = 1 \text{ MHz}, V_{in} = 0 \text{ V}$ | 9     |
|                   |            | TEST                                  | —   | —   | 180 | pF        | $f = 1 \text{ MHz}, V_{in} = 0 \text{ V}$ | 10    |
|                   |            | R1, R2                                | —   | —   | 30  | pF        | $f = 1 \text{ MHz}, V_{in} = 0 \text{ V}$ |       |

- Notes:
- When using the subsystem oscillator (32.768 kHz), one of the following relationships for  $f_{osc}$  must be applied.  
 $0.4 \text{ MHz} \leq f_{osc} \leq 1.0 \text{ MHz}$  or  $1.6 \text{ MHz} \leq f_{osc} \leq 5.0 \text{ MHz}$   
The operating range for  $f_{osc}$  can be set with bit 1 of system clock selection register 1 (SSR1: \$027).
  - When using the subsystem oscillator (32.768 kHz), one of the following relationships for  $f_{osc}$  must be applied.  
 $0.4 \text{ MHz} \leq f_{osc} \leq 1.0 \text{ MHz}$  or  $1.6 \text{ MHz} \leq f_{osc} \leq 8.5 \text{ MHz}$   
The operating range for  $f_{osc}$  can be set with bit 1 of system clock selection register 1 (SSR1: \$027).
  - $V_{CC} = 4.5$  to  $5.5\text{V}$
  - The oscillation stabilization time is the period required for the oscillator to stabilize in the following situations:
    - After  $V_{CC}$  reaches 2.7 V at power-on.
    - After RESET input goes low when stop mode is cancelled.
    - After STOPC input goes low when stop mode is cancelled.

To ensure the oscillation stabilization time at power-on or when stop mode is cancelled, RESET or STOPC must be input for at least a duration of  $t_{RC}$ .

When using a crystal or ceramic oscillator, consult with the manufacturer to determine what stabilization time is required, since it will depend on the circuit constants and stray capacitance.
  - Refer to figure 84.
  - Refer to figure 85.
  - Refer to figure 86.
  - Refer to figure 87.
  - Applies to the HD40A4364, HD40A4368, HD40A43612, and HD40A4369.
  - Applies to the HD407A4369.

## HD404369 Series

**Serial Interface Timing Characteristics (HD407A4369:  $V_{CC} = 2.7$  to  $5.5$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ ; HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/HD40A43612/HD40A4369:  $V_{CC} = 2.7$  to  $6.0$  V,  $GND = 0$  V,  $T_a = -20$  to  $+75^\circ\text{C}$ , unless otherwise specified)**

### During Transmit Clock Output

| Item                          | Symbol        | Pins             | Min | Typ | Max | Unit          | Test Condition          | Note |
|-------------------------------|---------------|------------------|-----|-----|-----|---------------|-------------------------|------|
| Transmit clock cycle time     | $t_{S_{cyc}}$ | $\overline{SCK}$ | 1   | —   | —   | $t_{cyc}$     | Load shown in figure 89 | 1    |
| Transmit clock high width     | $t_{SCKH}$    | $\overline{SCK}$ | 0.4 | —   | —   | $t_{S_{cyc}}$ | Load shown in figure 89 | 1    |
| Transmit clock low width      | $t_{SCKL}$    | $\overline{SCK}$ | 0.4 | —   | —   | $t_{S_{cyc}}$ | Load shown in figure 89 | 1    |
| Transmit clock rise time      | $t_{SCKr}$    | $\overline{SCK}$ | —   | —   | 80  | ns            | Load shown in figure 89 | 1    |
| Transmit clock fall time      | $t_{SCKf}$    | $\overline{SCK}$ | —   | —   | 80  | ns            | Load shown in figure 89 | 1    |
| Serial output data delay time | $t_{DSO}$     | SO               | —   | —   | 300 | ns            | Load shown in figure 89 | 1    |
| Serial input data setup time  | $t_{SSI}$     | SI               | 100 | —   | —   | ns            |                         | 1    |
| Serial input data hold time   | $t_{HSI}$     | SI               | 200 | —   | —   | ns            |                         | 1    |

### During Transmit Clock Input

| Item                          | Symbol        | Pins             | Min | Typ | Max | Unit          | Test Condition          | Note |
|-------------------------------|---------------|------------------|-----|-----|-----|---------------|-------------------------|------|
| Transmit clock cycle time     | $t_{S_{cyc}}$ | $\overline{SCK}$ | 1   | —   | —   | $t_{cyc}$     |                         | 1    |
| Transmit clock high width     | $t_{SCKH}$    | $\overline{SCK}$ | 0.4 | —   | —   | $t_{S_{cyc}}$ |                         | 1    |
| Transmit clock low width      | $t_{SCKL}$    | $\overline{SCK}$ | 0.4 | —   | —   | $t_{S_{cyc}}$ |                         | 1    |
| Transmit clock rise time      | $t_{SCKr}$    | $\overline{SCK}$ | —   | —   | 80  | ns            |                         | 1    |
| Transmit clock fall time      | $t_{SCKf}$    | $\overline{SCK}$ | —   | —   | 80  | ns            |                         | 1    |
| Serial output data delay time | $t_{DSO}$     | SO               | —   | —   | 300 | ns            | Load shown in figure 89 | 1    |
| Serial input data setup time  | $t_{SSI}$     | SI               | 100 | —   | —   | ns            |                         | 1    |
| Serial input data hold time   | $t_{HSI}$     | SI               | 200 | —   | —   | ns            |                         | 1    |

Note: 1. Refer to figure 88.

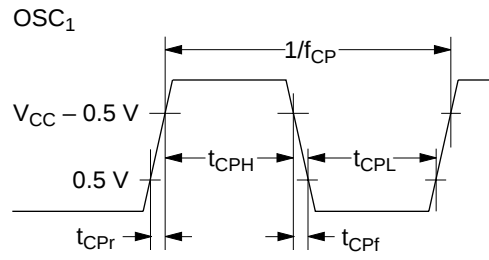


Figure 84 External Clock Timing

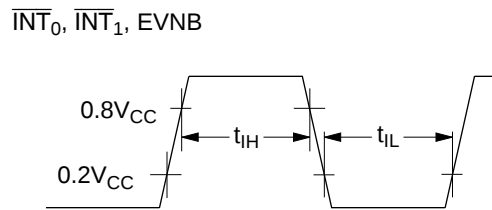


Figure 85 Interrupt Timing

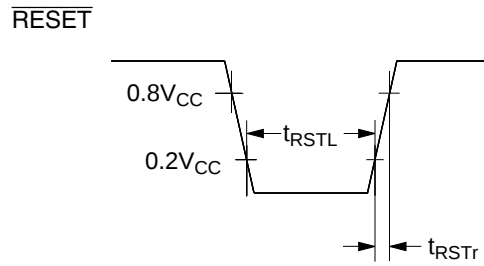


Figure 86  $\overline{RESET}$  Timing

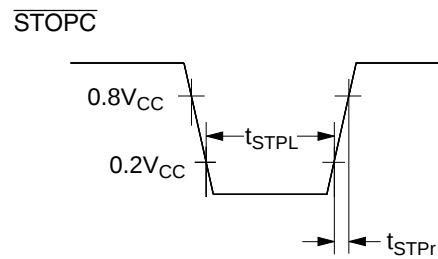
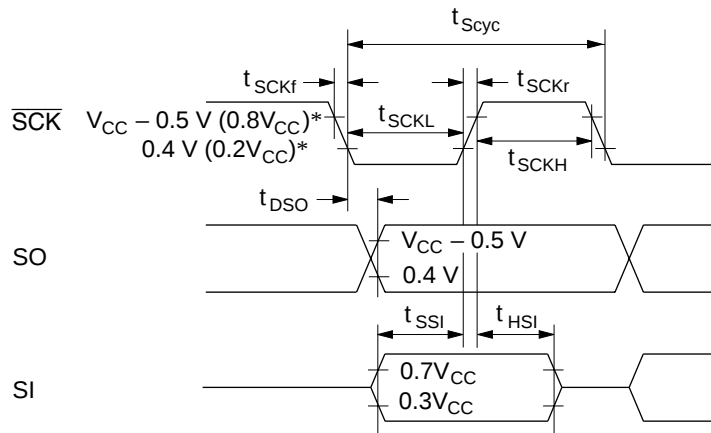


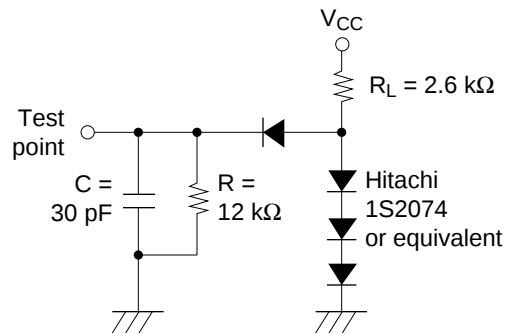
Figure 87  $\overline{STOPC}$  Timing

## HD404369 Series



Note: \*  $V_{\text{CC}} - 0.5 \text{ V}$  and  $0.4 \text{ V}$  are the threshold voltages for transmit clock output, and  $0.8V_{\text{CC}}$  and  $0.2V_{\text{CC}}$  are the threshold voltages for transmit clock input.

**Figure 88 Serial Interface Timing**



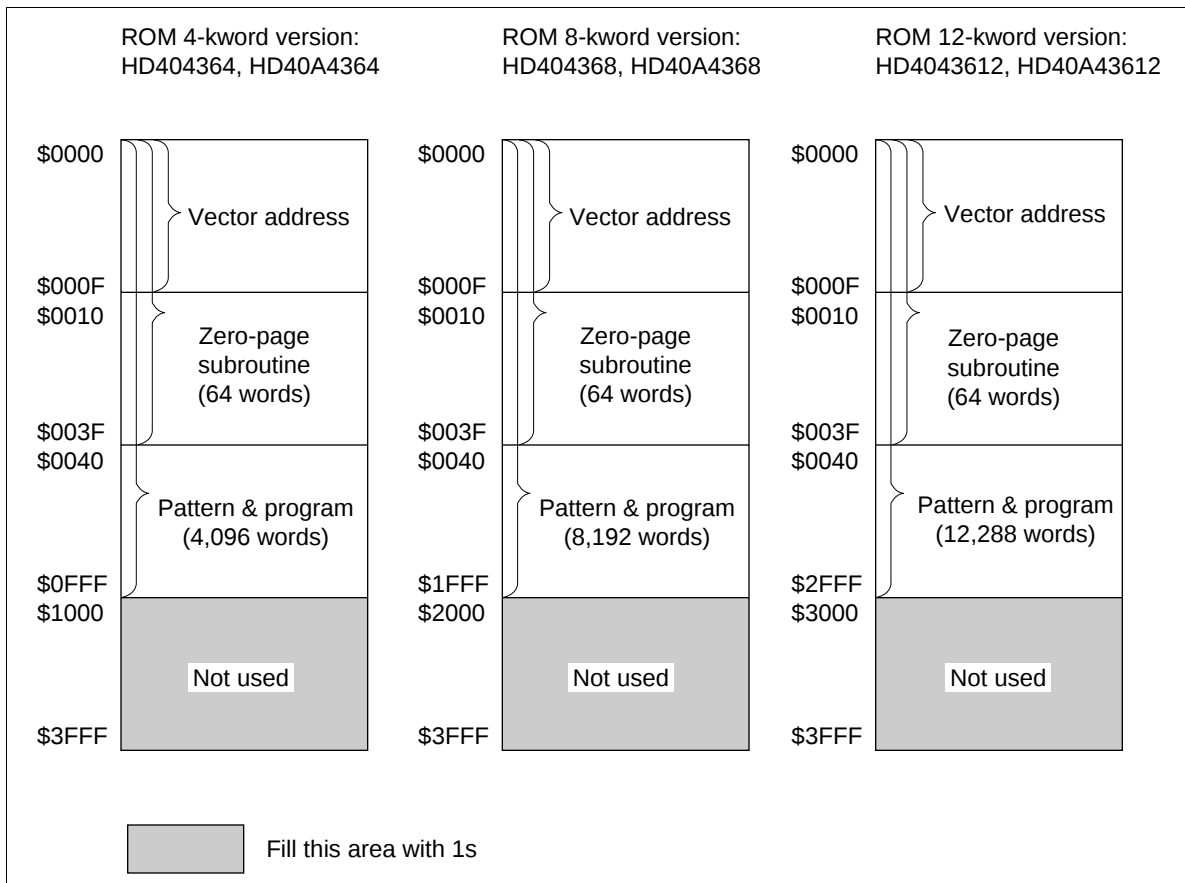
**Figure 89 Timing Load Circuit**

## Notes on ROM Out

Please pay attention to the following items regarding ROM out.

On ROM out, fill the ROM area indicated below with 1s to create the same data size for the HD404364, HD40A4364, HD404368, HD40A4368, HD4043612 and HD40A43612 as a 16-kword version (HD404369, HD40A4369). The 16-kword data sizes are required to change ROM data to mask manufacturing data since the program used is for a 16-kword version.

This limitation applies when using an EPROM or a data base.



---

## HD404369 Series

---

### HD404364/HD404368/HD4043612/HD404369/HD40A4364/HD40A4368/ HD40A43612/HD40A4369 Option List

Please check off the appropriate applications and enter the necessary information.

#### 1. ROM size

|                                            |            |          |
|--------------------------------------------|------------|----------|
| <input type="checkbox"/> 5 MHz operation   | HD404364   | 4-kword  |
| <input type="checkbox"/> 8.5 MHz operation | HD40A4364  |          |
| <input type="checkbox"/> 5 MHz operation   | HD404368   | 8-kword  |
| <input type="checkbox"/> 8.5 MHz operation | HD40A4368  |          |
| <input type="checkbox"/> 5 MHz operation   | HD4043612  | 12-kword |
| <input type="checkbox"/> 8.5 MHz operation | HD40A43612 |          |
| <input type="checkbox"/> 5 MHz operation   | HD404369   | 16-kword |
| <input type="checkbox"/> 8.5 MHz operation | HD40A4369  |          |

|               |  |
|---------------|--|
| Date of order |  |
| Customer      |  |
| Department    |  |
| Name          |  |
| ROM code name |  |
| LSI number    |  |

#### 2. Optional Functions

|                                                                                 |
|---------------------------------------------------------------------------------|
| <input type="checkbox"/> With 32-kHz CPU operation, with time base for clock    |
| <input type="checkbox"/> Without 32-kHz CPU operation, with time base for clock |
| <input type="checkbox"/> Without 32-kHz CPU operation, without time base        |

Note: \* Options marked with an asterisk require a subsystem crystal oscillator (X1, X2).

#### 3. ROM Code Media

Please specify the first type below (the upper bits and lower bits are mixed together), when using the EPROM on-package microcomputer type (including ZTAT™ version).

|                                                                                                                                                                                                    |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <input type="checkbox"/> EPROM: The upper bits and lower bits are mixed together. The upper five bits and lower five bits are programmed to the same EPROM in alternating order (i.e., LULULU...). |
| <input type="checkbox"/> EPROM: The upper bits and lower bits are separated. The upper five bits and lower five bits are programmed to different EPROMS.                                           |

#### 4. System Oscillator (OSC1, OSC2)

|                                             |     |     |
|---------------------------------------------|-----|-----|
| <input type="checkbox"/> Ceramic oscillator | f = | MHz |
| <input type="checkbox"/> Crystal oscillator | f = | MHz |
| <input type="checkbox"/> External clock     | f = | MHz |

#### 5. Stop mode

|                                   |
|-----------------------------------|
| <input type="checkbox"/> Used     |
| <input type="checkbox"/> Not used |

#### 6. Package

|                                 |
|---------------------------------|
| <input type="checkbox"/> DP-64S |
| <input type="checkbox"/> FP-64B |
| <input type="checkbox"/> FP-64A |

## **Cautions**

1. Hitachi neither warrants nor grants licenses of any rights of Hitachi's or any third party's patent, copyright, trademark, or other intellectual property rights for information contained in this document. Hitachi bears no responsibility for problems that may arise with third party's rights, including intellectual property rights, in connection with use of the information contained in this document.
  2. Products and product specifications may be subject to change without notice. Confirm that you have received the latest product standards or specifications before final design, purchase or use.
  3. Hitachi makes every attempt to ensure that its products are of high quality and reliability. However, contact Hitachi's sales office before using the product in an application that demands especially high quality and reliability or where its failure or malfunction may directly threaten human life or cause risk of bodily injury, such as aerospace, aeronautics, nuclear power, combustion control, transportation, traffic, safety equipment or medical equipment for life support.
  4. Design your application so that the product is used within the ranges guaranteed by Hitachi particularly for maximum rating, operating supply voltage range, heat radiation characteristics, installation conditions and other characteristics. Hitachi bears no responsibility for failure or damage when used beyond the guaranteed ranges. Even within the guaranteed ranges, consider normally foreseeable failure rates or failure modes in semiconductor devices and employ systemic measures such as fail-safes, so that the equipment incorporating Hitachi product does not cause bodily injury, fire or other consequential damage due to operation of the Hitachi product.
  5. This product is not designed to be radiation resistant.
  6. No one is permitted to reproduce or duplicate, in any form, the whole or part of this document without written approval from Hitachi.
  7. Contact Hitachi's sales office for any questions regarding this document or Hitachi semiconductor products.
- 
-