

Async/Page/Burst CellularRAM[®] 1.0 Memory

MT45W2MW16BGB

Features

- Single device supports asynchronous, page, and burst operations
- Random access time: 70ns
- VCC, VCCQ voltages
 - 1.7–1.95V VCC
 - 1.7–3.6V VCCQ
- Page mode read access
 - 16-word page size
 - Interpage read access: 70ns
 - Intrapage read access: 20ns
- Burst mode write access: continuous burst
- Burst mode read access
 - 4, 8, or 16 words or continuous burst
 - MAX clock rate: 104 MHz (^tCLK = 9.62ns)
 - Burst initial latency: 38.5ns (4 clocks) at 104 MHz
 - ^tACLK: 7ns at 104 MHz
- Low power consumption
 - Asynchronous read: <20mA
 - Intrapage read: <15mA
 - Intrapage read initial access, burst read: (38.5ns [4 clocks] at 104 MHz) <40mA
 - Continuous burst read: <25mA
 - Standby: <110µA
 - Deep power-down: <10µA (TYP at 25°C)
- Low-power features
 - Temperature-compensated refresh (TCR)
 - On-chip temperature sensor
 - Partial-array refresh (PAR)
 - Deep power-down (DPD) mode

Options

- Configuration
 - 2 Meg x 16
- Package
 - 54-ball VFBGA (“green”)
- Access time
 - 70ns
- Frequency
 - 80 MHz
 - 104 MHz

Designator

MT45W2MW16B
GB
-70
8
1

Figure 1: 54-Ball VFBGA Ball Assignment

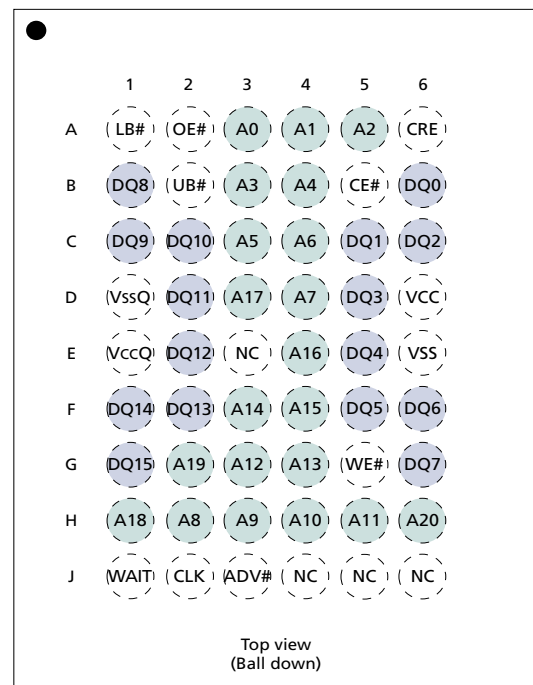




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General Description

Micron® CellularRAM® is a high-speed, CMOS PSRAM memory device developed for low-power, portable applications. The MT45W2MW16BGB is a 32Mb DRAM core device organized as 2 Meg x 16 bits. This device includes an industry-standard burst mode Flash interface that dramatically increases READ/WRITE bandwidth compared with other low-power SRAM or pseudo-SRAM (PSRAM) offerings.

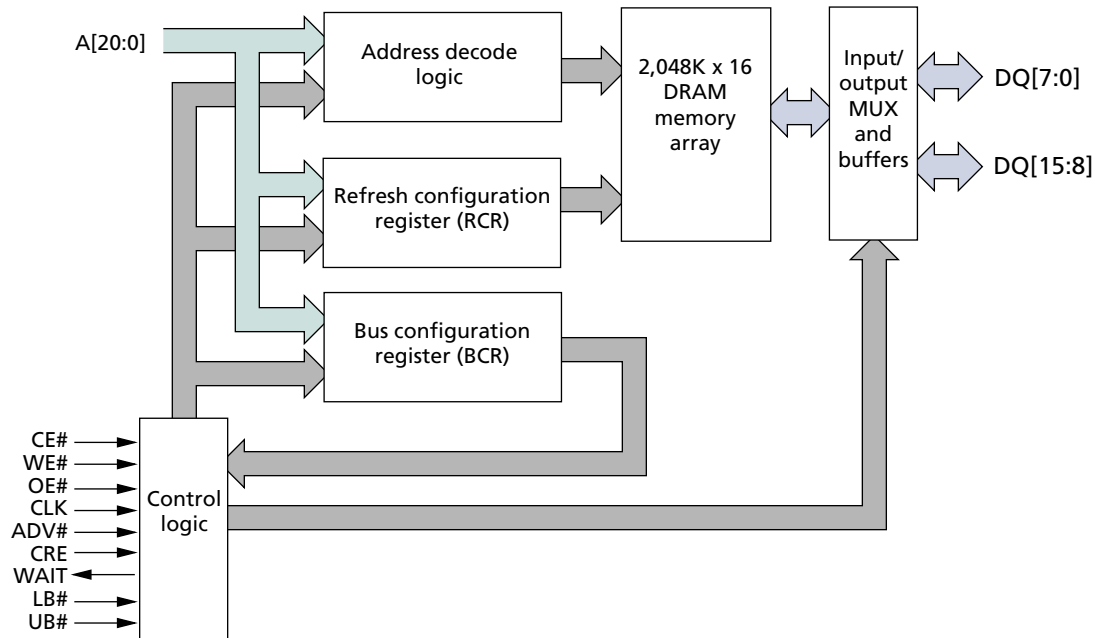
For seamless operation on a burst Flash bus, CellularRAM products incorporate a transparent self refresh mechanism. The hidden refresh requires no additional support from the system memory controller and has no significant impact on device READ/WRITE performance.

Two user-accessible control registers define device operation. The bus configuration register (BCR) defines how the CellularRAM device interacts with the system memory bus and is nearly identical to its counterpart on burst mode Flash devices. The refresh configuration register (RCR) is used to control how refresh is performed on the DRAM array. These registers are automatically loaded with default settings during power-up and can be updated anytime during normal operation.

Special attention has been focused on standby current consumption during self refresh. CellularRAM products include three system-accessible mechanisms to minimize standby current. Partial-array refresh (PAR) limits refresh to only that part of the DRAM array that contains essential data. Temperature-compensated refresh (TCR) uses an on-chip sensor to adjust the refresh rate to match the device temperature. The refresh rate decreases at lower temperatures to minimize current consumption during standby. Deep power-down (DPD) halts the REFRESH operation altogether and is used when no vital information is stored in the device. These three refresh mechanisms are accessed through the RCR.

Functional Block Diagram

Figure 2: Functional Block Diagram – 2 Meg x 16



Note: Functional block diagrams illustrate simplified device operation. See ball description table, bus operations tables, and timing diagrams for detailed information.

Ball Descriptions

Table 1: VFBGA Ball Descriptions

VFBGA Assignment	Symbol	Type	Description
H6, G2, H1, D3, E4, F4, F3, G4, G3, H5, H4, H3, H2, D4, C4, C3, B4, B3, A5, A4, A3	A[20:0]	Input	Address inputs: Inputs for addresses during READ and WRITE operations. Addresses are internally latched during READ and WRITE cycles. The address lines are also used to define the value to be loaded into the BCR or the RCR.
J3	ADV#	Input	Address valid: Indicates that a valid address is present on the address inputs. Addresses can be latched on the rising edge of ADV# during asynchronous READ and WRITE operations. ADV# can be held LOW during asynchronous READ and WRITE operations.
B5	CE#	Input	Chip enable: Activates the device when LOW. When CE# is HIGH, the device is disabled and goes into standby or deep power-down mode.
J2	CLK	Input	Clock: Synchronizes the memory to the system operating frequency during synchronous operations. When configured for synchronous operation, the address is latched on the first rising CLK edge when ADV# is active. CLK must be static LOW or HIGH during asynchronous access READ and WRITE operations and during PAGE READ ACCESS operations.
A6	CRE	Input	Configuration register enable: When CRE is HIGH, WRITE operations load the RCR or BCR, and READ operations either access the RCR or the BCR.
A1	LB#	Input	Lower byte enable: DQ[7:0].
A2	OE#	Input	Output enable: Enables the output buffers when LOW. When OE# is HIGH, the output buffers are disabled.
B2	UB#	Input	Upper byte enable: DQ[15:8].
G5	WE#	Input	WRITE enable: Determines whether a given cycle is a WRITE cycle. If WE# is LOW, the cycle is a WRITE to either a configuration register or the memory array.
G1, F1, F2, E2, D2, C2, C1, B1, G6, F6, F5, E5, D5, C6, C5, B6	DQ[15:0]	Input/Output	Data inputs/outputs.
J1	WAIT	Output	Wait: Provides data-valid feedback during burst READ and WRITE operations. The signal is gated by CE#. WAIT is used to arbitrate collisions between REFRESH and READ/WRITE operations. WAIT is asserted when a burst crosses a row boundary. WAIT is also used to mask the delay associated with opening a new internal page. WAIT is asserted and should be ignored during asynchronous and page mode operations. WAIT is High-Z when CE# is HIGH.
E3, J4, J5, J6	NC	–	Not internally connected.
D6	Vcc	Supply	Device power supply (1.7–1.95V): Power supply for device core operation.
E1	VccQ	Supply	I/O power supply (1.7–3.6V): Power supply for input/output buffers.
E6	Vss	Supply	Vss must be connected to ground.
D1	VssQ	Supply	VssQ must be connected to ground.

Note: The CLK and ADV# inputs can be tied to Vss if the device is always operating in asynchronous or page mode. WAIT will be asserted, but should be ignored during asynchronous and page mode operations.

Bus Operations

Table 2: Bus Operations: Asynchronous Mode

Mode	Power	CLK ¹	ADV#	CE#	OE#	WE#	CRE	LB#/UB#	WAIT ²	DQ[15:0] ³	Notes
READ	Active	L	L	L	L	H	L	L	Low-Z	Data-out	4
WRITE	Active	L	L	L	X	L	L	L	Low-Z	Data-in	4
Standby	Standby	L	X	H	X	X	L	X	High-Z	High-Z	5, 6
No operation	Idle	L	X	L	X	X	L	X	Low-Z	X	4, 6
Configuration register WRITE	Active	L	L	L	H	L	H	X	Low-Z	High-Z	
Configuration register READ	Active	L	L	L	H	H	H	X	Low-Z	Config. reg. out	8
DPD	Deep power-down	L	X	H	X	X	X	X	High-Z	High-Z	7

- Notes:
1. CLK must be static (HIGH or LOW) during asynchronous READ and asynchronous WRITE modes and to achieve standby power during standby and DPD modes. CLK must be static (HIGH or LOW) during burst suspend.
 2. The WAIT polarity is configured through the bus configuration register (BCR[10]).
 3. When LB# and UB# are in select mode (LOW), DQ[15:0] are affected. When only LB# is in select mode, DQ[7:0] are affected. When only UB# is in the select mode, DQ[15:8] are affected.
 4. The device will consume active power in this mode whenever addresses are changed.
 5. When the device is in standby mode, address inputs and data inputs/outputs are internally isolated from any external influence.
 6. VIN = VccQ or 0V; all device balls must be static (unswitched) to achieve standby current.
 7. DPD is maintained until RCR is reconfigured.
 8. CRE-controlled reading of the configuration register is supported for this device, though it is not an official CellularRAM 1.0 feature.

Table 3: Bus Operations: Burst Mode

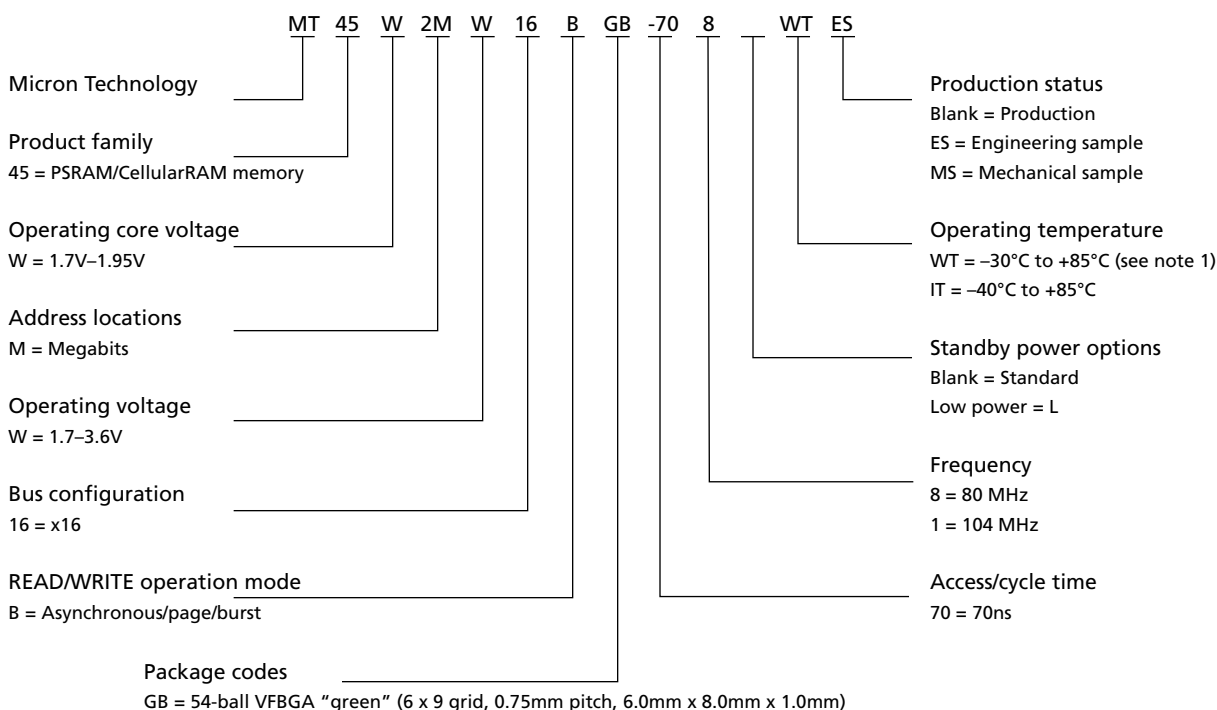
Mode	Power	CLK ¹	ADV#	CE#	OE#	WE#	CRE	LB#/UB#	WAIT ²	DQ[15:0] ³	Notes
Asynchronous READ	Active	L	L	L	L	H	L	L	Low-Z	Data-out	4
Asynchronous WRITE	Active	L	L	L	X	L	L	L	Low-Z	Data-in	4
Standby	Standby	L	X	H	X	X	L	X	High-Z	High-Z	5, 6
No operation	Idle	L	X	L	X	X	L	X	Low-Z	X	4, 6
Initial burst READ	Active		L	L	X	H	L	L	Low-Z	X	4, 8
Initial burst WRITE	Active		L	L	H	L	L	X	Low-Z	X	4, 8
Burst continue	Active		H	L	X	X	X	L	Low-Z	Data-in or data-out	4, 8
Burst suspend	Active	X	X	L	H	X	L	X	Low-Z	High-Z	4, 8
Configuration register WRITE	Active		L	L	H	L	H	X	Low-Z	High-Z	8
Configuration register READ	Active		L	L	H	H	H	X	Low-Z	Config. reg. out Z	8, 9
DPD	Deep power-down	L	X	H	X	X	X	X	High-Z	High-Z	7

- Notes:
1. CLK must be static (HIGH or LOW) during asynchronous READ and asynchronous WRITE modes and to achieve standby power during standby and DPD modes. CLK must be static (HIGH or LOW) during burst suspend.
 2. The WAIT polarity is configured through the bus configuration register (BCR[10]).
 3. When LB# and UB# are in select mode (LOW), DQ[15:0] are affected. When only LB# is in select mode, DQ[7:0] are affected. When only UB# is in the select mode, DQ[15:8] are affected.
 4. The device will consume active power in this mode whenever addresses are changed.
 5. When the device is in standby mode, address inputs and data inputs/outputs are internally isolated from any external influence.
 6. VIN = VCCQ or 0V; all device balls must be static (unswitched) to achieve standby current.
 7. DPD is maintained until RCR is reconfigured.
 8. Burst mode operation is initialized through the bus configuration register (BCR[15]).
 9. This device supports CRE-controlled configuration register READs. This feature is not an official CellularRAM 1.0 feature.

Part Numbering Information

Micron CellularRAM devices are available in several configurations and densities.

Figure 3: Part Number Chart



Note: –30°C exceeds the CellularRAM Workgroup 1.0 specification of –25°C.

Valid Part Number Combinations

After building the part number from the part numbering chart, visit the Micron Web site at www.micron.com/psram to verify that the part number is offered and valid. If the device required is not on this list, contact the factory.

Device Marking

Due to the size of the package, the Micron-standard part number is not printed on the top of the device. Instead, an abbreviated device mark consisting of a five-digit alphanumeric code is used. The abbreviated device marks are cross-referenced to the Micron part numbers at the FBGA Part Marking Decoder site, <http://www.micron.com/decoder>. To view the location of the abbreviated mark on the device, refer to customer service note, CSN-11, "Product Mark/Label," at www.micron.com/csn.

Functional Description

In general, the MT45W2MW16BGB devices are high-density alternatives to SRAM and PSRAM products, popular in low-power, portable applications.

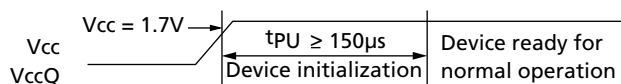
The MT45W2MW16BGB contains a 33,554,432-bit DRAM core organized as 2,097,152 addresses by 16 bits. This device implements the same high-speed bus interface found on burst mode Flash products.

The CellularRAM bus interface supports both asynchronous and burst mode transfers. Page mode accesses are also included as a bandwidth-enhancing extension to the asynchronous READ protocol.

Power-Up Initialization

CellularRAM products include an on-chip voltage sensor used to launch the power-up initialization process. Initialization will configure the BCR and the RCR with their default settings (see Figure 19 on page 26 and Figure 24 on page 31). VCC and VCCQ must be applied simultaneously. When they reach a stable level at or above 1.7V, the device will require 150 μ s to complete its self-initialization process. During the initialization period, CE# should remain HIGH. When initialization is complete, the device is ready for normal operation.

Figure 4: Power-Up Initialization Timing



Bus Operating Modes

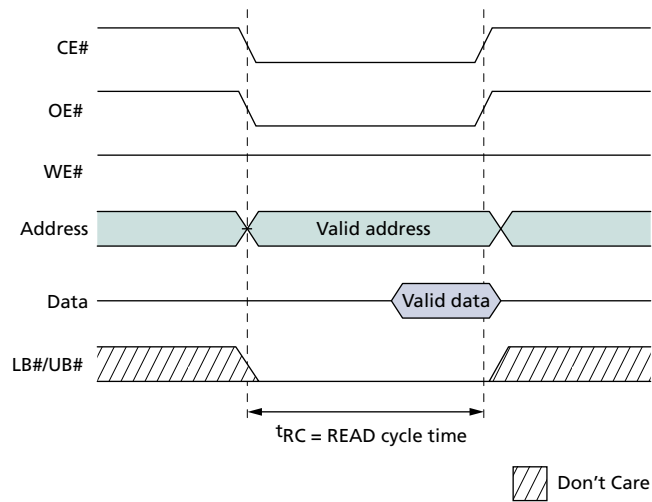
The MT45W2MW16BGB CellularRAM products incorporate a burst mode interface found on Flash products targeting low-power, wireless applications. This bus interface supports asynchronous, page mode, and burst mode READ and WRITE transfers. The specific interface supported is defined by the value loaded into the bus configuration register. Page mode is controlled by the refresh configuration register (RCR[7]).

Asynchronous Mode

CellularRAM products power up in the asynchronous operating mode. This mode uses the industry-standard SRAM control bus (CE#, OE#, WE#, and LB#/UB#). READ operations are initiated by bringing CE#, OE#, and LB#/UB# LOW while keeping WE# HIGH (see Figure 5 on page 12). Valid data will be driven out of the I/Os after the specified access time has elapsed. WRITE operations occur when CE#, WE#, and LB#/UB# are driven LOW (see Figure 6 on page 12). During asynchronous WRITE operations, the OE# level is a "Don't Care," and WE# will override OE#. The data to be written is latched on the rising edge of CE#, WE#, or LB#/UB#, whichever occurs first. Asynchronous operations (page mode disabled) either can use the ADV input to latch the address, or ADV can be driven LOW during the entire READ/WRITE operation.

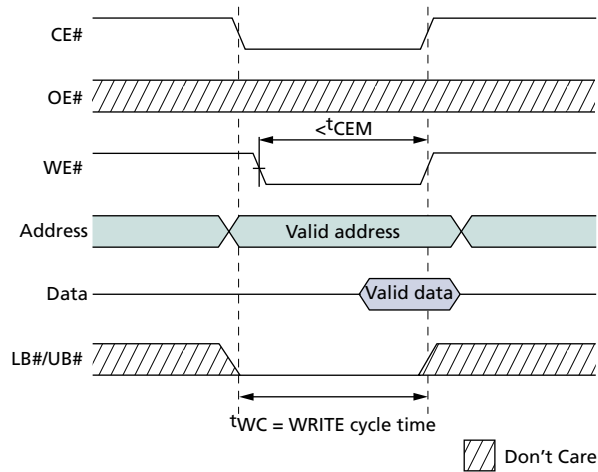
During asynchronous operation, the CLK input must be held static LOW or HIGH. WAIT will be driven while the device is enabled, and its state should be ignored. WE# LOW time must be limited to t_{CEM} .

Figure 5: READ Operation (ADV = LOW)



Note: ADV must remain LOW for page mode operation.

Figure 6: WRITE Operation (ADV = LOW)



Page Mode READ Operation

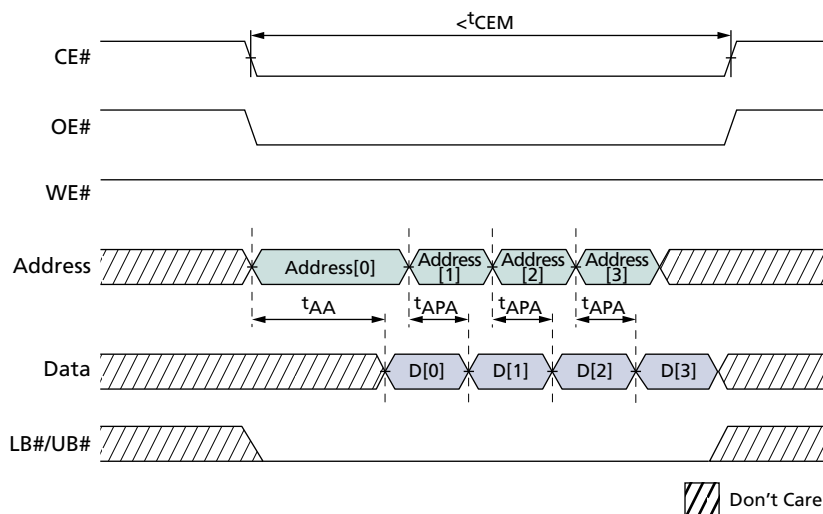
Page mode is a performance-enhancing extension to the legacy asynchronous READ operation. In page-mode-capable products, an initial asynchronous READ access is performed, and then adjacent addresses can be read quickly by simply changing the low-order address. Addresses A[3:0] are used to determine the members of the 16-address CellularRAM page. Any change in addresses A[4] or higher will initiate a new t_{AA} access time. Figure 7 on page 13 shows the timing for a page mode access.

Page mode takes advantage of the fact that adjacent addresses can be read in a shorter period of time than random addresses. WRITE operations do not include comparable page mode functionality.

During asynchronous page mode operation, the CLK input must be held static LOW or HIGH. CE# must be driven HIGH upon completion of a page mode access. WAIT will be driven while the device is enabled, and its state should be ignored. Page mode is enabled by setting RCR[7] to HIGH. ADV must be driven LOW during all page mode READ accesses.

The CE# LOW time is limited by refresh considerations. CE# must not stay LOW longer than t_{CEM} .

Figure 7: Page Mode READ Operation (ADV = LOW)



Burst Mode Operation

Burst mode operations enable high-speed synchronous READ and WRITE operations. Burst operations consist of a multiclock sequence that must be performed in an ordered fashion. After CE# goes LOW, the address to access is latched on the next rising edge of CLK that ADV# is LOW. During this first clock rising edge, WE# indicates whether the operation is going to be a READ (WE# = HIGH, Figure 8 on page 14) or WRITE (WE# = LOW, Figure 9 on page 15).

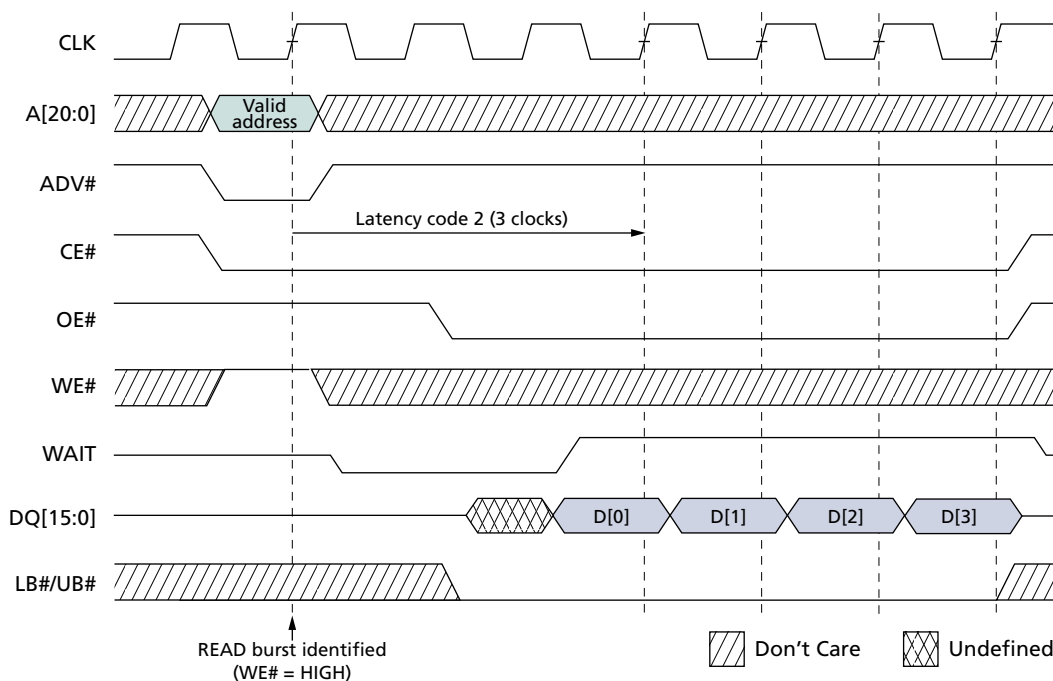
The size of a burst can be specified in the BCR either as fixed-length or continuous. Fixed-length bursts consist of 4, 8, or 16 words. Continuous bursts have the ability to start at a specified address and burst through the entire memory. The latency count stored in the BCR defines the number of clock cycles that elapse before the initial data value is transferred between the processor and CellularRAM device.

The WAIT output will be asserted as soon as CE# goes LOW and will be de-asserted to indicate when data is to be transferred into (or out of) the memory. WAIT will again be asserted if the burst crosses the boundary between 128-word rows. After the CellularRAM device has restored the previous row's data and accessed the next row, WAIT will be deasserted and the burst can continue (see Figure 35 on page 46).

The processor can access other devices without incurring the timing penalty of the initial latency for a new burst by suspending burst mode. Bursts are suspended by stopping CLK. CLK can be stopped HIGH or LOW. If another device will use the data bus while the burst is suspended, OE# should be taken HIGH to disable the CellularRAM outputs; otherwise, OE# can remain LOW. Note that the WAIT output will continue to be active, and, as a result, no other devices should directly share the WAIT connection to the controller. To continue the burst sequence, OE# is taken LOW, and then CLK is restarted after valid data is available on the bus.

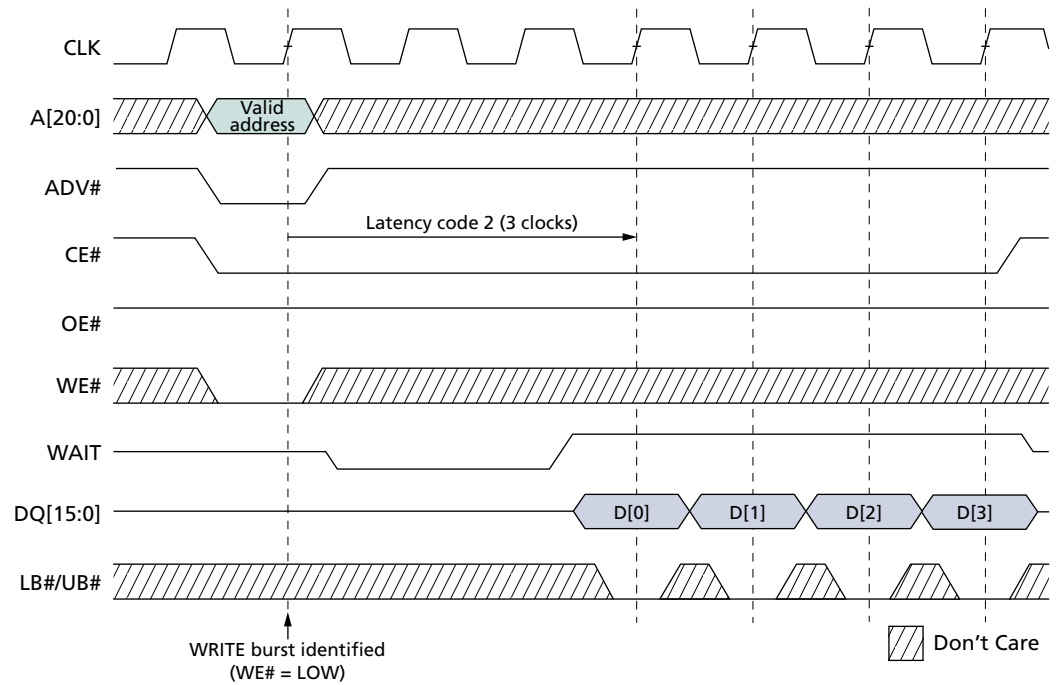
The CE# LOW time is limited by refresh considerations. CE# must not stay LOW longer than t_{CEM} unless row boundaries are crossed at least every t_{CEM} . If a burst suspension will cause CE# to remain LOW for longer than t_{CEM} , CE# should be taken HIGH and the burst restarted with a new CE# LOW/ADV# LOW cycle.

Figure 8: Burst Mode READ (4-Word Burst)



Note: Nondefault BCR settings: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Figure 9: Burst Mode WRITE (4-Word Burst)



Note: Nondefault BCR settings: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

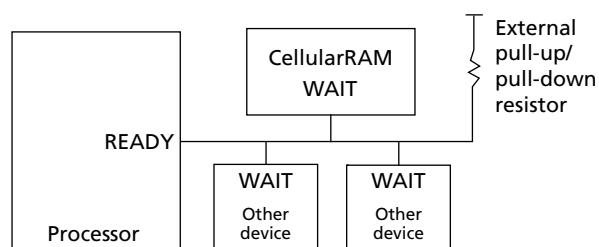
Mixed-Mode Operation

The device can support a combination of synchronous READ and asynchronous WRITE operations when the BCR is configured for synchronous operation. The asynchronous WRITE operation requires that the clock (CLK) be held static LOW or HIGH during the entire sequence. The ADV# signal can be used to latch the target address, or it can remain LOW during the entire WRITE operation. CE# must return HIGH when transitioning between mixed-mode operations. Note that the t_{CKA} period is the same as a READ or WRITE cycle. This time is required to ensure adequate refresh. Mixed-mode operation facilitates a seamless interface to legacy burst mode Flash memory controllers (see Figure 43 on page 54).

WAIT Operation

The WAIT output on a CellularRAM device is typically connected to a shared, system-level WAIT signal (see Figure 10). The shared WAIT signal is used by the processor to coordinate transactions with multiple memories on the synchronous bus.

Figure 10: Wired-OR WAIT Configuration



After a READ or WRITE operation has been initiated, WAIT goes active to indicate that the CellularRAM device requires additional time before data can be transferred. For READ operations, WAIT will remain active until valid data is output from the device. For WRITE operations, WAIT will indicate to the memory controller when data will be accepted into the CellularRAM device. When WAIT transitions to an inactive state, the data burst will progress on successive clock edges.

During a burst cycle, CE# must remain asserted until the first data is valid. Bringing CE# HIGH during this initial latency may cause data corruption.

The WAIT output also performs an arbitration role when a READ or WRITE operation is launched while an on-chip refresh is in progress. If a collision occurs, WAIT is asserted for additional clock cycles until the refresh has completed (see Figure 11 on page 17 and Figure 12 on page 18). When the REFRESH operation has completed, the READ or WRITE operation will continue normally.

WAIT is also asserted when a continuous READ or WRITE burst crosses a row boundary. The WAIT assertion allows time for the new row to be accessed and permits any pending REFRESH operations to be performed.

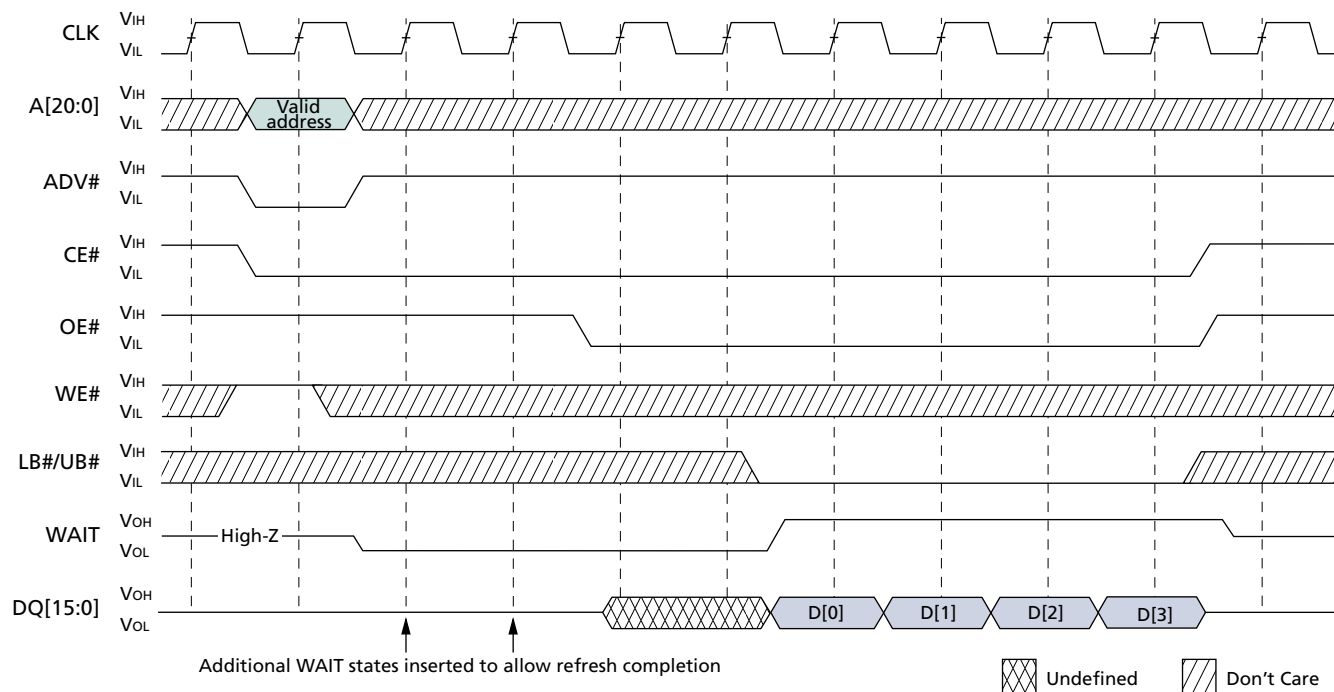
LB#/UB# Operation

The LB# enable and UB# enable signals support byte-wide data transfers. During READ operations, the enabled byte(s) are driven onto the DQ. The DQ associated with a disabled byte are put into a High-Z state during a READ operation. During WRITE oper-

ations, any disabled bytes will not be transferred to the RAM array, and the internal value will remain unchanged. During an asynchronous WRITE cycle, the data to be written is latched on the rising edge of CE#, WE#, LB#, or UB#, whichever occurs first.

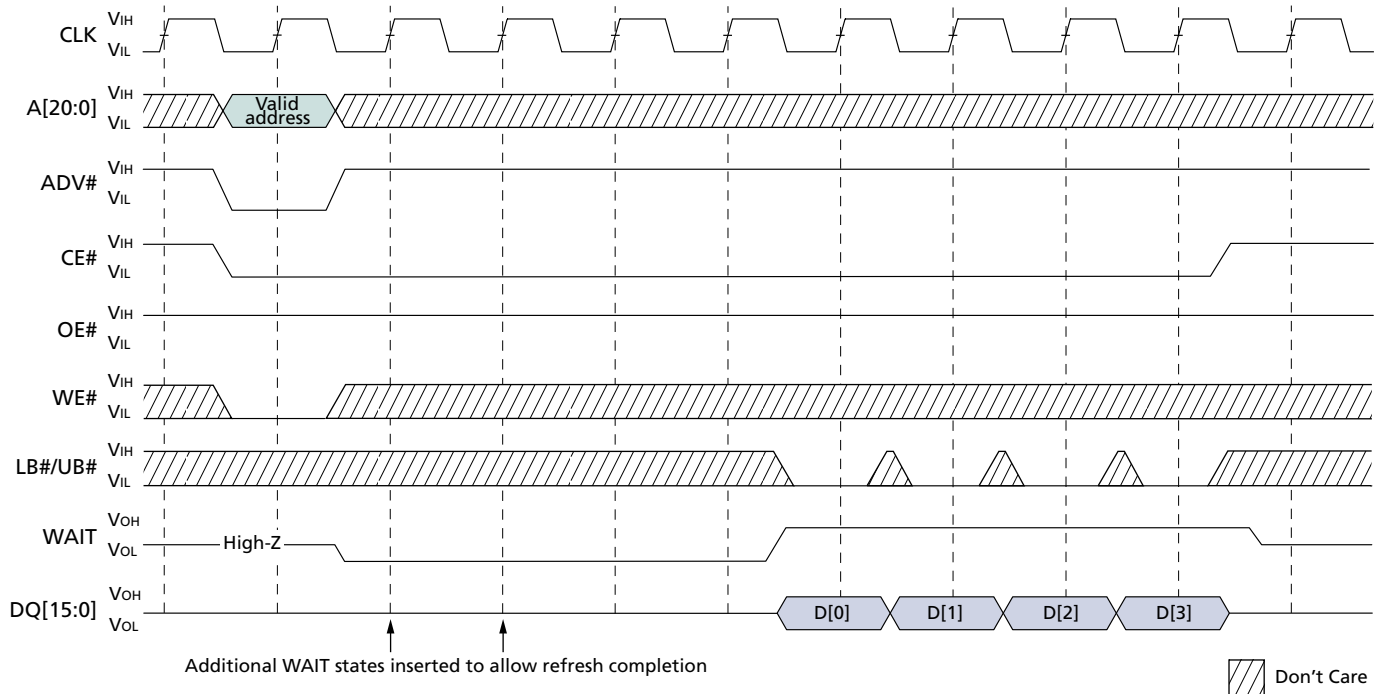
When both the LB# and UB# are disabled (HIGH) during an operation, the device will disable the data bus from receiving or transmitting data. Although the device will seem to be deselected, it remains in an active mode as long as CE# remains LOW.

Figure 11: Refresh Collision During READ Operation



Note: Nondefault BCR settings: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Figure 12: Refresh Collision During WRITE Operation



Note: Nondefault BCR settings: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Low-Power Operation

Standby Mode Operation

During standby, the device current consumption is reduced to the level necessary to perform the DRAM REFRESH operation. Standby operation occurs when CE# is HIGH.

The device will enter a reduced power state upon completion of a READ or WRITE operation or when the address and control inputs remain static for an extended period of time. This mode will continue until a change occurs to the address or control inputs.

Temperature-Compensated Refresh

Temperature-compensated refresh (TCR) allows for adequate refresh at different temperatures. This CellularRAM device includes an on-chip temperature sensor that continually adjusts the refresh rate according to the operating temperature.

Partial-Array Refresh

Partial-array refresh (PAR) restricts REFRESH operation to a portion of the total memory array. This feature enables the device to reduce standby current by refreshing only that part of the memory array required by the host system. The refresh options are full array, one-half array, one-quarter array, one-eighth array, or none of the array. The mapping of these partitions either can start at the beginning or the end of the address map (see Table 6 on page 32). READ and WRITE operations to address ranges receiving refresh will not be affected. Data stored in addresses not receiving refresh will become corrupted. When reenabling additional portions of the array, the new portions are available immediately upon writing to the RCR.

Deep Power-Down Operation

Deep power-down (DPD) operation disables all refresh-related activity. This mode is used if the system does not require the storage provided by the CellularRAM device. Any stored data will become corrupted when DPD is enabled. When refresh activity has been reenabled by rewriting the RCR, the CellularRAM device will require 150 μ s to perform an initialization procedure before normal operations can resume. During this 150 μ s period, the current consumption will be higher than the specified standby levels, but considerably lower than the active current specification.

DPD cannot be enabled or disabled by writing to the RCR using the software access sequence; the RCR should be accessed using CRE instead.

Configuration Registers

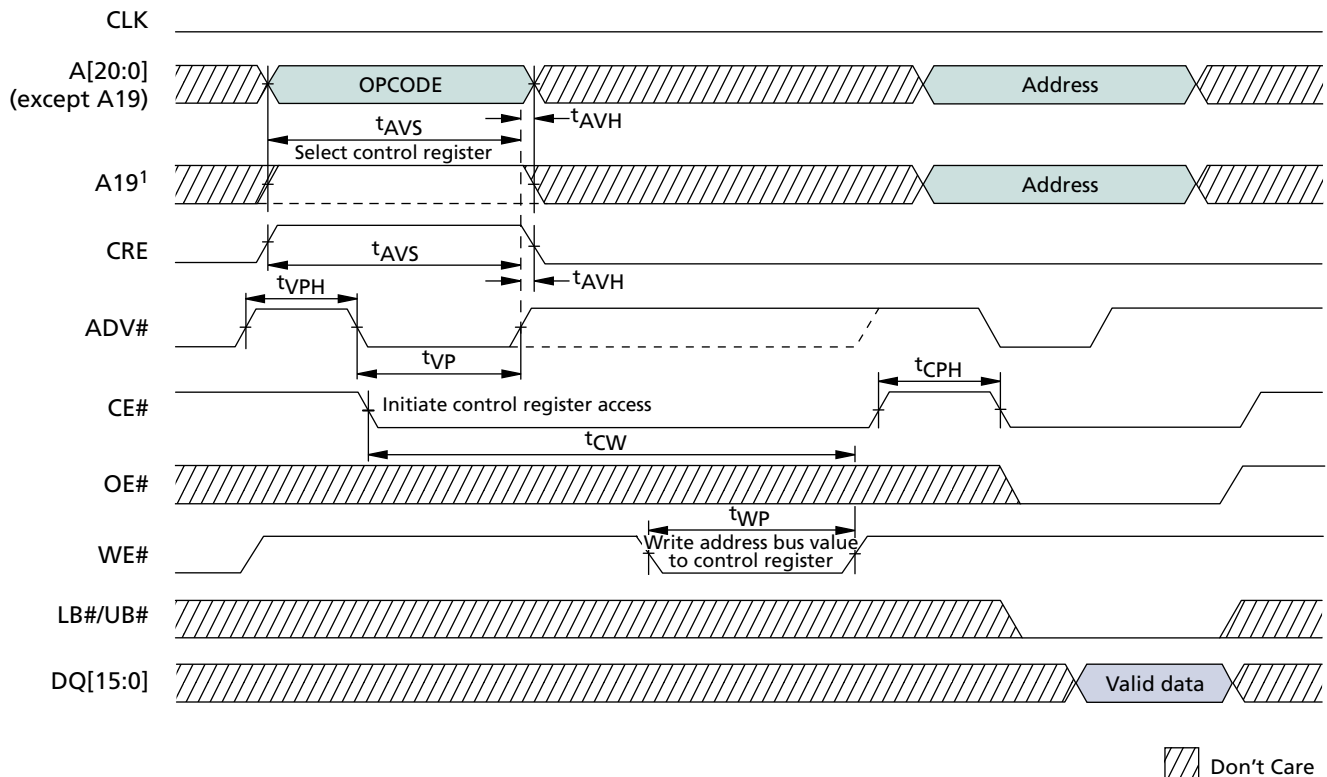
Two user-accessible configuration registers define the device operation. The bus configuration register (BCR) defines how the CellularRAM interacts with the system memory bus and is nearly identical to its counterpart on burst mode Flash devices. The refresh configuration register (RCR) is used to control how refresh is performed on the DRAM array. These registers are automatically loaded with default settings during power-up and can be updated any time the devices are operating in a standby state.

Access Using CRE

The configuration registers are loaded using either a synchronous or an asynchronous WRITE operation when the configuration register enable (CRE) input is HIGH (see Figure 13, and Figure 14 on page 21). When CRE is LOW, a READ or WRITE operation will access the memory array. The register values are placed on address pins A[19:0]. In an asynchronous WRITE, the values are latched into the configuration register on the rising edge of ADV#, CE#, or WE#, whichever occurs first; LB# and UB# are “Don’t Care.” The BCR is accessed when A[19] is HIGH; the RCR is accessed when A[19] is LOW. For READs, address inputs other than A19 are “Don’t Care,” and register bits 15:0 are output on DQ[15:0].

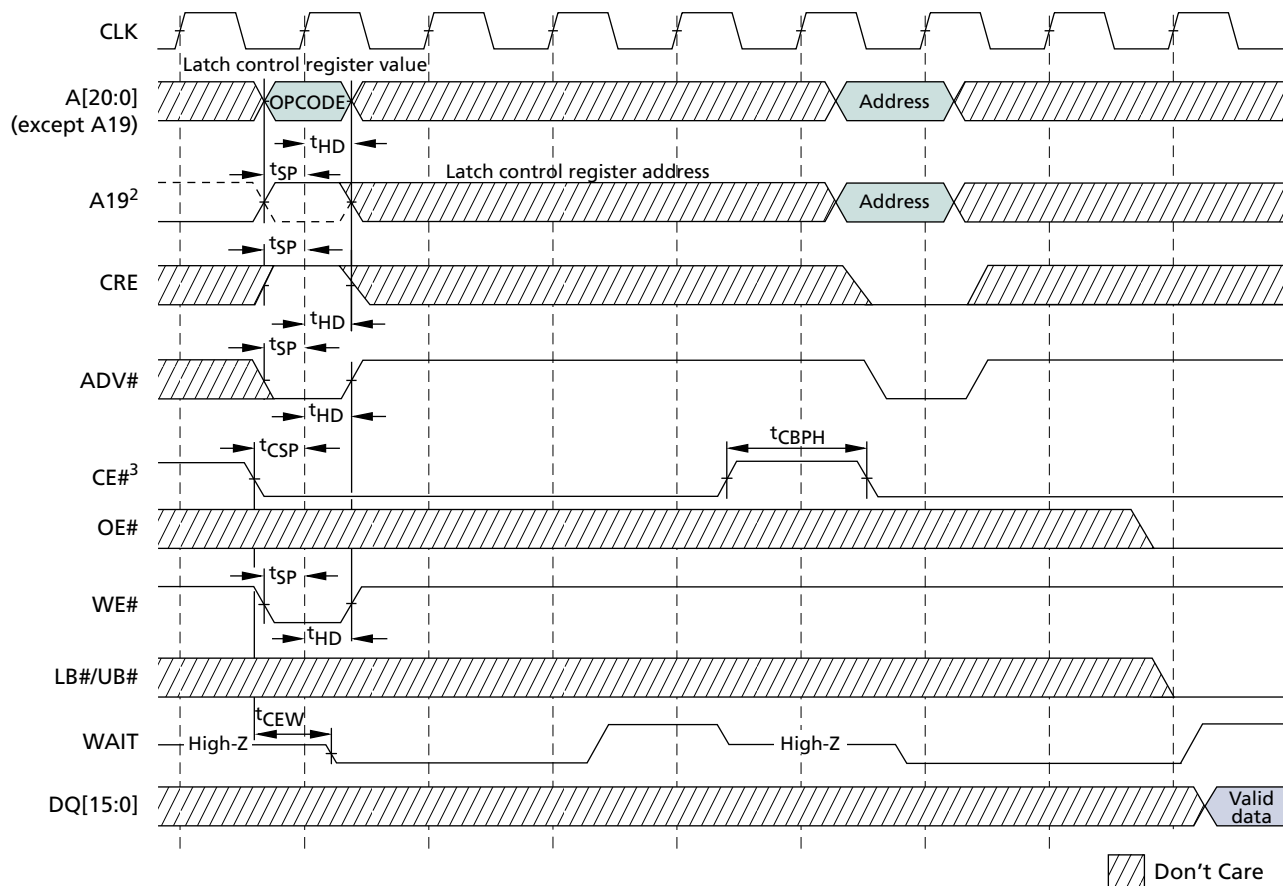
Figure 13: Asynchronous Mode Configuration Register WRITE Followed by READ ARRAY Operation

Note:



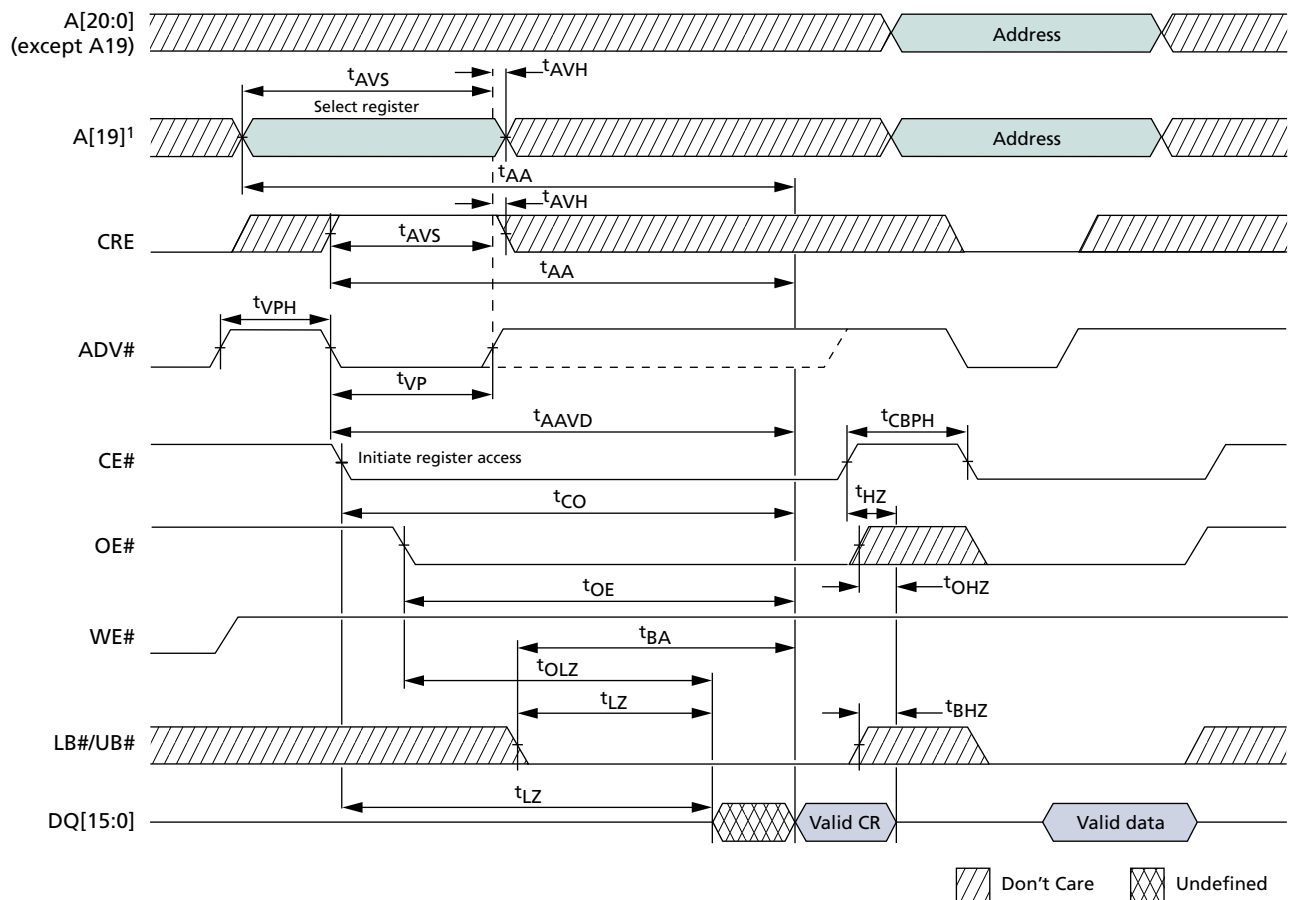
Note: A[19] = LOW to load RCR, HIGH to load BCR.

Figure 14: Synchronous Mode Configuration Register WRITE Followed by READ ARRAY Operation



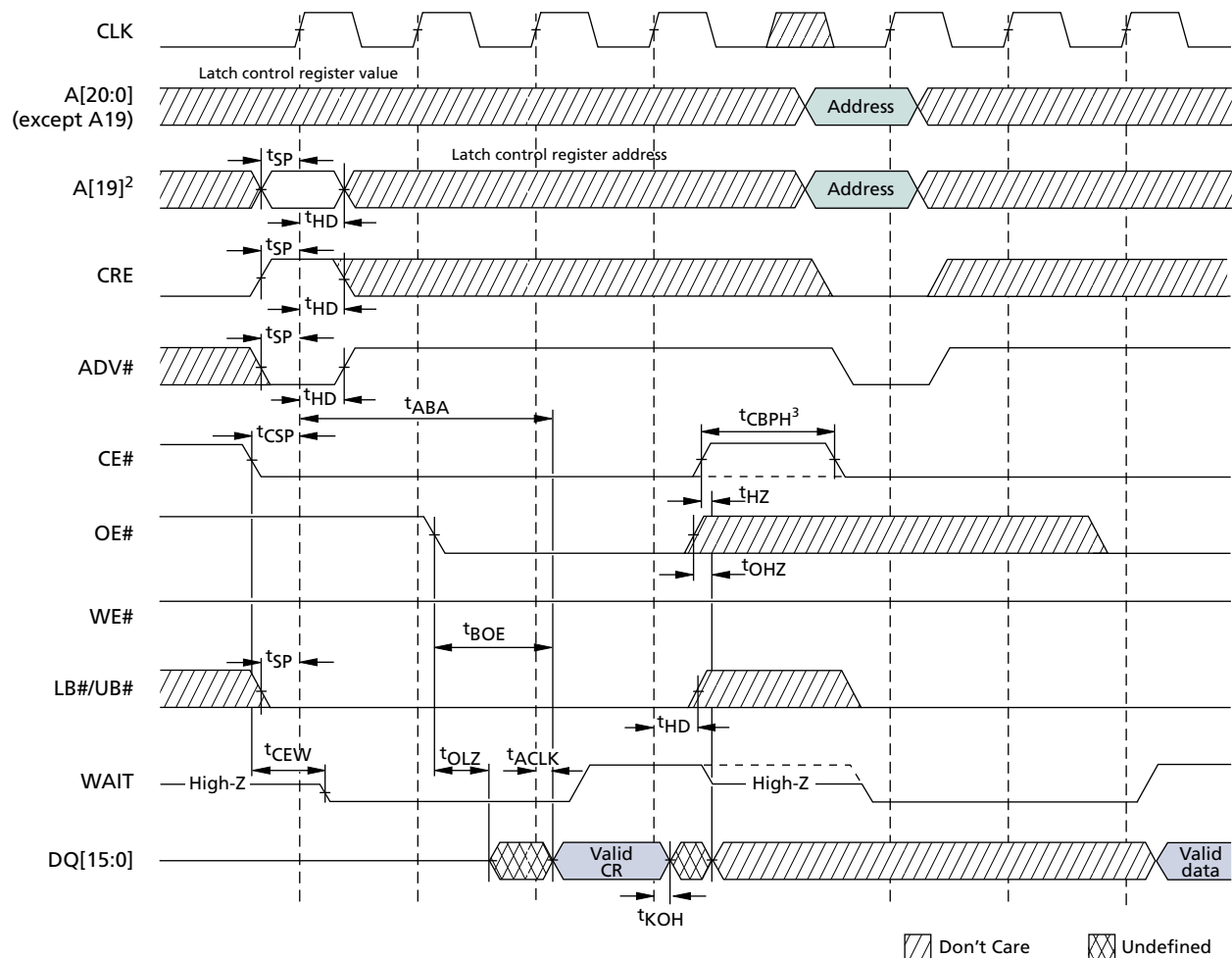
- Notes:
1. Nondefault BCR settings for CR WRITE in synchronous mode followed by READ ARRAY operation: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. A[19] = LOW to load RCR, HIGH to load BCR.
 3. CE# must remain LOW to complete a burst-of-one WRITE. WAIT must be monitored—additional WAIT cycles caused by refresh collisions require a corresponding number of additional CE# LOW cycles.

Figure 15: Asynchronous Mode Configuration Register READ Followed by READ ARRAY Operation



Note: A[19] = LOW to read RCR, HIGH to read BCR.

Figure 16: Synchronous Mode Configuration Register READ Followed by READ ARRAY Operation



- Notes:
1. Nondefault BCR settings for synchronous mode register READ followed by READ ARRAY operation: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. A[19] = LOW to read RCR, HIGH to read BCR.
 3. CE# must remain LOW to complete a burst-of-one READ. WAIT must be monitored—additional WAIT cycles caused by refresh collisions require a corresponding number of additional CE# LOW cycles.

Software Access to the Configuration Register

Software access of the configuration registers uses a sequence of asynchronous READ and asynchronous WRITE operations. The contents of the configuration registers can be read or modified using the software sequence.

The configuration registers are loaded using a four-step sequence consisting of two asynchronous READ operations followed by two asynchronous WRITE operations (see Figure 17). The READ sequence is virtually identical except that an asynchronous READ is performed during the fourth operation (see Figure 18 on page 25).

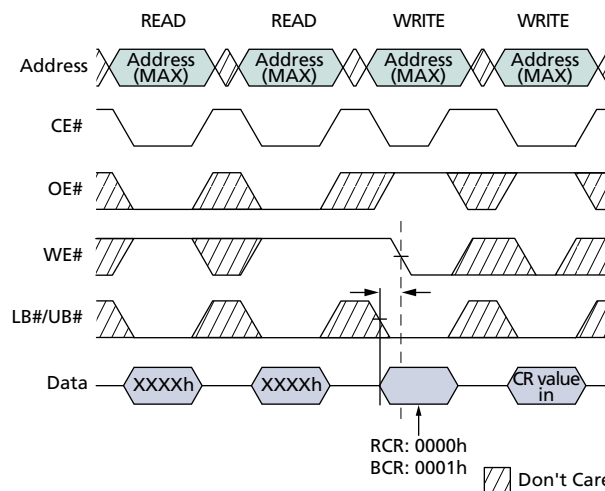
The address used during all READ and WRITE operations is the highest address of the CellularRAM device being accessed (1FFFFFFh for 32Mb); the content at this address is not changed by using this sequence.

The data value presented during the third operation (WRITE) in the sequence defines whether the BCR or the RCR is to be accessed. If the data is 0000h, the sequence will access the RCR; if the data is 0001h, the sequence will access the BCR. During the fourth operation, DQ[15:0] transfer data into or out of bits 15–0 of the configuration registers.

The use of the software sequence does not affect the ability to perform the standard (CRE-controlled) method of loading the configuration registers. However, the software nature of this access mechanism eliminates the need for the control register enable (CRE) pin. If the software mechanism is used, the CRE pin can simply be tied to VSS. The port line often used for CRE control purposes is no longer required.

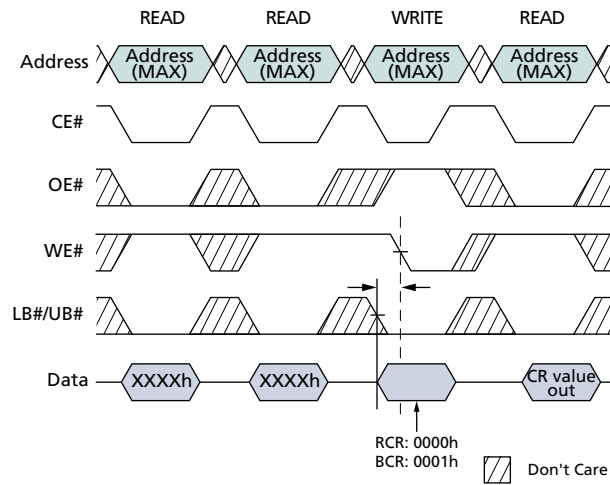
Software access of the RCR should not be used to enter or exit DPD.

Figure 17: Load Configuration Register



Note: It is possible that the data stored at the highest memory location will be altered if the data at the falling edge of WE# is not 0000h or 0001h.

Figure 18: Read Configuration Register



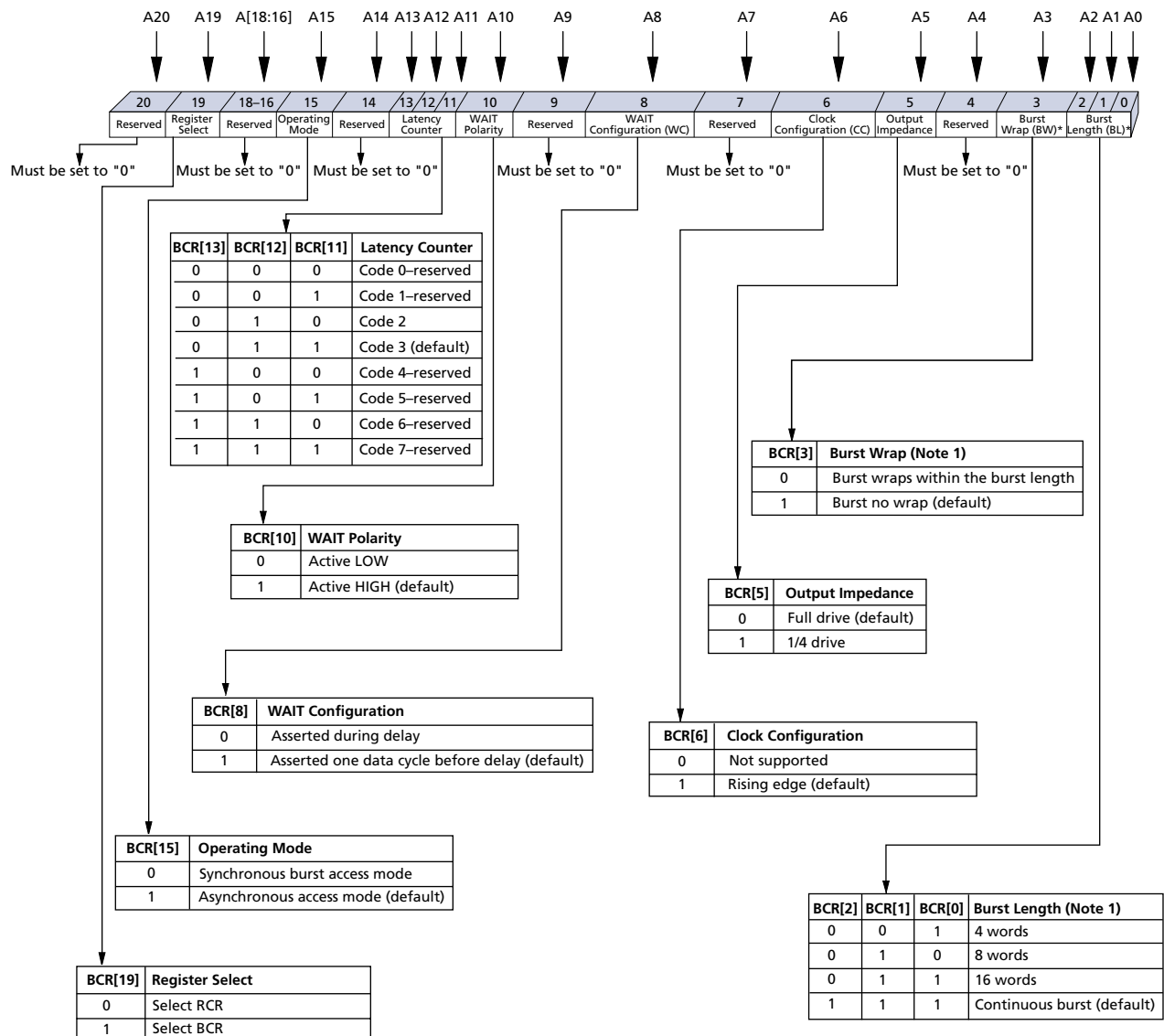
Note: It is possible that the data stored at the highest memory location will be altered if the data at the falling edge of WE# is not 0000h or 0001h.

Bus Configuration Register

The BCR defines how the CellularRAM device interacts with the system memory bus. Page mode operation is enabled by a bit contained in the RCR. Figure 19 describes the control bits in the BCR. At power-up, the BCR is set to 9D4Fh.

The BCR is accessed using CRE and A[19] HIGH or through the configuration register software sequence with DQ = 0001h on the third cycle.

Figure 19: Bus Configuration Register Definition



Note: All burst WRITES are continuous.

Table 4: Sequence and Burst Length

Burst Wrap		Starting Address	4-Word Burst Length	8-Word Burst Length	16-Word Burst Length	Continuous Burst
BCR[3]	Wrap	(Decimal)	Linear	Linear	Linear	Linear
0	Yes	0	0-1-2-3	0-1-2-3-4-5-6-7	0-1-2-3-4-5-6-7-8-9-10-11-12-13-14-15	0-1-2-3-4-5-6-...
		1	1-2-3-0	1-2-3-4-5-6-7-0	1-2-3-4-5-6-7-8-9-10-11-12-13-14-15-0	1-2-3-4-5-6-7-...
		2	2-3-0-1	2-3-4-5-6-7-0-1	2-3-4-5-6-7-8-9-10-11-12-13-14-15-0-1	2-3-4-5-6-7-8-...
		3	3-0-1-2	3-4-5-6-7-0-1-2	3-4-5-6-7-8-9-10-11-12-13-14-15-0-1-2	3-4-5-6-7-8-9-...
		4		4-5-6-7-0-1-2-3	4-5-6-7-8-9-10-11-12-13-14-15-0-1-2-3	4-5-6-7-8-9-10-...
		5		5-6-7-0-1-2-3-4	5-6-7-8-9-10-11-12-13-14-15-0-1-2-3-4	5-6-7-8-9-10-11-...
		6		6-7-0-1-2-3-4-5	6-7-8-9-10-11-12-13-14-15-0-1-2-3-4-5	6-7-8-9-10-11-12-...
		7		7-0-1-2-3-4-5-6	7-8-9-10-11-12-13-14-15-0-1-2-3-4-5-6	7-8-9-10-11-12-13-...
		...			...	...
		14			14-15-0-1-2-3-4-5-6-7-8-9-10-11-12-13	14-15-16-17-18-19-20-...
1	No	0	0-1-2-3	0-1-2-3-4-5-6-7	0-1-2-3-4-5-6-7-8-9-10-11-12-13-14-15	0-1-2-3-4-5-6-...
		1	1-2-3-4	1-2-3-4-5-6-7-8	1-2-3-4-5-6-7-8-9-10-11-12-13-14-15-16	1-2-3-4-5-6-7-...
		2	2-3-4-5	2-3-4-5-6-7-8-9	2-3-4-5-6-7-8-9-10-11-12-13-14-15-16-17	2-3-4-5-6-7-8-...
		3	3-4-5-6	3-4-5-6-7-8-9-10	3-4-5-6-7-8-9-10-11-12-13-14-15-16-17-18	3-4-5-6-7-8-9-...
		4		4-5-6-7-8-9-10-11	4-5-6-7-8-9-10-11-12-13-14-15-16-17-18-19	4-5-6-7-8-9-10-...
		5		5-6-7-8-9-10-11-12	5-6-7-8-9-10-11-12-13-...-15-16-17-18-19-20	5-6-7-8-9-10-11-...
		6		6-7-8-9-10-11-12-13	6-7-8-9-10-11-12-13-14-...-16-17-18-19-20-21	6-7-8-9-10-11-12-...
		7		7-8-9-10-11-12-13-14	7-8-9-10-11-12-13-14-...-17-18-19-20-21-22	7-8-9-10-11-12-13-...
		...			...	...
		14			14-15-16-17-18-19-...-23-24-25-26-27-28-29	14-15-16-17-18-19-20-...
		15			15-16-17-18-19-20-...-24-25-26-27-28-29-30	15-16-17-18-19-20-21-...

Burst Length (BCR[2:0]) Default = Continuous Burst

Burst lengths define the number of words the device outputs during a burst READ operation. The device supports a burst length of 4, 8, or 16 words. The device can also be set in continuous burst mode where data is output sequentially without regard to address boundaries; the internal address wraps to 000000h if the device is read past the last address. WRITE bursts are always performed using continuous burst mode.

Burst Wrap (BCR[3]) Default = Burst No Wrap (Within Burst Length)

The burst wrap option determines whether a 4-, 8-, or 16-word burst READ wraps within the burst length or steps through sequential addresses. If the wrap option is not enabled, the device outputs data from sequential addresses without regard to burst boundaries; the internal address wraps to 000000h if the device is read past the last address.

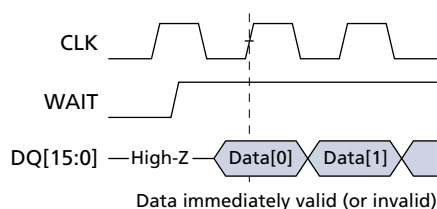
Output Impedance (BCR[5]) Default = Outputs Use Full Drive Strength

The output driver strength can be altered to adjust for different data bus loading scenarios. The reduced-strength option should be more than adequate in stacked chip (Flash + CellularRAM) environments when there is a dedicated memory bus. The reduced-drive-strength option is included to minimize noise generated on the data bus during READ operations. Normal output impedance should be selected when using a discrete CellularRAM device in a more heavily loaded data bus environment. Partial drive is approximately one-quarter full drive strength. Outputs are configured at full drive strength during testing.

WAIT Configuration (BCR[8]) Default = WAIT Transitions One Clock Before Data Valid/Invalid

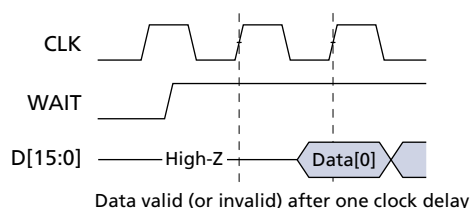
The WAIT configuration bit is used to determine when WAIT transitions between the asserted and the deasserted state with respect to valid data presented on the data bus. The memory controller will use the WAIT signal to coordinate data transfer during synchronous READ and WRITE operations. When BCR[8] = 0, data will be valid or invalid on the clock edge immediately after WAIT transitions to the deasserted or asserted state, respectively (see Figures 20 and 22). When BCR[8] = 1, the WAIT signal transitions one clock period prior to the data bus going valid or invalid (see Figure 21 and Figure 22 on page 29).

Figure 20: WAIT Configuration (BCR[8] = 0)



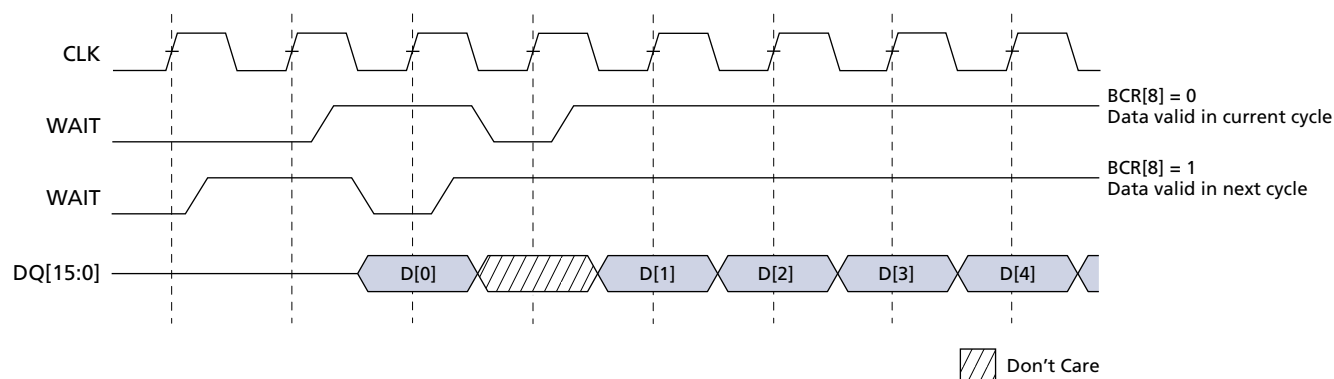
Note: Data valid/invalid immediately after WAIT transitions (BCR[8] = 0). See Figure 22 on page 29.

Figure 21: WAIT Configuration (BCR[8] = 1)



Note: Valid/invalid data delayed for one clock after WAIT transitions (BCR[8] = 1). See Figure 22 on page 29.

Figure 22: WAIT Configuration During Burst Operation



Note: Nondefault BCR setting for WAIT during BURST operation: WAIT active LOW.

WAIT Polarity (BCR[10]) Default = WAIT Active HIGH

The WAIT polarity bit indicates whether an asserted WAIT output should be HIGH or LOW. This bit will determine whether the WAIT signal requires a pull-up or pull-down resistor to maintain the deasserted state.

Latency Counter (BCR[13:11]) Default = Three-Clock Latency

The latency counter bits determine how many clocks occur between the beginning of a READ or WRITE operation and the first data value transferred. Only latency code 2 (3 clocks) or latency code 3 (4 clocks) is allowed (see Table 5 and Figure 23 on page 30).

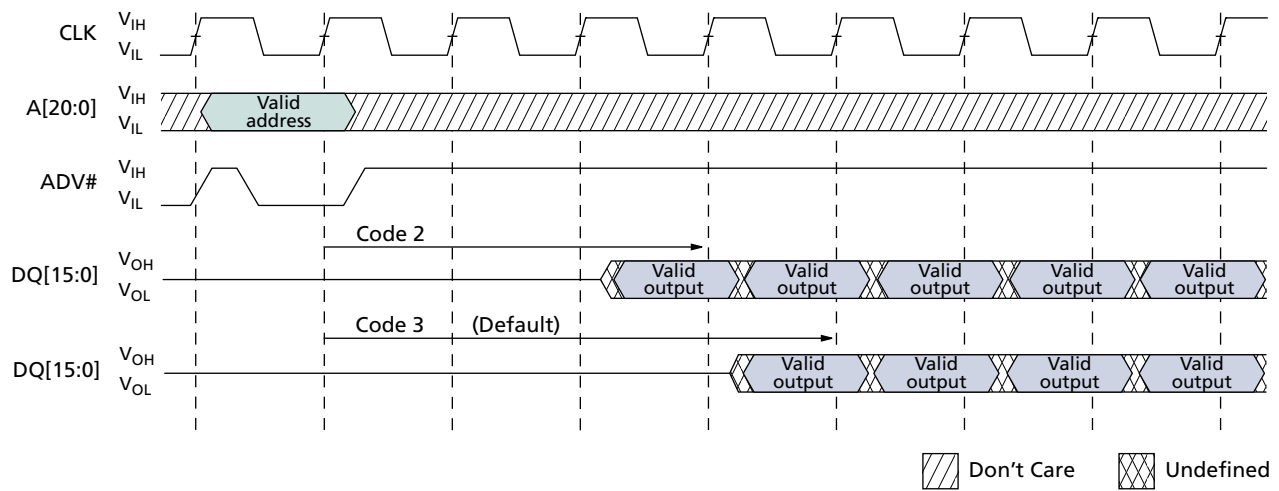
Operating Mode (BCR[15]) Default = Asynchronous Operation

The operating mode bit either selects synchronous burst operation or the default asynchronous mode of operation.

Table 5: Latency Configuration

Latency Configuration Code	Max Input CLK Frequency	
	104 MHz	80 MHz
2 (3 clocks)	66 (15ns)	53 (18.75ns)
3 (4 clocks) – default	104 (9.62ns)	80 (12.50ns)

Figure 23: Latency Counter (Variable Latency, No Refresh Collision)



Refresh Configuration Register

The refresh configuration register (RCR) defines how the CellularRAM device performs its transparent self refresh. Altering the refresh parameters can dramatically reduce current consumption during standby mode. Page mode control is also embedded into the RCR. Figure 24 describes the control bits used in the RCR. At power-up, the RCR is set to 0010h.

The RCR is accessed using CRE and A[19] LOW or through the configuration register software access sequence with DQ = 0000h on the third cycle (see “Configuration Registers” on page 20.)

Partial-Array Refresh (RCR[2:0]) Default = Full Array Refresh

The PAR bits restrict refresh operation to a portion of the total memory array. This feature enables the device to reduce standby current by refreshing only that part of the memory array required by the host system. The refresh options are full array, one-half array, one-quarter array, one-eighth array, or none of the array. The mapping of these partitions can start either at the beginning or the end of the address map (see Table 6 on page 32).

Figure 24: Refresh Configuration Register Mapping

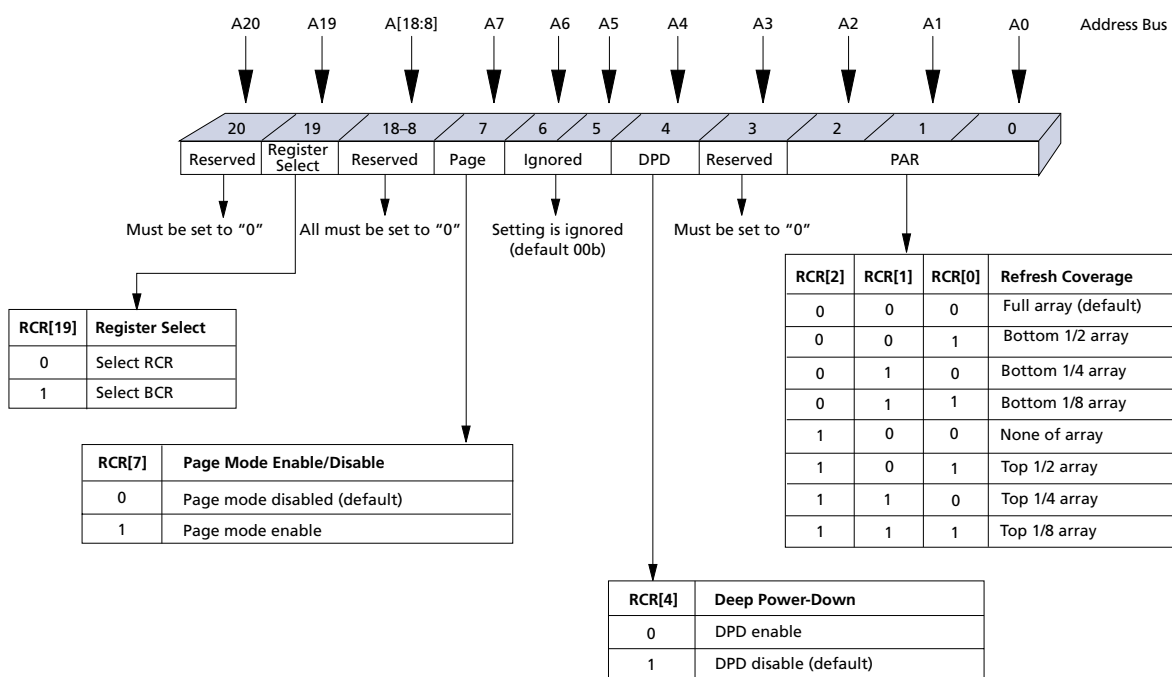


Table 6: 32Mb Address Patterns for PAR (RCR[4] = 1)

RCR[2]	RCR[1]	RCR[0]	Active Section	Address Space	Size	Density
0	0	0	Full die	000000h–1FFFFFFh	2 Meg x 16	32Mb
0	0	1	One-half of die	000000h–0FFFFFFh	1 Meg x 16	16Mb
0	1	0	One-quarter of die	000000h–07FFFFh	512K x 16	8Mb
0	1	1	One-eighth of die	000000h–03FFFFh	256K x 16	4Mb
1	0	0	None of die	0	0 Meg x 16	0Mb
1	0	1	One-half of die	100000h–1FFFFFFh	1 Meg x 16	16Mb
1	1	0	One-quarter of die	180000h–1FFFFFFh	512K x 16	8Mb
1	1	1	One-eighth of die	1C0000h–1FFFFFFh	256K x 16	4Mb

Deep Power-Down (RCR[4]) Default = DPD Disabled

The deep power-down bit enables and disables all refresh-related activity. This mode is used if the system does not require the storage provided by the CellularRAM device. Any stored data will become corrupted when DPD is enabled. When refresh activity has been reenabled, the CellularRAM device will require 150µs to perform an initialization procedure before normal operations can resume.

Deep power-down is enabled when RCR[4] = 0 and remains enabled until RCR[4] is set to “1.” DPD should not be enabled or disabled with the software access sequence; instead, use CRE to access the RCR.

Page Mode Operation (RCR[7]) Default = Disabled

The page mode operation bit determines whether page mode is enabled for asynchronous READ operations. In the power-up default state, page mode is disabled.

Electrical Characteristics

Stresses greater than those listed may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Table 7: Absolute Maximum Ratings

Parameter	Rating
Voltage to any ball except Vcc; VccQ relative to Vss	–0.5V to (4.0V or VccQ + 0.3V, whichever is less)
Voltage on Vcc supply relative to Vss	–0.2V to +2.45V
Voltage on VccQ supply relative to Vss	–0.2V to +4.0V
Storage temperature (plastic)	–55°C to +150°C
Operating temperature (case)	
Wireless ^{note} :	–30°C to +85°C
Industrial	–40°C to +85°C
Soldering temperature and time 10 seconds (solder ball only)	+260°C

Note: –30°C exceeds the CellularRAM Workgroup 1.0 specification of –25°C.

Table 8: Electrical Characteristics and Operating Conditions

Wireless temperature¹ ($-30^{\circ}\text{C} < T_C < +85^{\circ}\text{C}$); industrial temperature ($-40^{\circ}\text{C} < T_C < +85^{\circ}\text{C}$)

Description	Conditions	Symbol		Min	Max	Units	Notes
Supply voltage		V _{CC}		1.7	1.95	V	
I/O supply voltage		V _{CCQ}		1.7	3.6	V	
Input high voltage		V _{IH}		1.4	V _{CCQ} + 0.2	V	2, 3
Input low voltage		V _{IL}		−0.2	0.4	V	4
Output high voltage	I _{OH} = −0.2mA	V _{OH}		0.8 V _{CCQ}	–	V	5
Output low voltage	I _{OL} = +0.2mA	V _{OL}		–	0.2 V _{CCQ}	V	5
Input leakage current	V _{IN} = 0 to V _{CCQ}	I _{LI}		–	1	μA	
Output leakage current	OE# = V _{IH} or chip disabled	I _{LO}		–	1	μA	
Operating Current							
Asynchronous random READ/ WRITE	V _{IN} = V _{CCQ} or 0V chip enabled; I _{OUT} = 0	I _{CC1}	−70	–	20	mA	6
					–		
Asynchronous page READ		I _{CC1P}	−70	–	15	mA	6
					–		
Initial access, burst READ/WRITE		I _{CC2}	104 MHz	–	40	mA	6
			80 MHz		35		
Continuous burst READ		I _{CC3R}	104 MHz	–	25	mA	6
			80 MHz		18		
Continuous burst WRITE		I _{CC3W}	104 MHz	–	40	mA	6
			80 MHz		35		
Standby current	V _{IN} = V _{CCQ} or 0V CE# = V _{CCQ}	I _{SB}	Standard	– – –	110	μA	7

- Notes:
1. -30°C exceeds the CellularRAM Workgroup 1.0 specification of -25°C .
 2. Input signals may overshoot to V_{CCQ} + 1.0V for periods less than 2ns during transitions.
 3. V_{IH} (MIN) value is not aligned with CellularRAM Workgroup 1.0 specification of V_{CCQ} - 0.4V.
 4. Input signals may undershoot to V_{SS} - 1.0V for periods less than 2ns during transitions.
 5. BCR[5] = 0b.
 6. This parameter is specified with the outputs disabled to avoid external loading effects. The user must add the current required to drive output capacitance expected in the actual system.
 7. I_{SB} (MAX) values measured with PAR set to FULL ARRAY. To achieve low standby current, all inputs must be driven either to V_{CCQ} or V_{SS}. I_{SB} might be slightly higher for up to 500ms after power-up, after changes to the PAR array partition, or when entering standby mode.

Maximum and Typical Standby Currents

The following table and figure refer to the maximum and typical standby currents for the MT45W2MW16BGB device. The typical values shown in Figure 25 are measured with the default on-chip temperature sensor control enabled.

Table 9: Partial-Array Refresh Specifications and Conditions

Description	Conditions	Symbol		Array Partition	Max	Unit
Partial-array refresh standby current	$V_{IN} = V_{CCQ}$ or 0V; $CE\# = V_{CCQ}$	IPAR	Standard power (no designation)	Full	110	μA
				1/2	105	
				1/4	95	
				1/8	95	
				0	70	

Note: IPAR (MAX) values measured at 85°C. IPAR might be slightly higher for up to 500ms after changes to the PAR array partition or when entering standby mode. To achieve low standby current, all inputs must be driven either to V_{CCQ} or V_{SS} .

Figure 25: Typical Refresh Current vs. Temperature

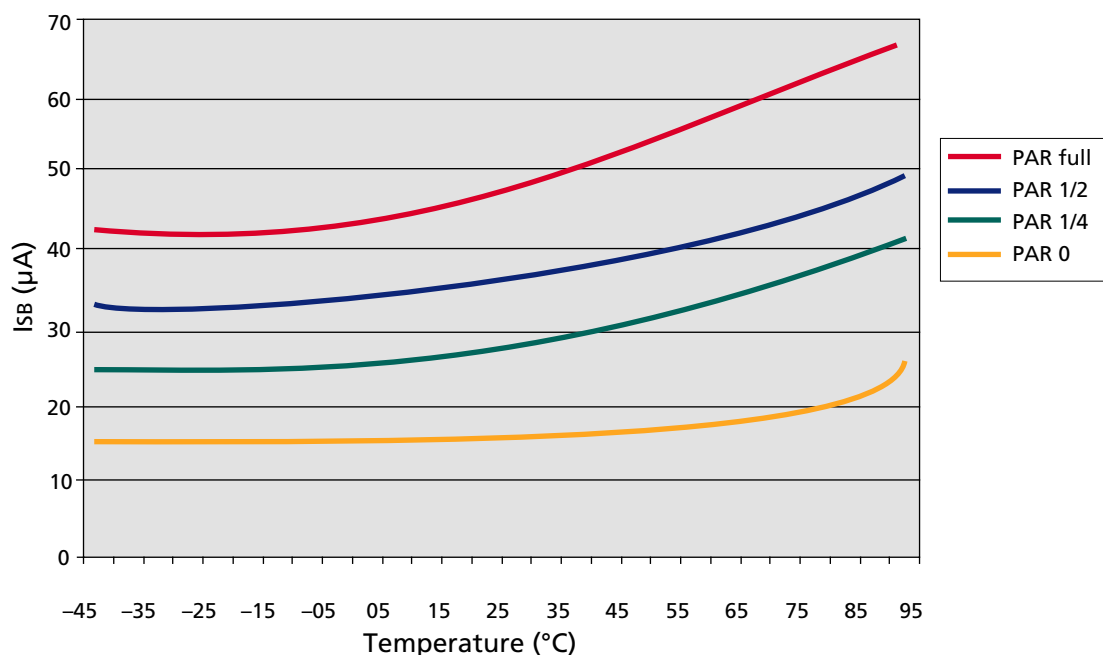


Table 10: Deep Power-Down Specifications

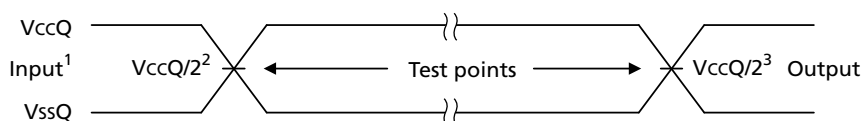
Description	Conditions	Symbol	Typ	Units
Deep power-down	$V_{IN} = V_{CCQ}$ or $0V$; $+25^{\circ}C$	I_{ZZ}	10	μA

Table 11: Capacitance

Description	Conditions	Symbol	Min	Max	Units	Notes
Input capacitance	$T_C = +25^{\circ}C$; $f = 1\text{ MHz}$; $V_{IN} = 0V$	C_{IN}	2.0	6.5	pF	Note:
Input/output capacitance (DQ)		C_{IO}	3.0	6.5	pF	Note:

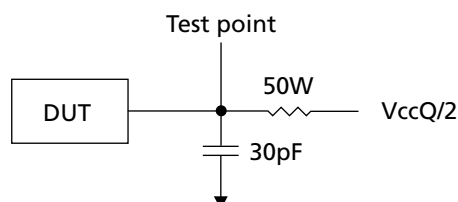
Note: These parameters are verified in device characterization and are not 100% tested.

Figure 26: AC Input/Output Reference Waveform



- Notes:
1. AC test inputs are driven at V_{CCQ} for a logic 1 and V_{SSQ} for a logic 0. Input rise and fall times (10% to 90%) $< 1.6ns$.
 2. Input timing begins at $V_{CCQ}/2$.
 3. Output timing ends at $V_{CCQ}/2$.

Figure 27: Output Load Circuit



Note: All tests are performed with the outputs configured for full drive strength (BCR[5] = 0b).

Timing Requirements

Table 12: Asynchronous READ Cycle Timing Requirements

Parameter ¹	Symbol	70ns		Units	Notes
		Min	Max		
Address access time	t_{AA}	–	70	ns	
ADV# access time	t_{AADV}	–	70	ns	
Page access time	t_{APA}	–	20	ns	
Address hold from ADV# HIGH	t_{AVH}	5	–	ns	
Address setup to ADV# HIGH	t_{AVS}	5	–	ns	
LB#/UB# access time	t_{BA}	–	70	ns	
LB#/UB# disable to DQ High-Z output	t_{BHZ}	–	8	ns	2
LB#/UB# enable to Low-Z output	t_{BLZ}	10	–	ns	3
Maximum CE# pulse width	t_{CEM}	–	8	μs	4
CE# LOW to WAIT valid	t_{CEW}	1	7.5	ns	
Chip select access time	t_{CO}	–	70	ns	
CE# LOW to ADV# HIGH	t_{CVS}	10	–	ns	
Chip disable to DQ and WAIT High-Z output	t_{HZ}	–	8	ns	2
Chip enable to Low-Z output	t_{LZ}	10	–	ns	3
Output enable to valid output	t_{OE}	–	20	ns	
Output hold from address change	t_{OH}	5	–	ns	
Output disable to DQ High-Z output	t_{OHZ}	–	8	ns	2
Output enable to Low-Z output	t_{OLZ}	3	–	ns	3
Page cycle time	t_{PC}	20	–	ns	
READ cycle time	t_{RC}	70	–	ns	
ADV# pulse width LOW	t_{VP}	10	–	ns	
ADV# pulse width HIGH	t_{VPH}	10	–	ns	

- Notes:
1. All tests are performed with the outputs configured for full drive strength (BCR[5] = 0b).
 2. Low-Z to High-Z timings are tested with the circuit shown in Figure 27 on page 35. The High-Z timings measure a 100mV transition either from V_{OH} or V_{OL} toward $V_{CCQ}/2$.
 3. High-Z to Low-Z timings are tested with the circuit shown in Figure 27 on page 35. The Low-Z timings measure a 100mV transition away from the High-Z ($V_{CCQ}/2$) level either toward V_{OH} or V_{OL} .
 4. Page mode enabled only.

Table 13: Burst READ Cycle Timing Requirements

Parameter ¹	Symbol	104 MHz		80 MHz		Units	Notes
		Min	Max	Min	Max		
Burst to READ access time	^t ABA	–	35.9	–	46.5	ns	
CLK to output delay	^t ACLK	–	7	–	9	ns	
Burst OE# LOW to output delay	^t BOE	–	20	–	20	ns	
CE# HIGH between subsequent burst and mixed-mode operations	^t CBPH	5	–	5	–	ns	2
Maximum CE# pulse width	^t CEM	–	8	–	8	μs	
CE# LOW to WAIT valid	^t CEW	1	7.5	1	7.5	ns	
CLK period	^t CLK	9.62	–	12.5	–	ns	
CE# setup time to active CLK edge	^t CSP	3	–	4.5	–	ns	
Hold time from active CLK edge	^t HD	2	–	2	–	ns	
Chip disable to DQ and WAIT High-Z output	^t HZ	–	8	–	8	ns	3
CLK rise or fall time	^t KHKL	–	1.6	–	1.8	ns	
CLK to WAIT valid	^t KHTL	–	7	–	9	ns	
Output HOLD from CLK	^t KOH	2	–	2	–	ns	
CLK HIGH or LOW time	^t KP	3	–	4	–	ns	
Output disable to DQ High-Z output	^t OHZ	–	8	–	8	ns	3
Output enable to Low-Z output	^t OLZ	3	–	3	–	ns	4
Setup time to active CLK edge	^t SP	3	–	3	–	ns	

- Notes:
1. All tests are performed with the outputs configured for full drive strength (BCR[5] = 0b).
 2. When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every ^tCEM. A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns.
 3. Low-Z to High-Z timings are tested with the circuit shown in Figure 27 on page 35. The High-Z timings measure a 100mV transition either from V_{OH} or V_{OL} toward V_{CCQ}/2.
 4. High-Z to Low-Z timings are tested with the circuit shown in Figure 27 on page 35. The Low-Z timings measure a 100mV transition away from the High-Z (V_{CCQ}/2) level either toward V_{OH} or V_{OL}.

Table 14: Asynchronous WRITE Cycle Timing Requirements

Parameter	Symbol	70ns		Units	Notes
		Min	Max		
Address and ADV# LOW setup time	t_{AS}	0	–	ns	
Address hold from ADV# going HIGH	t_{AVH}	5	–	ns	
Address setup to ADV# going HIGH	t_{AVS}	5	–	ns	
Address valid to end of WRITE	t_{AW}	70	–	ns	
LB#/UB# select to end of WRITE	t_{BW}	70	–	ns	
CE# LOW to WAIT valid	t_{CEW}	1	7.5	ns	
Asynchronous address-to-burst transition time	t_{CKA}	70	–	ns	
CE# HIGH between subsequent asynchronous operations	t_{CPH}	5	–	ns	
CE# LOW to ADV# HIGH	t_{CVS}	10	–	ns	
Chip enable to end of WRITE	t_{CW}	70	–	ns	
Data hold from WRITE time	t_{DH}	0	–	ns	
Data WRITE setup time	t_{DW}	23	–	ns	
Chip disable to WAIT High-Z output	t_{HZ}	–	8	ns	
Chip enable to Low-Z output	t_{LZ}	10	–	ns	2
End WRITE to Low-Z output	t_{OW}	5	–	ns	1
ADV# pulse width	t_{VP}	10	–	ns	
ADV# pulse width HIGH	t_{VPH}	10	–	ns	
ADV# setup to end of WRITE	t_{VS}	70	–	ns	
WRITE cycle time	t_{WC}	70	–	ns	
WRITE to DQ High-Z output	t_{WHZ}	–	8	ns	2
WRITE pulse width	t_{WP}	46	–	ns	3
WRITE pulse width HIGH	t_{WPH}	10	–	ns	
WRITE recovery time	t_{WR}	0	–	ns	

- Notes:
1. High-Z to Low-Z timings are tested with the circuit shown in Figure 27 on page 35. The Low-Z timings measure a 100mV transition away from the High-Z ($V_{CCQ}/2$) level either toward V_{OH} or V_{OL} .
 2. Low-Z to High-Z timings are tested with the circuit shown in Figure 27 on page 35. The High-Z timings measure a 100mV transition either from V_{OH} or V_{OL} toward $V_{CCQ}/2$.
 3. $WE\#$ LOW time must be limited to t_{CEM} (8 μ s).

Table 15: Burst WRITE Cycle Timing Requirements

Parameter	Symbol	104 MHz		80 MHz		Units	Notes
		Min	Max	Min	Max		
CE# HIGH between subsequent burst and mixed-mode operations	t_{CBPH}	5	–	5	–	ns	1
Maximum CE# pulse width	t_{CEM}	–	8	–	8	μs	1
CE# LOW to WAIT valid	t_{CEW}	1	7.5	1	7.5	ns	
Clock period	t_{CLK}	9.62	–	12.5	–	ns	
CE# setup to CLK active edge	t_{CSP}	3	–	4.5	–	ns	
Hold time from active CLK edge	t_{HD}	2	–	2	–	ns	
Chip disable to WAIT High-Z output	t_{HZ}	–	8	–	8	ns	
CLK rise or fall time	t_{KHKL}	–	1.6	–	1.8	ns	
Clock to WAIT valid	t_{KHTL}	–	7	–	9	ns	
CLK HIGH or LOW time	t_{KP}	3	–	4	–	ns	
Setup time to active CLK edge	t_{SP}	3	–	3	–	ns	

Note: When configured for synchronous mode ($BCR[15] = 0$), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns.

Figure 28: Initialization Period

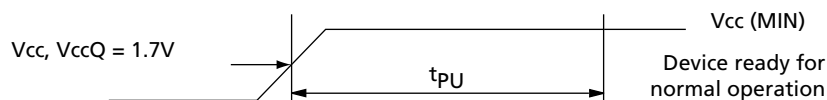


Table 16: Initialization Timing Parameters

Parameter	Symbol	-70		Units
		Min	Max	
Initialization period (required before normal operations)	t_{PU}	150	–	μs

Timing Diagrams

Figure 29: Asynchronous READ

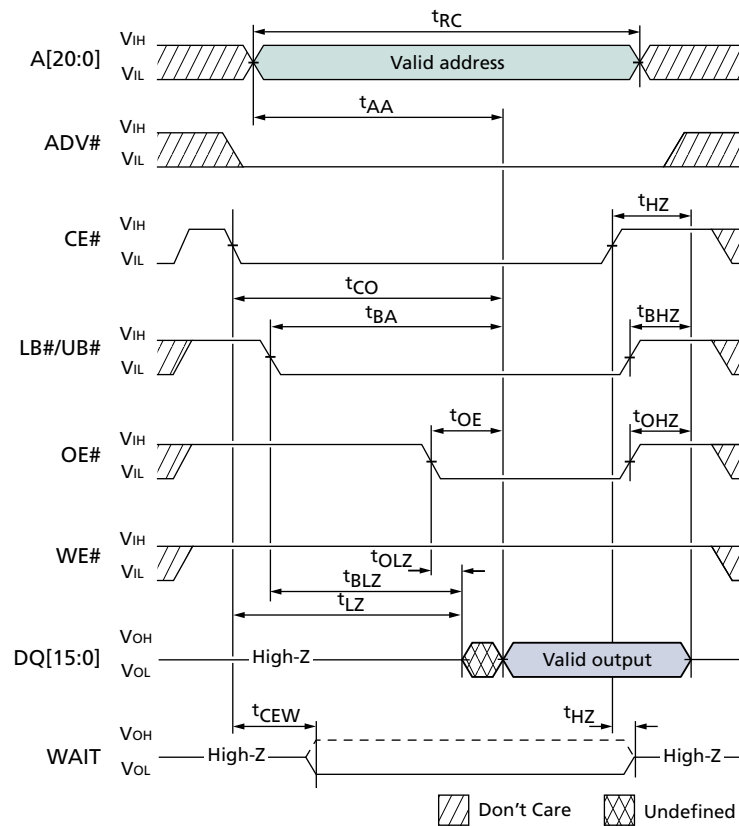


Figure 30: Asynchronous READ Using ADV#

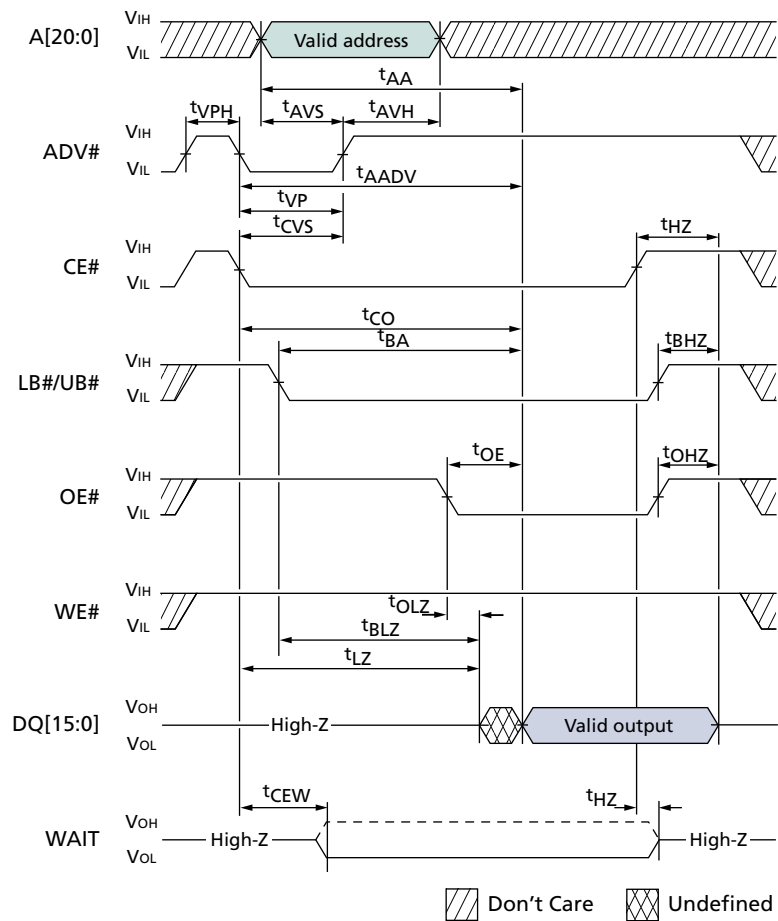


Figure 31: Page Mode READ

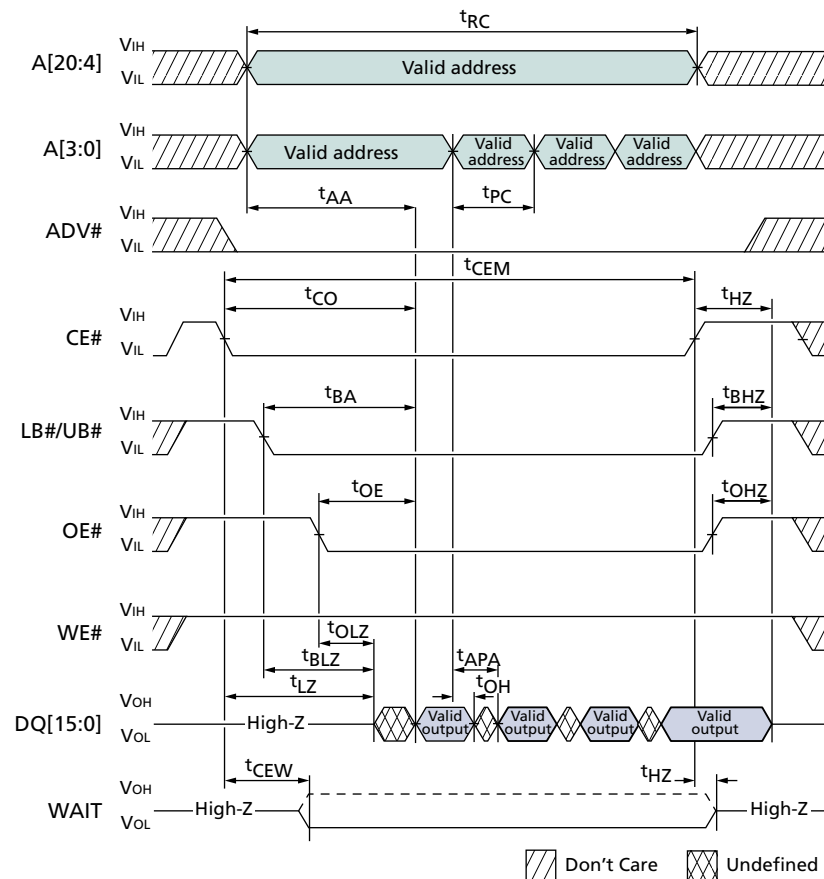
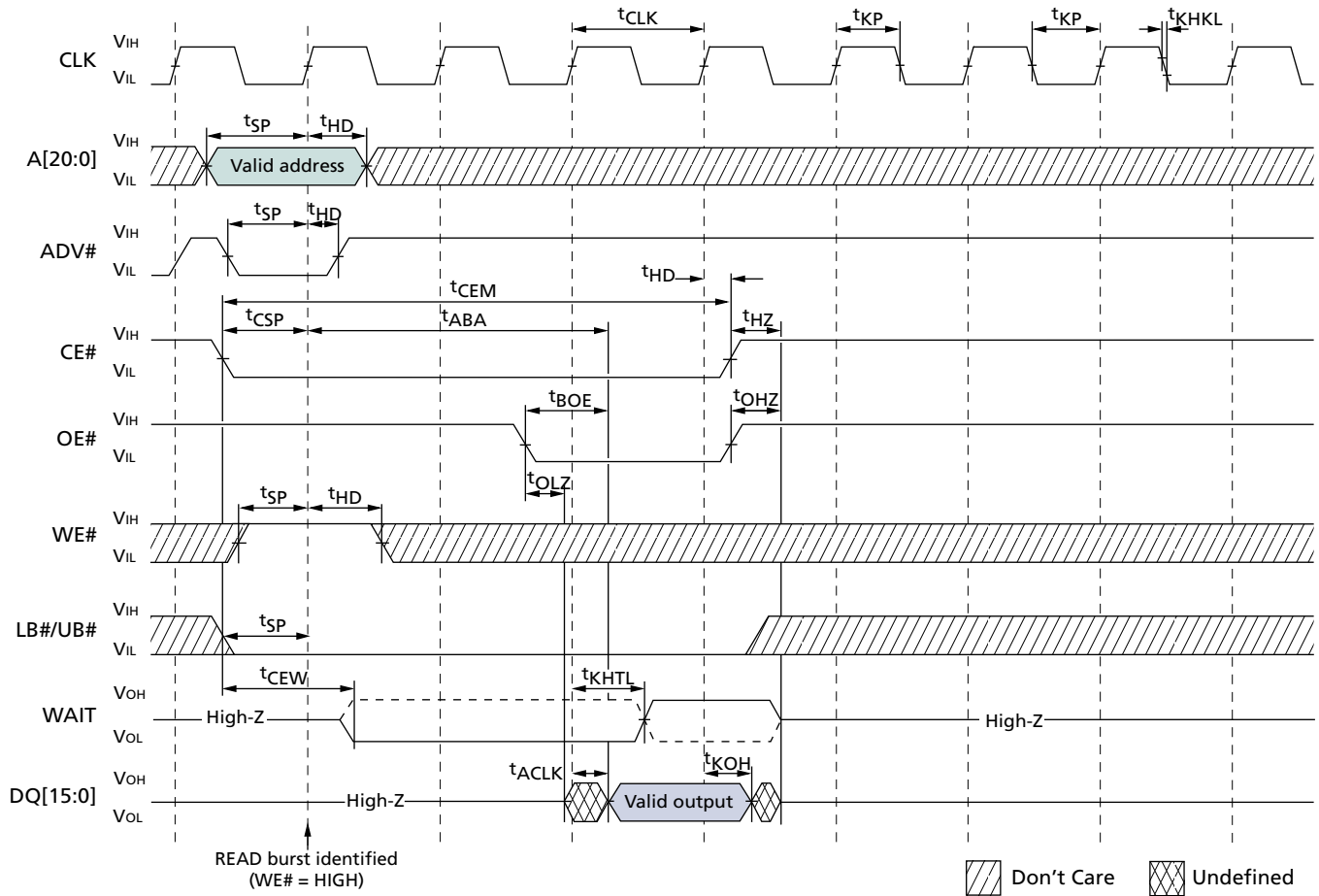
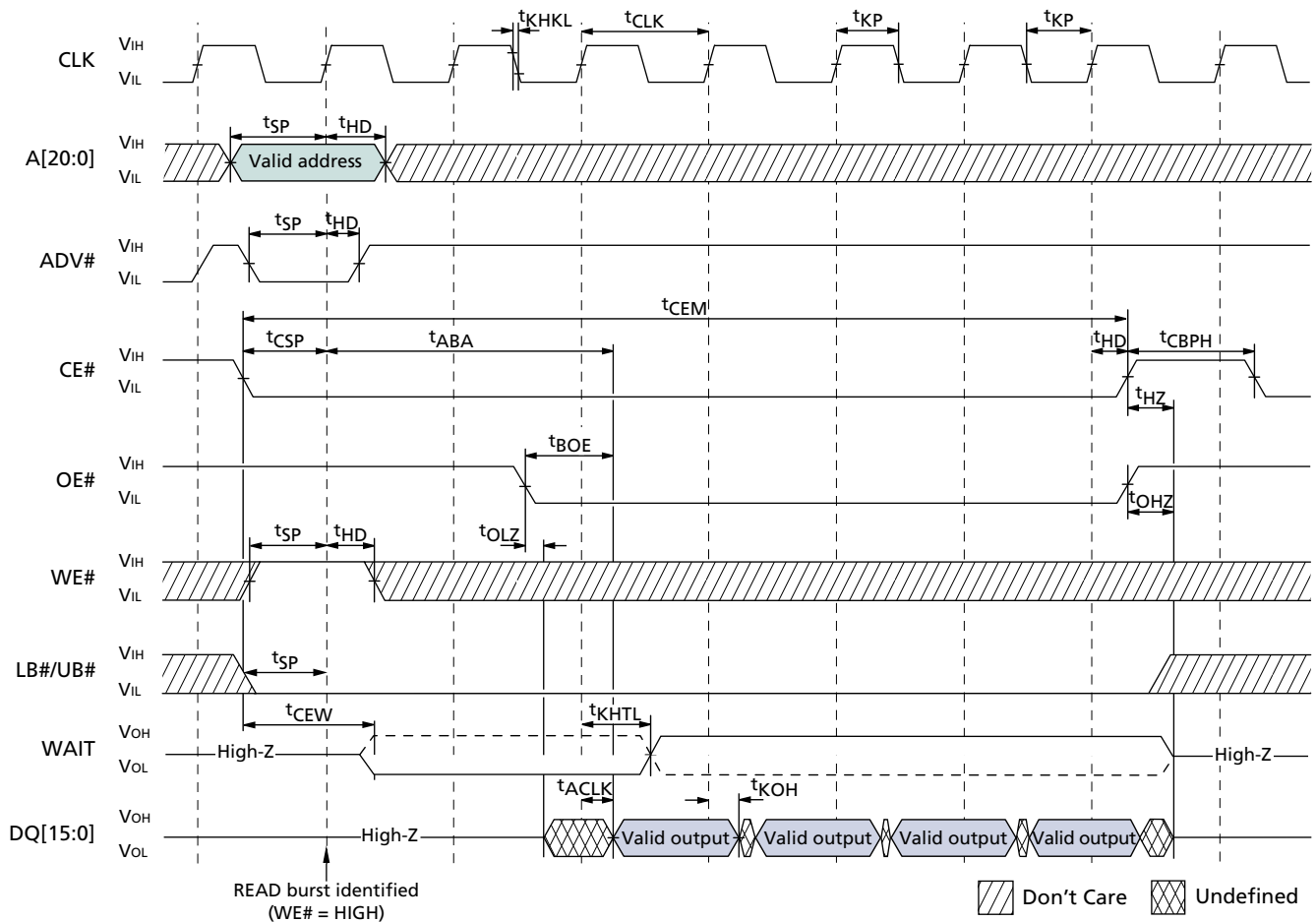


Figure 32: Single-Access Burst READ Operation



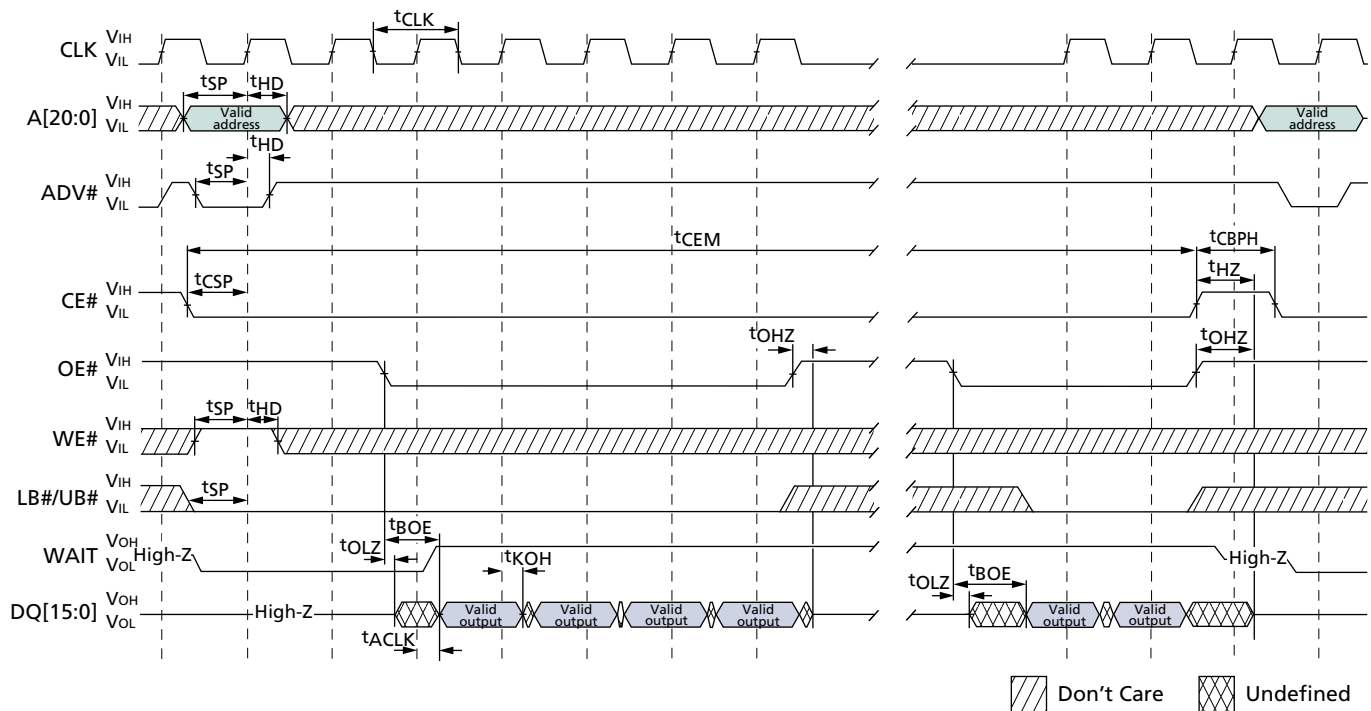
Note: Nondefault BCR settings for single-access burst READ operation: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Figure 33: 4-Word Burst READ Operation



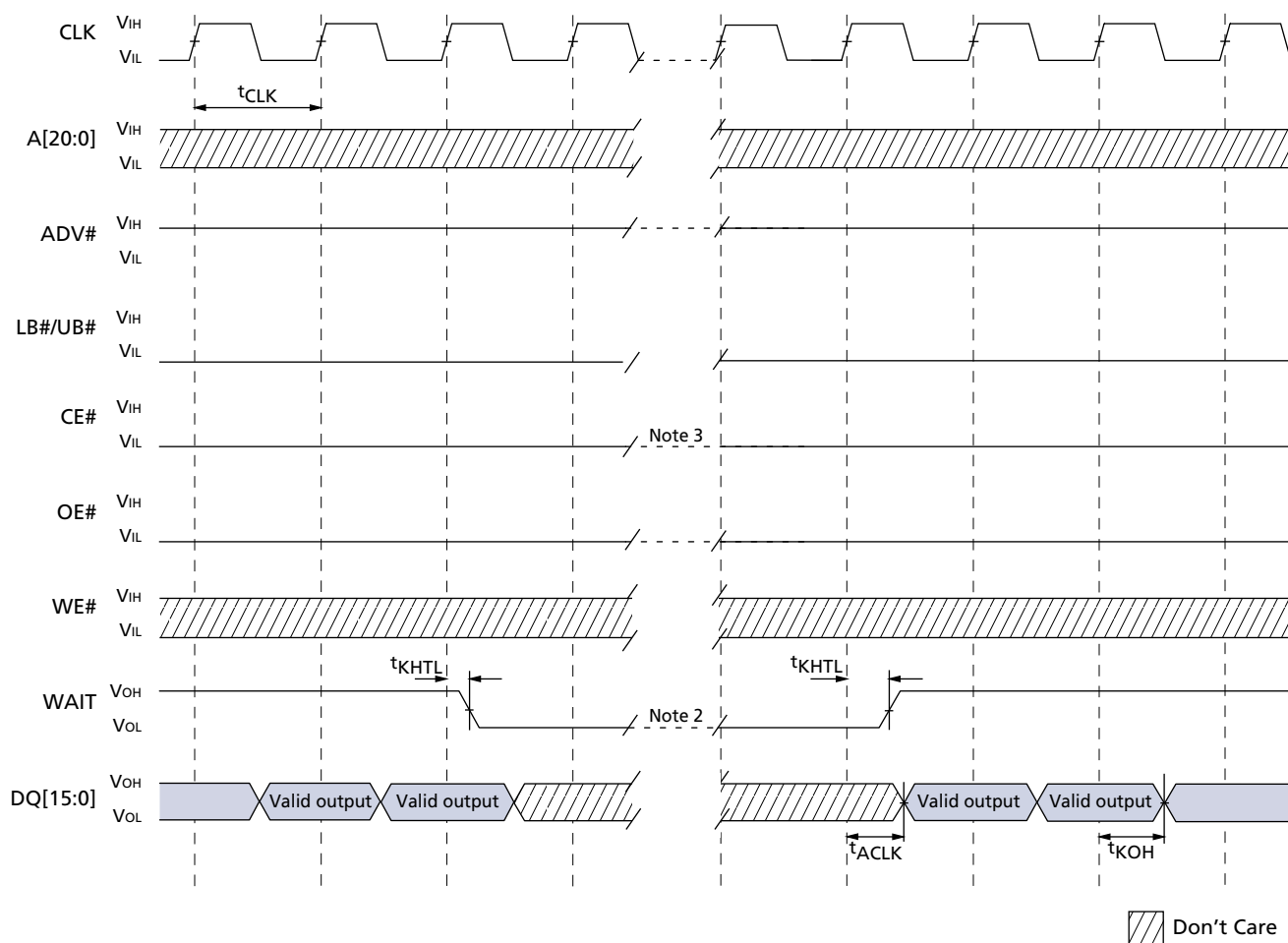
Note: Nondefault BCR settings for 4-word burst READ operation: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Figure 34: READ Burst Suspend



Note: Nondefault BCR settings for READ burst suspend: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.

Figure 35: Output Delay in Continuous Burst READ with BCR[8] = 0 for End-of-Row Condition



- Notes:
1. Nondefault BCR settings for continuous burst READ showing an output delay, BCR[8] = 0 for end-of-row condition: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. WAIT will be asserted a maximum of LC cycles (BCR[8] = 0; WAIT asserted during delay). LC = latency code (BCR[13:11]).
 3. CE# must not remain LOW longer than t_{CEM} .

Figure 36: CE#-Controlled Asynchronous WRITE

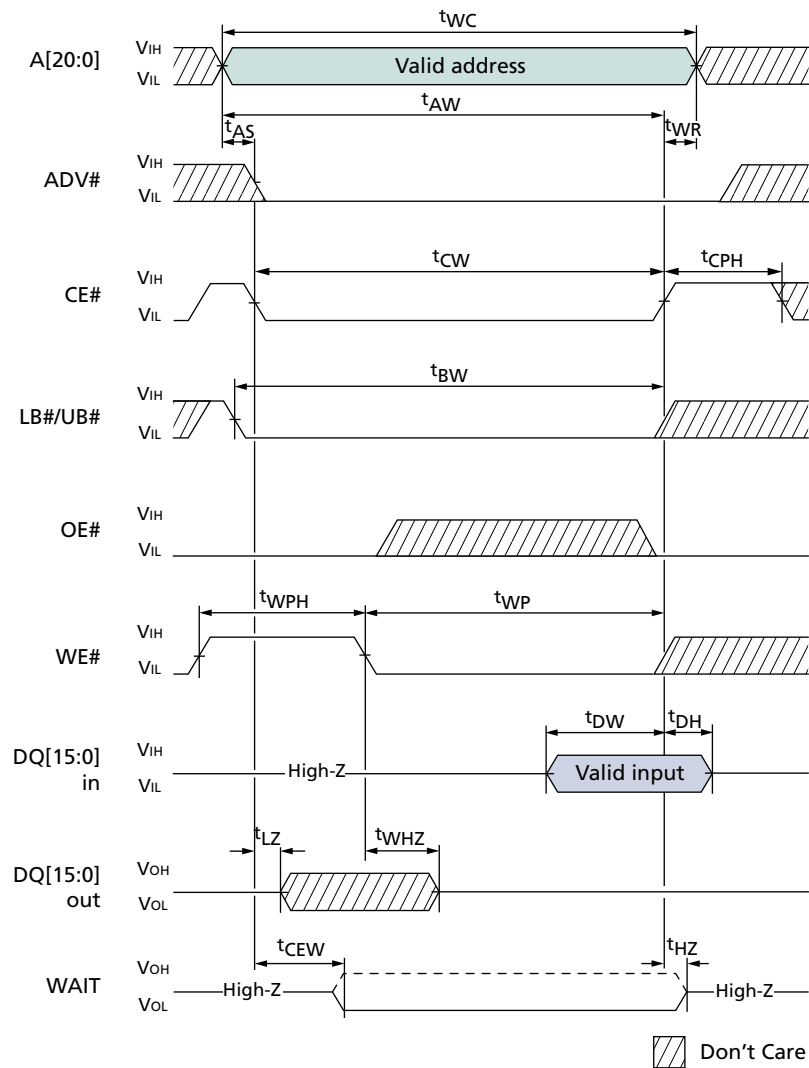


Figure 37: LB#/UB#-Controlled Asynchronous WRITE

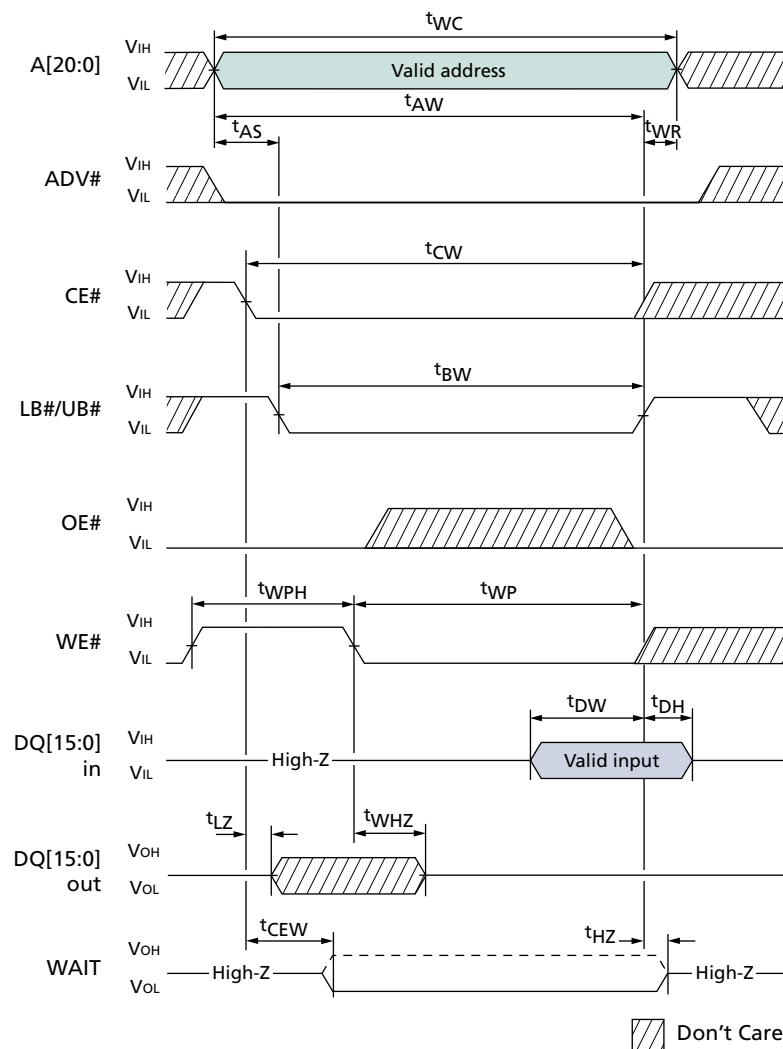


Figure 38: WE#-Controlled Asynchronous WRITE

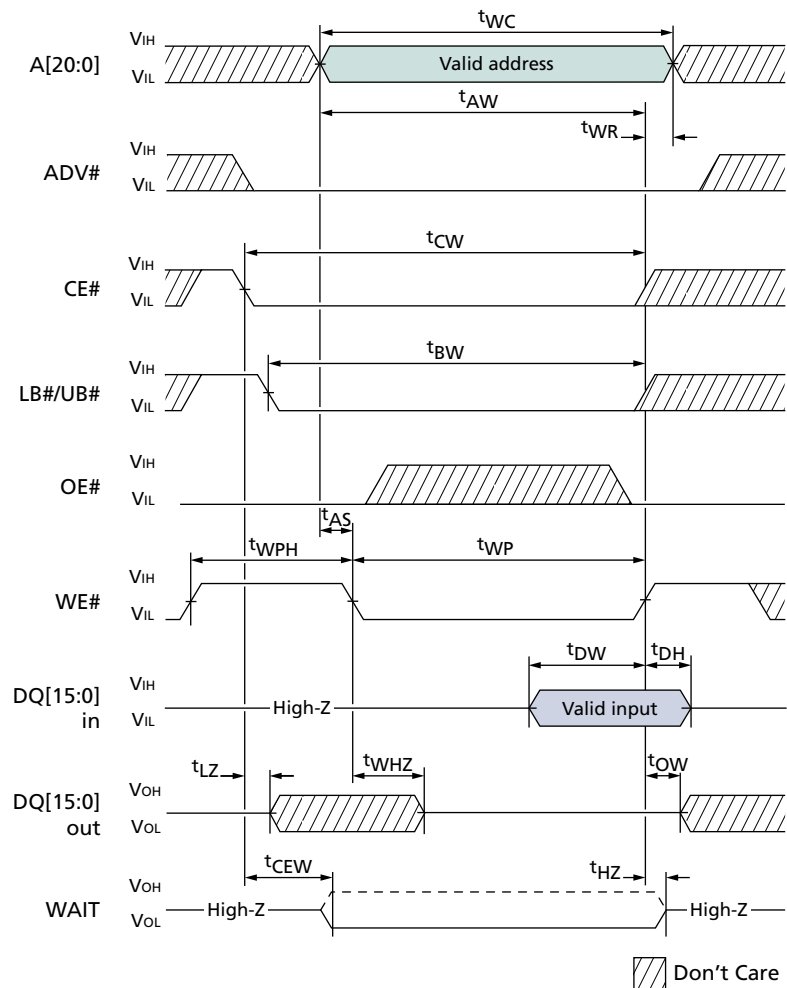


Figure 39: Asynchronous WRITE Using ADV#

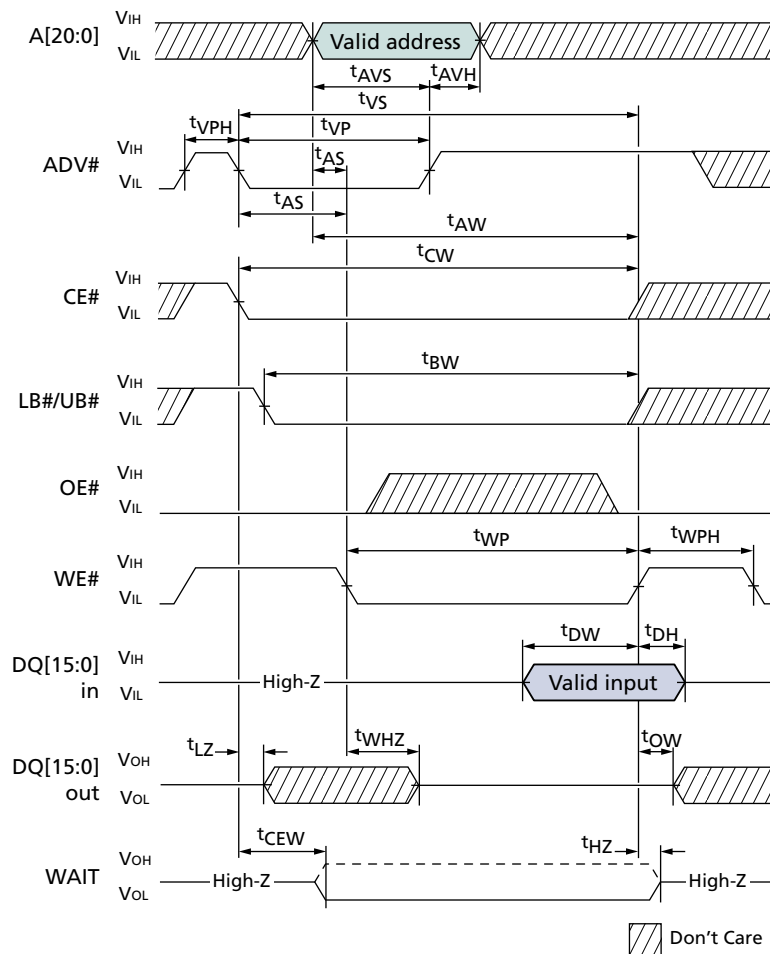
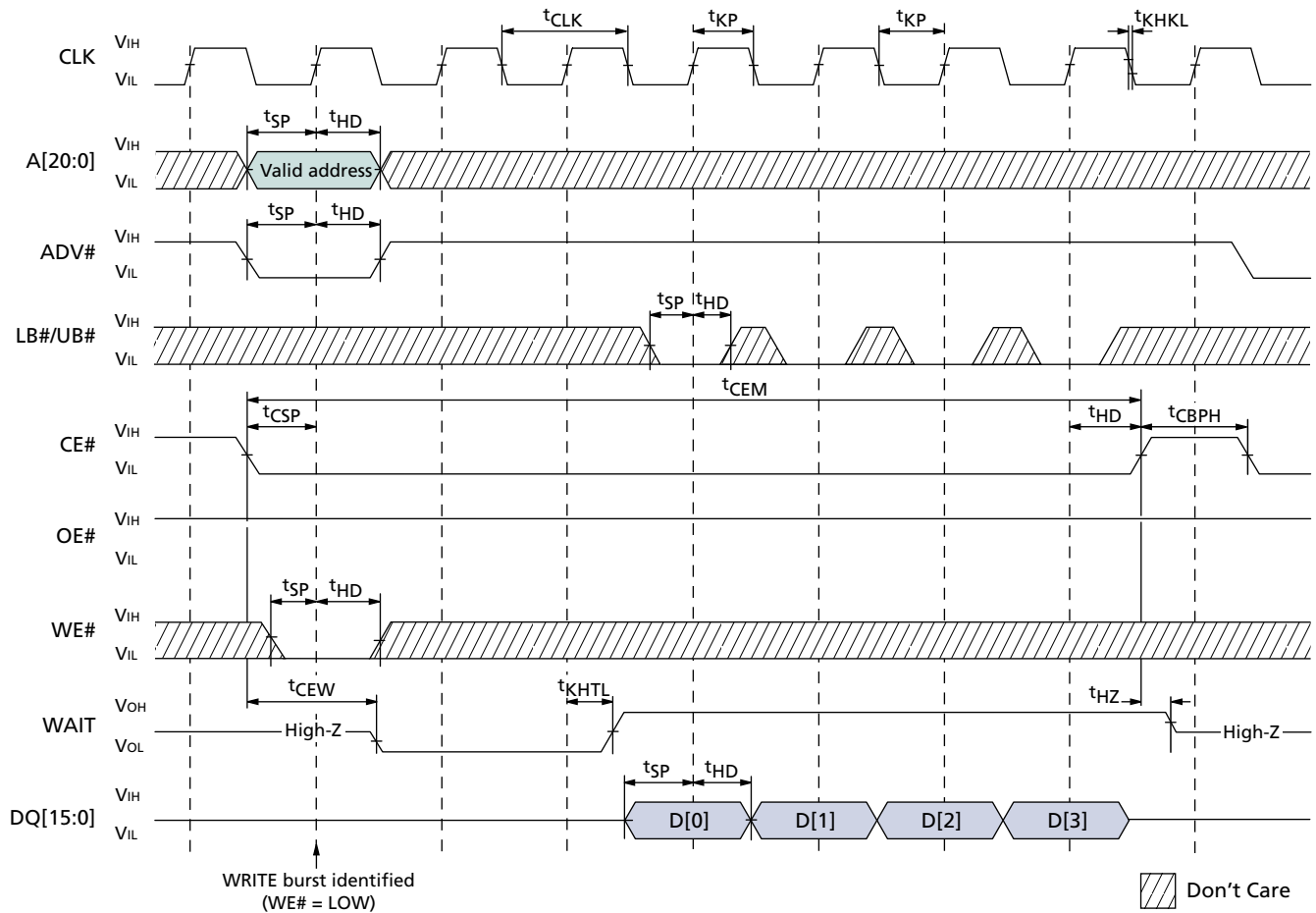
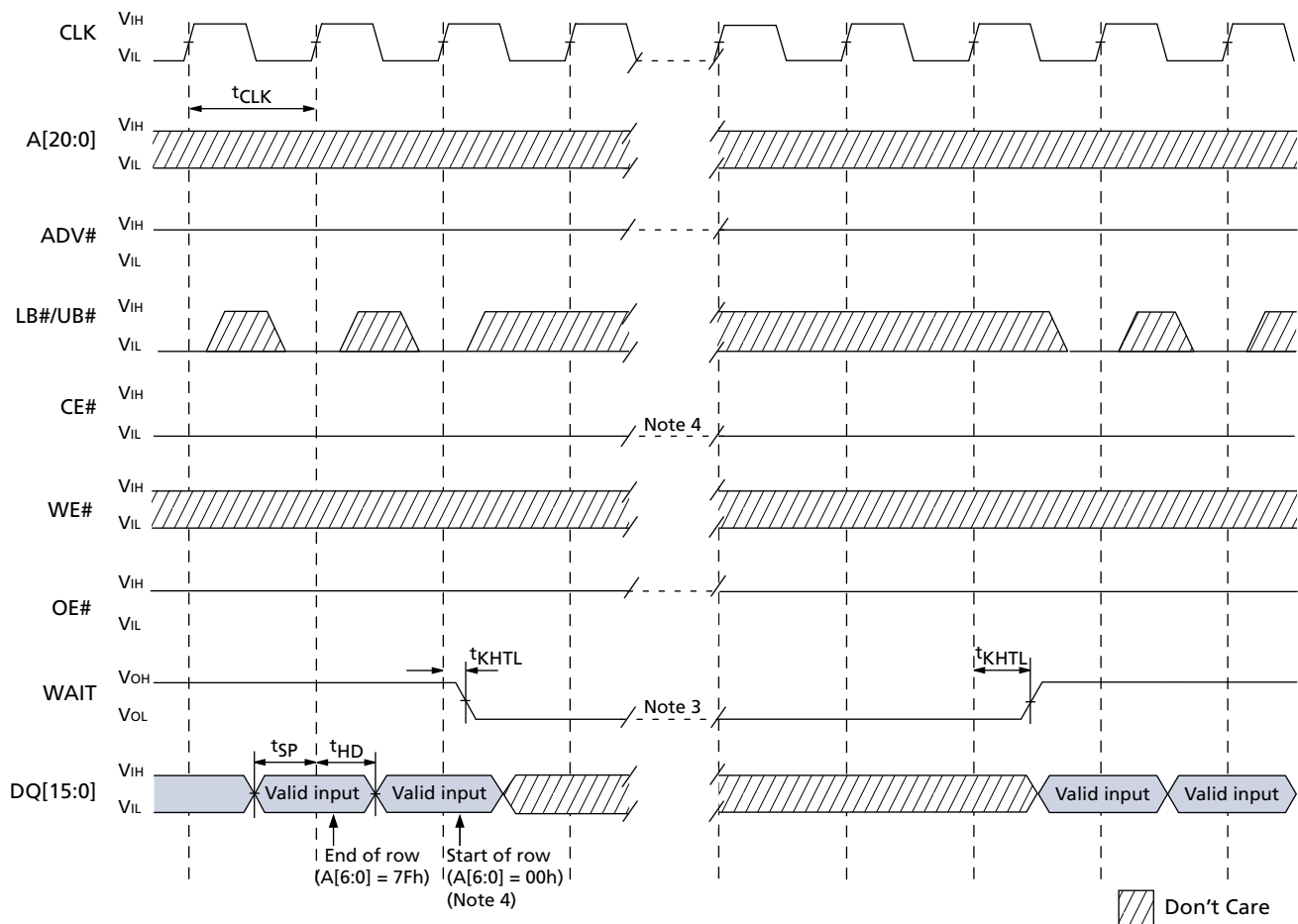


Figure 40: Burst WRITE Operation



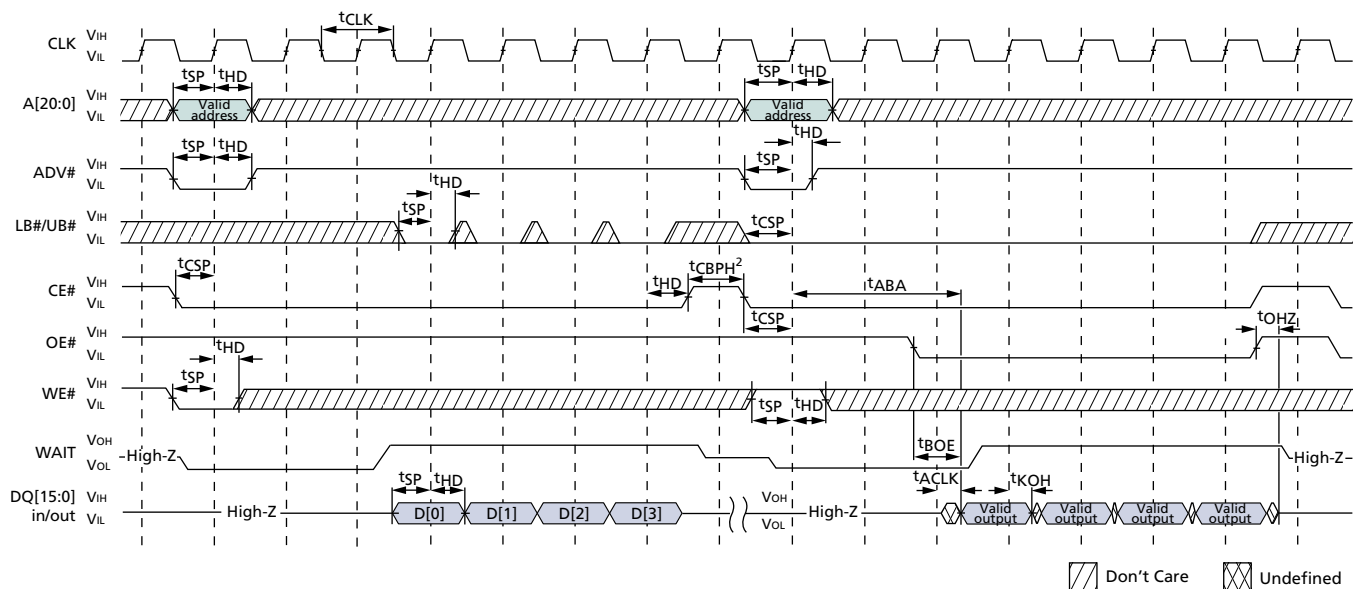
Note: Nondefault BCR settings for burst WRITE operation: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted.

Figure 41: Output Delay in Continuous Burst WRITE with BCR[8] = 0 for End-of-Row Condition



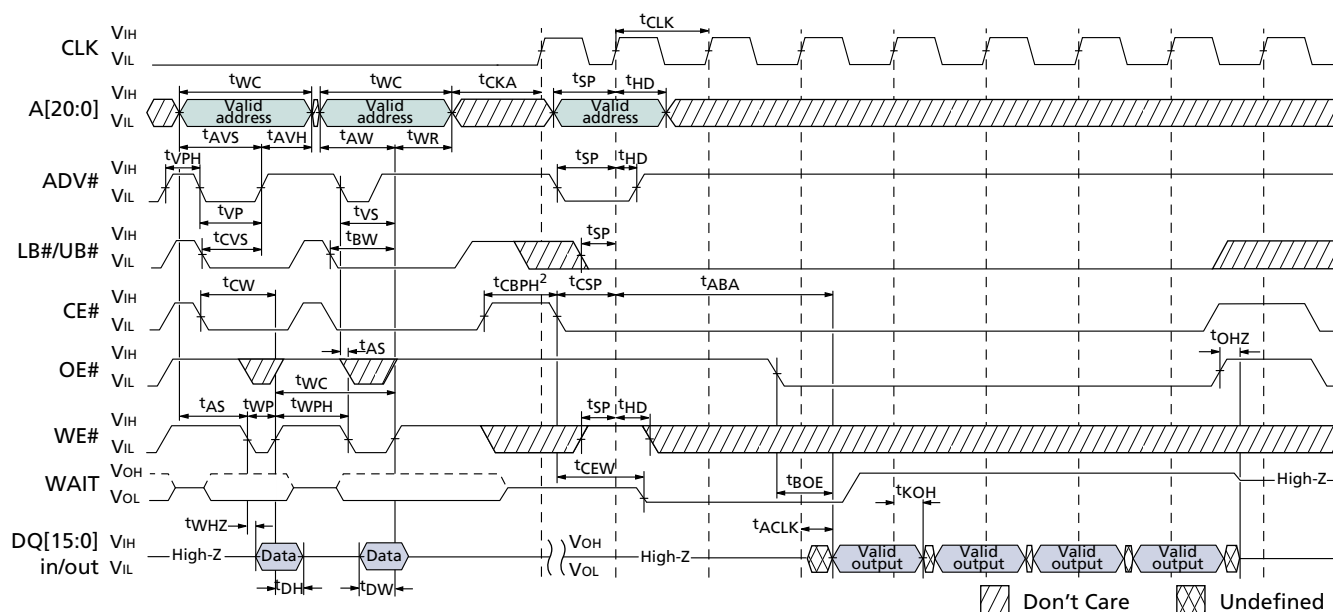
- Notes:
1. Nondefault BCR settings for continuous burst WRITE, BCR[8] = 0; WAIT active LOW; WAIT asserted during delay. Do not cross row boundaries with fixed latency.
 2. CE# must not remain LOW longer than t_{CEM} .
 3. WAIT asserts anywhere from LC to 2LC cycles. LC = latency code (BCR[13:11]).
 4. Taking CE# HIGH or ADV# LOW on the start-of-row cycle will abort the burst and not write the start-of-row data. Devices from different CellularRAM vendors can assert WAIT so that the start-of-row data is input just before (as shown) or just after WAIT asserts. This difference in behavior will not be noticed by controllers that monitor WAIT or that use WAIT to abort on the start-of-row input cycle.

Figure 42: Burst WRITE Followed by Burst READ



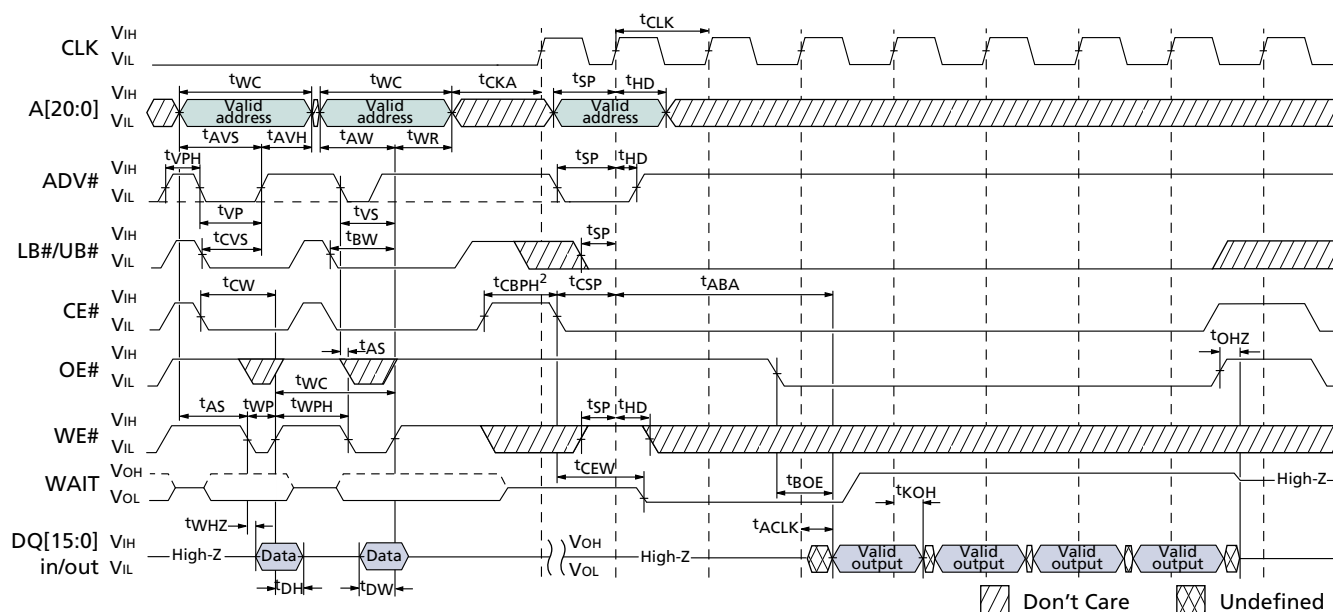
- Notes:
1. Nondefault BCR settings for burst WRITE followed by burst READ: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns. Note that the CellularRAM Workgroup 1.0 specification requires CE# to be clocked HIGH to terminate the burst.

Figure 43: Asynchronous WRITE Followed by Burst READ



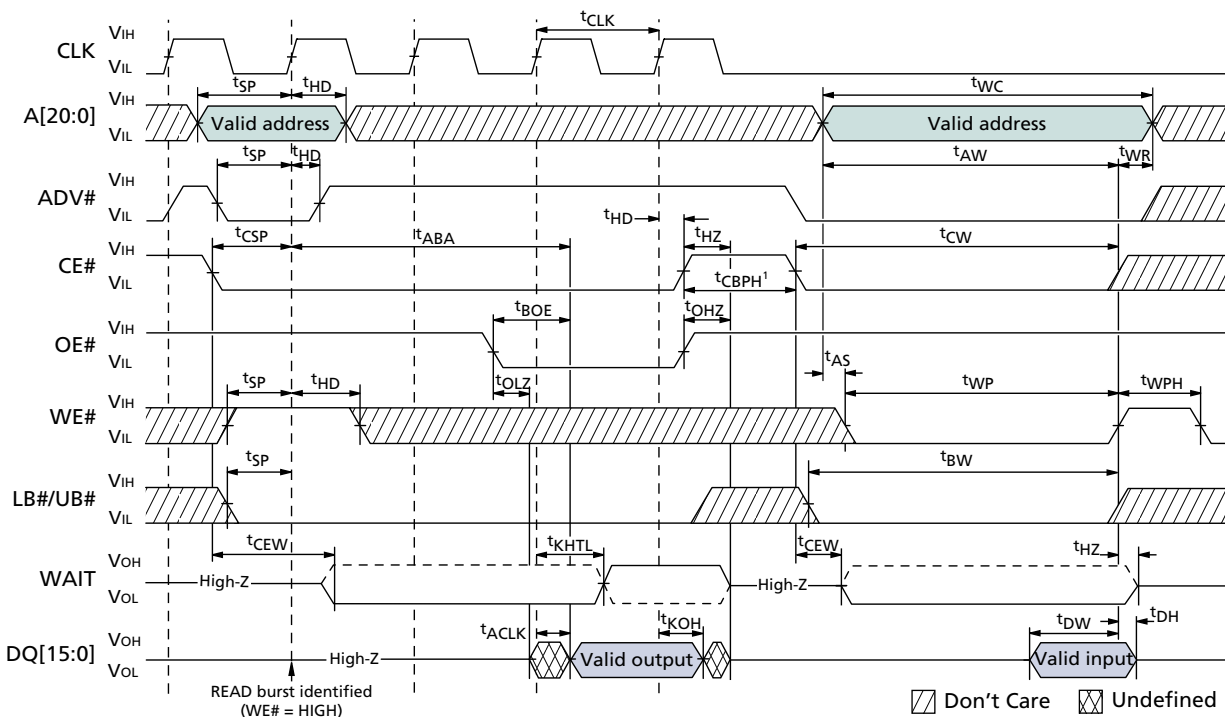
- Notes:
1. Nondefault BCR settings for asynchronous WRITE followed by burst READ: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns. Note that the CellularRAM Workgroup 1.0 specification requires CE# to be clocked HIGH to terminate the burst.

Figure 44: Asynchronous WRITE Followed by Burst READ with ADV# LOW



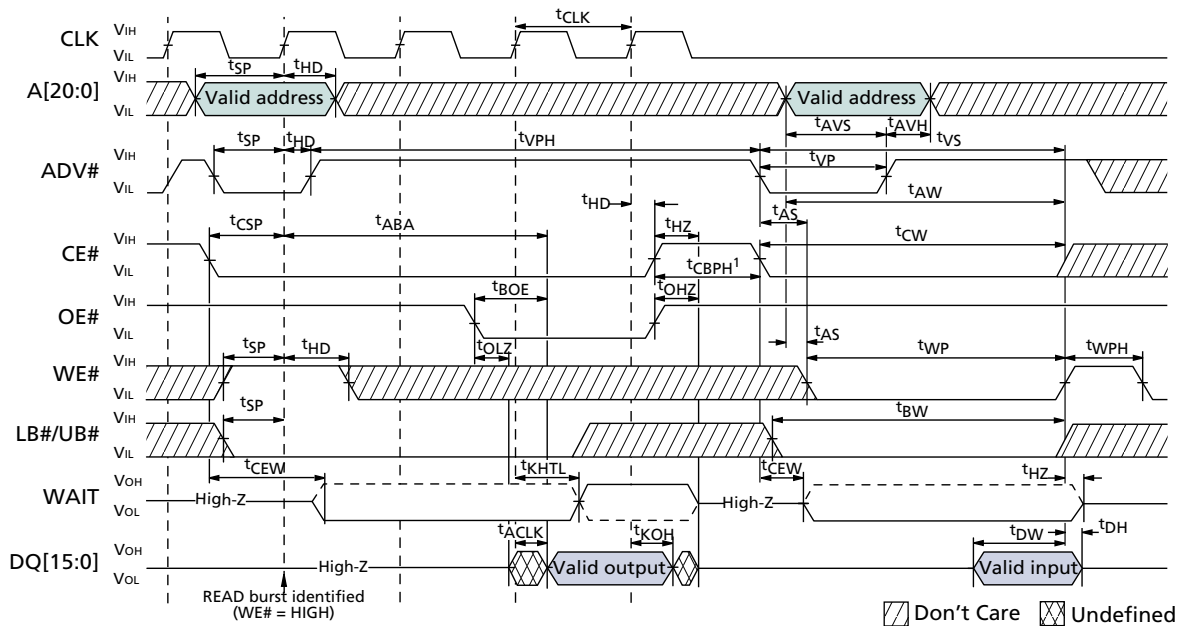
- Notes:
1. Nondefault BCR settings for asynchronous WRITE followed by burst READ: latency code 2 (3 clocks); WAIT active LOW; WAIT asserted during delay.
 2. When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of these conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns. Note that the CellularRAM Workgroup 1.0 specification requires CE# to be clocked HIGH to terminate the burst.

Figure 45: Burst READ Followed by Asynchronous WRITE (WE#-Controlled)



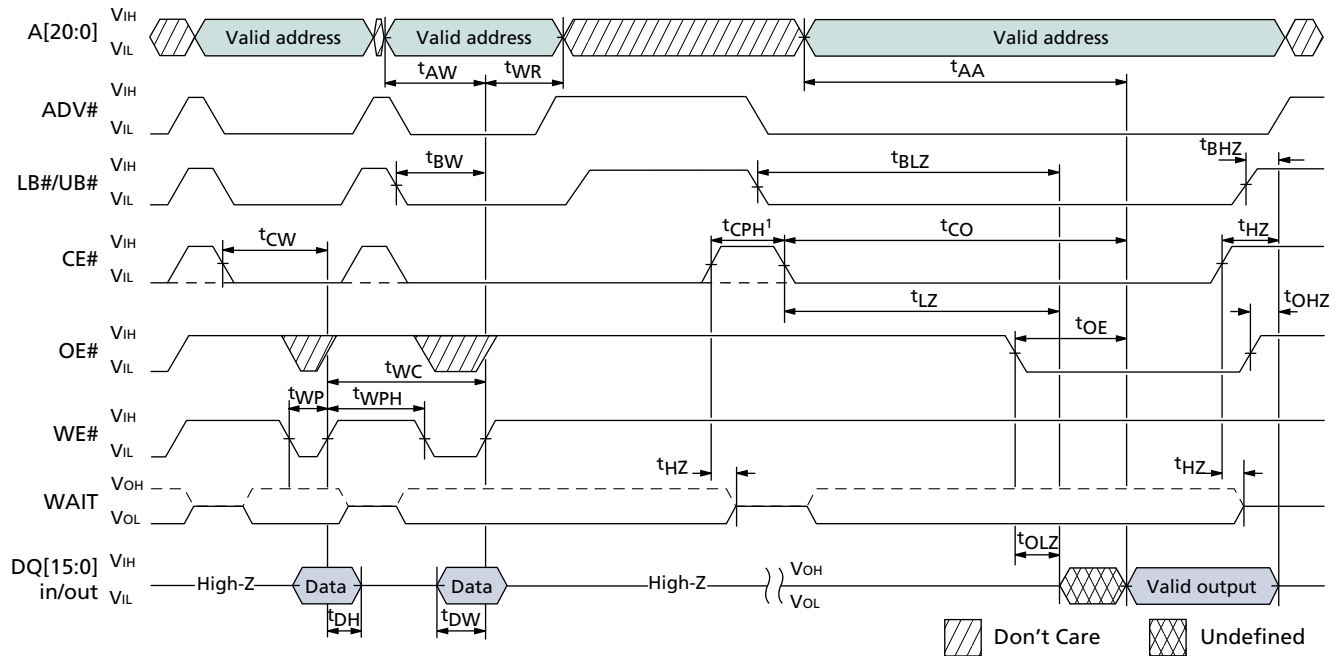
Note: When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns. Note that CellularRAM Workgroup specification 1.0 requires CE# to be clocked HIGH to terminate the burst.

Figure 46: Burst READ Followed by Asynchronous WRITE Using ADV#



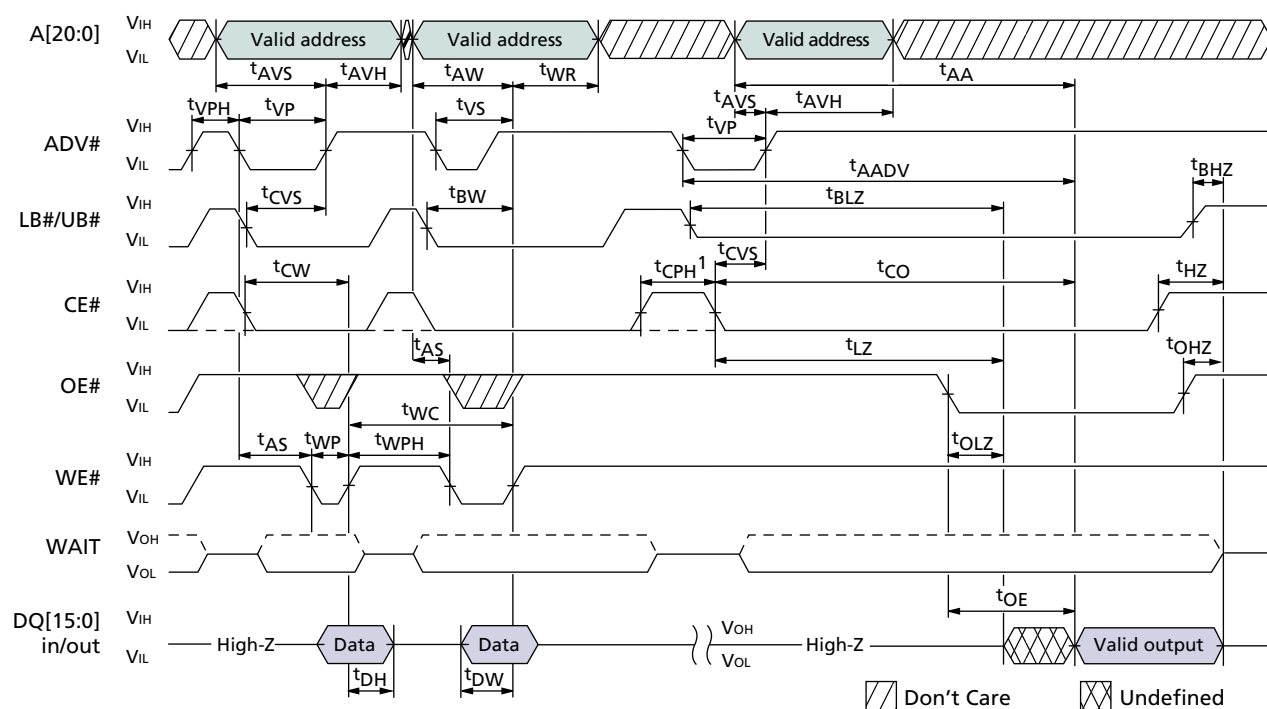
Note: When configured for synchronous mode (BCR[15] = 0), a refresh opportunity must be provided every t_{CEM} . A refresh opportunity is satisfied by either of the following two conditions: clocked CE# HIGH or CE# HIGH for greater than 15ns. Note that CellularRAM Workgroup specification 1.0 requires CE# to be clocked HIGH to terminate the burst.

Figure 47: Asynchronous WRITE Followed by Asynchronous READ with ADV# LOW



Note: When configured for synchronous mode ($BCR[15] = 0$), $CE\#$ must remain HIGH for at least 5ns (t_{CPH}) to schedule the appropriate internal refresh operation. Otherwise, t_{CPH} is only required after $CE\#$ -controlled WRITES.

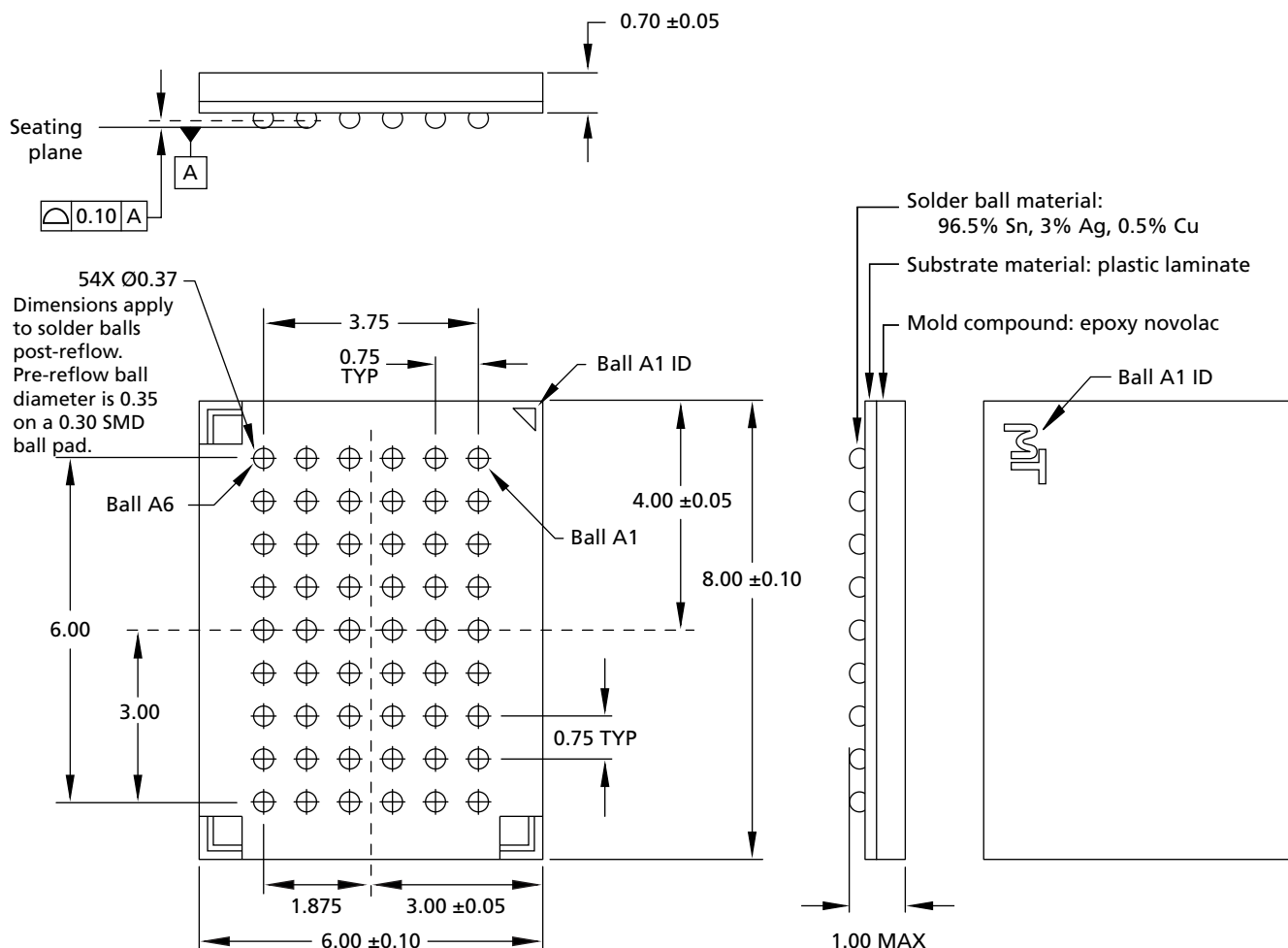
Figure 48: Asynchronous WRITE Followed by Asynchronous READ



Note: When configured for synchronous mode (BCR[15] = 0), CE# must remain HIGH for at least 5ns (t_{CPH}) to schedule the appropriate internal refresh operation. Otherwise, t_{CPH} is only required after CE#-controlled WRITES.

Package Dimensions

Figure 49: 54-Ball VFBGA



- Notes:
1. All dimensions are in millimeters.
 2. Package width and length do not include mold protrusion; allowable mold protrusion is 0.25mm per side.
 3. The MT45W2MW16BGB uses "green" packaging.



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Revision History

Rev. E, Production	09/08
• “Options” on page 1: Added “Low Power: L” to table. • Table 2, “Bus Operations: Asynchronous Mode,” on page 8: Changed note 1 from “CLK must be low...” to “CLK must be static HIGH or LOW...” • Table 3, “Bus Operations: Burst Mode,” on page 9: Changed note 1 from “CLK must be low...” to “CLK must be static HIGH or LOW...” • Figure 26: “AC Input/Output Reference Waveform,” on page 35: Changed “VCC” to “VCCQ” in two instances in the diagram; revised note 2 to read, “Input timing begins at VCCQ/2.” • Figure 32: “Single-Access Burst READ Operation,” on page 43: Changed symbol for LB#/UB# from ^tCSP to ^tSP. • Figure 33: “4-Word Burst READ Operation,” on page 44: Changed symbol for LB#/UB# from ^tCSP to ^tSP. • Figure 34: “READ Burst Suspend,” on page 45: Changed symbol for LB#/UB# from ^tCSP to ^tSP.	
Rev. D, Production	02/08
• Table 15, “Burst WRITE Cycle Timing Requirements,” on page 39: Corrected ^tCEM parameter label from minimum to maximum.	
Rev. C, Production	07/07
• Renumbered the notes in Table 12 on page 36. • Replaced “” with “2” in the “Notes” column in Table 12 on page 36.	
Rev. B, Production	05/07
• Changed revision status to Production. • Removed “Contact factory” note from the “Options” section on page 1. • Changed burst initial latency from “39ns” to “38.5ns” in the “Features” section on page 1. • Removed “...(contact factory)” from Figure 3 on page 10. • Moved the “WAIT Polarity (BCR[10]) Default = WAIT Active HIGH” section to page 29. • Changed A6 and A5 to “Ignored” and added the following text in Figure 24 on page 31: “Setting is ignored (default 00b).”	
Rev. A, Preliminary	02/07
• Initial release.	