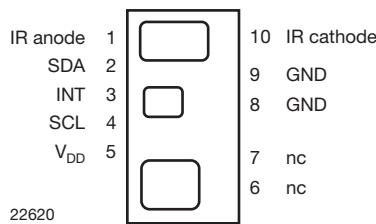
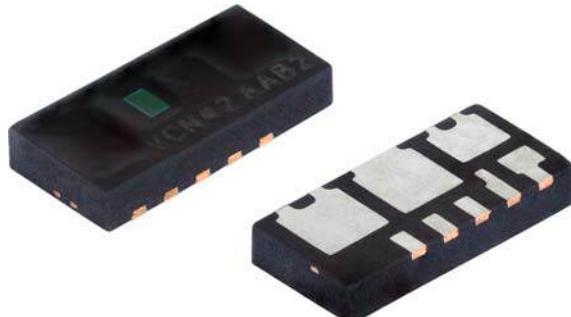


Fully Integrated Proximity and Ambient Light Sensor With Infrared Emitter, I²C Interface, and Interrupt Function



DESCRIPTION

The VCNL4020 is a fully integrated proximity and ambient light sensor. Fully integrated means that the infrared emitter is included in the package. It has 16 bit resolution. It includes a signal processing IC and features standard I²C communication interface. It features an interrupt function.

APPLICATIONS

- Proximity sensor for mobile devices (e.g. smart phones, touch phones, PDA, GPS) for touch screen locking, power saving, etc.
- Integrated ambient light function for display/keypad contrast control and dimming of mobile devices
- Proximity / optical switch for consumer, computing and industrial devices and displays
- Dimming control for consumer, computing and industrial displays

FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 4.90 x 2.40 x 0.83
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS-PD), proximity sensor (PD), and signal conditioning IC
- Interrupt function
- Supply voltage range V_{DD}: 2.5 V to 3.6 V
- Supply voltage range IR anode: 2.5 V to 5 V
- Communication via I²C interface
- I²C bus H-level range: 1.7 V to 5 V
- Floor life: 72 h, MSL 4, according to J-STD-020
- Low stand by current consumption: 1.5 μ A
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912



RoHS
COMPLIANT
HALOGEN
FREE
GREEN
(5-2008)

PROXIMITY FUNCTION

- Built-in infrared emitter and photo-pin-diode for proximity function
- 16 bit effective resolution for proximity detection range ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA in 10 mA steps
- Excellent ambient light suppression by signal modulation
- Proximity distance up to 200 mm

AMBIENT LIGHT FUNCTION

- Built-in ambient light photo-pin-diode with close-to-human-eye sensitivity
- 16 bit dynamic range from 0.25 lx to 16 klx
- 100 Hz and 120 Hz flicker noise rejection

PRODUCT SUMMARY

| PART NUMBER | OPERATING RANGE (mm) | OPERATING VOLTAGE RANGE (V) | I ² C BUS VOLTAGE RANGE (V) | LED PULSE CURRENT ⁽¹⁾ (mA) | AMBIENT LIGHT RANGE (lx) | AMBIENT LIGHT RESOLUTION (lx) | OUTPUT CODE | ADC RESOLUTION PROXIMITY / AMBIENT LIGHT |
|-------------|----------------------|-----------------------------|--|---------------------------------------|--------------------------|-------------------------------|--------------------------|--|
| VCNL4020 | 1 to 200 | 2.5 to 3.6 | 1.7 to 5 | 10 to 200 | 0.25 to 16 383 | 0.25 | 16 bit, I ² C | 16 bit / 16 bit |

Note

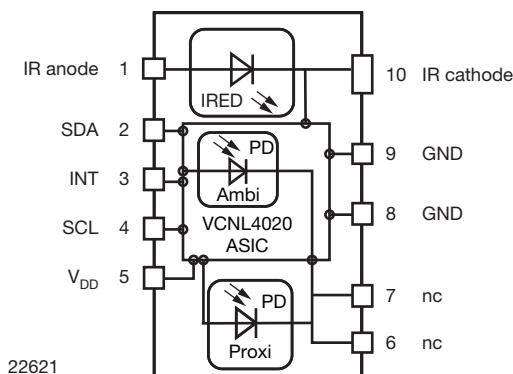
⁽¹⁾ Adjustable through I²C interface

| ORDERING INFORMATION | | | | | |
|----------------------|---------------|-----------------------|--|-----------------------------|--|
| ORDERING CODE | PACKAGING | VOLUME ⁽¹⁾ | | REMARKS | |
| VCNL4020-GS08 | Tape and reel | MOQ: 3300 pcs | | 4.90 mm x 2.40 mm x 0.83 mm | |
| VCNL4020-GS18 | | MOQ: 13 000 pcs | | | |

Note
⁽¹⁾ MOQ: minimum order quantity

| ABSOLUTE MAXIMUM RATINGS ($T_{amb} = 25^\circ\text{C}$, unless otherwise specified) | | | | | |
|---|---------------------------------|-----------|------|------|------|
| PARAMETER | TEST CONDITION | SYMBOL | MIN. | MAX. | UNIT |
| Supply voltage | | V_{DD} | -0.3 | 5.5 | V |
| Operation temperature range | | T_{amb} | -25 | +85 | °C |
| Storage temperature range | | T_{stg} | -25 | +85 | °C |
| Total power dissipation | $T_{amb} \leq 25^\circ\text{C}$ | P_{tot} | | 50 | mW |
| Junction temperature | | T_j | | 100 | °C |

| BASIC CHARACTERISTICS ($T_{amb} = 25^\circ\text{C}$, unless otherwise specified) | | | | | | |
|--|--|-----------|------|------|------|--------|
| PARAMETER | TEST CONDITION | SYMBOL | MIN. | TYP. | MAX. | UNIT |
| Supply voltage V_{DD} | | | 2.5 | | 3.6 | V |
| Supply voltage IR anode | | | 2.5 | | 5 | V |
| I^2C Bus H-level range | | | 1.7 | | 5 | V |
| INT H-level range | | | 1.7 | | 5 | V |
| INT low voltage | 3 mA sink current | | | | 0.4 | V |
| Current consumption | Standby current, no IRED-operation | | | 1.5 | 2 | µA |
| Current consumption proximity mode incl. IRED (averaged) | 2 measurements per second, IRED current 20 mA | | | 5 | | µA |
| | 250 measurements per second, IRED current 20 mA | | | 520 | | µA |
| | 2 measurements per second, IRED current 200 mA | | | 35 | | µA |
| | 250 measurements per second, IRED current 200 mA | | | 4 | | mA |
| Current consumption ambient light mode | 2 measurements per second averaging = 1 | | | 2.5 | | µA |
| | 8 measurements per second averaging = 1 | | | 10 | | µA |
| | 2 measurements per second averaging = 64 | | | 160 | | µA |
| | 8 measurements per second averaging = 64 | | | 640 | | µA |
| Ambient light resolution | Digital resolution (LSB count) | | | 0.25 | | lx |
| Ambient light output | $E_V = 100 \text{ lx}$ averaging = 64 | | | 400 | | counts |
| I^2C clock rate range | | f_{SCL} | | | 3400 | kHz |

CIRCUIT BLOCK DIAGRAM

Note

- nc must not be electrically connected
Pads 6 and 7 are only considered as solder pads

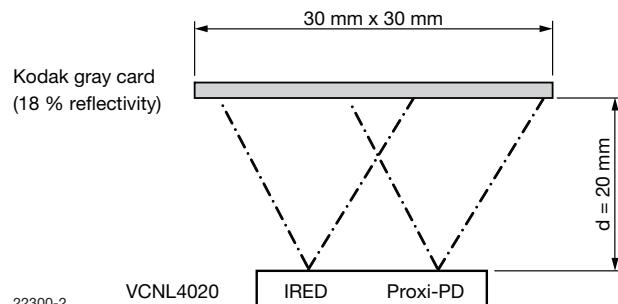
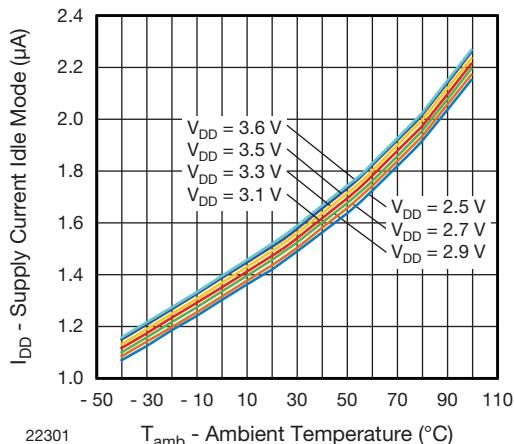
TEST CIRCUIT

BASIC CHARACTERISTICS ($T_{amb} = 25^\circ\text{C}$, unless otherwise specified)


Fig. 1 - Idle Current vs. Ambient Temperature

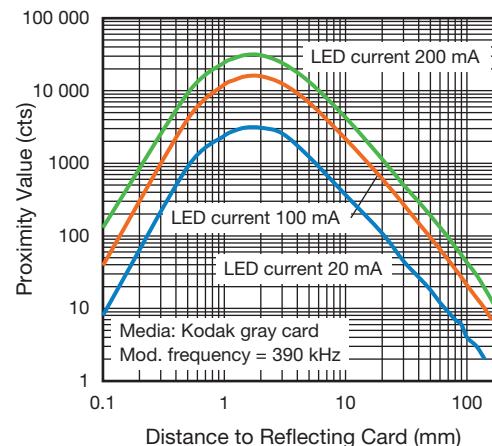


Fig. 3 - Proximity Value vs. Distance

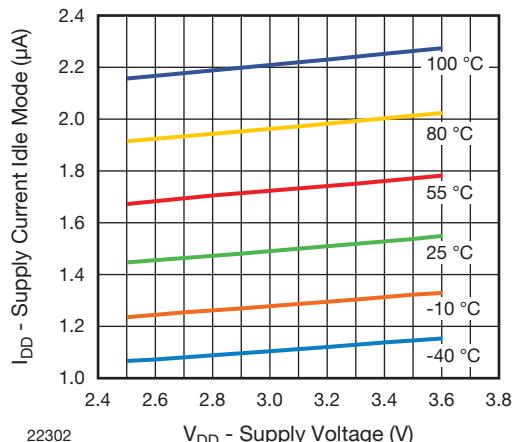


Fig. 2 - Idle Current vs. V_DD

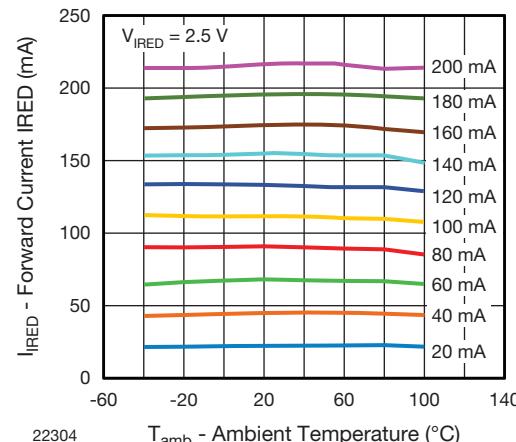


Fig. 4 - Forward Current vs. Temperature

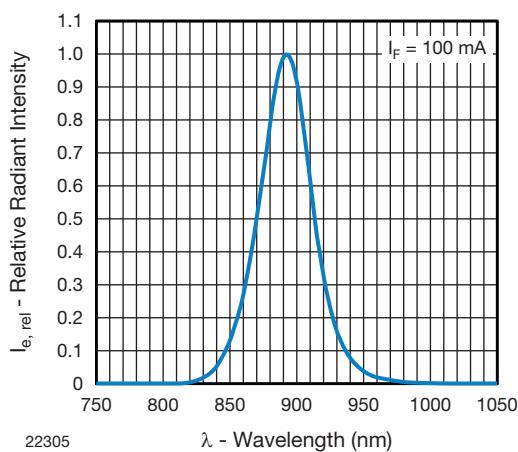


Fig. 5 - Relative Radiant Intensity vs. Wavelength

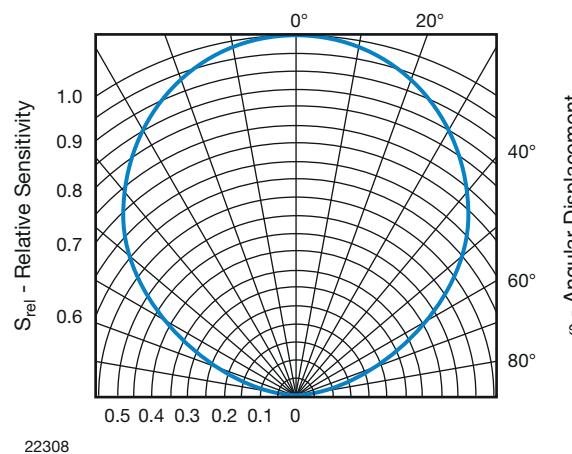


Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement (Proximity Sensor)

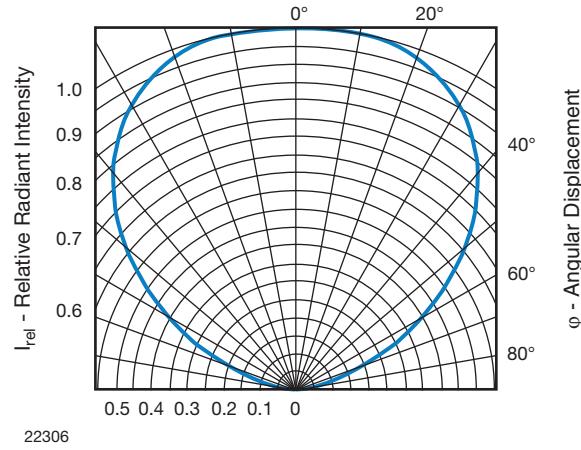


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement

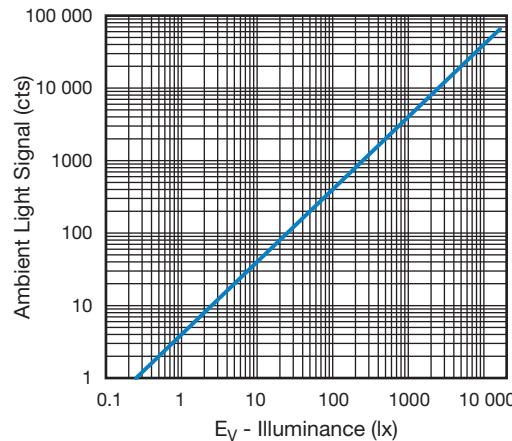


Fig. 9 - Ambient Light Value vs. Illuminance

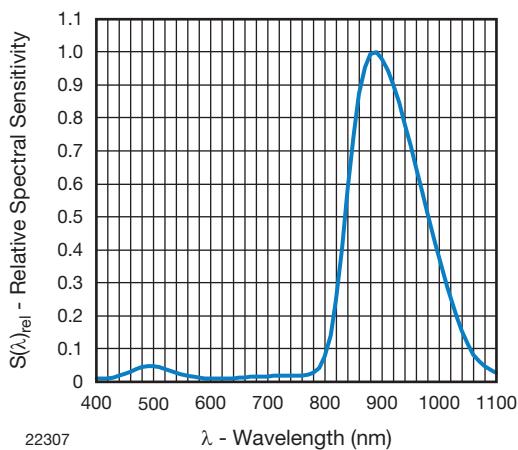


Fig. 7 - Relative Spectral Sensitivity vs. Wavelength (Proximity Sensor)

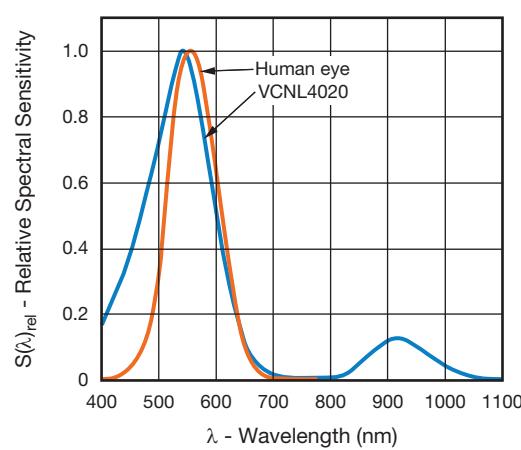
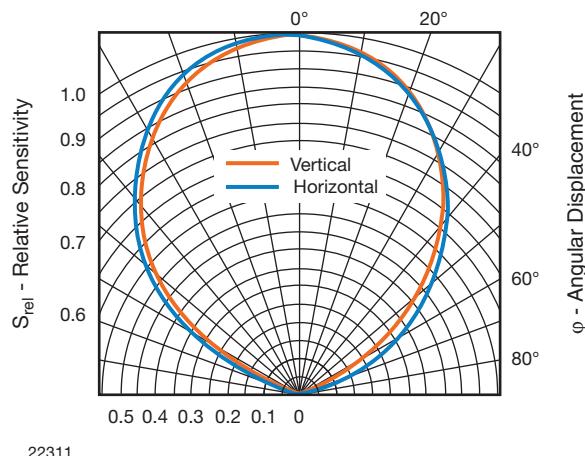


Fig. 10 - Relative Spectral Sensitivity vs. Wavelength (Ambient Light Sensor)



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Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement
(Ambient Light Sensor)

APPLICATION INFORMATION

VCNL4020 is a cost effective solution of proximity and ambient light sensor with I²C bus interface. The standard serial digital interface is easy to access "Proximity Signal" and "Light Intensity" without complex calculation and programming by external controller. Beside the digital output also a flexible programmable interrupt pin is available.

1. Application Circuit

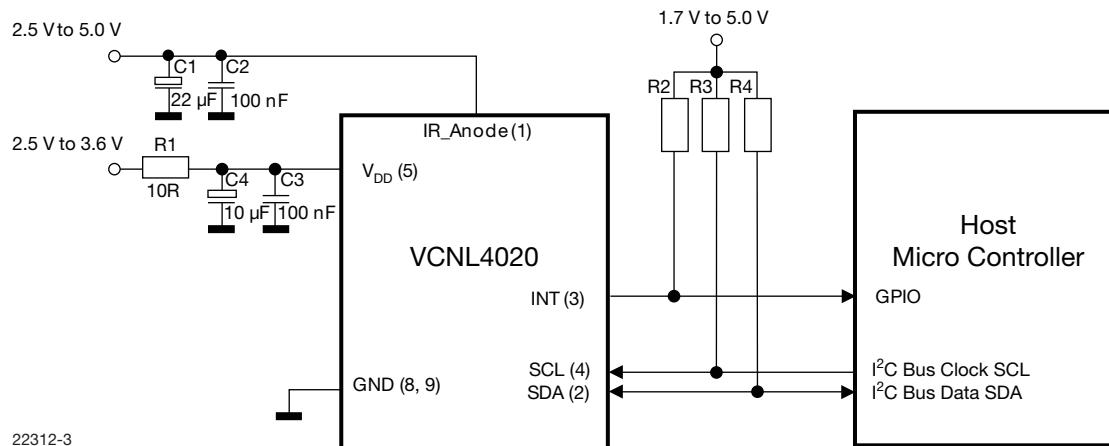


Fig. 12 - Application Circuit
(x) = Pin Number

Notes

- The interrupt pin is an open drain output. The needed pull-up resistor may be connected to the same supply voltage as the application controller and the pull-up resistors at SDA/SCL. Proposed value R2 should be $>1\text{ k}\Omega$, e.g. 10 k Ω to 100 k Ω . Proposed value for R3 and R4, e.g. 2.2 k Ω to 4.7 k Ω , depend also on the I²C bus speed. For detailed description about set-up and use of the interrupt as well as more application related information see AN: "Designing VCNL4020 into an Application".
- IR_Cathode needs no external connection. The needed connection to the driver is done internally.

2. I²C Interface

The VCNL4020 contains seventeen 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I²C communication. Figure 13 shows the basic I²C communication with VCNL4020.

The built in I²C interface is compatible with all I²C modes (standard, fast and high speed).

I²C H-level range = 1.7 V to 5 V.

Please refer to the I²C specification from NXP for details.

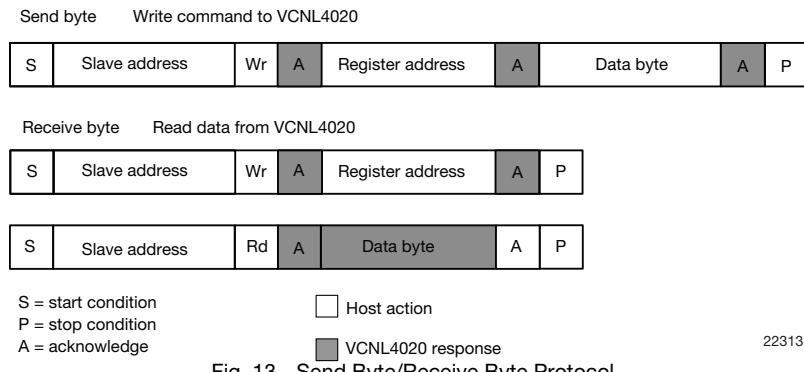


Fig. 13 - Send Byte/Receive Byte Protocol

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Device Address

The VCNL4020 has a fix slave address for the host programming and accessing selection. The predefined 7 bit I²C bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0010 011x = 26h for write, 27h for read.

Register Addresses

VCNL4020 has seventeen user accessible 8 bit registers. The register addresses are 80h (register #0) to 90h (register #16).

REGISTER FUNCTIONS

Register #0 Command Register

Register address = 80h

The register #0 is for starting ambient light or proximity measurements. This register contains 2 flag bits for data ready indication.

| TABLE 1 - COMMAND REGISTER #0 | | | | | | | |
|-------------------------------|---|---------------|--------|---------|--------|---------|--------------|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| config_lock | als_data_rdy | prox_data_rdy | als_od | prox_od | als_en | prox_en | selftimed_en |
| Description | | | | | | | |
| config_lock | Read only bit. Value = 1 | | | | | | |
| als_data_rdy | Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #5, reg #6) is read. | | | | | | |
| prox_data_rdy | Read only bit. Value = 1 when proximity measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #7, reg #8) is read. | | | | | | |
| als_od | R/W bit. Starts a single on-demand measurement for ambient light. If averaging is enabled, starts a sequence of readings and stores the averaged result. Result is available at the end of conversion for reading in the registers #5(HB) and #6(LB). | | | | | | |
| prox_od | R/W bit. Starts a single on-demand measurement for proximity. Result is available at the end of conversion for reading in the registers #7(HB) and #8(LB). | | | | | | |
| als_en | R/W bit. Enables periodic als measurement | | | | | | |
| prox_en | R/W bit. Enables periodic proximity measurement | | | | | | |
| selftimed_en | R/W bit. Enables state machine and LP oscillator for self timed measurements; no measurement is performed until the corresponding bit is set | | | | | | |

Note

- With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and proximity is done. Beside als_en and/or prox_en first selftimed_en needs to be set. On-demand measurement modes are disabled if selftimed_en bit is set. For the selftimed_en mode changes in reading rates (reg #4 and reg #2) can be made only when b0 (selftimed_en bit) = 0. For the als_od mode changes to the reg #4 can be made only when b4 (als_od bit) = 0; this is to avoid synchronization problems and undefined states between the clock domains. In effect this means that it is only reasonable to change rates while no selftimed conversion is ongoing.

Register #1 Product ID Revision Register

Register address = 81h. This register contains information about product ID and product revision.

Register data value of current revision = 21h.

| TABLE 2 - PRODUCT ID REVISION REGISTER #1 | | | | | | | | | | | |
|--|---------------------------|-------|-------|-------------|-------|-------|-------|--|--|--|--|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | | | |
| Product ID | | | | Revision ID | | | | | | | |
| Description | | | | | | | | | | | |
| Product ID | Read only bits. Value = 2 | | | | | | | | | | |
| Revision ID | Read only bits. Value = 1 | | | | | | | | | | |

Register #2 Rate of Proximity Measurement

Register address = 82h.

| TABLE 3 - PROXIMITY RATE REGISTER #2 | | | | | | | | | | | |
|---|---|-------|-------|--|-------|-------|-------|--|--|--|--|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | | | |
| n/a | | | | Rate of Proximity Measurement (no. of measurements per second) | | | | | | | |
| Description | | | | | | | | | | | |
| Proximity rate | R/W bits. 000 - 1.95 measurements/s (DEFAULT) 001 - 3.90625 measurements/s 010 - 7.8125 measurements/s 011 - 16.625 measurements/s 100 - 31.25 measurements/s 101 - 62.5 measurements/s 110 - 125 measurements/s 111 - 250 measurements/s | | | | | | | | | | |

Note

- If self_timed measurement is running, any new value written in this register will not be taken over until the mode is actually cycled.

Register #3 LED Current Setting for Proximity Mode

Register address = 83h. This register is to set the LED current value for proximity measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

| TABLE 4 - IR LED CURRENT REGISTER #3 | | | | | | | | | | | | | |
|---|---|----------------------|-------|-------|-------|-------|-------|--|--|--|--|--|--|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | | | | | |
| Fuse prog ID | | IR LED current value | | | | | | | | | | | |
| Description | | | | | | | | | | | | | |
| Fuse prog ID | Read only bits. Information about fuse program revision used for initial setup/calibration of the device. | | | | | | | | | | | | |
| IR LED current value | R/W bits. IR LED current = Value (dec.) x 10 mA. Valid Range = 0 to 20d. e.g. 0 = 0 mA, 1 = 10 mA,, 20 = 200 mA (2 = 20 mA = DEFAULT) LED Current is limited to 200 mA for values higher as 20d. | | | | | | | | | | | | |

Register #4 Ambient Light Parameter Register

Register address = 84h.

| TABLE 5 - AMBIENT LIGHT PARAMETER REGISTER #4 | | | | | | | | | | |
|--|----------|--|-------|--------------------------|---|-------|-------|--|--|--|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | | |
| Cont. conv. mode | als_rate | | | Auto offset compensation | Averaging function (number of measurements per run) | | | | | |
| | | Description | | | | | | | | |
| Cont. conversion mode | | R/W bit. Continuous conversion mode. Enable = 1; Disable = 0 = DEFAULT This function can be used for performing faster ambient light measurements. This mode should only be used with ambient light on-demand measurements. Do not use with self-timed mode. Please refer to the application information chapter 3.3 for details about this function. | | | | | | | | |
| Ambient light measurement rate | | R/W bits. Ambient light measurement rate 000 - 1 samples/s 001 - 2 samples/s = DEFAULT 010 - 3 samples/s 011 - 4 samples/s 100 - 5 samples/s 101 - 6 samples/s 110 - 8 samples/s 111 - 10 samples/s | | | | | | | | |
| Auto offset compensation | | R/W bit. Automatic offset compensation. Enable = 1 = DEFAULT; Disable = 0 In order to compensate a technology, package or temperature related drift of the ambient light values there is a built in automatic offset compensation function. With active auto offset compensation the offset value is measured before each ambient light measurement and subtracted automatically from actual reading. | | | | | | | | |
| Averaging function | | R/W bits. Averaging function. Bit values sets the number of single conversions done during one measurement cycle. Result is the average value of all conversions. Number of conversions = $2^{\text{decimal_value}}$ e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv.,7 = 128 conv. DEFAULT = 32 conv. (bit 2 to bit 0: 101) | | | | | | | | |

Note

- If self_timed measurement is running, any new value written in this register will not be taken over until the mode is actually cycled.

Register #5 and #6 Ambient Light Result Register

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings.

The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

| TABLE 6 - AMBIENT LIGHT RESULT REGISTER #5 | | | | | | | |
|--|-------|-------|-------|-------|-------|-------|-------|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| Description | | | | | | | |
| Read only bits. High byte (15:8) of ambient light measurement result | | | | | | | |

| TABLE 7 - AMBIENT LIGHT RESULT REGISTER #6 | | | | | | | |
|--|-------|-------|-------|-------|-------|-------|-------|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| Description | | | | | | | |
| Read only bits. Low byte (7:0) of ambient light measurement result | | | | | | | |

Register #7 and #8 Proximity Measurement Result Register

Register address = 87h and 88h. These registers are the result registers for proximity measurement readings.

The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

TABLE 8 - PROXIMITY RESULT REGISTER #7

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|--|-------|-------|-------|-------|-------|-------|-------|
| Description | | | | | | | |
| Read only bits. High byte (15:8) of proximity measurement result | | | | | | | |

TABLE 9 - PROXIMITY RESULT REGISTER #8

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|--|-------|-------|-------|-------|-------|-------|-------|
| Description | | | | | | | |
| Read only bits. Low byte (7:0) of proximity measurement result | | | | | | | |

Register #9 Interrupt Control Register

Register address = 89h.

TABLE 10 - INTERRUPT CONTROL REGISTER #9

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | |
|--------------------|-------|--|-------------------|------------------|--------------|---------------|-------|--|
| Int count exceed | | n/a | INT_PROX_ready_EN | INT_ALS_ready_EN | INT_THRES_EN | INT_THRES_SEL | | |
| Description | | | | | | | | |
| Int count exceed | | R/W bits. These bits contain the number of consecutive measurements needed above/below the threshold 000 - 1 count = DEFAULT 001 - 2 count 010 - 4 count 011 - 8 count 100 -16 count 101 - 32 count 110 - 64 count 111 - 128 count | | | | | | |
| INT_PROX_ready_EN | | R/W bit. Enables interrupt generation at proximity data ready | | | | | | |
| INT_ALS_ready_EN | | R/W bit. Enables interrupt generation at ambient data ready | | | | | | |
| INT_THRES_EN | | R/W bit. Enables interrupt generation when high or low threshold is exceeded | | | | | | |
| INT_THRES_SEL | | R/W bit. If 0: thresholds are applied to proximity measurements If 1: thresholds are applied to als measurements | | | | | | |

Register #10 and #11 Low Threshold

Register address = 8Ah and 8Bh. These registers contain the low threshold value. The value is a 16 bit word. The high byte is stored in register #10 and the low byte in register #11.

TABLE 11 - LOW THRESHOLD REGISTER #10

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Description |
|---|-------|-------|-------|-------|-------|-------|-------|-------------|
| R/W bits. High byte (15:8) of low threshold value | | | | | | | | |

TABLE 12 - LOW THRESHOLD REGISTER #11

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Description |
|---|-------|-------|-------|-------|-------|-------|-------|-------------|
| R/W bits. Low byte (7:0) of low threshold value | | | | | | | | |

Register #12 and #13 High Threshold

Register address = 8Ch and 8Dh. These registers contain the high threshold value. The value is a 16 bit word. The high byte is stored in register #12 and the low byte in register #13.

TABLE 13 - HIGH THRESHOLD REGISTER #12

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Description |
|--|-------|-------|-------|-------|-------|-------|-------|-------------|
| R/W bits. High byte (15:8) of high threshold value | | | | | | | | |

TABLE 14 - HIGH THRESHOLD REGISTER #13

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Description |
|--|-------|-------|-------|-------|-------|-------|-------|-------------|
| R/W bits. Low byte (7:0) of high threshold value | | | | | | | | |

Register #14 Interrupt Status Register

Register address = 8Eh. This register contains information about the interrupt status for either proximity or ALS function and indicates if high or low going threshold exceeded.

TABLE 15 - INTERRUPT STATUS REGISTER #14

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Description |
|--|-------|-------|-------|----------------|---------------|------------|-----------|-------------|
| n/a | | | | int_prox_ready | int_als_ready | int_th_low | int_th_hi | |
| R/W bit. Indicates a generated interrupt for proximity | | | | | | | | |
| R/W bit. Indicates a generated interrupt for als | | | | | | | | |
| R/W bit. Indicates a low threshold exceed | | | | | | | | |
| R/W bit. Indicates a high threshold exceed | | | | | | | | |

Note

- Once an interrupt is generated the corresponding status bit goes to 1 and stays there unless it is cleared by writing a 1 in the corresponding bit. The int pad will be pulled down while at least one of the status bit is 1.

Register #15 Proximity Modulator Timing Adjustment

Register address = 8Fh.

| TABLE 16 - PROXIMITY MODULATOR TIMING ADJUSTMENT #15 | | | | | | | | | | | | |
|---|-------|---|---------------------|-------|-------|----------------------|-------|--|--|--|--|--|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | | | | | |
| Modulation delay time | | | Proximity frequency | | | Modulation dead time | | | | | | |
| Description | | | | | | | | | | | | |
| Modulation delay time | | R/W bits. Setting a delay time between IR LED signal and IR input signal evaluation. This function is for compensation of delays from IR LED and IR photo diode. Also in respect to the possibility for setting different proximity signal frequency. Correct adjustment is optimizing measurement signal level. (DEFAULT = 0) | | | | | | | | | | |
| Proximity frequency | | R/W bits. Setting the proximity IR test signal frequency The proximity measurement is using a square IR signal as measurement signal. Four different values are possible: 00 = 390.625 kHz (DEFAULT) 01 = 781.25 kHz 10 = 1.5625 MHz 11 = 3.125 MHz | | | | | | | | | | |
| Modulation dead time | | R/W bits. Setting a dead time in evaluation of IR signal at the slopes of the IR signal. (DEFAULT = 1) This function is for reducing of possible disturbance effects. This function is reducing signal level and should be used carefully. | | | | | | | | | | |

Note

- The settings for best performance will be provided by Vishay. With first samples this is evaluated to:
Delay Time = 0 ; Dead Time = 1 and Prox Frequency = 0 . With that register#15 should be programmed with 1 (= default value).

Register #16 Ambient IR Light Level Register

Register address = 90h.

This register is not intended to be used by customer.

3. IMPORTANT APPLICATION HINTS AND EXAMPLES

3.1 Receiver standby mode

In standby mode the receiver has the lowest current consumption of about 1.5 μ A. In this mode only the I²C interface is active. This is always valid, when there are no measurement demands for proximity and ambient light executed. Also the current sink for the IR-LED is inactive, so there is no need for changing register #3 (IR LED current).

3.2 Data Read

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.

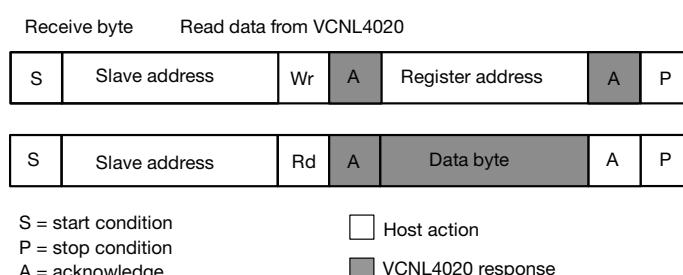


Fig. 14 - Send Byte/Receive Byte Protocol

The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

Note

- For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After one read command the internal register counter is increased automatically and any subsequent read command is accessing the next register.

Example: read register "Ambient Light Result Register" #5 and #6:

Addressing:command: 26h, 85h (VCNL4020_I²C_Bus_Write_Adrr., Ambient Light Result Register #5 [85])

Read register #5:command: 27h, data (VCNL4020_I²C_Bus_Read_Adrr., {High Byte Data of Ambient Light Result register #5 [85]})

Read register #6:command: 27h, data (VCNL4020_I²C_Bus_Read_Adrr., {Low Byte Data of Ambient Light Result register #6 [86]})

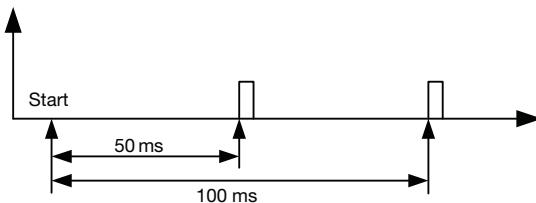
3.3 Continuous Conversion Mode in Ambient Light Measurement

In the following is a detail description of the function "continuous conversion" (bit 7 of register #4)

Standard mode (bit 7 of reg #4 = 0):

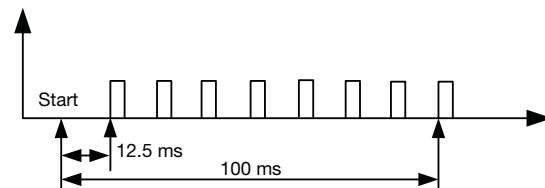
In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300 μ s.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).



22315

Fig. 15 - Ambient Light Measurement with Averaging = 2;
Final Measurement Result = Average of these 2 Measurements



22316

Fig. 16 - Ambient Light Measurement with Averaging = 8;
Final Measurement Result = Average of these 8 Measurements

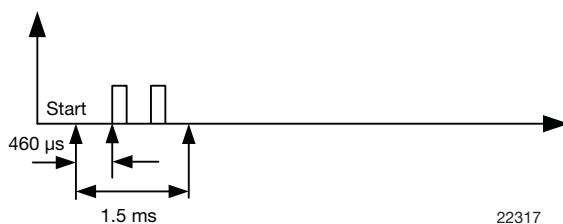
Note

- \geq Independent of setting of averaging the result is available only after 100 ms.

Continuous conversion mode (bit 7 of register #4 = 1):

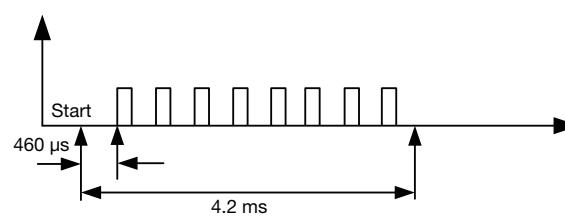
In continuous conversion mode the single measurements are done directly subsequent after each other.

See following examples in figure 17 and 18



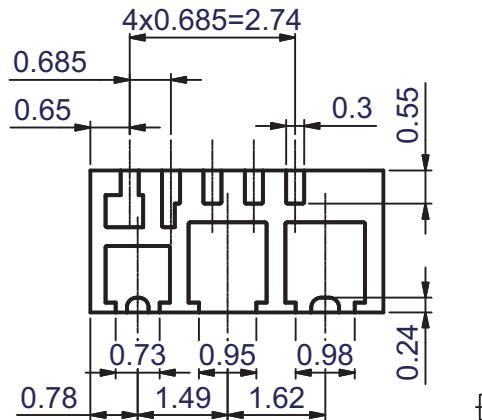
22317

Fig. 17 - Ambient Light Measurement with Averaging = 2;
using Continuous Conversion Mode

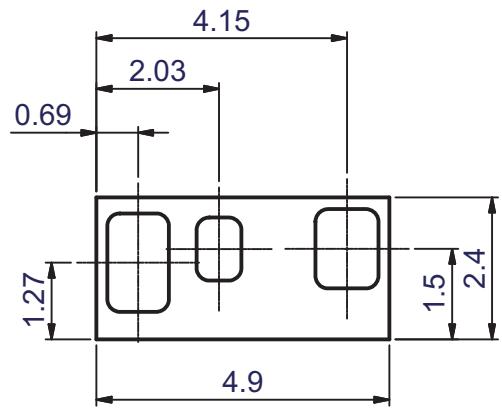
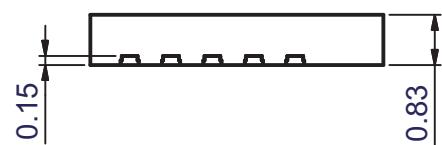


22318

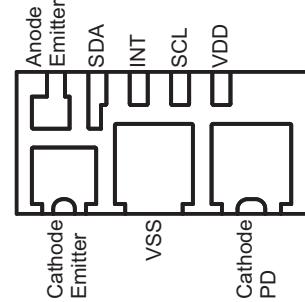
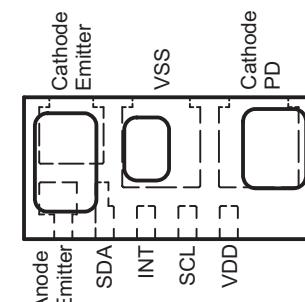
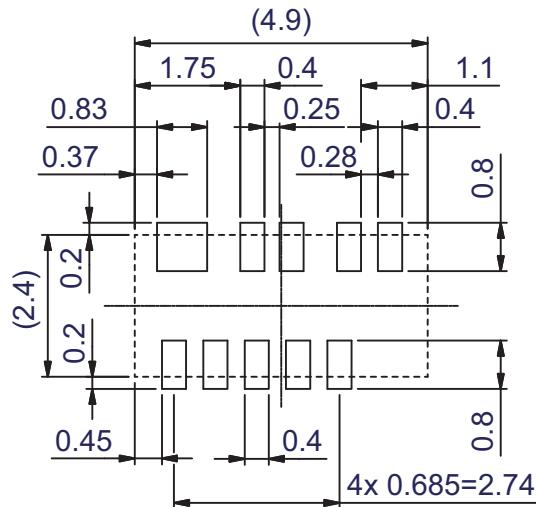
Fig. 18 - Ambient Light Measurement with Averaging = 8;
using Continuous Conversion Mode

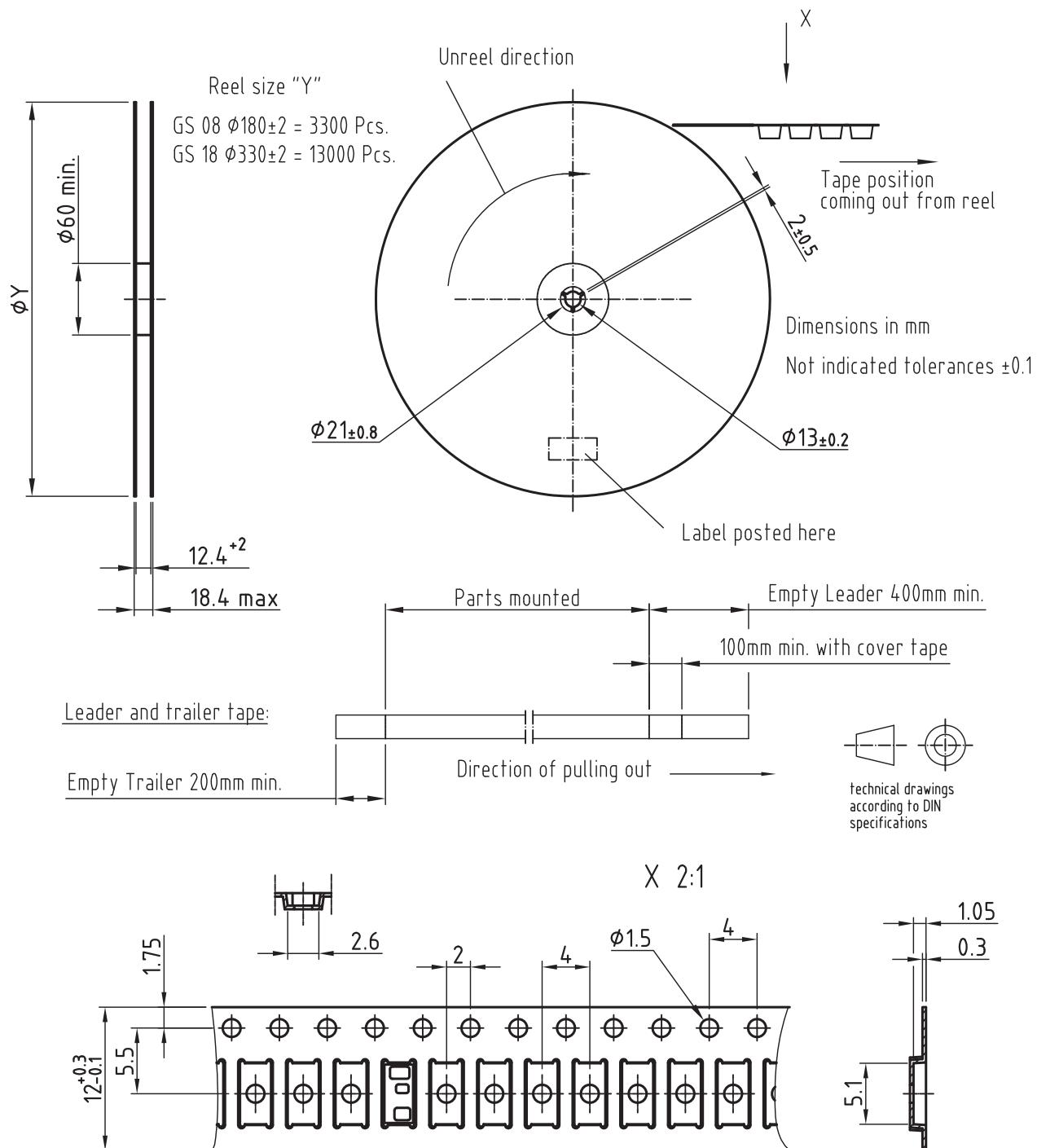
PACKAGE DIMENSIONS in millimeters


technical drawings
according to DIN
specifications



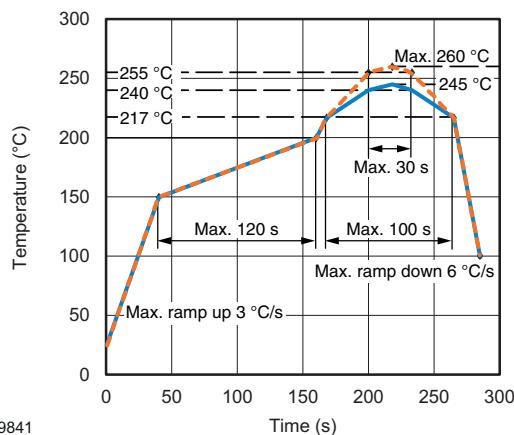
Drawing-No.: 6.550-5319

Not indicated tolerances ± 0.1
Pinning Bottom view

Pinning Top view

Proposed PCB Footprint


TAPE AND REEL DIMENSIONS in millimeters


Drawing-No.: 9.700-5387.01-4

SOLDER PROFILE



19841

Fig. 19 - Lead (Pb)-free Reflow Solder Profile
According to J-STD-020

DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

FLOOR LIFE

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 72 h

Conditions: $T_{amb} < 30^{\circ}\text{C}$, RH < 60 %

Moisture sensitivity level 4, according to J-STD-020.

DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.

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