

March 1997

NM24Cxx—Standard 2-Wire Bus Interface Serial EEPROM Family

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# **General Description**

The NM24Cxx devices are 2048/4096/8192/16,834 bits of CMOS nonvolatile electrically erasable memory. These devices conform to all specifications in the  $I^2C^{TM}$  2-wire protocol and are designed to minimize device pin count and simplify PC board layout requirements.

The upper half of the memory of the 03/05/09/17 can be disabled (Write Protected) by connecting the WP pin to  $V_{\rm CC}.$  This section of memory then becomes unalterable unless WP is switched to  $V_{\rm SS}.$ 

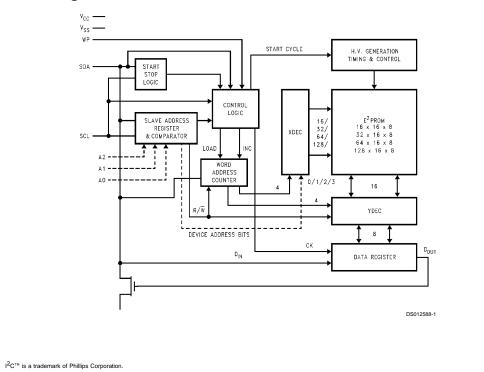
This communications protocol uses CLOCK (SCL) and DATA I/O (SDA) lines to synchronously clock data between the master (for example a microprocessor) and the slave EEPROM device(s). This bus structure allows for a maximum of 16k of EEPROM memory, which is supported by the NSC family in 2k, 4k, 8k, and 16k devices, allowing the user to configure the memory as the application requires with any combination of EEPROMs (not to exceed 16k).

Fairchild EEPROMs are designed and tested for applications requiring high endurance, high reliability and low power consumption.

### **Features**

- Extended operating voltage 2.7V-5.5V
- 400 kHz clock frequency (F)
- 500 μA active current typical
   10 μA standby current typical
   1 μA standby typical (L)
   0.1 μA standby typical (LZ)
- I<sup>2</sup>C compatible interface
  - Provides bidirectional data transfer protocol
- Sixteen byte page write mode
  - Minimizes total write time per byte
- Self timed write cycle
  - Typical write cycle time of 6 ms
- Hardwire write protect for upper block (03/05/09/17) only
- Endurance: 10<sup>6</sup> data changes
- Data retention greater than 40 years
- Packages available: 8-pin mini-DIP, 8-pin SO, and 8-pin TSSOP (2k, 4k) only

# **Block Diagram**



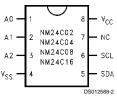
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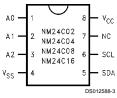


Dual-In-Line Package (N)



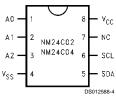
Top View See Package Number N08E (N)

SO Package (M8)



Top View See Package Number M08A (M8)

TSSOP Package (MT8)

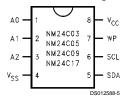


Top View See Package Number MTC08 (MT8)

## **Pin Names**

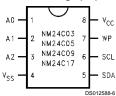
A0, A1, A2	Device Address Inputs
V <sub>SS</sub>	Ground
SDA	Data I/O
SCL	Clock Input
NC	No Connection
V <sub>CC</sub>	Power Supply





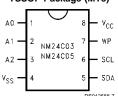
Top View See Package Number N08E (N)

# SO Package (M8)



Top View See Package Number M08A (M8)

# TSSOP Package (MT8)



Top View See Package Number MTC08 (MT8)

# **Pin Names**

A0, A1, A2	Device Address Inputs
V <sub>SS</sub>	Ground
SDA	Data I/O
SCL	Clock Input
WP	Write Protect
V <sub>cc</sub>	Power Supply

# **Ordering Information**

## **Commercial Temperature Range** (0°C to +70°C)

Order Number
NM24CxxN
NM24CxxLN
NM24CxxM8
NM24CxxLM8
NM24C02MT8/NM24C04MT8
NM24C03MT8/NM24C05MT8
NM24C02LMT8/NM24C04LMT8
NM24C03LMT8/NM24C05LMT8
NM24CxxFN
NM24CxxFLN
NM24CxxFM8
NM24CxxFLM8
NM24C02FMT8/NM24C04FMT8
NM24C03FMT8/NM24C05FMT8
NM24C02FLMT8/NM24C04FLMT8
NM24C03FLMT8/NM24C05FLMT8
NM24C08MT8

## **Extended Temperature Range** (-40°C to +85°C)

Order Number
NM24CxxEN
NM24CxxLEN
NM24CxxEM8
NM24CxxLEM8
NM24C02EMT8/NM24C04EMT8
NM24C03EMT8/NM24C05EMT8
NM24C02LEMT8/NM24C04LEMT8
NM24C03LEMT8/NM24C05LEMT8
NM24CxxFEN
NM24CxxFLEN
NM24CxxFEM8
NM24CxxFLEM8
NM24C02FEMT8/NM24C04FEMT8
NM24C03FEMT8/NM24C05FEMT8
NM24C02FLEMT8/NM24C04FLEMT8
NM24C03FLEMT8/NM24C05FLEMT8
NM24C08EMT8

# Automotive Temperature Range (-40°C to +125°C)

Order Number
NM24CxxVN
NM24CxxLVN
NM24CxxVM8
NM24CxxLVM8
NM24C02VMT8/NM24C04VMT8
NM24C03VMT8/NM24C05VMT8
NM24C02LVMT8/NM24C04LVMT8
NM24C03LVMT8/NM24C05LVMT8
NM24CxxFVN
NM24CxxFLVN
NM24CxxFVM8
NM24CxxFLVM8
NM24C02FVMT8/NM24C04FVMT8
NM24C03FVMT8/NM24C05FVMT8
NM24C02FLVMT8/NM24C04FLVMT8
NM24C03FLVMT8/NM24C05FLVMT8
NM24C08VMT8

# **Absolute Maximum Ratings** (Note 1)

Ambient Storage Temperature -65°C to +150°C

All Input or Output Voltages

with Respect to Ground

Lead Temperature

(Soldering, 10 seconds) ESD Rating

# **Operating Conditions**

Ambient Operating Temperature

NM24Cxx  $0^{\circ}$ C to +70 $^{\circ}$ C NM24CxxE –40°C to +85°C

 $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ NM24CxxV

Positive Power Supply

NM24Cxx 4.5V to 5.5V NM24CxxL 2.7V to 5.5V NM24CxxLZ 2.7V to 5.5V

# Standard $V_{\text{CC}}$ DC and AC Electrical Characteristics

6.5V to -0.3V

+300°C

2000V min

Symbol	Parameter	Test Conditions		Limits		Units
			Min	Typ (Note 2)	Max	
I <sub>CCA</sub>	Active Power Supply Current	f <sub>SCL</sub> = 100 kHz		0.5	1.0	mA
I <sub>SB</sub>	Standby Current	V <sub>IN</sub> = GND or V <sub>CC</sub>		10	50	μA
ILI	Input Leakage Current	V <sub>IN</sub> = GND to V <sub>CC</sub>		0.1	1	μA
I <sub>LO</sub>	Output Leakage Current	$V_{OUT}$ = GND to $V_{CC}$		0.1	1	μA
V <sub>IL</sub>	Input Low Voltage		-0.3		V <sub>CC</sub> x 0.3	V
V <sub>IH</sub>	Input High Voltage		V <sub>CC</sub> x 0.7		V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 3 mA			0.4	V

# Low V<sub>CC</sub> DC and AC Electrical Characteristics

Symbol	Parameter	Test Conditions		Limits		Units
			Min	Тур	Max	
				(Note 2)		
I <sub>CCA</sub>	Active Power Supply Current	f <sub>SCL</sub> = 100 kHz		0.5	1.0	mA
I <sub>SB</sub>	Standby Current	$V_{IN}$ = GND or $V_{CC}$		1	10	μA
(Note 2)	Standby Current for LZ	V <sub>IN</sub> = GND or V <sub>CC</sub>		0.1	1	μA
I <sub>LI</sub>	Input Leakage Current	V <sub>IN</sub> = GND to V <sub>CC</sub>		0.1	1	μA
I <sub>LO</sub>	Output Leakage Current	$V_{OUT}$ = GND to $V_{CC}$		0.1	1	μA
V <sub>IL</sub>	Input Low Voltage		-0.3		V <sub>CC</sub> x 0.3	V
V <sub>IH</sub>	Input High Voltage		V <sub>CC</sub> x 0.7		V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 3 mA			0.4	V

## Capacitance

 $T_A = +25$ °C, f = 1.0 MHz,  $V_{CC} = 5V$ 

Symbol	Test	Conditions	Max	Units
C <sub>I/O</sub>	Input/Output Capacitance (SDA)	V <sub>I/O</sub> = 0V	8	pF
C <sub>IN</sub>	Input Capacitance (A0, A1, A2, SCL)	V <sub>IN</sub> = 0V	6	pF

# **AC Conditions of Test**

Input Pulse Levels	V <sub>CC</sub> x 0.1 to V <sub>CC</sub> x 0.9
Input Rise and Fall Times	10 ns
Input and Output Timing Levels	V <sub>CC</sub> x 0.5
Output Load	1 TTL Gate and C <sub>L</sub> = 100 pF

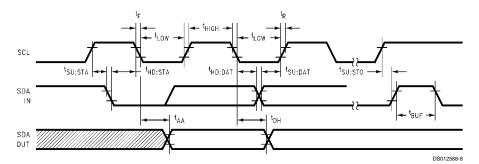
Note 2: Typical values are for  $T_A = 25^{\circ}C$  and nominal supply voltage (5V).

Symbol	Parameter	100	100 kHz		400 kHz	
		Min	Max	Min	Max	
f <sub>SCL</sub>	SCL Clock Frequency		100		400	kHz
T <sub>I</sub>	Noise Suppression Time Constant at					
	SCL, SDA Inputs (Minimum V <sub>IN</sub>		100		50	ns
	Pulse Width)					
t <sub>AA</sub>	SCL Low to SDA Data Out Valid	0.3	3.5	0.1	0.9	μs
t <sub>BUF</sub>	Time the Bus Must Be Free before	4.7		1.3		μs
	a New Transmission Can Start					
t <sub>HD:STA</sub>	Start Condition Hold Time	4.0		0.6		μs
t <sub>LOW</sub>	Clock Low Period	4.7		1.5		μs
t <sub>HIGH</sub>	Clock High Period	4.0		0.6		μs
t <sub>SU:STA</sub>	Start Condition Setup Time	4.7		0.6		μs
	(for a Repeated Start Condition)					
t <sub>HD:DAT</sub>	Data in Hold Time	0		0		μs
t <sub>SU:DAT</sub>	Data in Setup Time	250		100		ns
t <sub>R</sub>	SDA and SCL Rise Time		1		0.3	μs
t <sub>F</sub>	SDA and SCL Fall Time		300		300	ns
t <sub>SU:STO</sub>	Stop Condition Setup Time	4.7		0.6		μs
t <sub>DH</sub>	Data Out Hold Time	300		50		ns
t <sub>WR</sub> (Note 3)	Write Cycle Time — NM24Cxx		10		10	ms

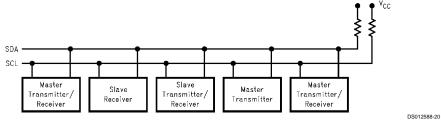
Note 3: The write cycle time (t<sub>WR</sub>) is the time from a valid stop condition of a write sequence to the end of the internal erase/program cycle. During the write cycle, the NM24Cxx bus interface circuits are disabled, SDA is allowed to remain high per the bus-level pull-up resistor, and the device does not respond to its slave ad-

# **Bus Timing**

- NM24CxxL/xxLZ



# **System Layout**

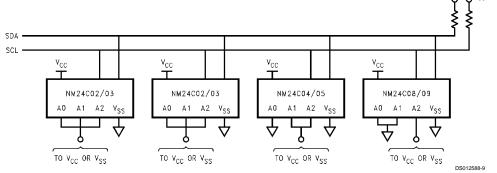


Note: Due to open drain configuration of SDA, a bus-level pull-up resistor is called for (typical value = 4.7 k $\Omega$ ).

FIGURE 1. Typical System Configuration

# System Layout (Continued)

#### Example of 16k (Maximum Size) of Memory on 2-Wire Bus



**Note:** The SDA pull-up resistor is required due to the open-drain/open collector output of  $l^2C$  bus devices. The SCL pull-up resistor is recommended because of the normal SCL line inactive "high" state. It is recommended that the total line capacitance be less than 400 pF.

Device		Address Pins	Memory Size	# of	
	A0	A1	A1 A2		Page Blocks
NM24C02/03	ADR	ADR	ADR	2048 Bits	1
NM24C04/05	No Connect	ADR	ADR	4096 Bits	2
NM24C08/09	No Connect	No Connect	ADR	8192 Bits	4
NM24C16/17	No Connect	No Connect	No Connect	16,384 Bits	8

ADR is the hardware address ( $V_{CC}/1$  or  $V_{SS}/0$ ) of the device(s) used.

# Device Operation Inputs (A0, A1, A2)

Device address pins A0, A1, and A2 are connected to  $V_{\rm CC}$  or  $V_{\rm SS}$  to configure the EEPROM chip address. *Table 1* shows the active pins across the NM24Cxx device family.

TABLE 1.

Device	A0	A1	A2	Effects of Addresses
NM24C02/03	ADR	ADR	ADR	$2^3 = 8 (8) \times (2k) = 16k$
NM24C04/05	х	ADR	ADR	$2^2 = 8 (8) x (2k) = 16k$
NM24C08/09	х	х	ADR	$2^1 = 8 (8) x (2k) = 16k$
NM24C16/17	х	х	х	$2^0 = 8 (8) \times (2k) = 16k$

#### BACKGROUND INFORMATION (I<sup>2</sup>C Bus)

As mentioned, the I<sup>2</sup>C bus allows synchronous bidirectional communication between Transmitter/Receiver using the SCL (clock) and SDA (Data I/O) lines. All communication must be started with a valid START condition, concluded with a STOP condition and acknowledged by the Receiver with an AC-KNOWLEDGE condition.

As shown below, the EEPROMs on the  $I^2C$  bus may be configured in any manner required, the total memory addressed can not exceed 16k (16,384 bits). EEPROM memory address programming is controlled by 2 methods:

 Hardware configuring the A0, A1, and A2 pins (Device Address pins) with pull-up or pull-down resistors. All unused pins must be grounded (tied to V<sub>SS</sub>).  Software addressing the required PAGE BLOCK within the device memory array (as sent in the Slave Address string).

Addressing an EEPROM memory location involves sending a command string with the following information:

[DEVICE TYPE]-[DEVICE ADDRESS]-[PAGE BLOCK ADDRESS]-[BYTE ADDRESS]

Definitions				
BYTE	8 bits (byte) of data			
PAGE	16 sequential addresses (one byte			
	each) that may be programmed during			
	a "Page Write" programming cycle			
PAGE BLOCK	2,048 (2k) bits organized into 16			
	pages of addressable memory. (8 bits)			
	x (16 bytes) x (16 pages) = 2,048 bits			
MASTER	Any I <sup>2</sup> C device CONTROLLING the			
	transfer of data (such as a			
	microprocessor)			
SLAVE	Device being controlled (EEPROMs			
	are always considered Slaves)			
TRANSMITTER	Device currently SENDING data on the			
	bus (may be either a Master or Slave)			
RECEIVER	Device currently receiving data on the			
	bus (Master or Slave)			

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Proof

## **Pin Descriptions**

#### SERIAL CLOCK (SCL)

The SCL input is used to clock all data into and out of the device.

#### SERIAL DATA (SDA)

SDA is a bidirectional pin used to transfer data into and out of the device. It is an open drain output and may be wire-ORed with any number of open drain or open collector outputs.

# WP Write Protection (03/05/09/17) Only

If tied to  $V_{\rm CC}$ , PROGRAM operations onto the upper half of the memory will not be executed. READ operations are possible. If tied to  $V_{\rm SS}$ , normal operation is enabled, READ/WRITE over the entire memory is possible.

This feature allows the user to assign the upper half of the memory as ROM which can be protected against accidental programming. When write is disabled, slave address and byte address will be acknowledged but data will not be acknowledged.

## **Device Operation**

The NM24Cxx supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is the master and the device that is controlled is the slave. The master will always initiate data transfers and provide the clock for both transmit and receive operations. Therefore, the NM24Cxx will be considered a slave in all applications.

#### **CLOCK AND DATA CONVENTIONS**

Data states on the SDA line can change only durIng SCL LOW. SDA state changes during SCL HIGH are reserved for indicating start and stop conditions. Refer to Figure 2 and Figure 3.

#### START CONDITION

All commands are preceded by the start condition, which is a HIGH to LOW transition of SDA when SCL is HIGH. The NM24Cxx continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met.

#### STOP CONDITION

All communications are terminated by a stop condition, which is a LOW to HIGH transition of SDA when SCL is HIGH. The stop condition is also used by the NM24Cxx to place the device in the standby power mode.

# Write Cycle Timing

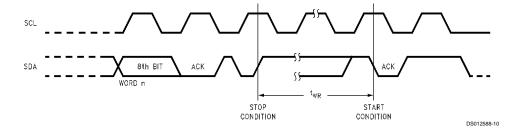
#### **ACKNOWLEDGE**

Acknowledge is a software convention used to indicate successful data transfers. The transmitting device, either master or slave, will release the bus after transmitting eight bits.

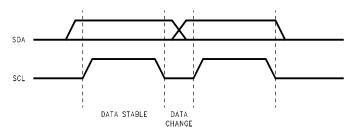
During the ninth clock cycle the receiver will pull the SDA line to LOW to acknowledge that it received the eight bits of data. Refer to *Figure 4*.

The NM24Cxx device will always respond with an acknowledge after recognition of a start condition and its slave address. If both the device and a write operation have been selected, the NM24Cxx will respond with an acknowledge after the receipt of each subsequent eight bit byte.

In the read mode the NM2Cxx slave will transmit eight bits of data, release the SDA line and monitor the line for an acknowledge. If an acknowledge is detected and no stop condition is generated by the master, the slave will continue to transmit data. If an acknowledge is not detected, the slave will terminate further data transmissions and await the stop condition to return to the standby power mode.



# Write Cycle Timing (Continued)



### FIGURE 2. Data Validity

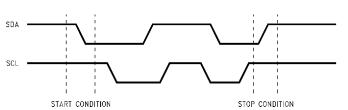


FIGURE 3. Start and Stop Definition

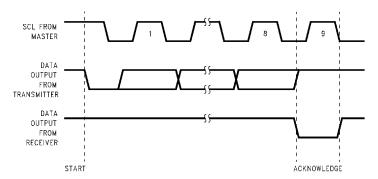


FIGURE 4. Acknowledge Response from Receiver

### **DEVICE ADDRESSING**

Following a start condition, the master must output the address of the slave it is accessing. The most significant four bits of the slave address are those of the device type identifier (*Figure 5*). This is fixed as 1010 for all devices.

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DS012588-12

DS012588-13

## Write Cycle Timing (Continued)

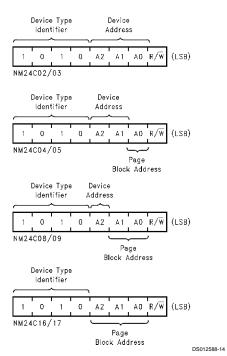


FIGURE 5. Slave Addresses

Refer to the following table for Slave Addresses string details:

Device	A0	A1	A2	Page	Page Block Ad-
				Blks	dresses
NM24C02/03	Α	Α	Α	1	(None)
				(2k)	
NM24C04/05	Р	Α	Α	2	0 1
				(4k)	
NM24C08/09	Р	Р	Α	4	00 01 10 11
				(8k)	
NM24C16/17	Р	Р	Р	8	000 001 010 011111
				(16k)	

A: Refers to a hardware configured Device Address pin.

P: Refers to an internal PAGE BLOCK memory segment.

All I<sup>2</sup>C EEPROMs use an internal protocol that defines a PAGE BLOCK size of 2k bits (for Byte addressess 0000 through 1111). Therefore, address bits A0, A1, or A2 (if designated "P") are used to access a PAGE BLOCK in conjuction with the Byte address used to access any individual data byte (Byte).

The last bit of the slave address defines whether a write or read condition is requested by the master. A "1" indicates that a read operation is to be executed, and a "0" initiates the write mode.

A simple review: After the NM24Cxx recognizes the start condition, the devices interfaced to the I<sup>2</sup>C bus wait for a slave address to be transmitted over the SDA line. If the transmitted slave address matches an address of one of the devices, the designated slave pulls the line LOW with an acknowledge signal and awaits further transmissions.

# **Write Operations**

#### BYTE WRITE

For a write operation a second address field is required which is a byte address that is comprised of eight bits and provides access to any one of the 256 bytes in the selected page of memory. Upon receipt of the byte address the NM24Cxx responds with an acknowledge and waits for the next eight bits of data, again, responding with an acknowledge. The master then terminates the transfer by generating a stop condition, at which time the NM24Cxx begins the internal write cycle to the nonvolatile memory. While the internal write cycle is in progress the NM24Cxx inputs are disabled, and the device will not respond to any requests from the master. Refer to Figure 6 for the address, acknowledge and data transfer sequence.

#### PAGE WRITE

The NM24Cxx is capable of a sixteen byte page write operation. It is initiated in the same manner as the byte write operation; but instead of terminating the write cycle after the first data byte is transferred, the master can transmit up to fifteen more bytes. After the receipt of each byte, the NM24Cxx will respond with an acknowledge.

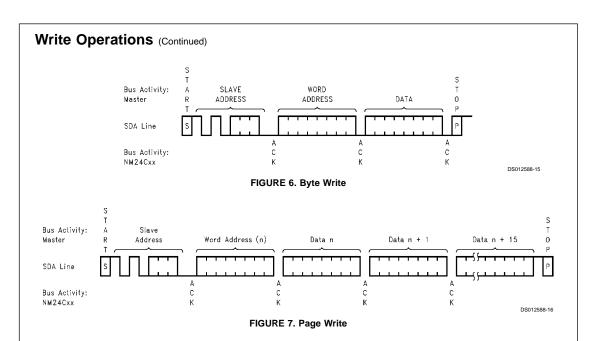
After the receipt of each byte, the internal address counter increments to the next address and the next SDA data is accepted. If the master should transmit more than sixteen bytes prior to generating the stop condition, the address counter will "roll over" and the previously written data will be overwritten. As with the byte write operation, all inputs are disabled until completion of the internal write cycle. Refer to Figure 9 for the address, acknowledge, and data transfer sequence.

# ACKNOWLEDGE POLLING

Once the stop condition is issued to indicate the end of the host's write operation the NM24Cxx initiates the internal write cycle. ACK polling can be initiated immediately. This involves issuing the start condition followed by the slave address for a write operation. If the NM24Cxx is sfill busy with the write operation no ACK will be returned. If the NM24Cxx has completed the write operation an ACK will be returned and the host can then proceed with the next read or write operation

#### WRITE PROTECTION (03/05/09/17) ONLY

Programming of the upper half of the memory will not take place if the WP pin of the NM24Cxx is connected to  $V_{CC}$ . The NM24Cxx will accept slave and byte addresses; but if the memory accessed is write protected by the WP pin, the NM24Cxx will not generate an acknowledge after the first byte of data has been received, and thus the program cycle will not be started when the stop condition is asserted.



# **Read Operations**

Read operations are initiated in the same manner as write operations, with the exception that the  $R / \overline{W}$  bit of the slave address is set to a one. There are three basic read operations: current address read, random read, and sequential read.

#### **CURRENT ADDRESS READ**

Internally the NM24Cxx contains an address counter that maintains the address of the last byte accessed, incremented by one. Therefore, if the last access (either a read or write) was to address n, the next read operation would access data from address n + 1. Upon receipt of the slave address with  $R\overline{\rm W}$  set to one, the NM24Cxx issues an acknowledge and transmits the eight bit byte. The master will not acknowledge the transfer but does generate a stop condition, and therefore the NM24Cxx discontinues transmission. Refer to Figure 8 for the sequence of address, acknowledge and data transfer.

#### RANDOM READ

Random read operations allow the master to access any memory location in a random manner. Prior to issuing the slave address with the  $R \overline{W}$  bit set to one, the master must first perform a "dummy" write operation. The master issues the start condition, slave address and then the byte address

it is to read. After the byte address acknowledge, the master immediately reissues the start condition and the slave address with the  $R\overline{\rm IW}$  bit set to one. This will be followed by an acknowledge from the NM24Cxx and then by the eight bit byte. The master will not acknowledge the transfer but does generate the stop condition, and therefore the NM24Cxx discontinues transmission. Refer to Figure 9 for the address, acknowledge and data transfer sequence.

#### SEQUENTIAL READ

Sequential reads can be initiated as either a current address read or random address read. The first byte is transmitted in the same manner as the other read modes; however, the master now responds with an acknowledge, indicating it requires additional data. The NM24Cxx continues to output data for each acknowledge received. The read operation is terminated by the master not responding with an acknowledge or by generating a stop condition.

The data output is sequential, with the data from address n followed by the data from n + 1. The address counter for read operations increments all byte address bits, allowing the entire memory contents to be serially read during one operation. After the entire memory has been read, the counter "rolls over" and the NM24Cxx continues to output data for each acknowledge received. Refer to Figure~10 for the address, acknowledge, and data transfer sequence.

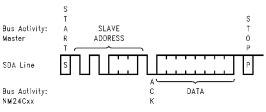
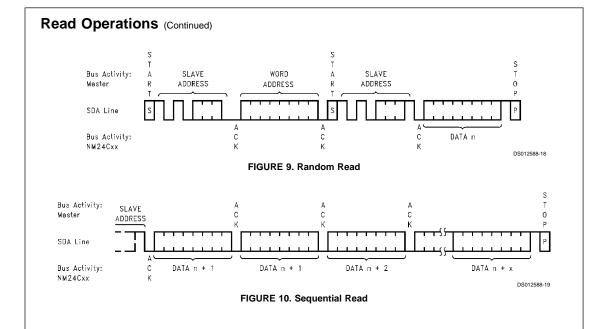


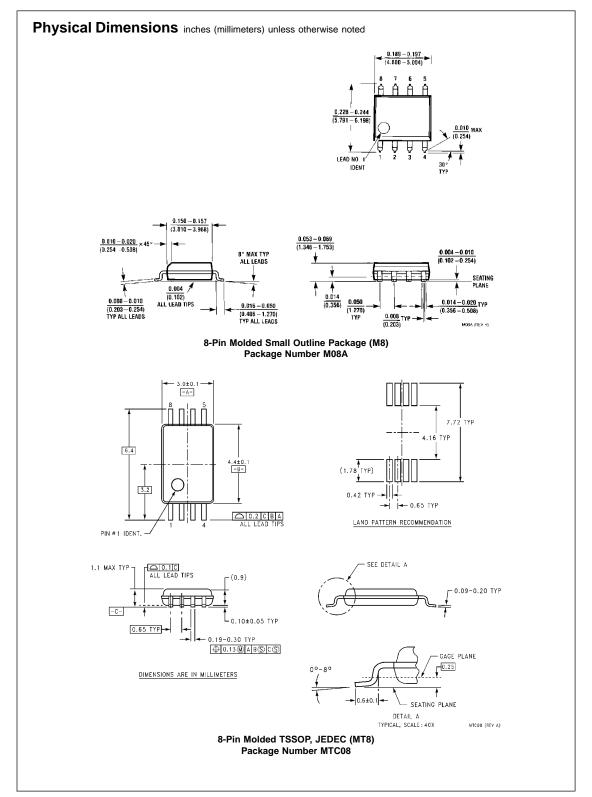
FIGURE 8. Current Address Read

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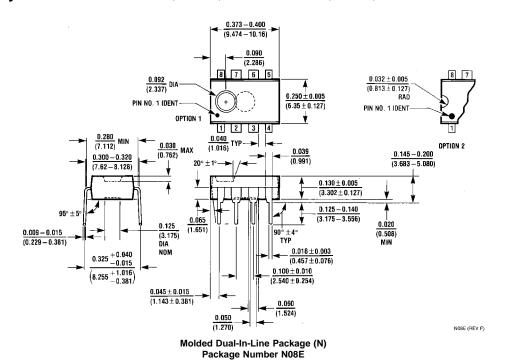
Book Extract End



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## Physical Dimensions inches (millimeters) unless otherwise noted (Continued)



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