

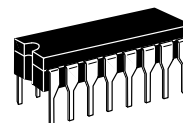
# MC14490

## Hex Contact Bounce Eliminator

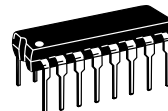
The MC14490 is constructed with complementary MOS enhancement mode devices, and is used for the elimination of extraneous level changes that result when interfacing with mechanical contacts. The digital contact bounce eliminator circuit takes an input signal from a bouncing contact and generates a clean digital signal four clock periods after the input has stabilized. The bounce eliminator circuit will remove bounce on both the "make" and the "break" of a contact closure. The clock for operation of the MC14490 is derived from an internal R-C oscillator which requires only an external capacitor to adjust for the desired operating frequency (bounce delay). The clock may also be driven from an external clock source or the oscillator of another MC14490 (see Figure 5).

NOTE: Immediately after power-up, the outputs of the MC14490 are in indeterminate states.

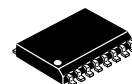
- Diode Protection on All Inputs
- Six Debouncers Per Package
- Internal Pullups on All Data Inputs
- Can Be Used as a Digital Integrator, System Synchronizer, or Delay Line
- Internal Oscillator (R-C), or External Clock Source
- TTL Compatible Data Inputs/Outputs
- Single Line Input, Debounces Both "Make" and "Break" Contacts
- Does Not Require "Form C" (Single Pole Double Throw) Input Signal
- Cascadable for Longer Time Delays
- Schmitt Trigger on Clock Input (Pin 7)
- Supply Voltage Range = 3.0 V to 18 V
- Chip Complexity: 546 FETs or 136.5 Equivalent Gates



**L SUFFIX**  
CERAMIC  
CASE 620



**P SUFFIX**  
PLASTIC  
CASE 648



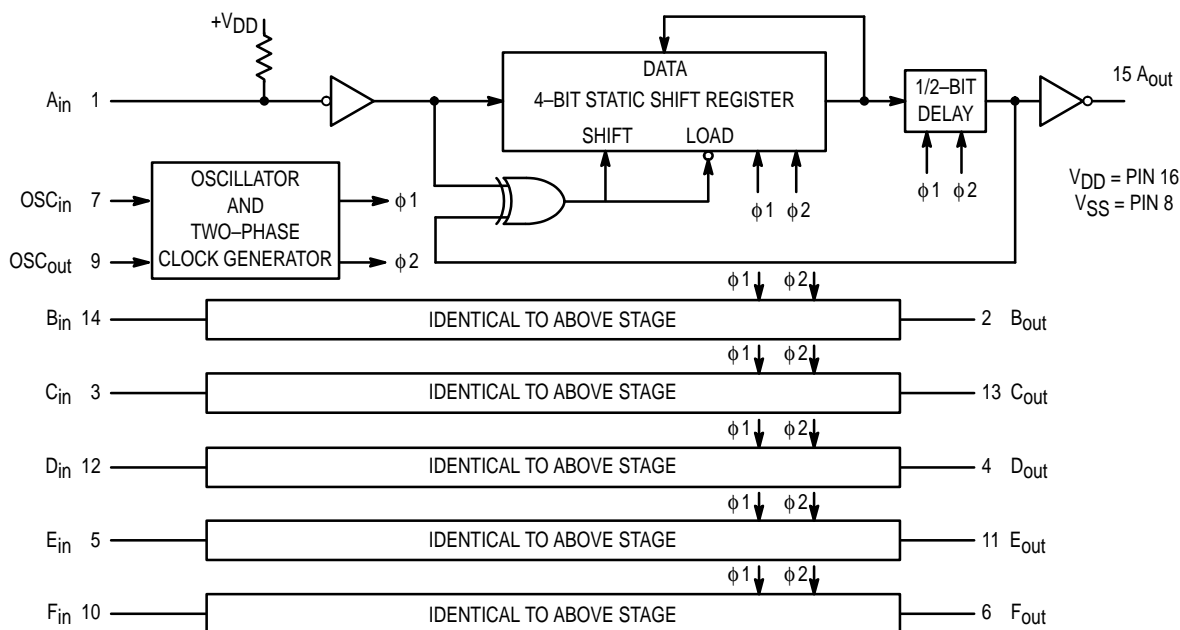
**DW SUFFIX**  
SOIC  
CASE 751G

### ORDERING INFORMATION

MC14490P	Plastic
MC14490L	Ceramic
MC14490DW	SOIC

$T_A = -55^\circ$  to  $125^\circ\text{C}$  for all packages.

### BLOCK DIAGRAM



**MAXIMUM RATINGS\*** (Voltages Referenced to V<sub>SS</sub>)

Symbol	Parameter	Value	Unit
V <sub>DD</sub>	DC Supply Voltage	− 0.5 to + 18.0	V
V <sub>in</sub> , V <sub>out</sub>	Input or Output Voltage (DC or Transient)	− 0.5 to V <sub>DD</sub> + 0.5	V
I <sub>in</sub>	Input Current (DC or Transient), per Pin	± 10	mA
P <sub>D</sub>	Power Dissipation, per Package†	500	mW
T <sub>stg</sub>	Storage Temperature	− 65 to + 150	°C
T <sub>L</sub>	Lead Temperature (8–Second Soldering)	260	°C

\* Maximum Ratings are those values beyond which damage to the device may occur.

† Temperature Derating:

Plastic “P and D/DW” Packages: − 7.0 mW/°C From 65°C To 125°C

Ceramic “L” Packages: − 12 mW/°C From 100°C to 125°C

**PIN ASSIGNMENT**

A <sub>in</sub>	1	16	V <sub>DD</sub>
B <sub>out</sub>	2	15	A <sub>out</sub>
C <sub>in</sub>	3	14	B <sub>in</sub>
D <sub>out</sub>	4	13	C <sub>out</sub>
E <sub>in</sub>	5	12	D <sub>in</sub>
F <sub>out</sub>	6	11	E <sub>out</sub>
OSC <sub>in</sub>	7	10	F <sub>in</sub>
V <sub>SS</sub>	8	9	OSC <sub>out</sub>

**ELECTRICAL CHARACTERISTICS** (Voltages Referenced to V<sub>SS</sub>)

Characteristic	Symbol	V <sub>DD</sub> Vdc	− 55°C		25°C			125°C		Unit
			Min	Max	Min	Typ #	Max	Min	Max	
Output Voltage V <sub>in</sub> = V <sub>DD</sub> or 0  V <sub>in</sub> = 0 or V <sub>DD</sub>	V <sub>OL</sub>	5.0	—	0.05	—	0	0.05	—	0.05	Vdc
		10	—	0.05	—	0	0.05	—	0.05	
		15	—	0.05	—	0	0.05	—	0.05	
	V <sub>OH</sub>	5.0	4.95	—	4.95	5.0	—	4.95	—	Vdc
		10	9.95	—	9.95	10	—	9.95	—	
		15	14.95	—	14.95	15	—	14.95	—	
Input Voltage V <sub>O</sub> = 4.5 or 0.5 Vdc V <sub>O</sub> = 9.0 or 1.0 Vdc V <sub>O</sub> = 13.5 or 1.5 Vdc  V <sub>O</sub> = 0.5 or 4.5 Vdc V <sub>O</sub> = 1.0 or 9.0 Vdc V <sub>O</sub> = 1.5 or 13.5 Vdc	V <sub>IL</sub>	5.0	—	1.5	—	2.25	1.5	—	1.5	Vdc
		10	—	3.0	—	4.50	3.0	—	3.0	
		15	—	4.0	—	6.75	4.0	—	4.0	
	V <sub>IH</sub>	5.0	3.5	—	3.5	2.75	—	3.5	—	Vdc
		10	7.0	—	7.0	5.50	—	7.0	—	
		15	11	—	11	8.25	—	11	—	
Output Drive Current Oscillator Output V <sub>OH</sub> = 2.5 V V <sub>OH</sub> = 4.6 V V <sub>OH</sub> = 9.5 V V <sub>OH</sub> = 13.5 V  Debounce Outputs V <sub>OH</sub> = 2.5 V V <sub>OH</sub> = 4.6 V V <sub>OH</sub> = 9.5 V V <sub>OH</sub> = 13.5 V  Oscillator Output V <sub>OL</sub> = 0.4 V V <sub>OL</sub> = 0.5 V V <sub>OL</sub> = 1.5 V  Debounce Outputs V <sub>OL</sub> = 0.4 V V <sub>OL</sub> = 0.5 V V <sub>OL</sub> = 1.5 V	I <sub>OH</sub>	5.0	− 0.6	—	− 0.5	− 1.5	—	− 0.4	—	mAdc
		5.0	− 0.12	—	− 0.1	− 0.3	—	− 0.08	—	
		10	− 0.23	—	− 0.2	− 0.8	—	− 0.16	—	
		15	− 1.4	—	− 1.2	− 3.0	—	− 1.0	—	
		5.0	− 0.9	—	− 0.75	− 2.2	—	− 0.6	—	
	I <sub>OL</sub>	5.0	0.36	—	0.3	0.9	—	0.24	—	mAdc
		10	0.9	—	0.75	2.3	—	0.6	—	
		15	4.2	—	3.5	10	—	2.8	—	
		5.0	2.6	—	2.2	4.0	—	1.8	—	
		10	4.0	—	3.3	9.0	—	2.7	—	
Input Current Debounce Inputs (V <sub>in</sub> = V <sub>DD</sub> )	I <sub>IH</sub>	15	—	2.0	—	0.2	2.0	—	11	μAdc
		15	—	± 620	—	± 255	± 400	—	± 250	
		15	—	± 620	—	± 255	± 400	—	± 250	
Pullup Resistor Source Current Debounce Inputs (V <sub>in</sub> = V <sub>SS</sub> )	I <sub>IL</sub>	5.0	175	375	140	190	255	70	225	μAdc
		10	340	740	280	380	500	145	440	
		15	505	1100	415	570	750	215	660	
Input Capacitance	C <sub>in</sub>	—	—	—	—	5.0	7.5	—	—	pF
Quiescent Current (V <sub>in</sub> = V <sub>SS</sub> or V <sub>DD</sub> , I <sub>out</sub> = 0 μA)	I <sub>SS</sub>	5.0	—	150	—	40	100	—	90	μAdc
		10	—	280	—	90	225	—	180	
		15	—	840	—	225	650	—	550	

#Data labelled “Typ” is not to be used for design purposes but is intended as an indication of the IC’s potential performance.

**SWITCHING CHARACTERISTICS** ( $C_L = 50 \text{ pF}$ ,  $T_A = 25^\circ\text{C}$ )

Characteristic	Symbol	V <sub>DD</sub> V <sub>dc</sub>	Min	Typ #	Max	Unit
Output Rise Time All Outputs	t <sub>TLH</sub>	5.0 10 15	— — —	180 90 65	360 180 130	ns
Output Fall Time Oscillator Output	t <sub>THL</sub>	5.0 10 15	— — —	100 50 40	200 100 80	ns
Debounce Outputs	t <sub>THL</sub>	5.0 10 15	— — —	60 30 20	120 60 40	
Propagation Delay Time Oscillator Input to Debounce Outputs	t <sub>PHL</sub>	5.0 10 15	— — —	285 120 95	570 240 190	
	t <sub>PLH</sub>	5.0 10 15	— — —	370 160 120	740 320 240	
Clock Frequency (50% Duly Cycle) (External Clock)	f <sub>cl</sub>	5.0 10 15	— — —	2.8 6 9	1.4 3.0 4.5	MHz
Setup Time (See Figure 1)	t <sub>su</sub>	5.0 10 15	100 80 60	50 40 30	— — —	ns
Maximum External Clock Input Rise and Fall Time Oscillator Input	t <sub>r</sub> , t <sub>f</sub>	5.0 10 15	No Limit			ns
Oscillator Frequency OSC <sub>out</sub> C <sub>ext</sub> ≥ 100 pF*	f <sub>osc</sub> , typ	5.0 10 15	<div><div>1.5</div><div>C<sub>ext</sub> (in μF)</div><div>4.5</div><div>C<sub>ext</sub> (in μF)</div><div>6.5</div><div>C<sub>ext</sub> (in μF)</div></div>			Hz
Note: These equations are intended to be a design guide. Laboratory experimentation may be required. Formulas are typically ± 15% of actual frequencies.						

\* The formulas given are for the typical characteristics only at  $25^\circ\text{C}$ .

#Data labelled "Typ" is not to be used for design purposes but is intended as an indication of the IC's potential performance.

**\*POWER-DOWN CONSIDERATIONS**

Large values of  $C_{ext}$  may cause problems when powering down the MC14490 because of the amount of energy stored in the capacitor. When a system containing this device is powered down, the capacitor may discharge through the input protection diodes at Pin 7 or the parasitic diodes at Pin 9. Current through these internal diodes must be limited to 10 mA, therefore the turn-off time of the power supply must not be faster than  $t = (V_{DD} - V_{SS}) \cdot C_{ext} / (10 \text{ mA})$ . For example, if  $V_{DD} - V_{SS} = 15 \text{ V}$  and  $C_{ext} = 1 \mu\text{F}$ , the power supply must turn off no faster than  $t = (15 \text{ V}) \cdot (1 \mu\text{F}) / 10 \text{ mA} = 1.5 \text{ ms}$ . This is usually not a problem because power supplies are heavily filtered and cannot discharge at this rate.

When a more rapid decrease of the power supply to zero volts occurs, the MC14490 may sustain damage. To avoid this possibility, use external clamping diodes, D1 and D2, connected as shown in Figure 2.

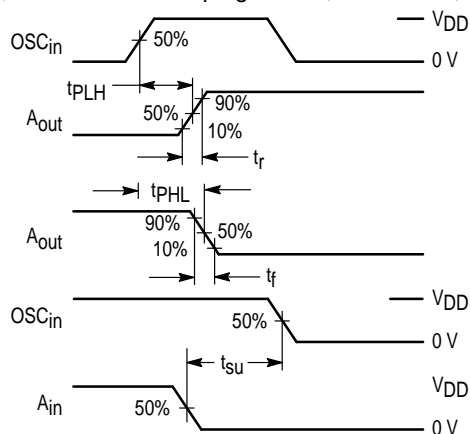


Figure 1. Switching Waveforms

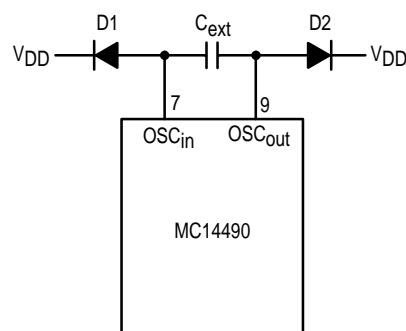


Figure 2. Discharge Protection During Power Down

## THEORY OF OPERATION

The MC14490 Hex Contact Bounce Eliminator is basically a digital integrator. The circuit can integrate both up and down. This enables the circuit to eliminate bounce on both the leading and trailing edges of the signal, shown in the timing diagram of Figure 3.

Each of the six Bounce Eliminators is composed of a 4-1/2-bit register (the integrator) and logic to compare the input with the contents of the shift register, as shown in Figure 4. The shift register requires a series of timing pulses in order to shift the input signal into each shift register location. These timing pulses (the clock signal) are represented in the upper waveform of Figure 3. Each of the six Bounce Eliminator circuits has an internal resistor as shown in Figure 4. A pullup resistor was incorporated rather than a pulldown resistor in order to implement switched ground input signals, such as those coming from relay contacts and push buttons. By switching ground, rather than a power supply lead, system faults (such as shorts to ground on the signal input leads) will not cause excessive currents in the wiring and contacts. Signal lead shorts to ground are much more probable than shorts to a power supply lead.

When the relay contact is closed, (see Figure 4) the low level is inverted, and the shift register is loaded with a high on each positive edge of the clock signal. To understand the operation, we assume all bits of the shift register are loaded with lows and the output is at a high level.

At clock edge 1 (Figure 3) the input has gone low and a high has been loaded into the first bit or storage location of the shift register. Just after the positive edge of clock 1, the input signal has bounced back to a high. This causes the shift register to be reset to lows in all four bits — thus starting the timing sequence over again.

During clock edges 3 to 6 the input signal has stayed low. Thus, a high has been shifted into all four shift register bits and, as shown, the output goes low during the positive edge of clock pulse 6.

It should be noted that there is a 3-1/2 to 4-1/2 clock period delay between the clean input signal and output signal. In this example there is a delay of 3.8 clock periods from the beginning of the clean input signal.

After some time period of  $N$  clock periods, the contact is opened and at  $N+1$  a low is loaded into the first bit. Just after  $N+1$ , when the input bounces low, all bits are set to a high. At  $N+2$  nothing happens because the input and output are low and all bits of the shift register are high. At time  $N+3$  and thereafter the input signal is a high, clean signal. At the positive edge of  $N+6$  the output goes high as a result of four lows being shifted into the shift register.

Assuming the input signal is long enough to be clocked through the Bounce Eliminator, the output signal will be no longer or shorter than the clean input signal plus or minus one clock period.

The amount of time distortion between the input and output signals is a function of the difference in bounce characteristics on the edges of the input signal and the clock frequency. Since most relay contacts have more bounce when making as compared to breaking, the overall delay, counting bounce period, will be greater on the leading edge of the input signal than on the trailing edge. Thus, the output signal will be shorter than the input signal — if the leading edge bounce is included in the overall timing calculation.

The only requirement on the clock frequency in order to obtain a bounce free output signal is that four clock periods do not occur while the input signal is in a false state. Referring to Figure 3, a false state is seen to occur three times at the beginning of the input signal. The input signal goes low three times before it finally settles down to a valid low state. The first three low pulses are referred to as false states.

If the user has an available clock signal of the proper frequency, it may be used by connecting it to the oscillator input (pin 7). However, if an external clock is not available the user can place a small capacitor across the oscillator input and output pins in order to start up an internal clock source (as shown in Figure 4). The clock signal at the oscillator output pin may then be used to clock other MC14490 Bounce Eliminator packages. With the use of the MC14490, a large number of signals can be cleaned up, with the requirement of only one small capacitor external to the Hex Bounce Eliminator packages.

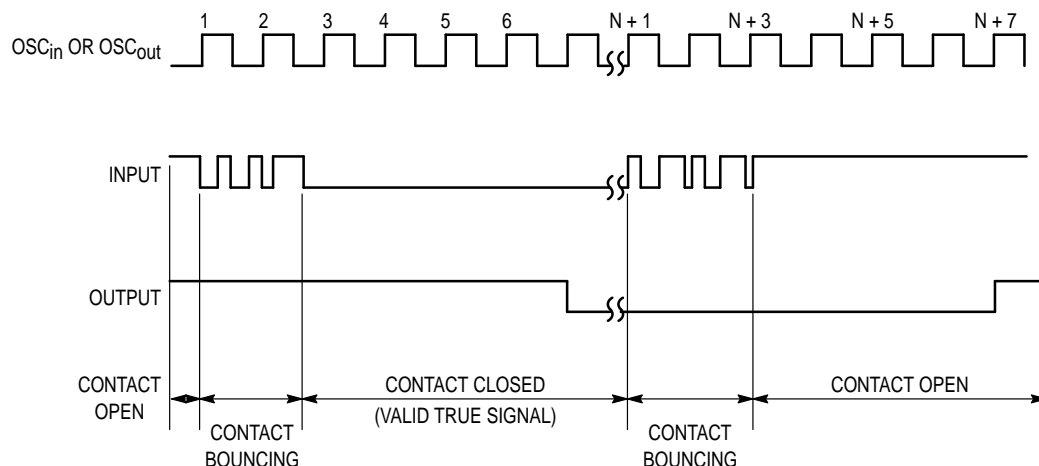
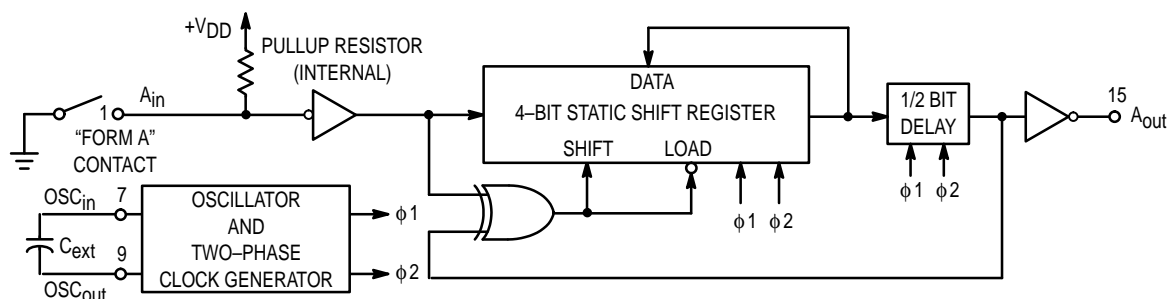


Figure 3. Timing Diagram



**Figure 4. Typical "Form A" Contact Debounce Circuit  
(Only One Debouncer Shown)**

## OPERATING CHARACTERISTICS

The single most important characteristic of the MC14490 is that it works with a single signal lead as an input, making it directly compatible with mechanical contacts (Form A and B).

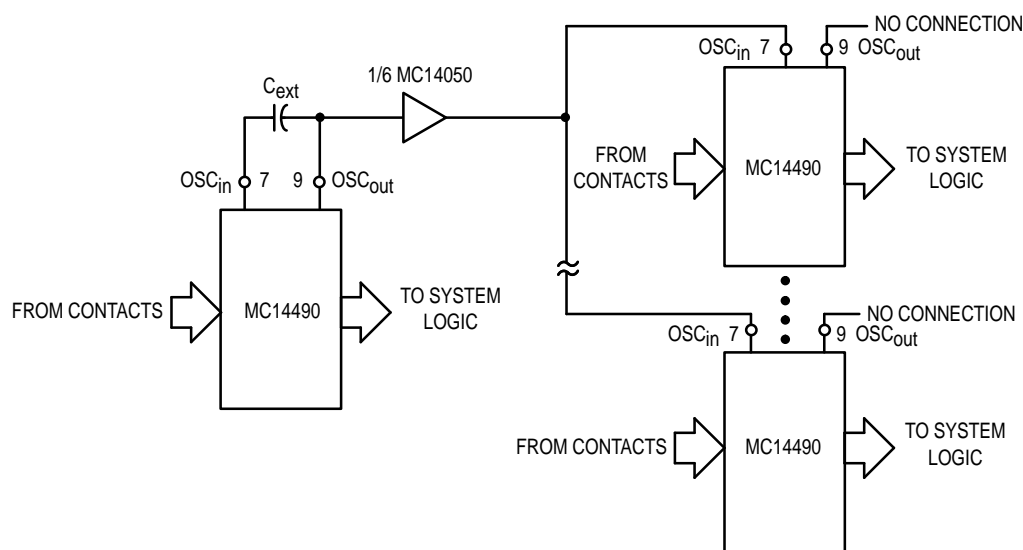
The circuit has a built-in pullup resistor on each input. The worst case value of the pullup resistor (determined from the Electrical Characteristics table) is used to calculate the contact wetting current. If more contact current is required, an external resistor may be connected between  $V_{DD}$  and the input.

Because of the built-in pullup resistors, the inputs cannot be driven with a single standard CMOS gate when  $V_{DD}$  is below 5 V. At this voltage, the input should be driven with paral-

leled standard gates or by the MC14049 or MC14050 buffers.

The clock input circuit (pin 7) has Schmitt trigger shaping such that proper clocking will occur even with very slow clock edges, eliminating any need for clock preshaping. In addition, other MC14490 oscillator inputs can be driven from a single oscillator output buffered by an MC14050 (see Figure 5). Up to six MC14490s may be driven by a single buffer.

The MC14490 is TTL compatible on both the inputs and the outputs. When  $V_{DD}$  is at 4.5 V, the buffered outputs can sink 1.6 mA at 0.4 V. The inputs can be driven with TTL as a result of the internal input pullup resistors.

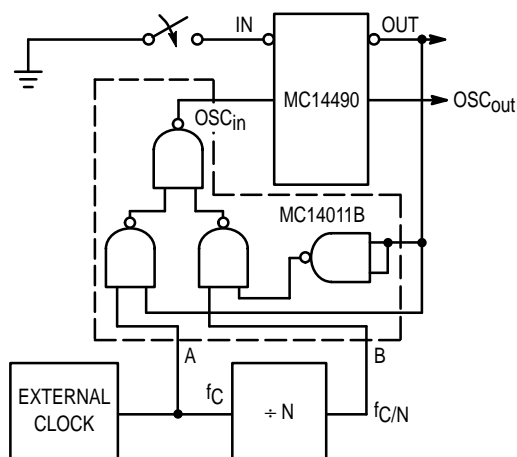


**Figure 5. Typical Single Oscillator Debounce System**

## TYPICAL APPLICATIONS

## ASYMMETRICAL TIMING

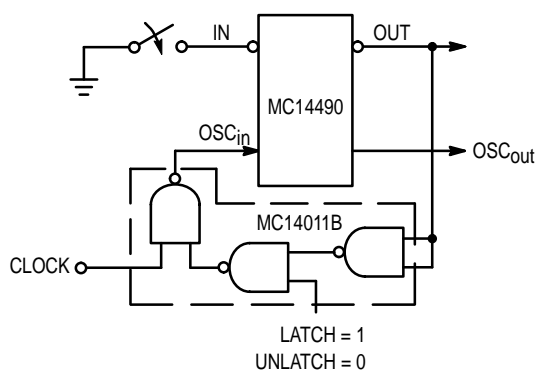
In applications where different leading and trailing edge delays are required (such as a fast attack/slow release timer.) Clocks of different frequencies can be gated into the MC14490 as shown in Figure 6. In order to produce a slow attack/fast release circuit leads A and B should be interchanged. The clock out lead can then be used to feed clock signals to the other MC14490 packages where the asymmetrical input/output timing is required.



### Figure 6. Fast Attack/Slow Release Circuit

## LATCHED OUTPUT

The contents of the Bounce Eliminator can be latched by using several extra gates as shown in Figure 7. If the latch lead is high the clock will be stopped when the output goes low. This will hold the output low even though the input has returned to the high state. Any time the clock is stopped the outputs will be representative of the input signal four clock periods earlier.

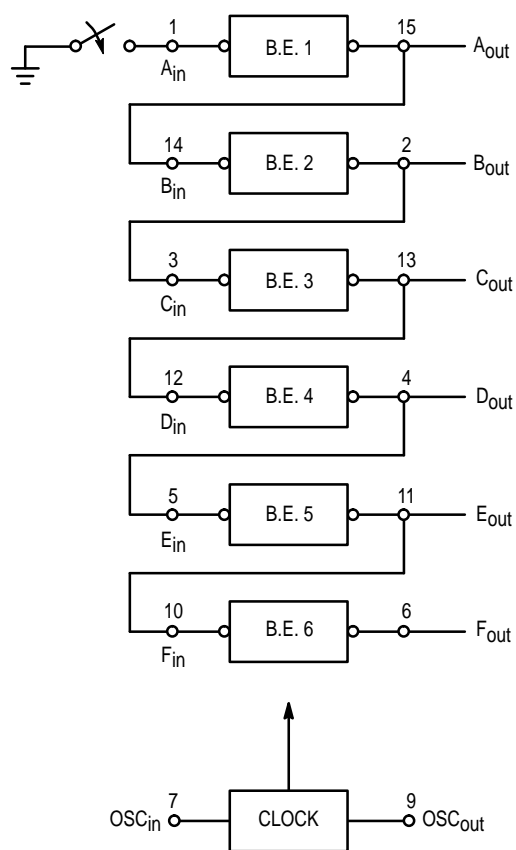


### Figure 7. Latched Output Circuit

## MULTIPLE TIMING SIGNALS

As shown in Figure 8, the Bounce Eliminator circuits can be connected in series. In this configuration each output is delayed by four clock periods relative to its respective input. This configuration may be used to generate multiple timing signals such as a delay line, for programming other timing operations.

One application of the above is shown in Figure 9, where it is required to have a single pulse output for a single operation (make) of the push button or relay contact. This only requires the series connection of two Bounce Eliminator circuits, one inverter, and one NOR gate in order to generate the signal  $\overline{AB}$  as shown in Figures 9 and 10. The signal  $\overline{AB}$  is four clock periods in length. If the inverter is switched to the A output, the pulse  $\overline{AB}$  will be generated upon release or break of the contact. With the use of a few additional parts many different pulses and waveshapes may be generated.



### Figure 8. Multiple Timing Circuit Connections

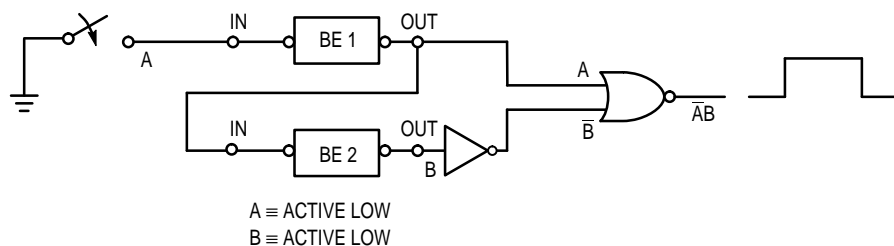


Figure 9. Single Pulse Output Circuit

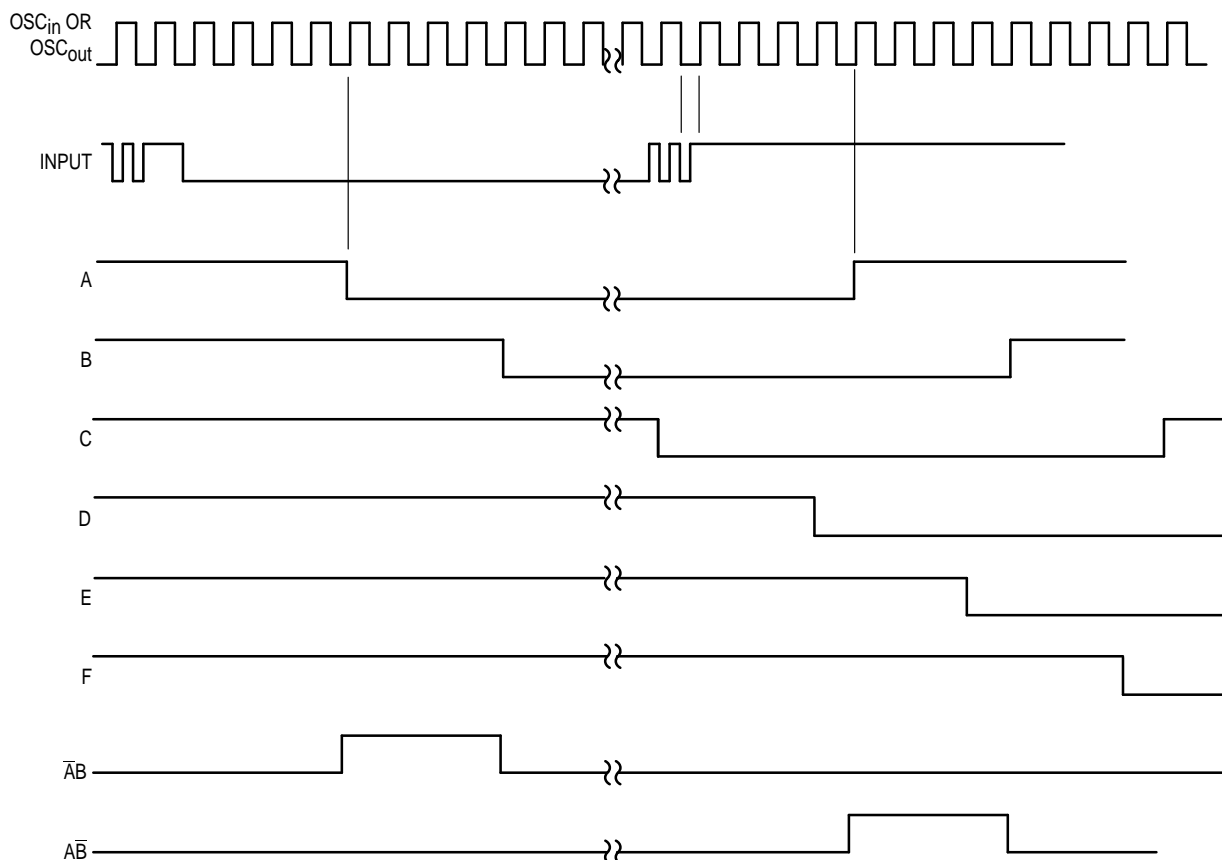


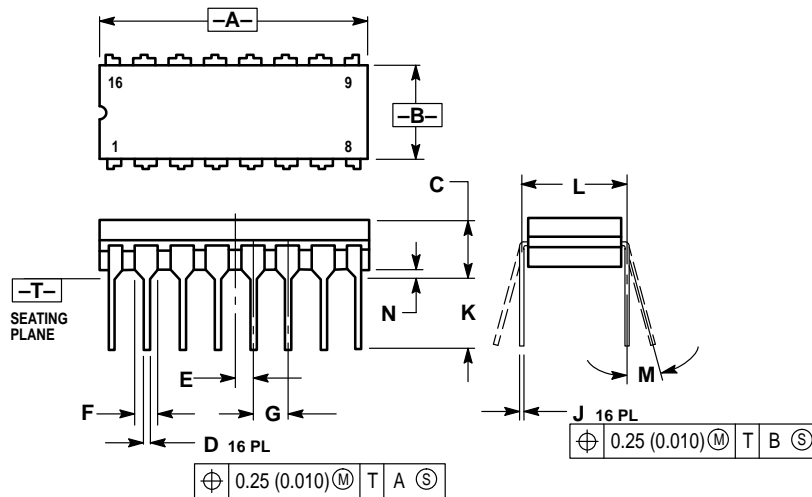
Figure 10. Multiple Output Signal Timing Diagram

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation,  $V_{in}$  and  $V_{out}$  should be constrained to the range  $V_{SS} \leq (V_{in} \text{ or } V_{out}) \leq V_{DD}$ .

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either  $V_{SS}$  or  $V_{DD}$ ). Unused outputs must be left open.

## OUTLINE DIMENSIONS

### L SUFFIX CERAMIC DIP PACKAGE CASE 620-10 ISSUE V

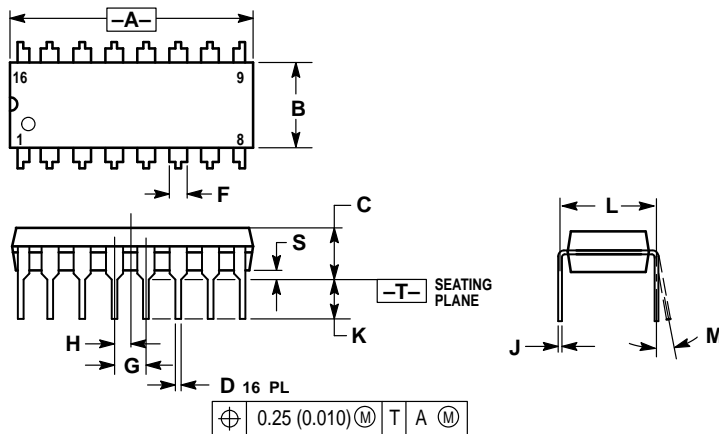


#### NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
4. DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.750	0.785	19.05	19.93
B	0.240	0.295	6.10	7.49
C	—	0.200	—	5.08
D	0.015	0.020	0.39	0.50
E	0.050 BSC		1.27 BSC	
F	0.055	0.065	1.40	1.65
G	0.100 BSC		2.54 BSC	
H	0.008	0.015	0.21	0.38
K	0.125	0.170	3.18	4.31
L	0.300 BSC		7.62 BSC	
M	0°	15°	0°	15°
N	0.020	0.040	0.51	1.01

### P SUFFIX PLASTIC DIP PACKAGE CASE 648-08 ISSUE R



#### NOTES:

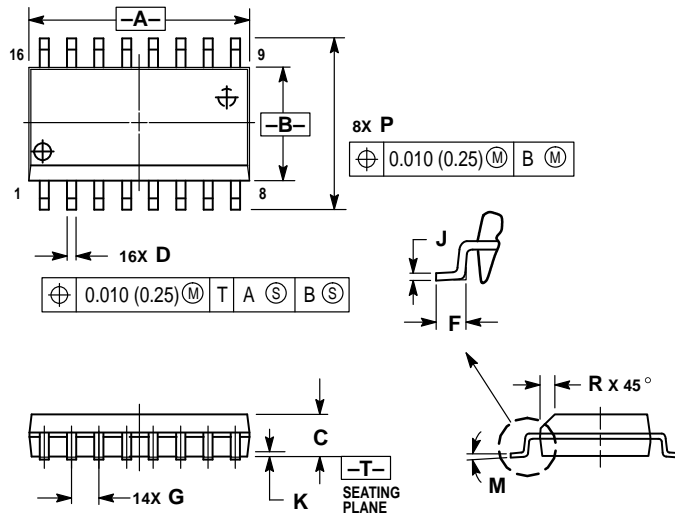
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01



## OUTLINE DIMENSIONS


### DW SUFFIX PLASTIC SOIC PACKAGE CASE 751G-02 ISSUE A



#### NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	10.15	10.45	0.400	0.411
B	7.40	7.60	0.292	0.299
C	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.50	0.90	0.020	0.035
G	1.27 BSC	0.050 BSC		
J	0.25	0.32	0.010	0.012
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029

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#### How to reach us:

**USA/EUROPE/Locations Not Listed:** Motorola Literature Distribution;  
P.O. Box 20912; Phoenix, Arizona 85036. 1-800-441-2447 or 602-303-5454

**MFAX:** RMFAX0@email.sps.mot.com – TOUCHTONE 602-244-6609  
**INTERNET:** <http://Design-NET.com>

**JAPAN:** Nippon Motorola Ltd.; Tatsumi-SPD-JLDC, 6F Seibu-Butsuryu-Center,  
3-14-2 Tatsumi Koto-Ku, Tokyo 135, Japan. 03-81-3521-8315

**ASIA/PACIFIC:** Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park,  
51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852-26629298



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