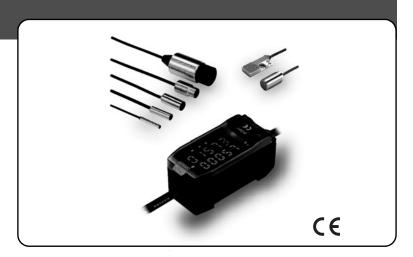


Smart Sensors (Inductive Displacement Type)

ZX-E Series

High-accuracy Detection of Metal Workpiece Displacement

- Sensor Heads support a wide variety of applications.
- Linearity can be adjusted for non-ferrous metals, such as SUS and aluminum, using the material selection function.
- Simple linearity compensation (teaching).
- Easily perform calculation for two Sensors by using a Calculating Unit.
- Prevent mutual interference for up to five Units by using a Calculating Unit



Ordering Information

■ Sensors

Sensor Heads (Refer to Dimensions on page 11.)

| Shape | Dimensions | Sensing distance | Resolution *1 | Model |
|-----------------------------|------------------|------------------|---------------|----------------|
| Cylindrical | 3 dia. x 18 mm | 0.5 mm | 1 μm | ZX-EDR5T |
| | 5.4 dia. x 18 mm | 1 mm | | ZX-ED01T *2 |
| | 8 dia. x 22 mm | 2 mm | | ZX-ED02T *2 |
| Screw-shaped | M10 x 22 mm | | | ZX-EM02T *2 |
| | M18 x 46.3 mm | 7 mm | | ZX-EM07MT *2 |
| Flat | 30 x 14 x 4.8 mm | 4 mm | | ZX-EV04T *2 *3 |
| Heat-resistant, cylindrical | M12 x 22 mm | 2 mm | | ZX-EM02HT *4 |

^{*1:} For an average count of 4,096.

Amplifier Units (Refer to Dimensions on page 13.)

| Appearance | Power supply | Output type | Model |
|------------|--------------|-------------|----------|
| | DC | NPN | ZX-EDA11 |
| | | PNP | ZX-EDA41 |

Note: Compatible connection with the Sensor Head.

^{*2:} Models with Protective Spiral Tubes are also available. Add a suffix of "-S" to the above model numbers when ordering. (Example: ZX-ED01T-S) For detailed dimensions of the Protective Spiral Tube, refer to the information on the E39-F32A on the OMRON website.

^{*3:} Be sure to use ZX-EDA Amplifier Unit version 1,200 or later with the ZX-EV04.

^{*4:} Be sure to use ZX-EDA Amplifier Unit version 1,300 or later with the ZX-EM02H.

Accessories (Order Separately)

Calculating Unit (Refer to Dimensions on page 14.)

| Appearance | Model |
|------------|---------|
| | ZX-CAL2 |

Amplifier Mounting Brackets

A ZX-XBE1 is provided with the Sensor. Order an Amplifier Mounting Bracket separately if required.

(Refer to Dimensions on page 14.)

| Appearance | Model | Remarks |
|------------|---------|------------------------------------|
| | ZX-XBE1 | Attached to each Sensor Head |
| | ZX-XBE2 | For DIN track mounting |

Logging Tool for Personal Computers

(Refer to Dimensions on page 15.)

| Appearance | Name | | Model |
|------------|----------------------------------|---------|-----------------------------|
| | Communications Interface Unit | RS-232C | ZX-SF11 |
| | | USB | ZX-SF21 |
| | | | ZX-SW11EV3 (See note 1.) |

Setup Tool for Personal Computer

| Appearance | Name | Model |
|------------|--|------------------------------|
| | Communications Interface Unit (RS-232C) + Smart Monitor Basic*2 (Function Setting Software) | ZX-SFW11EV3 (See note 1.) |

Note 1. The ZX-SFW11EV3 or ZX-SW11EV3 is required to use the Smart Monitor with the ZX-LDA11-N/41-N. Earlier versions cannot be used.

The Smart Monitor Basic does not have a logging function. Other than the logging function, the Smart Monitor Basic supports the same functions as the Smart Monitor.

Cables with Connectors on Both Ends (for Extension) (Refer to Dimensions on page 15.)*

| Cable length | Model | Quantity |
|--------------|---------|----------|
| 1 m | ZX-XC1A | 1 |
| 4 m | ZX-XC4A | |
| 8 m | ZX-XC8A | |

^{*} Robot cable models are also available. The model numbers are ZX-XC□R.

Bank Unit

| Appearance | Model |
|------------------|---------|
| 1242345 40000 | ZX-SB11 |

Specifications

■ Sansor Haads

| | | Model | ZX-EDR5T | ZX-ED01T | ZX-ED02T/ EM02T | ZX-EM07MT | ZX-EV04T | ZX-EM02H |
|--|------------|------------------|--|---|----------------------|---------------------------------|----------------------|----------------------------|
| Measurem | ent rang | е | 0 to 0.5 mm | 0 to 1 mm | 0 to 2 mm | 0 to 7 mm | 0 to 4 mm | 0 to 2 mm |
| Sensing ol | oject | | Magnetic metals (gineering Data on | | nges and linearit | ies are different fo | r non-magnetic m | etals. Refer to <i>En-</i> |
| Standard r | eference | e object | 18×18×3 mm 30×30×3 mm 60×60×3 mm 45×45×3 mm Material: ferrous (S50C) | | | | | |
| Resolution | ı *1 | | 1 μm | | | | | |
| Linearity *2 | 2 | | ±0.5% F.S. | | | | | ±1.0% F.S. *5 |
| Linear out | out rang | е | Same as measure | ement range. | | | | |
| Temperature characteristic *3 (including Amplifier Unit) | | 0.15% F.S./°C | .15% F.S./°C 0.07% F.S./°C 0.1% F.S | | | 0.1% F.S./°C | | |
| Ambient | Operatin | - | | to 50°C (with no ic10 to 60°C (with no icing or condensation) | | | | −10 to 200°C |
| temperature | Storage | *4 | ing or condensation) -20 to 70°C (with no icing or condensation) | | | (with no icing or condensation) | | |
| Ambient humidity | | | Operating and storage: 35% to 85% (with no condensation) | | | | | |
| Insulation | resistan | ce | 50 M Ω min. (at 500 DC) | | | | | |
| Dielectric : | strength | | 1,000 VAC, 50/60 Hz for 1 min between charged parts and case | | | | | |
| Vibration r | esistand | e (destruction) | 10 to 55 Hz with 1.5-mm double amplitude for 2 h each in X, Y, and Z directions | | | | | |
| Shock resi | stance (| destruction) | 500 m/s², 3 times each in X, Y, and Z directions | | | | | |
| Degree of | protection | on (Sensor Head) | IEC60529, IP65 | IEC60529, IP67 | , | | | IEC60529, IP60 *6 |
| Connectio | n metho | d | Connector relay (standard cable length: 2 m) | | | | | |
| Weight (pa | cked sta | ite) | Approx. 120 g | Approx. 140 g | | Approx. 160 g | Approx. 130 g | Approx. 160 g |
| Materials | Sensor | Case | Brass | Stainless steel | Brass | | Zinc (nickel-plated) | Brass |
| | Head | Sensing surface | Heat-resistant AB | S | • | | • | PEEK |
| | | Tightening nut | | 5 | Brass (nickel-plated | d) (except ZX-ED02T) | | Brass (nickel-plated) |
| Toothed washer | | | - | Iron (zinc-plated) | (except ZX-ED02T) | | Iron (zinc-plated) | |
| | Preampl | ifier | PES | | | | | |
| Accessorie | es | | Amplifier Mountin | g Brackets (ZX-X | BE1), Instruction | n Manual | | |

- *1:Resolution: The resolution is the deviation (±3σ) in the linear output when connected to the ZX-EDA Amplifier Unit. The above values indicate the deviations observed 30 minutes after the power is turned ON.
 - (The resolution is measured with OMRON's standard reference object at 1/2 of the measurement range with the ZX-EDA set for the maximum average count of 4,096 per period.)
 - The resolution is given at the repeat accuracy for a stationary workpiece, and is not an indication of the distance accuracy. The resolution may be adversely affected under strong electromagnetic fields.
- *2: Linearity: The linearity is given as the error in an ideal straight line displacement output when measuring the standard reference object. The linearity and measurement values vary with the object being measured.
- *3: Temperature characteristic: The temperature characteristic is measured with OMRON's standard reference object at 1/2 of the measurement range.
- *4: The ambient temperature given is only for the sensor head. It is -10 to 60°C for the preamp.
- *5: The value given is for an ambient temperature of 25°C.
- *6: Do not use in moist environments because the case is not waterproof.

■ Amplifier Units

| Current output: 4 to 20 mArF.S., Max. load resistance: 300 Ω | Model | ZX-EDA11 | ZX-EDA41 | |
|---|--------------------------------------|--|-------------------------|--|
| Current output '2 Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω | Measurement period *1 | 150 μs | | |
| Voltage output: ±4 V (±5 V, 1 to 5 V *3), Output impedance: 100 Ω | Possible average count settings | 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1,024, 2,048, or 4,096 | | |
| New orange hold New orang | Linear output *2 | Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω | | |
| Residual voltage: 1.2 V max. Residual voltage: 2 V max. ON: Supply voltage short-circuited or supply voltage input, iming input, reset input, input, judgement output hold input Service OFF: Open (leakage current: 0.1 mA max.) OFF: Op | | Voltage output: ± 4 V (\pm 5 V, 1 to 5 V *3), Output imp | edance: 100 Ω | |
| Continuity Con | | | | |
| less OFF: Open (leakage current: 0.1 mA max.) OFF: Open (leakage current: 0.1 mA max.) | · ' ' | | <u> </u> | |
| - Measurement value display - Set value/output value/resolution display - Linearity adjustment (materials selection) - Scaling - Display verse - Display OFF mode - ECO mode - Number of display digit changes - Sample hold - Peak hold - Peak hold - Average hold - New power hold - Delay hold - Delay hold - Zero reset - Initial reset - Linearity initialization - ON-delay timer - One-shot timer - Previous value comparison - Non-measurement setting - Numatic teaching - Hysteresis width setting - Previous value comparison - Non-measurement setting - Numatic teaching - Hysteresis width setting - Monitor focus - (A-B) calculation *4 - Sensor disconnection detection - Key lock - Sensor disconnection detection - Key lock - Sensor disconnection detection - Key lock - Sensor disconnection detection - Segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) - Segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) - Segment teaching - Self-beta hold - Self-bottom hold - Zero reset - ON-delay timer - Previous value comparison - Non-measurement setting - Direct threshold value setting - Previous value comparison - Non-measurement setting - Direct threshold value setting - Previous value comparison - Non-measurement setting - Hysteresis width setting - Previous value comparison - Non-measurement setting - Direct threshold value setting - Previous value comparison - Voleda value setting - Voleda value setting - Voleda value | input, judgement output hold input | | | |
| - Linearity adjustment (materials selection) - Scaling - Display reverse - Display OFF mode - ECO mode - Number of display digit changes - Bottom hold, peak-to-peak hold - Average hold - Average hold - Initial reset - OFF-delay timer - Non-measurement setting - Numer of display digit changes - Bottom hold, peak-to-peak hold - Initial reset - Linearity initialization - ON-delay timer - Non-measurement setting - Automatic teaching - Automatic teaching - Hysteresis width setting - Hysteresis widthsetting - Hysteresis widthsetting - Hysteresis widthsetting - | | | | |
| 7-segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) Voltage influence (including Sensor) 0.5% F.S. of linear output value at ±20% of power supply voltage 12 to 24 VDC ±10%, Ripple (p-p): 10% max. Current consumption 140 mA max. with power supply voltage of 24 VDC (with Sensor connected) Ambient temperature Operating and storage: 0 to 50°C (with no icing or condensation) Ambient humidity Operating and storage: 35% to 85% (with no condensation) Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Function | - Linearity adjustment (materials selection) - Display reverse - Number of display digit changes - Bottom hold, peak-to-peak hold - Average hold - Initial reset - OFF-delay timer - Non-measurement setting - Automatic teaching - Reset input - Linear output correction - K-(A+B) calculation *4 - Sensor disconnection detection - Display OFF mode - Display OFF mode - Self-Dottom hold - Self-bottom hold - Zero reset - ON-delay timer - ON-delay timer - Previous value comparise - Position teaching - Hysteresis width setting - Monitor focus - (A-B) calculations *4 - Mutual interference prevention *4 - Zero reset indicator | | |
| Power supply voltage 12 to 24 VDC ±10%, Ripple (p-p): 10% max. Current consumption 140 mA max. with power supply voltage of 24 VDC (with Sensor connected) Ambient temperature Operating and storage: 0 to 50°C (with no icing or condensation) Ambient humidity Operating and storage: 35% to 85% (with no condensation) Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Indications | 7-segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) | | |
| Current consumption 140 mA max. with power supply voltage of 24 VDC (with Sensor connected) Ambient temperature Operating and storage: 0 to 50°C (with no icing or condensation) Ambient humidity Operating and storage: 35% to 85% (with no condensation) Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Voltage influence (including Sensor) | 0.5% F.S. of linear output value at ±20% of power supply voltage | | |
| Ambient temperature Operating and storage: 0 to 50°C (with no icing or condensation) Ambient humidity Operating and storage: 35% to 85% (with no condensation) Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Power supply voltage | 12 to 24 VDC \pm 10%, Ripple (p-p): 10% max. | | |
| Ambient humidity Operating and storage: 35% to 85% (with no condensation) Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Current consumption | 140 mA max. with power supply voltage of $\overline{24}$ VDC (| (with Sensor connected) | |
| Insulation resistance 20 MΩ min. (at 500 DC) Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Ambient temperature | Operating and storage: 0 to 50°C (with no icing or co | ondensation) | |
| Dielectric strength 1,000 VAC, 50/60 Hz for 1 min Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Ambient humidity | Operating and storage: 35% to 85% (with no conder | nsation) | |
| Vibration resistance (destruction) 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Insulation resistance | 20 MΩ min. (at 500 DC) | | |
| Shock resistance (destruction) 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Dielectric strength | 1,000 VAC, 50/60 Hz for 1 min | | |
| Connection method Prewired (standard cable length: 2 m) Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Vibration resistance (destruction) | 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions | | |
| Weight (packed state) Approx. 350 g Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Shock resistance (destruction) | 300 m/s², 3 times each in 6 directions (up, down, left, right, forward, backward) | | |
| Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Connection method | | | |
| Materials Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | Weight (packed state) | , | | |
| Accessories Instruction Manual | Materials | | | |
| | Accessories | Instruction Manual | | |

^{*1:}The response time for the first linear output or judgment output is calculated as follows (with fixed sensitivity): Measurement period × (Average count setting + 1). The response time for the second and later outputs is the measurement period specified in the table.

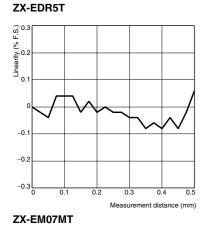
^{*2:} The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.

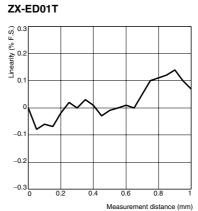
^{*3:} Setting is possible via the monitor focus function.

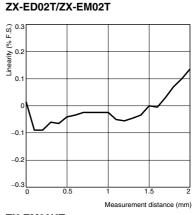
^{*4:} A Calculating Unit (ZX-CAL2) is required.

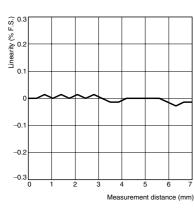
Engineering Data (Typical)

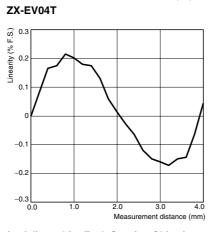
Measurement Distance vs. Linearity (with Linearity Adjusted for Standard Sensing Object)

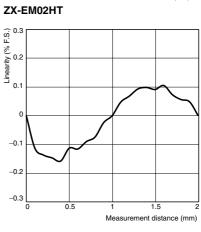




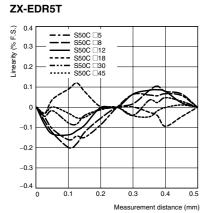


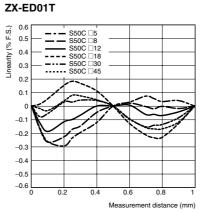


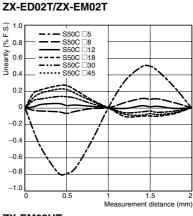


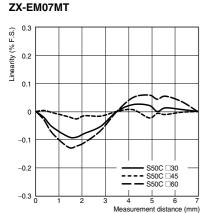


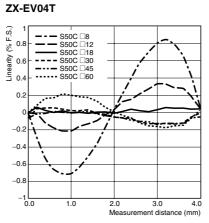
Size of Sensing Object vs. Linearity (with Linearity Adjusted for Each Sensing Object)

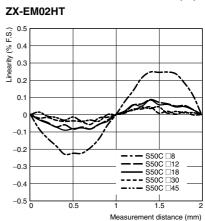






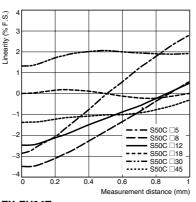




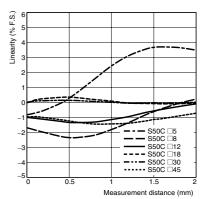


Size of Sensing Object vs. Linearity (with Linearity Adjusted for Standard Sensing Object)

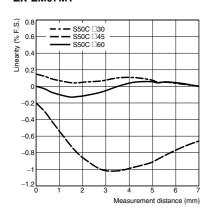




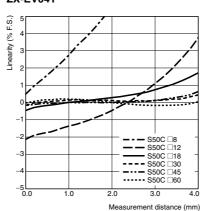
ZX-ED02T/ZX-EM02T



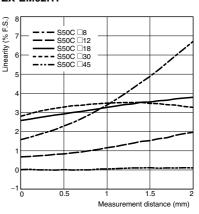
ZX-EM07MT



ZX-EV04T

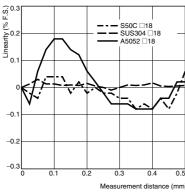


ZX-EM02HT

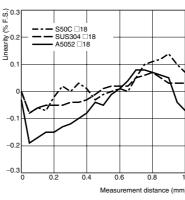


Material of Sensing Object vs. Linearity (with Linearity Adjusted for Each Sensing Object)

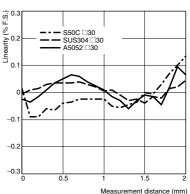




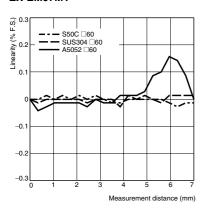
ZX-ED01



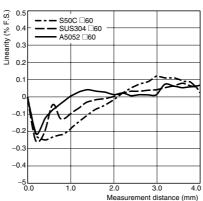
ZX-ED02T/ZX-EM02T



ZX-EM07MT

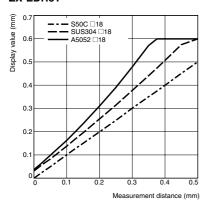


ZX-EV04T

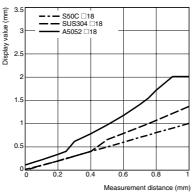


Material of Sensing Object vs. Linearity (with Linearity Adjusted for Standard Sensing Object and Iron)

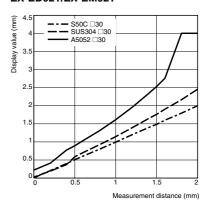
ZX-EDR5T



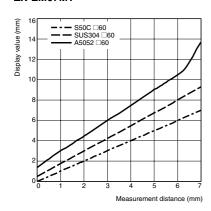
ZX-ED01T



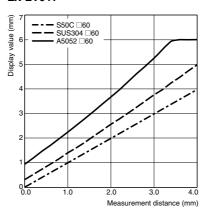
ZX-ED02T/ZX-EM02T



ZX-EM07MT

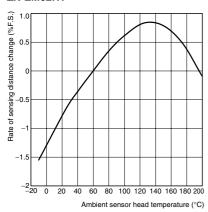


ZX-EV04T



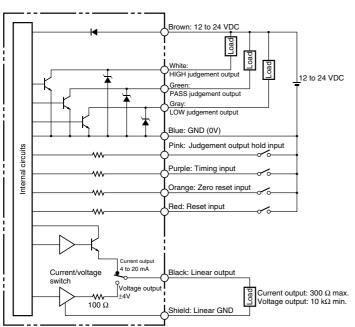
Temperature Characteristics

ZX-EM02HT

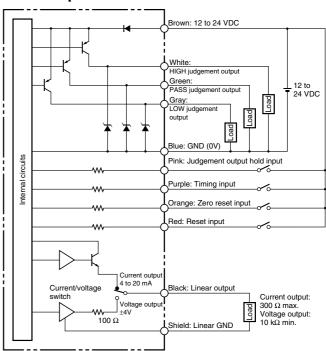


I/O Circuit Diagrams

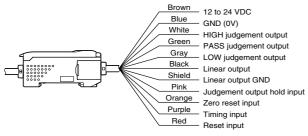
NPN Amplifier Unit: ZX-EDA11



PNP Amplifier Unit: ZX-EDA41



Connections: Amplifier Unit



- Note 1. Use a separate stabilized power supply for the Amplifier Unit, particularly when high resolution is required.
 - 2. Wire the Unit correctly. Incorrect wiring may result in damage to the Unit. (Do not allow wiring, particularly the linear output, to come into contact with other lines.)
 - 3. Use the blue (0-V) line for the power supply and use the shield wire (linear output ground) together with the black (linear output) line for linear output. Each of these grounds must be used for the designed purpose. When not using the linear output, connect the linear output ground to the 0-V ground.

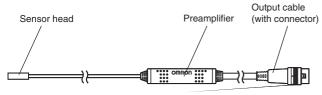
Part Names

Sensors

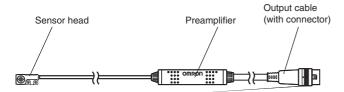
ZX-EDR5T ZX-ED01T ZX-ED02T ZX-EM02T

ZX-EM07MT

ZX-EM02HT

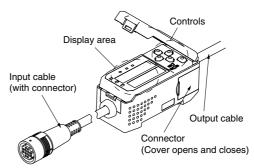


ZX-EV04T



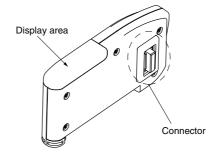
Amplifier Units

ZX-EDA11 ZX-EDA41



Calculating Unit

ZX-CAL2



Precautions

■ Design Precautions

Conform to the specified ratings and performance. Refer to *Specifications* on page 2 for details.

Objects of certain materials or shapes may not be detectable, or the detection accuracy may not be sufficiently high.

Environment

Do not operate the product in locations subject to flammable or explosive gases.

In order to ensure safe operation and maintenance, do not install the product in the vicinity of high-voltage devices or power equipment.

■ Wiring

Do not use the product at voltages exceeding the rated values. Doing so may result in damage.

Do not connect the product to an AC power supply or connect the power supply in reverse.

Do not short-circuit the load for open-collector output.

■ Correct Use Design Precautions

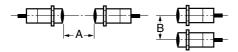
Power Supplies

Allow a warm-up period of approximately 30 minutes after turning ON the power supply.

Mutual Interference

Up to 5 Sensor Heads can be used together by connecting the ZX-CAL2 Calculating Unit between Amplifier Units.

When installing Sensor Heads facing each other or in parallel, separate them by the minimum distances given in the table below.



Mutual Interference

| Model | Α | В |
|-----------|--------|-------------|
| ZX-EDR5T | 5 mm | 20 (3.1) mm |
| ZX-ED01T | 10 mm | 50 (5.4) mm |
| ZX-ED02T | 20 mm | 50 (8) mm |
| ZX-EM02T | 20 mm | 50 (10) mm |
| ZX-EM07MT | 100 mm | 150 (30) mm |
| ZX-EV04T | 80 mm | 50 (14) mm |
| ZX-EM02HT | 20 mm | 50 (12) mm |

Note: The figures in parentheses apply when the mutual interference prevention function is used.

Compatibility

Sensors and Amplifier Units are mutually compatible. Sensors can be added or replaced individually.

Influence of High-frequency Electromagnetic Fields

Using the product in the vicinity of devices that generate high-frequency electromagnetic fields, such as ultrasonic cleaning equipment, high-frequency generators, transceivers, mobile phones, and inverters, may result in malfunction.

Calculating Unit

Do not lay the power cable for the product together with or in the same duct as high-voltage lines or power lines. Doing so may result in incorrect operation or damage due to induction.

Do not connect or disconnect connectors while the power is ON. Doing so may result in damage.

■ Adjustment

Setting

When setting threshold values, ensure that the Amplifier Unit's judgement output hold input line is ON so that there is no judgement output to external devices.

■ Other Precautions

Do not attempt to disassemble, repair, or modify the product.

Dispose of the product using standard procedures for industrial waste.

These Sensors are not compatible with the ZX-L \square Smart Sensors (laser type). Do not connect combinations of ZX-E \square Smart Sensors and ZX-T \square Smart Sensors.

Influence of Metallic Objects

When installing the product, separate it from metallic objects by the distances shown below.



Influence of Metallic Objects

| Model | d | D |
|----------------|------------|--------|
| ZX-EDR5T | 8 mm | 9 mm |
| ZX-ED01T | 10 mm | |
| ZX-ED02T/EM02T | 12 mm | |
| ZX-EM07MT | 55 mm | 20 mm |
| ZX-EV04T | 16 × 32 mm | 4.8 mm |
| ZX-EM02HT | 18 mm | 9 mm |

Wiring

Wiring Check

After wiring is completed, before turning ON the power, confirm that the power supply is connected correctly, that there are no faulty connections, such as load short-circuits, and that the load current is correct. Incorrect wiring may result in failure.

Cable Extension

Do not extend the cable for the Sensor and the Amplifier Unit to a length exceeding 10 m. Use a ZX-XC \square A Extension Cable (sold separately) to extend the Sensor's cable. Extend the Amplifier Unit's cable using a shielded cable of the same type.

Power Supply

When using a commercially available switching regulator, ground the FG (frame ground) terminal.

If the power supply line is subject to surges, connect a surge absorber that meets the conditions of the operating environment.

When using a Calculating Unit, connect the linear output ground of the corresponding Amplifier Unit.

Connectors

Do not connect or disconnect connectors while the power is ON.

Be sure hold to connectors by the cover when connecting or disconnecting.

Mounting

Handling

When mounting the Sensor Head, do not apply excessive shock by, for example, using a hammer. Doing so may result in damage or a reduction in the level of water-proofing. Also, there are screw-shaped models that require a toothed washer to allow for a tolerance in the tightening torque for the nut.

When using a heat-resistant model like the ZX-EM02HT, develop designs that account for thermal expansion due to rising sensing object temperature so the sensing object will never touch the sensing surface. Also note that any sudden rise in temperature will shorten the service life of the product.

Tightening Torque

Do not apply excessive torque when tightening the nut. Use a toothed washer if necessary.

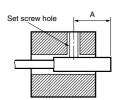


| Model | Tightening torque |
|-----------|-------------------|
| ZX-EM02T | 15 N·m |
| ZX-EM07MT | |
| ZX-EM02HT | 59 N⋅m |

Note: The above figure applies for use with a toothed washer.

Mounting Cylindrical Models:

Tighten set screws with a tightening torque of 0.2 N·m max.





| Model | Α |
|----------|-------------|
| ZX-EDR5T | 9 to 18 mm |
| ZX-ED01T | |
| ZX-ED02T | 11 to 22 mm |

Installation Location

Do not install the product in the following locations.

- Locations subject to temperatures outside the specified range
- Locations subject to condensation due to sudden temperature changes
- Locations subject to humidity levels outside range 35% to 85%
- Locations subject to corrosive or flammable gases
- Locations subject to dust, salts, or metallic powder.
- Locations directly subject to vibrations and shocks
- Locations subject to direct sunlight
- · Locations subject to splashes of water, oil, or chemicals
- Locations subject to strong electromagnetic or electrical fields

Maintenance and Inspection

- Be sure to turn OFF the power supply before adjusting or removing the Sensor Head.
- Cleaning:

Do not use thinners, benzine, acetone, or kerosene for cleaning.

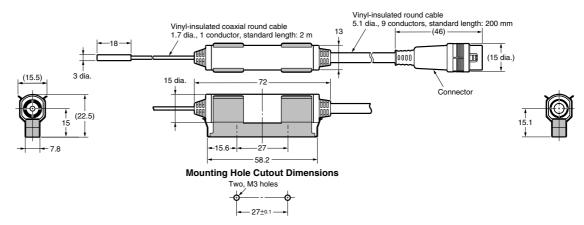
Dimensions

Sensors

Sensor Heads

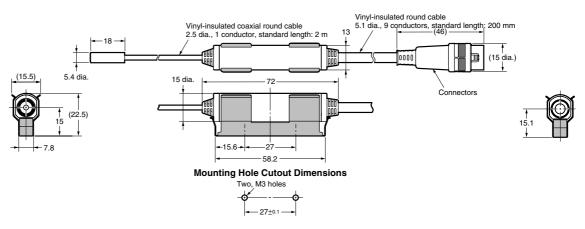
ZX-EDR5T

Dimensions with Mounting Bracket Attached



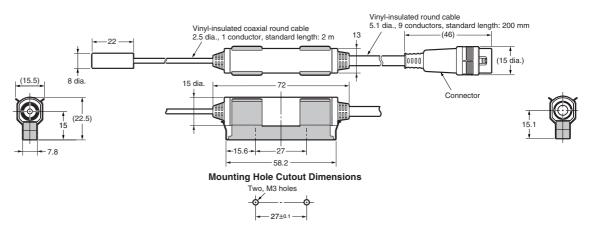
ZX-ED01T

Dimensions with Mounting Bracket Attached



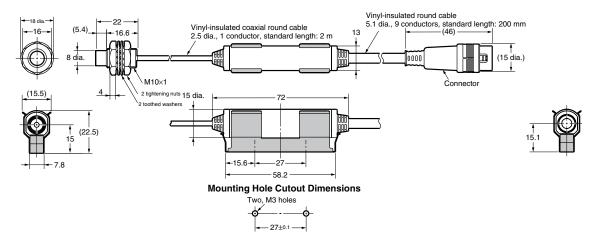
ZX-ED02T

Dimensions with Mounting Bracket Attached



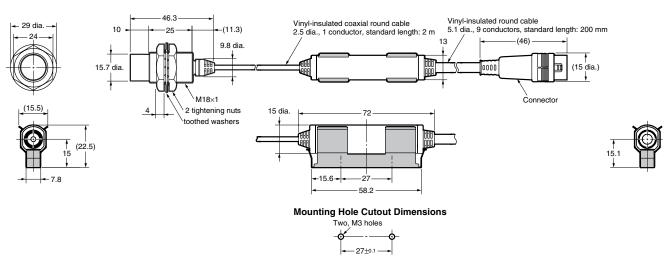
ZX-EM02T

Dimensions with Mounting Bracket Attached

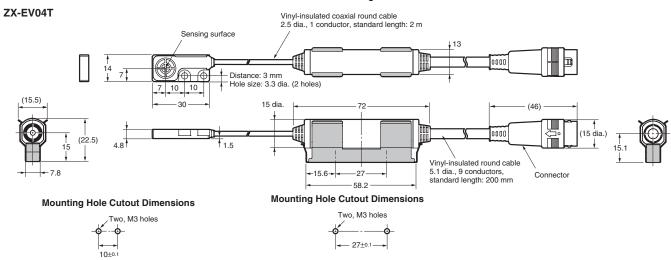


ZX-EM07MT

Dimensions with Mounting Bracket Attached

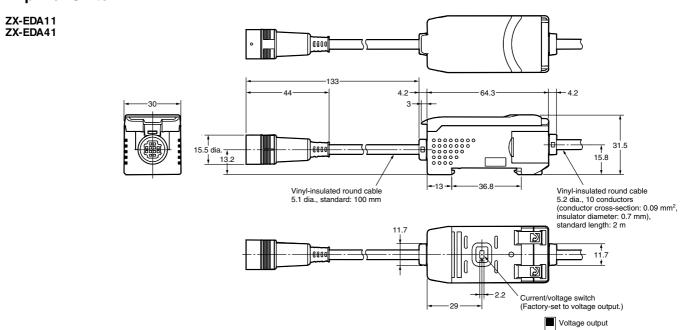


Dimensions with Mounting Bracket Attached



Dimensions with Mounting Bracket Attached ZX-EM02HT Fluororesin-insulated coaxial round cable 2.5 dia., single conductor standard length: 2m 17 10.5 dia 0000 M12×1 Two fastening nuts 15 dia Toothed washer 0000 (22.5) 7.8 **-**15.6→ 27 Vinyl-insulated round cable 5.1 dia., 9 conductors, standard length: 200 mm -58.2 **Mounting Hole Cutout Dimensions**

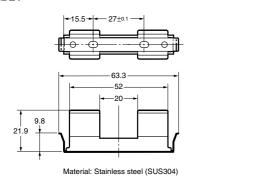
Amplifier Units



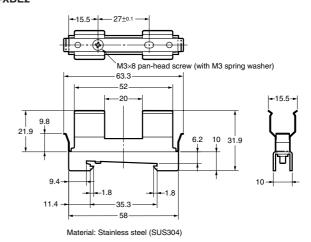
Accessories (Sold Separately)

Preamplifier Mounting Bracket

ZX-XBE1

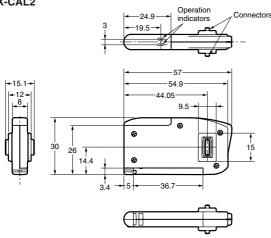


ZX-XBE2



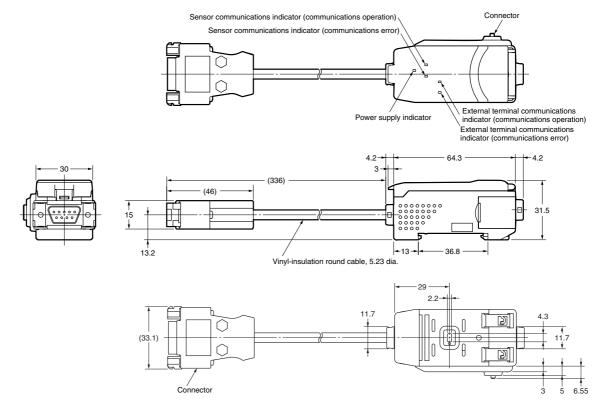
Calculating Unit

ZX-CAL2



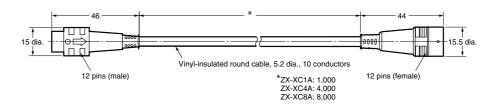
ZX-series Communications Interface Unit

ZX-SF11



Cables with Connectors on Both Ends (for Extension)

ZX-XC1A (1 m) ZX-XC4A (4 m) ZX-XC8A (8 m)





ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

This document provides information mainly for selecting suitable models. Please read the manual carefully for information that the user must understand and accept before purchase, including information on warranty, limitations of liability, and precautions.

CSM_6_1_0911 E331-E1

In the interest of product improvement, specifications are subject to change without notice.

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Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

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