

# Frequency Multiplier and Zero Delay Buffer

#### **Features**

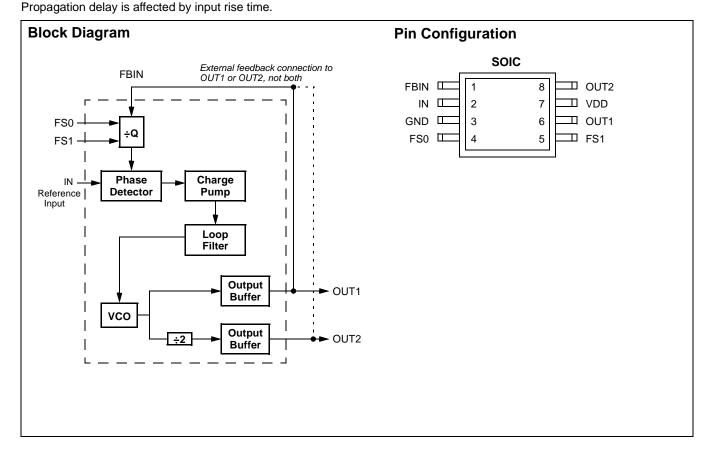
- Two outputs
- . Configuration options allow various multiplications of the reference frequency—refer to *Table 1* to determine the specific option which meets your multiplication
- Available in 8-pin SOIC package

### **Key Specifications**

Operating Voltage:	3.3V ±5% or 5.0 ±10%
Operating Range:	10 MHz < f <sub>OUT1</sub> < 133 MHz
Absolute Jitter:	±500 ps
Output to Output Skew:	250 ps
Propagation Delay:	

**Table 1. Configuration Options** 

FBIN	FS0	FS1	OUT1	OUT2
OUT1	0	0	2 X REF	REF
OUT1	1	0	4 X REF	2 X REF
OUT1	0	1	REF	REF/2
OUT1	1	1	8 X REF	4 X REF
OUT2	0	0	4 X REF	2 X REF
OUT2	1	0	8 X REF	4 X REF
OUT2	0	1	2 X REF	REF
OUT2	1	1	16 X REF	8 X REF





### **Pin Definitions**

Pin Name	Pin No.	Pin Type	Pin Description
IN	2	I	Reference Input: The output signals will be synchronized to this signal.
FBIN	1	I	<b>Feedback Input:</b> This input must be fed by one of the outputs (OUT1 or OUT2) to ensure proper functionality. If the trace between FBIN and the output pin being used for feedback is equal in length to the traces between the outputs and the signal destinations, then the signals received at the destinations will be synchronized to the REF signal input (IN).
OUT1	6	0	Output 1: The frequency of the signal provided by this pin is determined by the feedback signal connected to FBIN, and the FS0:1 inputs (see Table 1).
OUT2	8	0	Output 2: The frequency of the signal provided by this pin is one-half of the frequency of OUT1. See Table 1.
VDD	7	Р	<b>Power Connections:</b> Connect to 3.3V or 5V. This pin should be bypassed with a 0.1-μF decoupling capacitor. Use ferrite beads to help reduce noise for optimal jitter performance.
GND	3	Р	Ground Connection: Connect all grounds to the common system ground plane.
FS0:1	4, 5	I	Function Select Inputs: Tie to V <sub>DD</sub> (HIGH, 1) or GND (LOW, 0) as desired per Table 1.

### Overview

The CY2302 is a two-output zero delay buffer and frequency multiplier. It provides an external feedback path allowing maximum flexibility when implementing the Zero Delay feature. This is explained further in the sections of this data sheet titled "How to Implement Zero Delay," and "Inserting Other Devices in Feedback Path."

The CY2302 is a pin-compatible upgrade of the Cypress W42C70-01. The CY2302 addresses some application dependent problems experienced by users of the older device.

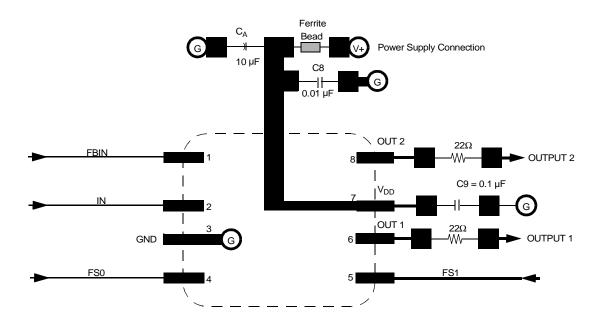


Figure 1. Schematic/Suggested Layout



### **How to Implement Zero Delay**

Typically, Zero Delay Buffers (ZDBs) are used because a designer wants to provide multiple copies of a clock signal in phase with each other. The whole concept behind ZDBs is that the signals at the destination chips are all going HIGH at the same time as the input to the ZDB. In order to achieve this, layout must compensate for trace length between the ZDB and the target devices. The method of compensation is described below.

External feedback is the trait that allows for this compensation. The PLL on the ZDB will cause the feedback signal to be in phase with the reference signal. When laying out the board, match the trace lengths between the output being used for feedback and the FBIN input to the PLL.

If it is desirable to either add a little delay, or slightly precede the input signal, this may also be implemented by either making the trace to the FBIN pin a little shorter or a little longer than the traces to the devices being clocked.

### **Inserting Other Devices in Feedback Path**

Another nice feature available due to the external feedback is the ability to synchronize signals to the signal coming from some other device. This implementation can be applied to any device (ASIC, multiple output clock buffer/driver, etc.) that is put into the feedback path.

Referring to Figure 2, if the traces between the ASIC/Buffer and the destination of the clock signal(s) (A) are equal in length to the trace between the buffer and the FBIN pin, the signals at the destination(s) device will be driven HIGH at the same time the Reference clock provided to the ZDB goes HIGH. Synchronizing the other outputs of the ZDB to the outputs from the ASIC/Buffer is more complex however, as any propagation delay from the ZDB output to the ASIC/Buffer output must be accounted for.

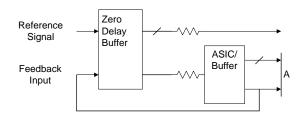


Figure 2. Six Output Buffer in the Feedback Path



### **Absolute Maximum Ratings**

Stresses greater than those listed in this table may cause permanent damage to the device. These represent a stress rating only. Operation of the device at these or any other conditions

above those specified in the operating sections of this specification is not implied. Maximum conditions for extended periods may affect reliability.

Parameter	Description	Rating	Unit
V <sub>DD</sub> , V <sub>IN</sub>	Voltage on Any Pin with Respect to GND	-0.5 to +7.0	V
T <sub>STG</sub>	Storage Temperature	-65 to +150	°C
T <sub>A</sub>	Operating Temperature	0 to +70	°C
T <sub>B</sub>	Ambient Temperature under Bias	−55 to +125	°C
P <sub>D</sub>	Power Dissipation	0.5	W

# **DC Electrical Characteristics**: $T_A = 0$ °C to 70°C or -40° to 85°C, $V_{DD} = 3.3$ V ±5%

Parameter	Description	Test Condition	Min.	Тур.	Max.	Unit
I <sub>DD</sub>	Supply Current	Unloaded, 100 MHz		17	35	mA
V <sub>IL</sub>	Input Low Voltage				0.8	V
V <sub>IH</sub>	Input High Voltage		2.0			V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 12 mA I <sub>OL</sub> = 8 mA			0.4	V
V <sub>OH</sub>	Output High Voltage	I <sub>OL</sub> = 12 mA I <sub>OL</sub> = 8 mA	2.4			V
I <sub>IL</sub>	Input Low Current	V <sub>IN</sub> = 0V	-40		5	μΑ
I <sub>IH</sub>	Input High Current	$V_{IN} = V_{DD}$			5	μΑ

## DC Electrical Characteristics: $T_A = 0$ °C to 70°C or -40° to 85°C, $V_{DD} = 5V \pm 10\%$

Parameter	Description	Test Condition	Min.	Тур.	Max.	Unit
I <sub>DD</sub>	Supply Current	Unloaded, 100 MHz		17	35	mA
V <sub>IL</sub>	Input Low Voltage				0.8	V
V <sub>IH</sub>	Input High Voltage		2.0			V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 12 mA I <sub>OL</sub> = 8 mA			0.4	V
V <sub>OH</sub>	Output High Voltage	I <sub>OL</sub> = 12 mA I <sub>OL</sub> = 8 mA	2.4			V
I <sub>IL</sub>	Input Low Current	V <sub>IN</sub> = 0V	-80		5	μΑ
I <sub>IH</sub>	Input High Current	$V_{IN} = V_{DD}$			5	μΑ



# AC Electrical Characteristics: $T_A = 0$ °C to +70°C or -40° to 85°C, $V_{DD} = 3.3 V \pm 5\%$

Parameter	Description	Test Condition	Min.	Тур.	Max.	Unit
f <sub>IN</sub>	Input Frequency <sup>[1]</sup>	OUT2 = REF	5		133	MHz
f <sub>ОUТ</sub>	Output Frequency	OUT1 15-pF load <sup>[2]</sup>	10		133	MHz
t <sub>R</sub>	Output Rise Time	2.0V to 0.8V, 15-pF load			3.5	ns
t <sub>F</sub>	Output Fall Time	2.0V to 0.8V, 15-pF load			2.5	ns
t <sub>ICLKR</sub>	Input Clock Rise Time <sup>[3]</sup>				10	ns
t <sub>ICLKF</sub>	Input Clock Fall Time <sup>[3]</sup>				10	ns
t <sub>PD</sub>	FBIN to REF Skew <sup>[4, 5]</sup>	Measured at V <sub>DD</sub> /2	-2	0.6	2	ns
t <sub>D</sub>	Duty Cycle	15-pF load <sup>[6]</sup>	40	50	60	%
t <sub>LOCK</sub>	PLL Lock Time	Power supply stable			1.0	ms
t <sub>JC</sub>	Jitter, Cycle-to-Cycle	f <sub>OUT</sub> >30 MHz			300	ps
t <sub>DC</sub>	Die Out Time <sup>[7]</sup>		100			Clock Cycles

## AC Electrical Characteristics: $T_A = 0$ °C to +70°C or -40° to 85°C, $V_{DD} = 5.0$ V ±10%

Parameter	Description	Test Condition	Min.	Тур.	Max.	Unit
f <sub>IN</sub>	Input Frequency <sup>[1]</sup>	OUT2 = REF	5		133	MHz
f <sub>OUT</sub>	Output Frequency	OUT1 15-pF load <sup>[2]</sup>	10		133	MHz
t <sub>R</sub>	Output Rise Time	2.0V to 0.8V, 15-pF load			2.5	ns
t <sub>F</sub>	Output Fall Time	2.0V to 0.8V, 15-pF load			1.5	ns
t <sub>ICLKR</sub>	Input Clock Rise Time <sup>[3]</sup>				10	ns
t <sub>ICLKF</sub>	Input Clock Fall Time <sup>[3]</sup>				10	ns
t <sub>PD</sub>	FBIN to REF Skew <sup>[4, 5]</sup>	Measured at V <sub>DD</sub> /2	-2	0.6	2	ns
t <sub>D</sub>	Duty Cycle	15-pF load <sup>[6, 8]</sup>	40	50	60	%
t <sub>LOCK</sub>	PLL Lock Time	Power supply stable			1.0	ms
t <sub>JC</sub>	Jitter, Cycle-to-Cycle	FOUT > 30 MHz			200	ps

### **Ordering Information**

Ordering Code	Option	Package Name	Package Type	Temperature Grade
CY2302	-01	S	8-pin SOIC (150-mil)	C = Commercial (0° to 70° C) I = Industrial (-40° to 85°C)

### Notes:

- Input frequency is limited by output frequency range and input to output frequency multiplication factor (which is determined by circuit configuration). For the higher drive -11, the load is 20 pF.

  Longer input rise and fall time will degrade skew and jitter performance.

  All AC specifications are measured with a 50Ω transmission line, load terminated with 50Ω to 1.4V.

  Skew is measured at 1.4V on rising edges.

  Duty cycle is measured at 1.4V.

  33 MHz reference input suddenly stopped (0 MHz). Number of cycles provided prior to output falling to <16 MHz.

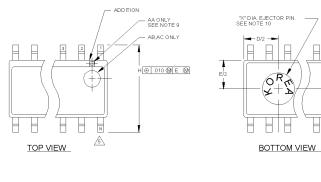
  Duty Cycle measured at 120 MHz. For 133 MHz, degrades to 35/65 worst case.

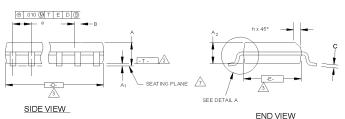
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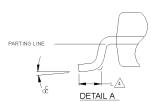


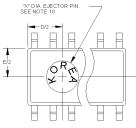
### Package Diagram

#### 8-Pin Small Outlined Integrated Circuit (SOIC, 150-mil)









- NOTES:
- 1. MAXIMUM DIE THICKNESS ALLOWABLE IS .015.
- 2. DIMENSIONING & TOLERANCES PER ANSI.Y14.5M 1982.
- /3. "T" IS A REFERENCE DATUM.
- AT THE MOLD PARTING LINE. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.006 INCHES PER SIDE.
- 5. "L" IS THE LENGTH OF TERMINAL FOR SOLDERING TO A SUBSTRATE
- 6 "N" IS THE NUMBER OF TERMINAL POSITIONS.
- TERMINAL POSITIONS ARE SHOWN FOR
- REFERENCE ONLY.

  8 FORMED LEADS SHALL BE PLANAR WITH RESPECT TO
  ONE ANOTHER WITHIN .003 INCHES AT SEATING PLANE.
- THE APPEARANCE OF PIN #1 I.D ON THE 8 LD IS OPTIONAL, ROUND TYPE ON SINGLE LEADFRAME AND RECTANGULAR TYPE ON MATRIX LEADFRAME.
- 10. COUNTRY OF ORIGIN LOCATION AND EJECTOR PIN ON PACKAGE BOTTOM IS OPTIONAL AND DEPEND ON ASSEMBLY LOCATION.
- 11, CONTROLLING DIMENSION: INCHES.

### THIS TABLE IN INCHES

S		COMMO	V		NOTE		3		5
M B	D	<b>IMENSIOI</b>	VS.	N <sub>O</sub>	VARI-		D		N
2	MIN.	NOM.	MAX.	T <sub>E</sub>	ATIONS	MIN.	NOM.	MAX.	
Α	.061	.064	.068		AA	.189	.194	.196	8
A,	.004	.006	.0098		AB	.337	.342	.344	14
$A_2$	.055	.058	.061		AC	.386	.391	.393	16
В	.0138	.016	.0192						
С	.0075	.008	.0098						
D	SEE VARIATIONS			3					
E	.150	.155	.157						
е		.050 BSC							
H	.230	.236	.244						
h	.010	.013	.016						
L	.016	.025	.035						
Ν	SEE VARIATIONS		5						
oc	0°	5°	8°						
Х									

#### THIS TABLE IN MILLIMETERS

S		COMMO	V		NOTE		3		5
M B	D	DIMENSIONS			VARI-		D		N
2	MIN.	NOM.	MAX.	T <sub>E</sub>	ATIONS	MIN.	NOM.	MAX.	
Α	1.55	1.63	1.73		AA	4.80	4.93	4.98	8
Αı	0.127	0.15	0.25		AB	8.58	8.69	8.74	14
$A_2$	1.40	1.47	1.55		AC	9.80	9.93	9.98	16
В	0.35	0.41	0.49						
С	0.19	0.20	0.25						
P	SEE VARIATIONS			3					
	3.81	3.94	3.99						
е		1.27 BSC							
H	5.84	5.99	6.20						
h	0.25	0.33	0.41						
L	0.41	0.64	0.89						
Ϋ́	SEE VARIATIONS		5						
ος	0°	5°	8°						
Χ	2.16	2.36	2.54						



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