

EVALUATION KIT  
AVAILABLE

MAX1280/MAX1281

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

## General Description

The MAX1280/MAX1281 12-bit ADCs combine an 8-channel analog-input multiplexer, high-bandwidth track/hold, and serial interface with high conversion speed and low power consumption. The MAX1280 operates from a single +4.5V to +5.5V supply; the MAX1281 operates from a single +2.7V to +3.6V supply. Both devices' analog inputs are software configurable for unipolar/bipolar and single-ended/pseudo-differential operation.

The 4-wire serial interface connects directly to SPI™/QSPI™/MICROWIRE™ devices without external logic. A serial strobe output allows direct connection to TMS320-family digital signal processors. The MAX1280/MAX1281 use an external serial-interface clock to perform successive-approximation analog-to-digital conversions. Both parts feature an internal +2.5V reference and a reference-buffer amplifier with a  $\pm 1.5\%$  voltage-adjustment range. An external reference with a 1V to V<sub>DD1</sub> range may also be used.

The MAX1280/MAX1281 provide a hard-wired  $\overline{\text{SHDN}}$  pin and four software-selectable power modes (normal operation, reduced power, fast power-down, and full power-down). These devices can be programmed to automatically shut down at the end of a conversion or to operate with reduced power. When using the power-down modes, accessing the serial interface automatically powers up the devices, and the quick turn-on time allows them to be powered down between all conversions. This technique can cut supply current to under 100 $\mu$ A at reduced sampling rates.

The MAX1280/MAX1281 are available in 20-pin TSSOP packages. These devices are higher-speed versions of the MAX146/MAX147 (for more information, see the respective data sheet).

## Applications

Portable Data Logging  
Data Acquisition  
Medical Instruments  
Battery-Powered Instruments  
Pen Digitizers  
Process Control

SPI and QSPI are trademarks of Motorola, Inc.

MICROWIRE is a trademark of National Semiconductor Corp.



## Features

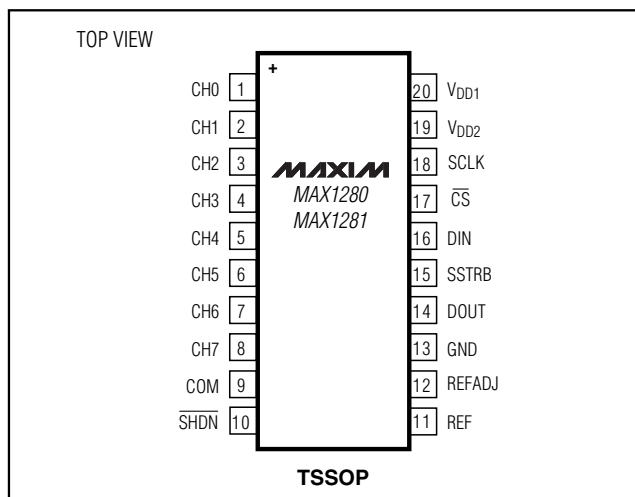
- ◆ 8-Channel Single-Ended or 4-Channel Pseudo-Differential Inputs
- ◆ Internal Multiplexer and Track/Hold
- ◆ Single-Supply Operation
  - +4.5V to +5.5V (MAX1280)
  - +2.7V to +3.6V (MAX1281)
- ◆ Internal +2.5V Reference
- ◆ 400ksps Sampling Rate (MAX1280)
- ◆ Low Power 2.5mA (400ksps)
  - 1.3mA (Reduced-Power Mode)
  - 0.9mA (Fast Power-Down Mode)
  - 2 $\mu$ A (Full Power-Down)
- ◆ SPI/QSPI/MICROWIRE/TMS320-Compatible 4-Wire Serial Interface
- ◆ Software-Configurable Unipolar or Bipolar Inputs
- ◆ 20-Pin TSSOP Package

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	INL (LSB)
MAX1280BCUP+	0°C to +70°C	20 TSSOP	$\pm 1$
MAX1280BEUP+	-40°C to +85°C	20 TSSOP	$\pm 1$
MAX1281BCUP+	0°C to +70°C	20 TSSOP	$\pm 1$
MAX1281BEUP+	-40°C to +85°C	20 TSSOP	$\pm 1$

+Denotes a lead(Pb)-free/RoHS-compliant package.

## Pin Configuration



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## ABSOLUTE MAXIMUM RATINGS

$V_{DD_1}$ to GND .....	-0.3V to +6V	20-Pin TSSOP (derate 7.0mW/°C above +70°C) .....	559mW
$V_{DD1}$ to $V_{DD2}$ .....	-0.3V to +0.3V	Operating Temperature Ranges	
CH0–CH7, COM to GND .....	-0.3V to ( $V_{DD1}$ + 0.3V)	MAX128_BCUP .....	0°C to +70°C
REF, REFADJ to GND .....	-0.3V to ( $V_{DD1}$ + 0.3V)	MAX128_BEUP .....	-40°C to +85°C
Digital Inputs to GND .....	-0.3V to +6V	Storage Temperature Range .....	-60°C to +150°C
Digital Outputs to GND .....	-0.3V to ( $V_{DD2}$ + 0.3V)	Lead Temperature (soldering, 10s) .....	+300°C
Digital Output Sink Current .....	25mA	Soldering Temperature (reflow) .....	+260°C
Continuous Power Dissipation ( $T_A$ = +70°C)			

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS—MAX1280

( $V_{DD1}$  =  $V_{DD2}$  = +4.5V to +5.5V, COM = GND,  $f_{SCLK}$  = 6.4MHz, 50% duty cycle, 16 clocks/conversion cycle (400ksps), external +2.5V at REF, REFADJ =  $V_{DD1}$ ,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A$  = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>DC ACCURACY</b> (Note 1)						
Resolution			12			Bits
Relative Accuracy (Note 2)	INL				±1.0	LSB
Differential Nonlinearity	DNL	No missing codes over temperature			±1.0	LSB
Offset Error					±6.0	LSB
Gain Error (Note 3)					±7.0	LSB
Gain-Error Temperature Coefficient				±0.8		ppm/°C
Channel-to-Channel Offset-Error Matching				±0.1		LSB
<b>DYNAMIC SPECIFICATIONS</b> (100kHz sine-wave input, 2.5Vp-p, 400ksps, 6.4MHz clock, bipolar input mode)						
Signal-to-Noise plus Distortion Ratio	SINAD			70		dB
Total Harmonic Distortion	THD	Up to the 5th harmonic		-81		dB
Spurious-Free Dynamic Range	SFDR			80		dB
Intermodulation Distortion	IMD	$f_{IN1}$ = 99kHz, $f_{IN2}$ = 102kHz		76		dB
Channel-to-Channel Crosstalk (Note 4)		$f_{IN}$ = 200kHz, $V_{IN}$ = 2.5Vp-p		-78		dB
Full-Power Bandwidth		-3dB point		6		MHz
Full-Linear Bandwidth		SINAD > 68dB		350		kHz
<b>CONVERSION RATE</b>						
Conversion Time (Note 5)	$t_{CONV}$		2.5			μs
Track/Hold Acquisition Time	$t_{ACQ}$				468	ns
Aperture Delay				10		ns
Aperture Jitter				<50		ps
Serial Clock Frequency	$f_{SCLK}$		0.5		6.4	MHz
Duty Cycle			40		60	%

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## ELECTRICAL CHARACTERISTICS—MAX1280 (continued)

( $V_{DD1} = V_{DD2} = +4.5V$  to  $+5.5V$ ,  $COM = GND$ ,  $f_{SCLK} = 6.4MHz$ , 50% duty cycle, 16 clocks/conversion cycle (400ksps), external  $+2.5V$  at REF,  $REFADJ = V_{DD1}$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
ANALOG INPUTS (CH7–CH0, COM)						
Input Voltage Range, Single-Ended and Differential (Note 6)	VCH_	Unipolar, VCOM = 0	VREF			V
		Bipolar, VCOM or VCH_ = VREF/2, referenced to COM or CH_	±VREF/2			
Multiplexer Leakage Current		On/off leakage current, VCH_ = 0 or VDD1	±0.001	±1		µA
Input Capacitance			18			pF
INTERNAL REFERENCE						
REF Output Voltage	VREF	TA = +25°C	2.480	2.500	2.520	V
REF Short-Circuit Current			30			mA
REF Output Temperature Coefficient	TC VREF		±15			ppm/°C
Load Regulation (Note 7)		0 to 1mA output load	0.1	2.0		mV/mA
Capacitive Bypass at REF			4.7	10		µF
Capacitive Bypass at REFADJ			0.01	10		µF
REFADJ Output Voltage			1.22			V
REFADJ Input Range		For small adjustments, from 1.22V	±50			mV
REFADJ Buffer Disable Threshold		To power down the internal reference	1.33	VDD1		V
Buffer Voltage Gain			2.05			V/V
EXTERNAL REFERENCE (Reference buffer disabled, reference applied to REF)						
REF Input Voltage Range		(Note 8)	1.0	VDD1 + 50mV		V
REF Input Current		VREF = 2.500V, fSCLK = 6.4MHz	200	350		µA
		VREF = 2.500V, fSCLK = 0		320		
		In power-down, fSCLK = 0		5		
DIGITAL INPUTS (DIN, SCLK, CS, SHDN)						
Input High Voltage	VINH		3.0			V
Input Low Voltage	VINL			0.8		V
Input Hysteresis	VHYST		0.2			V
Input Leakage	IIN	VIN = 0 or VDD2		±1		µA
Input Capacitance	CIN		15			pF
DIGITAL OUTPUTS (DOUT, SSTRB)						
Output Voltage Low	VOL	ISINK = 5mA		0.4		V
Output Voltage High	VOH	ISOURCE = 1mA	4			V
Three-State Leakage Current	IL	CS = 5V		±10		µA
Three-State Output Capacitance	COUT	CS = 5V	15			pF

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## ELECTRICAL CHARACTERISTICS—MAX1280 (continued)

( $V_{DD1} = V_{DD2} = +4.5V$  to  $+5.5V$ ,  $COM = GND$ ,  $f_{SCLK} = 6.4MHz$ , 50% duty cycle, 16 clocks/conversion cycle (400ksps), external  $+2.5V$  at REF,  $REFADJ = V_{DD1}$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
POWER SUPPLY							
Positive Supply Voltage (Note 9)	V <sub>DD1</sub> , V <sub>DD2</sub>			4.5		5.5	V
Supply Current	I <sub>VDD1</sub> + I <sub>VDD2</sub>	V <sub>DD1</sub> = V <sub>DD2</sub> = 5.5V	Operating mode (Note 10)		2.5	4.0	mA
			Reduced-power mode (Note 11)		1.3	2.0	
			Fast power-down (Note 11)		0.9	1.5	
			Full power-down (Note 11)		2	10	μA
Power-Supply Rejection	PSR	V <sub>DD1</sub> = V <sub>DD2</sub> = 5V ±10%, midscale input			±0.5	±2.0	mV

## ELECTRICAL CHARACTERISTICS—MAX1281

( $V_{DD1} = V_{DD2} = +2.7V$  to  $+3.6V$ ,  $COM = GND$ ,  $f_{SCLK} = 4.8MHz$ , 50% duty cycle, 16 clocks/conversion cycle (300ksps), external  $+2.5V$  at REF,  $REFADJ = V_{DD1}$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>DC ACCURACY</b> (Note 1)						
Resolution			12			Bits
Relative Accuracy (Note 2)	INL				$\pm 1.0$	LSB
Differential Nonlinearity	DNL	No missing codes over temperature			$\pm 1.0$	LSB
Offset Error					$\pm 6.0$	LSB
Gain Error (Note 3)					$\pm 7.0$	LSB
Gain-Error Temperature Coefficient				$\pm 1.6$		ppm/ $^{\circ}C$
Channel-to-Channel Offset-Error Matching				$\pm 0.2$		LSB
<b>DYNAMIC SPECIFICATIONS</b> (75kHz sine-wave input, 2.5Vp-p, 300ksps, 4.8MHz clock, bipolar input mode)						
Signal-to-Noise plus Distortion Ratio	SINAD			70		dB
Total Harmonic Distortion	THD	Up to the 5th harmonic		-81		dB
Spurious-Free Dynamic Range	SFDR			80		dB
Intermodulation Distortion	IMD	$f_{IN1} = 73kHz$ , $f_{IN2} = 77kHz$		76		dB
Channel-to-Channel Crosstalk (Note 4)		$f_{IN} = 150kHz$ , $V_{IN} = 2.5Vp-p$		-78		dB
Full-Power Bandwidth		-3dB point		3		MHz
Full-Linear Bandwidth		SINAD $> 68dB$		250		kHz

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

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## ELECTRICAL CHARACTERISTICS—MAX1281 (continued)

(V<sub>DD1</sub> = V<sub>DD2</sub> = +2.7V to +3.6V, COM = GND, f<sub>SCLK</sub> = 4.8MHz, 50% duty cycle, 16 clocks/conversion cycle (300ksps), external +2.5V at REF, REFADJ = V<sub>DD1</sub>, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
CONVERSION RATE							
Conversion Time (Note 5)	tCONV	Normal operating mode	3.3			μs	
Track/Hold Acquisition Time	tACQ	Normal operating mode	625			ns	
Aperture Delay			10			ns	
Aperture Jitter			< 50			ps	
Serial Clock Frequency	fSCLK	Normal operating mode	0.5	4.8		MHz	
Duty Cycle			40	60		%	
ANALOG INPUTS (CH7–CH0, COM)							
Input Voltage Range, Single-Ended and Differential (Note 6)	VCH_	Unipolar, VCOM = 0	VREF			V	
		Bipolar, VCOM or VCH_ = VREF/2, referenced to COM or CH_	±VREF/2				
Multiplexer Leakage Current		On/off leakage current, VCH_ = 0 or VDD1	±0.001	±1	μA		
Input Capacitance			18			pF	
INTERNAL REFERENCE							
REF Output Voltage	VREF	TA = +25°C	2.480	2.500	2.520	V	
REF Short-Circuit Current			15			mA	
REF Output Temperature Coefficient	TC VREF		±15			ppm/°C	
Load Regulation (Note 7)		0 to 0.75mA output load	0.1			2.0	mV/mA
Capacitive Bypass at REF			4.7	10		μF	
Capacitive Bypass at REFADJ			0.01	10		μF	
REFADJ Output Voltage			1.22			V	
REFADJ Input Range		For small adjustments, from 1.22V	±50			mV	
REFADJ Buffer Disable Threshold		To power down the internal reference	1.33	VDD1 - 1		V	
Buffer Voltage Gain			2.05			V/V	
EXTERNAL REFERENCE (Reference buffer disabled, reference applied to REF)							
REF Input Voltage Range		(Note 8)	1.0	VDD1 + 50mV		V	
REF Input Current		VREF = 2.500V, fSCLK = 4.8MHz	200	350		μA	
		VREF = 2.500V, fSCLK = 0	320				
		In power-down, fSCLK = 0	5				
DIGITAL INPUTS (DIN, SCLK, CS, SHDN)							
Input High Voltage	VINH		2.0			V	
Input Low Voltage	VINL		0.8			V	
Input Hysteresis	VHYST		0.2			V	
Input Leakage	IIN	VIN = 0 or VDD2	±1			μA	
Input Capacitance	CIN		15			pF	

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

## ELECTRICAL CHARACTERISTICS—MAX1281 (continued)

( $V_{DD1} = V_{DD2} = +2.7V$  to  $+3.6V$ ,  $COM = GND$ ,  $f_{SCLK} = 4.8MHz$ , 50% duty cycle, 16 clocks/conversion cycle (300ksps), external  $+2.5V$  at REF,  $REFADJ = V_{DD1}$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DIGITAL OUTPUTS (DOUT, SSTRB)							
Output Voltage Low	VOL	ISINK = 5mA				0.4	V
Output Voltage High	VOH	ISOURCE = 0.5mA		VDD2 - 0.5V			V
Three-State Leakage Current	IL	CS = 3V				±10	μA
Three-State Output Capacitance	COUT	CS = 3V			15		pF
POWER SUPPLY							
Positive Supply Voltage (Note 9)	VDD1, VDD2			2.7		3.6	V
Supply Current (Note 10)	IVDD1 + IVDD2	VDD1 = VDD2 = 3.6V	Operating mode		2.5	3.5	mA
			Reduced-power mode (Note 11)		1.3	2.0	
			Fast power-down (Note 11)		0.9	1.5	
			Full power-down (Note 11)		2	10	μA
Power-Supply Rejection	PSR	VDD1 = VDD2 = 2.7V to 3.6V, midscale input			±0.5	±2.0	mV

## TIMING CHARACTERISTICS—MAX1280

(Figures 1, 2, 6, 7;  $V_{DD1} = V_{DD2} = +4.5V$  to  $+5.5V$ ;  $T_A = T_{MIN}$  to  $T_{MAX}$ ; unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Period	$t_{CP}$		156			ns
SCLK Pulse Width High	$t_{CH}$		62			ns
SCLK Pulse Width Low	$t_{CL}$		62			ns
DIN to SCLK Setup	$t_{DS}$		35			ns
DIN to SCLK Hold	$t_{DH}$		0			ns
$\overline{CS}$ Fall to SCLK Rise Setup	$t_{CSS}$		35			ns
SCLK Rise to $\overline{CS}$ Rise Hold	$t_{CSH}$		0			ns
SCLK Rise to $\overline{CS}$ Fall Ignore	$t_{CSO}$		35			ns
$\overline{CS}$ Rise to SCLK Rise Ignore	$t_{CS1}$		35			ns
SCLK Rise to DOUT Hold	$t_{DOH}$	$C_{LOAD} = 20pF$	10	20		ns
SCLK Rise to SSTRB Hold	$t_{STH}$	$C_{LOAD} = 20pF$	10	20		ns
SCLK Rise to DOUT Valid	$t_{DOV}$	$C_{LOAD} = 20pF$			80	ns
SCLK Rise to SSTRB Valid	$t_{STV}$	$C_{LOAD} = 20pF$			80	ns
$\overline{CS}$ Rise to DOUT Disable	$t_{DOD}$	$C_{LOAD} = 20pF$	10		65	ns
$\overline{CS}$ Rise to SSTRB Disable	$t_{STD}$	$C_{LOAD} = 20pF$	10		65	ns
$\overline{CS}$ Fall to DOUT Enable	$t_{DOE}$	$C_{LOAD} = 20pF$			65	ns
$\overline{CS}$ Fall to SSTRB Enable	$t_{STE}$	$C_{LOAD} = 20pF$			65	ns
$\overline{CS}$ Pulse Width High	$t_{CSW}$		100			ns

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## TIMING CHARACTERISTICS—MAX1281

(Figures 1, 2, 6, 7;  $V_{DD1} = V_{DD2} = +2.7V$  to  $+3.6V$ ;  $T_A = T_{MIN}$  to  $T_{MAX}$ ; unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Period	$t_{CP}$		208			ns
SCLK Pulse Width High	$t_{CH}$		83			ns
SCLK Pulse Width Low	$t_{CL}$		83			ns
DIN to SCLK Setup	$t_{DS}$		45			ns
DIN to SCLK Hold	$t_{DH}$		0			ns
$\overline{CS}$ Fall to SCLK Rise Setup	$t_{CSS}$		45			ns
SCLK Rise to $\overline{CS}$ Rise Hold	$t_{CSH}$		0			ns
SCLK Rise to $\overline{CS}$ Fall ignore	$t_{CSO}$		45			ns
$\overline{CS}$ Rise to SCLK Rise Ignore	$t_{CS1}$		45			ns
SCLK Rise to DOUT Hold	$t_{DOH}$	$C_{LOAD} = 20pF$	13	20		ns
SCLK Rise to SSTRB Hold	$t_{STH}$	$C_{LOAD} = 20pF$	1	20		ns
SCLK Rise to DOUT Valid	$t_{DOV}$	$C_{LOAD} = 20pF$			100	ns
SCLK Rise to SSTRB Valid	$t_{STV}$	$C_{LOAD} = 20pF$			100	ns
$\overline{CS}$ Rise to DOUT Disable	$t_{DOD}$	$C_{LOAD} = 20pF$	13		85	ns
$\overline{CS}$ Rise to SSTRB Disable	$t_{STD}$	$C_{LOAD} = 20pF$	13		85	ns
$\overline{CS}$ Fall to DOUT Enable	$t_{DOE}$	$C_{LOAD} = 20pF$			85	ns
$\overline{CS}$ Fall to SSTRB Enable	$t_{STE}$	$C_{LOAD} = 20pF$			85	ns
$\overline{CS}$ Pulse Width High	$t_{CSW}$		100			ns

**Note 1:** MAX1280 tested at  $V_{DD1} = V_{DD2} = +5V$ , MAX1281 tested at  $V_{DD1} = V_{DD2} = +3V$ ; COM = GND; unipolar single-ended input mode.

**Note 2:** Relative accuracy is the deviation of the analog value at any code from its theoretical value after the gain error and offset error have been nulled.

**Note 3:** Offset nulled.

**Note 4:** Ground “on” channel; sine wave applied to all “off” channels.

**Note 5:** Conversion time is defined as the number of clock cycles multiplied by the clock period; clock has 50% duty cycle.

**Note 6:** The absolute voltage range for the analog inputs (CH7–CH0, and COM) is from GND to  $V_{DD1}$ .

**Note 7:** External load should not change during conversion for specified accuracy. Guaranteed specification of 2mV/mA is a result of production test limitations.

**Note 8:** ADC performance is limited by the converter’s noise floor, typically 300 $\mu$ Vp-p.

**Note 9:** Electrical characteristics are guaranteed from  $V_{DD1(MIN)} = V_{DD2(MIN)}$  to  $V_{DD1(MAX)} = V_{DD2(MAX)}$ . For operations beyond this range, see the *Typical Operating Characteristics*. For guaranteed specifications beyond the limits, contact the factory.

**Note 10:**  $A_{IN}$  = midscale. Unipolar mode. MAX1280 tested with 20pF on DOUT, 20pF on SSTRB, and  $f_{SCLK} = 6.4MHz$ , 0 to 5V. MAX1281 tested with same loads,  $f_{SCLK} = 4.8MHz$ , 0 to 3V. DOUT = FFF hex.

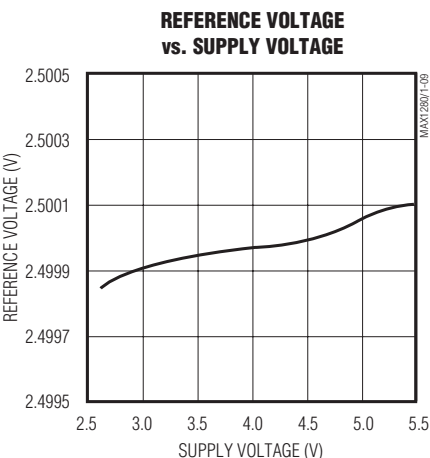
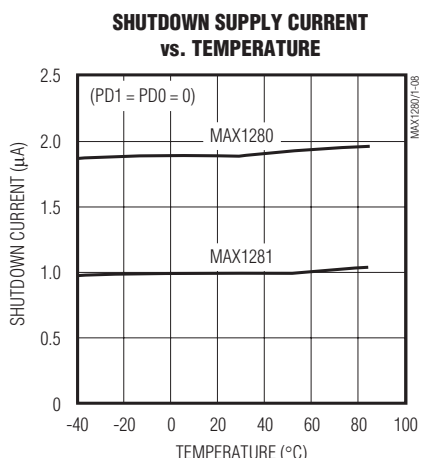
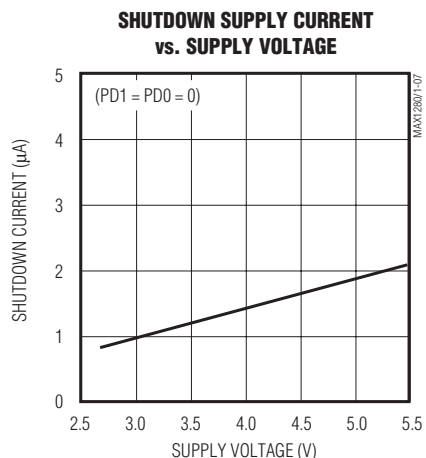
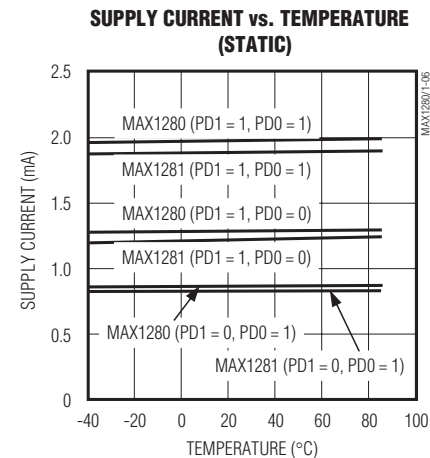
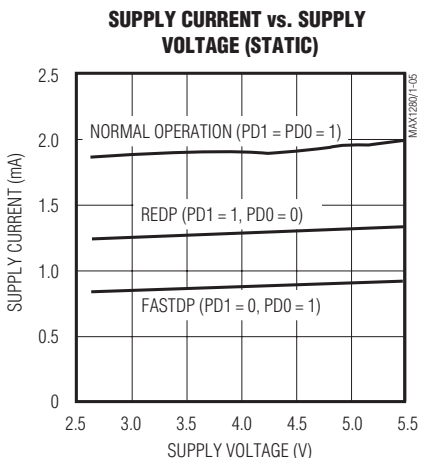
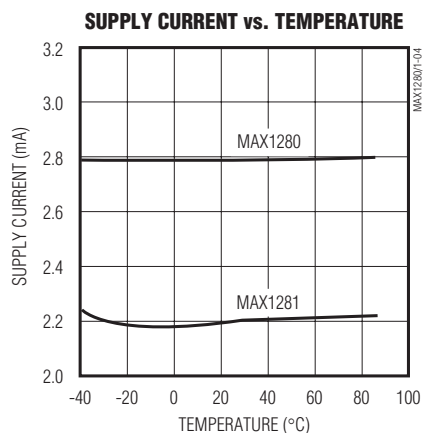
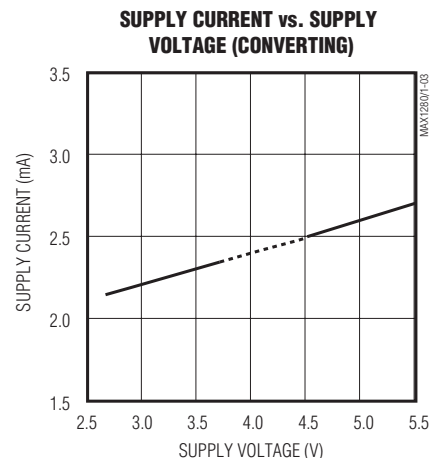
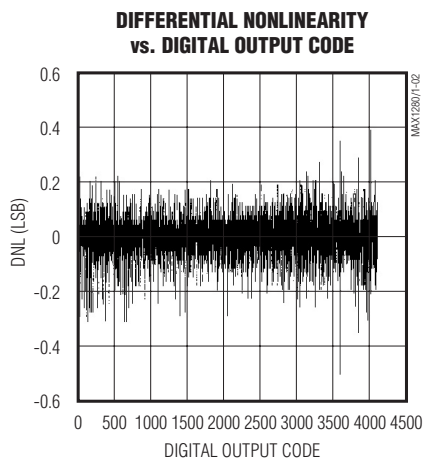
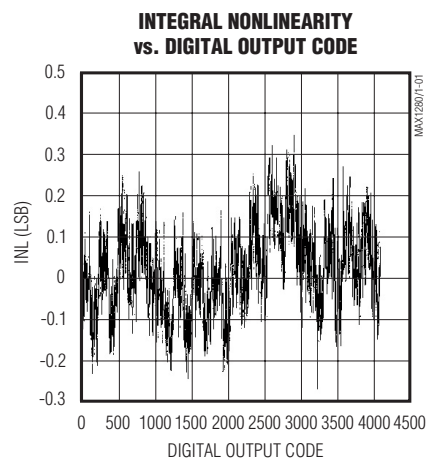
**Note 11:**

PD1	PD0	MODE
0	0	Full power-down.
0	1	Fast power-down.
1	0	Reduced power mode.
1	1	Normal operation (operating mode).

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

## Typical Operating Characteristics

(MAX1280:  $V_{DD1} = V_{DD2} = 5.0V$ ,  $f_{SCLK} = 6.4MHz$ ; MAX1281:  $V_{DD1} = V_{DD2} = 3.0V$ ,  $f_{SCLK} = 4.8MHz$ ;  $C_{LOAD} = 20pF$ ,  $4.7\mu F$  capacitor at REF,  $0.01\mu F$  capacitor at REFADJ,  $T_A = +25^\circ C$ , unless otherwise noted.)



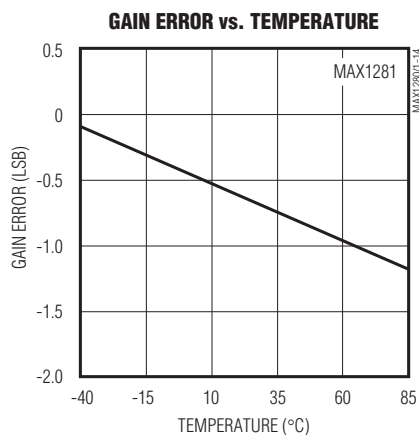
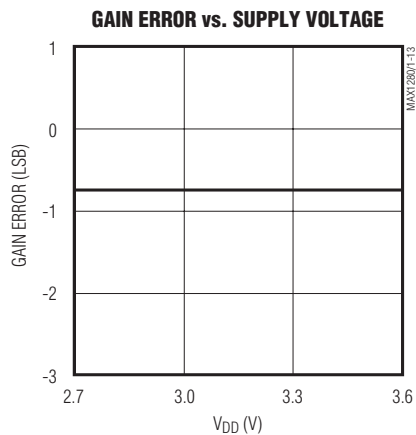
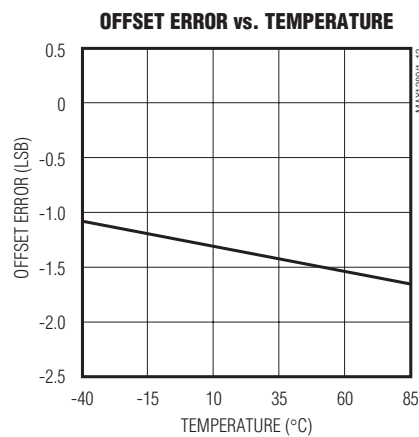
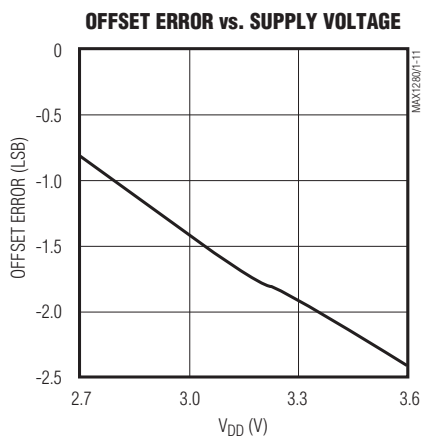
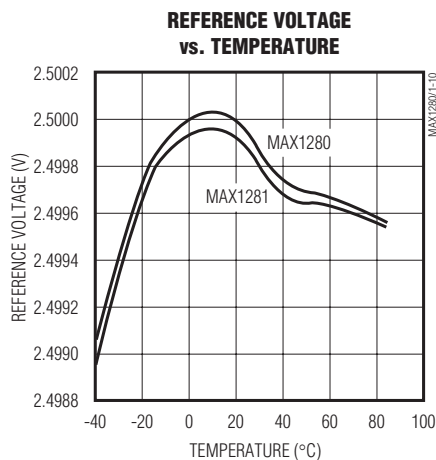


# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

MAX1280/MAX1281

## Typical Operating Characteristics (continued)

(MAX1280:  $V_{DD1} = V_{DD2} = 5.0V$ ,  $f_{SCLK} = 6.4MHz$ ; MAX1281:  $V_{DD1} = V_{DD2} = 3.0V$ ,  $f_{SCLK} = 4.8MHz$ ;  $C_{LOAD} = 20pF$ ,  $4.7\mu F$  capacitor at REF,  $0.01\mu F$  capacitor at REFADJ,  $T_A = +25^\circ C$ , unless otherwise noted.)



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## Pin Description

PIN	NAME	FUNCTION
1–8	CH0–CH7	Sampling Analog Inputs
9	COM	Ground Reference for Analog Inputs. COM sets zero-code voltage in single-ended mode. Must be stable to $\pm 0.5\text{LSB}$ .
10	$\overline{\text{SHDN}}$	Active-Low Shutdown Input. Pulling $\overline{\text{SHDN}}$ low shuts down the device, reducing supply current to $2\mu\text{A}$ (typ).
11	REF	Reference-Buffer Output/ADC Reference Input. Reference voltage for analog-to-digital conversion. In internal reference mode, the reference buffer provides a $+2.500\text{V}$ nominal output, externally adjustable at REFADJ. In external reference mode, disable the internal buffer by pulling REFADJ to $V_{\text{DD1}}$ .
12	REFADJ	Input to the Reference-Buffer Amplifier. To disable the reference-buffer amplifier, tie REFADJ to $V_{\text{DD1}}$ .
13	GND	Analog and Digital Ground
14	DOUT	Serial Data Output. Data is clocked out at SCLK's rising edge. High impedance when $\overline{\text{CS}}$ is high.
15	SSTRB	Serial Strobe Output. SSTRB pulses high for one clock period before the MSB decision. High impedance when $\overline{\text{CS}}$ is high.
16	DIN	Serial Data Input. Data is clocked in at SCLK's rising edge.
17	$\overline{\text{CS}}$	Active-Low Chip Select. Data will not be clocked into DIN unless $\overline{\text{CS}}$ is low. When $\overline{\text{CS}}$ is high, DOUT and SSTRB are high impedance.
18	SCLK	Serial Clock Input. Clocks data in and out of the serial interface and sets the conversion speed. (Duty cycle must be 40% to 60%.)
19	$V_{\text{DD2}}$	Positive Supply Voltage
20	$V_{\text{DD1}}$	Positive Supply Voltage

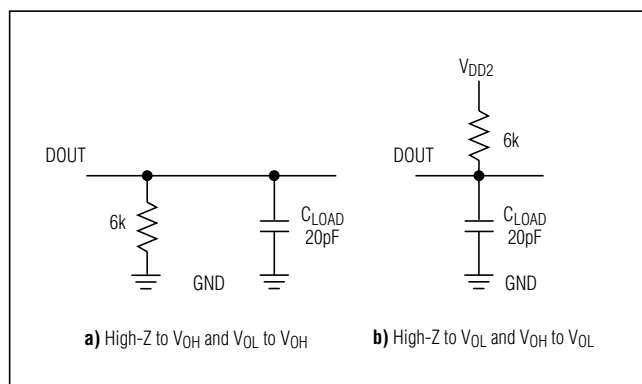


Figure 1. Load Circuits for Enable Time

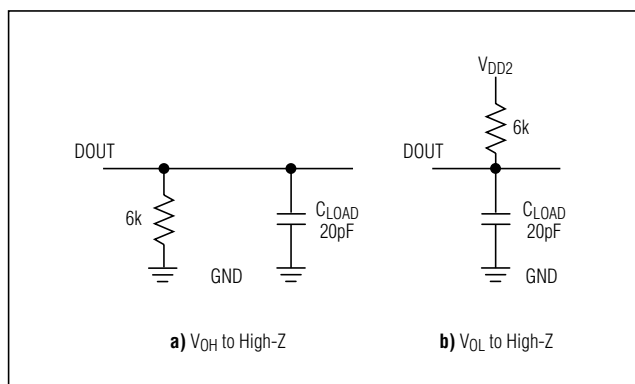


Figure 2. Load Circuits for Disable Time

**MAX1280/MAX1281**

### Detailed Description

The MAX1280/MAX1281 analog-to-digital converters (ADCs) use a successive-approximation conversion technique and input track/hold (T/H) circuitry to convert an analog signal to a 12-bit digital output. A flexible serial interface provides easy interface to microprocessors ( $\mu$ Ps). Figure 3 shows a functional diagram of the MAX1280/MAX1281.

## Pseudo-Differential Input

The equivalent input circuit of Figure 4 shows the MAX1280/MAX1281's input architecture, which is composed of a T/H, input multiplexer, input comparator, switched-capacitor DAC, and reference.

In single-ended mode, the positive input (IN+) is connected to the selected input channel and the negative input (IN-) is set to COM. In differential mode, IN+ and IN- are selected from the following pairs: CH0/CH1, CH2/CH3, CH4/CH5, and CH6/CH7. Configure the channels according to Tables 2 and 3.

The MAX1280/MAX1281 input configuration is pseudo-differential in that only the signal at IN+ is sampled. The return side (IN-) is connected to the sampling capacitor while converting and must remain stable within  $\pm 0.5\text{LSB}$  ( $\pm 0.1\text{LSB}$  for best results) with respect to GND during a conversion.

If a varying signal is applied to the selected IN-, its amplitude and frequency must be limited to maintain accuracy. The following equations determine the relationship between the maximum signal amplitude and its frequency

in order to maintain  $\pm 0.5\text{LSB}$  accuracy. Assuming a sinusoidal signal at  $\text{IN-}$ , the input voltage is determined by:

$$v_{|N-} = (V_{|N-}) \sin(2\pi f t)$$

The maximum voltage variation is determined by:

$$\max \frac{dv_{IN-}}{dt} = (V_{IN-}) 2\pi f \leq \frac{1\text{LSB}}{t_{\text{CONV}}} = \frac{V_{\text{REF}}}{2^{12} t_{\text{CONV}}}$$

A 650mVp-p 60Hz signal at IN- will generate  $\pm 0.5$ LSB of error when using a +2.5V reference voltage and a 2.5 $\mu$ s conversion time ( $15/f_{\text{SCLK}}$ ). When a DC reference voltage is used at IN-, connect a 0.1 $\mu$ F capacitor to GND to minimize noise at the input.

During the acquisition interval, the channel selected as the positive input (IN+) charges capacitor CHOLD. The acquisition interval spans three SCLK cycles and ends on the falling SCLK edge after the last bit of the input control word has been entered. At the end of the acquisition interval, the T/H switch opens, retaining charge on CHOLD as a sample of the signal at IN+. The conversion interval begins with the input multiplexer switching CHOLD from IN+ to IN-. This unbalances node ZERO at the comparator's input. The capacitive DAC adjusts during the remainder of the conversion cycle to restore node ZERO to  $V_{DD1}/2$  within the limits of 12-bit resolution. This action is equivalent to transferring a  $12\text{pF} \times (V_{IN+} - V_{IN-})$  charge from CHOLD to the binary-weighted capacitive DAC, which in turn forms a digital representation of the analog input signal.

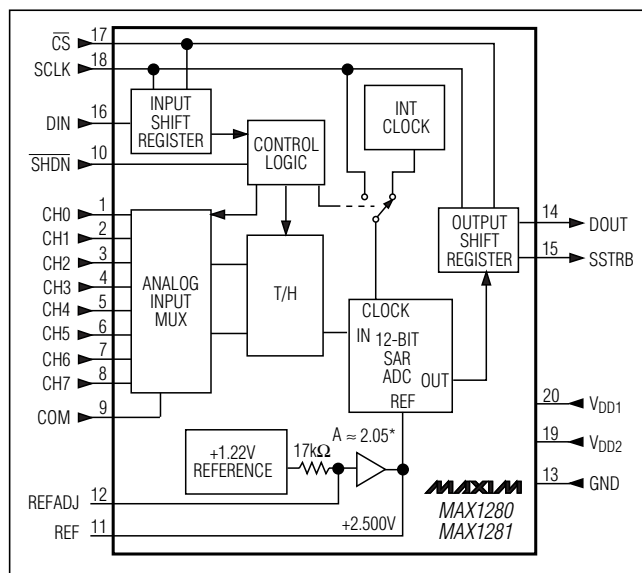


Figure 3. Functional Diagram

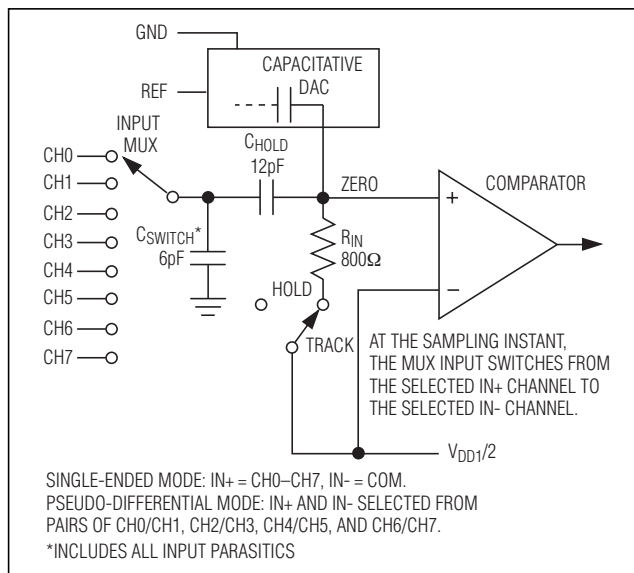


Figure 4. Equivalent Input Circuit

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## Track/Hold

The T/H enters its tracking mode on the falling clock edge after the fifth bit of the 8-bit control word has been shifted in. It enters its hold mode on the falling clock edge after the eighth bit of the control word has been shifted in. If the converter is set up for single-ended inputs, IN- is connected to COM and the converter converts the “+” input. If the converter is set up for differential inputs, the difference of [(IN+) - (IN-)] is converted. At the end of the conversion, the positive input connects back to IN+ and CHOLD charges to the input signal.

The time required for the T/H to acquire an input signal is a function of how quickly its input capacitance is charged. If the input signal's source impedance is high, the acquisition time lengthens, and more time must be allowed between conversions. The acquisition time,  $t_{ACQ}$ , is the maximum time the device takes to acquire the signal and is also the minimum time needed for the signal to be acquired. It is calculated by the following equation:

$$t_{ACQ} = 9 \times (R_S + R_{IN}) \times 12\text{pF}$$

where  $R_{IN} = 800\Omega$ ,  $R_S$  = the source impedance of the input signal;  $t_{ACQ}$  is never less than 468ns (MAX1280) or 625ns (MAX1281). Note that source impedances below  $2\text{k}\Omega$  do not significantly affect the ADC's AC performance.

## Input Bandwidth

The ADC's input tracking circuitry has a 6MHz (MAX1280) or 3MHz (MAX1281) small-signal bandwidth, so it is possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using under-sampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

## Analog Input Protection

Internal protection diodes, which clamp the analog input to  $V_{DD1}$  and GND, allow the channel input pins to swing from  $\text{GND} - 0.3\text{V}$  to  $V_{DD1} + 0.3\text{V}$  without damage. However, for accurate conversions near full scale, the inputs must not exceed  $V_{DD1}$  by more than 50mV or be lower than GND by 50mV.

**If the analog input exceeds 50mV beyond the supplies, do not allow the input current to exceed 2mA.**

## Quick Look

To quickly evaluate the MAX1280/MAX1281's analog performance, use the circuit of Figure 5. The MAX1280/MAX1281 require a control byte to be written to DIN before each conversion. Connecting DIN to  $V_{DD2}$  feeds in control bytes of \$FF (HEX), which trigger single-ended unipolar conversions on CH7 without powering down between conversions. The SSTRB output pulses

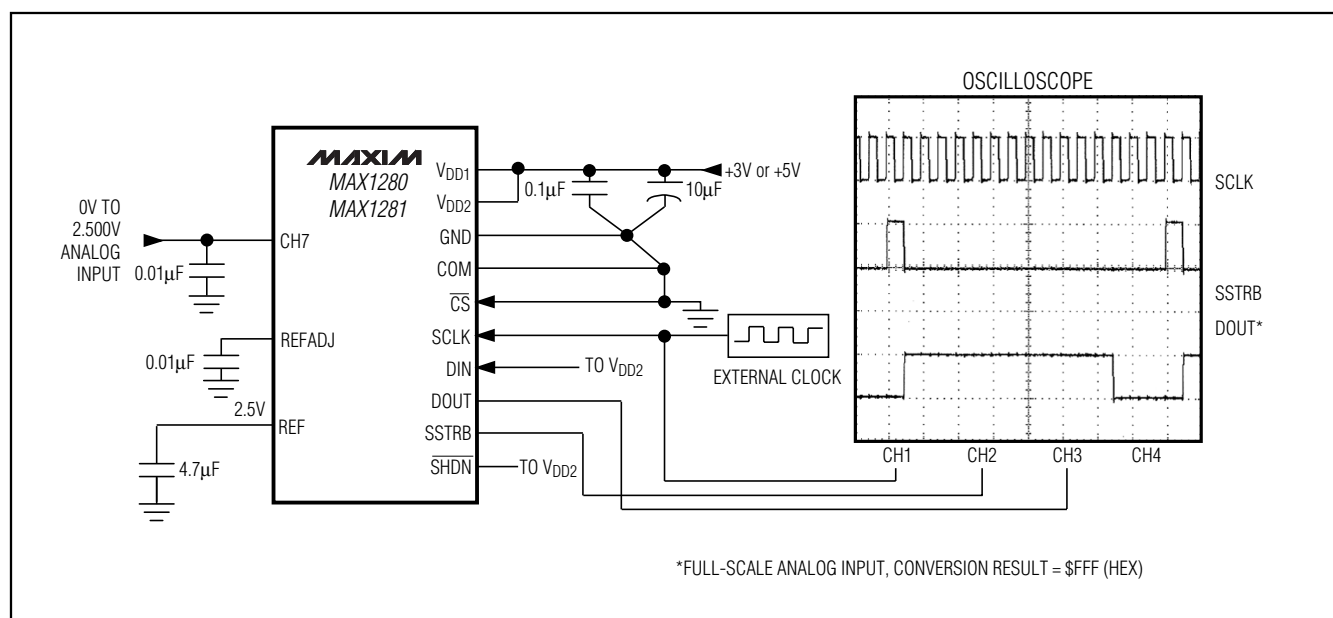


Figure 5. Quick-Look Circuit

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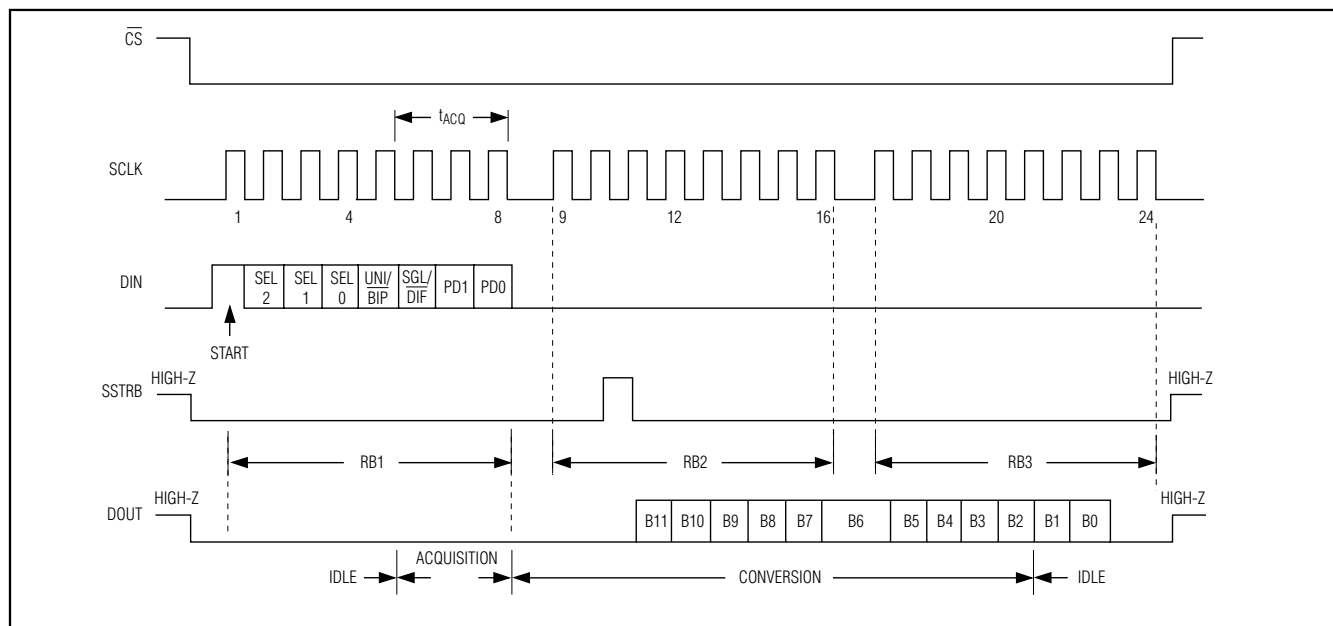


Figure 6. Single-Conversion Timing

high for one clock period before the MSB of the 12-bit conversion result is shifted out of DOUT. Varying the analog input to CH7 will alter the sequence of bits from DOUT. A total of 16 clock cycles is required per conversion. All transitions of the SSTRB and DOUT outputs typically occur 20ns after the rising edge of SCLK.

### Starting a Conversion

Start a conversion by clocking a control byte into DIN. With  $\overline{CS}$  low, each rising edge on SCLK clocks a bit from DIN into the MAX1280/MAX1281's internal shift register. After  $\overline{CS}$  falls, the first arriving logic "1" bit defines the control byte's MSB. Until this first "start" bit arrives, any number of logic "0" bits can be clocked into DIN with no effect. Table 1 shows the control-byte format.

The MAX1280/MAX1281 are compatible with SPI/QSPI and MICROWIRE devices. For SPI, select the correct clock polarity and sampling edge in the SPI control registers: set CPOL = 0 and CPHA = 0. MICROWIRE, SPI, and QSPI all transmit a byte and receive a byte at the same time. Using the *Typical Operating Circuit*, the simplest software interface requires only three 8-bit transfers to perform a conversion (one 8-bit transfer to configure the ADC, and two more 8-bit transfers to clock out the 12-bit conversion result). See Figure 17 for MAX1280/MAX1281 QSPI connections.

### Simple Software Interface

Make sure the CPU's serial interface runs in master mode, so the CPU generates the serial clock. Choose a

clock frequency from 500kHz to 6.4MHz (MAX1280) or 4.8MHz (MAX1281).

- 1) Set up the control byte and call it TB1. TB1 should be of the format 1XXXXXXX binary, where the Xs denote the particular channel, selected conversion mode, and power mode.
- 2) Use a general-purpose I/O line on the CPU to pull  $\overline{CS}$  low.
- 3) Transmit TB1 and, simultaneously, receive a byte and call it RB1. Ignore RB1.
- 4) Transmit a byte of all zeros (\$00 hex) and, simultaneously, receive byte RB2.
- 5) Transmit a byte of all zeros (\$00 hex) and, simultaneously, receive byte RB3.
- 6) Pull  $\overline{CS}$  high.

Figure 6 shows the timing for this sequence. Bytes RB2 and RB3 contain the result of the conversion, padded with three leading zeros and one trailing zero. The total conversion time is a function of the serial-clock frequency and the amount of idle time between 8-bit transfers. To avoid excessive T/H droop, make sure the total conversion time does not exceed 120 $\mu$ s.

### Digital Output

In unipolar input mode, the output is straight binary (Figure 14). For bipolar input mode, the output is two's complement (Figure 15). Data is clocked out on the rising edge of SCLK in MSB-first format.

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**Table 1. Control-Byte Format**

BIT 7 (MSB)	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0 (LSB)															
START	SEL2	SEL1	SEL0	UNI/BIP	SGL/DIF	PD1	PD0															
BIT	NAME	DESCRIPTION																				
7 (MSB)	START	The first logic “1” bit after $\overline{CS}$ goes low defines the beginning of the control byte.																				
6 5 4	SEL2 SEL1 SEL0	These three bits select which of the eight channels are used for the conversion (Tables 2 and 3).																				
3	UNI/BIP	1 = unipolar, 0 = bipolar. Selects unipolar or bipolar conversion mode. In unipolar mode, an analog input signal from 0 to $V_{REF}$ can be converted; in bipolar mode, the differential signal can range from $-V_{REF}/2$ to $+V_{REF}/2$ .																				
2	SGL/DIF	1 = single ended, 0 = differential. Selects single-ended or differential conversions. In single-ended mode, input signal voltages are referred to COM. In differential mode, the voltage difference between two channels is measured (Tables 2 and 3).																				
1 0 (LSB)	PD1 PD0	Select operating mode. <table><tr><th>PD1</th><th>PD0</th><th>Mode</th></tr><tr><td>0</td><td>0</td><td>Full power-down</td></tr><tr><td>0</td><td>1</td><td>Fast power-down</td></tr><tr><td>1</td><td>0</td><td>Reduced Power</td></tr><tr><td>1</td><td>1</td><td>Normal Operation</td></tr></table>						PD1	PD0	Mode	0	0	Full power-down	0	1	Fast power-down	1	0	Reduced Power	1	1	Normal Operation
PD1	PD0	Mode																				
0	0	Full power-down																				
0	1	Fast power-down																				
1	0	Reduced Power																				
1	1	Normal Operation																				

**Table 2. Channel Selection in Single-Ended Mode ( $SGL/\overline{DIF} = 1$ )**

SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7	COM
0	0	0	+								–
0	0	1			+						–
0	1	0					+				–
0	1	1							+		–
1	0	0		+							–
1	0	1				+					–
1	1	0						+			–
1	1	1								+	–

**Table 3. Channel Selection in Psuedo-Differential Mode ( $SGL/\overline{DIF} = 0$ )**

SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7
0	0	0	+	–						
0	0	1			+	–				
0	1	0					+	–		
0	1	1							+	–
1	0	0	–	+						
1	0	1			–	+				
1	1	0					–	+		
1	1	1							–	+

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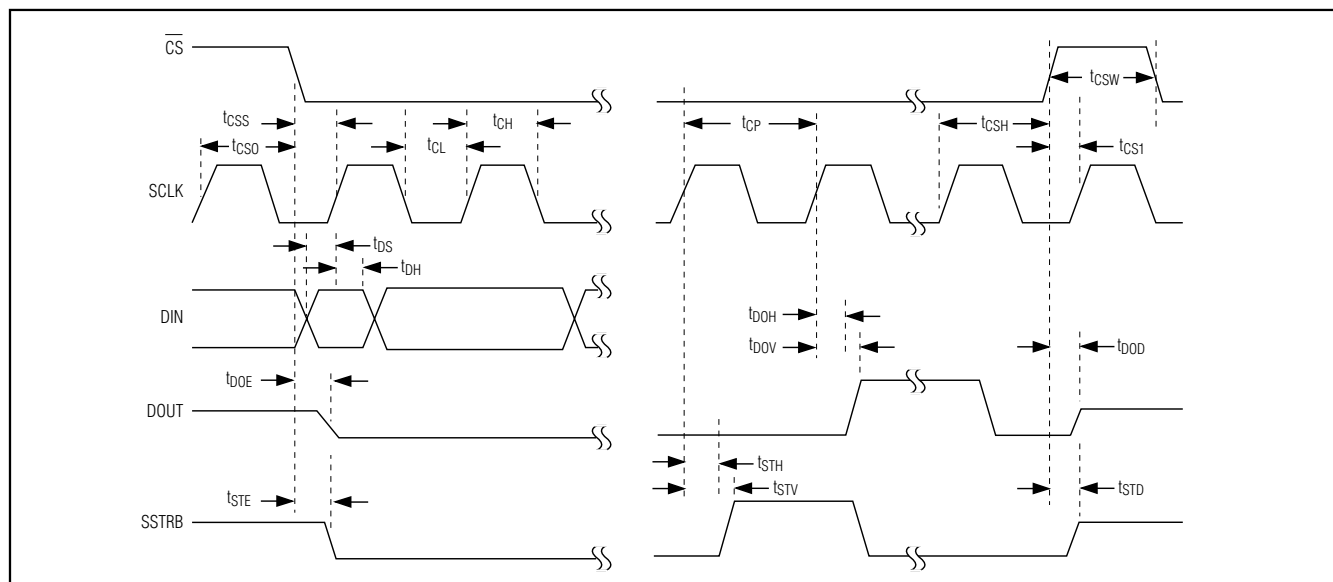


Figure 7. Detailed Serial-Interface Timing

### Serial Clock

The external serial clock not only shifts data in and out, but also drives the analog-to-digital conversion steps. SSTRB pulses high for one clock period after the last bit of the control byte. Successive-approximation bit decisions are made and appear at DOUT on each of the next 12 SCLK falling edges (Figure 6). SSTRB and DOUT go into a high-impedance state when  $\overline{CS}$  goes high; after the next  $\overline{CS}$  rising edge, SSTRB outputs a logic low. Figure 7 shows the detailed serial-interface timing.

The conversion must complete in 120 $\mu$ s or less, or droop on the sample-and-hold capacitors may degrade conversion results.

### Data Framing

The falling edge of  $\overline{CS}$  does **not** start a conversion. The first logic high clocked into DIN is interpreted as a start bit and defines the first bit of the control byte. A conversion starts on SCLK's falling edge after the eighth bit of the control byte (the PD0 bit) is clocked into DIN. The start bit is defined as follows:

The first high bit clocked into DIN with  $\overline{CS}$  low any time the converter is idle, e.g., after  $V_{DD1}$  and  $V_{DD2}$  are applied.

OR

The first high bit clocked into DIN after bit 6 of a conversion in progress is clocked onto the DOUT pin.

Once a start bit has been recognized, the current conversion may only be terminated by pulling  $\overline{SHDN}$  low.

The fastest the MAX1280/MAX1281 can run with  $\overline{CS}$  held low between conversions is 16 clocks per conversion. Figure 8 shows the serial-interface timing necessary to perform a conversion every 16 SCLK cycles. If  $\overline{CS}$  is tied low and SCLK is continuous, guarantee a start bit by first clocking in 16 zeros.

## Applications Information

### Power-On Reset

When power is first applied, and if  $\overline{SHDN}$  is not pulled low, internal power-on reset circuitry activates the MAX1280/MAX1281 in normal operating mode, ready to convert with SSTRB = low. The MAX1280/MAX1281 require 10 $\mu$ s to reset after the power supplies stabilize; no conversions should be initiated during this time. If  $\overline{CS}$  is low, the first logic 1 on DIN is interpreted as a start bit. Until a conversion takes place, DOUT shifts out zeros. Additionally, wait for the reference to stabilize when using the internal reference.

### Power Modes

You can save power by placing the converter in one of the two low-current operating modes or in full power-down between conversions. Select the power mode through bit 1 and bit 0 of the DIN control byte (Tables 1 and 4), or force the converter into hardware shutdown by driving  $\overline{SHDN}$  to GND.

The software power-down modes take effect after the conversion is completed;  $\overline{SHDN}$  overrides any software power mode and immediately stops any conversion in



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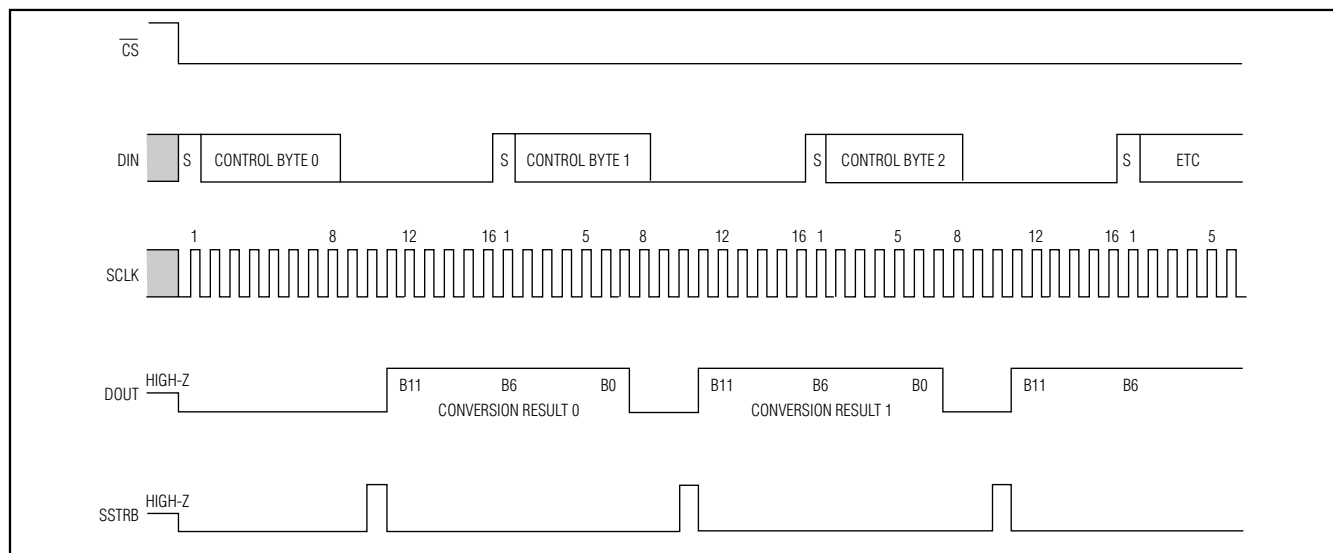


Figure 8. Continuous 16-Clock/Conversion Timing

Table 4. Software-Controlled Power Modes

PD1/PD0	MODE	TOTAL SUPPLY CURRENT		CIRCUIT SECTIONS*	
		CONVERTING	AFTER CONVERSION	INPUT COMPARATOR	REFERENCE
00	Full Power-Down (FULLPD)	2.5mA	2 $\mu$ A	Off	Off
01	Fast Power-Down (FASTPD)	2.5mA	0.9mA	Reduced Power	On
10	Reduced-Power Mode (REDPD)	2.5mA	1.3mA	Reduced Power	On
11	Operating Mode	2.5mA	2.0mA	Full Power	On

\*Circuit operation between conversions; during conversion, all circuits are fully powered up.

progress. In software power-down mode, the serial interface remains active, waiting for a new control byte to start conversion and switch to full-power mode. Once the conversion is completed, the device goes into the programmed power mode until a new control byte is written.

The power-up delay is dependent on the power-down state. Software low-power modes will be able to start conversion immediately when running at decreased clock rates (see *Power-Down Sequencing*). During power-on reset, when exiting software full power-down mode or exiting hardware shutdown, the device goes immediately into full-power mode and is ready to convert after 2 $\mu$ s when using an external reference. When using the internal reference, wait for the typical power-

up delay from a full power-down (software or hardware), as shown in Figure 9.

### Software Power-Down

Software power-down is activated using bits PD1 and PD0 of the control byte. When software shutdown is asserted, the ADC completes the conversion in progress and powers down into the specified low-quiescent-current state (2 $\mu$ A, 0.9mA, or 1.3mA).

The first logic 1 on DIN is interpreted as a start bit and puts the MAX1280/MAX1281 into their full-power mode. Following the start bit, the data input word or control byte also determines the next power-down state. For example, if the DIN word contains PD1 = 0 and PD0 = 1, a 0.9mA power-down starts after the conversion.



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Table 4 details the four power modes with the corresponding supply current and operating sections. For data rates achievable in software power-down modes, see *Power-Down Sequencing* section.

### Hardware Power-Down

Pulling  $\overline{\text{SHDN}}$  low places the converter in hardware power-down. Unlike software power-down mode, the conversion is terminated immediately. When returning to normal operation from  $\overline{\text{SHDN}}$  with an external reference, the MAX1280/MAX1281 can be considered fully powered-up within 2 $\mu\text{s}$  of actively pulling  $\overline{\text{SHDN}}$  high. When using the internal reference, the conversion should be initiated only after the reference has settled; its recovery time depends on the external bypass capacitors and shutdown duration.

### Power-Down Sequencing

The MAX1280/MAX1281's automatic power-down modes can save considerable power when operating at

less than maximum sample rates. Figures 10 and 11 show the average supply current as a function of the sampling rate.

### Using Full Power-Down Mode

Full power-down mode (FULLPD) achieves the lowest power consumption at up to 1000 conversions per channel per second. Figure 10a shows the MAX1281's power consumption for 1- or 8-channel conversions using full power-down mode ( $\text{PD1} = \text{PD0} = 0$ ), with the internal reference and the maximum clock speed. A 0.01 $\mu\text{F}$  bypass capacitor plus the internal 17k $\Omega$  reference resistor at REFADJ forms an RC filter with a 200 $\mu\text{s}$  time constant. To achieve full 12-bit accuracy, 10 time constants or 2ms are required after power-up if the bypass capacitor is fully discharged between conversions. Waiting this 2ms in FASTPD mode or reduced-power mode (REDP) instead of full power-down mode can further reduce power consumption. This is achieved by using the sequence shown in Figure 12a.

Figure 10b shows the MAX1281's power consumption for 1- or 8-channel conversions using FULLPD mode ( $\text{PD1} = \text{PD0} = 0$ ), an external reference, and the maximum clock speed. One dummy conversion to power-up the device is needed, but no wait-time is necessary to start the second conversion, thereby achieving lower power consumption at up to the full sampling rate.

### Using Fast Power-Down and Reduced-Power Modes

FASTPD and REDP modes achieve the lowest power consumption at speeds close to the maximum sample rate. Figure 11 shows the MAX1281's power consumption in FASTPD mode ( $\text{PD1} = 0, \text{PD0} = 1$ ), REDP mode ( $\text{PD1} = 1, \text{PD0} = 0$ ), and (for comparison) normal operating mode ( $\text{PD1} = 1, \text{PD0} = 1$ ). The figure shows

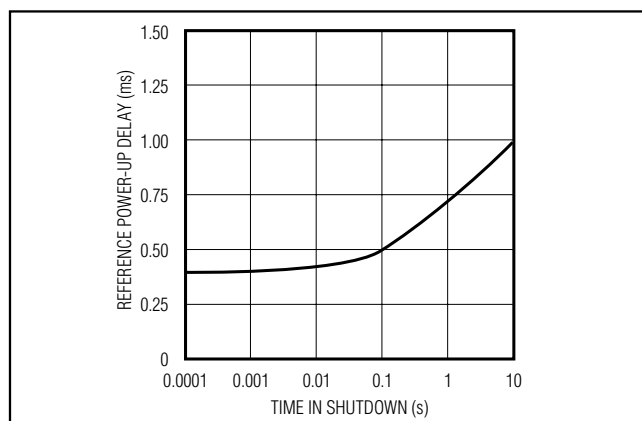


Figure 9. Reference Power-Up Delay vs. Time in Shutdown

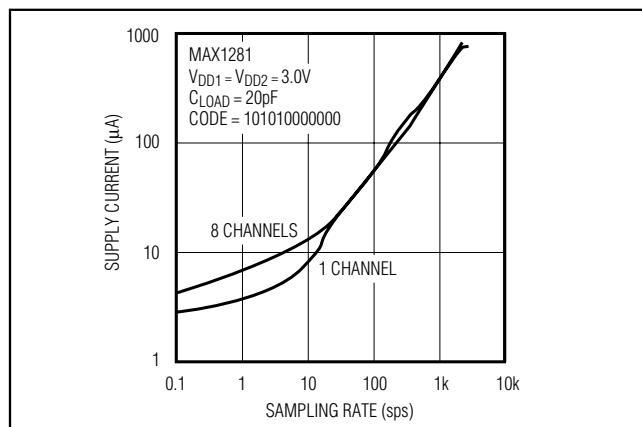


Figure 10a. Average Supply Current vs. Sample Rate (Using FULLPD and Internal Reference)

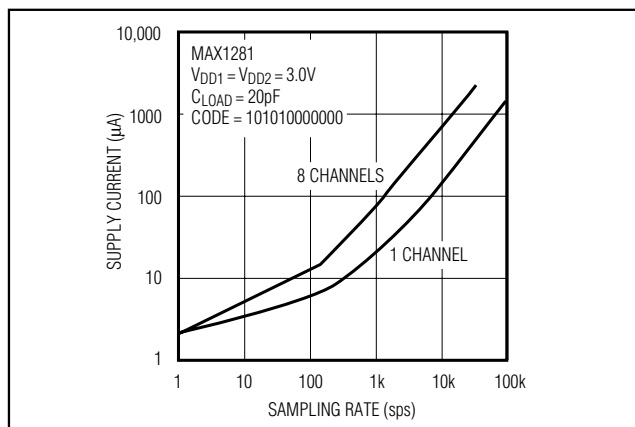


Figure 10b. Average Supply Current vs. Sampling Rate (Using FULLPD and External Reference)

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power consumption using the specified power-down mode, with the internal reference and the maximum clock speed. The clock speed in FASTPD or REDP should be limited to 4.8MHz for the MAX1280/MAX1281. FULLPD mode may provide increased power

savings in applications where the MAX1280/MAX1281 are inactive for long periods of time, but where intermittent bursts of high-speed conversions are required.

### Internal and External References

The MAX1280/MAX1281 can be used with an internal or external reference. An external reference can be connected directly at REF or at the REFADJ pin.

An internal buffer is designed to provide 2.5V at REF for both the MAX1280/MAX1281. The internally trimmed 1.22V reference is buffered with a gain of +2.05V/V.

### Internal Reference

The MAX1280/MAX1281's full-scale range with the internal reference is 2.5V for unipolar inputs and  $\pm 1.25V$  for bipolar inputs. The internal reference voltage is adjustable to  $\pm 100mV$  with the circuit of Figure 13.

### External Reference

An external reference can be placed at either the input (REFADJ) or the output (REF) of the internal reference-buffer amplifier. The REFADJ input impedance is typically  $17k\Omega$ . At REF, the DC input resistance is a minimum of

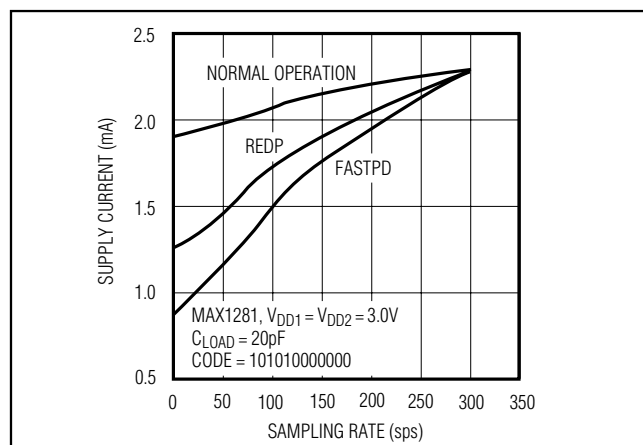


Figure 11. Average Supply Current vs. Sampling Rate (Using REDP, FASTPD, and Normal Operation and Internal Reference)

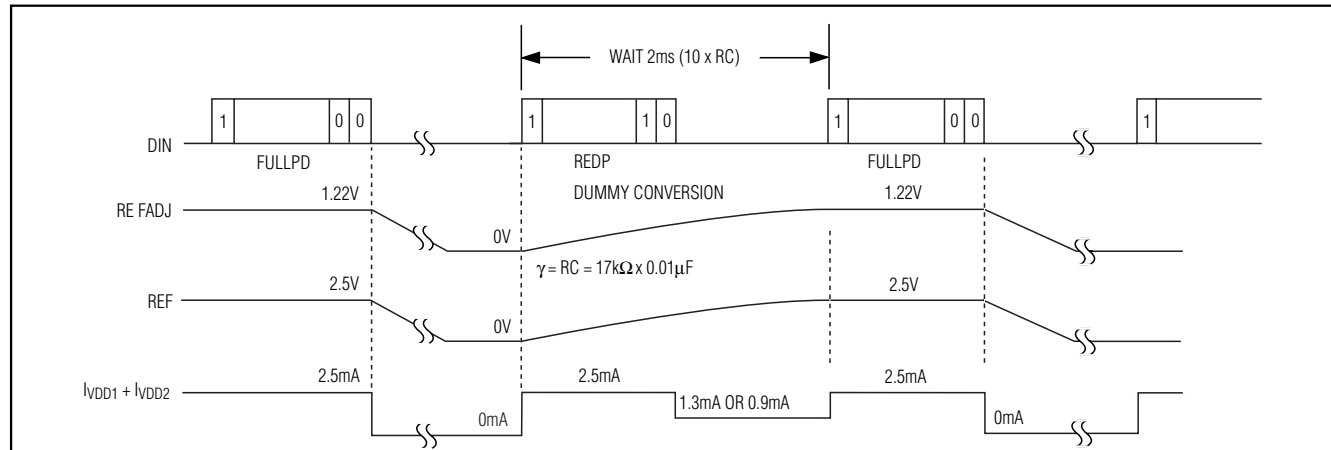


Figure 12a. Full Power-Down Timing

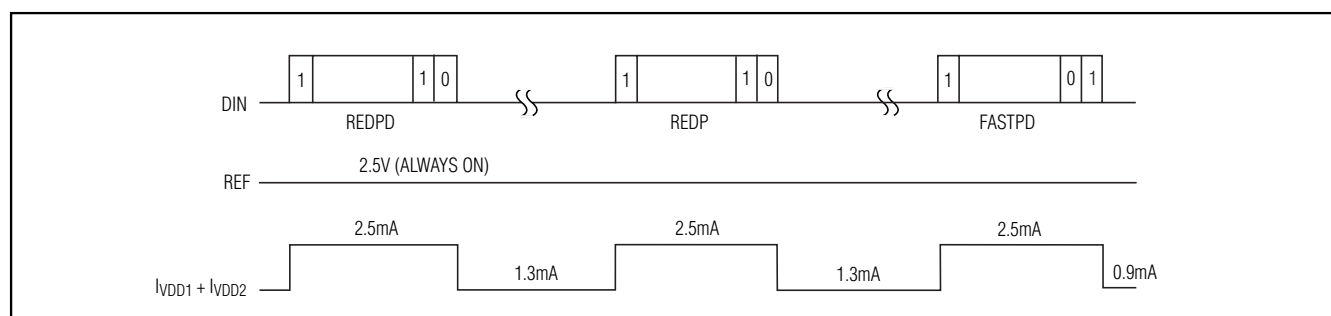


Figure 12b. Reduced-Power/Fast Power-Down Timing

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

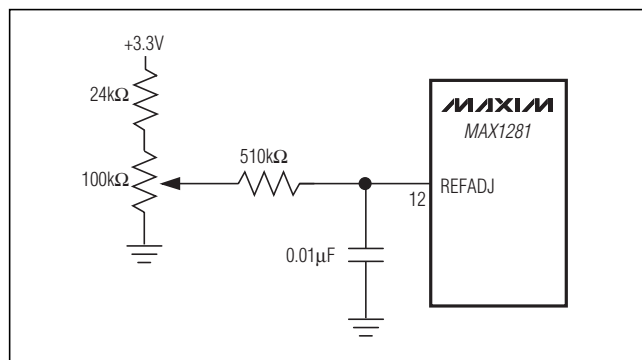


Figure 13. MAX1281 Reference-Adjust Circuit

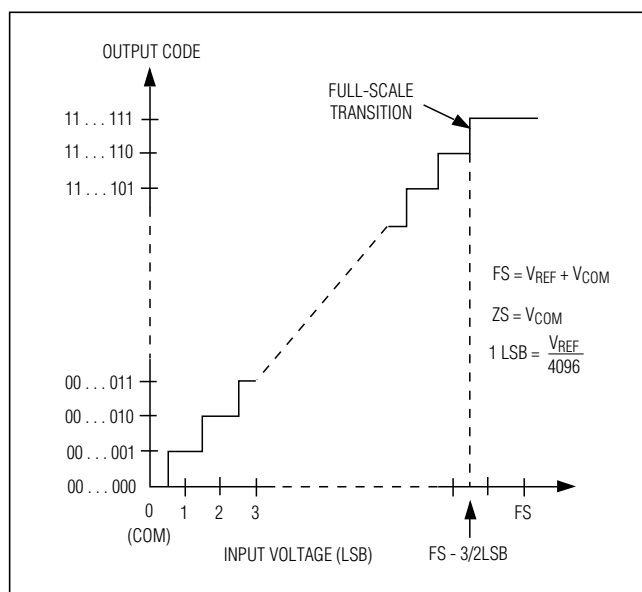


Figure 14. Unipolar Transfer Function, Full Scale (FS) =  $V_{REF} + V_{COM}$ , Zero Scale (ZS) =  $V_{COM}$

18kΩ. During conversion, an external reference at REF must deliver up to 350μA DC load current and have 10Ω or less output impedance. If the reference has a higher output impedance or is noisy, bypass it close to the REF pin with a 4.7μF capacitor.

Using the REFADJ input makes buffering the external reference unnecessary. To use the direct REF input, disable the internal buffer by connecting REFADJ to VDD1.

## Transfer Function

Table 5 shows the full-scale voltage ranges for unipolar and bipolar modes. Figure 14 depicts the nominal, unipolar input/output (I/O) transfer function, and Figure 15 shows the bipolar I/O transfer function. Code transi-

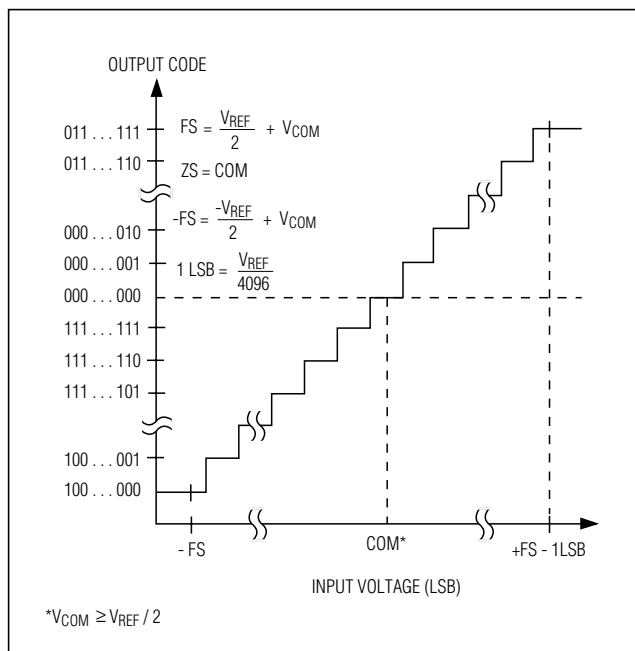


Figure 15. Bipolar Transfer Function, Full Scale (FS) =  $V_{REF}/2 + V_{COM}$ , Zero Scale (ZS) =  $V_{COM}$

tions occur halfway between successive-integer LSB values. Output coding is binary, with 1LSB = 610μV for unipolar and bipolar operation.

## Layout, Grounding, and Bypassing

For best performance, use printed circuit boards; wire-wrap boards are not recommended. Board layout should ensure that digital and analog signal lines are separated from each other. Do not run analog and digital (especially clock) lines parallel to one another, or digital lines underneath the ADC package.

Figure 16 shows the recommended system ground connections. Establish a single-point analog ground (star ground point) at GND. Connect all analog grounds to the star ground. Connect the digital system ground to star ground at this point only. For lowest-noise operation, the ground return to the star ground's power supply should be low impedance and as short as possible.

High-frequency noise in the VDD1 power supply may affect the high-speed comparator in the ADC. Bypass the supply to the star ground with 0.1μF and 10μF capacitors, located close to pin 20 of the MAX1280/MAX1281. Minimize capacitor lead lengths for best supply-noise rejection. If the power supply is very noisy, a 10Ω resistor can be connected as a lowpass filter (Figure 16).

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Table 5. Full Scale and Zero Scale

UNIPOLAR MODE		BIPOLAR MODE		
Full Scale	Zero Scale	Positive Full Scale	Zero Scale	Negative Full Scale
$V_{REF} + V_{COM}$	COM	$V_{REF} / 2 + V_{COM}$	$V_{COM}$	$-V_{REF} / 2 + V_{COM}$

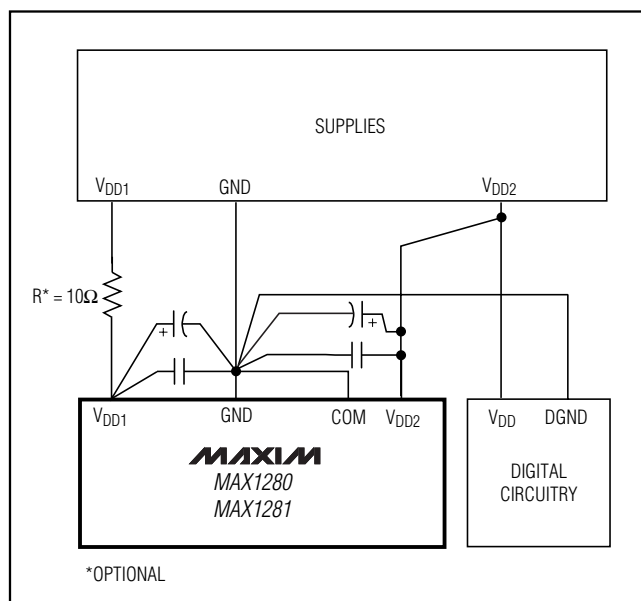


Figure 16. Power-Supply Grounding Connection

## High-Speed Digital Interfacing with QSPI

The MAX1280/MAX1281 can interface with QSPI using the circuit in Figure 17 ( $f_{SCLK} = 4.0\text{MHz}$ ,  $CPOL = 0$ ,  $CPHA = 0$ ). This QSPI circuit can be programmed to do a conversion on each of the eight channels. The result is stored in memory without taxing the CPU, since QSPI incorporates its own microsequencer.

## TMS320LC3x Interface

Figure 18 shows an application circuit that interfaces the MAX1280/MAX1281 to the TMS320 in external clock mode. The timing diagram for this interface circuit is shown in Figure 19.

Use the following steps to initiate a conversion in the MAX1280/MAX1281 and to read the results:

- 1) The TMS320 should be configured with CLKX (transmit clock) as an active-high output clock and with CLKR (TMS320 receive clock) as an active-high input clock. CLKX and CLKR on the TMS320 are

connected with the MAX1280/MAX1281's SCLK input.

- 2) The MAX1280/MAX1281's  $\overline{CS}$  pin is driven low by the TMS320's XF<sub>I/O</sub> port to enable data to be clocked into the MAX1280/MAX1281's DIN pin.
- 3) An 8-bit word (1XXXXX11) should be written to the MAX1280/MAX1281 to initiate a conversion and place the device into normal operating mode. See Table 1 to select the proper XXXXX bit values for your specific application.
- 4) The MAX1280/MAX1281's SSTRB output is monitored through the TMS320's FSR input. A falling edge on the SSTRB output indicates that the conversion is in progress and data is ready to be received from the MAX1280/MAX1281.
- 5) The TMS320 reads in one data bit on each of the next 16 rising edges of SCLK. These data bits represent the 12-bit conversion result followed by four trailing bits, which should be ignored.
- 6) Pull  $\overline{CS}$  high to disable the MAX1280/MAX1281 until the next conversion is initiated.

## Definitions

### Integral Nonlinearity

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. The static linearity parameters for the MAX1280/MAX1281 are measured using the endpoint method.

### Differential Nonlinearity

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes and a monotonic transfer function.

### Aperture Jitter

Aperture jitter ( $t_{AJ}$ ) is the sample-to-sample variation in the time between the samples.

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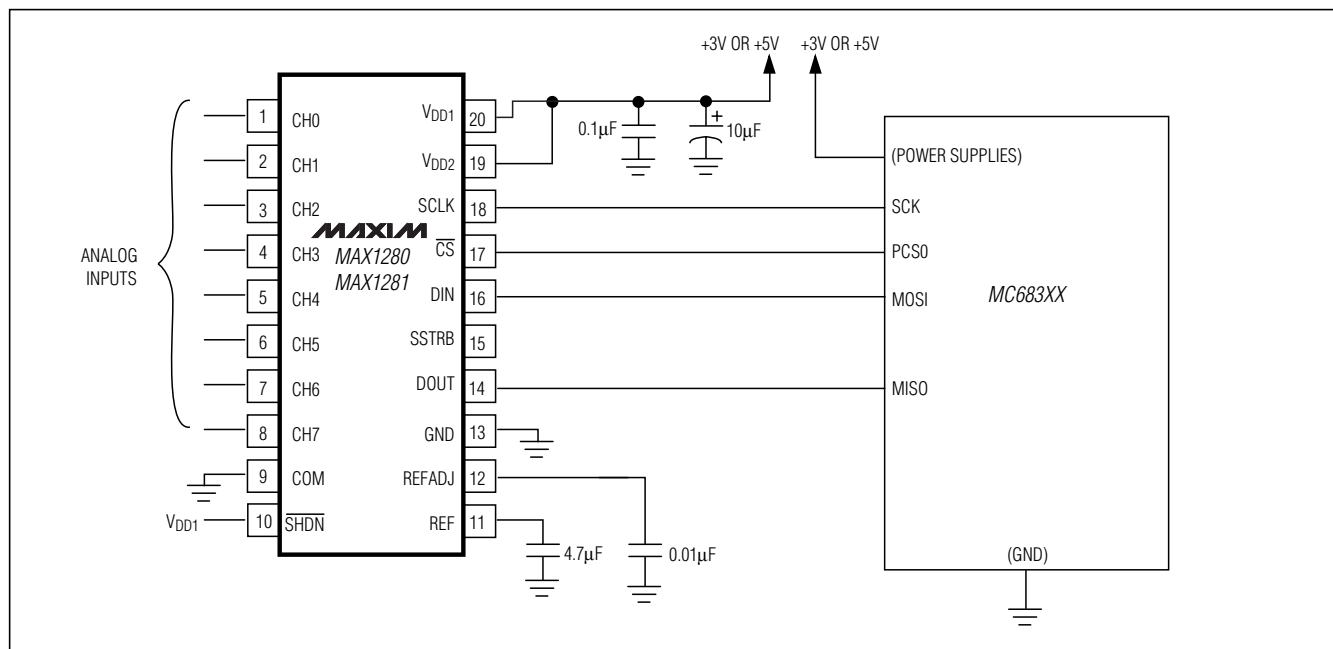


Figure 17. QSPI Connections

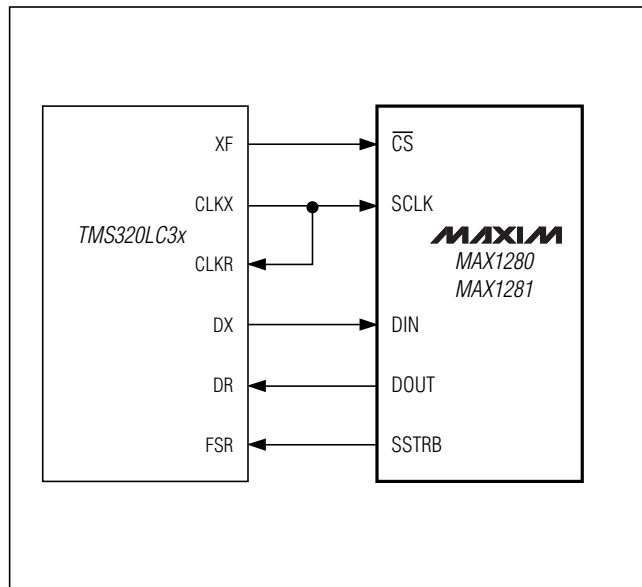


Figure 18. MAX1280/MAX1281-to-TMS320 Serial Interface

## Aperture Delay

Aperture delay ( $t_{AD}$ ) is the time defined between the falling edge of the sampling clock and the instant when an actual sample is taken.

## Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, Signal-to-noise ratio (SNR) is the ratio of full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR = (6.02 \times N + 1.76)dB$$

In reality, there are other noise sources besides quantization noise, including thermal noise, reference noise, clock jitter, etc. Therefore, SNR is calculated by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

## Signal-to-Noise Plus Distortion

Signal-to-noise ratio plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to RMS equivalent of all other ADC output signals.

$$SINAD (dB) = 20 \times \log (Signal_{RMS} / Noise_{RMS})$$

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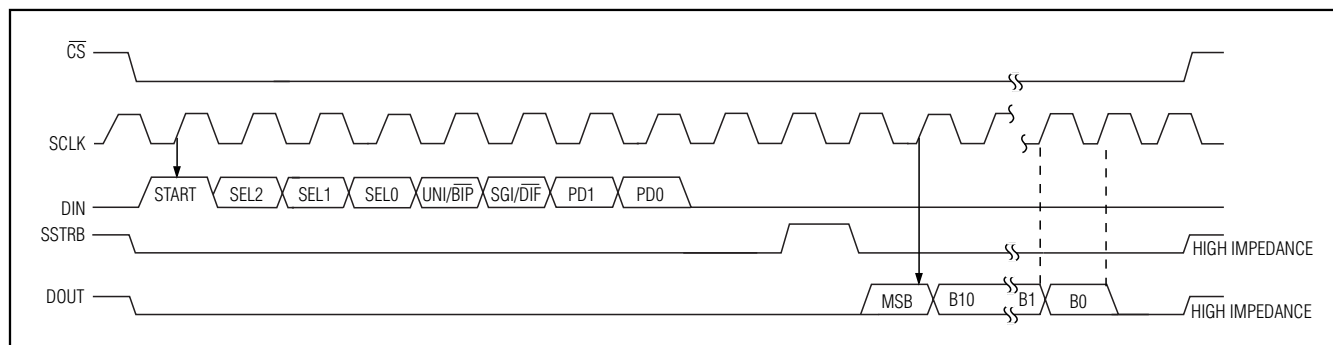


Figure 19. MAX1280/MAX1281-to-TMS320 Serial Interface

## Effective Number of Bits

Effective number of bits (ENOB) indicates the global accuracy of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. With an input range equal to the full-scale range of the ADC, calculate the effective number of bits as follows:

$$\text{ENOB} = (\text{SINAD} - 1.76) / 6.02$$

## Total Harmonic Distortion (THD)

Total harmonic distortion (THD) is the ratio of the RMS sum of the first five harmonics of the input signal to the fundamental itself. This is expressed as:

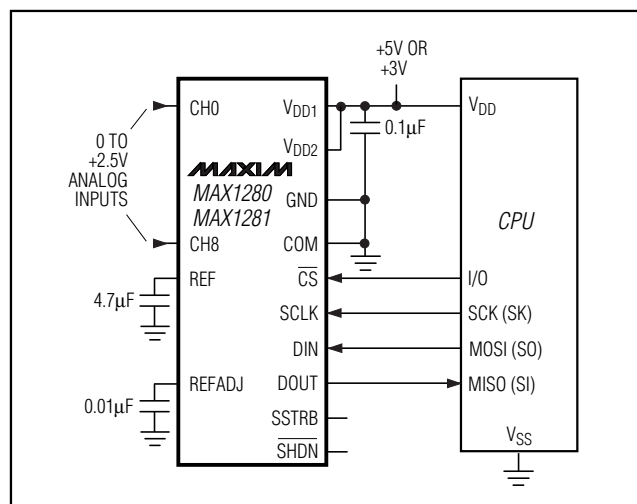
$$\text{THD} = 20 \times \log \left( \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_4^2 + V_5^2}}{V_1} \right)$$

where  $V_1$  is the fundamental amplitude, and  $V_2$  through  $V_5$  are the amplitudes of the 2nd- through 5th-order harmonics, respectively.

## Spurious-Free Dynamic Range

Spurious-free dynamic range (SFDR) is the ratio of RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest distortion component.

## Typical Operating Circuit



# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

## Chip Information

PROCESS: BiCMOS

## Package Information

For the latest package outline information and land patterns, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
20 TSSOP	U20+2	<a href="#">21-0066</a>

MAX1280/MAX1281

# 400ksps/300ksps, Single-Supply, Low-Power, 8-Channel, Serial 12-Bit ADCs with Internal Reference

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	5/00	Initial release	—
1	4/10	Changed specifications due to single pass flow qualifications and added lead-free information	1–5
2	10/10	Changed multiplexer leakage current condition, added note to supply current condition, changed Note 11, changed Figures 4 and 12b	5, 6, 7, 11, 18

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