



V962PBC Rev. B2

LOCAL BUS TO PCI BRIDGE

FOR DE-MULTIPLEXED A/D PROCESSORS

- Glueless interface between Intel i960 Cx/Hx processors and PCI bus
- Fully compliant with PCI 2.1 specification
- Configurable for primary master, bus master, or target operation
- Up to 1Kbyte burst access support on both local and PCI interface
- 576 bytes of programmable FIFO storage with *DYNAMIC BANDWIDTH ALLOCATION™*
- Two channel DMA controller
- Enhanced support for 8/16-bit local bus devices with programmable region size register
- 16 8-bit bi-directional mailbox registers with doorbell interrupts
- Dual bi-directional address space remapping
- On-the-fly byte order (endian) conversion
- Optional power on serial EEPROM initialization
- I²O ATU and messaging unit including hardware controlled circular queues
- Flexible PCI and local interrupt management
- Support for real-mode DOS "holes"
- Ability to generate both Type 0 and Type 1 configuration cycles
- 33MHz and 40MHz local bus versions available with independent PCI operation up to 33MHz
- Low cost 160-pin EIAJ PQFP package

V962PBC provides the highest performance, most flexible, and most economical method to directly connect i960Cx/Hx processors to the PCI bus. V292PBC is also a suitable candidate for a variety of 32-bit de-multiplexed local bus applications based on intel embedded processors - where a minimal amount of glue logic is required. V962PBC may also be used in systems without a CPU for a generic PCI master/target interface.

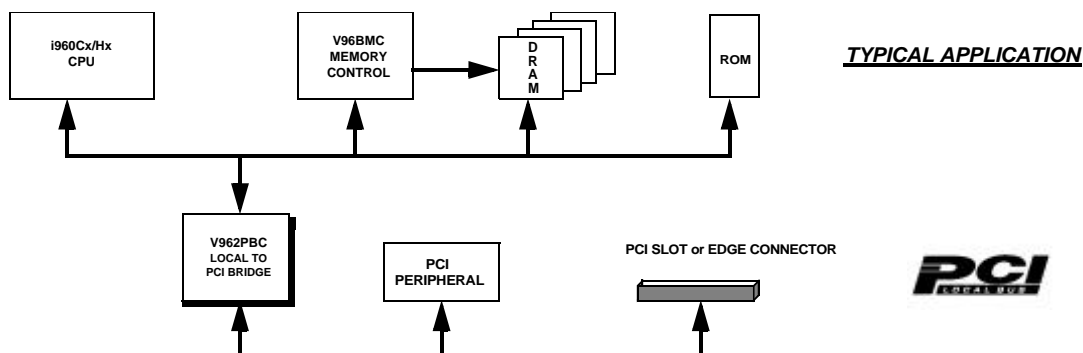
V962PBC Rev B2 is the first I2O ready PCI bridge, fully backward compatible with V962PBC Rev B1. The PCI bus can be run at the full 33MHz frequency, independent of local bus clock rate. The overall throughput of the system is dramatically improved by increasing the FIFO depth and utilizing the unique *DYNAMIC*

BANDWIDTH ALLOCATION™ architecture.

Access to the PCI bus can be performed through two programmable address apertures. Two more apertures are provided for PCI-to-local bus accesses. There are 32-bytes of read FIFO's in each direction, 16-byte dedicated for each aperture. V962PBC also includes bi-directional remapping capabilities, and on-the-fly byte order conversion

Two DMA channels are provided for autonomous PCI-to-Local/Local-to-PCI transfers. Mailbox registers and flexible PCI interrupt controllers are also included to provide a simple mechanism to emulate PCI device control ports.

The part is available in 160-pin low cost EIAJ Plastic Quad Flat Pack (PQFP) package.



V962PBC

This document contains the product codes, pinouts, package mechanical information, DC characteristics, and AC characteristics for the V962PBC. Detailed functional information is contained in the User's Manual.

V3 Semiconductor retains the rights to change documentation, specifications, or device functionality at any time without notice. Please verify that you have the latest copy of all documents before finalizing a design.

1.0 Product Codes

Table 1: Product Codes

| Product Code | Processor | Bus Type | Package | Frequency |
|-------------------|-----------|-----------------------|-------------------|-----------|
| V962PBC-33 REV B2 | i960Cx/Hx | 32-bit de-multiplexed | 160-pin EIAJ PQFP | 33MHz |
| V962PBC-40 REV B2 | i960Cx/Hx | 32-bit de-multiplexed | 160-pin EIAJ PQFP | 40MHz |

2.0 Pin Description and Pinout

Table 2 below lists the pin types found on the V962PBC. Table 3 describes the function of each pin on the V962PBC. Table 5 lists the pins by pin number. Figure 1 shows the pinout for the 160-pin EIAJ PQFP package and Figure 2 shows the mechanical dimensions of the package.

Table 2: Pin Types

| Pin Type | Description |
|------------------|---------------------------------------|
| PCI I | PCI input only pin. |
| PCI O | PCI output only pin. |
| PCI I/O | PCI tri-state I/O pin. |
| PCI I/OD | PCI input with open drain output. |
| I/O ₄ | TTL I/O pin with 4mA output drive. |
| I | TTL input only pin. |
| O ₄ | TTL output pin with 4mA output drive. |

Table 3: Signal Descriptions

| PCI Bus Interface | | | |
|-------------------|----------|----------------|--|
| Signal | Type | R ^a | Description |
| AD[31:0] | PCI I/O | Z | Address and data, multiplexed on the same pins. |
| C/BE[3:0] | PCI I/O | Z | Bus Command and Byte Enables, multiplexed on the same pins. |
| PAR | PCI I/O | Z | Parity represents even parity across AD[31:0] and C/BE[3:0]. |
| FRAME | PCI I/O | Z | Cycle Frame indicates the beginning and burst length of an access. |
| IRDY | PCI I/O | Z | Initiator Ready indicates the initiating agent's (bus master's) ability to complete the current data phase of the transaction. |
| TRDY | PCI I/O | Z | Target Ready indicates the target agent's (selected device's) ability to complete the current data phase of the transaction. |
| STOP | PCI I/O | Z | Stop indicates the current target is requesting the master to stop the current transaction (retry or disconnect). |
| DEVSEL | PCI I/O | Z | Device Select, when actively driven by a target, indicates the driving device has decoded its address as the target of the current access. As an input to the initiator, DEVSEL indicates whether any device on the bus has been selected. |
| IDSEL | PCI I | | Initialization Device Select is used as a chip select during configuration read and write transactions. It must be driven high in order to access the chip's internal configuration space. |
| REQ | PCI O | H | Request indicates to the arbiter that this agent requests use of the bus. |
| GNT | PCI I | | Grant indicates to the agent that access to the bus has been granted. |
| PCLK | PCI I | | PCLK provides timing for all transactions on the PCI bus. |
| PRST | PCI I/O | Z/L | Acts as an input when RDIR is high, an output when RDIR is low. As an input it is asserted low to bring all internal PBC operation to a reset state. |
| PERR | PCI I/O | Z | Parity Error is used to report data parity errors during all PCI transactions except a Special Cycle. |
| SERR | PCI I/OD | Z | System Error is used to report address parity errors, data parity errors on the Special Cycle command, or any other system error where the result will be catastrophic. |
| INT[A:D] | PCI I/OD | Z | Level-sensitive interrupt requests may be received or generated. |

Table 3: Signal Descriptions (cont'd)

| Local Bus Interface | | | |
|--------------------------------|------|-----|--|
| Signal | Type | R | Description |
| LD[31:0] | I/O4 | Z | Local multiplexed address and data bus. |
| LA[31:2] | I/O4 | Z | Local address bus. |
| $\overline{\text{BE}}[3:0]$ | I/O4 | Z | Local bus byte enables. |
| $\text{W}/\overline{\text{R}}$ | I/O4 | Z | Write/Read. |
| $\overline{\text{ADS}}$ | I/O4 | Z | Asserted low to indicate the beginning of a bus cycle. |
| $\overline{\text{READY}}$ | I/O4 | Z | Local Bus data ready |
| HOLD | O4 | L | Local bus hold request: asserted by the chip to initiate a local bus master cycle. |
| HOLDA | I | | Local bus hold acknowledge. |
| LPAR[3:0] | I/O4 | Z | Local bus parity. |
| $\overline{\text{BLAST}}$ | I/O4 | Z | Burst request. Burst last. |
| $\overline{\text{BTERM}}$ | I/O4 | Z | Bus Time-out. Burst terminate. |
| $\overline{\text{LINT}}$ | O4 | H | Local interrupt request. |
| $\overline{\text{LRST}}$ | I/O4 | L/Z | Local bus RESET signal. |
| LCLK | I | | Local bus clock. |

| Serial EEPROM Interface | | | |
|--------------------------------------|------|---|-----------------------------------|
| Signal | Type | R | Description |
| $\text{SCL}/\overline{\text{LPERR}}$ | O4 | X | EEPROM clock. Local parity error. |
| SDA | I/O4 | X | EEPROM data. |

| Configuration | | | |
|---------------|------|---|---|
| Signal | Type | R | Description |
| RDIR | I | | Reset direction. Tie low to drive $\overline{\text{PRST}}$ out and $\overline{\text{LRST}}$ in, high to drive LRST out and PRST in. |

Table 3: Signal Descriptions (cont'd)

| Power and Ground Signals | | | |
|--------------------------|------|---|--|
| Signal | Type | R | Description |
| V _{CC} | - | | POWER leads intended for external connection to a V _{CC} board plane. |
| GND | - | | GROUND leads intended for external connection to a GND board plane. |

a. R indicates state during reset.

2.1 Test Mode Pins

Several device pins are used during manufacturing test to put the V962PBC device into various test modes. ***These pins must be maintained at proper levels during reset to insure proper operation.*** This is typically handled through pull-up or pull-down resistors (typically 1K to 10K) on the signal pins if they are not guaranteed to be at the proper level during reset. Table 4 below shows the reset states for test mode pins:

Table 4: RESET State for Test Mode Pins

| PIN# | 134 | 135 | 153 |
|------------|---------|---------|---------|
| Connection | Pull-Up | Pull-Up | Pull-Up |

Table 5: Pin Assignments

| PIN # | Signal | PIN # | Signal | PIN # | Signal | PIN # | Signal |
|-------|--------------------------|-------|-----------------|-------|-----------------|-------|-----------------|
| 1 | V _{CC} | 41 | V _{CC} | 81 | V _{CC} | 121 | V _{CC} |
| 2 | $\overline{\text{INTD}}$ | 42 | AD14 | 82 | LA23 | 122 | LA6 |
| 3 | $\overline{\text{PRST}}$ | 43 | AD13 | 83 | LD8 | 123 | LD25 |
| 4 | PCLK | 44 | AD12 | 84 | LA22 | 124 | LA5 |
| 5 | $\overline{\text{GNT}}$ | 45 | AD11 | 85 | LD9 | 125 | LD26 |
| 6 | $\overline{\text{REQ}}$ | 46 | AD10 | 86 | LA21 | 126 | LA4 |
| 7 | AD31 | 47 | AD9 | 87 | LD10 | 127 | LD27 |
| 8 | AD30 | 48 | AD8 | 88 | LA20 | 128 | LA3 |

Table 5: Pin Assignments (cont'd)

| PIN # | Signal | PIN # | Signal | PIN # | Signal | PIN # | Signal |
|-------|----------------------------|-------|----------------------------|-------|-----------------|-------|---------------------------|
| 9 | AD29 | 49 | C/ $\overline{\text{BE0}}$ | 89 | LD11 | 129 | LD28 |
| 10 | AD28 | 50 | V _{CC} | 90 | LA19 | 130 | LA2 |
| 11 | GND | 51 | GND | 91 | LD12 | 131 | LD29 |
| 12 | AD27 | 52 | AD7 | 92 | LA18 | 132 | LD30 |
| 13 | AD26 | 53 | AD6 | 93 | LD13 | 133 | LD31 |
| 14 | AD25 | 54 | AD5 | 94 | LA17 | 134 | '1' |
| 15 | AD24 | 55 | AD4 | 95 | LD14 | 135 | $\overline{\text{BTERM}}$ |
| 16 | C/ $\overline{\text{BE3}}$ | 56 | AD3 | 96 | LA16 | 136 | $\overline{\text{READY}}$ |
| 17 | IDSEL | 57 | AD2 | 97 | LD15 | 137 | HOLD |
| 18 | AD23 | 58 | AD1 | 98 | LA15 | 138 | HOLDA |
| 19 | AD22 | 59 | AD0 | 99 | LD16 | 139 | $\overline{\text{ADS}}$ |
| 20 | V _{CC} | 60 | V _{CC} | 100 | V _{CC} | 140 | V _{CC} |
| 21 | GND | 61 | GND | 101 | GND | 141 | GND |
| 22 | AD21 | 62 | LD0 | 102 | LA14 | 142 | LCLK |
| 23 | AD20 | 63 | LA31 | 103 | LD17 | 143 | GND |
| 24 | AD19 | 64 | LD1 | 104 | LA13 | 144 | V _{CC} |
| 25 | AD18 | 65 | LA30 | 105 | LD18 | 145 | $\overline{\text{BE3}}$ |
| 26 | AD17 | 66 | LD2 | 106 | LA12 | 146 | $\overline{\text{BE2}}$ |
| 27 | AD16 | 67 | LA29 | 107 | LD19 | 147 | $\overline{\text{BE1}}$ |
| 28 | C/ $\overline{\text{BE2}}$ | 68 | LD3 | 108 | LA11 | 148 | $\overline{\text{BE0}}$ |
| 29 | $\overline{\text{FRAME}}$ | 69 | LA28 | 109 | LD20 | 149 | $\overline{\text{BLAST}}$ |
| 30 | GND | 70 | LD4 | 110 | LA10 | 150 | W/ $\overline{\text{R}}$ |
| 31 | $\overline{\text{IRDY}}$ | 71 | LA27 | 111 | LD21 | 151 | RDIR |
| 32 | $\overline{\text{TRDY}}$ | 72 | LD5 | 112 | LA9 | 152 | $\overline{\text{LRST}}$ |
| 33 | $\overline{\text{DEVSEL}}$ | 73 | LA26 | 113 | LD22 | 153 | '1' |
| 34 | $\overline{\text{STOP}}$ | 74 | LD6 | 114 | LA8 | 154 | $\overline{\text{LINT}}$ |
| 35 | $\overline{\text{PERR}}$ | 75 | LA25 | 115 | LD23 | 155 | SDA |

Table 5: Pin Assignments (cont'd)

| PIN # | Signal | PIN # | Signal | PIN # | Signal | PIN # | Signal |
|-------|----------------------------------|-------|--------|-------|--------|-------|------------------------------------|
| 36 | $\overline{\text{SERR}}$ | 76 | LD7 | 116 | LA7 | 156 | $\frac{\text{SCL/}}{\text{LPERR}}$ |
| 37 | PAR | 77 | LA24 | 117 | LPAR2 | 157 | $\overline{\text{INTA}}$ |
| 38 | $\text{C}/\overline{\text{BE1}}$ | 78 | LPAR0 | 118 | LPAR3 | 158 | $\overline{\text{INTB}}$ |
| 39 | AD15 | 79 | LPAR1 | 119 | LD24 | 159 | $\overline{\text{INTC}}$ |
| 40 | GND | 80 | GND | 120 | GND | 160 | GND |

Figure 1: Pinout for 160-pin EIAJ PQFP (top view)

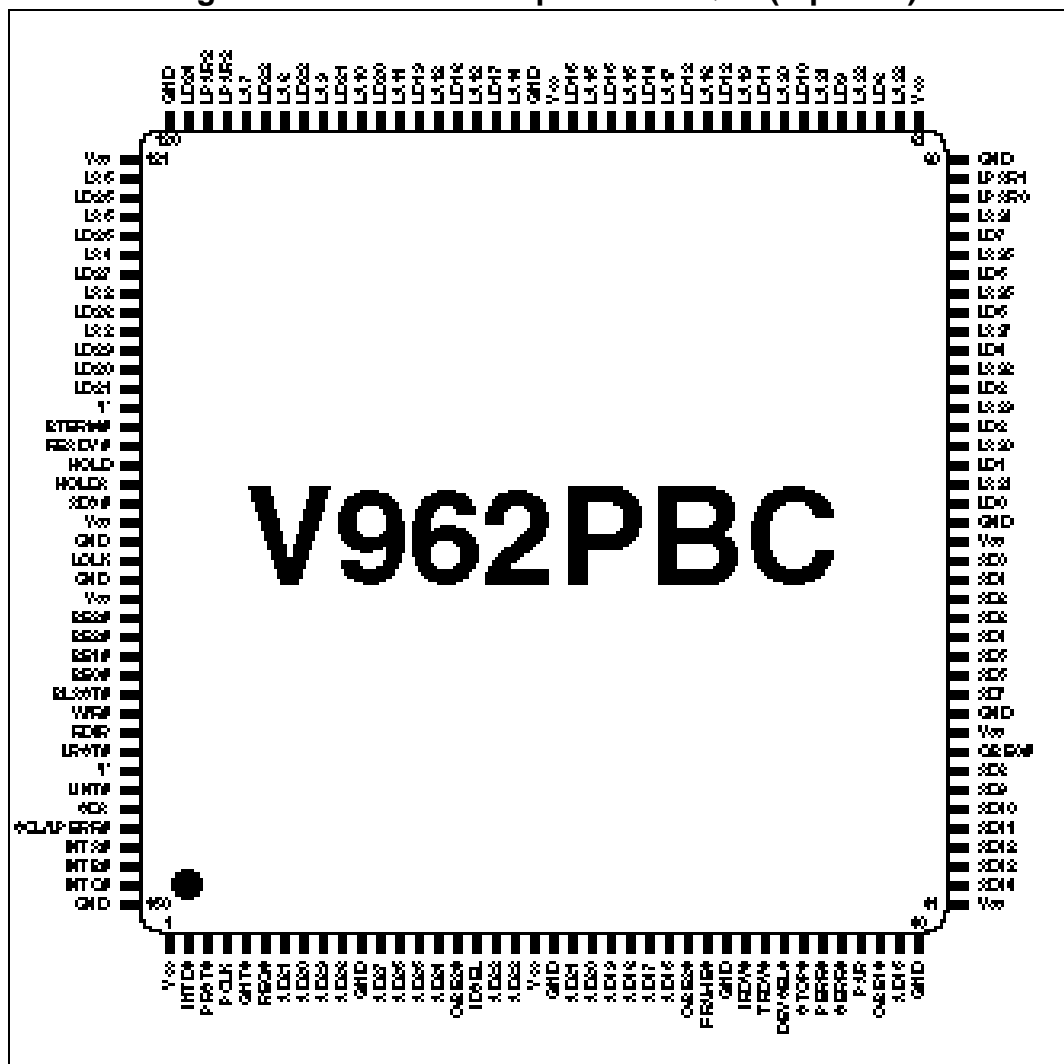
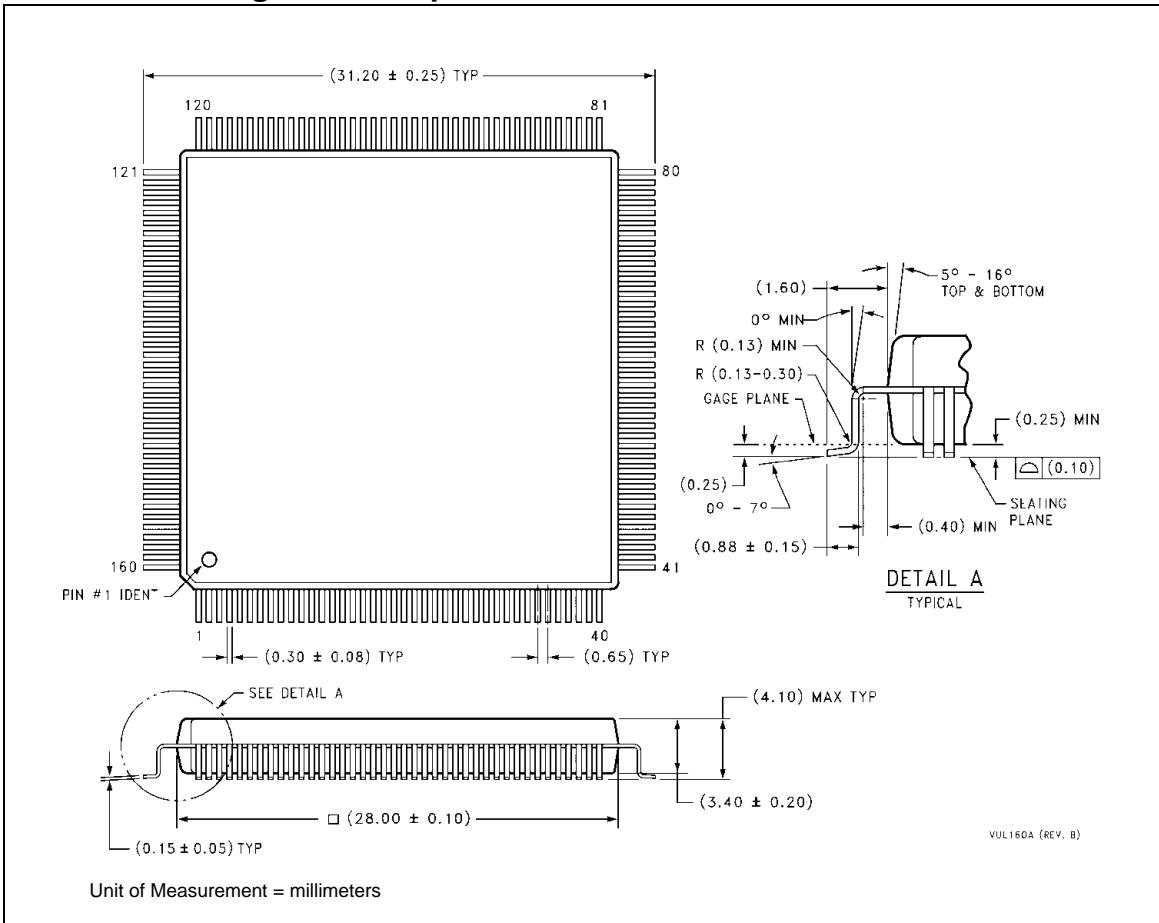


Figure 2: 160-pin EIAJ PQFP mechanical details



3.0 DC Specifications

The DC specifications for the PCI bus signals match exactly those given in the PCI Specification, Rev. 2.1, Section 4.2.1.1. For more information on the PCI DC specifications, see the PCI Specification.

Table 6: Absolute Maximum Ratings

| Symbol | Parameter | Value | Units |
|-----------|---------------------------|----------------------|-------|
| V_{CC} | Supply voltage | -0.3 to +7 | V |
| V_{IN} | DC input voltage | -0.3 to $V_{CC}+0.3$ | V |
| I_{IN} | DC input current | ± 10 | mA |
| T_{STG} | Storage temperature range | -40 to +125 | °C |

Table 7: Guaranteed Operating Conditions

| Symbol | Parameter | Value | Units |
|----------|---------------------------|--------------|-------|
| V_{CC} | Supply voltage | 4.75 to 5.25 | V |
| T_A | Ambient temperature range | 0 to 70 | °C |

3.1 PCI Bus DC Specifications

Table 8: PCI Bus Signals DC Operating Specifications

| Symbol | Parameter | Condition | Min | Max | Units | Notes |
|-------------|----------------------------|----------------------|------|--------------|---------|-------|
| V_{IH} | Input high voltage | | 2.0 | $V_{CC}+0.5$ | V | |
| V_{IL} | Input low voltage | | -0.5 | 0.8 | V | |
| I_{IH} | Input high leakage current | $V_{IN} = 2.7V$ | | 70 | μA | 1 |
| I_{IL} | Input low leakage current | $V_{IN} = 0.5V$ | | -70 | μA | 1 |
| V_{OH} | Output high voltage | $I_{OUT} = -2mA$ | 2.4 | | V | |
| V_{OL} | Output low voltage | $I_{OUT} = 3mA, 6mA$ | | 0.55 | V | 2 |
| C_{IN} | Input pin capacitance | | | 10 | pF | 3 |
| C_{CLK} | PCLK pin capacitance | | 5 | 12 | pF | |
| C_{IDSEL} | IDSEL pin capacitance | | | 8 | pF | 4 |
| L_{PIN} | Pin inductance | | | 20 | nH | |

V962PBC

Notes:

1. Input leakage currents include high impedance output leakage for all bi-directional buffers with tri-state outputs.
2. Signals without pull-up resistors have greater than 3mA low output current. Signals requiring pull resistors have greater than 6mA output current. The latter include FRAME, TRDY, IRDY, STOP, SERR, PERR.
3. Absolute maximum pin capacitance for a PCI unit is 10pF (except for CLK).
4. Lower capacitance on this input-only pin allows for non-resistive coupling to AD[xx].

3.2 Local Bus DC Specifications

Table 9: Local Bus Signals DC Operating Specifications

| Symbol | Description | Conditions | Min | Max | Units |
|------------------------|---|---|-----|-----|---------|
| V_{IL} | Low level input voltage | $V_{CC} = 4.75V$ | | 0.8 | V |
| V_{IH} | High level input voltage | $V_{CC} = 5.25V$ | 2.0 | | V |
| I_{IL} | Low level input current | $V_{IN}=GND, V_{CC}=5.25V$ | -10 | | μA |
| I_{IH} | High level input current | $V_{IN} = V_{CC} = 5.25V$ | | 10 | μA |
| V_{OL4} | Low level output voltage for 4 mA outputs and I/O pins | $I_{OL} = -4 \text{ mA}$ | | 0.4 | V |
| V_{OH4} | High level output voltage for 4 mA outputs and I/O pins | $I_{OH} = 4 \text{ mA}$ | 2.4 | | V |
| I_{OZL} | Low level float input leakage | $V_{IN} = GND$ | -10 | | μA |
| I_{OZH} | High level float input leakage | $V_{IN} = V_{CC}$ | | 10 | μA |
| $I_{CC} \text{ (max)}$ | Maximum supply current | $V_{CC} = 5.25V$ $PCLK = LCLK = 33MHz$ | | 150 | mA |
| $I_{CC} \text{ (typ)}$ | Typical supply current | $V_{CC} = 5.0V$ $PCLK = LCLK = 33MHz$ | | 120 | mA |
| C_{IO} | Input and output capacitance | | | 10 | pF |

4.0 AC Specifications

The AC specifications for the PCI bus signals match exactly those given in the PCI Specification, Rev. 2.1, Section 4.2.1.2. For more information on the PCI AC specifications, including the V/I curves for 5V signalling, see section 4.2.1.2 of Rev 2.1 PCI Specification.

4.1 PCI Bus Timings

Table 10: PCI Bus Signals AC Operating Specifications

| Symbol | Parameter | Condition | Min | Max | Units | Notes |
|--------------|---------------------------|--------------------------|-------------------------------|------------|-------|---------|
| $I_{OH(AC)}$ | Switching current high | $0V < V_{OUT} \leq 1.4V$ | -44 | | mA | 1 |
| | | $1.4V < V_{OUT} < 2.4V$ | $-44 + (V_{OUT} - 1.4)/0.024$ | Equation A | mA | 1, 2, 3 |
| | (Test point) | $V_{OUT} = 3.1V$ | | -142 | mA | 3 |
| $I_{OL(AC)}$ | Switching current low | $V_{OUT} \geq 2.2V$ | 95 | | mA | 1 |
| | | $2.2V > V_{OUT} > 0.55V$ | $V_{OUT}/0.023$ | Equation B | mA | 1, 3 |
| | (Test point) | $V_{OUT} = 0.71V$ | | 206 | mA | 3 |
| I_{CL} | Low clamp current | $-5 < V_{IN} \leq -1$ | $-25 + (V_{IN} + 1)/0.015$ | | mA | |
| t_R | Unloaded output rise time | 0.4V to 2.4V | 1 | 5 | V/ns | 4 |
| t_F | Unloaded output fall time | 2.4V to 0.4V | 1 | 5 | V/ns | 4 |

Notes:

1. Refer to the V/I curves in Section 4.2.1 of the PCI Specification. This specification does not apply to CLK and RST which are system outputs. "Switching Current High" specifications are not relevant to open drain outputs such as SERR and INTA-INTD.
2. Note that this segment of the minimum current curve is drawn from the AC drive point directly to the DC drive point rather than toward the voltage rail (as it does in the pull-down curve). This difference is intended to allow for an optional N-channel pull-up.
3. Maximum current requirements are met as drivers pull beyond the first step voltage (AC drive point). Equations defining these maximums (A and B) are provided with the respective V/I curves given in the PCI Spec. The equation defined maxima is met by design.
4. The minimum slew rate (slowest signal edge) is met by the PCI drivers. The maximum slew rate (fastest signal edge) is a guideline. Motherboard designers must bear in mind that rise and fall times faster than this maximum guideline could occur, and should ensure that signal integrity modeling accounts for this.

$$\text{Equation A: } I_{OH} = 11.9 \cdot (V_{OUT} - 5.25V) \cdot (V_{OUT} + 2.45V) \text{ for } V_{CC} > V_{OUT} > 3.1V$$

$$\text{Equation B: } I_{OL} = 78.5 \cdot V_{OUT}(4.4V - V_{OUT}) \text{ for } 0V < V_{OUT} < 0.71V$$

4.2 Local Bus Timings

Table 11: i960Cx/Hx Local Bus AC Test Conditions

| Symbol | Parameter | Limits | Units |
|------------------|--|--------------|-------|
| V _{CC} | Supply voltage | 4.75 to 5.25 | V |
| V _{IN} | Input low and high voltages | 0.4 and 2.0 | V |
| C _{OUT} | Capacitive load on output and I/O pins | 50 | pF |

Table 12: Capacitive Derating for Output and I/O Pins

| Output Drive Limit | Derating |
|--------------------|------------------------------|
| 4mA | 0.058 ns/pF for loads > 50pF |

Figure 3: Clock and Synchronous Signals

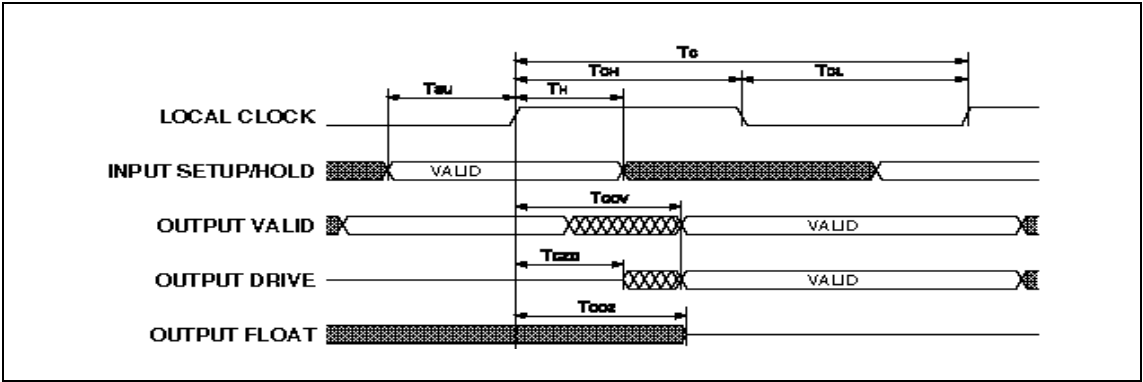


Table 13: Local Bus Timing Parameters for Vcc = 5 Volts +/- 5%

| | | | | 33MHz | | 40MHz | | |
|----|------------------|--|-------|-------------------|-----|-------------------|-----|-------|
| # | Symbol | Description | Notes | Min | Max | Min | Max | Units |
| 1 | T _C | LCLK period | | 30 | | 25 | | ns |
| 2 | T _{CH} | LCLK high time | 1 | 12 | | 11 | | ns |
| 3 | T _{CL} | LCLK low time | 1 | 12 | | 11 | | ns |
| 4 | T _{SU} | Synchronous input setup | 2 | 7 | | 6 | | ns |
| 4a | T _{SU} | Synchronous input setup ($\overline{\text{BLAST}}$) | | 8 | | 7 | | ns |
| 4b | T _{SU} | Synchronous input setup ($\overline{\text{W/R}}, \overline{\text{BTERM}}$) | | 4 | | 4 | | ns |
| 4c | T _{SU} | Synchronous input setup ($\overline{\text{ADS}}$) | | 6 | | 5 | | ns |
| 4d | T _{SU} | Synchronous input setup (address, data, byte enables) | | 9 | | 8 | | ns |
| 4e | T _{SU} | Synchronous input setup for read data when in local bus master mode | | 5 | | 5 | | ns |
| 5 | T _H | Synchronous input hold | | | 2 | | 2 | ns |
| 6 | T _{COV} | LCLK to output valid delay | 3 | 3 | 14 | 3 | 12 | ns |
| 6a | T _{COV} | LCLK to output valid delay (address, data, byte enable, parity) | | 3 | 15 | 3 | 14 | ns |
| 7 | T _{CZO} | LCLK to output driving delay | | 3 | 15 | 3 | 14 | ns |
| 8 | T _{COZ} | LCLK to high impedance delay | 4 | 3 | 15 | 3 | 14 | ns |
| 9 | T _{RST} | Reset period when LRST used as input | | 16·T _C | | 16·T _C | | ns |

Notes:

1. Measured at 1.5V.
2. All local bus signals except those in 4a, 4b, 4c, 4d and 4e.
3. All local bus signals except those in 6a.
4. READY, BLAST, ADS are driven to high impedance at the falling edge of LCLK.

Table 14: PCI Bus Timing Parameters for Vcc = 5 Volts +/- 5%

| # | Symbol | Description | Notes | Min | Max | Units |
|----|-----------------|---|-------|-----|-----|-------|
| 1 | T _C | PCLK period | | 30 | | ns |
| 2 | T _{SU} | Synchronous input setup to PCLK | 1 | 7 | | ns |
| 2a | T _{SU} | Synchronous input setup to PCLK ($\overline{\text{GNT}}$) | | 10 | | ns |
| 3 | T _H | Synchronous input hold from PCLK | | 0 | | ns |

Table 14: PCI Bus Timing Parameters for $V_{CC} = 5 \text{ Volts} \pm 5\%$

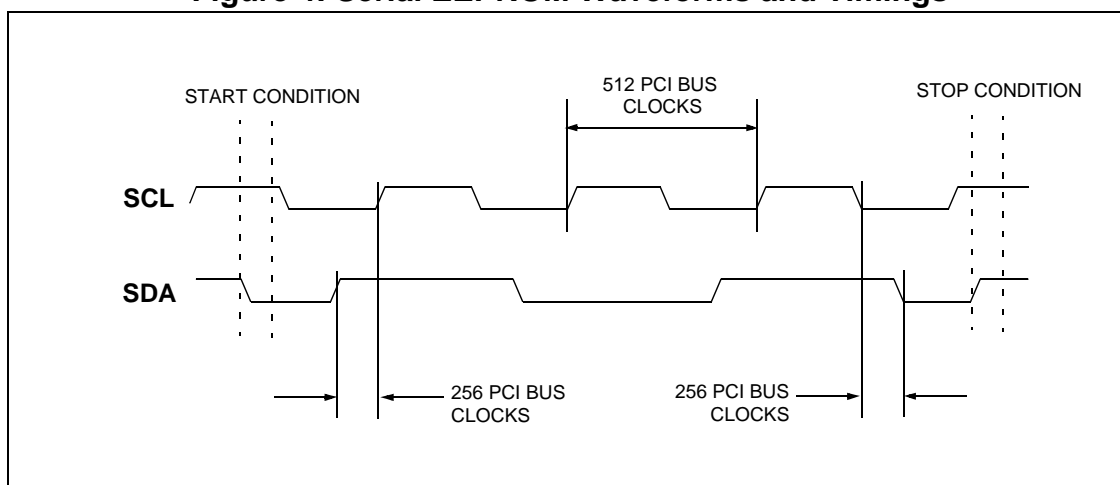
| | | | | | | |
|----|-----------|---|---|----------------|----|----|
| 4 | T_{COV} | PCLK to output valid delay | 2 | 3 | 11 | ns |
| 4a | T_{COV} | PCLK to output valid delay (\overline{REQ}) | | 4 | 12 | ns |
| 5 | T_{CZO} | PCLK to output driving delay | | 4 | 11 | ns |
| 6 | T_{COZ} | PCLK to high impedance delay | | 5 | 18 | ns |
| 7 | T_{RST} | Reset period when PRST used as input | | $16 \cdot T_C$ | | |

Notes:

1. All PCI bus signals except those in 2a.
2. All PCI bus signals except those in 4a.

4.3 Serial EEPROM Port Timings

The clock for the serial EEPROM interface is derived by dividing the PCI bus clock. The waveforms generated are shown in Figure 4.

Figure 4: Serial EEPROM Waveforms and Timings

5.0 Revision History

Table 15: Revision History

| Revision Number | Date | Comments and Changes |
|-----------------|-------|---|
| 2.4 | 5/98 | Data sheet up date to B2-step values |
| 2.3 | 10/96 | Data Book revision. 1. In Table 3, changed "LPAR[3:0]" to "LPAR[3:0]". |

Table 15: Revision History (cont'd)

| Revision Number | Date | Comments and Changes |
|-----------------|-------|--|
| 2.2 | 06/96 | 1. In Table 3, changed "PERR I/OD" to "PERR I/O". 2. In Table 3, added " V_{CC} " and "GND" description. 3. In Table 13 and 14, added min T_{COV} and min T_{CZO} timing. |
| 2.1 | 03/96 | 1. Updated timings to final B1-step values. 2. Simplified data sheet format. |
| 2.0 | 11/95 | Removed operational description (found in User's Manual). Device related changes: 1. LA5, LA4, LA3, LA2 pins added to pinout for V960PBC and V961PBC. 2. Changed references to PCI 2.0 to PCI 2.1 spec level compliance. 3. Updated timings to final B0-step values. 4. Added new T_{CZO} timing. 5. Added test mode pin description. |
| 1.3 | 4/95 | 1. In Table 1, changed Draining Strategy to "3 or more words" from "4 or more writes". 2. In Table 3, changed Base Address 3 to Unimplemented. 3. In Table 5, changed "PAR" to "PAR". 4. In Table 6, changed "SCL" to "SCL/PERR". 5. In Table 6, changed \overline{SDA} to " I/O_4 " from " O_4 ". 6. In Table 6, changed \overline{ROMCSx} , \overline{LREQ} , and \overline{ADS} to " I/O_4 " from " O_4 " (device dependent). 7. In Table 6, changed \overline{GREQ} , \overline{LBREQ} , and \overline{HOLD} to " O_4 " from " I/O_4 " (device dependent). 8. In Table 6, changed \overline{BURST} and \overline{BLAST} to " I/O_4 " from " O_4 " (device dependent). 9. In Table 6, changed \overline{ERR} and \overline{BTERM} to " I/O_4 " from " O_4 " (device dependent). 10. In Table 14, added timings for 16MHz and 40MHz (device dependent). |
| 1.2 | 3/95 | First released version of the data sheet. Some changes to AC and DC specifications and to waveforms. All future changes to the data sheet will be documented in detail in this section. |
| 1.1 | 2/95 | Clean pinouts. Some DC and AC specs. Sent only to a limited number of customers. |
| 1.0 | 1/95 | First pre-silicon revision of preliminary data sheet. DC and AC specs TBD. Sent only to a limited number of customers. |



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V962PBC