

4.5-V TO 20-V INPUT, 3-A OUTPUT SYNCHRONOUS PWM SWITCHER WITH INTEGRATED FET (SWIFT™)

FEATURES

- 100 mΩ, 4.5-A Peak MOSFET Switch for High Efficiency at 3-A Continuous Output Current
- Uses External Lowside MOSFET or Diode
- Fixed Output Versions – 1.2V/1.5V/1.8V/2.5V/3.3V/5.0V
- Internally Compensated for Low Parts Count
- Synchronizes to External Clock
- 180° Out of Phase Synchronization
- Wide PWM Frequency – Fixed 250 kHz, 500 kHz or Adjustable 250 kHz to 700 kHz
- Internal Slow Start
- Load Protected by Peak Current Limit and Thermal Shutdown
- Adjustable Undervoltage Lockout
- 16-Pin TSSOP PowerPAD™ Package

APPLICATIONS

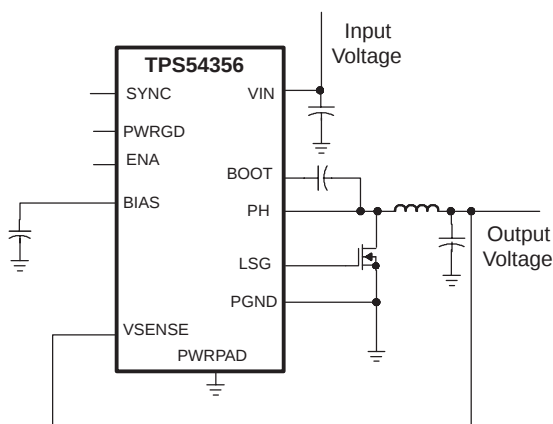
- Industrial & Commercial Low Power Systems
- LCD Monitors and TVs
- Computer Peripherals
- Point of Load Regulation for High Performance DSPs, FPGAs, ASICs and Microprocessors

DESCRIPTION

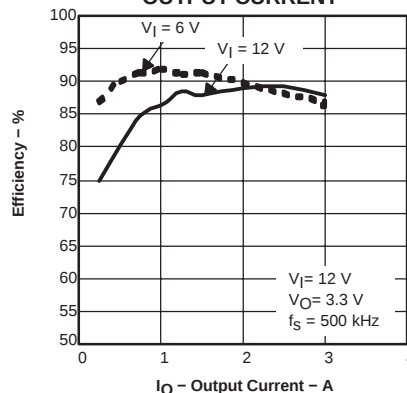
The TPS5435x is a medium output current synchronous buck PWM converter with an integrated high side MOSFET and a gate driver for an optional low side external MOSFET. Features include a high performance voltage error amplifier that enables maximum performance under transient conditions. The TPS5435x has an under-voltage-lockout circuit to prevent start-up until the input voltage reaches a preset value; an internal slow-start circuit to limit in-rush currents; and a power good output to indicate valid output conditions. The synchronization feature is configurable as either an input or an output for easy 180° out of phase synchronization.

The TPS5435x devices are available in a thermally enhanced 16-pin TSSOP (PWP) PowerPAD™ package. TI provides evaluation modules and the SWIFT™ Designer software tool to aid in quickly achieving high-performance power supply designs to meet aggressive equipment development cycles.

SIMPLIFIED SCHEMATIC



EFFICIENCY
VS
OUTPUT CURRENT



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD and SWIFT are trademarks of Texas Instruments.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ORDERING INFORMATION

T _A	OUTPUT VOLTAGE	PACKAGE	PART NUMBER
-40°C to 85°C	1.2 V	Plastic HTSSOP (PWP)	TPS54352PWP
	1.5 V	Plastic HTSSOP (PWP)	TPS54353PWP
	1.8 V	Plastic HTSSOP (PWP)	TPS54354PWP
	2.5 V	Plastic HTSSOP (PWP)	TPS54355PWP
	3.3 V	Plastic HTSSOP (PWP)	TPS54356PWP
	5.0 V	Plastic HTSSOP (PWP)	TPS54357PWP

(1) The PWP package is also available taped and reeled. Add an R suffix to the device type (i.e. TPS5435xPWPR).

PACKAGE DISSIPATION RATINGS(1)

PACKAGE	THERMAL IMPEDANCE JUNCTION-TO-AMBIENT	T _A = 25°C POWER RATING	T _A = 70°C POWER RATING	T _A = 85°C POWER RATING
16-Pin PWP with solder(2)	42.1°C/W	2.36	1.31	0.95
16-Pin PWP without solder	151.9°C/W	0.66	0.36	0.26

(1) See Figure 47 for power dissipation curves.

(2) Test Board Conditions

1. Thickness: 0.062"
2. 3" x 3"
3. 2 oz. Copper traces located on the top and bottom of the PCB for soldering
4. Copper areas located on the top and bottom of the PCB for soldering
5. Power and ground planes, 1 oz. copper (0.036 mm thick)
6. Thermal vias, 0.33 mm diameter, 1.5 mm pitch
7. Thermal isolation of power plane

For more information, refer to TI technical brief SLMA002.

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted⁽¹⁾

		UNIT
Input voltage range, V_I	VIN	–0.3 V to 21.5 V
	VSENSE	–0.3 V to 8.0 V
	UVLO	–0.3 V to 8.0 V
	SYNC	–0.3 V to 4.0 V
	ENA	–0.3 V to 4.0 V
	BOOT	$V_I(\text{PH}) + 8.0 \text{ V}$
Output voltage range, V_O	VBIAS	–0.3 to 8.5 V
	LSG	–0.3 to 8.5 V
	SYNC	–0.3 to 4.0 V
	RT	–0.3 to 4.0 V
	PWRGD	–0.3 to 6.0 V
	COMP	–0.3 to 4.0 V
	PH	–1.5 V to 22 V
Source current, I_O	PH	Internally Limited (A)
	LSG (Steady State Current)	10 mA
	COMP, VBIAS	3 mA
Sink current, I_S	SYNC	5 mA
	LSG (Steady State Current)	100 mA
	PH (Steady State Current)	500 mA
	COMP	3 mA
	ENA, PWRGD	10 mA
Voltage differential	AGND to PGND	±0.3 V
Operating virtual junction temperature range, T_J		–40°C to +150°C
Storage temperature, T_{stg}		–65°C to +150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds		260°C

⁽¹⁾ Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

ELECTROSTATIC DISCHARGE (ESD) PROTECTION

	MIN	MAX	UNIT
Human body model		600	V
CDM		1.5	kV

RECOMMENDED OPERATING CONDITIONS

		MIN	NOM	MAX	UNIT
Input voltage range, V_I	TPS54352–6	4.5		20	V
	TPS54357	6.65		20	
Operating junction temperature, T_J		–40		125	°C

ELECTRICAL CHARACTERISTICS

$T_J = -40^{\circ}\text{C}$ to 125°C , $V_{IN} = 4.5\text{ V}$ to 20 V (unless otherwise noted)

PARAMETER			TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CURRENT							
I _Q Quiescent current			Operating current, PH pin open, No external low side MOSFET, RT = Hi-Z	5			mA
			Shutdown, ENA = 0 V	1			mA
VIN	Start threshold voltage	TPS54352–6		4.32	4.49	V	
		TPS54357		6.4	6.65		
	Stop threshold voltage	TPS54352–6	3.69	3.97	V		
		TPS54357	5.45	5.80			
	Hysteresis	TPS54352–6	350		mV		
		TPS54357	600		mV		
OUTPUT VOLTAGE							
V _O	Output voltage	TPS54352	T _J = 25°C, I _O = 100 mA to 3 A	1.88	1.2	1.212	V
			I _O = 100 mA to 3 A	1.176	1.2	1.224	
		TPS54353	T _J = 25°C, I _O = 100 mA to 3 A	1.485	1.5	1.515	
			I _O = 100 mA to 3 A	1.47	1.5	1.53	
		TPS54354	T _J = 25°C, I _O = 100 mA to 3 A	1.782	1.8	1.818	
			I _O = 100 mA to 3 A	1.764	1.8	1.836	
		TPS54355	T _J = 25°C, I _O = 100 mA to 3 A	2.475	2.5	2.525	
			I _O = 100 mA to 3 A	2.45	2.5	2.55	
		TPS54356	T _J = 25°C, VIN = 5.5 V to 20 V, I _O = 100 mA to 3 A	3.267	3.3	3.333	
			VIN = 5.5 V to 20 V, I _O = 100 mA to 3 A	3.234	3.3	3.366	
		TPS54357	T _J = 25°C, VIN = 7.5 V to 20 V, I _O = 100 mA to 3 A	4.95	5.0	5.05	
			VIN = 7.5 V to 20 V, I _O = 100 mA to 3 A	4.90	5.0	5.10	
UNDER VOLTAGE LOCK OUT (UVLO PIN)							
UVLO	Start threshold voltage		1.20	1.24		V	
	Stop threshold voltage		1.02	1.10		V	
	Hysteresis		100			mV	
BIAS VOLTAGE (VBIAS PIN)							
VBIAS	Output voltage	I _{VBIAS} = 1 mA, VIN ≥ 12 V	7.5	7.8	8.0	V	
		I _{VBIAS} = 1 mA, VIN = 4.5 V	4.4	4.47	4.5		
OSCILLATOR (RT PIN)							
Internally set PWM switching frequency			RT Grounded	200	250	300	kHz
			RT Open	400	500	600	
Externally set PWM switching frequency			RT = 100 kΩ (1% resistor to AGND)	425	500	575	kHz

ELECTRICAL CHARACTERISTICS (CONTINUED)
 $T_J = -40^{\circ}\text{C}$ to 125°C , $V_{IN} = 4.5\text{ V}$ to 20 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
FALLING EDGE TRIGGERED BIDIRECTIONAL SYNC SYSTEM (SYNC PIN)						
SYNC out low-to-high rise time (10%/90%) (1)		25 pF to ground		200	500	ns
SYNC out high-to-low fall time (90%/10%) (1)		25 pF to ground		5	10	ns
Falling edge delay time (1)		Delay from rising edge to rising edge of PH pins, see Figure 19		180		°
Minimum input pulse width (1)		RT = 100 kΩ		100		ns
Delay (falling edge SYNC to rising edge PH) (1)		RT = 100 kΩ		360		ns
SYNC out high level voltage		50-kΩ Resistor to ground, no pullup resistor	2.5			V
SYNC out low level voltage					0.6	V
SYNC in low level threshold			0.8			V
SYNC in high level threshold					2.3	V
SYNC in frequency range (1)		Percentage of programmed frequency	−10%		10%	
			225		770	kHz
FEED- FORWARD MODULATOR (INTERNAL SIGNAL)						
Modulator gain		VIN = 12 V, TJ = 25°C		8		V/V
Modulator gain variation			−25%		25%	
Minimum controllable ON time (1)				180		ns
Maximum duty factor (1)		VIN = 4.5 V	80%	86%		
VSENSE PIN						
Input bias current, VSENSE pin				1		μA
ENABLE (ENA PIN)						
Disable low level input voltage					0.5	V
Internal slow-start time (10% to 90%)	TPS54352	fS = 250 kHz, RT = ground (1)		3.20		ms
		fS = 500 kHz, RT = Hi-Z (1)		1.60		
	TPS54353	fS = 250 kHz, RT = ground (1)		4.00		
		fS = 500 kHz, RT = Hi-Z (1)		2.00		
	TPS54354	fS = 250 kHz, RT = ground (1)		4.60		
		fS = 500 kHz, RT = Hi-Z (1)		2.30		
	TPS54355	fS = 250 kHz, RT = ground (1)		4.40		
		fS = 500 kHz, RT = Hi-Z (1)		2.20		
	TPS54356	fS = 250 kHz, RT = ground (1)		5.90		
		fS = 500 kHz, RT = Hi-Z (1)		2.90		
TPS54357	fS = 250 kHz, RT = ground (1)		5.40			
	fS = 500 kHz, RT = Hi-Z (1)		2.70			
Pullup current source			1.8	5	10	μA
Pulldown MOSFET		II(ENA)= 1 mA		0.1		V
POWER GOOD (PWRGD PIN)						
Power good threshold		Rising voltage		97%		
Rising edge delay (1)		fS = 250 kHz		4		ms
		fS = 500 kHz		2		
PWRGD	Output saturation voltage		Isink = 1 mA, VIN > 4.5 V	0.05		V
	Output saturation voltage		Isink = 100 μA, VIN = 0 V	0.76		V
	Open drain leakage current		Voltage on PWRGD = 6 V		3	μA

(1) Ensured by design, not production tested.

ELECTRICAL CHARACTERISTICS (CONTINUED)

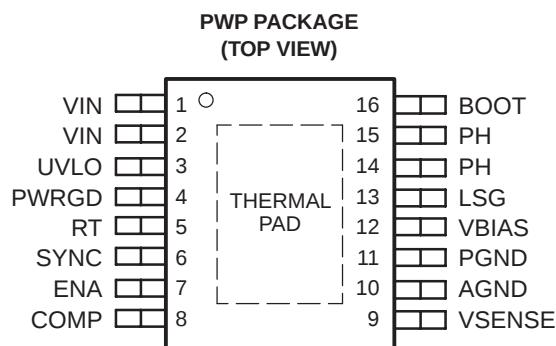
T_J = –40°C to 125°C, VIN = 4.5 V to 20 V (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
CURRENT LIMIT					
Current limit	VIN = 12 V	3.3	4.5	6.5	A
Current limit hiccup time ⁽¹⁾	f _S = 500 kHz		4.5		ms
THERMAL SHUTDOWN					
Thermal shutdown trip point ⁽¹⁾			165		°C
Thermal shutdown hysteresis ⁽¹⁾			7		°C
LOW SIDE MOSFET DRIVER (LSG PIN)					
Turn on rise time, (10%/90%) ⁽¹⁾	VIN = 4.5 V, Capacitive load = 1000 pF		15		ns
Deadtime ⁽¹⁾	VIN = 12 V		60		ns
Driver ON resistance	VIN = 4.5 V sink/source		7.5		Ω
	VIN = 12 V sink/source		5		
OUTPUT POWER MOSFETS (PH PIN)					
Phase node voltage when disabled	DC conditions and no load, ENA = 0 V		0.5		V
Voltage drop, low side FET and diode	VIN = 4.5 V, I _{dc} = 100 mA		1.13	1.42	V
	VIN = 12 V, I _{dc} = 100 mA		1.08	1.38	
r _{DS(ON)} High side power MOSFET switch ⁽²⁾	VIN = 4.5 V, BOOT-PH = 4.5 V, I _O = 0.5 A		150	300	mΩ
	VIN = 12 V, BOOT-PH = 8 V, I _O = 0.5 A		100	200	

(1) Ensured by design, not production tested.

(2) Resistance from VIN to PH pins.

PIN ASSIGNMENTS

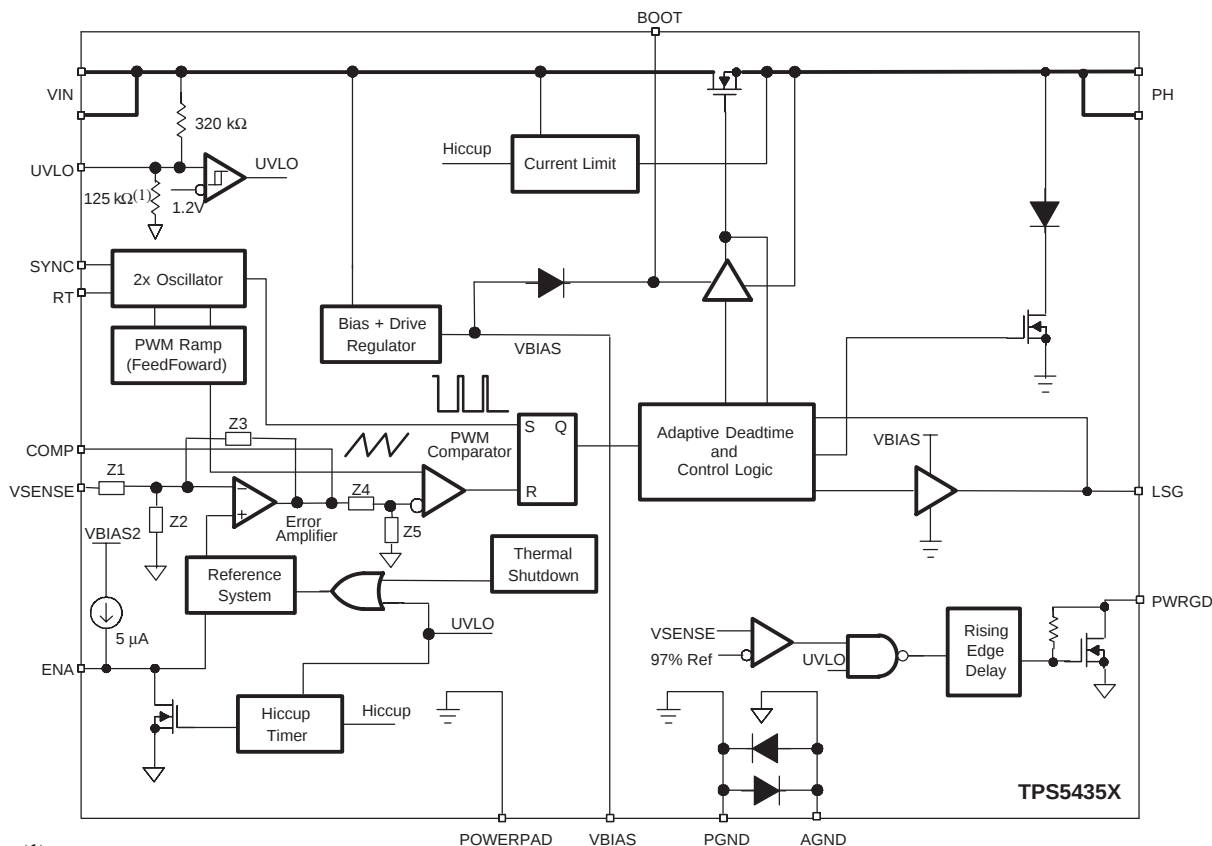


NOTE: If there is not a Pin 1 indicator, turn device to enable reading the symbol from left to right. Pin 1 is at the lower left corner of the device.

Terminal Functions

TERMINAL NO.	NAME	DESCRIPTION
1, 2	VIN	Input supply voltage, 4.5 V to 20 V. Must bypass with a low ESR 10- μ F ceramic capacitor. Place cap as close to device as possible; see Figure 23 for an example.
3	UVLO	Undervoltage lockout pin. Connecting an external resistive voltage divider from VIN to the pin will override the internal default VIN start and stop thresholds.
4	PWRGD	Power good output. Open drain output. A low on the pin indicates that the output is less than the desired output voltage. There is an internal rising edge filter on the output of the PWRGD comparator.
5	RT	Frequency setting pin. Connect a resistor from RT to AGND to set the switching frequency. Connecting the RT pin to ground or floating will set the frequency to an internally preselected frequency.
6	SYNC	Bidirectional synchronization I/O pin. SYNC pin is an output when the RT pin is floating or connected low. The output is a falling edge signal out of phase with the rising edge of PH. SYNC may be used as an input to synchronize to a system clock by connecting to a falling edge signal when an RT resistor is used. See 180° Out of Phase Synchronization operation in the Application Information section. In ALL cases, a 10 k Ω resistor Must be tied to the SYNC pin in parallel with ground. For information on how to extend slow start, see the <i>Enable (ENA) and Internal Slow Start</i> section on page 9.
7	ENA	Enable. Below 0.5 V, the device stops switching. Float pin to enable.
8	COMP	Error amplifier output. Do NOT connect ANYTHING to this pin.
9	VSENSE	Feedback pin
10	AGND	Analog ground—internally connected to the sensitive analog ground circuitry. Connect to PGND and PowerPAD.
11	PGND	Power ground—Noisy internal ground—Return currents from the LSG driver output return through the PGND pin. Connect to AGND and PowerPAD.
12	VBIAS	Internal 8.0-V bias voltage. A 1.0- μ F ceramic bypass capacitance is required on the VBIAS pin.
13	LSG	Gate drive for optional low side MOSFET. Connect gate of n-channel MOSFET for a higher efficiency synchronous buck converter configuration. Otherwise, leave open and connect schottky diode from ground to PH pins.
14, 15	PH	Phase node—Connect to external L-C filter.
16	BOOT	Bootstrap capacitor for high side gate driver. Connect a 0.1- μ F ceramic capacitor from BOOT to PH pins.
	PowerPAD	PGND and AGND pins must be connected to the exposed pad for proper operation. See Figure 23 for an example PCB layout.

FUNCTIONAL BLOCK DIAGRAM



(1) 75 kΩ for the TPS54357

DETAILED DESCRIPTION

Undervoltage Lockout (UVLO)

The undervoltage lockout (UVLO) system has an internal voltage divider from VIN to AGND. The defaults for the start/stop values are labeled VIN and given in Table 1. The internal UVLO threshold can be overridden by placing an external resistor divider from VIN to ground. The internal divider values are approximately 320 kΩ for the high side resistor and 125 kΩ for the low side resistor. The divider ratio (and therefore the default start/stop values) is quite

accurate, but the absolute values of the internal resistors may vary as much as 15%. If high accuracy is required for an externally adjusted UVLO threshold, select lower value external resistors to set the UVLO threshold. Using a 1-kΩ resistor for the low side resistor (R2 see Figure 1) is recommended. Under no circumstances should the UVLO pin be connected directly to VIN.

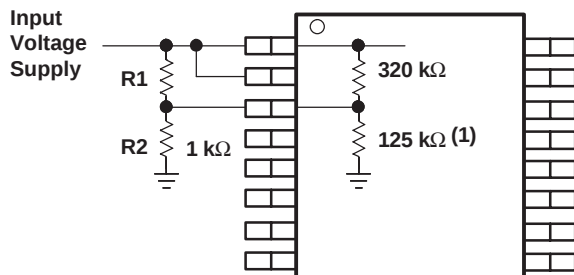
Table 1. Start/Stop Voltage Threshold

		START VOLTAGE THRESHOLD	STOP VOLTAGE THRESHOLD
VIN (Default)	TPS54352–6	4.49	3.69
	TPS54357	6.65	5.45
UVLO		1.24	1.02

The equations for selecting the UVLO resistors are:

$$R1 = \frac{VIN(start) \times 1 \text{ k}\Omega}{1.24 \text{ V}} - 1 \text{ k}\Omega \quad (1)$$

$$VIN(stop) = \frac{(R1 + 1 \text{ k}\Omega) \times 1.02 \text{ V}}{1 \text{ k}\Omega} \quad (2)$$



(1) 75 kΩ for the TPS54357

Figure 1. Circuit Using External UVLO Function

For applications which require an undervoltage lock out (UVLO) threshold greater than 4.49 V (6.6 V for TPS54357), external resistors may be implemented, see Figure 1, to adjust the start voltage threshold. For example, an application needing an UVLO start voltage of approximately 7.8 V using the equation (1), R1 is calculated to the nearest standard resistor value of 5.36 kΩ. Using equation (2), the input voltage stop threshold is calculated as 6.48 V.

Enable (ENA) and Internal Slow Start

The TPS5435x has an internal digital slow start that ramps the reference voltage to its final value in 1150 switching cycles. The internal slow start time (10% – 90%) is approximated by the following expression:

$$T_{SS_INTERNAL}(ms) = \frac{1.15k}{f_S(kHz) \times n} \quad (3)$$

Use n in Table 2

Table 2. Slow Start Characteristics

DEVICE	n
TPS54352	1.485
TPS54353	1.2
TPS54354	1
TPS54355	1.084
TPS54356	0.818
TPS54357	0.900

Once the TPS5435x device is in normal regulation, the ENA pin is high. If the ENA pin is pulled below the stop threshold of 0.5 V, switching stops and the internal slow start resets. If an application requires the TPS5435x to be disabled, use open drain or open collector output logic to interface to the ENA pin (see Figure 2). The ENA pin has an internal pullup current source. Do not use external pullup resistors.

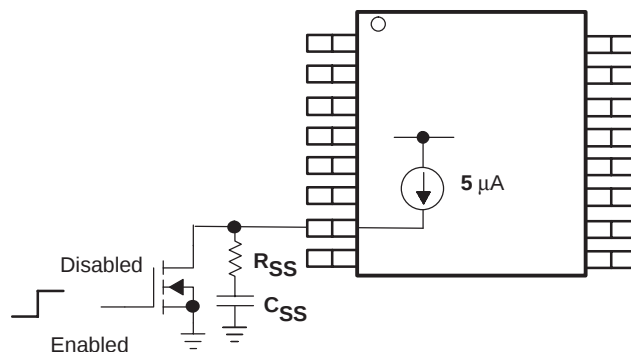


Figure 2. Interfacing to the ENA Pin

Extending Slow Start Time

In applications that use large values of output capacitance there may be a need to extend the slow start time to prevent the startup current from tripping the current limit. The current limit circuit is designed to disable the high side MOSFET and reset the internal voltage reference for a short amount of time when the high side MOSFET current exceeds the current limit threshold. If the output capacitance and load current cause the startup current to exceed the current limit threshold, the power supply output will not reach the desired output voltage. To extend the slow start time and to reduce the startup current, an external resistor and capacitor can be added to the ENA pin. The slow start capacitance is calculated using the following equation:

$$C_{SS}(\mu F) = 5.55 \times 10^{-3} \times n \times T_{SS}(ms) \quad (4)$$

Use n in Table 2

The R_{SS} resistor must be 2 kΩ and the slow start capacitor must be less than 0.47 μF.

Switching Frequency (RT)

The TPS5435x has an internal oscillator that operates at twice the PWM switching frequency. The internal oscillator frequency is controlled by the RT pin. Grounding the RT pin sets the PWM switching frequency to a default frequency of 250 kHz. Floating the RT pin sets the PWM switching frequency to 500 kHz.

Connecting a resistor from RT to AGND sets the frequency according to the following equation (also see Figure 30).

$$RT(k\Omega) = \frac{46000}{f_S(kHz) - 35.9} \quad (5)$$

The RT pin controls the SYNC pin functions. If the RT pin is floating or grounded, SYNC is an output. If the switching frequency has been programmed using a resistor from RT to AGND, then SYNC functions as an input.

The internal voltage ramp charging current increases linearly with the set frequency and keeps the feed forward modulator constant (K_m = 8) regardless of the frequency set point.

Table 3.

SWITCHING FREQUENCY	SYNC PIN	RT PIN
250 kHz, internally set	Generates SYNC output signal	AGND
500 kHz, internally set	Generates SYNC output signal	Float
Externally set to 250 kHz to 700 kHz	Terminate to quiet ground with 10-k Ω resistor.	R = 215 k Ω to 69 k Ω
Externally synchronized frequency	Synchronization Signal	Set RT resistor equal to 90% to 110% of external synchronization frequency. When using a dual setup (see Figure 27 for example), if the <i>master</i> 35x device RT pin is left floating, use a 110 k Ω resistor to tie the <i>slave</i> RT pin to ground. Conversely, if the <i>master</i> 35x device RT pin is grounded, use a 237 k Ω resistor to tie the <i>slave</i> RT pin to ground.

180° Out of Phase Synchronization (SYNC)

The SYNC pin is configurable as an input or as an output, per the description in the previous section. When operating as an input, the SYNC pin is a falling-edge triggered signal (see Figures 3, 4, and 19). When operating as an output, the signal's falling edge is approximately 180° out of phase with the rising edge of the PH pins. Thus, two TPS5435x devices operating in a system can share an input capacitor and draw ripple current at twice the frequency of a single unit.

When operating the two TPS5435x devices 180° out of phase, the total RMS input current is reduced. Thus reducing the amount of input capacitance needed and increasing efficiency.

When synchronizing a TPS5435x to an external signal, the timing resistor on the RT pin must be set so that the oscillator is programmed to run at 90% to 110% of the synchronization frequency.

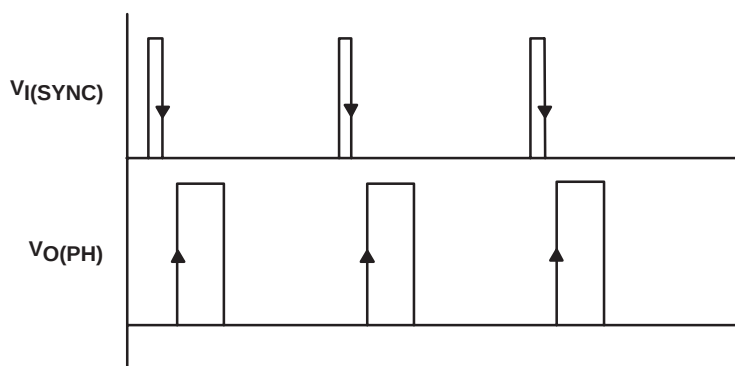


Figure 3. SYNC Input Waveform

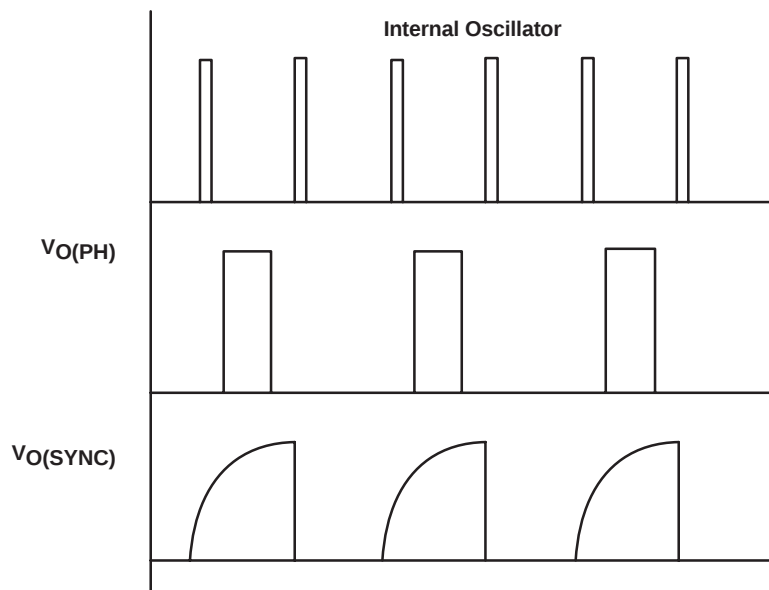


Figure 4. SYNC Output Waveform

Power Good (PWRGD)

The VSENSE pin is compared to an internal reference signal, if the VSENSE is greater than 97% and no other faults are present, the PWRGD pin presents a high impedance. A low on the PWRGD pin indicates a fault. The PWRGD pin has been designed to provide a weak pull-down and indicates a fault even when the device is unpowered. If the TPS5435x has power and has any fault flag set, the TPS5435x indicates the power is not good by driving the PWRGD pin low. The following events, singly or in combination, indicate power is not good:

- VSENSE pin out of bounds
- Overcurrent
- Thermal shutdown
- UVLO undervoltage
- Input voltage not present (weak pull-down)
- Slow-starting
- VBIAS voltage is low

Once the PWRGD pin presents a high impedance (i.e., power is good), a VSENSE pin out of bounds condition forces PWRGD pin low (i.e., power is bad) after a time delay. This time delay is a function of the switching frequency and is calculated using equation 6:

$$T_{\text{delay}} = \frac{1000}{f_S(\text{kHz})} \text{ ms} \quad (6)$$

Bias Voltage (VBIAS)

The VBIAS regulator provides a stable supply for the internal analog circuits and the low side gate driver. Up to 1 mA of current can be drawn for use in an external application circuit. The VBIAS pin must have a bypass

capacitor value of 1.0 μF . X7R or X5R grade dielectric ceramic capacitors are recommended because of their stable characteristics over temperature.

Bootstrap Voltage (BOOT)

The BOOT capacitor obtains its charge cycle by cycle from the VBIAS capacitor. A capacitor from the BOOT pin to the PH pins is required for operation. The bootstrap connection for the high side driver must have a bypass capacitor of 0.1 μF .

Error Amplifier

The VSENSE pin is the error amplifier inverting input. The error amplifier is a true voltage amplifier with 1.5 mA of drive capability with a minimum of 60 dB of open loop voltage gain and a unity gain bandwidth of 2 MHz.

Voltage Reference

The voltage reference system produces a precision reference signal by scaling the output of a temperature stable bandgap circuit. During production testing, the bandgap and scaling circuits are trimmed to produce 0.891 V at the output of the error amplifier, with the amplifier connected as a voltage follower. The trim procedure improves the regulation, since it cancels offset errors in the scaling and error amplifier circuits.

PWM Control and Feed Forward

Signals from the error amplifier output, oscillator, and current limit circuit are processed by the PWM control logic. Referring to the internal block diagram, the control logic includes the PWM comparator, PWM latch, and the adaptive dead-time control logic. During steady-state operation below the current limit threshold, the PWM comparator output and oscillator pulse train alternately reset and set the PWM latch.

Once the PWM latch is reset, the low-side driver and integrated pull-down MOSFET remain on for a minimum duration set by the oscillator pulse width. During this period, the PWM ramp discharges rapidly to the valley voltage. When the ramp begins to charge back up, the low-side driver turns off and the high-side FET turns on. The peak PWM ramp voltage varies inversely with input voltage to maintain a constant modulator and power stage gain of 8 V/V.

As the PWM ramp voltage exceeds the error amplifier output voltage, the PWM comparator resets the latch, thus turning off the high-side FET and turning on the low-side FET. The low-side driver remains on until the next oscillator pulse discharges the PWM ramp.

During transient conditions, the error amplifier output can be below the PWM ramp valley voltage or above the PWM peak voltage. If the error amplifier is high, the PWM latch is never reset and the high-side FET remains on until the oscillator pulse signals the control logic to turn the high-side FET off and the internal low-side FET and driver on. The device operates at its maximum duty cycle until the output voltage rises to the regulation set point, setting VSENSE to approximately the same voltage as the internal voltage reference. If the error amplifier output is low, the PWM latch is continually reset and the high-side FET does not turn on. The internal low-side FET and low side driver remain on until the VSENSE voltage decreases to a range that allows the PWM comparator to change states. The TPS5435x is capable of sinking current through the external low side FET until the output voltage reaches the regulation set point.

The minimum on time is designed to be 180 ns. During the internal slow-start interval, the internal reference ramps from 0 V to 0.891 V. During the initial slow-start interval, the internal reference voltage is very small resulting in a couple of skipped pulses because the minimum on time causes the actual output voltage to be slightly greater than the preset output voltage until the internal reference ramps up.

Deadtime Control

Adaptive dead time control prevents shoot through current from flowing in the integrated high-side MOSFET and the external low-side MOSFET during the switching transitions by actively controlling the turn on times of the drivers. The high-side driver does not turn on until the voltage at the gate of the low-side MOSFET is below 1 V. The low-side driver does not turn on until the voltage at the gate of the high-side MOSFET is below 1 V.

Low Side Gate Driver (LSG)

LSG is the output of the low-side gate driver. The 100-mA MOSFET driver is capable of providing gate drive for most popular MOSFETs suitable for this application. Use the SWIFT Designer Software Tool to find the most appropriate MOSFET for the application. Connect the LSG pin directly to the gate of the low-side MOSFET. Do not use a gate resistor as the resulting turn-on time may be too slow.

Integrated Pulldown MOSFET

The TPS5435x has a diode-MOSFET pair from PH to PGND. The integrated MOSFET is designed for light-load continuous-conduction mode operation when only an external Schottky diode is used. The combination of devices keeps the inductor current continuous under conditions where the load current drops below the inductor's critical current. Care should be taken in the selection of inductor in applications using only a low-side Schottky diode. Since the inductor ripple current flows through the integrated low-side MOSFET at light loads, the inductance value should be selected to limit the peak current to less than 0.3 A during the high-side FET turn off time. The minimum value of inductance is calculated using the following equation:

$$L(H) = \frac{VO \times \left(1 - \frac{VO}{VI}\right)}{f_S \times 0.6} \quad (7)$$

Thermal Shutdown

The device uses the thermal shutdown to turn off the MOSFET drivers and controller if the junction temperature exceeds 165°C. The device is restarted automatically when the junction temperature decreases to 7°C below the thermal shutdown trip point and starts up under control of the slow-start circuit.

Overcurrent Protection

Overcurrent protection is implemented by sensing the drain-to-source voltage across the high-side MOSFET and compared to a voltage level which represents the overcurrent threshold limit. If the drain-to-source voltage exceeds the overcurrent threshold limit for more than 100 ns, the ENA pin is pulled low, the high-side MOSFET is disabled, and the internal digital slow-start is reset to 0 V. ENA is held low for approximately the time that is calculated by the following equation:

$$T_{HICCUP}(ms) = \frac{2250}{f_S(kHz)} \quad (8)$$

Once the hiccup time is complete, the ENA pin is released and the converter initiates the internal slow-start.

Switching Frequency Limitations

Due to the internal design of the TPS54352–6 there are limitations to the maximum usable switching frequency for any given input voltage. This limit is constrained by the minimum controllable on time which may be as high as 220 ns. Figure 31 shows the maximum switching frequency versus input voltage for each device. This family

of curves is valid for output currents greater than 0.5 A. As output currents decrease towards no load (0 A), the apparent on time increases, decreasing the maximum switching frequency that may be obtained for a given input and output voltage. Figure 32 shows the maximum switching frequency versus input voltage for each device for zero load current various operating frequencies.

TYPICAL CHARACTERISTICS

Conditions are $V_I = 12\text{ V}$, $V_O = 3.3\text{ V}$, $f_s = 500\text{ kHz}$, $I_O = 3\text{ A}$, $T_A = 25^\circ\text{C}$, unless otherwise noted

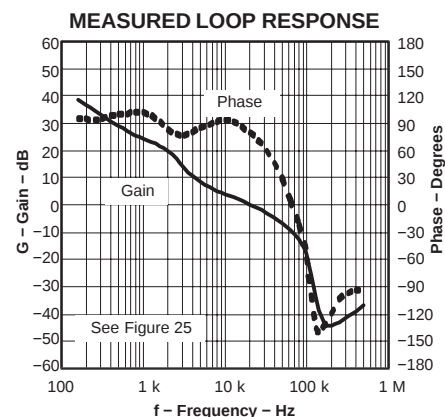


Figure 5

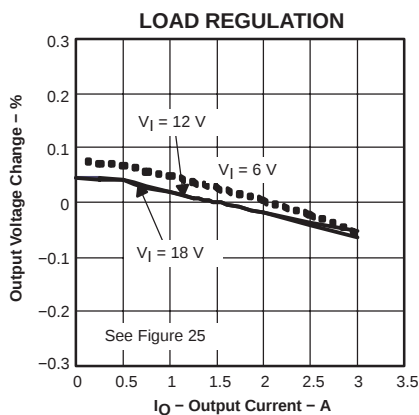


Figure 6

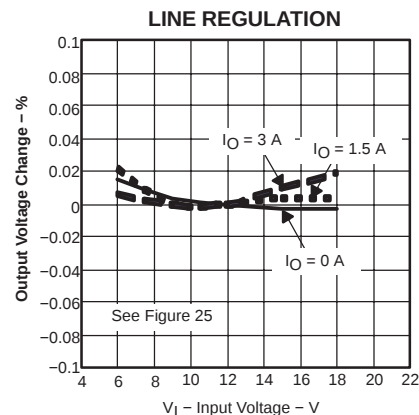


Figure 7

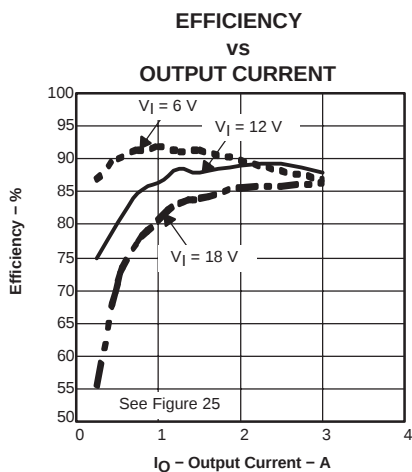


Figure 8

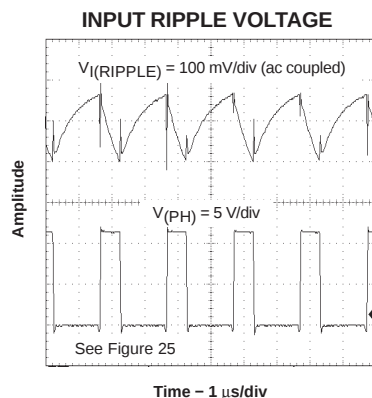


Figure 9

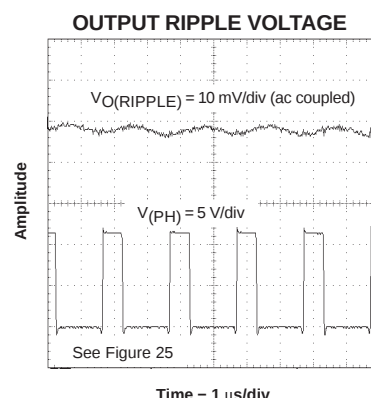


Figure 10

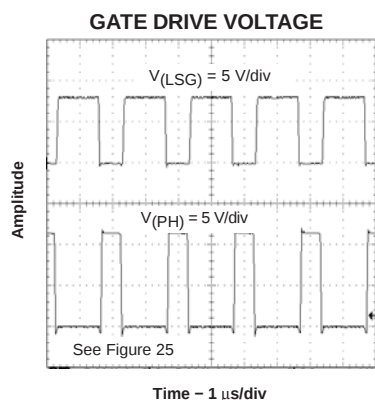


Figure 11

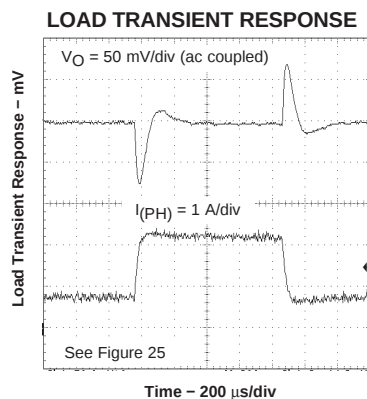


Figure 12

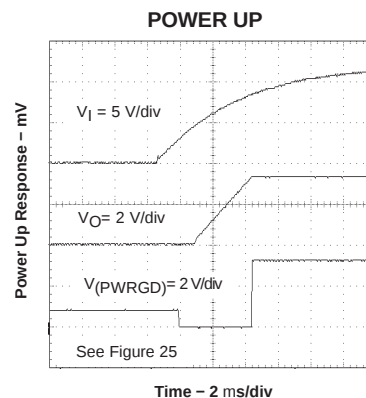


Figure 13

Conditions are $V_I = 12\text{ V}$, $V_O = 3.3\text{ V}$, $f_s = 500\text{ kHz}$, $I_O = 3\text{ A}$, $T_A = 25\text{ }^\circ\text{C}$, unless otherwise noted

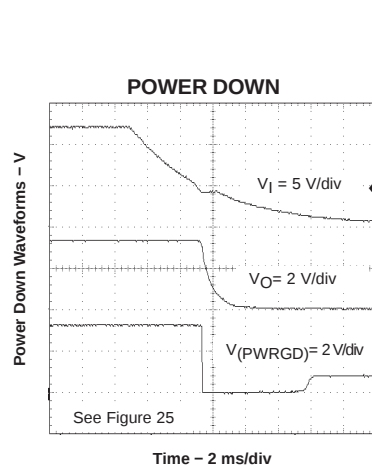


Figure 14

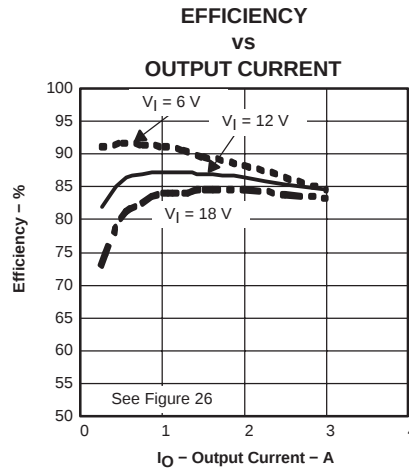


Figure 15

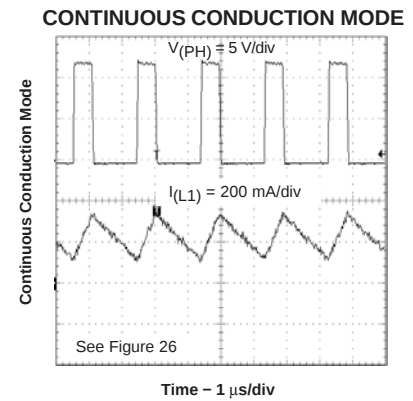


Figure 16

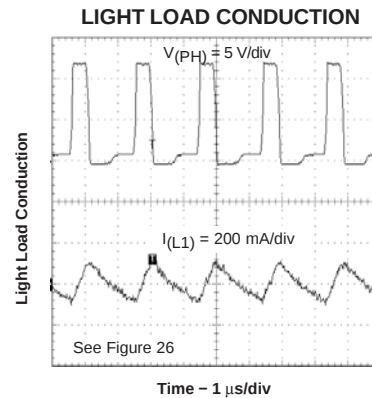


Figure 17

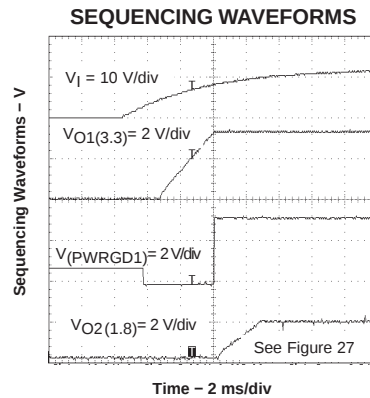


Figure 18

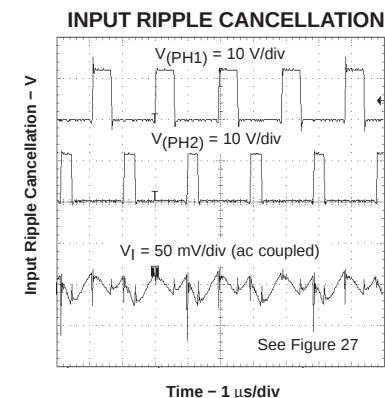


Figure 19

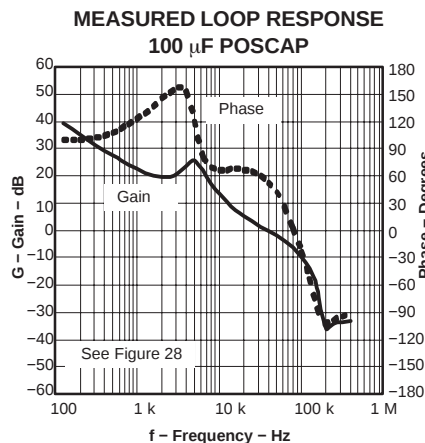


Figure 20

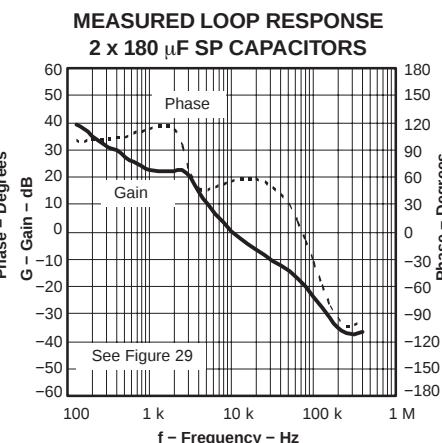


Figure 21

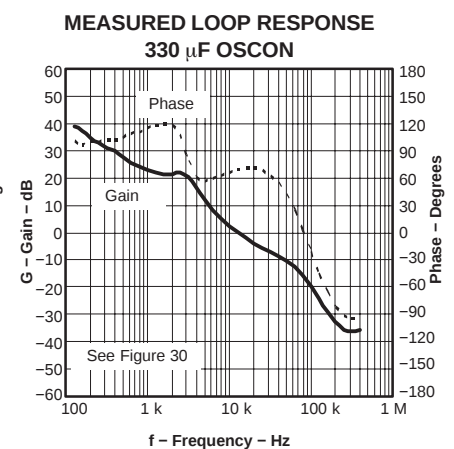


Figure 22

LAYOUT INFORMATION

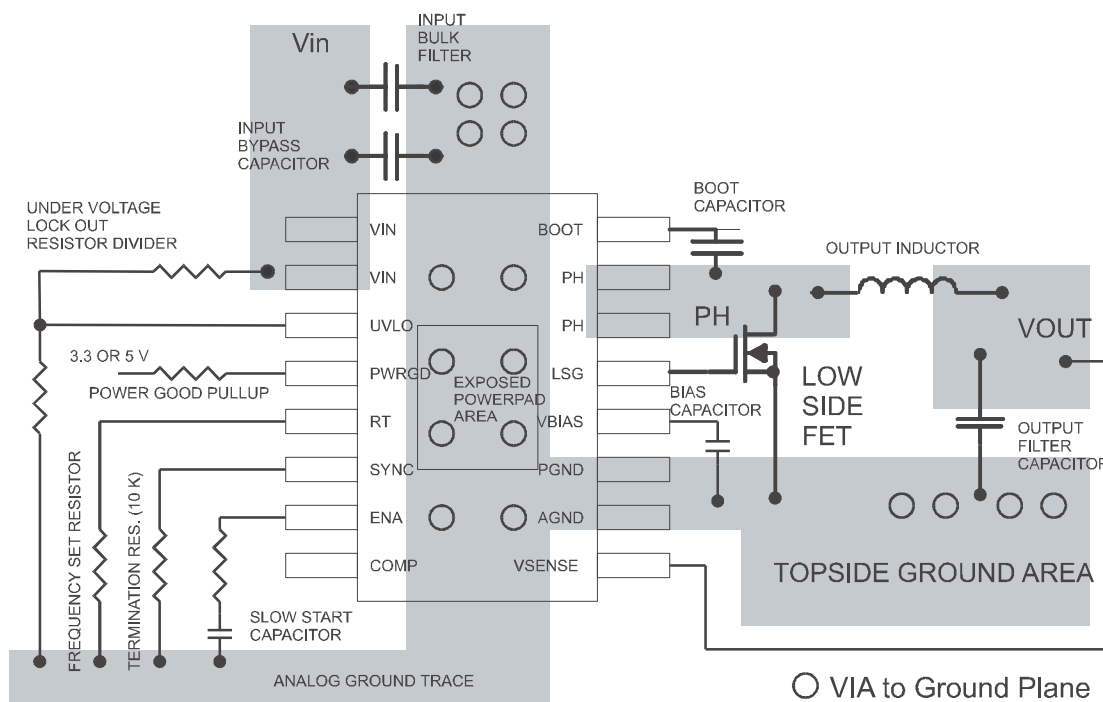


Figure 23. TPS5435x PCB Layout

PCB LAYOUT

The VIN pins should be connected together on the printed circuit board (PCB) and bypassed with a low ESR ceramic bypass capacitor. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the VIN pins, and the TPS5435x ground pins. The minimum recommended bypass capacitance is 10- μ F ceramic with a X5R or X7R dielectric and the optimum placement is closest to the VIN pins and the AGND and PGND pins. See Figure 23 for an example of a board layout. The AGND and PGND pins should be tied to the PCB ground plane at the pins of the IC. The source of the low-side MOSFET and the anode of the Schottky diode should be connected directly to the PCB ground plane. The PH pins should be tied together and routed to the drain of the low-side MOSFET or to the cathode of the external Schottky diode. Since the PH connection is the switching node, the MOSFET (or diode) should be located very close to the PH pins, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. The recommended conductor width from pins 14 and 15 is 0.050 inch to 0.075 inch of 1-ounce

copper. The length of the copper land pattern should be no more than 0.2 inch.

For operation at full rated load, the analog ground plane must provide adequate heat dissipating area. A 3-inch by 3-inch plane of copper is recommended, though not mandatory, dependent on ambient temperature and airflow. Most applications have larger areas of internal ground plane available, and the PowerPAD should be connected to the largest area available. Additional areas on the bottom or top layers also help dissipate heat, and any area available should be used when 3 A or greater operation is desired. Connection from the exposed area of the PowerPAD to the analog ground plane layer should be made using 0.013-inch diameter vias to avoid solder wicking through the vias. Four vias should be in the PowerPAD area with four additional vias outside the pad area and underneath the package. Additional vias beyond those recommended to enhance thermal performance should be included in areas not under the device package.

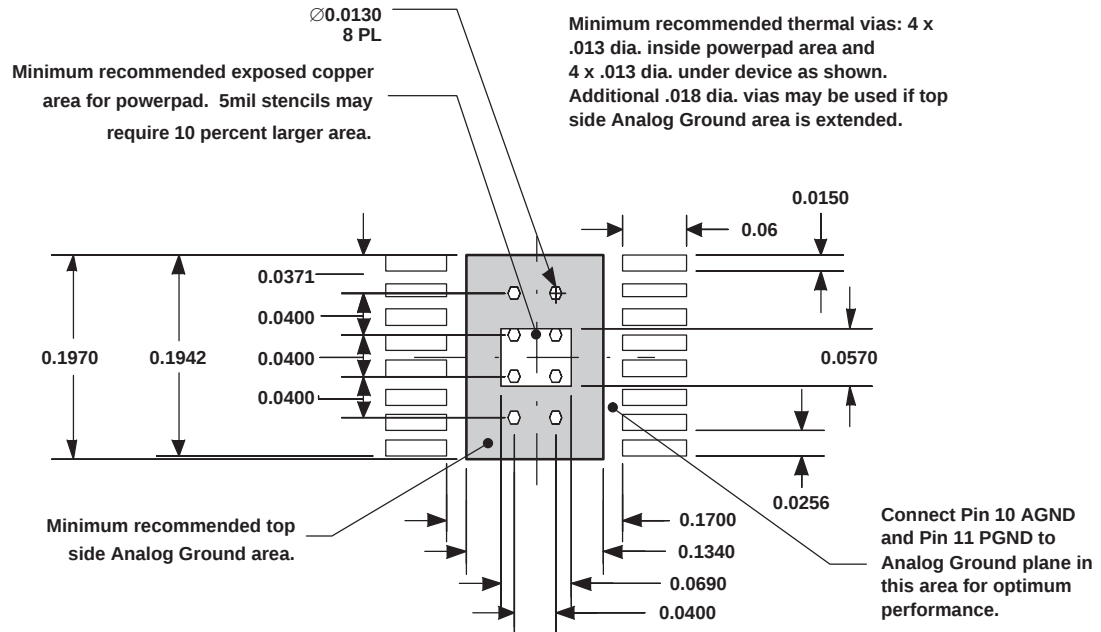


Figure 24. Thermal Considerations for PowerPAD Layout

APPLICATION INFORMATION

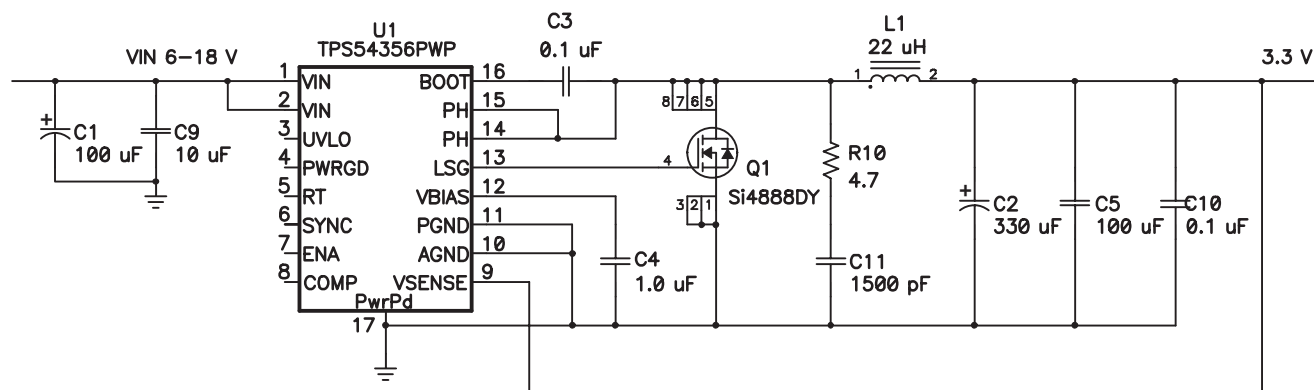


Figure 25. Application Circuit, 12 V to 3.3 V

Figure 25 shows the schematic for a typical TPS54356 application. The TPS54356 can provide up to 3-A output current at a nominal output voltage of 3.3 V. For proper thermal performance, the exposed PowerPAD underneath the device must be soldered down to the printed circuit board.

DESIGN PROCEDURE

The following design procedure can be used to select component values for the TPS54356. Alternately, the SWIFT Designer Software may be used to generate a complete design. The SWIFT Designer Software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. This section presents a simplified discussion of the design process.

To begin the design process a few parameters must be decided upon. The designer needs to know the following:

- Input voltage range
- Output voltage
- Input ripple voltage
- Output ripple voltage
- Output current rating
- Operating frequency

For this design example, use the following as the input parameters:

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage range	6 V to 18 V
Output voltage	3.3 V
Input ripple voltage	300 mV
Output ripple voltage	10 mV
Output current rating	3 A
Operating frequency	500 kHz

SWITCHING FREQUENCY

The switching frequency is set using the RT pin. Grounding the RT pin sets the PWM switching frequency to a default frequency of 250 kHz. Floating the RT pin sets the PWM switching frequency to 500 kHz. By connecting a resistor from RT to AGND, any frequency in the range of 250 kHz to 700 kHz can be set. Use equation 9 to determine the proper value of RT.

$$RT(k\Omega) = \frac{46000}{f_S(kHz) - 35.9} \quad (9)$$

In this example circuit, RT is not connected and the switching frequency is set at 500 kHz.

INPUT CAPACITORS

The TPS54356 requires an input decoupling capacitor and, depending on the application, a bulk input capacitor. The minimum value for the decoupling capacitor, C9, is 10µF. A high quality ceramic type X5R or X7R is recommended. The voltage rating should be greater than the maximum input voltage. Additionally some bulk capacitance may be needed, especially if the TPS54356 circuit is not located within about 2 inches from the input voltage source. The value for this capacitor is not critical but it also should be rated to handle the maximum input voltage including ripple voltage and should filter the output so that input ripple voltage is acceptable.

This input ripple voltage can be approximated by equation 10:

$$\Delta V_{IN} = \frac{I_{OUT(MAX)} \times 0.25}{C_{BULK} \times f_{sw}} + (I_{OUT(MAX)} \times ESR_{MAX}) \quad (10)$$

Where $I_{OUT(MAX)}$ is the maximum load current, f_{sw} is the switching frequency, C_{BULK} is the bulk capacitor value and ESR_{MAX} is the maximum series resistance of the bulk capacitor.

The maximum RMS ripple current also needs to be checked. For worst case conditions, this can be approximated by equation 11:

$$I_{CIN} = \frac{I_{OUT(MAX)}}{2} \quad (11)$$

In this case the input ripple voltage would be 140 mV and the RMS ripple current would be 1.5 A. The maximum voltage across the input capacitors would be $V_{IN\ max}$ plus $\Delta V_{IN}/2$. The chosen bulk and bypass capacitors are each rated for 25 V and the combined ripple current capacity is greater than 3 A, both providing ample margin. It is very important that the maximum ratings for voltage and current are not exceeded under any circumstance.

OUTPUT FILTER COMPONENTS

Inductor Selection

To calculate the minimum value of the output inductor, use equation 12:

$$L_{(MIN)} = \frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times K_{IND} \times I_{OUT} \times f_{sw}} \quad (12)$$

K_{IND} is a coefficient that represents the amount of inductor ripple current relative to the maximum output current. For designs using low ESR output capacitors such as ceramics, use $K_{IND} = 0.3$. When using higher ESR output capacitors, $K_{IND} = 0.2$ yields better results.

For this design example use $K_{IND} = 0.1$ to keep the inductor ripple current small. The minimum inductor value is calculated to be 17.96 µH. The next highest standard value is 22 µH, which is used in this design.

For the output filter inductor it is important that the RMS current and saturation current ratings not be exceeded. The RMS inductor current can be found from equation 13:

$$I_{L(RMS)} = \sqrt{I_{OUT(MAX)}^2 + \frac{1}{12} \times \left(\frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times L_{OUT} \times f_{sw} \times 0.8} \right)^2} \quad (13)$$

and the peak inductor current can be determined with equation 14:

$$I_{L(PK)} = I_{OUT(MAX)} + \frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{1.6 \times V_{IN(MAX)} \times L_{OUT} \times f_{sw}} \quad (14)$$

For this design, the RMS inductor current is 3.007 A and the peak inductor current is 3.15 A. The chosen inductor is a Coiltronics DR127-220 22 µH. It has a saturation current rating of 7.57 A and a RMS current rating of 4 A, easily meeting these requirements. A lesser rated inductor could be used if less margin is desired. In general, inductor values for use with the TPS54356 are in the range of 6.8 µH to 47 µH.

Capacitor Requirements

The important design factors for the output capacitor are dc voltage rating, ripple current rating, and equivalent series resistance (ESR). The dc voltage and ripple current ratings cannot be exceeded. The ESR is important because along with the inductor current it determines the amount of output ripple voltage. The actual value of the output capacitor is not critical, but some practical limits do exist.

Consider the relationship between the desired closed loop crossover frequency of the design and LC corner frequency of the output filter. In general, it is desirable to keep the closed loop crossover frequency at less than 1/5 of the switching frequency. With high switching frequencies such as the 500-kHz frequency of this design, internal circuit limitations of the TPS54356 limit the practical maximum crossover frequency to about 70 kHz. Additionally, the capacitor type and value must be chosen to work with the internal compensation network of the TPS5435x family of dc/dc converters. To allow for adequate phase gain in the compensation network, the LC corner frequency should be about one decade or so below the closed loop crossover frequency. This limits the minimum capacitor value for the output filter to:

$$C_{OUT(MIN)} = \frac{1}{L_{OUT}} \times \left(\frac{K}{2\pi f_{CO}} \right)^2 \quad (15)$$

Where K is the frequency multiplier for the spread between f_{LC} and f_{CO} . K should be between 5 and 15, typically 10 for one decade difference. For a desired crossover of 20 kHz and a 22- μ H inductor, the minimum value for the output capacitor is 288 μ F. The selected output capacitor must be rated for a voltage greater than the desired output voltage plus one half the ripple voltage. Any derating amount must also be included. The maximum RMS ripple current in the output capacitor is given by equation 16:

$$I_{COUT(RMS)} = \frac{1}{\sqrt{12}} \times \left[\frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times L_{OUT} \times f_{sw}} \right] \quad (16)$$

The calculated RMS ripple current is 156 mA in the output capacitors.

CHOOSING CAPACITOR VALUE

For this design example, a relatively large aluminum electrolytic capacitor is combined with a smaller value ceramic capacitor. This combination provides a stable high performance design at a relatively low cost. Also, by carefully choosing the capacitor values and ESRs, the design can be tailored to complement the internal compensation poles and zeros of the TPS54356.

These preconfigured poles and zeroes internal to the TPS54356 limit the range of output filter configurations. A variety of capacitor values and types of dielectric are supported. There are a number of different ways to calculate the output filter capacitor value and ESR to work with the internal compensation network. This procedure outlines a relatively simple procedure that produces good results with an output filter consisting of a high ESR dielectric capacitor in parallel with a low ESR ceramic capacitor. Use of the SWIFT Designer Software for designs with unusually high closed loop crossover frequencies, low value, low ESR output capacitors such as ceramics or if the designer is unsure about the design procedure.

The TPS54356 contains a compensation network with the following nominal characteristics:

$$f_{INT} = 1.7 \text{ kHz}$$

$$f_{Z1} = 2.5 \text{ kHz}$$

$$f_{Z2} = 4.8 \text{ kHz}$$

$$f_{P1} = 95 \text{ kHz}$$

$$f_{P2} = 125 \text{ kHz}$$

For a stable design, the closed loop crossover frequency should be set less than one fifth of the switching frequency, and the phase margin at crossover must be greater than 45 degrees. The general procedure outlined here produces results consistent with these requirements without going into great detail about the theory of loop compensation.

In this case, the output filter LC corner frequency should be selected to be near the first compensation zero frequency as described by equation 17:

$$f_{LC} = \frac{1}{2\pi \sqrt{L_{OUT} C2}} \cong f_{Z1} \quad (17)$$

Placement of the LC corner frequency at f_{Z1} is not critical, it only needs to be close. For the design example, $f_{LC} = 2$ kHz.

Solving for C2 using equation 18:

$$C2 \cong \frac{1}{4\pi^2 f^2 Z1 L_{OUT}} \quad (18)$$

The desired value for C2 is calculated as 184 μ F. A close standard value of 330 μ F is chosen with a resulting LC corner frequency of 1.9 kHz. As to be shown, this value is not critical as long as it results in a corner frequency in the vicinity of f_{Z1} .

Next, when using a large ceramic capacitor in parallel with a high ESR electrolytic capacitor, there is a pole in the output filter that should be at f_{Z2} as shown in equation 19:

$$f_{P(ESR)} = \frac{1}{2\pi R_{(C2ESR)} C5} = f_{Z2} \quad (19)$$

Now the actual C2 capacitor must be selected based on the ESR and the value of capacitor C5 so that the above equation is satisfied. In this example, the $R_{(C2ESR)} C5$ product should be 3.18×10^{-5} . From the available capacitors, by choosing a Panasonic EEVFKOJ331XP aluminum electrolytic capacitor with a nominal ESR of 0.34 Ω yields a calculated value for C5 of 98 μ F. The closest standard value is 100 μ F. As the actual ESR of the capacitor can vary by a large amount, this value also is not critical.

The closed loop crossover frequency should be greater than f_{LC} and less than one fifth of the switching frequency. Also, the crossover frequency should not exceed 70 kHz, as the error amplifier may not provide the desired gain. As stated previously, closed loop crossover frequencies between 5 and 15 times f_{LC} work well. For this design, the crossover frequency can be estimated by:

$$f_{CO} = 1.125 \times 10^{-3} \times f_{P(ESR)} \times f_{LC} \quad (20)$$

This simplified equation is valid for this design because the output filter capacitors are mixed technology. Compare this result to the actual measured loop response plot of

Figure 5. The measured closed loop crossover frequency of 19.95 kHz differs from the calculated value because the actual output filter capacitor component parameters differed slightly from the specified data sheet values.

CAPACITOR ESR AND OUTPUT RIPPLE

The amount of output ripple voltage as specified in the initial design parameters is determined by the maximum ESR of the output capacitor and the input ripple current. The output ripple voltage is the inductor ripple current times the ESR of the output filter so the maximum specified ESR as listed in the capacitor data sheet is given by equation 21:

$$ESR_{(MAX)} = \left(\frac{V_{IN(MAX)} \times L_{OUT} \times f_{sw} \times 0.8}{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})} \right) \times \Delta V_{p-p(MAX)} \quad (21)$$

and the maximum ESR required is 33 mΩ. In this design, the aluminum electrolytic capacitor has an ESR of 0.340 mΩ, but it is in parallel with an ultra low ESR ceramic capacitor of 2 mΩ maximum. The measured output ripple voltage for this design is approximately 4 mV_{p-p} as shown in Figure 10.

BIAS AND BOOTSTRAP CAPACITORS

Every TPS54356 design requires a bootstrap capacitor, C3 and a bias capacitor, C4. The bootstrap capacitor must be 0.1 μF. The bootstrap capacitor is located between the PH pins and BOOT pin. The bias capacitor is connected between the VBIAS pin and AGND. The value should be 1.0 μF. Both capacitors should be high quality ceramic types with X7R or X5R grade dielectric for temperature stability. They should be placed as close to the device connection pins as possible.

LOW-SIDE FET

The TPS54356 is designed to operate using an external low-side FET, and the LSG pin provides the gate drive output. Connect the drain to the PH pin, the source to PGND, and the gate to LSG. The TPS54356 gate drive circuitry is designed to accommodate most common n-channel FETs that are suitable for this application. The SWIFT Designer Software can be used to calculate all the design parameters for low-side FET selection. There are some simplified guidelines that can be applied that produce an acceptable solution in most designs.

The selected FET must meet the absolute maximum ratings for the application:

- **Drain-source voltage (V_{DSS}) must be higher than the maximum voltage at the PH pin, which is V_{INMAX} + 0.5 V.**
- **Gate-source voltage (V_{GSS}) must be greater than 8 V.**
- **Drain current (I_d) must be greater than 1.1 x I_{OUTMAX}.**
- **Drain-source on resistance (R_{DS(on)}) should be as small as possible, less than 30 mΩ is desirable. Lower values for R_{DS(on)} result in designs with higher efficiencies. It is important to note that the low-side FET on time is typically longer than the high-side FET on time, so attention paid to low-side FET parameters can make a marked improvement in overall efficiency.**
- **Total gate charge (Q_g) must be less than 50 nC. Again, lower Q_g characteristics result in higher efficiencies.**
- **Additionally, check that the device chosen is capable of dissipating the power losses.**

For this design, a Fairchild FDR6674A 30-V n-channel MOSFET is used as the low-side FET. This particular FET is specifically designed to be used as a low-side synchronous rectifier.

POWER GOOD

The TPS54356 is provided with a power good output pin PWRGD. This output is an open drain output and is intended to be pulled up to a 3.3-V or 5-V logic supply. A 10-kΩ, pull-up resistor works well in this application. The absolute maximum voltage is 6 V, so care must be taken not to connect this pull-up resistor to VIN if the maximum input voltage exceeds 6 V.

SNUBBER CIRCUIT

R10 and C11 of the application schematic in Figure 25 comprise a snubber circuit. The snubber is included to reduce over-shoot and ringing on the phase node when the internal high-side FET turns on. Since the frequency and amplitude of the ringing depends to a large degree on parasitic effects, it is best to choose these component values based on actual measurements of any design layout. See literature number SLVP100 for more detailed information on snubber design.

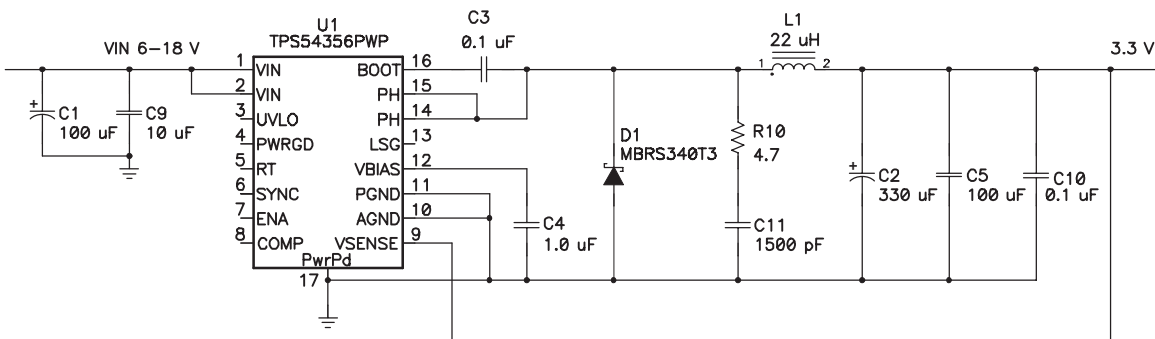


Figure 26. 3.3-V Power Supply With Schottky Diode

Figure 26 shows an application where a clamp diode is used in place of the low-side FET. The TPS54352-7 incorporates an integrated pull-down FET so that the circuit remains operating in continuous mode during light

load operation. A 3-A, 40-V Schottky diode such as the Motorola MBRS340T3 or equivalent is recommended. See Figures 15-17 for efficiency data and switching waveforms for this circuit.

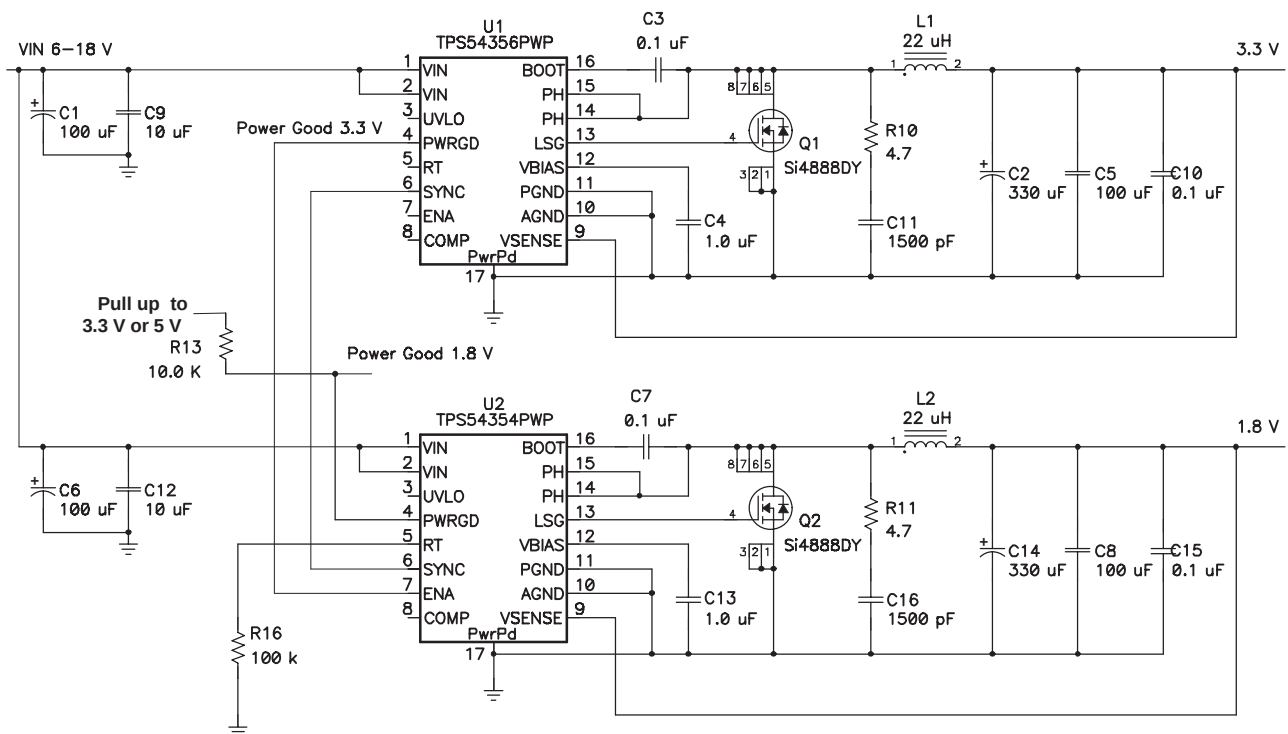


Figure 27. 3.3-V/1.8-V Power Supply with Sequencing

Figure 27 is an example of power supply sequencing using a TPS54356 (U1) to generate an output of 3.3 V, and a TPS54354 (U2) to generate a 1.8-V output. These output voltages are typical I/O and core voltages for microprocessors and FPGAs. In the circuit, the 3.3-V supply is designed to power up first.

The PWRGD pin of U1 is tied to the ENA pin of U2 so that the 1.8-V supply starts to ramp up after the 3.3-V supply is within regulation. Figure 18 shows these start up sequence waveforms.

Since the RT pin of U1 is floating, the SYNC pin is an output. This synchronization signal is fed the SYNC pin of U2. The RT pin of U2 has a 110-kΩ resistor to ground, and the SYNC pin for this device acts as an input. The 1.8-V supply operates synchronously with the 3.3-V supply and their switching node rising edges are approximately 180 degrees out of phase allowing for a reduction in the input voltage ripple. See Figure 19 for this wave form.

ALTERNATE OUTPUT FILTER DESIGNS

The previous design procedure example demonstrated a technique to design a 3.3-V power supply using both aluminum electrolytic and ceramic output filter capacitors. Other types of output filter capacitors are supported by the TPS5435x family of dc/dc converters. Figures 26–28 show designs using other popular capacitor types.

In Figure 28, the TPS54356 shown with a single 100-μF 6-V POSCAP as the output filter capacitor. C10 is a high frequency bypass capacitor and does not enter into the design equations. The design procedure is similar to the previous example except in the design of the output filter. In the previous example, the output filter LC corner was set at the first zero in the compensation network, while the second compensation zero was used to counteract the output filter pole caused by the interaction of the C2 capacitor ESR with C5. In this design example, the output LC corner frequency is to be set at the second zero frequency f_{z2} of the internal compensation network, approximately 5 kHz, while the first zero is used to provide phase boost prior to the LC corner frequency.

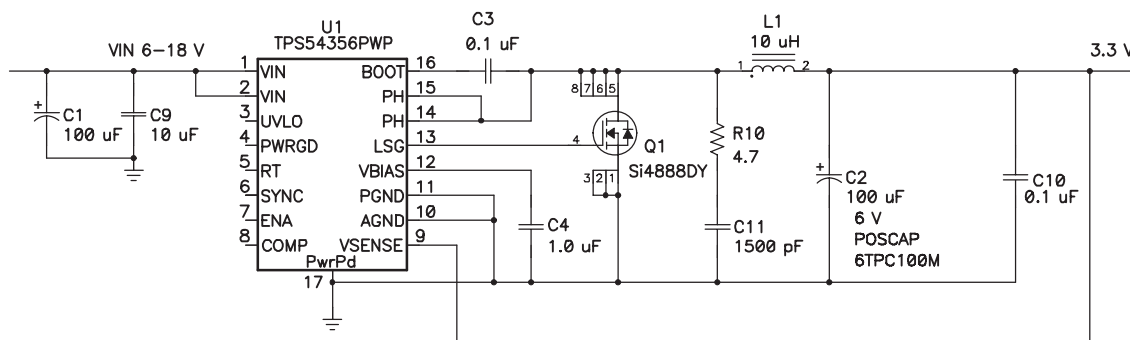


Figure 28. 3.3-V Power Supply with Sanyo POSCAP Output Filter Capacitor

Inductor Selection

Using equation 12 and a K_{IND} of 0.2, the minimum inductor value required is 8.98 μH. The closest standard value, 10 μH is selected. RMS and peak inductor currents are the same as calculated previously.

Capacitor Selection

With the inductor set at 10 μH and a desired corner frequency of 5 kHz, the output capacitor value is given by:

$$C2 = \frac{1}{4\pi^2 f_{z2}^2 L_{out}} = \frac{1}{4 \times \pi^2 \times 5000^2 \times 10^{-5}} = 101 \mu F$$

Use 100 μF as the closest standard value.

Calculating the RMS ripple current in the output capacitor using equation 16 yields 156 mA. The POSCAP 6TPC100M capacitor selected is rated for 1700 mA. See the closed loop response curve for this design in Figure 20.

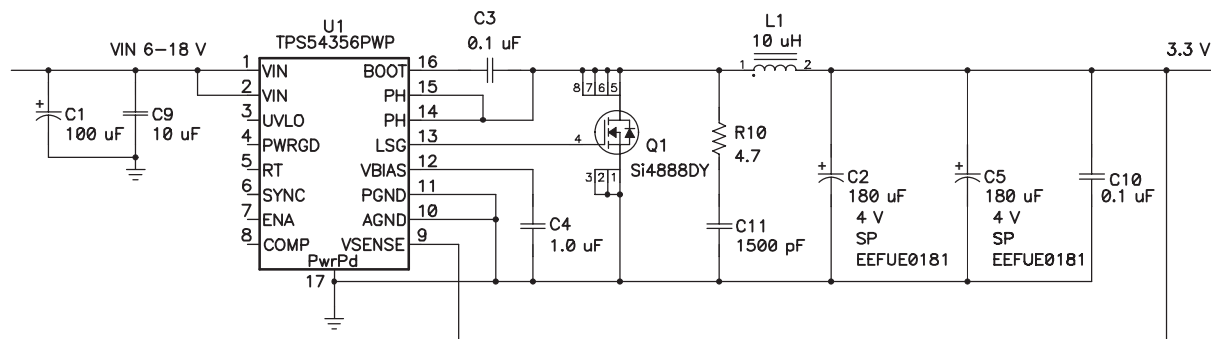


Figure 29. 3.3-V Power Supply with Panasonic SP Output Filter Capacitors

In Figure 29, the TPS54356 shown with two 180- μ F 4-V special polymer dielectric output filter capacitors (C2 and C5). C10 is a high frequency bypass capacitor and does not enter into the design equations. In the previous example, the output LC corner frequency is to be set at the second zero frequency f_{z2} of the internal compensation network, approximately 5 kHz, while the first zero is used to provide phase boost prior to the LC corner frequency. The special polymer electrolytic capacitors used in this design require that the closed loop crossover frequency be lowered due to the significantly lower ESR of this type of capacitor.

Inductor Selection

The inductor is the same 10- μ H value as the previous example.

Capacitor Selection

To lower the closed loop crossover it is necessary to reduce the LC corner frequency below 5 kHz. Using a target value of 2500 Hz, the output capacitor value is given by:

$$C2 = \frac{1}{4\pi^2 f_{z2}^2 L_{out}} = \frac{1}{4 \times \pi^2 \times 2500^2 \times 10^{-5}} = 405 \mu F$$

Use 2 x 180 μ F = 360 μ F as a combination of standard values that is close to 405 μ F.

The RMS ripple current in the output capacitor is the same as before. The selected capacitors are each 3.3 A. See the closed loop response curve for this design in Figure 21.

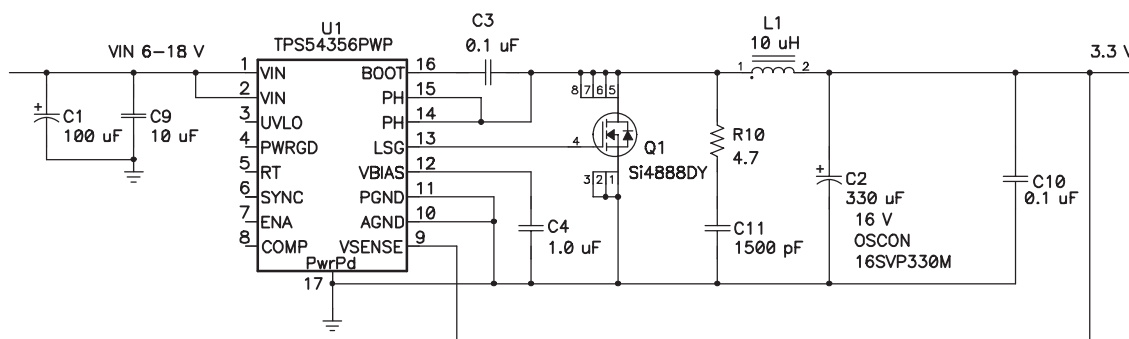


Figure 30. 3.3-V Power Supply with Sanyo OSCON Output Filter Capacitor

In Figure 30, the TPS54356 shown with a Sanyo OSCON output filter capacitor (C2). C10 is a high frequency bypass capacitor and does not enter into the design equations. This design is identical to the previous example except that a single OSCON capacitor of 330 μ F is used for the calculated value of 405 μ F. Compare the closed loop response for this design in Figure 22 to the closed loop response in Figure 21. Note that there is only a slight

difference in the response and the general similarity in both the gain and phase plots. This is the expected result for these two similar output filters.

Many other additional output filter designs are possible. Use the SWIFT Designer Software to generate other designs or follow the general design procedures illustrated in this application section.

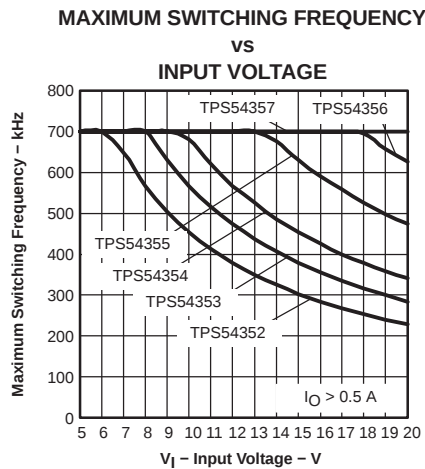


Figure 31

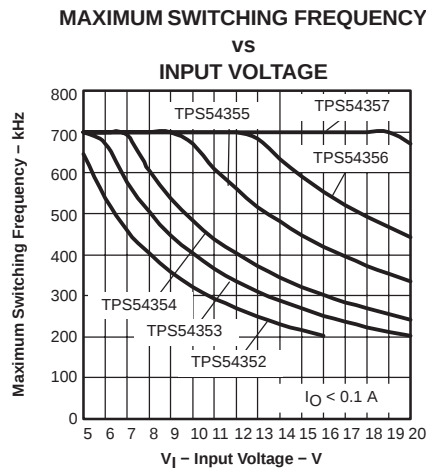


Figure 32

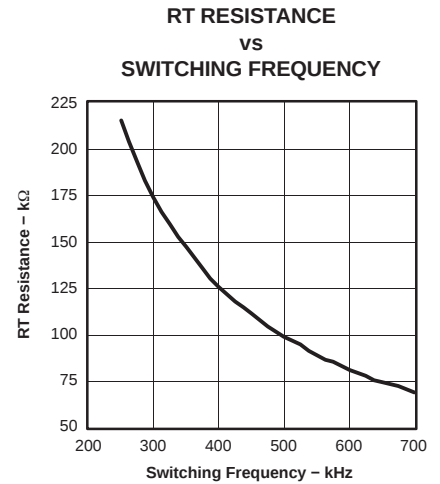


Figure 33

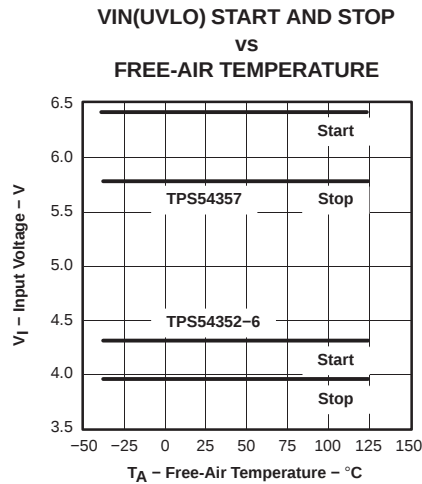


Figure 34

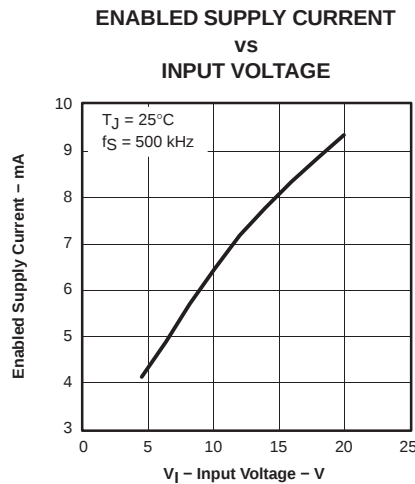


Figure 35

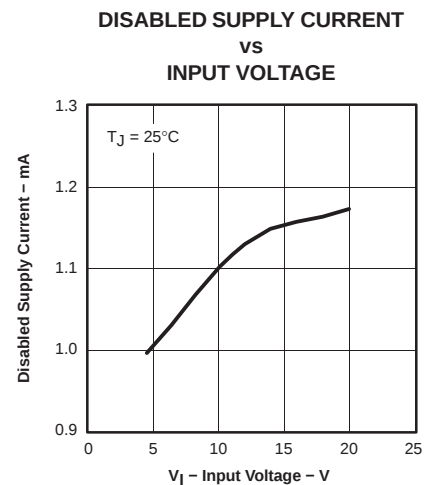


Figure 36

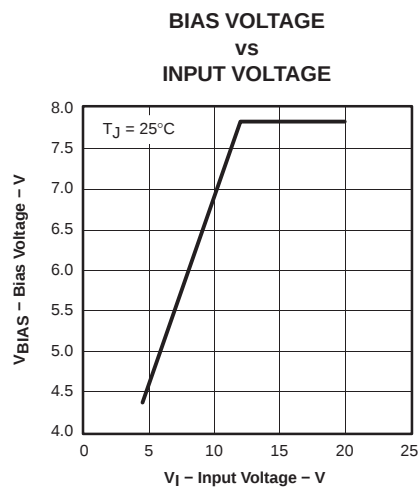


Figure 37

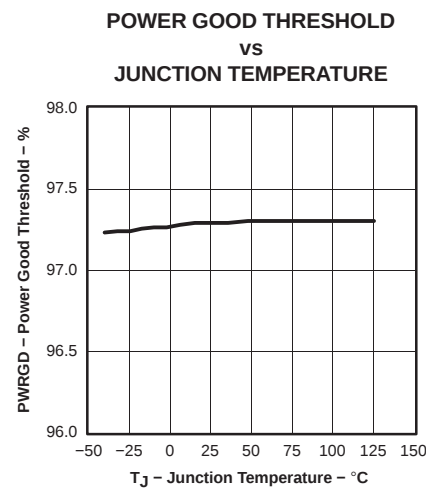


Figure 38

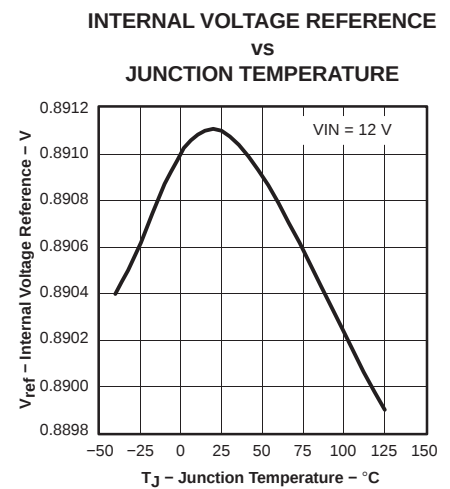


Figure 39

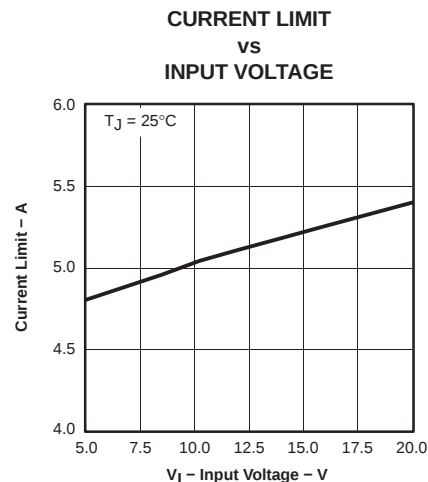


Figure 40

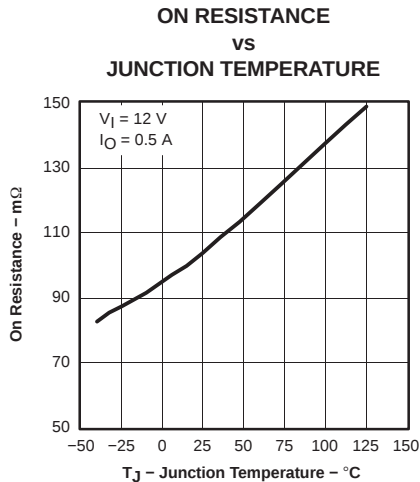


Figure 41

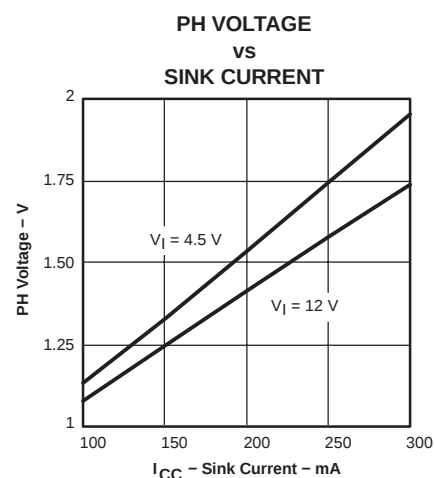


Figure 42

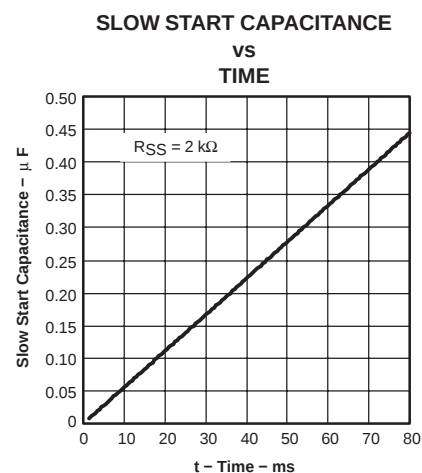


Figure 43

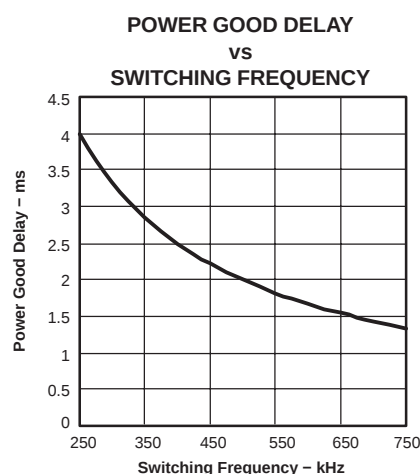


Figure 44

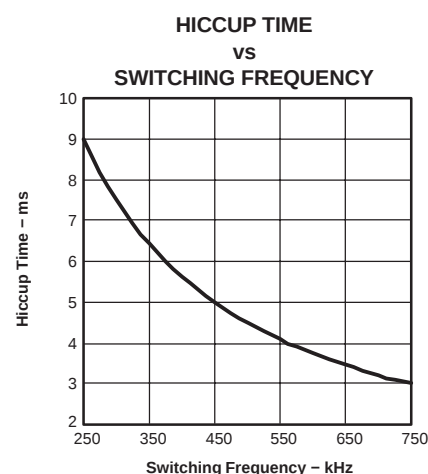


Figure 45

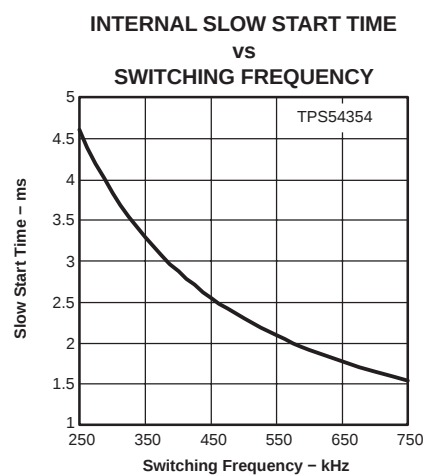


Figure 46

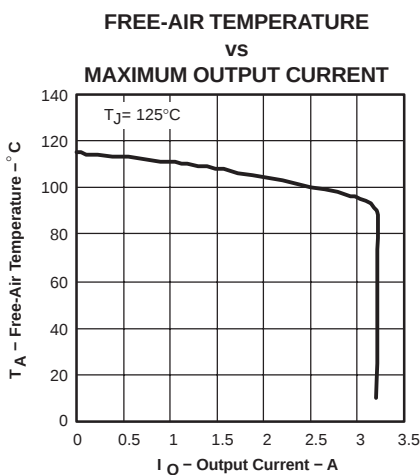


Figure 47

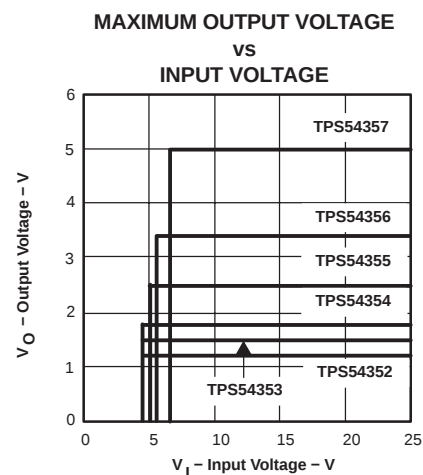


Figure 48

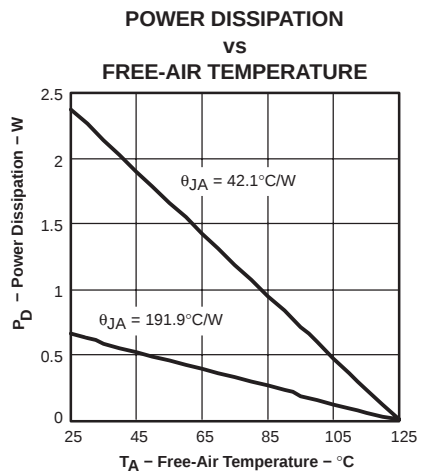
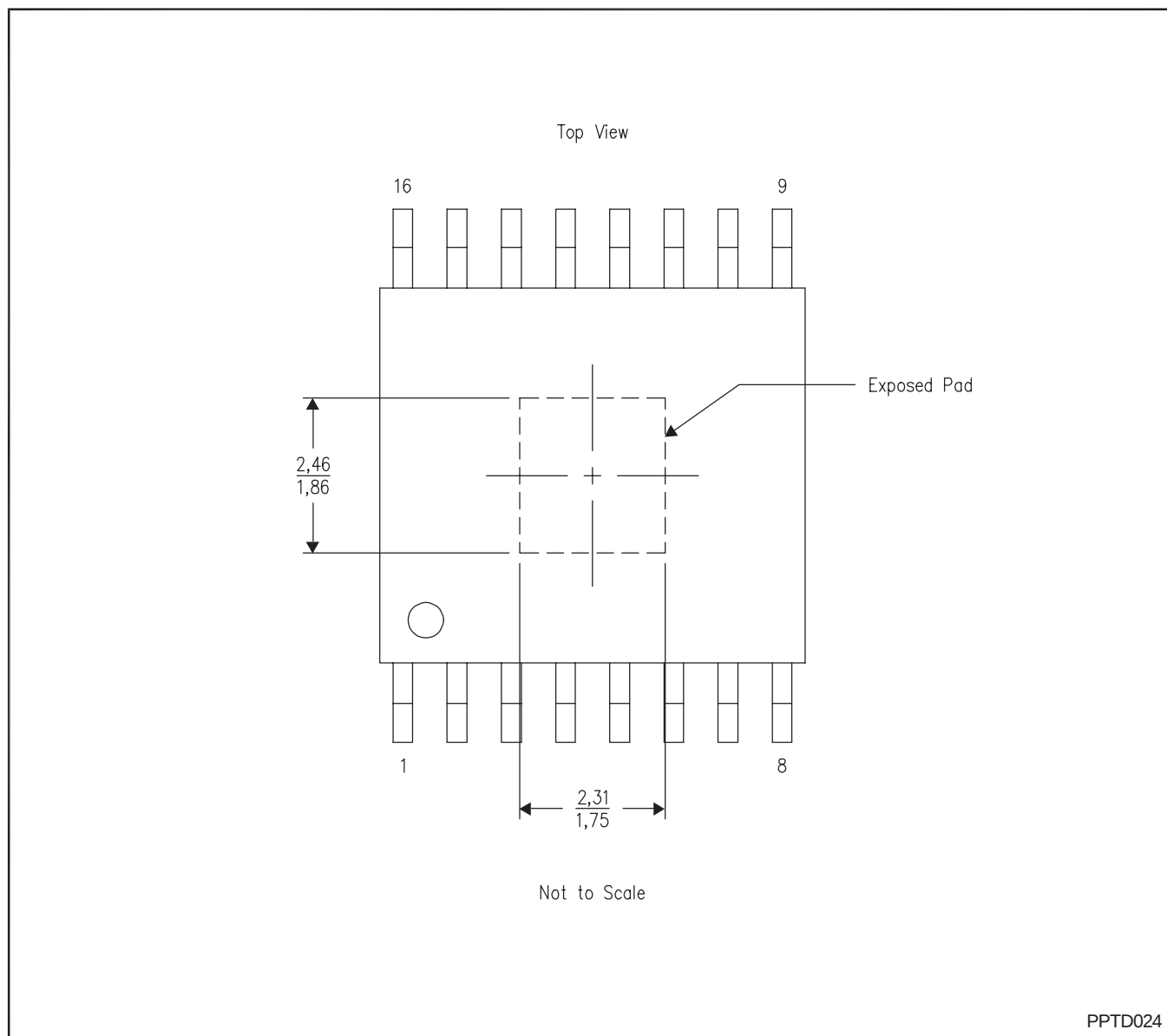


Figure 49

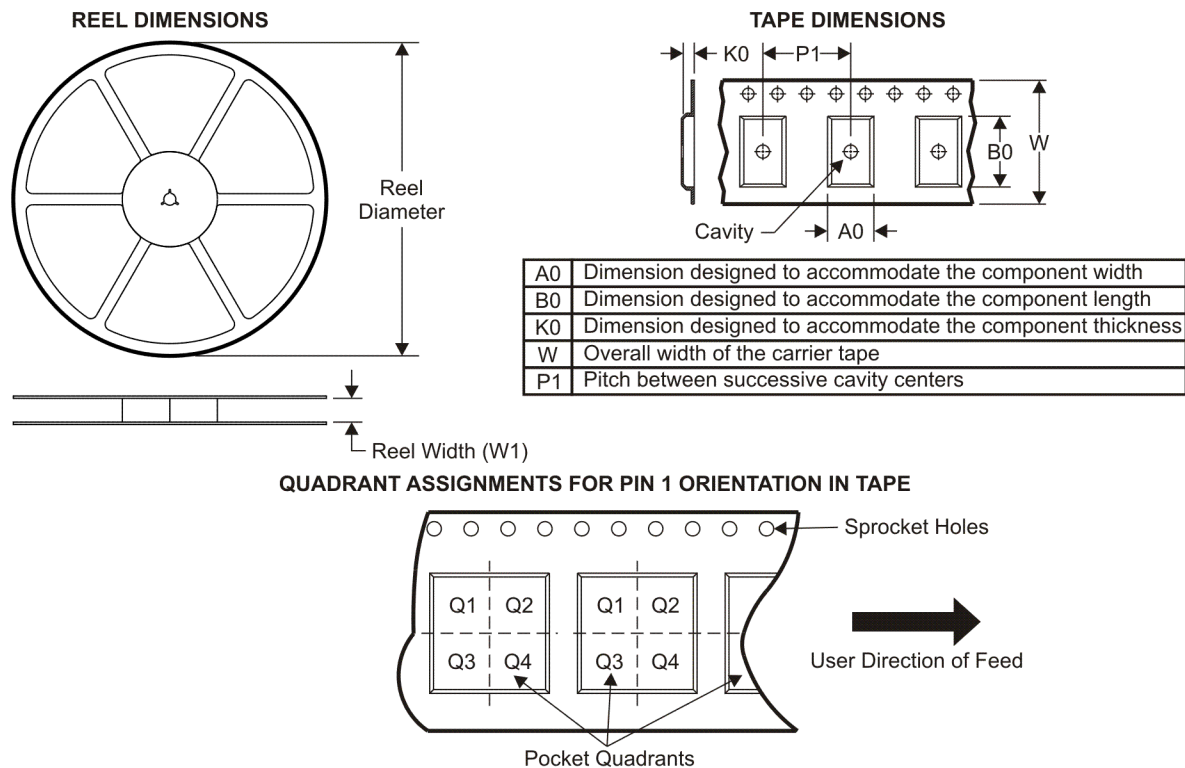
THERMAL PAD MECHANICAL DATA

PWP (R-PDSO-G16)

PowerPAD™ PLASTIC SMALL-OUTLINE



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - For additional information on the PowerPAD™ package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, **PowerPAD Thermally Enhanced Package**, Texas Instruments Literature No. SLMA002 and Application Brief, **PowerPAD Made Easy**, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS54352PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS54353PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS54354PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS54355PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS54356PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS54357PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

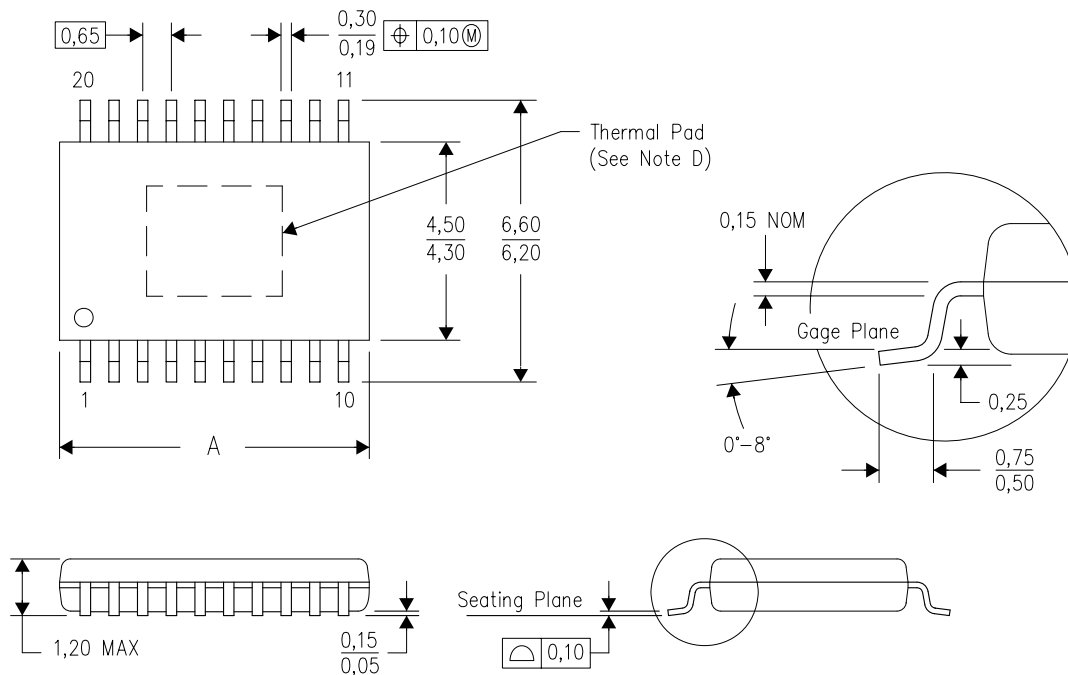
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS54352PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0
TPS54353PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0
TPS54354PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0
TPS54355PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0
TPS54356PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0
TPS54357PWPR	HTSSOP	PWP	16	2000	346.0	346.0	29.0

MECHANICAL DATA

PWP (R-PDSO-G**)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE

20 PIN SHOWN



PINS **	14	16	20	24	28
DIM					
A MAX	5,10	5,10	6,60	7,90	9,80
A MIN	4,90	4,90	6,40	7,70	9,60

4073225/H 12/05

- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Body dimensions do not include mold flash or protrusions. Mold flash and protrusion shall not exceed 0.15 per side.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <<http://www.ti.com>>.
 - Falls within JEDEC MO-153

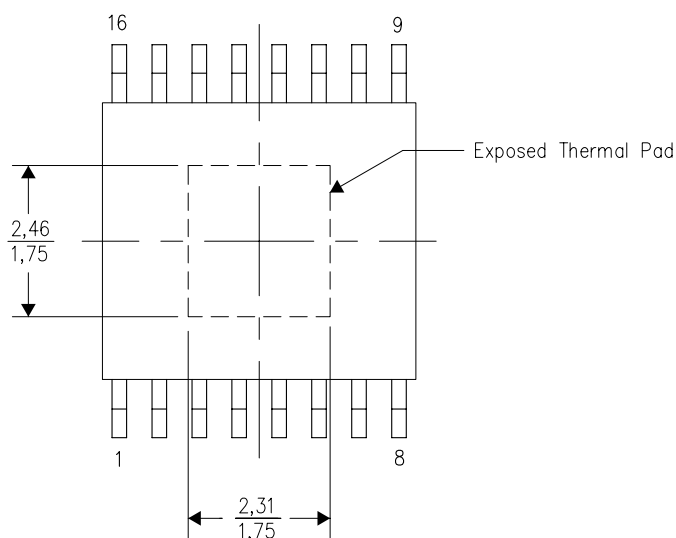
PowerPAD is a trademark of Texas Instruments.

THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

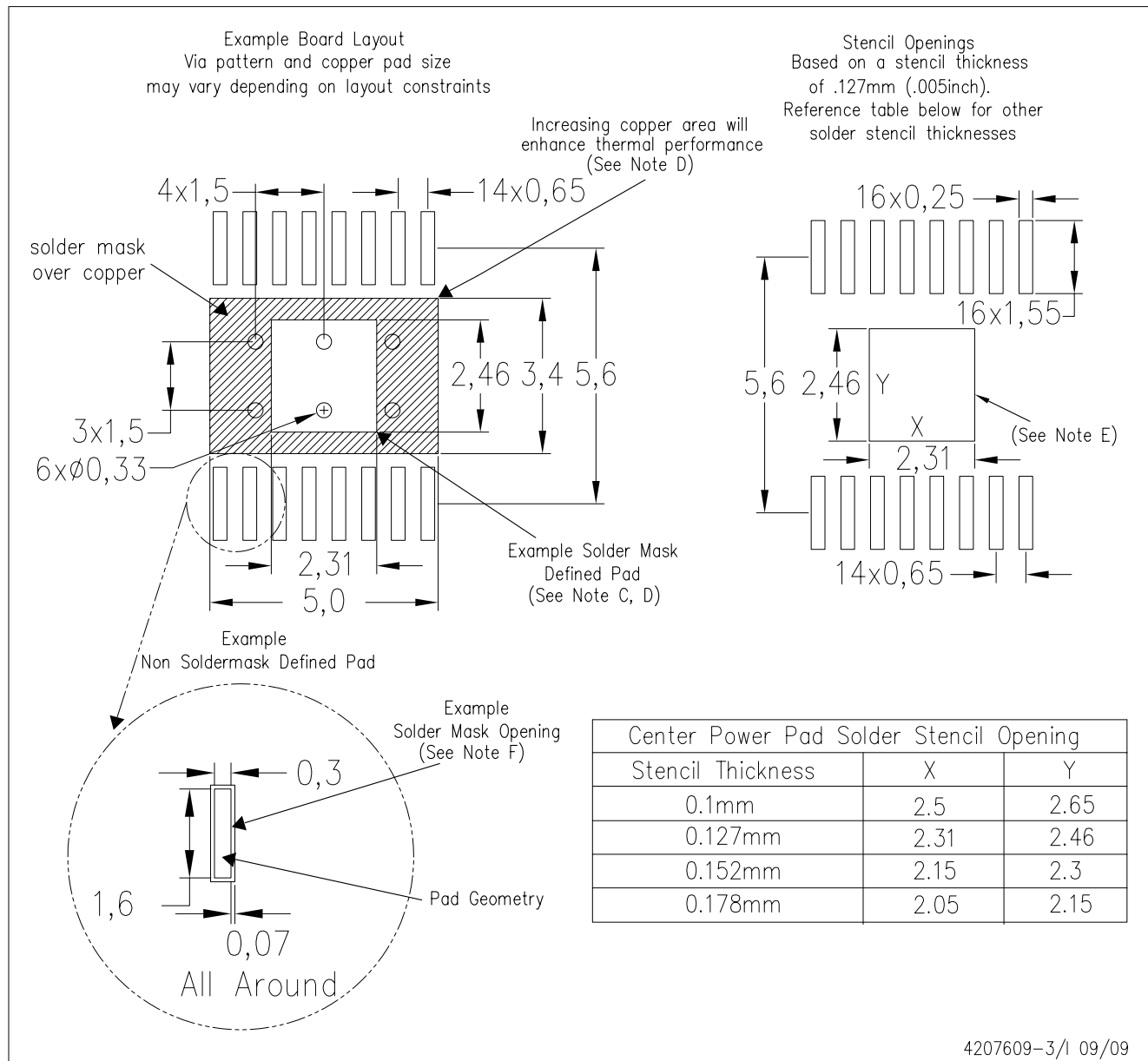


Top View

NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions

PWP (R-PDSO-G16) PowerPAD™



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
 - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

PowerPAD is a trademark of Texas Instruments.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DLP® Products	www.dlp.com	Communications and Telecom	www.ti.com/communications
DSP	dsp.ti.com	Computers and Peripherals	www.ti.com/computers
Clocks and Timers	www.ti.com/clocks	Consumer Electronics	www.ti.com/consumer-apps
Interface	interface.ti.com	Energy	www.ti.com/energy
Logic	logic.ti.com	Industrial	www.ti.com/industrial
Power Mgmt	power.ti.com	Medical	www.ti.com/medical
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
RFID	www.ti-rfid.com	Space, Avionics & Defense	www.ti.com/space-avionics-defense
RF/IF and ZigBee® Solutions	www.ti.com/lprf	Video and Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless-apps