# Slim Proximity Sensor

# Slim Model of Width 12 mm.

• Ideal for side-by-side mounting.





Be sure to read Safety Precautions on page 5.

# **Ordering Information**

Appearance	Sensing distance	Output specifications		Model Output configuration	
					NC
Shielded		DC 3-wire models	NPN	TL-T2E1	TL-T2E2
	2 mm	DC 3-wire models	PNP	TL-T2F1	
		AC 2-wire models		TL-T2Y1	TL-T2Y2
_ <u></u>		DC 3-wire models	NPN	TL-T5ME1	TL-T5ME2
Unshielded	5 mm	AC 2-wire models		TL-T5MY1	TL-T5MY2

Note: Models with a different frequency are available. The model numbers are TL-T $\square\square\square$ 5. (e.g., TL-T2E15).

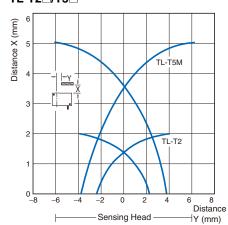
# **Ratings and Specifications**

	Model	TL-T2E1 TL-T2E2	TL-T2Y1 TL-T2Y2	TL-T5ME1 TL-T5ME2	TL-T5MY1 TL-T5MY2	
Item		TL-T2F1				
Sensing distance 2 mm±10%				5 mm±10%		
Setting d		0 to 1.6 mm		0 to 4 mm		
Differenti	ial travel	10% max. of sensing dista				
Sensing	object	Ferrous metal (The sensing distance decreases with non-ferrous metal. Refer to <i>Engineering</i> page 3.)				
Standard	l sensing object	$ lron 12 \times 12 \times 1 mm                         $				
Respons	e frequency	E and F models: 800 Hz, Y models: 20 Hz	· ·		E models: 250 Hz, Y models: 20 Hz	
Supply v	oltage	E and F models: 12 to 24	VDC (10 to 30 VDC), ripp	le (p-p): 20% max.		
(operatin	g voltage range)	Y models: 100 to 2	20 VAC (90 to 250 VAC) 5	50/60 Hz		
Current of	consumption	E and F models: 15 mA m	nax. at 24 VDC			
Leakage	current	Y models: 2.5 mA max. a	t 200 VAC			
	Switching	E and F models: 100 mA	max. at 12 VDC, 200 mA	max. at 24 VDC		
Control	capacity	Y models: 10 to 20	0 mA			
output	Residual	E and F models: 1.0 V max. with a load current of 100 mA and cord length of 2 m				
	voltage Y models: Refer to Residual Voltage (Typical) on page 3.					
Indicator	'S	Detection indicator (red)				
Operation (with sen proachin	sing object ap-	E1 models: NO E2 models: NC F1 models: NO Refer to I/O Circuit Diagrams Timing Chart on page 4. Y1 models: NO Y2 models: NC				
Circuit p	rotection	E models: Reverse connection protection and surge absorber Y models: Surge absorber				
Ambient	temperature	Operating/Storage: -25°C	to 70°C (with no icing or	condensation)		
Ambient	humidity	Operating/Storage: 35% t	o 95% (with no condensat	ion)		
Tempera	ture influence	$\pm 10\%$ max. of sensing distance at 23% in the temperature range of –25 to 70°C				
Voltage influence		E and F models: $\pm 2.5\%$ max. of sensing distance within a range of $\pm 15\%$ of the rated power supply voltage Y models: $\pm 2.5\%$ max. of sensing distance within a range of $\pm 10\%$ of the rated power supply voltage				
Insulation	n resistance	50 M $\Omega$ min. (at 500 VDC) between case and current-carrying parts				
Dielectric strength		E and F models: 1,000 VAC, 50/60 Hz for 1 min between case and current-carrying parts Y models: 2,000 VAC, 50/60 Hz for 1 min between case and current-carrying parts				
Vibration resistance (destruction)		10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions				
Shock resistance (destruction)		500 m/s² for 10 times each in X, Y, and Z directions				
Degree of protection		IEC IP67, in-house standard for oil-resistance				
Connection method		Pre-wired Models (Standard cable length: 2 m)				
Weight (p	packed state)	Approx. 70 g				
Material	Case Sensing surface	Heat-resistant ABS resin				
Accessor	ries	Instruction sheet				

# **Engineering Data (Typical)**

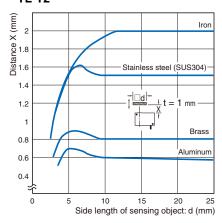
# **Operating Range**

# TL-T2□/T5□

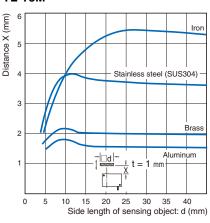


# **Sensing Object Size and Material Influence**

TL-T2

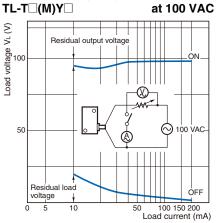


# TL-T5M

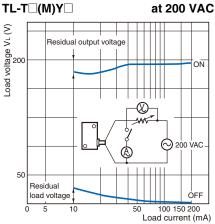


# **Residual Voltage (Typical)**

 $TL-T\square(M)Y\square$ 

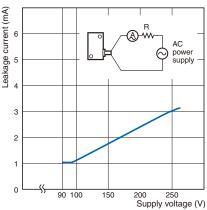


TL-T□(M)Y□



**Leakage Current (Typical)** 

# $\mathsf{TL}\text{-}\mathsf{T}\square\mathsf{Y}$



# I/O Circuit Diagrams

# **DC 3-wire Models**

Operation mode	Output specifications	Models	Timing charts	Output circuits
NO	TL-T2E1 TL-T5ME1		Sensing object Present Not present Load (between brown and black) Reset  Output voltage (between black and blue)  Detection ON indicator (red) OFF	Brown +V  Proximity Sensor  Black 1
NC	- NPN	TL-T2E2 TL-T5ME2	Sensing object Not present Not present Load (between brown and black) Output voltage (between black and blue) Detection indicator (red) OFF	*1. 200 mA (load current) *2. When a transistor is connected
NO	PNP	TL-T2F1	Sensing object Present Not present Load (between brown and black) Output voltage (between black and blue) Detection indicator (red) OVER PRESENT OPERATOR NOT PRESENT OPERATOR	Brown  Proximity Sensor main circuit  4.7 kΩ  *1. 200 mA (load current)  *2. When a transistor is connected

# **AC 2-wire Models**

Operation mode	Models	Timing charts	Output circuits
NO	TL-T2Y1 TL-T5MY1	Sensing object Present Not present  Load Operate Reset  Detection indicator ON (red) OFF	Proximity Sensor main
NC	TL-T2Y2 TL-T5MY2	Sensing object Present Not present  Operate Reset  Detection indicator ON (red) OFF	main Blue

# **Safety Precautions**

# $\triangle$

# WARNING

This product is not designed or rated for ensuring safety of persons.

Do not use it for such purposes.



- Do not short the load. Explosion or burning may result.
- Do not supply power to the Sensor with no load connected, otherwise internal parts may be damaged or burnt.



Applicable Models: AC 2-wire Models

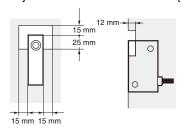
# **Precautions for Correct Use**

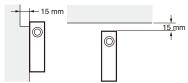
Do not use this product under ambient conditions that exceed the ratings.

# Design

# **Effect of Surrounding Metals**

 Be sure to separate the Sensor from surrounding metal objects as shown in the following illustration.



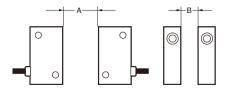


• The TL-T2 will not be influenced by metal when it is embedded in metal.



### **Mutual Interference**

When two or more Sensors are mounted face-to-face or sideby-side, separate them as shown below. The table below indicates the minimum distances A and B.



### **Mutual Interference**

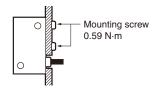
(Unit: mm)

Distance Model	Α	В
TL-T2	40 (10)	12 (0)
TL-T5	120 (60)	80 (40)

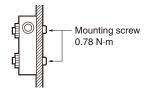
Note: Figures in parentheses will apply if the Sensors in use are different from each other in response frequency.

# Mounting

• At the time of rear mounting, be sure that the tightening torque does not exceed 0.59 N·m.



• At the time of side mounting, be sure that the tightening torque does not exceed 0.78 N·m.



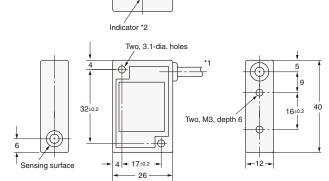
(Unit: mm)

# Unless otherwise specified, the tolerance class IT16 is used for dimensions in this data sheet.

# Dimensions

TL-T





- \*1. DC-switching model: 4.0-dia. vinyl-insulated round cable with 3 conductors (Conductor cross section: 0.2 mm², Insulator diameter: 1.2 mm), Standard length: 2 m AC-switching model: 4.0-dia. vinyl-insulated round cable with 2 conductors (Conductor cross section: 0.3 mm², Insulator diameter: 1.3 mm), Standard length: 2 m
- \*2. Detection indicator (red)

In the interest of product improvement, specifications are subject to change without notice.

# **General Precautions**

For precautions on individual products, refer to the Safety Precautions in individual product information.



These products cannot be used in safety devices for presses or other safety devices used to protect human life.



These products are designed for use in applications for sensing workpieces and workers that do not affect safety.

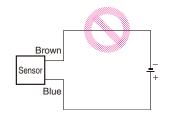
# **Precautions for Safe Use**

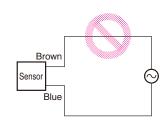
To ensure safety, always observe the following precautions.

#### Wiring Considerations **Typical examples** DC 3-Wire NPN Output Sensors DC 2-Wire Sensors **Power Supply Voltage** Do not use a voltage that exceeds the operat-Load ing voltage range. Applying a voltage that is higher than the operating voltage range, or us-Brown ing an AC power supply (100 VAC or higher) for a Sensor that requires a DC power supply may cause explosion or burning. Blue -Blue DC 3-Wire NPN Output Sensors DC 2-Wire Sensors Load short-circuiting • Even with the load short-circuit protection • Do not short-circuit the load. Explosion or function, protection will not be provided when burning may result. a load short circuit occurs if the power supply • The load short-circuit protection function oppolarity is not correct. erates when the power supply is connected with the correct polarity and the power is Load within the rated voltage range. (Load short circuit) Load Brown (I gad short Black DC 3-Wire NPN Output Sensors **Incorrect Wiring** Be sure that the power supply polarity and oth-Load er wiring is correct. Incorrect wiring may cause explosion or burning. Brown Brown Load Blue Black Blue DC 2-Wire Sensors AC 2-Wire Sensors Connection without a Load • Even with the load short-circuit protection

If the power supply is connected directly without a load, the internal elements may explode or burn. Be sure to insert a load when connecting the power supply.

function, protection will not be provided if both the power supply polarity is incorrect and no load is connected.





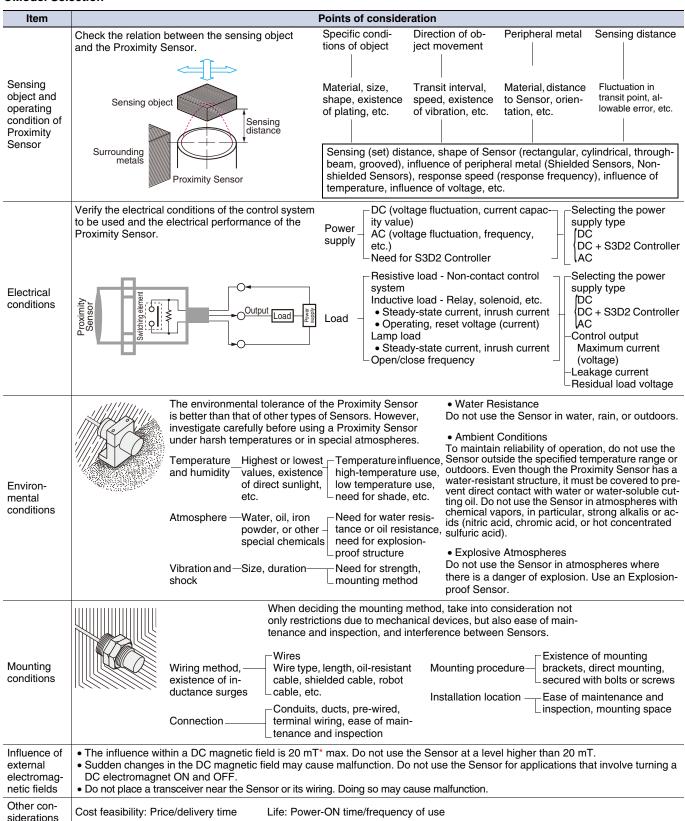
# Operating Environment

Do not use the Sensor in an environment where there are explosive or combustible gases.

# **Precautions for Correct Use**

The following conditions must be considered to understand the conditions of the application and location as well as the relation to control equipment.

### •Model Selection



<sup>\*</sup>mT (millitesla) is a unit for expressing magnetic flux density. One tesla is the equivalent of 10,000 gauss.

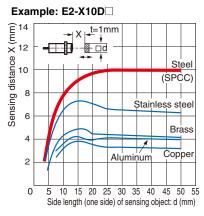
http://www.ia.omron.com/

# ●Design

### **Sensing Object Material**

The sensing distance varies greatly depending on the material of the sensing object. Study the engineering data for the influence of sensing object material and size and select a distance with sufficient leeway.

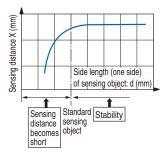
 In general, if the sensing object is a nonmagnetic metal (for example, aluminum), the sensing distance decreases.



## **Size of Sensing Object**

In general, if the object is smaller than the standard sensing object, the sensing distance decreases.

- Design the setup for an object size that is the same or greater than the standard sensing object size from the graphs showing the sensing object size and sensing distance.
- When the size of the standard sensing object is the same or less than the size of the standard sensing object, select a sensing distance with sufficient leeway.

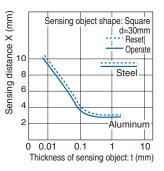


# **Thickness of Sensing Object**

- The thickness of ferrous metals (iron, nickel, etc.) must be 1 mm or greater.
- For non-magnetic metal, a sensing distance equivalent to a magnetic body can be obtained when the coating thickness is 0.01 mm or less. With pulse-response models (e.g., E2V), however, the characteristics may vary. Be sure to check the catalog information for the relevant model.

  When the coating is extremely

When the coating is extremely thin and is not conductive, such as a vacuum deposited film, detection is not possible.



 Influence of Plating If the sensing object is plated, the sensing distance will change (see the table below).

Effect of Plating (Typical)

(Reference values: Percent of non-plated sensing distance)

Thickness and base material of plating	Steel	Brass
No plating	100	100
Zn 5 to 15 μm	90 to 120	95 to 105
Cd 5 to 15 μm	100 to 110	95 to 105
Ag 5 to 15 μm	60 to 90	85 to 100
Cu 10 to 20 μm	70 to 95	95 to 105
Cu 5 to 15 μm	-	95 to 105
Cu (5 to 10 $\mu$ m) + Ni (10 to 20 $\mu$ m)	70 to 95	-
Cu (5 to 10 $\mu\text{m})$ + Ni (10 $\mu\text{m})$ + Cr (0.3 $\mu\text{m})$	75 to 95	-

# **Mutual Interference**

- Mutual interference refers to a state where a Sensor is affected by magnetism (or static capacitance) from an adjacent Sensor and the output is unstable.
- One means of avoiding interference when mounting Proximity Sensors close together is to alternate Sensors with different frequencies. The model tables indicate whether different frequencies are available. Please refer to the tables.
- When Proximity Sensors with the same frequency are mounted together in a line or face-to-face, they must be separated by a minimum distance. For details, refer to *Mutual Interference* in the *Safety Precautions* for individual Sensors.

# **Power Reset Time**

A Sensor is ready for detection within 100 ms after turning ON the power. If the load and Sensor are connected to separate power supplies, design the system so that the Sensor power turns ON first.

# **Turning OFF the Power**

An output pulse may be generated when the power is turned OFF, so design the system so that the load or load line power turns OFF first.

# **Influence of Surrounding Metal**

The existence of a metal object other than the sensing object near the sensing surface of the Proximity Sensor will affect detection performance, increase the apparent operating distance, degrade temperature characteristics, and cause reset failures. For details, refer to the influence of surrounding metal table in *Safety Precautions* for individual Sensors.

The values in the table are for the nuts provided with the Sensors. Changing the nut material will change the influence of the surrounding metal.

### **Power Transformers**

Be sure to use an insulated transformer for a DC power supply. Do not use an auto-transformer (single-coil transformer).

# Precautions for AC 2-Wire/DC 2-Wire Sensors

# **Surge Protection**

Although the Proximity Sensor has a surge absorption circuit, if there is a device (motor, welder, etc.) that causes large surges near the Proximity Sensor, insert a surge absorber near the source of the surges.

# **Influence of Leakage Current**

Even when the Proximity Sensor is OFF, a small amount of current runs through the circuit as leakage current.

For this reason, a small current may remain in the load (residual voltage in the load) and cause load reset failures. Verify that this voltage is lower than the load reset voltage (the leakage current is less than the load reset current) before using the Sensor.

# Using an Electronic Device as the Load for an AC 2-Wire Sensor

When using an electronic device, such as a Timer, some types of devices use AC half-wave rectification. When a Proximity Sensor is connected to a device using AC half-wave rectification, only AC half-wave power will be supplied to the Sensor. This will cause the Sensor operation to be unstable. Also, do not use a Proximity Sensor to turn the power supply ON and OFF for electronic devices that use DC half-wave rectification. In such a case, use a relay to turn the power supply ON and OFF, and check the system for operating stability after connecting it.

Examples of Timers that Use AC Half-wave Rectification Timers: H3Y, H3YN, H3RN, H3CA-8, RD2P, and H3CR (-A, -A8, -AP, -F, -G)

# **Countermeasures for Leakage Current (Examples)**

### **AC 2-Wire Sensors**

Connect a bleeder resistor to bypass the leakage current flowing in the load so that the current flowing through the load is less than the load reset current.

When using an AC 2-Wire Sensor, connect a bleeder resistor so that the Proximity Sensor current is at least 10 mA, and the residual load voltage when the Proximity Sensor is OFF is less than the load reset voltage.



Calculate the bleeder resistance and allowable power using the following equation.

$$R \le \frac{Vs}{10 - l} (k\Omega)$$
  $P > \frac{Vs^2}{R} (mW)$ 

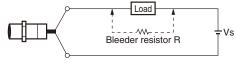
P : Watts of bleeder resistance (the actual number of watts used should be several times this number)

I : Load current (mA)

It is recommend that leeway be included in the actual values used. For 100 VAC, use 10 k $\Omega$  or less and 3 W (5 W) or higher, and for 200 VAC, use 20 k $\Omega$  or less and 10 W (20 W) or higher. If the effects of heat generation are a problem, use the number of watts in parentheses ( ) or higher.

### **DC 2-Wire Sensors**

Connect a bleeder resistor to bypass the leakage current flowing in the load, and design the load current so that (leakage current)  $\times$  (load input impedance) < reset voltage.



Calculate the bleeder resistance and allowable power using the following equation.

$$R \le \frac{Vs}{I_{R} - I_{OFFR}} (k\Omega)$$
  $P > \frac{Vs^{2}}{R} (mW)$ 

P : Watts of bleeder resistance (the actual number of watts used should be several times this number)

in : Leakage current of Proximity Sensor (mA)

ioff: Load reset current (mA)

It is recommend that leeway be included in the actual values used. For 12 VDC, use 15 k $\Omega$  or less and 450 mW or higher, and for 24 VDC, use 30 k $\Omega$  or less and 0.1 W or higher.

# **Loads with Large Inrush Current**

Loads, such as lamps or motors, that cause a large inrush current\* will weaken or damage the switching element. In this situation, use a relay.

\* E2K, TL-N□Y: 1 A or higher

# Mounting

# **Mounting the Sensor**

When mounting a Sensor, do not tap it with a hammer or otherwise subject it to excessive shock. This will weaken water resistance and may damage the Sensor. If the Sensor is being secured with bolts, observe the allowable tightening torque. Some models require the use of toothed washers.

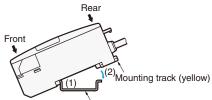
For details, refer to the mounting precautions in *Precautions for Correct Use* in individual product information.

# Mounting/Removing Using DIN Track

# (Example for E2CY)

# <Mounting>

- (1)Insert the front of the Sensor into the special Mounting Bracket (included) or DIN Track.
- (2)Press the rear of the Sensor into the special Mounting Bracket or DIN Track.



DIN Track (or Mounting Bracket)

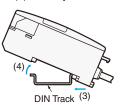
 When mounting the side of the Sensor using the special Mounting Bracket, first secure the Amplifier Unit to the special Mounting Bracket, and then mount the special Mounting Bracket with M3 screws and flat washers with a diameter of 6 mm maximum.



Flat washers (6 dia. max.)

### <Removing>

 While pressing the Amplifier Unit in the direction of (3), lift the fiber plug in the direction of (4) for easy removal without a screwdriver.



### **Set Distance**

The sensing distance may vary due to fluctuations in temperature and voltage. When mounting the Sensor, it is recommend that installation be based on the set distance.

# Wiring Considerations

# **AND/OR Connections for Proximity Sensors**

Model	Type of connection	Connection	Description
DC 2-Wire	AND (series connection)	Vs Vs	Keep the number of connected Sensors (N) within the range of the following equation.  Vs - N × Vn ≥ Operating load voltage  N: Number of Sensors that can be connected Vn: Residual output voltage of Proximity Sensor Vs: Power voltage  It is possible, however, that the indicators may not light correctly and error pulses (of approximately 1 ms) may be generated because the rated power supply voltage and current are not supplied to individual Proximity Sensors. Verify that this is not a problem before operation.
	OR (parallel connection)	Vs Vs	Keep the number of connected Sensors (N) within the range of the following equation.  N × i ≤ Load reset current  N: Number of Sensors that can be connected i: Leakage current of Proximity Sensor  Example: When an MY (24-VDC) Relay is used as the load, the maximum number of Sensors that can be connected is 4.
AC 2-wire	AND (series connection)	Vs Vs Vs Vs Vs Vs Vs Vs ≥ 100V	<tl-ny, e2k-□my□,="" tl-my,="" tl-t□y=""> The above Proximity Sensors cannot be used in a series connection. If needed, connect through relays. <e2e-x□y> For the above Proximity Sensors, the voltage VL that can be applied to the load when ON is VL = Vs - (Output residual voltage × Number of Sensors), for both 100 VAC and 200 VAC. The load will not operate unless VL is higher than the load operating voltage. This must be verified before use. When using two or more Sensors in series with an AND circuit, the limit is three Sensors. (Be careful of the VS value in the diagram at left.)</e2e-x□y></tl-ny,>
	OR (parallel connection)	(A) Load Alddris Jawod QV (A) (A) (B) (A) (A) (A) (A) (A) (A) (A) (A) (A) (A	In general it is not possible to use two or more Proximity Sensors in parallel with an OR circuit.  A parallel connection can be used if A and B will not be operated simultaneously and there is no need to hold the load. The leakage current, however, will be n times the value for each Sensor and reset failures will frequently occur.  ("n" is the number of Proximity Sensors.)  If A and B will be operated simultaneously and the load is held, a parallel connection is not possible.  If A and B operate simultaneously and the load is held, the voltages of both A and B will fall to about 10 V when A turns ON, and the load current will flow through A causing random operation. When the sensing object approaches B, the voltage of both terminals of B is too low at 10 V and the switching element of B will not operate. When A turns OFF again, the voltages of both A and B rise to the power supply voltage and B is finally able to turn ON.  During this period, there are times when A and B both turn OFF (approximately 10 ms) and the loads are momentarily restored. In cases where the load is to be held in this way, use a relay as shown in the diagram at left.

Note: When AND/OR connections are used with Proximity Sensors, the effects of erroneous pulses or leakage current may prevent use. Verify that there are no problems before use.

Model	Type of connection	Connection	Description
DC 3-wire	AND (series connection)	(A) + OUT iL Load Vs	Keep the number of connected Sensors (N) within the range of the following equation. $ \begin{aligned} & \text{iL} + (N-1) \times \text{i} \leq \text{Upper limit of Proximity Sensor control output} \\ & \text{Vs - N} \times \text{Vr} \geq \text{Operating load voltage} \end{aligned} $ Now the sumber of Sensors that can be connected $ \begin{aligned} & \text{NR: Residual output voltage of Sensor} \\ & \text{VR: Residual output voltage of Sensor} \\ & \text{VS: Power supply voltage} \\ & \text{i : Current consumption of Sensor} \\ & \text{iL: Load current} \end{aligned} $ Note: When an AND circuit is connected, the operation of Proximity Sensor B causes power to be supplied to Proximity Sensor A, and thus erroneous pulses (approximately 1 ms) may be generated in A when the power is turned ON. For this reason, take care when the load has a high response speed because malfunction may result. \end{aligned}
	OR (parallel connection)	Vs	For Sensors with a current output, a minimum of three OR connections is possible. Whether or not four or more connections is possible depends on the model.

Note: When AND/OR connections are used with Proximity Sensors, the effects of erroneous pulses or leakage current may prevent use. Verify that there are no problems before use.

## **Extending Cable Length**

The cable of a Built-in Amplifier Sensor can be extended to a maximum length of 200 m with each of the standard cables (excluding some models).

For Separate Amplifier Sensors (E2C-EDA, E2C, E2J, E2CY), refer to the specific precautions for individual products.

# **Bending the Cable**

If you need to bend the cable, we recommend a bend radius that is at least 3 times the outer diameter of the cable (with the exception of coaxial and shielded cables).

# **Cable Tensile Strength**

In general, do not subject the cable to a tension greater than that indicated in the following table.

Cable diameter	Tensile strength
Less than 4 mm	30 N max.
4 mm min.	50 N max.

Note: Do not subject a shielded cable or coaxial cable to tension.

# **Separating High-voltage Lines**

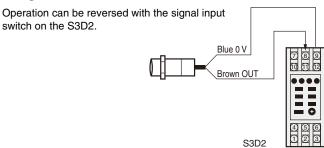
Using Metal Conduits

If a power line is to be located near the Proximity Sensor cable, use a separate metal conduit to prevent malfunction or damage. (Same for DC models.)

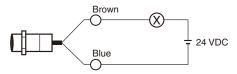
# **Example of Connection with S3D2 Sensor Controller**

# DC 2-Wire Sensors

# **Using the S3D2 Sensor Controller**



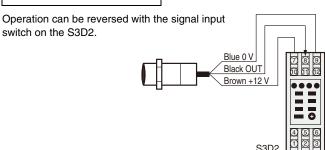
# **Connecting to a Relay Load**



Note: DC 2-Wire Sensors have a residual voltage of 3 V. Check the operating voltage of the relay before use.

The residual voltage of the E2E-XD-M1J-T is 5 V.





# ●Operating Environment

### **Water Resistance**

Do not use the Sensor in water, rain, or outdoors.

### **Ambient Conditions**

Do not use the Sensor in the following environments.

Doing so may cause malfunction or failure of the Sensor.

- To maintain operational reliability and service life, use the Sensor only within the specified temperature range and do not use it outdoors.
- The Sensor has a water resistant structure, however, attaching a cover to prevent direct contact with water will help improve reliability and prolong product life.
- Avoid using the Sensor where there are chemical vapors, especially strong alkalis or acids (nitric acid, chromic acid, or hot concentrated sulfuric acid).

### •Maintenance and inspection

### **Periodic Inspection**

To ensure long-term stable operation of the Proximity Sensor, inspect for the following on a regular basis. Conduct these inspections also for control devices.

- Shifting, loosening, or deformation of the sensing object and Proximity Sensor mounting
- Loosening, bad contact, or wire breakage in the wiring and connections
- 3. Adherence or accumulation of metal powder
- 4. Abnormal operating temperature or ambient conditions
- 5. Abnormal indicator flashing (on setting indicator types)

# **Disassembly and Repair**

Do not under any circumstances attempt to disassemble or repair the product.

# **Quick Failure Check**

You can conveniently check for failures by connecting the E39-VA Handy Checker to check the operation of the Sensor.



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### Read and Understand This Catalog

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments

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