



Typical unit

### FEATURES

- Fixed DC outputs, 12V @ 20A
- Industry standard quarter brick 2.3" x 1.45" x 0.46" open frame package
- Wide range 18 to 60 Vdc input voltages with 2250 Volt Basic isolation
- Remote ON/Off enable control
- DOSA-compatible pinouts and form factor
- High efficiency synchronous rectifier topology
- Multiple-unit parallel operation for increased current
- Stable no-load operation
- Monotonic startup into pre-bias output condition
- Certified to UL/60950-1, CSA-C22.2 No. 60950-1, 2nd edition safety approvals
- Extensive self-protection, OVP, input undervoltage, current limiting and thermal shutdown
- Trimmable output from 10.8V to 13.2V

### PRODUCT OVERVIEW

The UWQ series offers high output current (up to 20 Amps) in an industry standard "quarter brick" package requiring no heat sink for most applications. The UWQ series delivers fixed DC output voltages up to 240 Watts (12V @ 20A) for printed circuit board mounting. Wide range inputs of 18 to 60 Volts DC (48 Volts nominal) are ideal for datacom and telecom systems.

The UWQ-12/20-T48xS offers a load sharing option for paralleling up to three modules in the most demanding, power hungry applications. The UWQ-12/20-T48xT is trimmable from 10.8Vout to 13.2Vout and includes Sense pins to compensate for voltage drops at the load.

Advanced automated surface mount assembly and planar magnetics deliver galvanic isolation rated at 2250 Vdc for basic insulation. To power digital systems, the outputs offer fast settling to current steps and tolerance of higher capacitive

loads. Excellent ripple and noise specifications assure compatibility to CPUs, ASICs, programmable logic and FPGAs. No minimum load is required. For systems needing controlled startup/shutdown, an external remote On/Off control may use either positive or negative logic.

A wealth of self-protection features include input undervoltage lockout and overtemperature shutdown using an on-board temperature sensor; overcurrent protection using the "hiccup" auto-restart technique, provides indefinite short-circuit protection, along with output OVP. The synchronous rectifier topology offers high efficiency for minimal heat generation and "no heat sink" operation. The UWQ series is certified to safety standards UL/IEC/CSA 60950-1, 2nd edition. It meets class B EMI conducted emission compliance to EN55022, CISPR22 with an external filter.

### APPLICATIONS

- Embedded systems, datacom and telecom installations, wireless base stations
- Disk farms, data centers and cellular repeater sites
- Remote sensor systems, dedicated controllers
- Instrumentation systems, R&D platforms, automated test fixtures
- Data concentrators, voice forwarding and speech processing systems

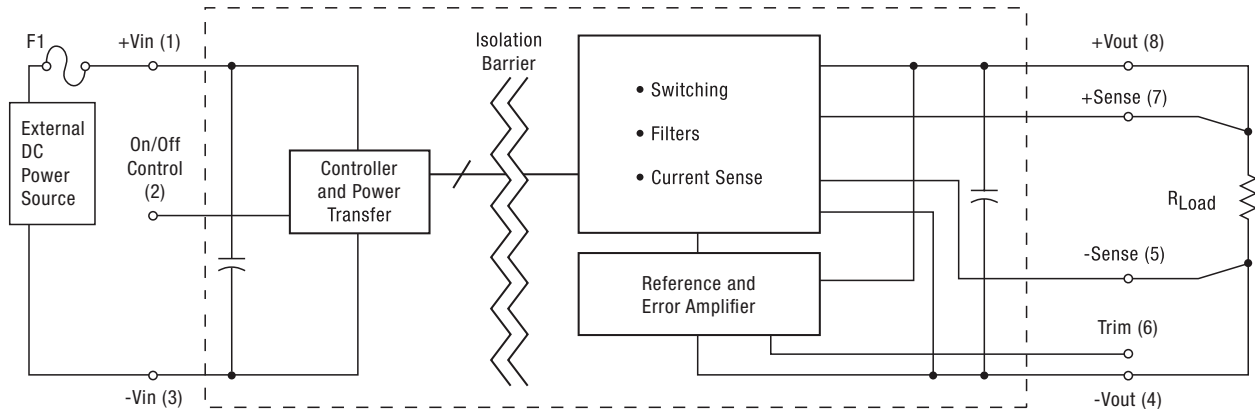


Figure 1. Connection Diagram

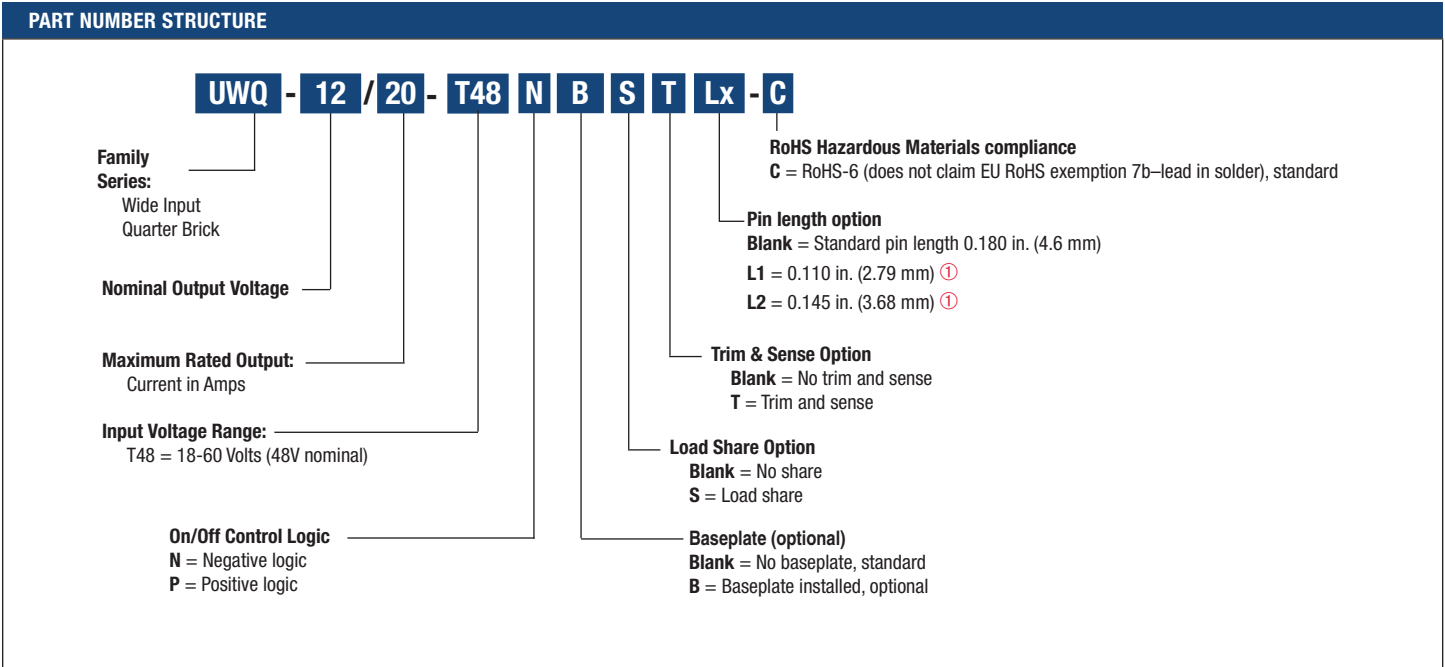
Typical topology is shown. Murata Power Solutions recommends an external fuse.



PERFORMANCE SPECIFICATIONS SUMMARY AND ORDERING GUIDE ①															
Root Model ①	Output						Input				Efficiency		Dimensions (open frame)		
	Vout (Volts)	Iout (Amps, max.)	Power (Watts)	R/N (mV pk-pk)		Regulation (Max.) ②		Vin Nom. (Volts)	Range (Volts)	Iin no load (mA)	Iin full load (Amps)	Min.	Typ.	(inches)	(mm)
				Typ.	Max.	Line	Load								
UWQ-12/20-T48	12	20	240	100	120	±1.0	±1.5	48	18-60	90	5.43	90%	92%	2.30x1.45x0.46 max.	58.4x36.8x11.7
UWQ-12/20-T48xS	12	20	240	100	120	±1.25	±2.5	48	18-60	90	5.43	90%	92%	2.30x1.45x0.46 max.	58.4x36.8x11.7
UWQ-12/20-T48xT	12	20	240	100	120	±0.25	±0.3	48	18-60	80	5.43	90%	92%	2.30x1.45x0.46 max.	58.4x36.8x11.7

① Please refer to the part number structure for additional ordering information and options.  
 ② All specifications are typical at nominal line voltage and full load, +25°C unless otherwise noted. See

detailed specifications. Output capacitors are 1 µF || 10 µF with a 22µF input capacitor. These caps are necessary for our test equipment and may not be needed for your application.



① Special quantity order is required; samples available with standard pin length only.  
 ② Some model number combinations may not be available. See website or contact your local Murata sales representative.

**Complete Model Number Example:** **UWQ-12/20-T48NBL1-C**  
 Negative On/Off logic, baseplate installed, 0.110" pin length, RoHS-6 compliance

### FUNCTIONAL SPECIFICATIONS, UWQ-12/20-T48

ABSOLUTE MAXIMUM RATINGS	Conditions ①	Minimum	Typical/Nominal	Maximum	Units
Input Voltage, Continuous	Full power operation	18	48	70	Vdc
Input Voltage, Transient	Operating or non-operating, 100 mS max. duration			75	Vdc
Isolation Voltage	Input to output			2250	Vdc
On/Off Remote Control	Power on or off, referred to -Vin	0		13.5	Vdc
Output Power		0		247.2	W
Output Current	Current-limited, no damage, short-circuit protected	0		20	A
Storage Temperature Range	Vin = Zero (no power)	-55		125	°C
Absolute maximums are stress ratings. Exposure of devices to greater than any of these conditions may adversely affect long-term reliability. Proper operation under conditions other than those listed in the Performance/Functional Specifications Table is not implied or recommended.					
INPUT					
Conditions ① ③					
Operating voltage range		18	48	60	Vdc
Recommended External Fuse	Fast blow		20		A
Start-up threshold	Rising input voltage	16	16.75	17.5	Vdc
Undervoltage shutdown	Falling input voltage	14.75	15.5	16.75	Vdc
Internal Filter Type			L-C		
Input current					
Full Load Conditions	Vin = nominal		5.43	5.72	A
Low Line	Vin = minimum		14.65	15.34	A
Inrush Transient	Vin = 48V.		0.05	0.1	A2-Sec.
Output in Short Circuit			50	100	mA
No Load input current (T48xT models)	Iout = minimum, unit = ON		80	150	mA
No Load input current (all other models)	Iout = minimum, unit = ON		90	150	mA
Shut down mode input current			5	8	mA
Reflected (back) ripple current ②	Measured at input with specified filter		15	25	mA, RMS
Pre-biased startup	External output voltage < Vset		Monotonic		
GENERAL and SAFETY					
Efficiency	Vin=48V, full load	90	92		%
	Vin=min	89.5	91		%
Isolation					
Isolation Voltage, input to output	With or without baseplate	2250			Vdc
Isolation Voltage, input to baseplate	With baseplate	1500			Vdc
Isolation Voltage, output to baseplate	With baseplate	1500			Vdc
Insulation Safety Rating			basic		
Isolation Resistance			100		MΩ
Isolation Capacitance			1500		pF
Safety (certified to the following requirements)	UL-60950-1, CSA-C22.2 No.60950-1, IEC/60950-1, 2nd edition		Yes		
Calculated MTBF	Per Telcordia SR-332, issue 1, class 3, ground fixed, Tambient = +25°C		TBD		Hours x 10 <sup>3</sup>
DYNAMIC CHARACTERISTICS (T48xT models)					
Fixed Switching Frequency		250	275	300	KHz
Startup Time	Power On, to Vout regulation band		60	65	mS
Startup Time	Remote ON to Vout Regulated		60	65	mS
Dynamic Load Response	50-75-50% load step to 3% error band		220	275	μSec
Dynamic Load Peak Deviation	same as above		±500	±700	mV
DYNAMIC CHARACTERISTICS (all other models)					
Fixed Switching Frequency		180	200	220	KHz
Startup Time	Power On, to Vout regulation band		10	20	mS
Startup Time	Remote ON to Vout Regulated		10	20	mS
Dynamic Load Response	50-75-50% load step to 3% error band		200	250	μSec
Dynamic Load Peak Deviation	same as above		±1100	±1300	mV
FEATURES and OPTIONS					
Remote On/Off Control ④					
"N" suffix:					
Negative Logic, ON state	ON = pin grounded or external voltage	0		1	Vdc
Negative Logic, OFF state	OFF = pin open or external voltage	3.5		13.5	Vdc
Control Current	open collector/drain		1	2	mA
"P" suffix:					
Positive Logic, ON state	ON = pin open or external voltage	3.5		13.5	V
Positive Logic, OFF state	OFF = ground pin or external voltage	0		1	V
Control Current	open collector/drain		1	2	mA
Base Plate	"B" suffix		optional		

### FUNCTIONAL SPECIFICATIONS, UWQ-12/20-T48, (CONT.)

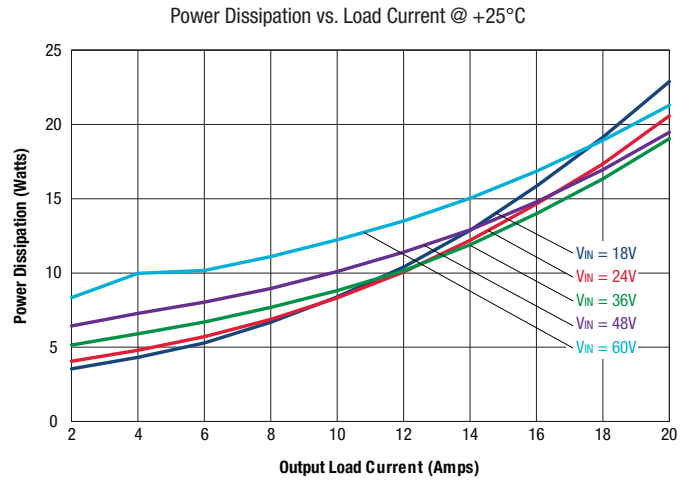
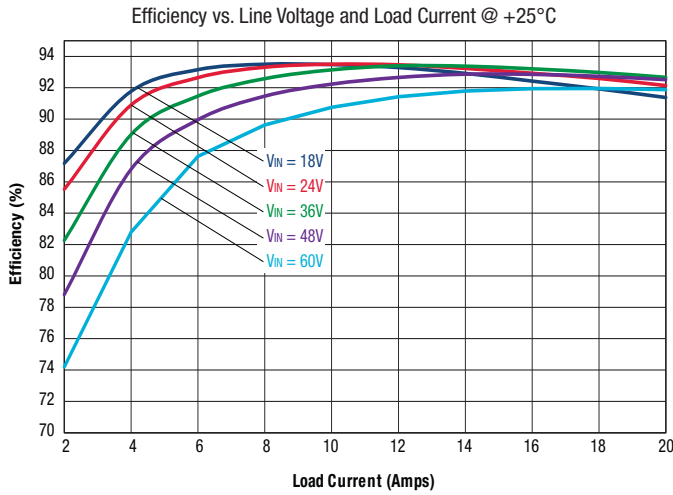
OUTPUT	Conditions ①	Minimum	Typical/Nominal	Maximum	Units
<b>Total Output Power</b>		0.0	240	247.2	W
<b>Voltage</b>					
<b>Setting Accuracy, fixed output</b>	At 50% load, not user adjustable	11.64	12	12.36	Vdc
<b>Output Voltage Range (T48xT models)</b>	User-adjustable	-10		+10	% of Vnom.
<b>Overvoltage Protection</b>	Via magnetic feedback			15	Vdc
<b>Current</b>					
<b>Output Current Range</b>		0	20	20	A
<b>Minimum Load</b>			No minimum load		
<b>Current Limit Inception</b>	96% of Vnom., cold condition	23.5	25.5	27.5	A
<b>Short Circuit</b>					
<b>Short Circuit Current</b>	Hiccup technique, autorecovery within 1.25% of Vout		1	2	A
<b>Short Circuit Duration (remove short for recovery)</b>	Output shorted to ground, no damage		Continuous		
<b>Short circuit protection method</b>	Hiccup current limiting		Non-latching		
<b>Regulation (standard 12/20-T48) ⑤</b>					
<b>Line Regulation</b>	Vin=min. to max., Vout=nom., full load			±1	% of Vout
<b>Load Regulation</b>	Iout=min. to max., Vin=nom.			±1.5	% of Vout
<b>Regulation (T48xS models) ⑤</b>					
<b>Line Regulation</b>	Vin=min. to max., Vout=nom., full load			±1.25	% of Vout
<b>Load Regulation</b>	Iout=min. to max., Vin=nom.			±2.5	% of Vout
<b>Regulation (T48xT models) ⑤</b>					
<b>Line Regulation</b>	Vin=min. to max., Vout=nom., full load			±0.25	% of Vout
<b>Load Regulation</b>	Iout=min. to max., Vin=nom.			±0.3	% of Vout
<b>Ripple and Noise ⑥</b>	5 Hz- 20 MHz BW, Cout=1µF MLCC paralleled with 10µF tantalum		100	120	mV pk-pk
<b>Temperature Coefficient</b>	At all outputs		0.02		% of Vout./°C
<b>Maximum Capacitive Loading</b>	Low ESR		5000		µF
<b>Current Share Accuracy (2 units in parallel) (T48xS models)</b>	Percent deviation from ideal sharing (50%)			±10	%
<b>Remote Sense Compliance (T48xT models)</b>	Sense connected at load			10	% of Vout
<b>MECHANICAL (Through Hole Models)</b>					
<b>Outline Dimensions (no baseplate)</b>			2.3x1.45x0.46 max.		Inches
(Please refer to outline drawing)	LxWxH		58.4x36.8x11.68		mm
<b>Outline Dimensions (with baseplate)</b>			2.3x1.45x0.5		Inches
			58.4x36.8x12.7		mm
<b>Weight</b>	No baseplate		1.6		Ounces
	No baseplate		45		Grams
	With baseplate		2.24		Ounces
	With baseplate		63.5		Grams
<b>Through Hole Pin Diameter</b>			0.04 & 0.06		Inches
			1.016 & 1.52		mm
<b>Through Hole Pin Material</b>			Copper alloy		
<b>TH Pin Plating Metal and Thickness</b>	Nickel subplate		50		µ-inches
	Gold overplate		5		µ-inches
<b>Baseplate Material</b>			Aluminum		
<b>ENVIRONMENTAL</b>					
<b>Operating Ambient Temperature Range</b>	See derating curves	-40		85	°C
<b>Operating Case Temperature</b>	With baseplate, no derating	-40		110	°C
<b>Storage Temperature</b>	Vin = Zero (no power)	-55		125	°C
<b>Thermal Protection/Shutdown</b>	Measured at hotspot	135	140	150	°C
<b>Electromagnetic Interference Conducted, EN55022/CISPR22</b>	External filter is required		B		Class
<b>RoHS rating</b>			RoHS-6		

### Notes

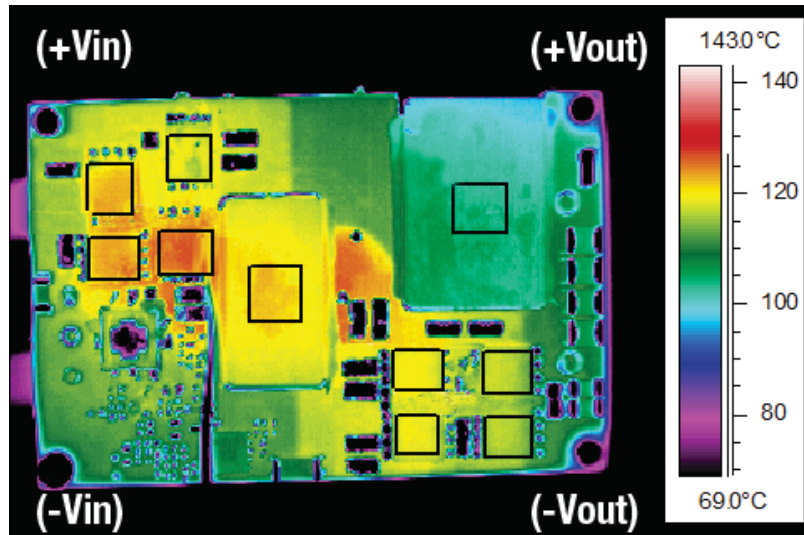
- ① Unless otherwise noted, all specifications apply at Vin = nominal, nominal output voltage and full output load. General conditions are near sea level altitude, no base plate installed and natural convection airflow unless otherwise specified. All models are tested and specified with external parallel 1 µF and 10 µF multi-layer ceramic output capacitors and a 22µF external input capacitor (see Technical Notes). All capacitors are low-ESR types wired close to the converter. These capacitors are necessary for our test equipment and may not be needed in the user's application.
- ② Input (back) ripple current is tested and specified over 5 Hz to 20 MHz bandwidth. Input filtering is Cin = 33 µF/100V, Cbus = 220µF/100V and Lbus = 12 µH.

- ③ All models are stable and regulate to specification under no load.
- ④ The Remote On/Off Control is referred to -Vin.
- ⑤ Regulation specifications describe the output voltage changes as the line voltage or load current is varied from its nominal or midpoint value to either extreme. The load step is ±25% of full load current.
- ⑥ Output Ripple and Noise is measured with Cout = 1 µF || 10 µF, 20 MHz oscilloscope bandwidth and full resistive load.

**PERFORMANCE DATA, UWQ-12/20-T48-C**

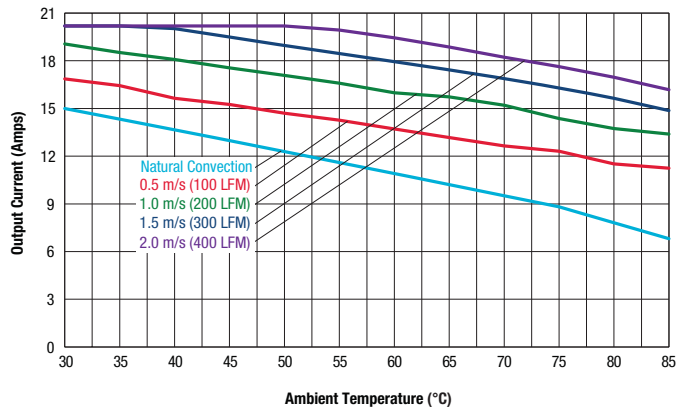


Thermal image with hot spot at 10.8A with 25°C ambient temperature. Natural convection is used with no forced airflow. Identifiable and recommended maximum value to be verified in application.

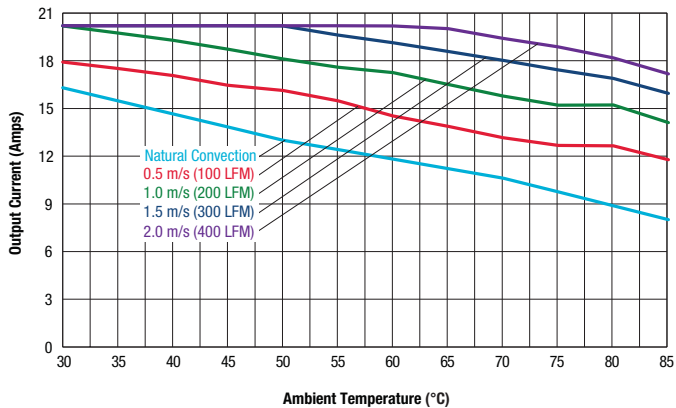


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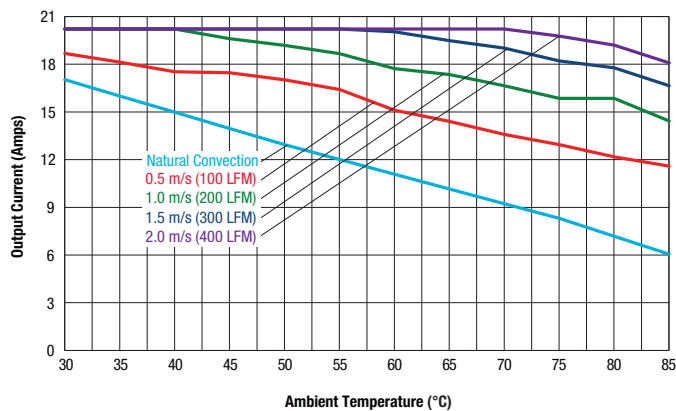
Maximum Current Temperature Derating at sea level  
(Vin = 18V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



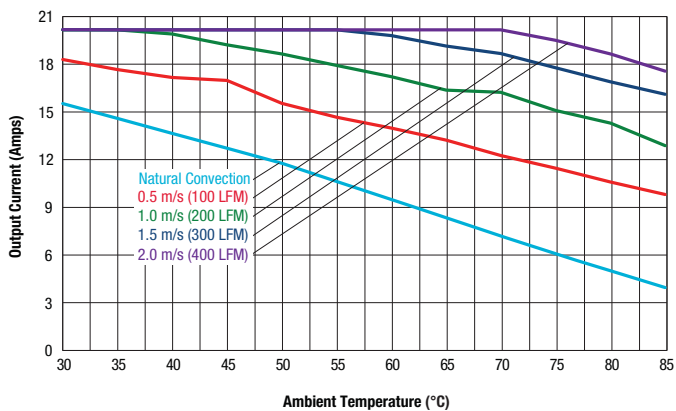
Maximum Current Temperature Derating at sea level  
(Vin = 24V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



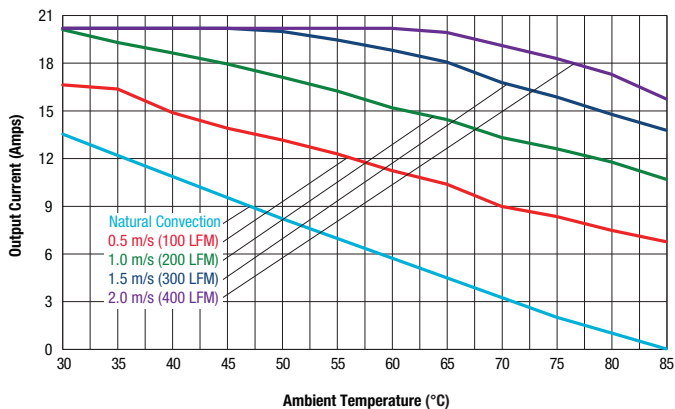
Maximum Current Temperature Derating at sea level  
(Vin = 36V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



Maximum Current Temperature Derating at sea level  
(Vin = 48V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)

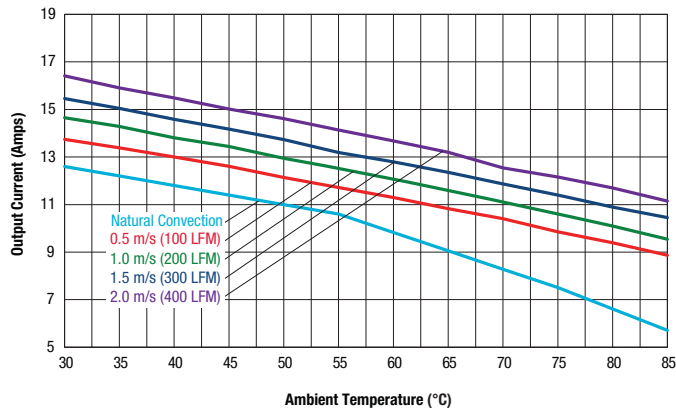


Maximum Current Temperature Derating at sea level  
(Vin = 60V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)

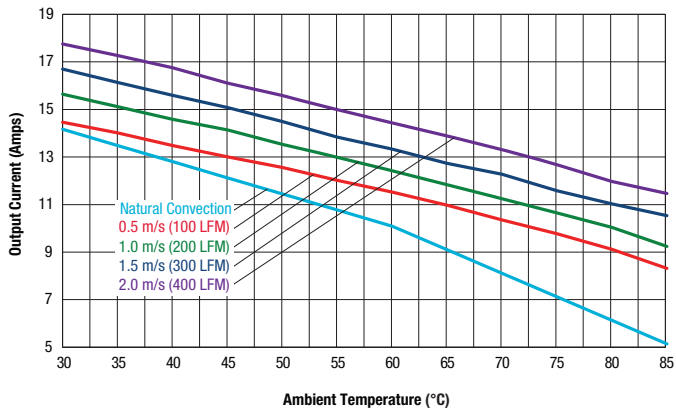


**PERFORMANCE DATA, UWQ-12/20-T48-C**

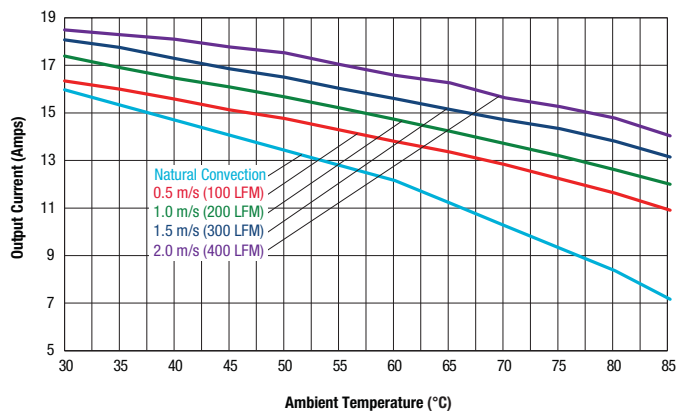
Maximum Current Temperature Derating at sea level  
(Vin = 18V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)



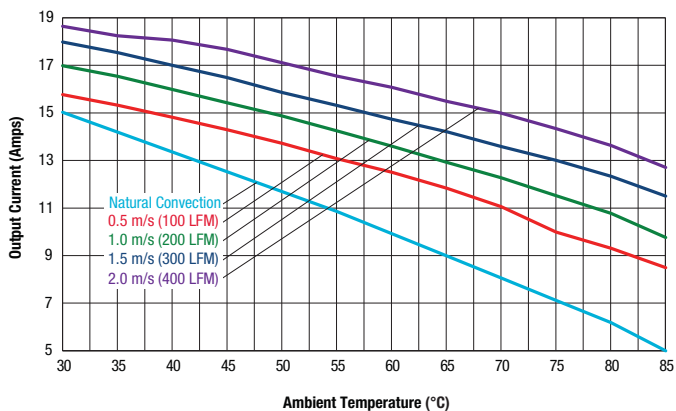
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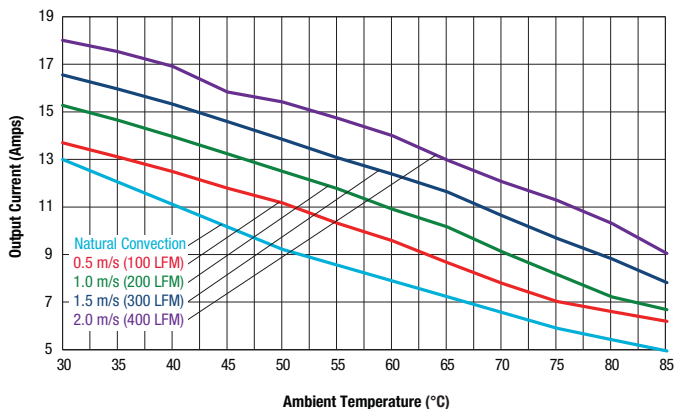
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(Vin = 48V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)



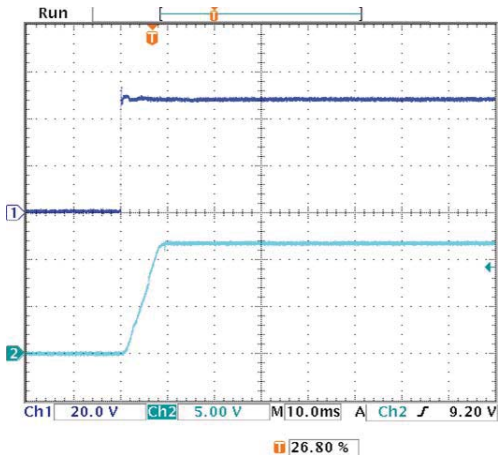
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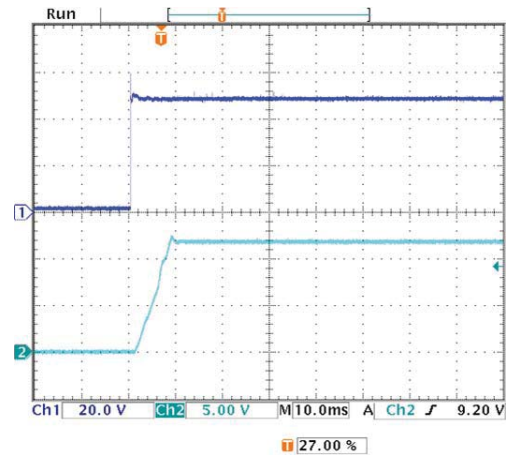


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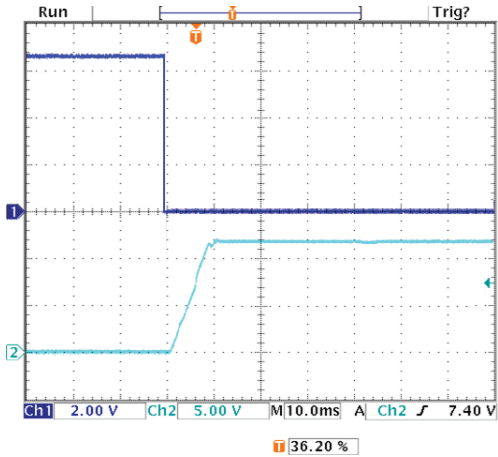
Start-up Delay ( $V_{in} = 48V$ ,  $I_{out} = 0A$ ,  $C_{load} = 0$ ,  $T_a = +25^{\circ}C$ ) Ch1 = Vin, Ch2 = Vout



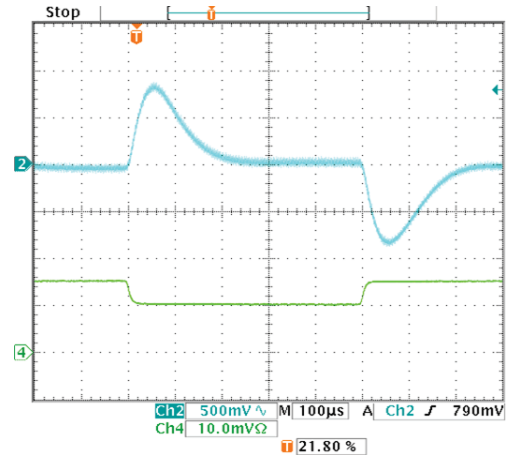
Start-up Delay ( $V_{in} = 48V$ ,  $I_{out} = 20A$ ,  $C_{load} = 5000\mu F$ ,  $T_a = +25^{\circ}C$ ) Ch1 = Vin, Ch2 = Vout



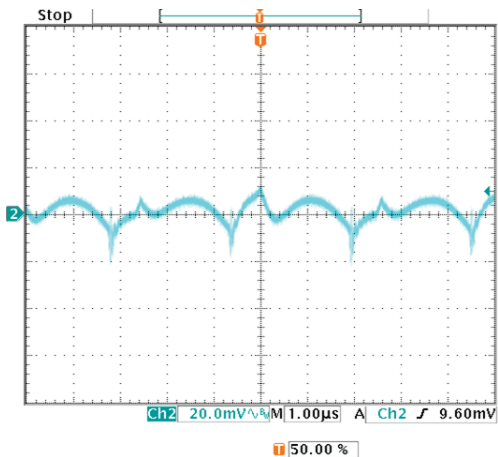
On/Off Enable Delay ( $V_{in} = 48V$ ,  $V_{out} = \text{nom}$ ,  $I_{out} = 20A$ ,  $C_{load} = 5000\mu F$ ,  $T_a = +25^{\circ}C$ ) Ch1 = Enable, Ch2 = Vout.



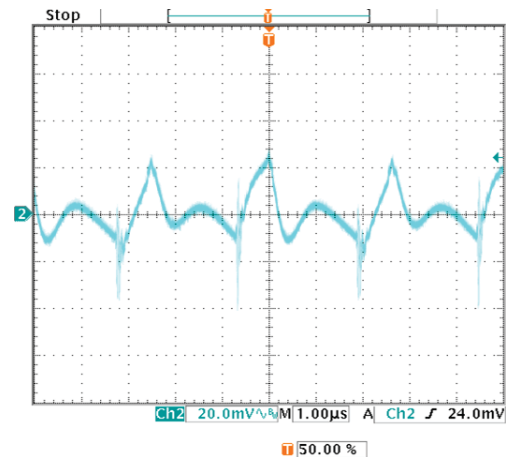
Stepload Transient Response ( $V_{in} = 48V$ ,  $I_{out} = 50-75-50\%$  of  $I_{max}$ ,  $C_{load} = 1\mu F \parallel 10\mu F$ ,  $I_o = 10A/\text{div}$ ,  $T_a = +25^{\circ}C$ ) Ch2 = Vout, Ch4 =  $I_{out}$



Output ripple and Noise ( $V_{in} = 48V$ ,  $I_{out} = 0A$ ,  $C_{load} = 1\mu F \parallel 10\mu F$ ,  $T_a = +25^{\circ}C$ ,  $BW = 20\text{MHz}$ )



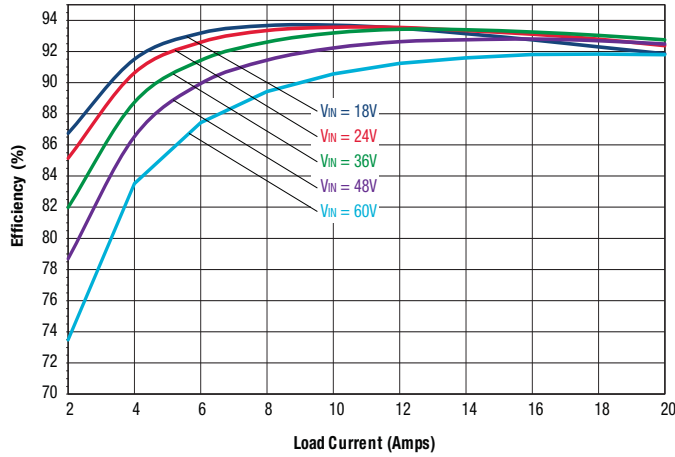
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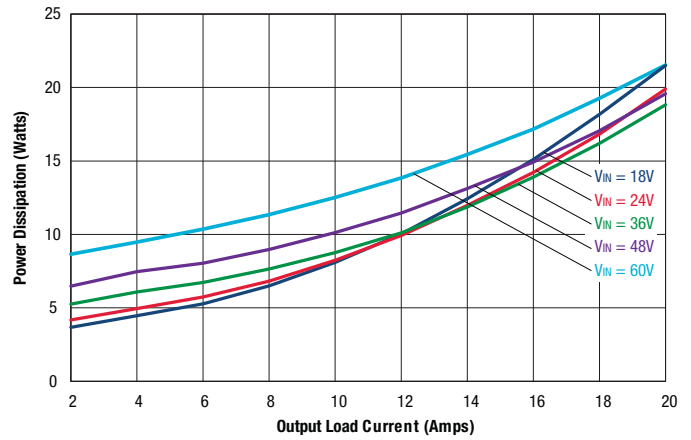


**PERFORMANCE DATA, UWQ-12/20-T48xS**

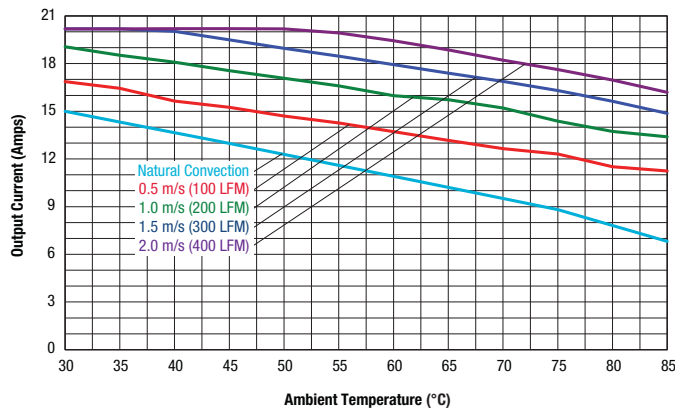
Efficiency vs. Line Voltage and Load Current @ +25°C



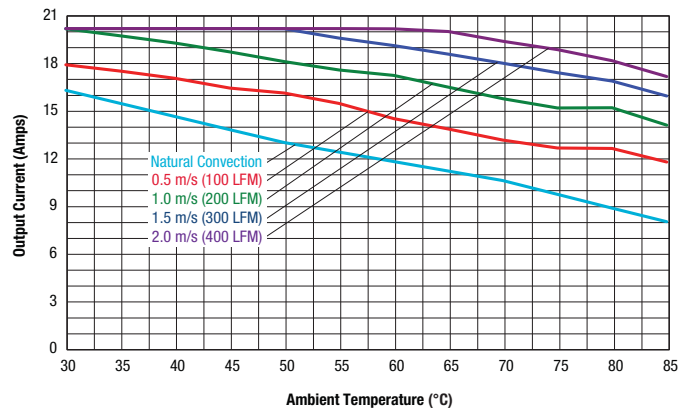
Power Dissipation vs. Load Current @ +25°C



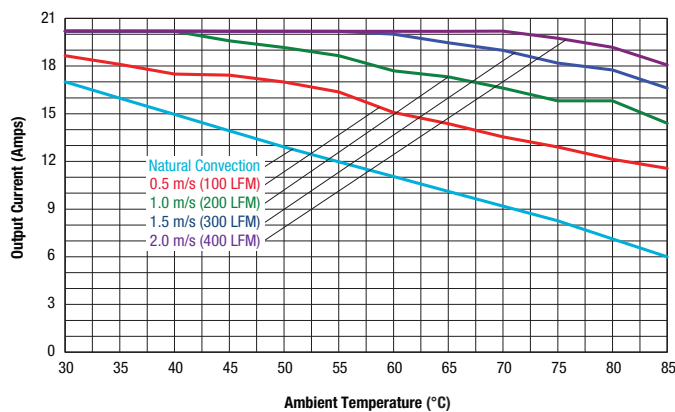
Maximum Current Temperature Derating at sea level  
(V<sub>IN</sub> = 18V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



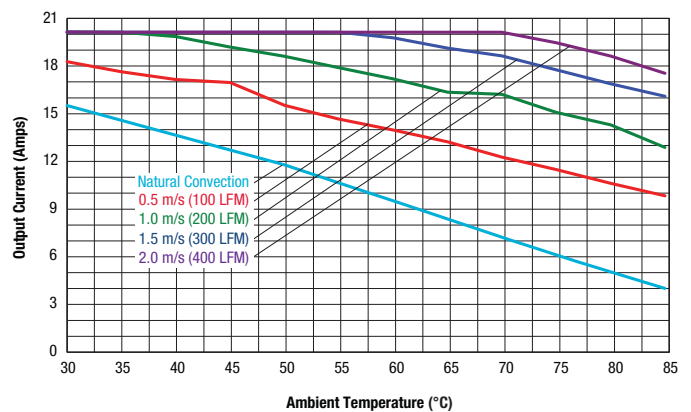
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(V<sub>IN</sub> = 36V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)

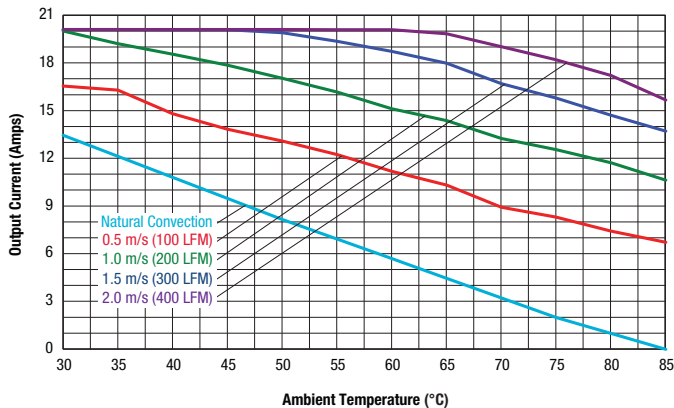


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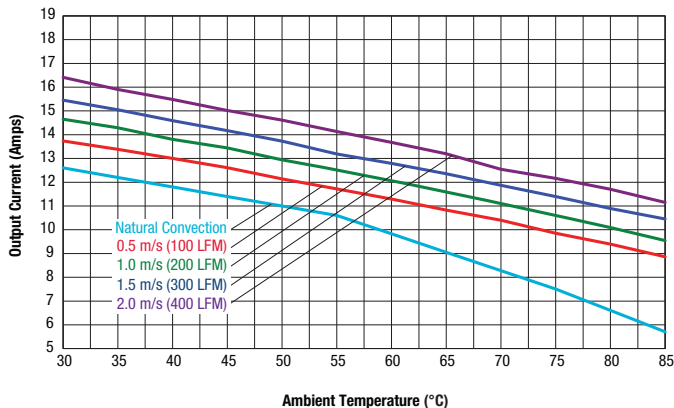


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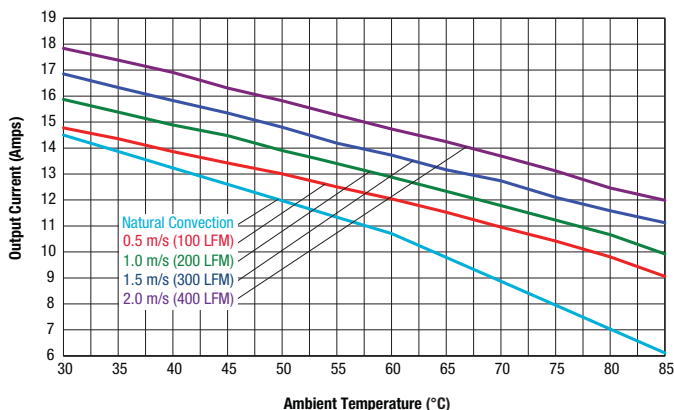
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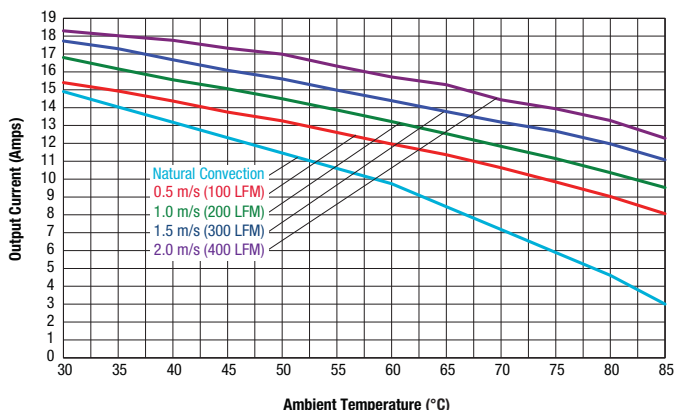
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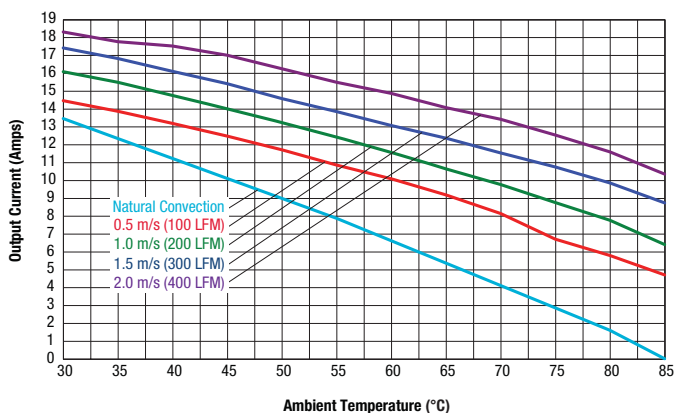
Maximum Current Temperature Derating at sea level  
(Vin = 24V, air flow from Pin 3 to Pin 1 on PCB, without baseplate)



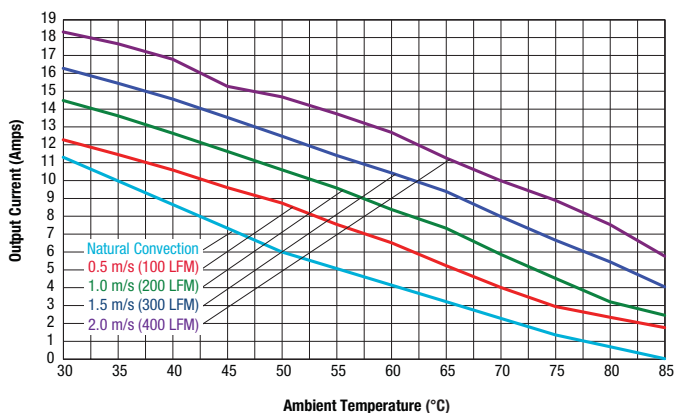
Maximum Current Temperature Derating at sea level  
(Vin = 36V, air flow from Pin 3 to Pin 1 on PCB, without baseplate)



Maximum Current Temperature Derating at sea level  
(Vin = 48V, air flow from Pin 3 to Pin 1 on PCB, without baseplate)

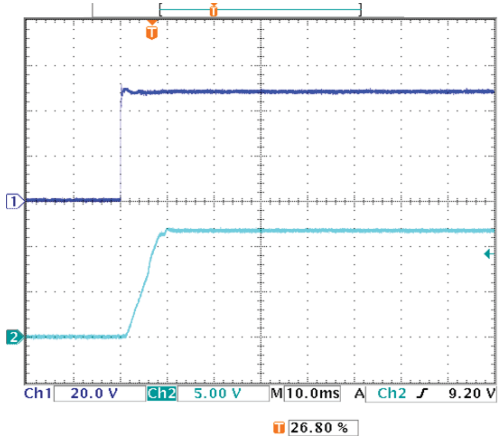


Maximum Current Temperature Derating at sea level  
(Vin = 60V, air flow from Pin 3 to Pin 1 on PCB, without baseplate)

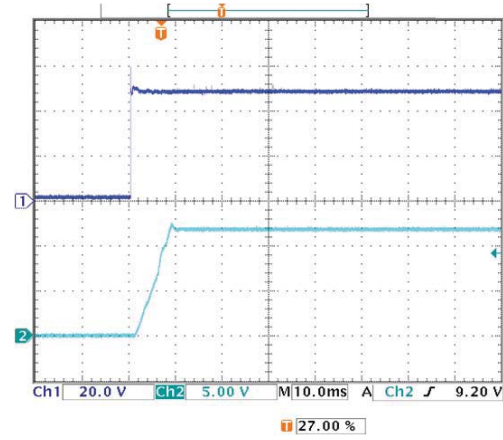


**PERFORMANCE DATA, UWQ-12/20-T48xS**

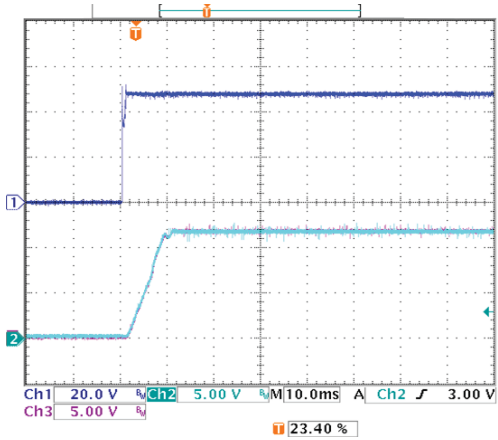
Start-up Delay (Vin=48V, Iout=0A, Cload=5000μF, Ta=+25°C) Ch1= Vin, Ch2= Vout



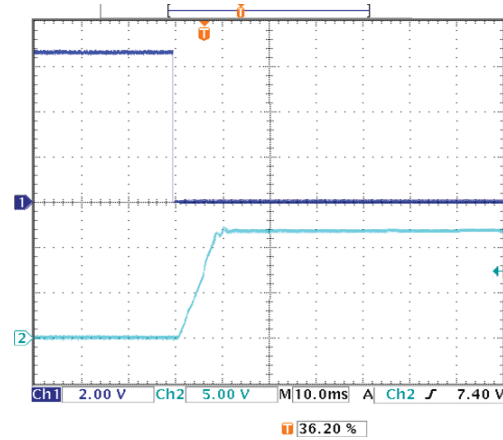
Start-up Delay (Vin=48V, Iout=20A, Cload=5000μF, Ta=+25°C) Ch1= Vin, Ch2= Vout



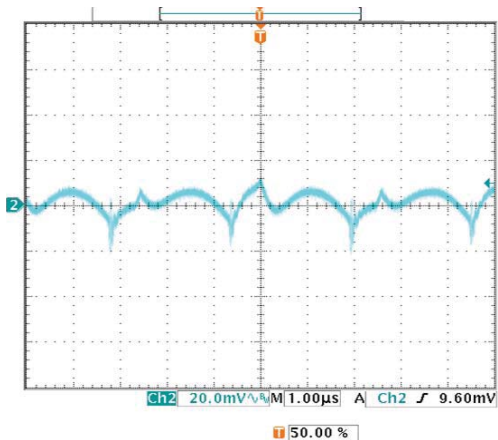
Start-up Parallel Operation (Vin=48V, Iout=full load, Cload=10000μF, Ta=+25°C)  
Ch1= Vin, Ch2, Ch3= Vout



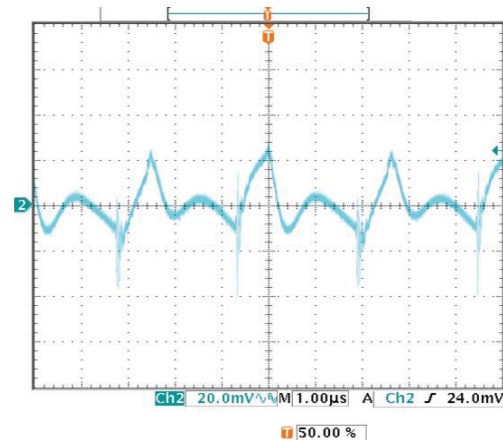
Enable Start-up Delay (Vin=48V, Iout=20A, Cload=5000μF, Ta=+25°C) Ch1= Enable, Ch2= Vout



Output Ripple and Noise (Vin=48V, Iout=0A, Cload= 1μF || 10μF, Ta=+25°C, BW=20Mhz)

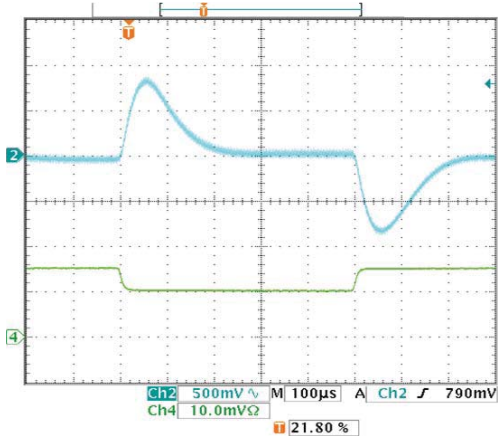


Output Ripple and Noise (Vin=48V, Iout=20A, Cload= 1μF || 10μF, Ta=+25°C, BW=20Mhz)

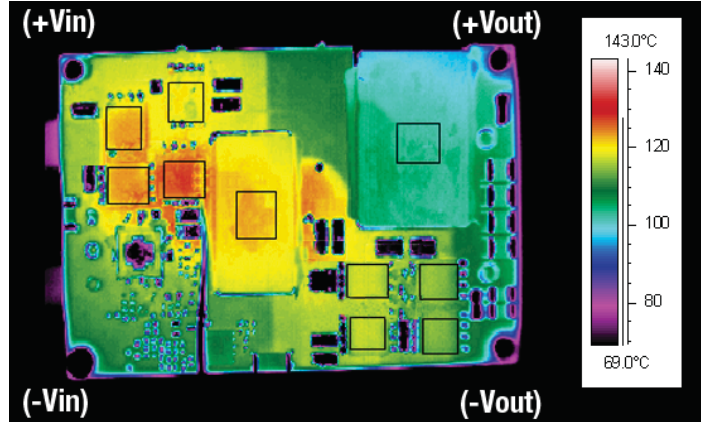


**PERFORMANCE DATA, UWQ-12/20-T48xS**

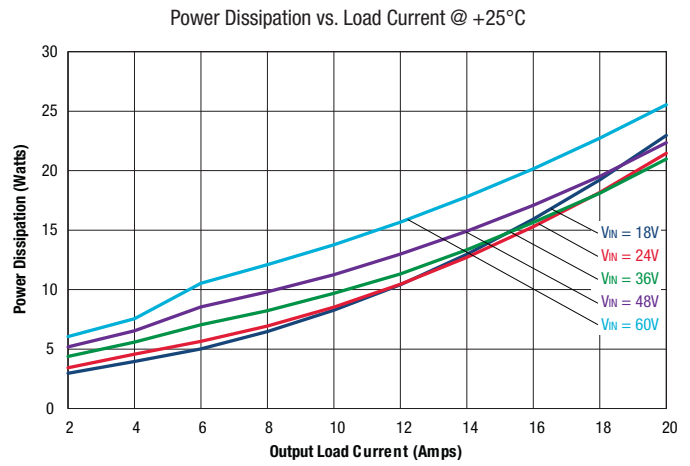
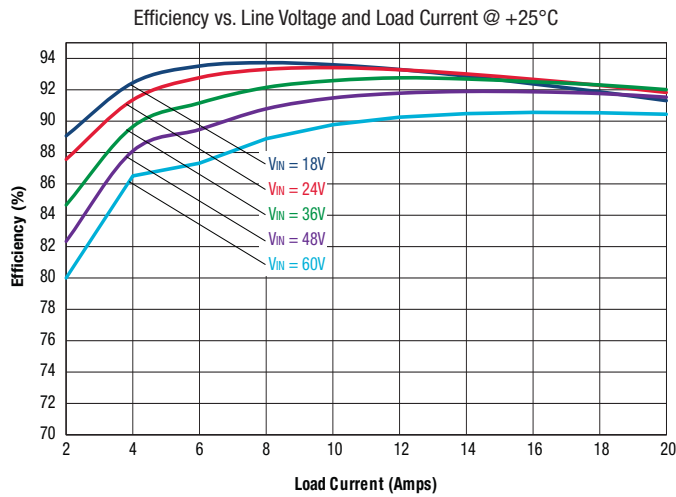
Stepload Transient Response ( $V_{in}=48V$ ,  $I_{out}=50-75-50\%$  of  $I_{max}$ ,  $C_{load}=1\mu F \parallel 10\mu F$ ,  $I_o=10A/div$ ,  $T_a=+25^{\circ}C$ ) Ch2=Vout, Ch4=lout



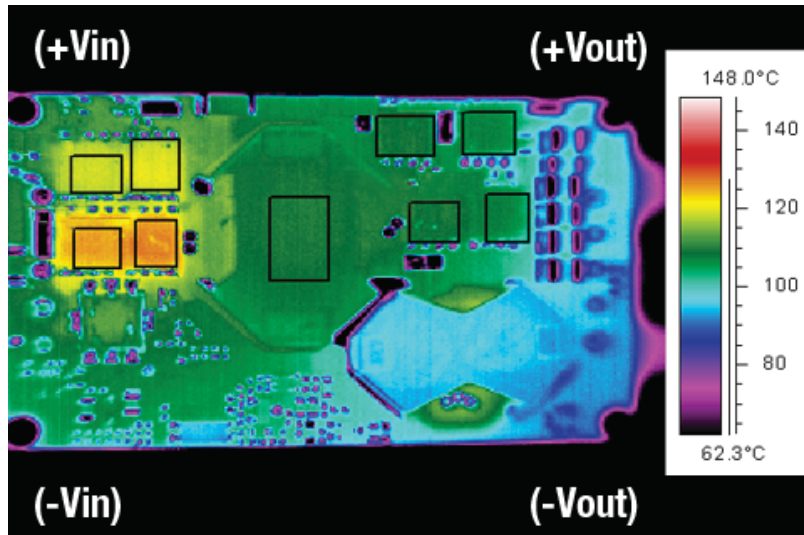
Thermal image with hot spot at 10.8A with 25°C ambient temperature.  
Natural convection is used with no forced airflow.  
Identifiable and recommended maximum value to be verified in application.



**PERFORMANCE DATA, UWQ-12/20-T48xT**

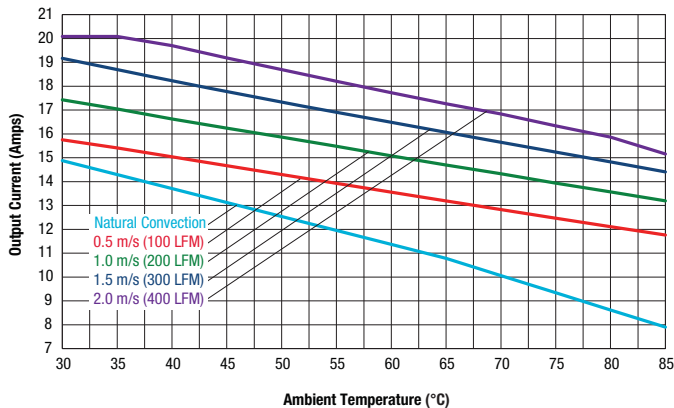


Thermal image with hot spot at 8.9A with 25°C ambient temperature. Natural convection is used with no forced airflow. Identifiable and recommended maximum value to be verified in application

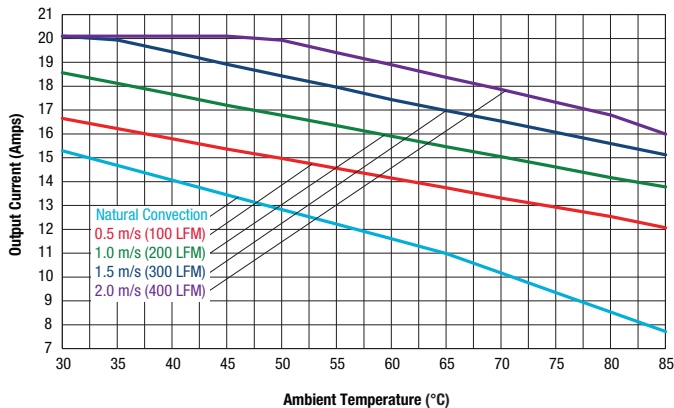


**PERFORMANCE DATA, UWQ-12/20-T48xT**

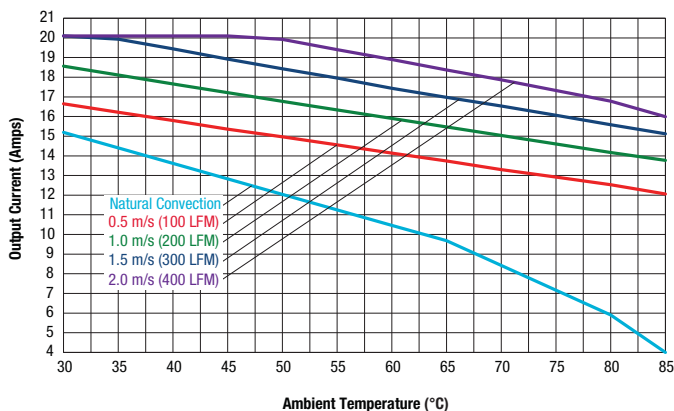
Maximum Current Temperature Derating at sea level  
(Vin = 18V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



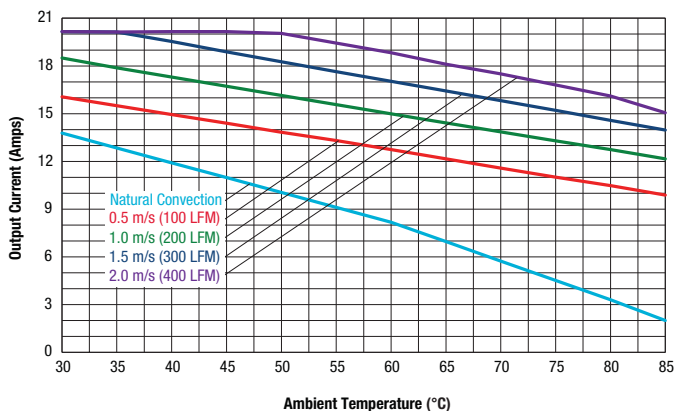
Maximum Current Temperature Derating at sea level  
(Vin = 24V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



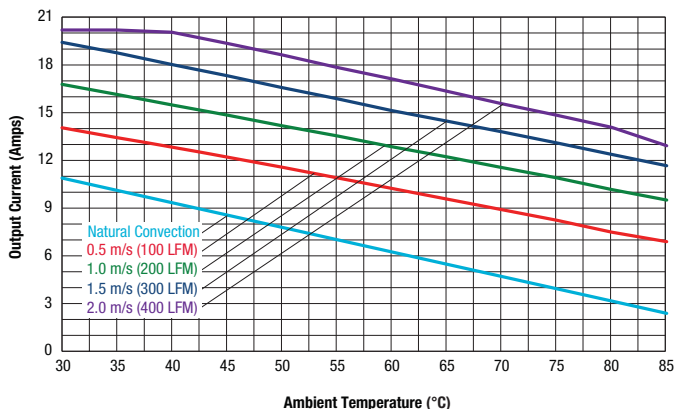
Maximum Current Temperature Derating at sea level  
(Vin = 36V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



Maximum Current Temperature Derating at sea level  
(Vin = 48V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



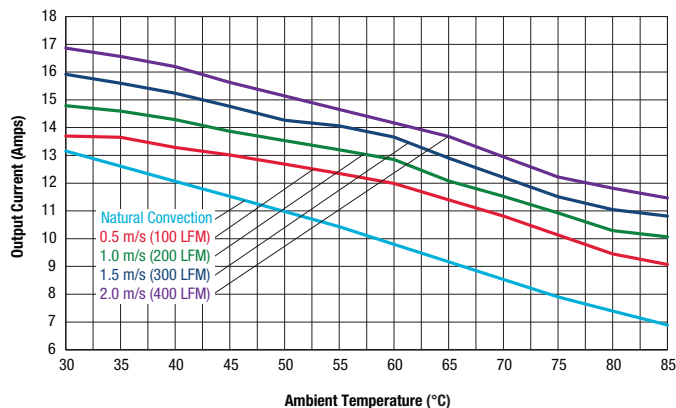
Maximum Current Temperature Derating at sea level  
(Vin = 60V, air flow from Pin 3 to Pin 1 on PCB, with baseplate)



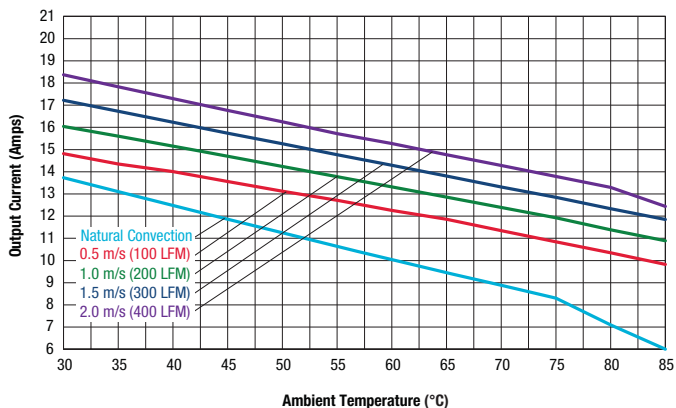


**PERFORMANCE DATA, UWQ-12/20-T48xT**

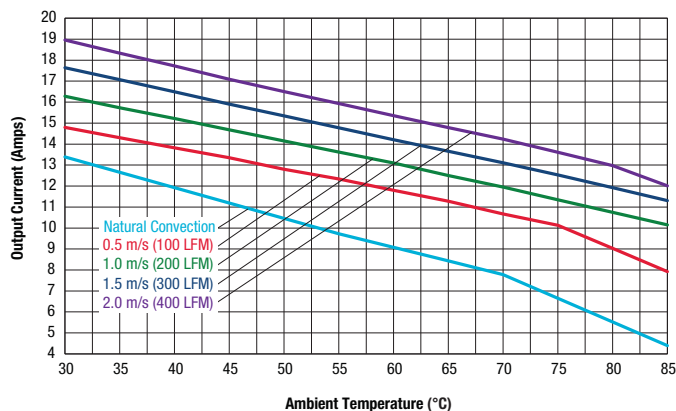
Maximum Current Temperature Derating at sea level  
(Vin = 18V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)



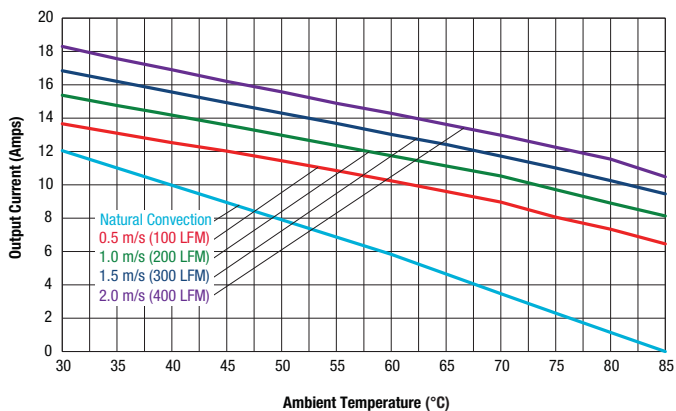
Maximum Current Temperature Derating at sea level  
(Vin = 24V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)



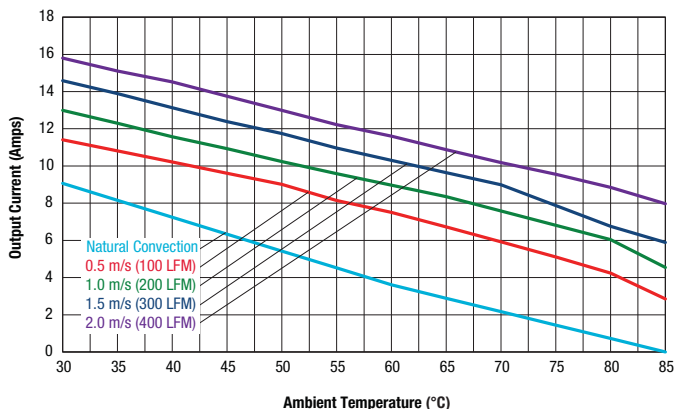
Maximum Current Temperature Derating at sea level  
(Vin = 36V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)



Maximum Current Temperature Derating at sea level  
(Vin = 48V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)

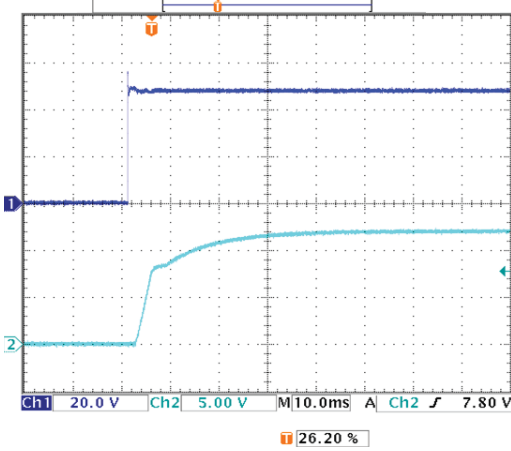


Maximum Current Temperature Derating at sea level  
(Vin = 60V, air flow from Pin 3 to Pin 1 on PCB, no baseplate)

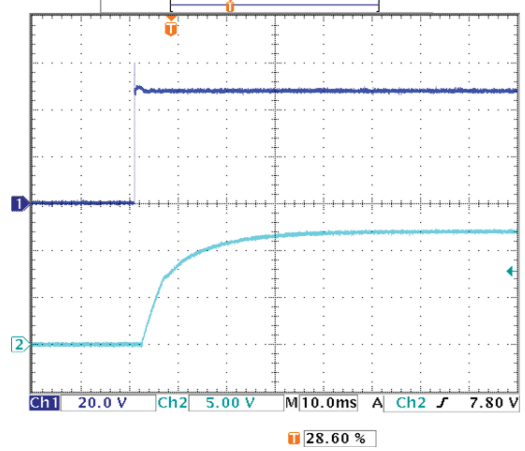


**TYPICAL PERFORMANCE DATA, UWQ-12/20-T48xT**

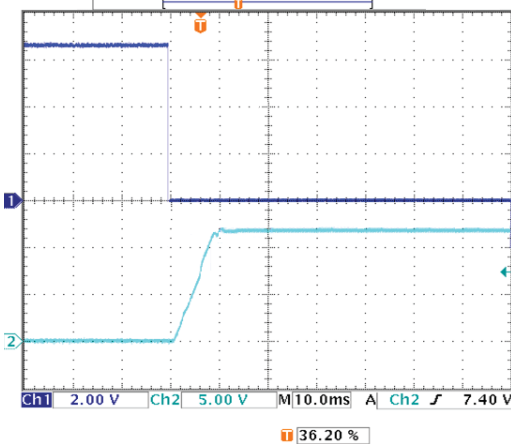
Start-up Delay (Vin=48V, Iout=0A, Cload=5000µF, Ta=+25°C) Ch1= Vin, Ch2= Vout



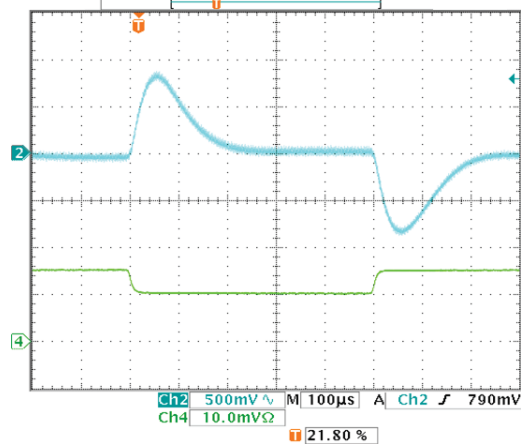
Start-up Delay (Vin=48V, Iout=20A, Cload=5000µF, Ta=+25°C) Ch1= Vin, Ch2= Vout



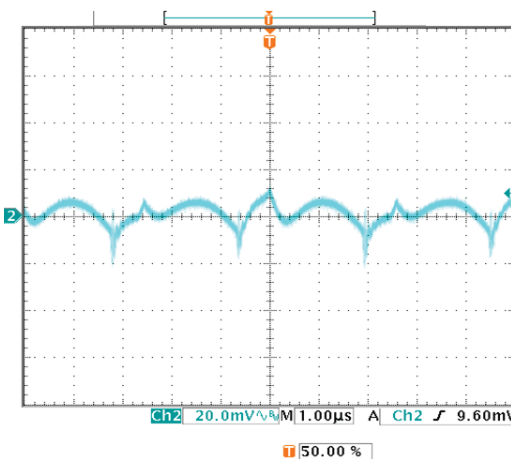
On/Off Enable Delay (Vin=48V, Vout=nom, Iout=20A, Cload=5000µF, Ta=+25°C)  
Ch1= Enable, Ch2= Vout.



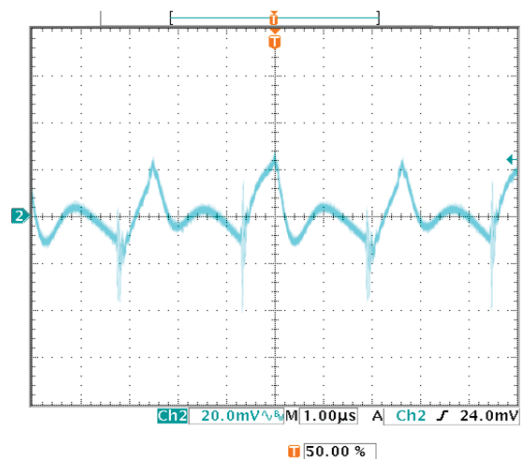
Stepload Transient Response (Vin=48V, Iout=50-75-50% of Imax, Cload=1µF || 10µF, I0=10A/div, Ta=+25°C) Ch2=Vout, Ch4=Iout



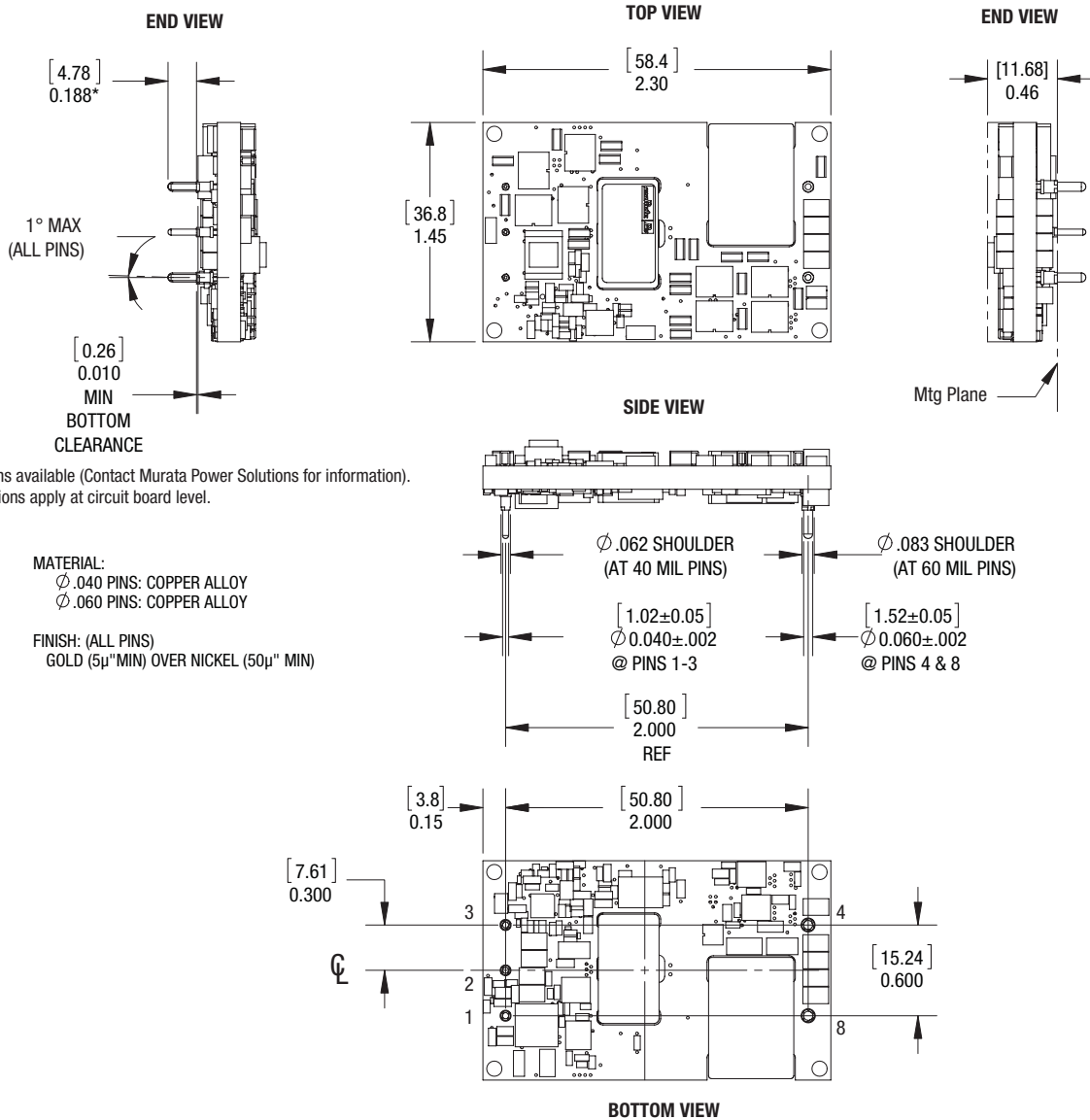
Output ripple and Noise (Vin=48V, Iout=0A, Cload= 1µF || 10µF, Ta=+25°C, BW=20Mhz)



Output ripple and Noise (Vin=48V, Iout=20A, Cload= 1µF || 10µF, Ta=+25°C, BW=20Mhz)



**MECHANICAL SPECIFICATIONS (OPEN FRAME)—STANDARD AND T48xS MODELS**

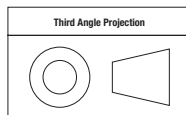


\*Alternate pin lengths available (Contact Murata Power Solutions for information).  
Pin location dimensions apply at circuit board level.

**MATERIAL:**  
 $\phi .040$  PINS: COPPER ALLOY  
 $\phi .060$  PINS: COPPER ALLOY

**FINISH: (ALL PINS)**  
 GOLD (5 $\mu$ " MIN) OVER NICKEL (50 $\mu$ " MIN)

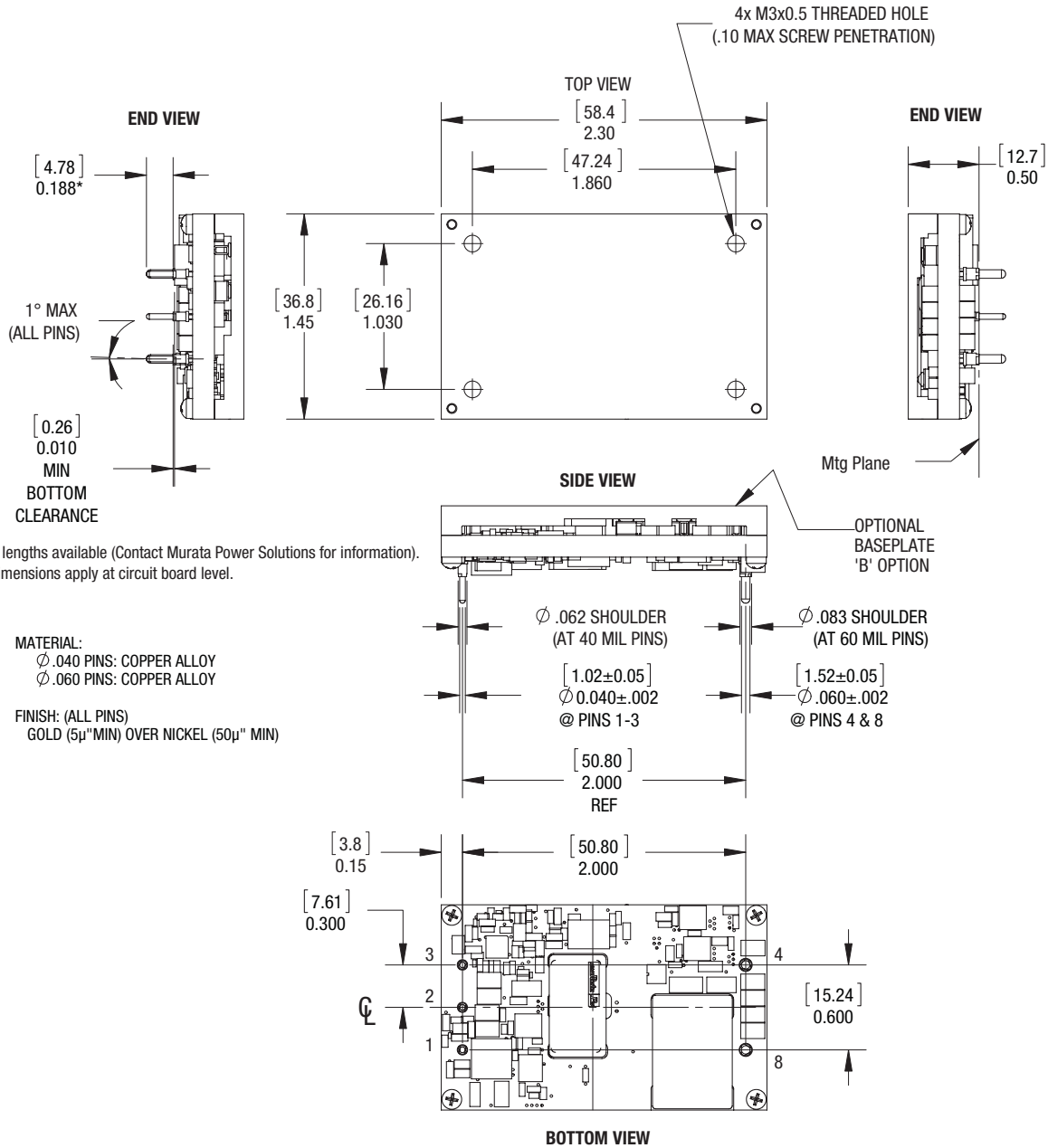
Dimensions are in inches (mm) shown for ref. only.



Tolerances (unless otherwise specified):  
 .XX ± 0.02 (0.5)  
 .XXX ± 0.010 (0.25)  
 Angles ± 2°

I/O Connections (pin side view)			
Pin	Function	Pin	Function
1	+Vin	4	-Vout
2	Remote On/Off Control		
3	-Vin	8	+Vout

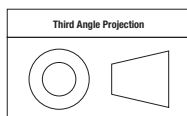
**MECHANICAL SPECIFICATIONS (BASEPLATE)—STANDARD AND T48xS MODELS**



\*Alternate pin lengths available (Contact Murata Power Solutions for information).  
Pin location dimensions apply at circuit board level.

**MATERIAL:**  
 $\phi .040$  PINS: COPPER ALLOY  
 $\phi .060$  PINS: COPPER ALLOY  
**FINISH: (ALL PINS)**  
 GOLD ( $5\mu$ " MIN) OVER NICKEL ( $50\mu$ " MIN)

Dimensions are in inches (mm) shown for ref. only.



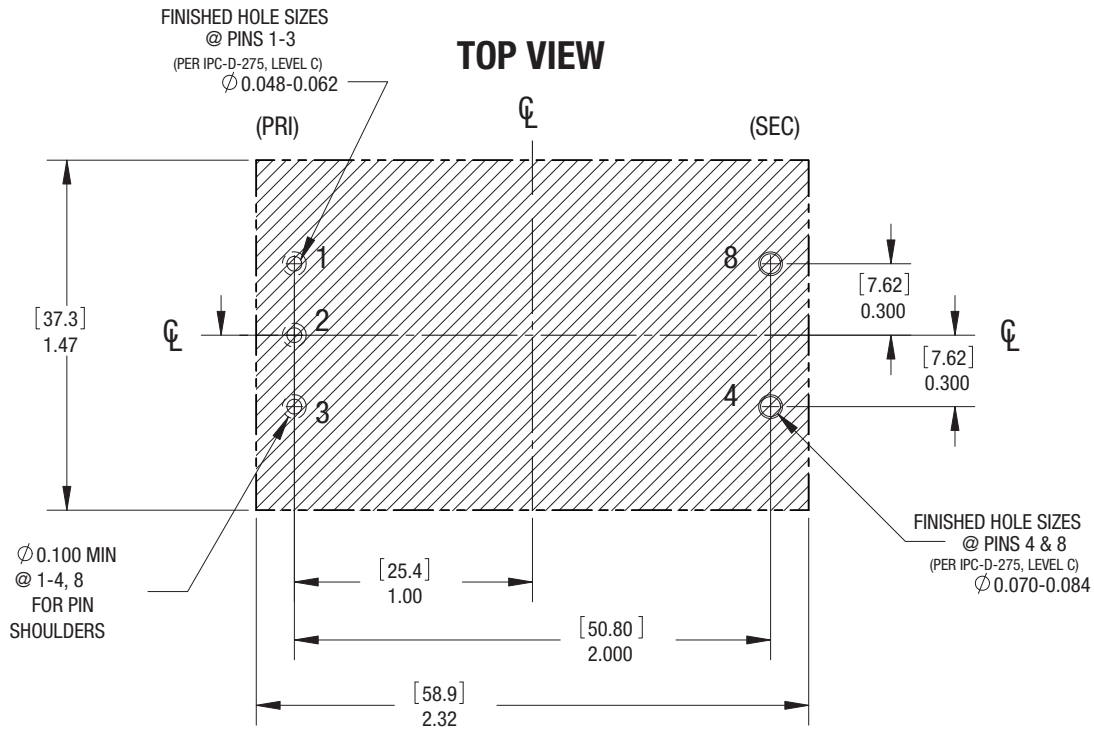
Tolerances (unless otherwise specified):  
 .XX  $\pm 0.02$  (0.5)  
 .XXX  $\pm 0.010$  (0.25)  
 Angles  $\pm 2^\circ$

I/O Connections (pin side view)			
Pin	Function	Pin	Function
1	+Vin	4	-Vout
2	Remote On/Off Control		
3	-Vin	8	+Vout

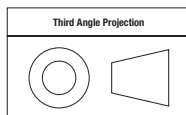
**RECOMMENDED FOOTPRINT—STANDARD AND T48xS MODELS**

**Recommended Footprint  
(view through converter)**

REF: DOSA Standard Specification  
for Quarter-Brick DC/DC Converters



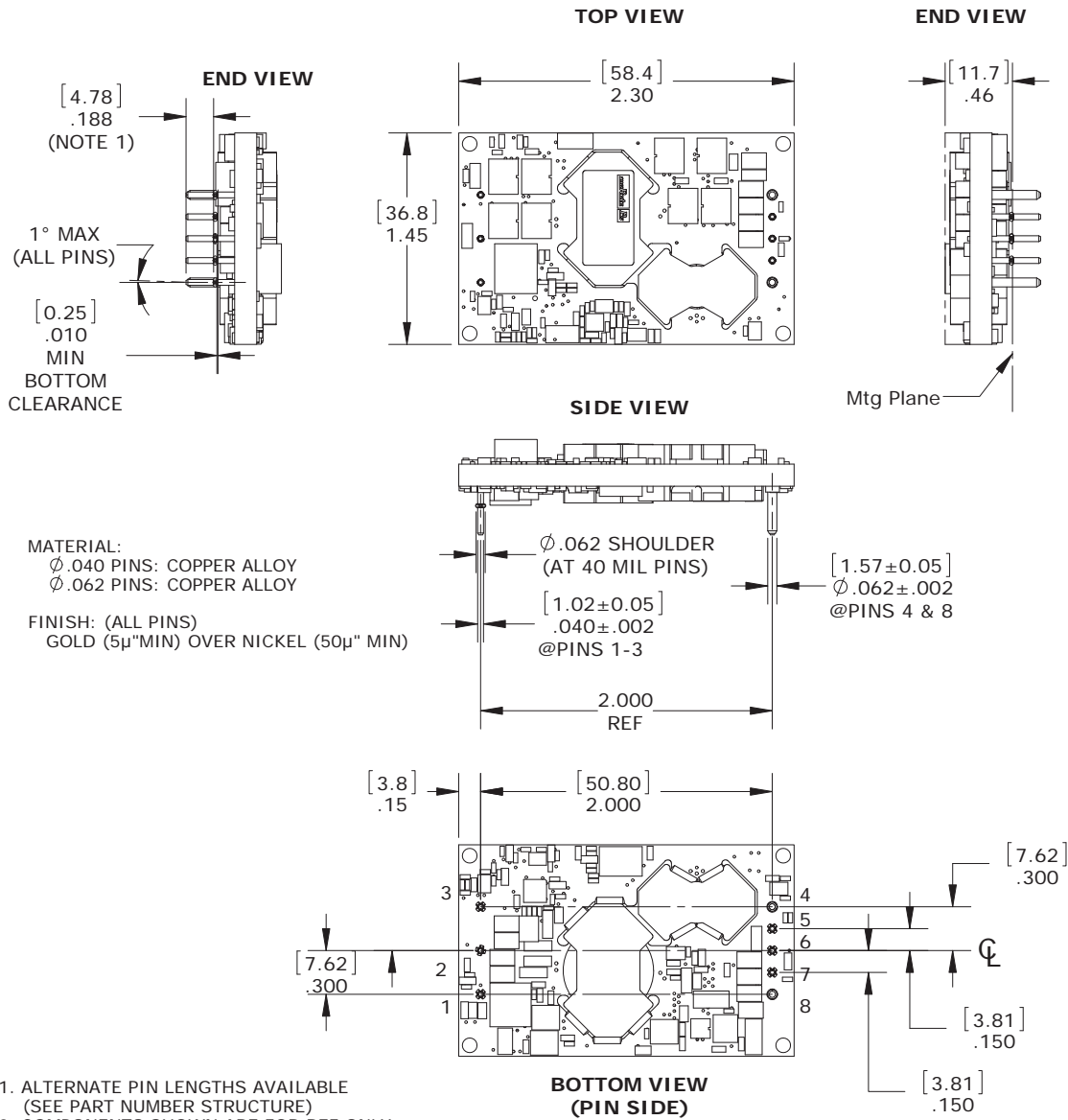
Dimensions are in inches (mm) shown for ref. only.



Tolerances (unless otherwise specified):  
.XX ± 0.02 (0.5)  
.XXX ± 0.010 (0.25)  
Angles ± 2°

I/O Connections (pin side view)			
Pin	Function	Pin	Function
1	+Vin	4	-Vout
2	Remote On/Off Control		
3	-Vin	8	+Vout

**MECHANICAL SPECIFICATIONS (OPEN FRAME)—T48xT MODELS**



**MATERIAL:**  
 Ø .040 PINS: COPPER ALLOY  
 Ø .062 PINS: COPPER ALLOY

**FINISH: (ALL PINS)**  
 GOLD (5µ"MIN) OVER NICKEL (50µ" MIN)

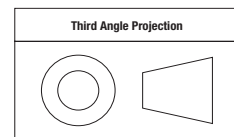
1. ALTERNATE PIN LENGTHS AVAILABLE (SEE PART NUMBER STRUCTURE)
2. COMPONENTS SHOWN ARE FOR REF ONLY
3. DIMENSIONS ARE IN INCHES [mm]
4. PIN LOCATION DIMENSIONS APPLY AT CIRCUIT BOARD LEVEL
5. THESE CONVERTERS MEET THE MECHANICAL SPECIFICATIONS OF A QUARTER BRICK DC-DC CONVERTER

**INPUT/OUTPUT CONNECTIONS**

Pin	Function
1	+Vin
2	Remote On/Off *
3	-Vin
4	-Vout
5	-Sense
6	Trim
7	+Sense
8	+Vout

\*The Remote On/Off can be provided with either positive (P suffix) or negative (N suffix) logic.

Dimensions are in inches (mm shown for ref. only).

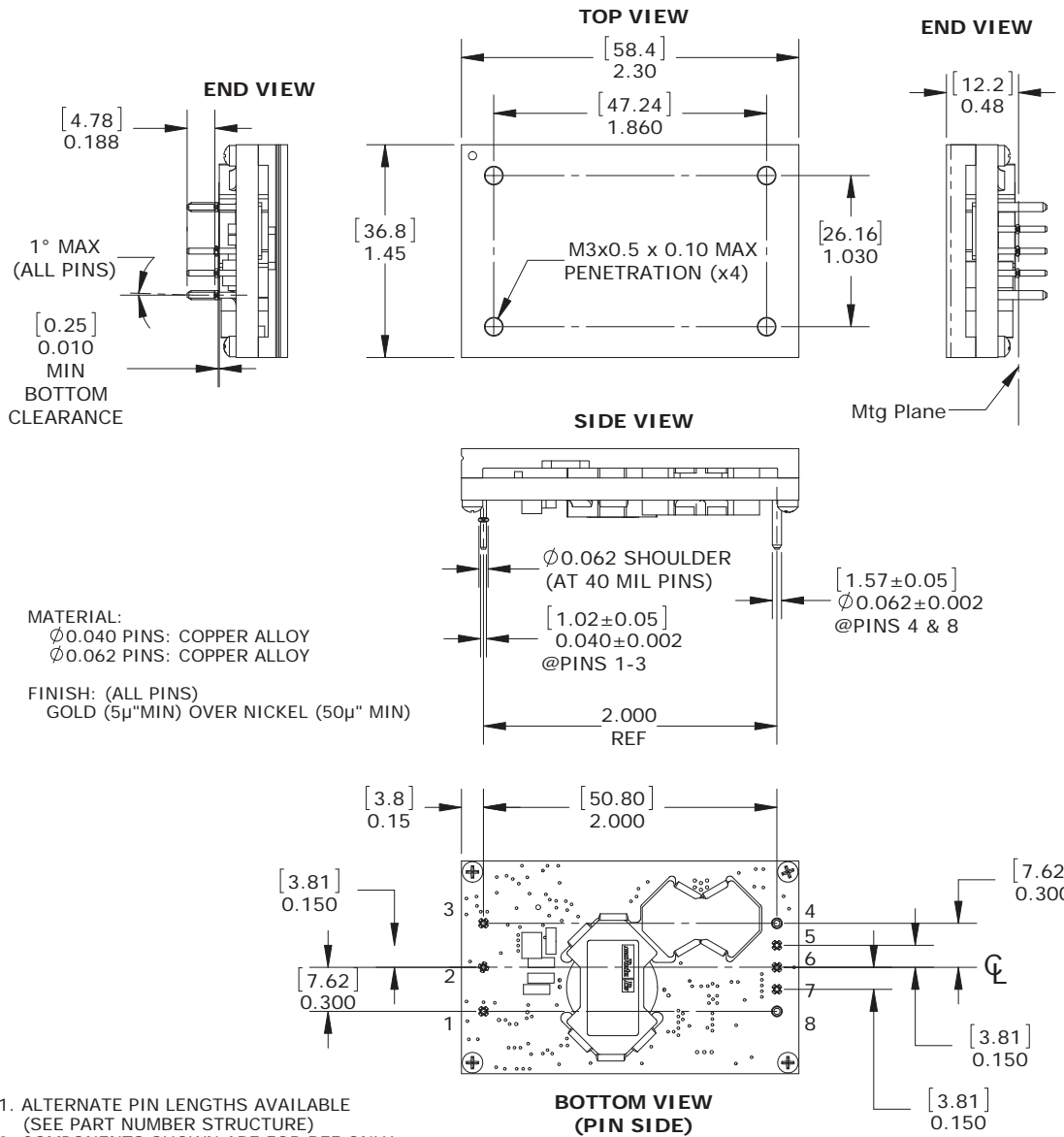


Tolerances (unless otherwise specified):  
 .XX ± 0.02 (0.5)  
 .XXX ± 0.010 (0.25)  
 Angles ± 2°

Components are shown for reference only and may vary between units.



**MECHANICAL SPECIFICATIONS (BASEPLATE)—T48xT MODELS**



**MATERIAL:**  
 Ø0.040 PINS: COPPER ALLOY  
 Ø0.062 PINS: COPPER ALLOY

**FINISH: (ALL PINS)**  
 GOLD (5µ"MIN) OVER NICKEL (50µ" MIN)

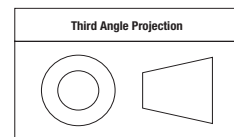
1. ALTERNATE PIN LENGTHS AVAILABLE (SEE PART NUMBER STRUCTURE)
2. COMPONENTS SHOWN ARE FOR REF ONLY
3. DIMENSIONS ARE IN INCHES [mm]
4. PIN LOCATION DIMENSIONS APPLY AT CIRCUIT BOARD LEVEL
5. THESE CONVERTERS MEET THE MECHANICAL SPECIFICATIONS OF A QUARTER BRICK DC-DC CONVERTER

**INPUT/OUTPUT CONNECTIONS**

Pin	Function
1	+Vin
2	Remote On/Off *
3	-Vin
4	-Vout
5	-Sense
6	Trim
7	+Sense
8	+Vout

\*The Remote On/Off can be provided with either positive (P suffix) or negative (N suffix) logic.

Dimensions are in inches (mm shown for ref. only).

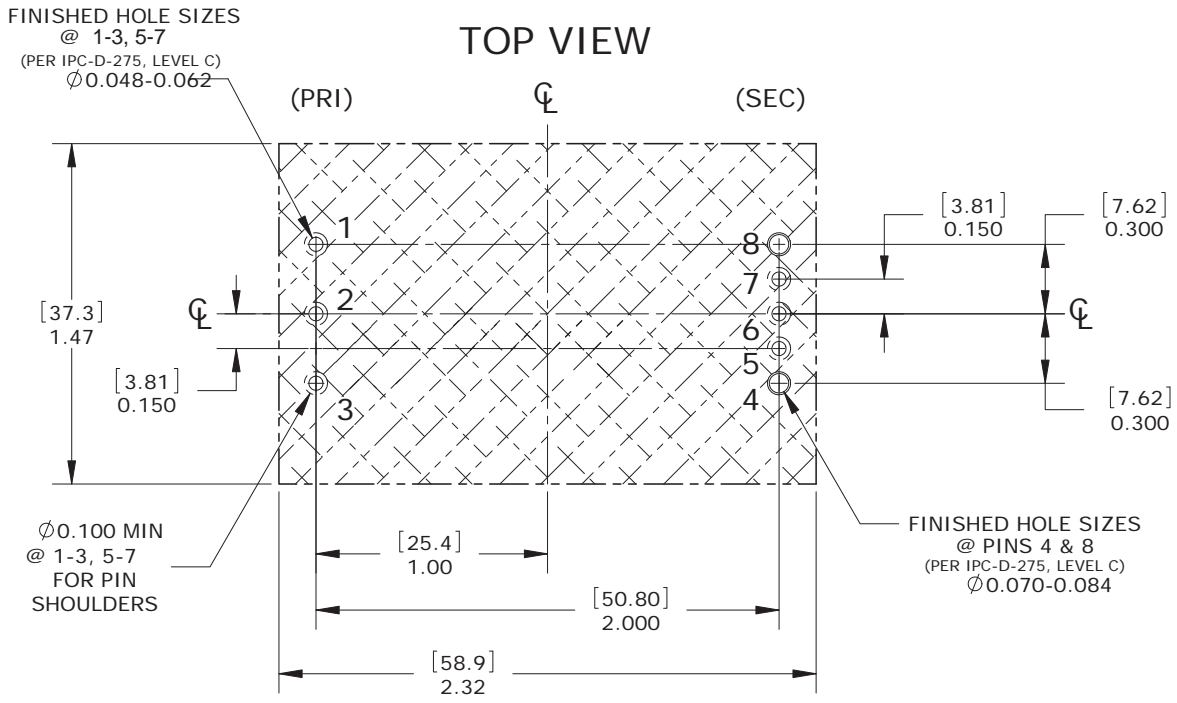


Tolerances (unless otherwise specified):  
 .XX ± 0.02 (0.5)  
 .XXX ± 0.010 (0.25)  
 Angles ± 2°

Components are shown for reference only and may vary between units.

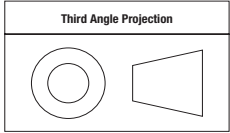
**RECOMMENDED FOOTPRINT—T48xT MODELS**

**RECOMMENDED FOOTPRINT  
(VIEW THROUGH CONVERTER)**  
REF: DOSA STANDARD SPECIFICATION  
FOR QUARTER BRICK DC/DC CONVERTERS



IT IS RECOMMENDED THAT NO PARTS  
BE PLACED BENEATH CONVERTER  
(HATCHED AREA)

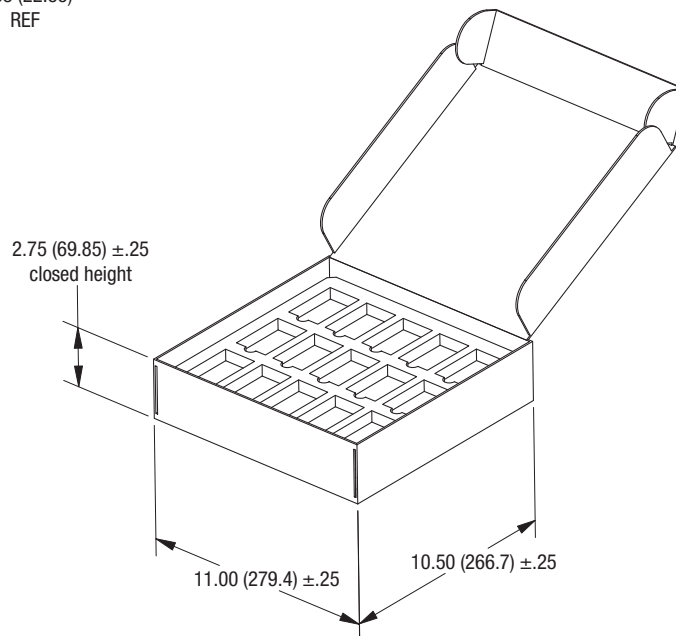
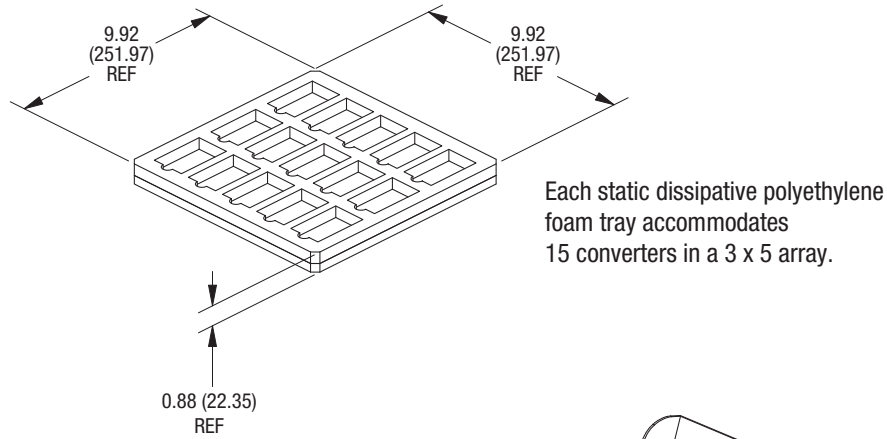
Dimensions are in inches (mm shown for ref. only).



Tolerances (unless otherwise specified):  
.XX  $\pm 0.02$  (0.5)  
.XXX  $\pm 0.010$  (0.25)  
Angles  $\pm 2^\circ$

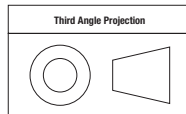
Components are shown for reference only  
and may vary between units.

**STANDARD PACKAGING**



Carton accommodates two (2) trays yielding 30 converters per carton

Dimensions are in inches (mm) shown for ref. only.



Tolerances (unless otherwise specified):  
 .XX ± 0.02 (0.5)  
 .XXX ± 0.010 (0.25)  
 Angles ± 2'

**TECHNICAL NOTES**

### Input Fusing

Certain applications and/or safety agencies may require fuses at the inputs of power conversion components. Fuses should also be used when there is the possibility of sustained input voltage reversal which is not current-limited. For greatest safety, we recommend a fast blow fuse installed in the ungrounded input supply line.

The installer must observe all relevant safety standards and regulations. For safety agency approvals, install the converter in compliance with the end-user safety standard.

### Parallel Load Sharing (S Option, Load Sharing)

Two or more converters may be connected in parallel at both the input and output terminals to support higher output current (total power, see figure 2) or to improve reliability due to the reduced stress that results when the modules are operating below their rated limits. For applications requiring current share, follow the guidelines below. The output voltage will decrease when the load current is increased. Our goal is to have each converter contribute nearly identical current into the output load under all input, environmental and load conditions.

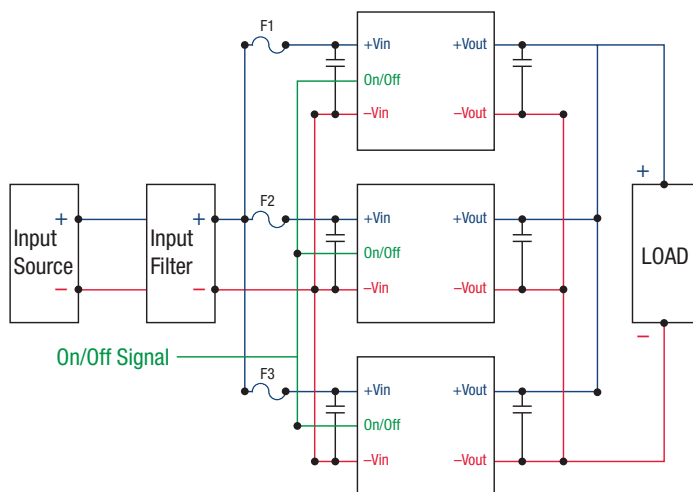


Figure 2. Load Sharing Block Diagram

### Using Parallel Connections – Load Sharing (Power Boost)

- All converters must be powered up and powered down simultaneously. Use a common input power source.
- It is required to use a common Remote On/Off logic control signal to turn on modules (see figure 2).
- When Vin has reached steady state, apply control signal to the all modules. Figure 3 illustrates the turn on process for positive logic modules.
- First power up the parallel system (all converters) with a load not exceeding the rated load of each converter and allow converters to settle (typically 20-100mS) before applying full load. As a practical matter, if the loads are downstream PoL converters, power these up shortly after the converter has reached steady state output. Also be aware of the delay caused by charging up external bypass capacitors.
- It is critical that the PCB layout incorporates identical connections from each module to the load; use the same trace rating and airflow/thermal environments. If you add input filter components, use identical components and layout.
- When converters are connected in parallel, allow for a safety factor of at least 10%. Up to 90% of max output current can be used from each module.

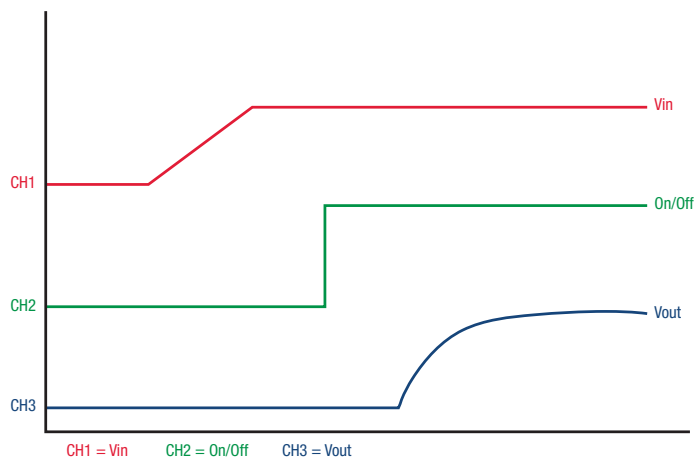


Figure 3. Typical Turn On for Positive Logic Modules

**CAUTION:** This converter is not internally fused. To avoid danger to persons or equipment and to retain safety certification, the user must connect an external fast-blow input fuse as listed in the specifications. Be sure that the PC board pad area and etch size are adequate to provide enough current so that the fuse will blow with an overload.

### Using Parallel Connections – Redundancy (N+1)

The redundancy connections in figure 4 requires external user supplied “OR”ing diodes or “OR”ing MOSFETs for reliability purposes. The diodes allow for an uninterruptable power system operation in case of a catastrophic failure (shorted output) by one of the converters.

The diodes should be identical part numbers to enhance balance between the converters. The default factory nominal voltage should be sufficiently matched between converters. The OR’ing diode system is the responsibility of the user. Be aware of the power levels applied to the diodes and possible heat sink requirements.

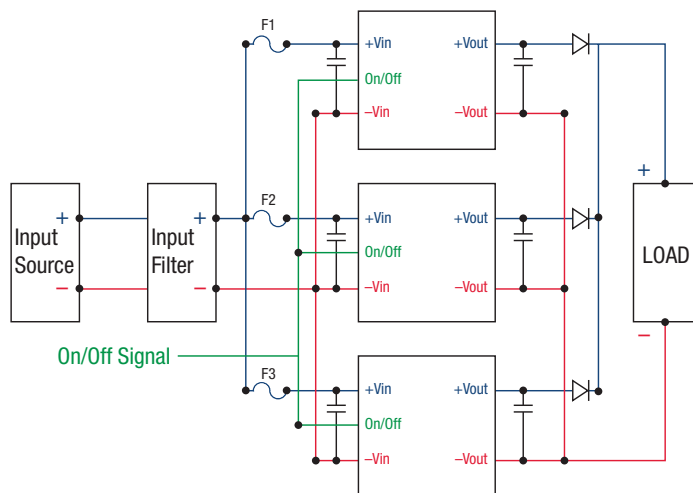


Figure 4. Redundant Parallel Connections

Schottky power diodes with approximately 0.3V drops or “OR”ing MOSFETs may be suitable in the loop whereas 0.7 V silicon power diodes may not be advisable. In the event of an internal device fault or failure of the mains power modules on the primary side, the other devices automatically take over the entire supply of the loads. In the basic N+1 power system, the “N” equals the number of modules required to fully power the system and “+1” equals one back-up module that will take over for a failed module. If the system consists of two power modules, each providing 50% of the total load power under normal operation and one module fails, another one delivers full power to the load. This means you can use smaller and less expensive power converters as the redundant elements, while achieving the goal of increased availability.

**Input Under-Voltage Shutdown and Start-Up Threshold**

Under normal start-up conditions, converters will not begin to regulate properly until the rising input voltage exceeds and remains at the Start-Up Threshold Voltage (see Specifications). Once operating, converters will not turn off until the input voltage drops below the Under-Voltage Shutdown Limit. Subsequent restart will not occur until the input voltage rises again above the Start-Up Threshold. This built-in hysteresis prevents any unstable on/off operation at a single input voltage.

Users should be aware however of input sources near the Under-Voltage Shutdown whose voltage decays as input current is consumed (such as capacitor inputs), the converter shuts off and then restarts as the external capacitor recharges. Such situations could oscillate. To prevent this, make sure the operating input voltage is well above the UV Shutdown voltage AT ALL TIMES.

**Start-Up Delay**

Assuming that the output current is set at the rated maximum, the Vin to Vout Start-Up Delay (see Specifications) is the time interval between the point when the rising input voltage crosses the Start-Up Threshold and the fully loaded regulated output voltage enters and remains within its specified regulation band. Actual measured times will vary with input source impedance, external input capacitance, input voltage slew rate and final value of the input voltage as it appears at the converter.

These converters include a soft start circuit to moderate the duty cycle of the PWM controller at power up, thereby limiting the input inrush current.

The On/Off Remote Control interval from inception to Vout regulated assumes that the converter already has its input voltage stabilized above the Start-Up Threshold before the On command. The interval is measured from the On command until the output enters and remains within its specified regulation band. The specification assumes that the output is fully loaded at maximum rated current.

**Input Source Impedance**

These converters will operate to specifications without external components, assuming that the source voltage has very low impedance and reasonable input voltage regulation. Since real-world voltage sources have finite impedance, performance is improved by adding external filter components. Sometimes only a small ceramic capacitor is sufficient. Since it is difficult to totally characterize all applications, some experimentation may be needed. Note that external input capacitors must accept high speed switching currents.

Because of the switching nature of DC-DC converters, the input of these converters must be driven from a source with both low AC impedance and adequate DC input regulation. Performance will degrade with increasing input

inductance. Excessive input inductance may inhibit operation. The DC input regulation specifies that the input voltage, once operating, must never degrade below the Shut-Down Threshold under all load conditions. Be sure to use adequate trace sizes and mount components close to the converter.

**I/O Filtering, Input Ripple Current and Output Noise**

All models in this converter series are tested and specified for input reflected ripple current and output noise using designated external input/output components, circuits and layout as shown in the figures below. External input capacitors (CIN in the figure) serve primarily as energy storage elements, minimizing line voltage variations caused by transient IR drops in the input conductors. Users should select input capacitors for bulk capacitance (at appropriate frequencies), low ESR and high RMS ripple current ratings. In the figure below, the CBUS and LBUS components simulate a typical DC voltage bus. Your specific system configuration may require additional considerations. Please note that the values of CIN, LBUS and CBUS may vary according to the specific converter model.

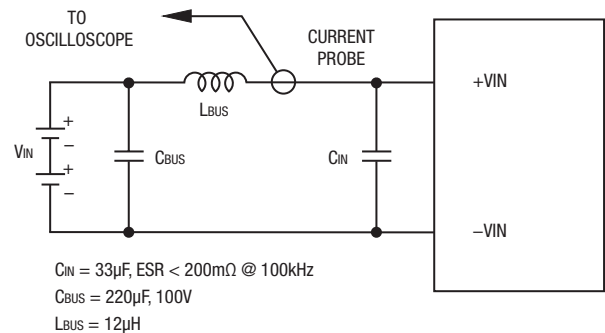


Figure 5. Measuring Input Ripple Current

In critical applications, output ripple and noise (also referred to as periodic and random deviations or PARD) may be reduced by adding filter elements such as multiple external capacitors. Be sure to calculate component temperature rise from reflected AC current dissipated inside capacitor ESR.

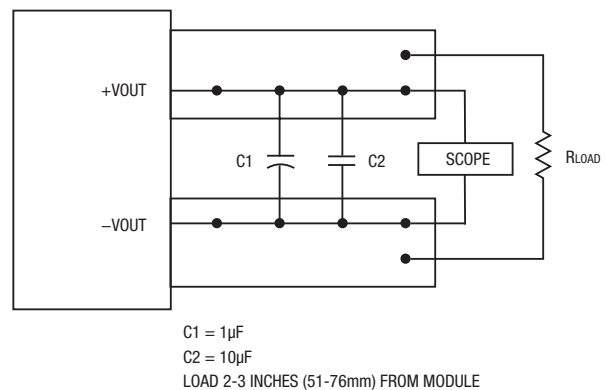


Figure 6. Measuring Output Ripple and Noise (PARD)

### Floating Outputs

Since these are isolated DC-DC converters, their outputs are “floating” with respect to their input. The essential feature of such isolation is ideal ZERO CURRENT FLOW between input and output. Real-world converters however do exhibit tiny leakage currents between input and output (see Specifications). These leakages consist of both an AC stray capacitance coupling component and a DC leakage resistance. When using the isolation feature, do not allow the isolation voltage to exceed specifications. Otherwise the converter may be damaged. Designers will normally use the negative output (-Output) as the ground return of the load circuit. You can however use the positive output (+Output) as the ground return to effectively reverse the output polarity.

### Minimum Output Loading Requirements

These converters employ a synchronous rectifier design topology. All models regulate within specification and are stable under no load to full load conditions. Operation under no load might however slightly increase output ripple and noise.

### Thermal Shutdown

To protect against thermal over-stress, these converters include thermal shutdown circuitry. If environmental conditions cause the temperature of the DC-DC's to rise above the Operating Temperature Range up to the shutdown temperature, an on-board electronic temperature sensor will power down the unit. When the temperature decreases below the turn-on threshold, the converter will automatically restart. There is a small amount of hysteresis to prevent rapid on/off cycling. CAUTION: If you operate too close to the thermal limits, the converter may shut down suddenly without warning. Be sure to thoroughly test your application to avoid unplanned thermal shutdown.

### Temperature Derating Curves

The graphs in this data sheet illustrate typical operation under a variety of conditions. The Derating curves show the maximum continuous ambient air temperature and decreasing maximum output current which is acceptable under increasing forced airflow measured in Linear Feet per Minute (“LFM”). Note that these are AVERAGE measurements. The converter will accept brief increases in temperature and/or current or reduced airflow as long as the average is not exceeded.

Note that the temperatures are of the ambient airflow, not the converter itself which is obviously running at higher temperature than the outside air. Also note that “natural convection” is defined as very low flow rates which are not using fan-forced airflow. Depending on the application, “natural convection” is usually about 30-65 LFM but is not equal to still air (0 LFM).

Murata Power Solutions makes Characterization measurements in a closed cycle wind tunnel with calibrated airflow. We use both thermocouples and an infrared camera system to observe thermal performance. As a practical matter, it is quite difficult to insert an anemometer to precisely measure airflow in most applications. Sometimes it is possible to estimate the effective airflow if you thoroughly understand the enclosure geometry, entry/exit orifice areas and the fan flowrate specifications.

CAUTION: If you exceed these Derating guidelines, the converter may have an unplanned Over Temperature shut down. Also, these graphs are all collected near Sea Level altitude. Be sure to reduce the derating for higher altitude.

### Output Overvoltage Protection (OVP)

This converter monitors its output voltage for an over-voltage condition using an on-board electronic comparator. The signal is optically coupled to the primary side PWM controller. If the output exceeds OVP limits, the sensing circuit

will power down the unit, and the output voltage will decrease. After a time-out period, the PWM will automatically attempt to restart, causing the output voltage to ramp up to its rated value. It is not necessary to power down and reset the converter for this automatic OVP-recovery restart.

If the fault condition persists and the output voltage climbs to excessive levels, the OVP circuitry will initiate another shutdown cycle. This on/off cycling is referred to as “hiccup” mode.

### Output Fusing

The converter is extensively protected against current, voltage and temperature extremes. However, your application circuit may need additional protection. In the extremely unlikely event of output circuit failure, excessive voltage could be applied to your circuit. Consider using an appropriate external protection.

### Current Limiting (Power limit with current mode control)

As power demand increases on the output and enters the specified “limit inception range” (current in voltage mode and power in current mode) limiting circuitry activates in the DC-DC converter to limit/restrict the maximum current or total power available. In voltage mode, current limit can have a “constant or foldback” characteristic. In current mode, once the current reaches a certain range the output voltage will start to decrease while the output current continues to increase, thereby maintaining constant power, until a maximum peak current is reached and the converter enters a “hiccup” (on off cycling) mode of operation until the load is reduced below the threshold level, whereupon it will return to a normal mode of operation. Current limit inception is defined as the point where the output voltage has decreased by a pre-specified percentage (usually a 2% decrease from nominal).

### Short Circuit Condition (Current mode control)

The short circuit condition is an extension of the “Current Limiting” condition. When the monitored peak current signal reaches a certain range, the PWM controller's outputs are shut off thereby turning the converter “off.” This is followed by an extended time out period. This period can vary depending on other conditions such as the input voltage level. Following this time out period, the PWM controller will attempt to re-start the converter by initiating a “normal start cycle” which includes softstart. If the “fault condition” persists, another “hiccup” cycle is initiated. This “cycle” can and will continue indefinitely until such time as the “fault condition” is removed, at which time the converter will resume “normal operation.” Operating in the “hiccup” mode during a fault condition is advantageous in that average input and output power levels are held low preventing excessive internal increases in temperature.

### Remote On/Off Control

On the input side, a remote On/Off Control can be specified with either positive or negative logic as follows:

**Positive:** Models equipped with positive logic are enabled when the On/Off pin is left open or is pulled high to +13.5V<sub>DC</sub> with respect to -V<sub>IN</sub>. An internal bias current causes the open pin to rise to +V<sub>IN</sub>. Positive-logic devices are disabled when the On/Off is grounded or brought to within a low voltage (see Specifications) with respect to -V<sub>IN</sub>.

**Negative:** Models with negative logic are on (enabled) when the On/Off is grounded or brought to within a low voltage (see Specifications) with respect to -V<sub>IN</sub>. The device is off (disabled) when the On/Off is left open or is pulled high to +13.5V<sub>DC</sub> Max. with respect to -V<sub>IN</sub>.



Dynamic control of the On/Off function should be able to sink the specified signal current when brought low and withstand specified voltage when brought high. Be aware too that there is a finite time in milliseconds (see Specifications) between the time of On/Off Control activation and stable, regulated output. This time will vary slightly with output load type and current and input conditions.

There are two CAUTIONs for the On/Off Control:

**CAUTION:** While it is possible to control the On/Off with external logic if you carefully observe the voltage levels, the preferred circuit is either an open drain/open collector transistor or a relay (which can thereupon be controlled by logic). The On/Off prefers to be set at approx. +13.5V (open pin) for the ON state, assuming positive logic.

**CAUTION:** Do not apply voltages to the On/Off pin when there is no input power voltage. Otherwise the converter may be permanently damaged.

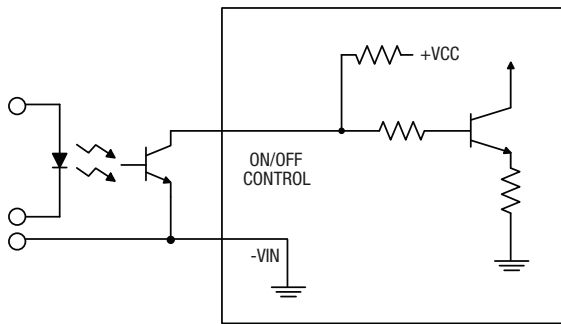


Figure 7. Driving the On/Off Control Pin (suggested circuit)

### Emissions Performance

Murata Power Solutions measures its products for radio frequency emissions against the EN 55022 and CISPR 22 standards. Passive resistance loads are employed and the output is set to the maximum voltage. If you set up your own emissions testing, make sure the output load is rated at continuous power while doing the tests.

The recommended external input and output capacitors (if required) are included. Please refer to the fundamental switching frequency. All of this information is listed in the Product Specifications. An external discrete filter is installed and the circuit diagram is shown below.

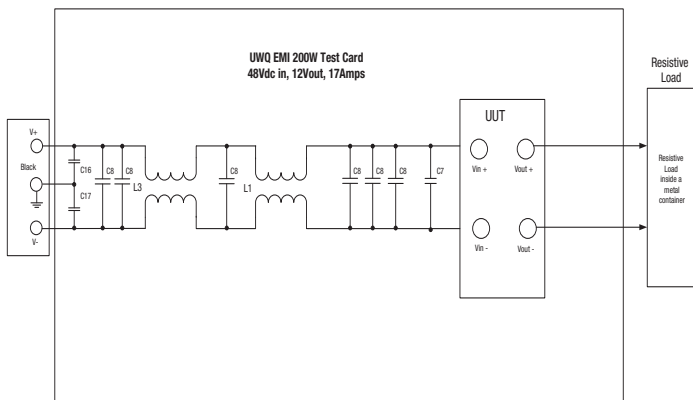


Figure 8. Conducted Emissions Test Circuit

### [1] Conducted Emissions Parts List

Reference	Part Number	Description	Vendor
L1	PE-62913	1mH, 6A	Pulse
L3	500uH, 10A, MPS	500uH, 10A	Murata
C8		2.2µFd	Murata
C7	VZ Series	Qty 2 - Electrolytic Capacitor 22µFd, 100V	Panasonic
C16, C17		.22µFd	Unknown

### [2] Conducted Emissions Test Equipment Used

Rohde & Schwarz EMI Test Receiver (9KHz – 1000MHz) ESPC

Rohde & Schwarz Software ESPC-1 Ver. 2.20

HP11947A Transient Limiter (Agilent)

OHMITE 25W – Resistor combinations

DC Source Programmable DC Power Supply Model 62012P-100-50

### [3] Layout Recommendations

Most applications can use the filtering which is already installed inside the converter or with the addition of the recommended external capacitors. For greater emissions suppression, consider additional filter components and/or shielding. Emissions performance will depend on the user's PC board layout, the chassis shielding environment and choice of external components. Please refer to Application Note GEAN02 for further discussion.

Since many factors affect both the amplitude and spectra of emissions, we recommend using an engineer who is experienced at emissions suppression.

### Trimming Output Voltage

UWQ converters have a trim capability (pin 6) that enables users to adjust the output voltage from +10% to -10% (refer to the trim equations in the table below). Adjustments to the output voltage can be accomplished with a single fixed resistor as shown in Figures 9 and 10. A single fixed resistor can increase or decrease the output voltage depending on its connection. Resistors should be located close to the converter and have TCR's less than 100ppm/°C to minimize sensitivity to changes in temperature. If the trim function is not used, leave the trim pin open.

Standard UWQs have a "positive trim" where a single resistor connected from the Trim pin (pin 6) to the +Sense (pin 7) will increase the output voltage. A resistor connected from the Trim Pin (pin 6) to the -Sense (pin 5) will decrease the output voltage.

Trim adjustments greater than the specified +10%/-10% can have an adverse affect on the converter's performance and are not recommended. Excessive voltage differences between V<sub>OUT</sub> and Sense, in conjunction with trim adjustment of the output voltage, can cause the overvoltage protection circuitry to activate (see Performance Specifications for overvoltage limits).

Temperature/power derating is based on maximum output current and voltage at the converter's output pins. Use of the trim and sense functions can cause output voltages to increase, thereby increasing output power beyond the UWQ's specified rating, or cause output voltages to climb into the output overvoltage region. Therefore:

$$(V_{out \text{ at pins}}) \times (I_{out}) \leq \text{rated output power}$$

The Trim pin (pin 6) is a relatively high impedance node that can be susceptible to noise pickup when connected to long conductors in noisy environments.

Trim Up*	Trim Down*
$R_{TUP} (k\Omega) = \frac{49.6(V_o - 1.226)}{V_o - 12} - 10.2$	$R_{TDOWN} (k\Omega) = \frac{60.45}{12 - V_o} - 10.2$

\*Vo = Desirable output voltage in Volts

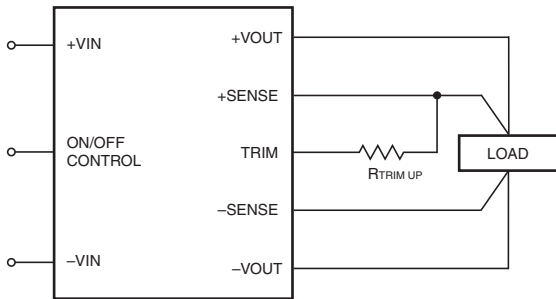


Figure 9. Trim Connections To Increase Output Voltages Using Fixed Resistors

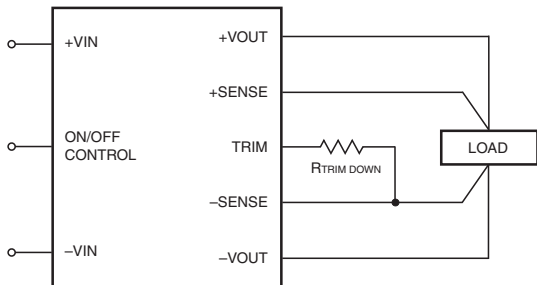


Figure 10. Trim Connections To Decrease Output Voltages Using Fixed Resistors

**Remote Sense Input**

Use the Sense inputs with caution. Sense is normally connected **at the load**. Sense inputs compensate for output voltage inaccuracy delivered at the load. This is done by correcting IR voltage drops along the output wiring and the current carrying capacity of PC board etc. This output drop (the difference between Sense and Vout when measured at the converter) should not exceed 0.5V. Consider using heavier wire if this drop is excessive. Sense inputs also improve the stability of the converter and load system by optimizing the control loop phase margin.

Note: The Sense input and power Vout lines are internally connected through low value resistors to their respective polarities so that the converter can operate without external connection to the Sense. Nevertheless, if the Sense function is not used for remote regulation, the user should connect +Sense to +Vout and -Sense to -Vout at the converter pins.

The remote Sense lines carry very little current. They are also capacitively coupled to the output lines and therefore are in the feedback control loop to regulate and stabilize the output. As such, they are not low impedance inputs and must be treated with care in PC board layouts. Sense lines on the PCB should run adjacent to DC signals, preferably Ground. In cables and discrete wiring, use twisted pair, shielded tubing or similar techniques.

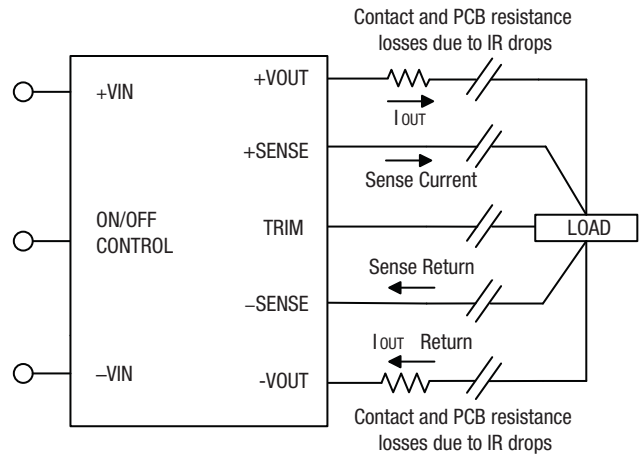


Figure 11. Remote Sense Circuit Configuration

Any long, distributed wiring and/or significant inductance introduced into the Sense control loop can adversely affect overall system stability. If in doubt, test your applications by observing the converter's output transient response during step loads. There should not be any appreciable ringing or oscillation. You may also adjust the output trim slightly to compensate for voltage loss in any external filter elements. Do not exceed maximum power ratings.

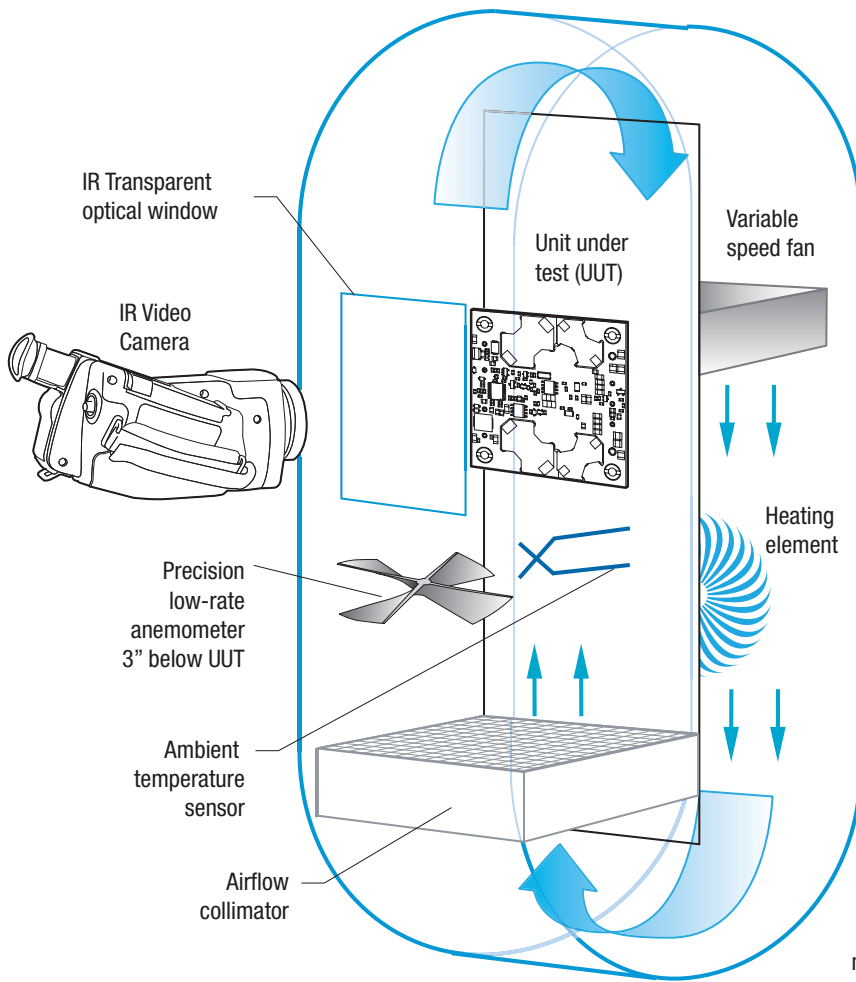


Figure 12. Vertical Wind Tunnel

**Vertical Wind Tunnel**

Murata Power Solutions employs a computer controlled custom-designed closed loop vertical wind tunnel, infrared video camera system, and test instrumentation for accurate airflow and heat dissipation analysis of power products. The system includes a precision low flow-rate anemometer, variable speed fan, power supply input and load controls, temperature gauges, and adjustable heating element.

The IR camera monitors the thermal performance of the Unit Under Test (UUT) under static steady-state conditions. A special optical port is used which is transparent to infrared wavelengths.

Both through-hole and surface mount converters are soldered down to a host carrier board for realistic heat absorption and spreading. Both longitudinal and transverse airflow studies are possible by rotation of this carrier board since there are often significant differences in the heat dissipation in the two airflow directions. The combination of adjustable airflow, adjustable ambient heat, and adjustable Input/ Output currents and voltages mean that a very wide range of measurement conditions can be studied.

The collimator reduces the amount of turbulence adjacent to the UUT by minimizing airflow turbulence. Such turbulence influences the effective heat transfer characteristics and gives false readings. Excess turbulence removes more heat from some surfaces and less heat from others, possibly causing uneven overheating.

Both sides of the UUT are studied since there are different thermal gradients on each side. The adjustable heating element and fan, built-in temperature gauges, and no-contact IR camera mean that power supplies are tested in real-world conditions.

**Soldering Guidelines**

Murata Power Solutions recommends the specifications below when installing these converters. These specifications vary depending on the solder type. Exceeding these specifications may cause damage to the product. Your production environment may differ; therefore please thoroughly review these guidelines with your process engineers.

Wave Solder Operations for through-hole mounted products (THMT)			
For Sn/Ag/Cu based solders:		For Sn/Pb based solders:	
Maximum Preheat Temperature	115° C.	Maximum Preheat Temperature	105° C.
Maximum Pot Temperature	270° C.	Maximum Pot Temperature	250° C.
Maximum Solder Dwell Time	7 seconds	Maximum Solder Dwell Time	6 seconds

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ISO 9001 and 14001 REGISTERED



**This product is subject to the following operating requirements and the Life and Safety Critical Application Sales Policy:**  
Refer to: <http://www.murata-ps.com/requirements/>

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