



Motor Control, Current Measurement 1-Bit, 10MHz, 2nd-Order, Delta-Sigma Modulator

FEATURES

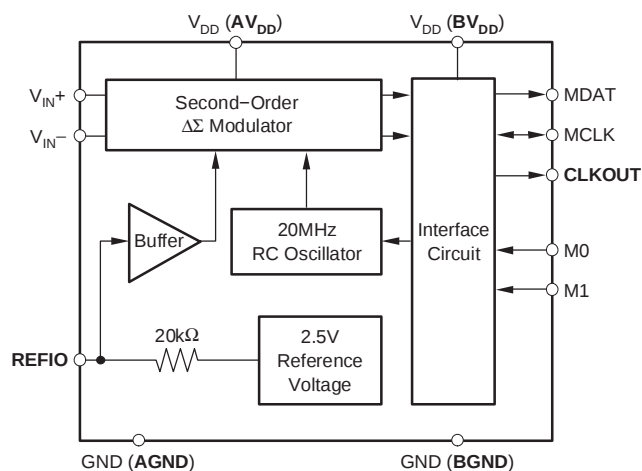
- 16-Bit Resolution
- 14-Bit Linearity
- $\pm 250\text{mV}$ Input Range with Single +5V Supply
- 1% Internal Reference Voltage
- 1% Gain Error
- Flexible Serial Interface with Four Different Modes
- Implemented Twinned Binary Coding as Split-Phase or Manchester Coding for One-Line Interfacing
- Operating Temperature Range: -40°C to $+125^{\circ}\text{C}$

APPLICATIONS

- Motor Control
- Current Measurement
- Industrial Process Control
- Instrumentation
- Smart Transmitters

DESCRIPTION

The ADS1203 is a delta-sigma ($\Delta\Sigma$) modulator with a 95dB dynamic range, operating from a single +5V supply. The differential inputs are ideal for direct connection to transducers or low-level signals. With the appropriate digital filter and modulator rate, the device can be used to achieve 16-bit analog-to-digital (A/D) conversion with no missing codes. An effective resolution of 14 bits or SNR of 85dB (typical) can be maintained with a digital filter bandwidth of 40kHz at a modulator rate of 10MHz. The ADS1203 is designed for use in medium- to high-resolution measurement applications including current measurements, smart transmitters, and industrial process control. The ADS1203 is available in TSSOP-8 and QFN-16 (3x3) packages.



NOTE: **BOLD** pins are available only in QFN package.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

All trademarks are the property of their respective owners.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

ORDERING INFORMATION

For the most current package and ordering information, see the Package Option Addendum located at the end of this data sheet, or see the TI website at www.ti.com.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

over operating free-air temperature range unless otherwise noted

	ADS1203	UNIT
Supply Voltage, AV_{DD} to AGND or V_{DD} to GND	-0.3 to 6	V
Supply Voltage, BV_{DD} to BGND	-0.3 to 6	V
Analog Input Voltage with Respect to AGND or GND	AGND - 0.3 to $AV_{DD} + 0.3$	V
Reference Input Voltage with Respect to AGND	AGND - 0.3 to $AV_{DD} + 0.3$	V
Digital Input Voltage with Respect to BGND or GND	BGND - 0.3 to $BV_{DD} + 0.3$	V
Ground Voltage Difference, AGND to BGND	± 0.3	V
Voltage Differences, BV_{DD} to AGND	-0.3 to 6	V
Input Current to Any Pin Except Supply	± 10	mA
Power Dissipation	See Dissipation Rating Table	
Operating Virtual Junction Temperature Range, T_J	-40 to +150	°C
Operating Free-Air Temperature Range, T_A	-40 to +125	°C
Storage Temperature Range, T_{STG}	-65 to +150	°C

⁽¹⁾ Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

PARAMETER	MIN	NOM	MAX	UNIT
Supply Voltage, AV_{DD} to AGND or V_{DD} to GND	4.5	5	5.5	V
Supply Voltage, BV_{DD} to BGND	Low-Voltage Levels		3.6	V
	5V Logic Levels		5.5	V
Reference Input Voltage	0.5	2.5	2.6	V
Operating Common-Mode Signal	0		5	V
Analog Inputs	$V_{IN+} - V_{IN-}$ (TSSOP package)		+250	mV
	$V_{IN+} - V_{IN-}$ (QFN package)		$+0.1 \times \text{REFIO}$	V
External Clock ⁽¹⁾	16	20	24	MHz
Operating Junction Temperature Range, T_J	-40		+150	°C

⁽¹⁾ With reduced accuracy, clock can go from 1MHz up to 32MHz; see Typical Characteristic curves.

DISSIPATION RATINGS

PACKAGE	$T_A \leq +25^\circ\text{C}$ POWER RATING	DERATING FACTOR ABOVE $T_A = +25^\circ\text{C}$ ⁽¹⁾	$T_A = +70^\circ\text{C}$ POWER RATING	$T_A = +85^\circ\text{C}$ POWER RATING	$T_A = +125^\circ\text{C}$ POWER RATING
TSSOP-8	532mW	4.3mW/°C	338mW	274mW	102mW
QFN-16	2540mW	20.4mW/°C	1622mW	1316mW	500mW

⁽¹⁾ This is the inverse of the traditional junction-to-ambient thermal resistance ($R_{\theta JA}$). Thermal resistances are not production tested and are for informational purposes only.

ELECTRICAL CHARACTERISTICS

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $\text{AV}_{\text{DD}} = \text{BV}_{\text{DD}} = +5\text{V}$ or $\text{V}_{\text{DD}} = +5\text{V}$, $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, $\text{V}_{\text{IN}-} = 0\text{V}$, Mode 3, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.

PARAMETER	TEST CONDITIONS	ADS1203I			UNITS
		MIN	TYP ⁽¹⁾	MAX	
Resolution		16			Bits
DC Accuracy					
INL Integral linearity error ⁽²⁾			± 1	± 4	LSB
	$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$			± 3	LSB
DNL Differential nonlinearity ⁽³⁾				± 1	LSB
V_{OS} Input offset ⁽⁴⁾			± 220	± 1000	μV
TCV_{OS} Input offset drift			± 3.5	± 8	$\mu\text{V}/^{\circ}\text{C}$
G_{ERR} Gain error ⁽⁴⁾	REFIO = internal 2.5V		± 0.2	± 1.4	%
	REFIO = internal 2.5V, $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	-1		1	%
TCG_{ERR} Gain error drift			± 30		$\text{ppm}/^{\circ}\text{C}$
	$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$		± 20		$\text{ppm}/^{\circ}\text{C}$
PSRR Power-supply rejection ratio	$4.5\text{V} < \text{AV}_{\text{DD}}$ or $\text{V}_{\text{DD}} < 5.5\text{V}$		80		dB
Analog Input					
FSR Full-scale differential range	$(\text{V}_{\text{IN}+}) - (\text{V}_{\text{IN}-})$			± 320	mV
	Operating common-mode signal ⁽³⁾	-0.1		5	V
	Input capacitance	Common-mode	3		pF
	Input leakage current			± 16	nA
		$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$		± 1	nA
	Differential input resistance	Equivalent	28		k Ω
	Differential input capacitance		5		pF
CMRR Common-mode rejection ratio	At DC		92		dB
	$\text{V}_{\text{IN}} = 0\text{V}$ to 5V at 50kHz		105		dB
Internal Clock for Modes 0, 1, and 2					
Clock frequency		8.7	10	11	MHz
	$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	9		11	MHz
External Clock for Mode 3					
Clock frequency ⁽⁵⁾		16	20	24	MHz

(1) All typical values are at $T_A = +25^{\circ}\text{C}$.

(2) Integral nonlinearity is defined as the maximum deviation of the line through the end points of the specified input range of the transfer curve for $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, expressed either as the number of LSBs or as a percent of measured input range (500mV).

(3) Ensured by design.

(4) Maximum values, including temperature drift, are ensured over the full specified temperature range.

(5) With reduced accuracy, the supported external clock frequency range is 1MHz up to 32MHz.

(6) Available only for QFN package.

(7) Applicable for 5.0V nominal supply: $\text{BV}_{\text{DD}} = 4.5\text{V}$ to 5.5V .

(8) Applicable for 3.0V nominal supply: $\text{BV}_{\text{DD}} = 2.7\text{V}$ to 3.6V .

(9) Measured with CLKOUT pin not loaded.

ELECTRICAL CHARACTERISTICS (continued)

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $\text{AV}_{\text{DD}} = \text{BV}_{\text{DD}} = +5\text{V}$ or $\text{V}_{\text{DD}} = +5\text{V}$, $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, $\text{V}_{\text{IN}-} = 0\text{V}$, Mode 3, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.

PARAMETER		TEST CONDITIONS	ADS1203I			UNITS
			MIN	TYP ⁽¹⁾	MAX	
AC Accuracy						
SINAD	Signal-to-noise + distortion	V _{IN} = ±250mV _{PP} at 5kHz	81	85		dB
		V _{IN} = ±250mV _{PP} at 5kHz, T _A = −40°C to +85°C	82.5			dB
SNR	Signal-to-noise ratio	V _{IN} = ±250mV _{PP} at 5kHz	81.5	85		dB
		V _{IN} = ±250mV _{PP} at 5kHz, T _A = −40°C to +85°C	83			dB
THD	Total harmonic distortion	V _{IN} = ±250mV _{PP} at 5kHz		−95	−87	dB
		V _{IN} = ±250mV _{PP} at 5kHz, T _A = −40°C to +85°C			−88	dB
SFDR	Spurious-free dynamic range	V _{IN} = ±250mV _{PP} at 5kHz	88	95		dB
		V _{IN} = ±250mV _{PP} at 5kHz, T _A = −40°C to +85°C	90			dB
Voltage Reference Output ⁽⁶⁾						
V _{OUT}	Reference voltage output		2.440	2.5	2.560	V
dV _{OUT} /dT	Reference voltage temperature drift			±30		ppm/°C
		T _A = −40°C to +85°C		±20		ppm/°C
	Output voltage noise	f = 0.1Hz to 10Hz, C _L = 10μF		10		μVrms
		f =10Hz to 10kHz, C _L = 10μF		12		μVrms
PSRR	Power-supply rejection ratio			60		dB
I _{OUT}	Output current			10		μA
I _{SC}	Short-circuit current			0.5		mA
	Turn-on settling time	To 0.1% at C _L = 0		100		μs
Voltage Reference Input ⁽⁶⁾						
V _{IN}	Reference voltage input		0.5	2.5	2.6	V
	Reference input resistance			20		kΩ
	Reference input capacitance			5		pF
	Reference input current				1	μA
Digital Inputs ⁽⁷⁾						
	Logic family		CMOS with Schmitt Trigger			
V _{IH}	High-level input voltage		0.7×BV _{DD}	BV _{DD} +0.3		V
V _{IL}	Low-level input voltage		−0.3	0.3×BV _{DD}		V
I _{IN}	Input current	V _{IN} = BV _{DD} or GND		±50		nA
C _I	Input capacitance			5		pF
Digital Outputs ⁽⁷⁾						
	Logic family		CMOS			
V _{OH}	High-level output voltage	BV _{DD} = 4.5V, I _{OH} = −100μA	4.44			V
V _{OL}	Low-level output voltage	BV _{DD} = 4.5V, I _{OL} = +100μA			0.5	V
C _L	Load capacitance				30	pF
	Data format		Bit Stream			

(1) All typical values are at $\text{T}_\text{A} = +25^{\circ}\text{C}$.

(2) Integral nonlinearity is defined as the maximum deviation of the line through the end points of the specified input range of the transfer curve for $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, expressed either as the number of LSBs or as a percent of measured input range (500mV).

(3) Ensured by design.

(4) Maximum values, including temperature drift, are ensured over the full specified temperature range.

(5) With reduced accuracy, the supported external clock frequency range is 1MHz up to 32MHz.

(6) Available only for QFN package.

(7) Applicable for 5.0V nominal supply: $\text{BV}_{\text{DD}} = 4.5\text{V}$ to 5.5V .

(8) Applicable for 3.0V nominal supply: $\text{BV}_{\text{DD}} = 2.7\text{V}$ to 3.6V .

(9) Measured with CLKOUT pin not loaded.

ELECTRICAL CHARACTERISTICS (continued)

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $\text{AV}_{\text{DD}} = \text{BV}_{\text{DD}} = +5\text{V}$ or $\text{V}_{\text{DD}} = +5\text{V}$, $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, $\text{V}_{\text{IN}-} = 0\text{V}$, Mode 3, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.

PARAMETER		TEST CONDITIONS	ADS1203I			UNITS
			MIN	TYP ⁽¹⁾	MAX	
Digital Inputs ⁽⁶⁾⁽⁸⁾						
Logic family			LVCMOS			
V _{IH}	High-level input Voltage	BV _{DD} = 3.6V	2		BV _{DD} +0.3	V
V _{IL}	Low-level input voltage	BV _{DD} = 2.7V	-0.3		0.8	V
I _{IN}	Input current	V _I = BV _{DD} or GND			±50	nA
C _I	Input capacitance			5		pF
Digital Outputs ⁽⁶⁾⁽⁸⁾						
Logic family			LVCMOS			
V _{OH}	High-level output voltage	BV _{DD} = 2.7V, I _{OH} = -100μA	BV _{DD} -0.2			V
V _{OL}	Low-level output voltage	BV _{DD} = 2.7V, I _{OL} = +100μA	0.2			V
C _L	Load capacitance		30			pF
Data format			Bit Stream			
Power Supply						
V _{DD}	Supply voltage		4.5		5.5	V
AV _{DD} ⁽⁶⁾	Analog supply voltage		4.5		5.5	V
BV _{DD} ⁽⁶⁾	Buffer I/O supply voltage	Low-voltage levels	2.7		3.6	V
		5V logic levels	4.5		5.5	V
I _{DD}	Supply current	Mode 0		8.4	10.5	mA
		Mode 3		6.7	8.5	mA
AI _{DD} ⁽⁶⁾	Analog operating supply current	Mode 0		6.2	7.5	mA
		Mode 3		5.9	6.9	mA
BI _{DD} ⁽⁶⁾	Buffer I/O operating supply current	BV _{DD} = 3V, Mode 0		2.2	2.3	mA
		BV _{DD} = 3V, Mode 3 ⁽⁹⁾		0.8	0.9	mA
	Power dissipation	Mode 0		42	49	mW
		Mode 3 ⁽⁹⁾		33.5	39	mW

(1) All typical values are at $\text{T}_\text{A} = +25^{\circ}\text{C}$.

(2) Integral nonlinearity is defined as the maximum deviation of the line through the end points of the specified input range of the transfer curve for $\text{V}_{\text{IN}+} = -250\text{mV}$ to $+250\text{mV}$, expressed either as the number of LSBs or as a percent of measured input range (500mV).

(3) Ensured by design.

(4) Maximum values, including temperature drift, are ensured over the full specified temperature range.

(5) With reduced accuracy, the supported external clock frequency range is 1MHz up to 32MHz.

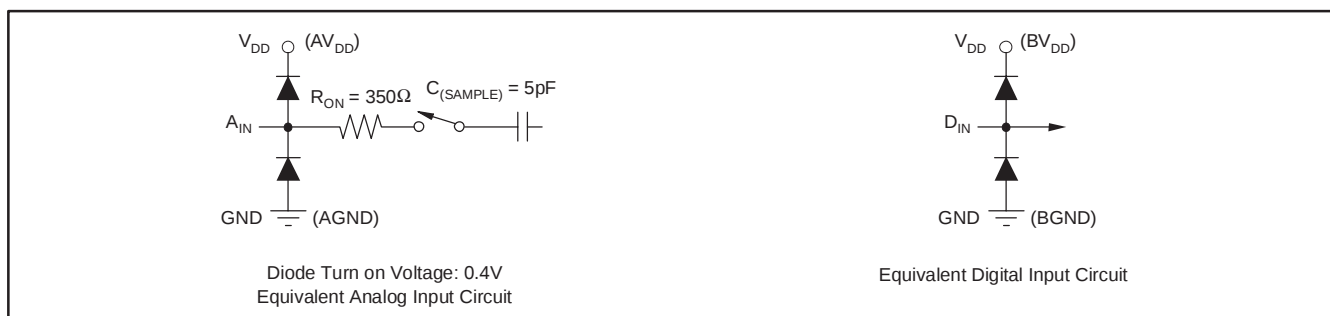
(6) Available only for QFN package.

(7) Applicable for 5.0V nominal supply: $\text{BV}_{\text{DD}} = 4.5\text{V}$ to 5.5V .

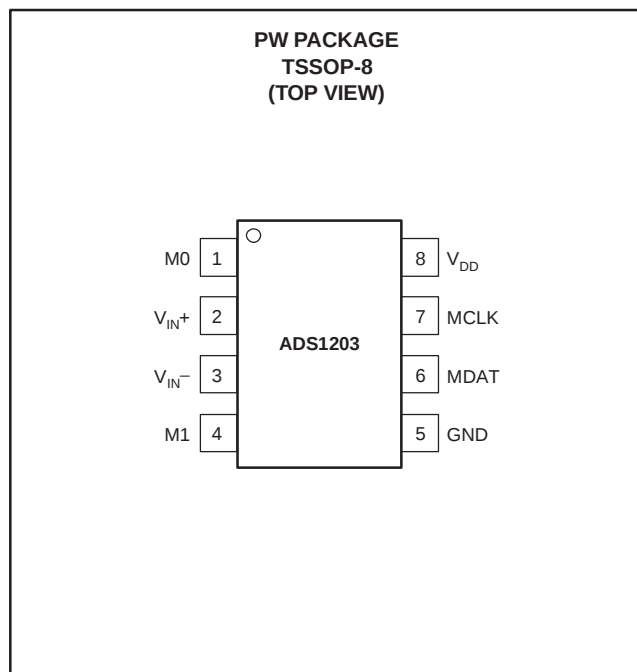
(8) Applicable for 3.0V nominal supply: $\text{BV}_{\text{DD}} = 2.7\text{V}$ to 3.6V .

(9) Measured with CLKOUT pin not loaded.

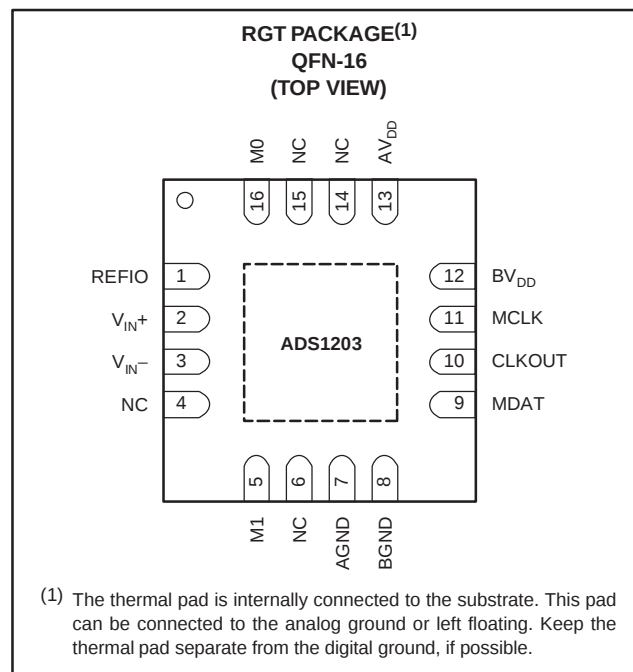
EQUIVALENT INPUT CIRCUIT



PIN ASSIGNMENTS: PW (TSSOP) PACKAGE



PIN ASSIGNMENTS: RGT (QFN) PACKAGE



Terminal Functions: PW (TSSOP) Package

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
M0	1	I	Mode input
V _{IN+}	2	I	Noninverting analog input
V _{IN-}	3	I	Inverting analog input
M1	4	I	Mode input
GND	5		Power supply ground
MDAT	6	O	Modulator data output
MCLK	7	I/O	Modulator clock input or output
V _{DD}	8		Power supply: +5V nominal

NOTE: For the TSSOP package, BGND and AGND are internally connected to the GND pin. Additionally, the AV_{DD} and BV_{DD} pins are connected to V_{DD}.

Terminal Functions: RGT (QFN) Package

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
REFIO	1	I/O	Reference voltage input/output
V _{IN+}	2	I	Noninverting analog input
V _{IN-}	3	I	Inverting analog input
NC	4, 6, 14, 15	I	Not connected
M1	5	I	Mode input
AGND	7		Analog power-supply ground
BGND	8		Interface power-supply ground
MDAT	9	O	Modulator data output
CLKOUT	10	O	Modulator clock output (Mode 3 only)
MCLK	11	I/O	Modulator clock input or output
BV _{DD}	12		Interface power supply
AV _{DD}	13		Analog power supply
M0	16		Mode input

PARAMETER MEASUREMENT INFORMATION

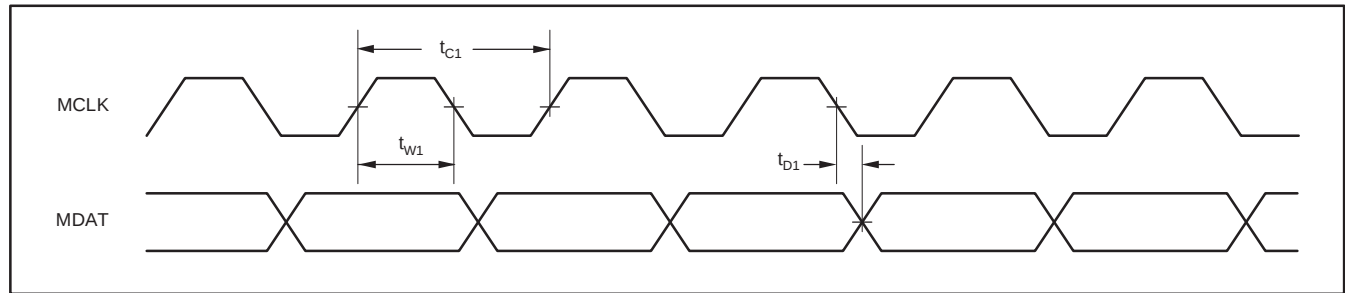


Figure 1. Mode 0 Operation

TIMING CHARACTERISTICS: MODE 0

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $AV_{DD} = BV_{DD} = +5V^{(1)}$ or $AV_{DD} = +5V$, $BV_{DD} = +3V^{(2)}$ or $V_{DD} = +5V^{(1)}$, unless otherwise noted.

PARAMETER	MODE	MIN	MAX	UNIT
t_{C1} Clock period	0	91	111	ns
t_{W1} Clock high time	0	$(t_{C1}/2) - 5$	$(t_{C1}/2) + 5$	ns
t_{D1} Data delay after falling edge of clock	0	-2	2	ns

(1) Applicable for 5.0V nominal supply: $BV_{DD}(\text{min}) = 4.5V$ and $BV_{DD}(\text{max}) = 5.5V$.

(2) Only for QFN package. Applicable for 3.0V nominal supply: $BV_{DD}(\text{min}) = 2.7V$ and $BV_{DD}(\text{max}) = 3.6V$.

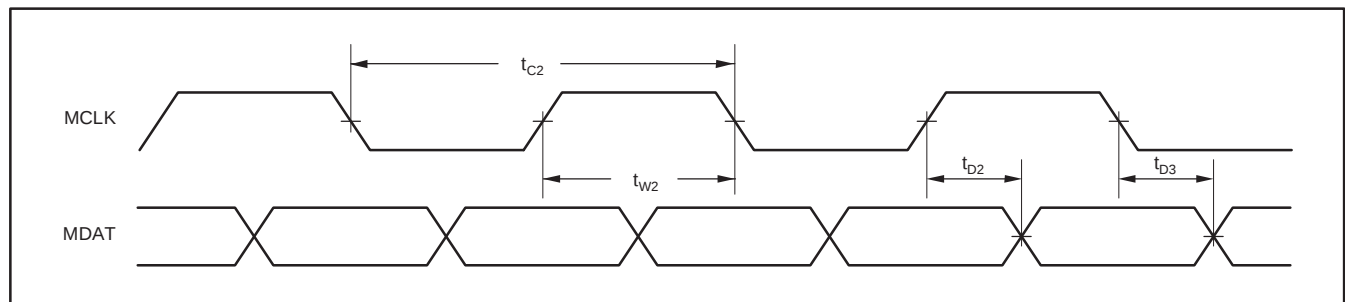


Figure 2. Mode 1 Operation

TIMING CHARACTERISTICS: MODE 1

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $AV_{DD} = BV_{DD} = +5V^{(1)}$ or $AV_{DD} = +5V$, $BV_{DD} = +3V^{(2)}$ or $V_{DD} = +5V^{(1)}$, unless otherwise noted.

PARAMETER	MODE	MIN	MAX	UNIT
t_{C2} Clock period	1	182	222	ns
t_{W2} Clock high time	1	$(t_{C2}/2) - 5$	$(t_{C2}/2) + 5$	ns
t_{D2} Data delay after rising edge of clock	1	$(t_{W2}/2) - 2$	$(t_{W2}/2) + 2$	ns
t_{D3} Data delay after falling edge of clock	1	$(t_{W2}/2) - 2$	$(t_{W2}/2) + 2$	ns

(1) Applicable for 5.0V nominal supply: $BV_{DD}(\text{min}) = 4.5V$ and $BV_{DD}(\text{max}) = 5.5V$.

(2) Only for QFN package. Applicable for 3.0V nominal supply: $BV_{DD}(\text{min}) = 2.7V$ and $BV_{DD}(\text{max}) = 3.6V$.

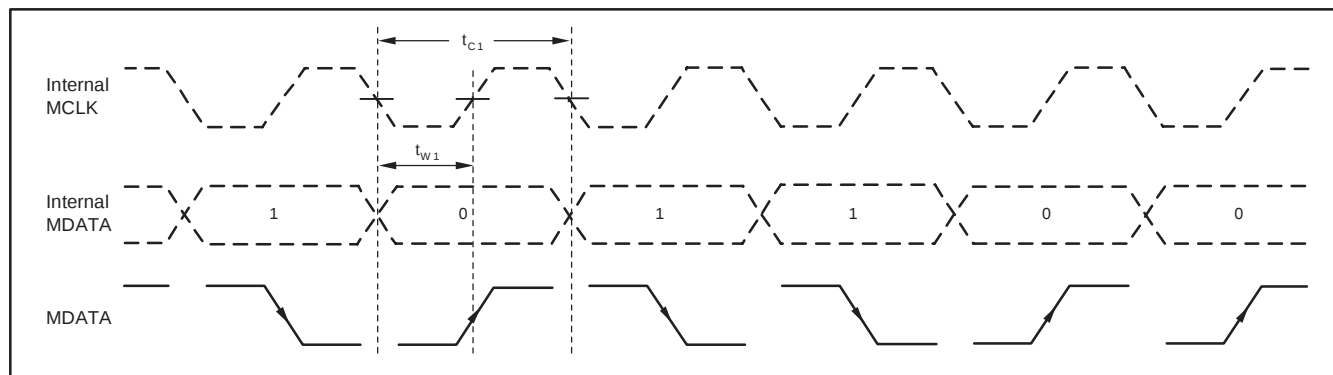


Figure 3. Mode 2 Operation

TIMING CHARACTERISTICS: MODE 2

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $\text{AV}_{\text{DD}} = \text{BV}_{\text{DD}} = +5\text{V}^{(1)}$ or $\text{AV}_{\text{DD}} = +5\text{V}$, $\text{BV}_{\text{DD}} = +3\text{V}^{(2)}$ or $\text{V}_{\text{DD}} = +5\text{V}^{(1)}$, unless otherwise noted.

PARAMETER	MODE	MIN	MAX	UNIT
t_{C1} Clock period	2	91	111	ns
t_{W1} Clock high time	2	$(t_{\text{C1}}/2) - 5$	$(t_{\text{C1}}/2) + 5$	ns

(1) Applicable for 5.0V nominal supply: BV_{DD} (min) = 4.5V and BV_{DD} (max) = 5.5V.

(2) Only for QFN package. Applicable for 3.0V nominal supply: BV_{DD} (min) = 2.7V and BV_{DD} (max) = 3.6V.

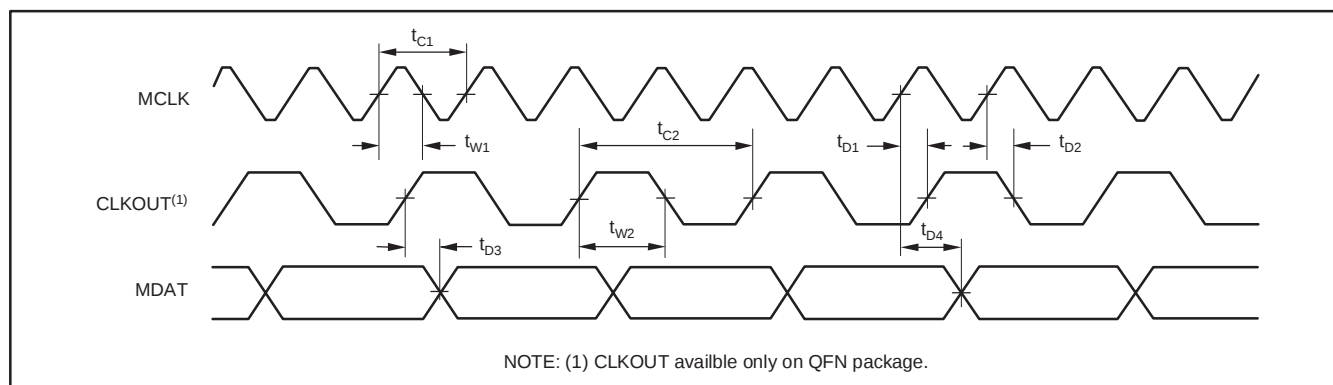


Figure 4. Mode 3 Operation

TIMING CHARACTERISTICS: MODE 3

Over recommended operating free-air temperature range at -40°C to $+125^{\circ}\text{C}$, $\text{AV}_{\text{DD}} = \text{BV}_{\text{DD}} = +5\text{V}^{(1)}$ or $\text{AV}_{\text{DD}} = +5\text{V}$, $\text{BV}_{\text{DD}} = +3\text{V}^{(2)}$ or $\text{V}_{\text{DD}} = +5\text{V}^{(1)}$, unless otherwise noted.

PARAMETER	MIN	MAX	UNIT
t_{C1} MCLK period	41.6	1000	ns
t_{W1} MCLK high time	10	$t_{\text{C1}} - 10$	ns
t_{C2} CLKOUT period	$2 \times t_{\text{C1}}$	$2 \times t_{\text{C1}}$	ns
t_{W2} CLKOUT high time	$(t_{\text{C2}}/2) - 5$	$(t_{\text{C2}}/2) + 5$	ns
t_{D1} CLKOUT rising edge delay after MCLK rising edge	0	10	ns
t_{D2} CLKOUT falling edge delay after MCLK rising edge	0	10	ns
t_{D3} Data valid delay after rising edge of CLKOUT	-2	+2	ns
t_{D4} Data valid delay after rising edge of MCLK	0	10	ns

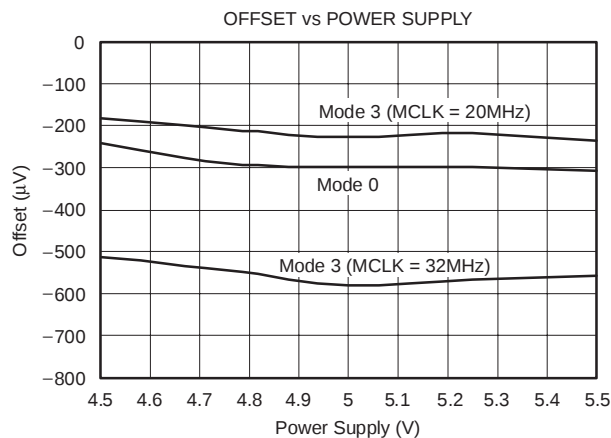
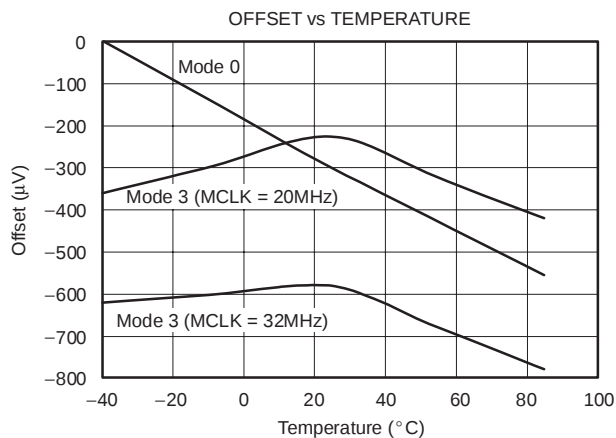
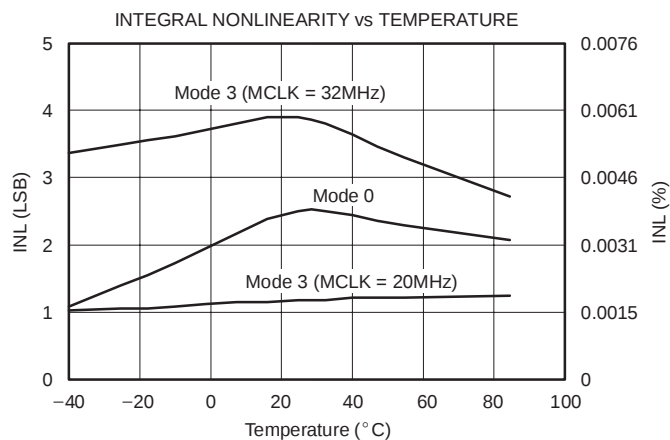
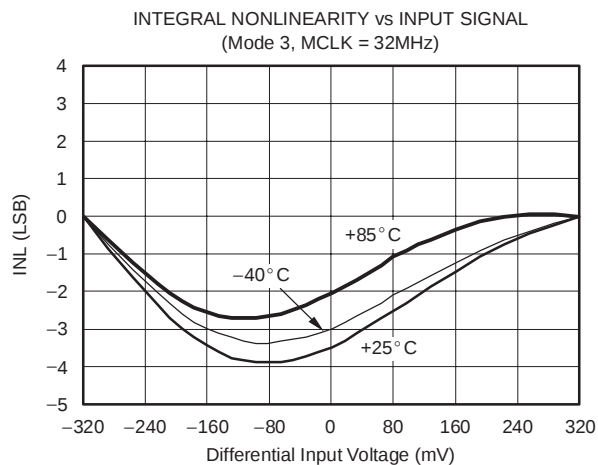
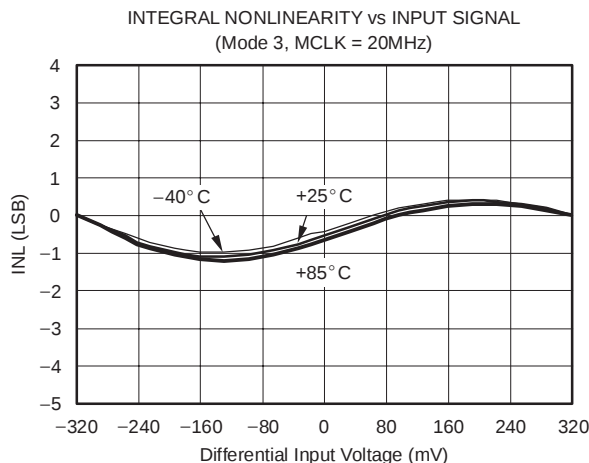
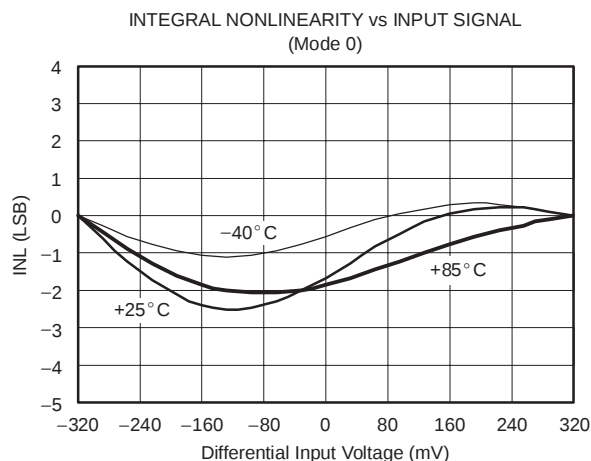
NOTE: Input signal is specified with $t_{\text{R}} = t_{\text{F}} = 5\text{ns}$ (10% to 90% of BV_{DD} or V_{DD}) and timed from a voltage level of $(V_{\text{IL}} + V_{\text{IH}})/2$. See timing diagram.

(1) Applicable for 5.0V nominal supply: BV_{DD} (min) = 4.5V and BV_{DD} (max) = 5.5V.

(2) Only for QFN package. Applicable for 3.0V nominal supply: BV_{DD} (min) = 2.7V and BV_{DD} (max) = 3.6V.

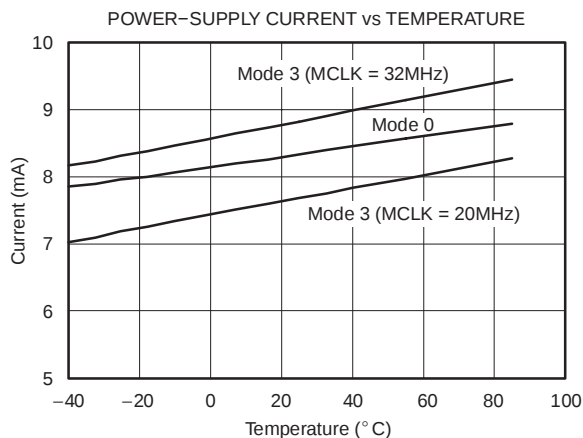
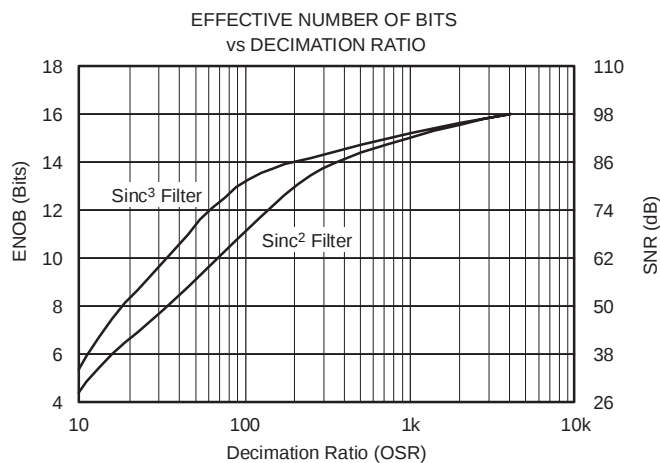
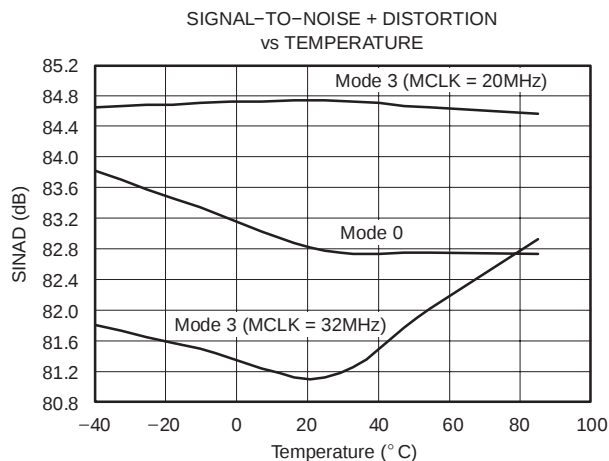
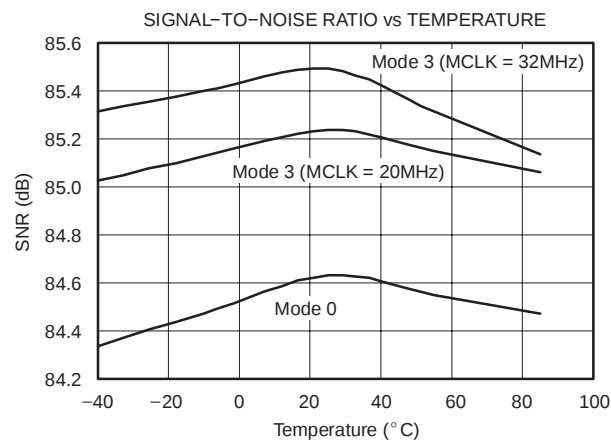
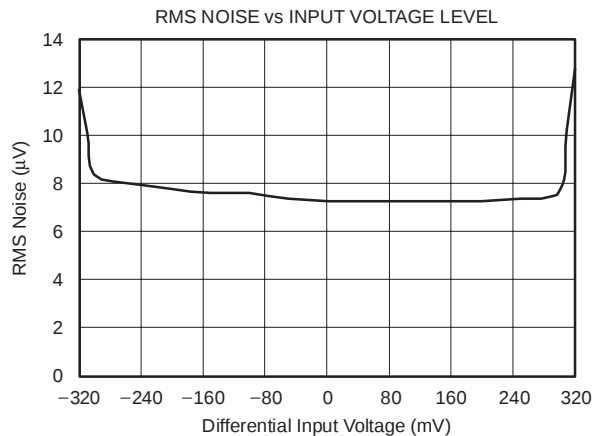
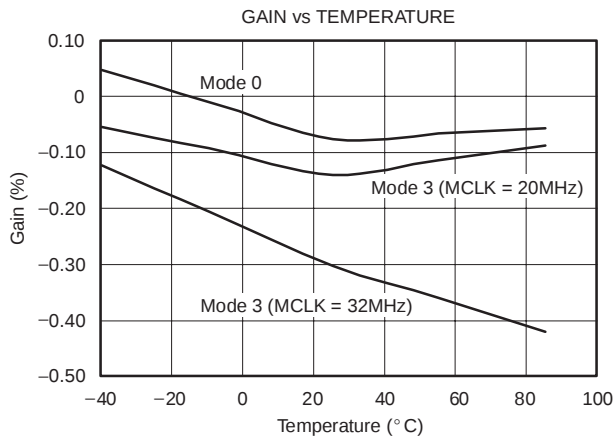
TYPICAL CHARACTERISTICS

$AV_{DD} = BV_{DD} = +5V$ or $V_{DD} = +5V$, $V_{IN+} = -250mV$ to $+250mV$, $V_{IN-} = 0V$, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.



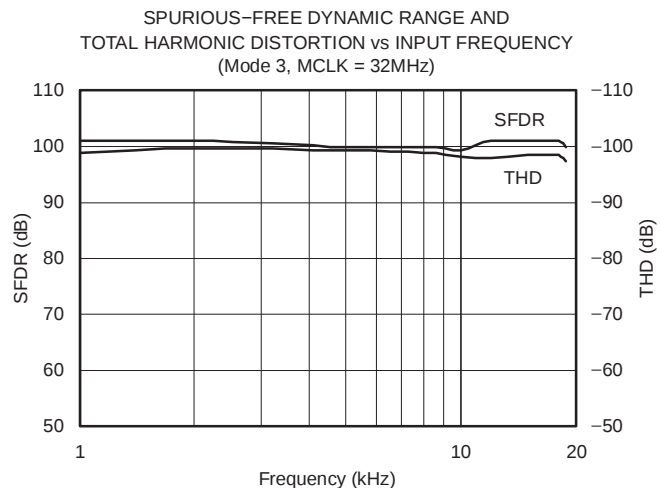
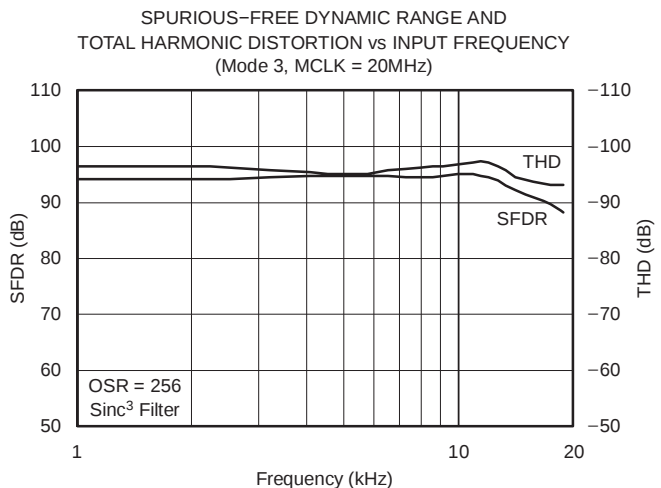
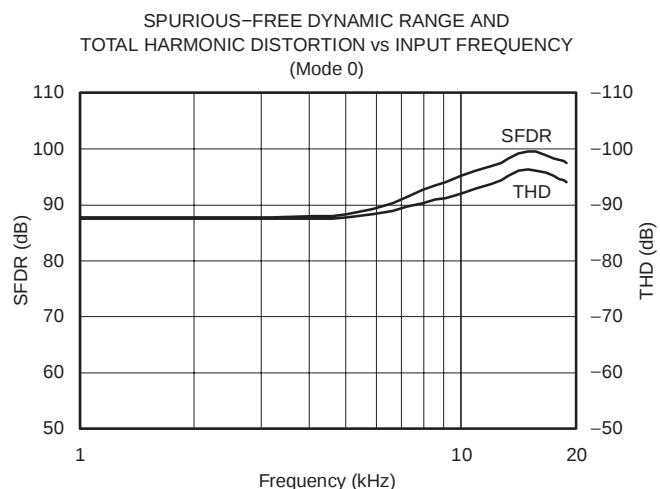
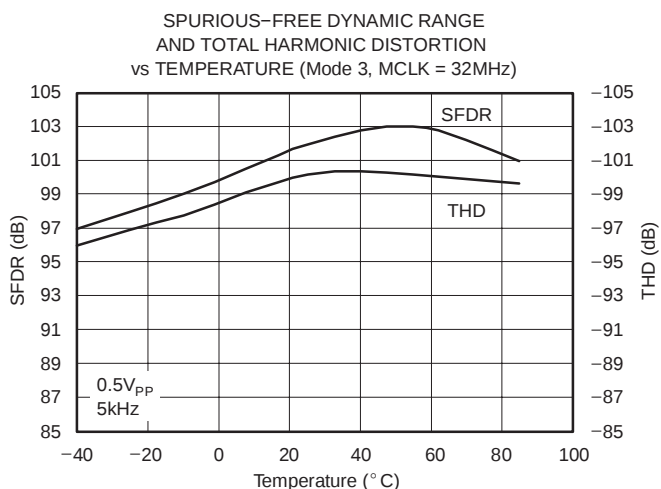
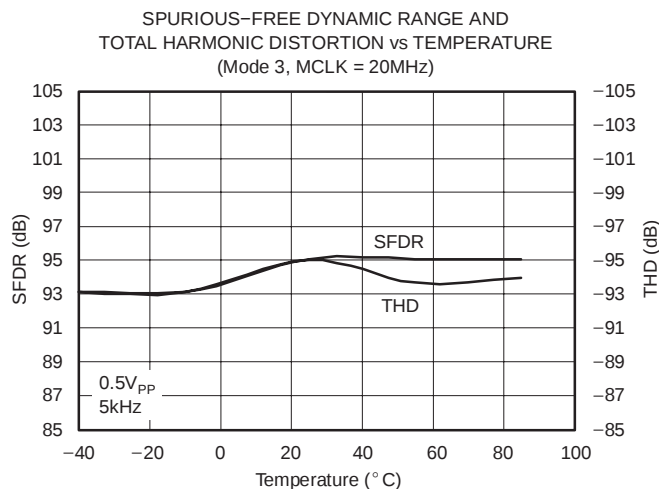
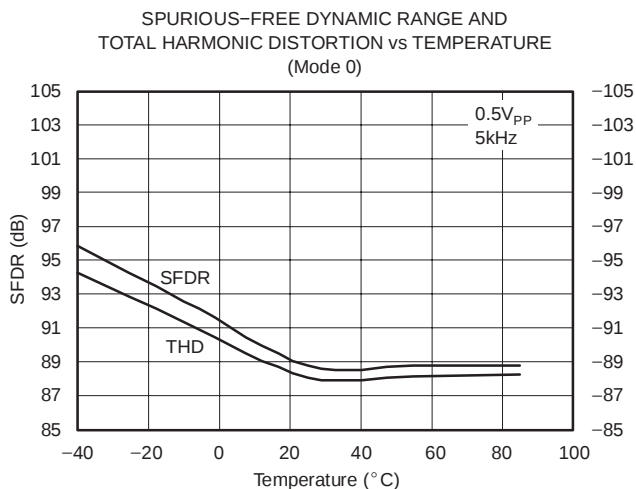
TYPICAL CHARACTERISTICS (continued)

$V_{DD} = BV_{DD} = +5V$ or $V_{DD} = +5V$, $V_{IN+} = -250mV$ to $+250mV$, $V_{IN-} = 0V$, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.



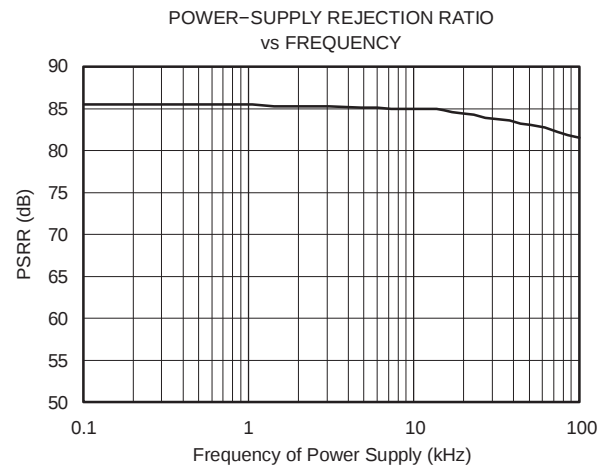
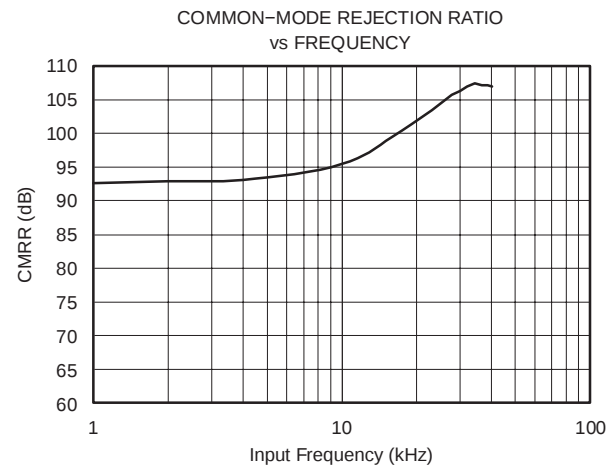
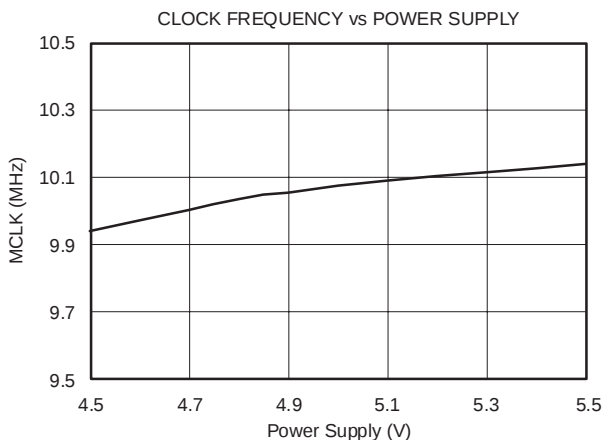
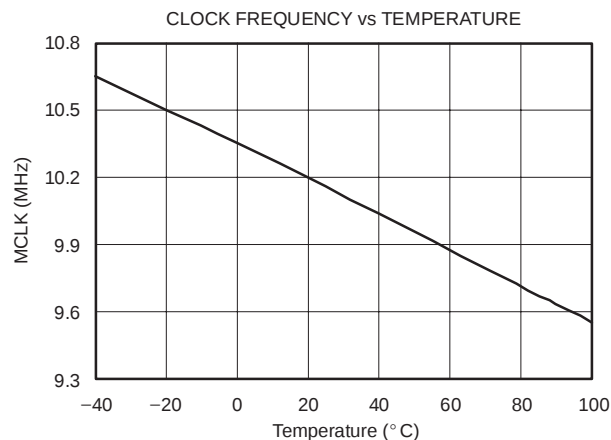
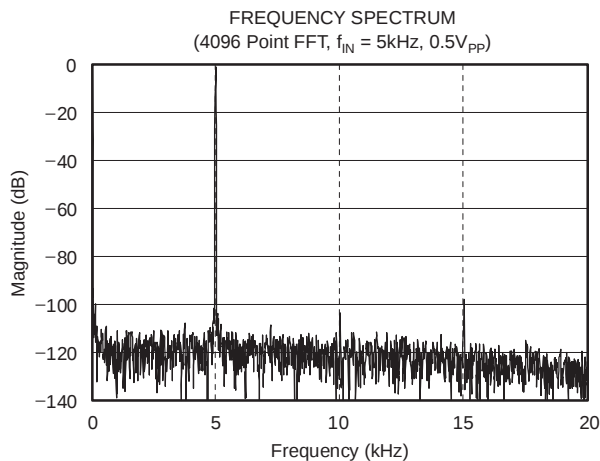
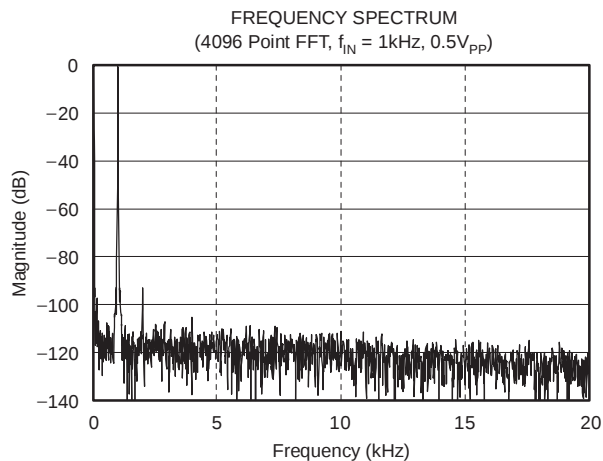
TYPICAL CHARACTERISTICS (continued)

$AV_{DD} = BV_{DD} = +5V$ or $V_{DD} = +5V$, $V_{IN+} = -250mV$ to $+250mV$, $V_{IN-} = 0V$, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.



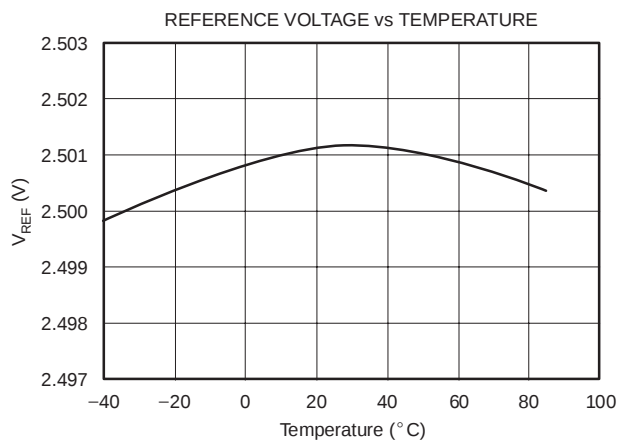
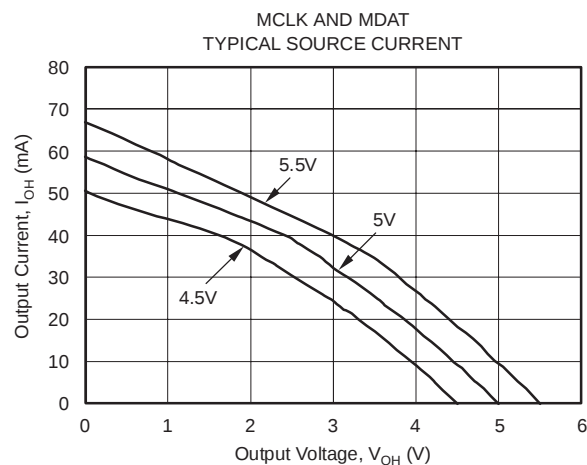
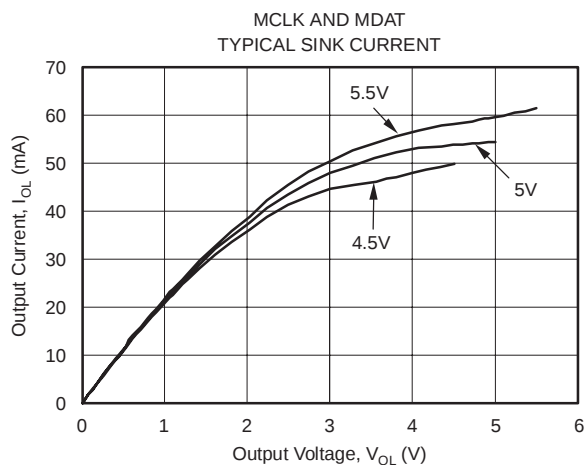
TYPICAL CHARACTERISTICS (continued)

$AV_{DD} = BV_{DD} = +5V$ or $V_{DD} = +5V$, $V_{IN+} = -250mV$ to $+250mV$, $V_{IN-} = 0V$, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.



TYPICAL CHARACTERISTICS (continued)

$AV_{DD} = BV_{DD} = +5V$ or $V_{DD} = +5V$, $V_{IN+} = -250mV$ to $+250mV$, $V_{IN-} = 0V$, MCLK input = 20MHz, and 16-bit Sinc³ filter, with OSR = 256, unless otherwise noted.



GENERAL DESCRIPTION

The ADS1203 is a single-channel, 2nd-order, CMOS delta-sigma modulator, designed for medium- to high-resolution A/D conversions from DC to 39kHz with an oversampling ratio (OSR) of 256. The output of the converter (MDAT) provides a stream of digital ones and zeros. The time average of this serial output is proportional to the analog input voltage.

The modulator shifts the quantization noise to high frequencies. A low-pass digital filter should be used at the output of the delta-sigma modulator. The primary purpose of the digital filter is to filter out high-frequency noise. The secondary purpose is to convert the 1-bit data stream at a high sampling rate into a higher-bit data word at a lower rate (decimation). A digital signal processor (DSP), microcontroller (μ C), or field programmable gate array (FPGA) could be used to implement the digital filter. Figure 6 shows the ADS1203 connected to a DSP.

The overall performance (speed and accuracy) depends on the selection of an appropriate OSR and filter type. A higher OSR produces greater output accuracy while operating at a lower refresh rate. Alternatively, a lower OSR produces lower output accuracy, but operates at a higher refresh rate. This system allows flexibility with the digital filter design and is capable of A/D conversion results that have a dynamic range exceeding 95dB with an OSR = 256.

THEORY OF OPERATION

The differential analog input of the ADS1203 is implemented with a switched-capacitor circuit. This circuit implements a 2nd-order modulator stage, which digitizes the analog input signal into a 1-bit output stream. The clock source can be internal as well as external. Different frequencies for this clock allow for a variety of solutions and signal bandwidths (however,

this can only be used in mode 3). The analog input signal is continuously sampled by the modulator and compared to an internal voltage reference. A digital stream, which accurately represents the analog input voltage over time, appears at the output of the converter.

REFERENCE

Under normal operation, REFIO (pin 1) provides an internal +2.5V reference to the ADS1203. However, the ADS1203 can operate with an external reference in the range of 0.5V to 2.6V, for a corresponding full-scale range of $0.256 \times \text{REFIO}$, as long as the input does not exceed the $\text{AV}_{\text{DD}} + 0.3\text{V}$ value. The recommended input range is $\pm 0.1 \times \text{REFIO}$.

The ADS1203 reference is double-buffered. If the internal reference is used to drive an external load, it can only drive a high-impedance load because $R_1 = 20\text{k}\Omega$. If an external reference voltage is used, the external source must be capable of driving the $20\text{k}\Omega$ resistor. To minimize noise, a $0.1\mu\text{F}$ capacitor should be connected to REFIO.

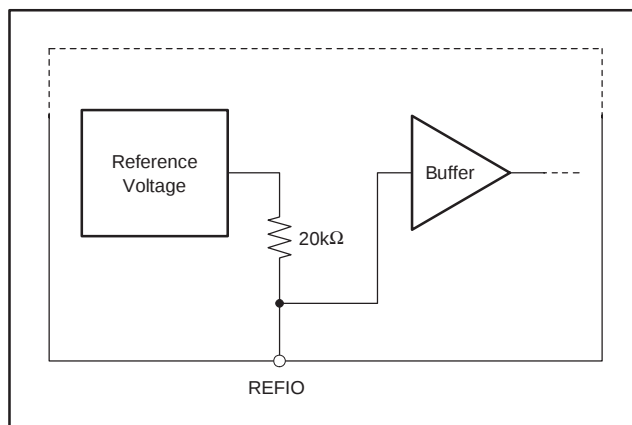


Figure 5. REFIO Voltage Reference Connection

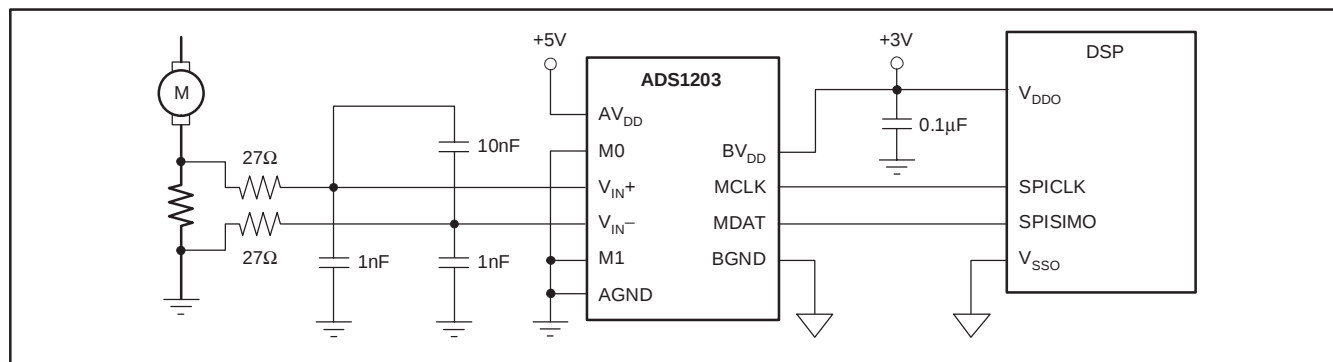


Figure 6. Connection Diagram for the ADS1203 Delta-Sigma Modulator Including DSP

ANALOG INPUT STAGE

Analog Input

The input design topology of the ADS1203 is based on a fully differential switched-capacitor architecture. This input stage provides the mechanism to achieve low system noise, high common-mode rejection (92dB), and excellent power-supply rejection.

The input impedance of the analog input depends on the modulator clock frequency (f_{CLK}), which is also the sampling frequency of the modulator. Figure 7 shows the basic input structure of the ADS1203. The relationship between the input impedance of the ADS1203 and the modulator clock frequency is:

$$Z_{IN} = \frac{28k\Omega}{f_{CLK}/10MHz} \quad (1)$$

The input impedance becomes a consideration in designs where the source impedance of the input signal is high. This may cause a degradation in gain, linearity and THD. The importance of this effect depends on the desired system performance. There are two restrictions on the analog input signals, V_{IN+} and V_{IN-} . If the input voltage exceeds the range $GND - 0.4V$ to $V_{DD} + 0.3V$, the input current must be limited to 10mA because the input protection diodes on the front end of the converter will begin to turn on. In addition, the linearity and the noise performance of the device are ensured only when the differential analog voltage resides within $\pm 250mV$; however, the FSR input voltage is $\pm 320mV$.

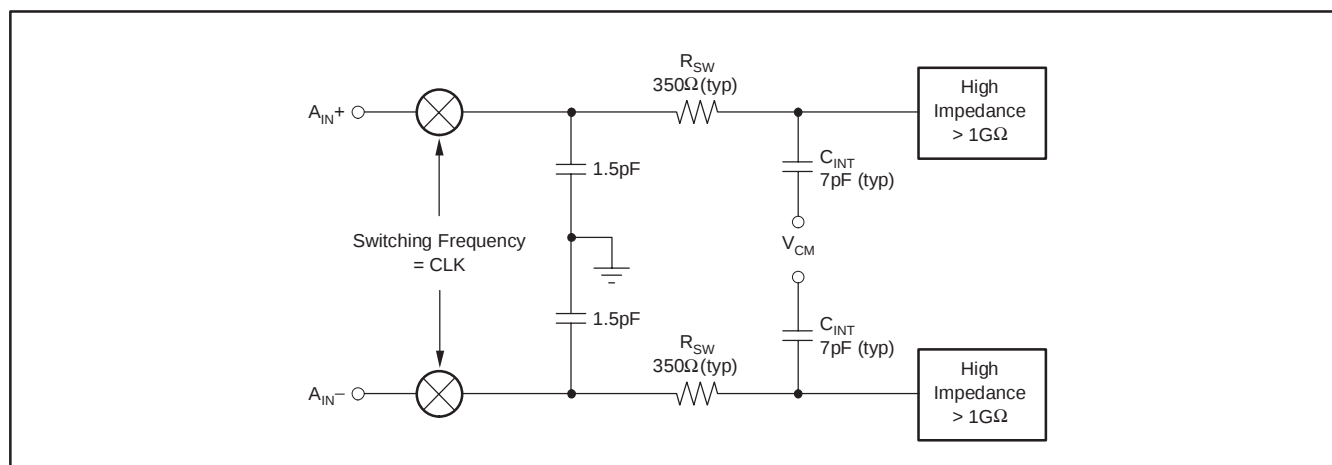


Figure 7. Input Impedance of the ADS1203

Modulator

The ADS1203 can be operated in four modes. Modes 0, 1, and 2 use the internal clock, which is fixed at 20MHz. The modulator can also be operated with an external clock in mode 3. In all modes, the clock is divided by 2 internally and is used as the modulator clock. The frequency of the external clock can vary from 1MHz to 32MHz to adjust for the clock requirements of the application.

The modulator topology is fundamentally a 2nd-order, switched-capacitor, delta-sigma modulator, such as the one conceptualized in Figure 8. The analog input voltage and the output of the 1-bit digital-to-analog converter (DAC) are differentiated, providing analog

voltages at X_2 and X_3 . The voltages at X_2 and X_3 are presented to the respective individual integrators. The output of these integrators progresses in a negative or positive direction. When the value of the signal at X_4 equals the comparator reference voltage, the output of the comparator switches from negative to positive, or positive to negative, depending on its original state. When the output value of the comparator switches from high to low or vice versa, the 1-bit DAC responds on the next clock pulse by changing its analog output voltage at X_6 , causing the integrators to progress in the opposite direction. The feedback of the modulator to the front end of the integrators forces the value of the integrator output to track the average of the input.

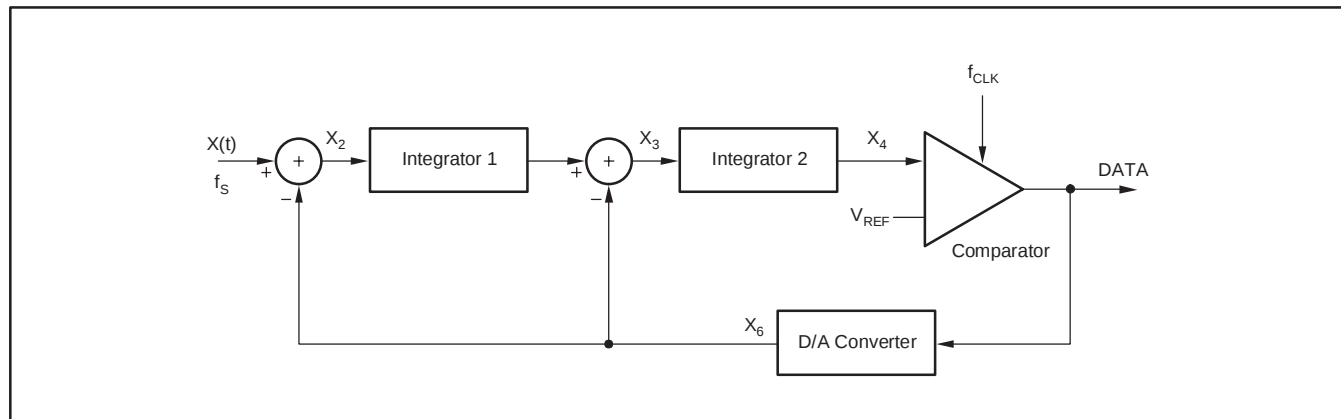


Figure 8. Block Diagram of the 2nd-Order Modulator

DIGITAL OUTPUT

A differential input signal of 0V ideally produces a stream of ones and zeros that is high 50% of the time and low 50% of the time. A differential input of +256mV produces a stream of ones and zeros that is high 80% of the time. A differential input of –256mV produces a stream of ones and zeros that is high 20% of the time. The input voltage versus the output modulator signal is shown in Figure 9.

DIGITAL INTERFACE

INTRODUCTION

The analog signal that is connected to the input of the delta-sigma modulator is converted using the clock signal applied to the modulator. The result of the conversion, or modulation, is the output signal DATA from the delta-sigma modulator. In most applications where a direct connection is realized between the delta-sigma modulator and an ASIC, FPGA, DSP, or μ C

(each with an implemented filter), the two standard signals (MCLK and MDAT) are provided from the modulator. To reduce the wiring (for example, for galvanic isolation), a single line is preferred. Therefore, in mode 2, the data stream is Manchester-encoded.

MODES OF OPERATION

The system clock of the ADS1203 is 20MHz by default. The system clock can be provided either from the internal 20MHz RC oscillator or from an external clock source. For this purpose, the MCLK pin is bidirectional and controlled by the mode setting.

The system clock is divided by 2 for the modulator clock. Therefore, the default clock frequency of the modulator is 10MHz. With a possible external clock range of 1MHz to 32MHz, the modulator operates between 500kHz and 16MHz.

The four modes of operation for the digital data interface are shown in Table 1.

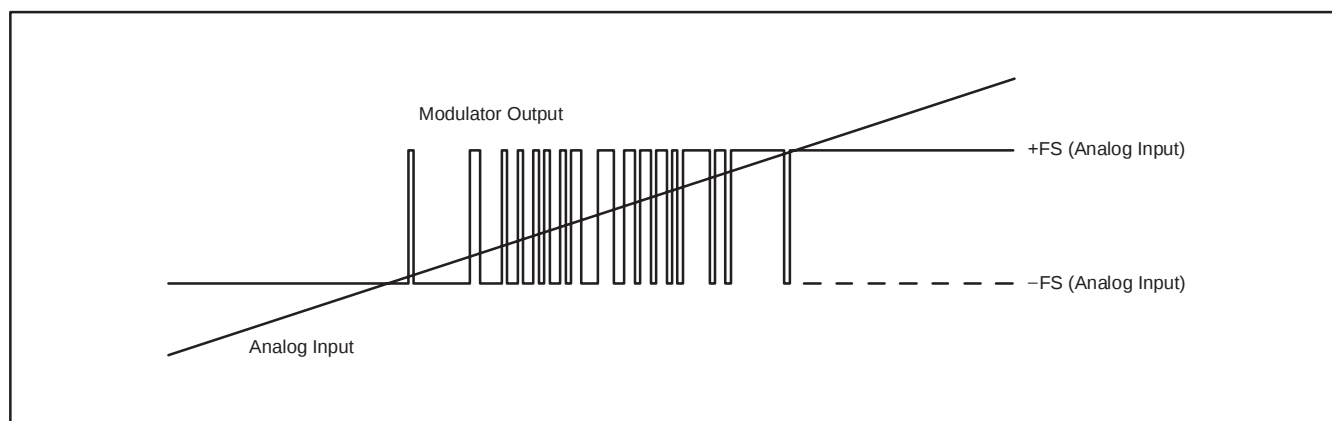


Figure 9. Analog Input vs Modulator Output of the ADS1203

Table 1. Digital Data Interface Modes of Operation

MODE	DEFINITION	M1	M0
0	Internal clock, synchronous data output	Low	Low
1	Internal clock, synchronous data output, half output clock frequency	Low	High
2	Internal clock, Manchester-encoded data output	High	Low
3	External clock, synchronous data output	High	High

Mode 0

In mode 0, the internal RC oscillator is running. The data are provided at the MDAT output pin, and the modulator clock at the MCLK pin. The data change at the falling edge of MCLK; therefore, the data can safely be strobed with the rising edge. See Figure 1 on page 7.

Mode 1

In mode 1, the internal RC oscillator is running. The data are provided at the MDAT output pin. The MCLK pin provides the half modulator clock. The data must be strobed at both the rising and falling edges of MCLK. The data at MDAT change in the middle, between the rising and falling edge. In this mode the frequency of both MCLK and MDAT is only 5MHz. See Figure 2 on page 7.

Mode 2

In mode 2, the internal RC oscillator is running. The data are Manchester-encoded and are provided at the MDAT pin. The MCLK output is set to low. There is no clock output provided in this mode. The Manchester coding allows the data transfer with only a single line. See Figure 3 on page 8.

Mode 3

In mode 3, the internal RC oscillator is disabled. The system clock must be provided externally at the input MCLK. The system clock must have twice the frequency of the chosen modulator clock. The data are provided at the MDAT output pin. Because the modulator runs with the half system clock, the data change at every other falling edge of the external clock. The data can safely be strobed at every other rising edge of MCLK. This mode allows synchronous operation to any digital system or the use of clocks different from 10MHz. See Figure 4 on page 8. On the QFN package, the modulator clock is provided as the CLKOUT signal. Output data can be strobed at each rising edge of CLKOUT.

FILTER USAGE

The modulator generates only a bitstream, which does not output a digital word like an analog-to-digital converter (ADC). In order to output a digital word equivalent to the analog input voltage, the bitstream must be processed by a digital filter.

A very simple filter built with minimal effort and hardware is the sinc³ filter:

$$H(z) = \left(\frac{1 - z^{-OSR}}{1 - z^{-1}} \right)^3 \quad (2)$$

This filter provides the best output performance at the lowest hardware size (for example, count of digital gates). For oversampling ratios in the range of 16 to 256, this is a good choice. All the characterizations in the data sheet are also done using a sinc³ filter with an oversampling ratio of OSR = 256 and an output word width of 16 bits.

In a sinc³ filter response (shown in Figure 10 and Figure 11), the location of the first notch occurs at the frequency of output data rate $f_{DATA} = f_{CLK}/OSR$. The -3dB point is located at half the Nyquist frequency or $f_{DATA}/4$. For some applications, it may be necessary to use another filter type for better frequency response.

This performance can be improved, for example, by a cascaded filter structure. The first decimation stage can be a sinc³ filter with a low OSR and the second stage a high-order filter.

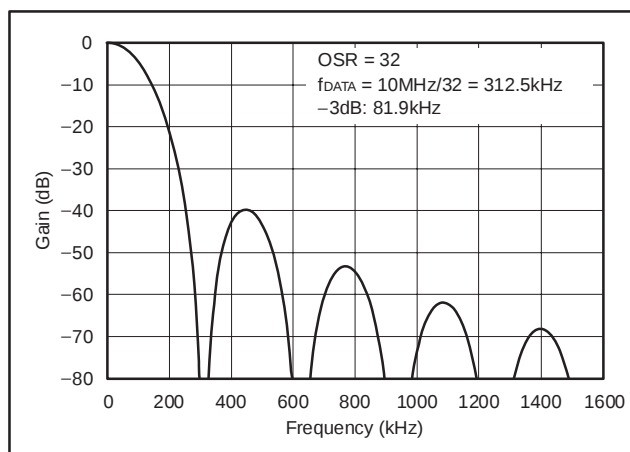


Figure 10. Frequency Response of Sinc³ Filter

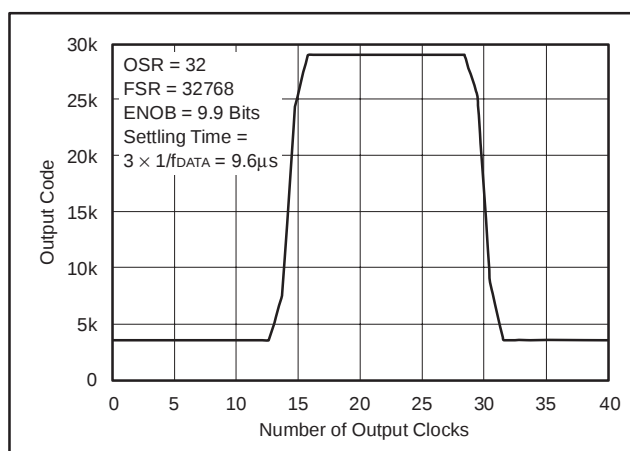


Figure 11. Pulse Response of Sinc³ Filter
($f_{MOD} = 10\text{MHz}$)

The effective number of bits (ENOB) can be used to compare the performance of ADCs and delta-sigma modulators. Figure 12 shows the ENOB of the ADS1203 with different filter types. In this data sheet, the ENOB is calculated from the SNR:

$$\text{SNR} = 1.76\text{dB} + 6.02\text{dB} \times \text{ENOB} \quad (3)$$

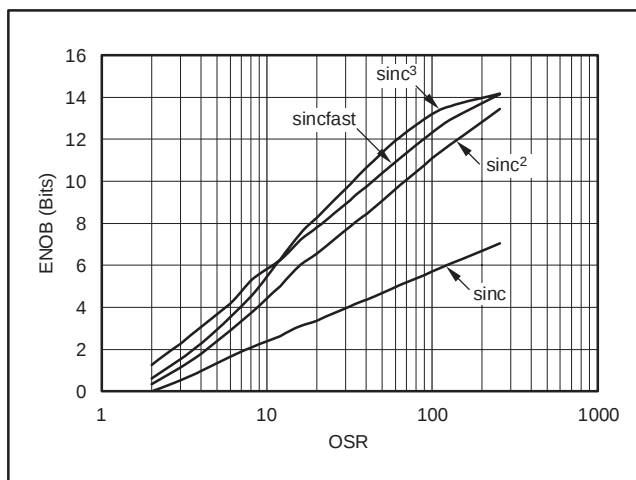


Figure 12. Measured ENOB vs OSR

In motor control applications, a very fast response time for overcurrent detection is required. There is a constraint between 1μs and 5μs with 3 bits to 7 bits resolution. The time for full settling depends on the filter order. Therefore, the full settling of the sinc³ filter needs three data clocks and the sinc² filter needs two data

clocks. The data clock is equal to the modulator clock divided by the OSR. For overcurrent protection, filter types other than sinc³ might be a better choice. A simple example is a sinc² filter. Figure 13 compares the settling time of different filter types. The sincfast is a modified sinc² filter:

$$H(z) = \left(\frac{1 - z^{-\text{OSR}}}{1 - z^{-1}} \right)^2 (1 + z^{-2 \times \text{OSR}}) \quad (4)$$

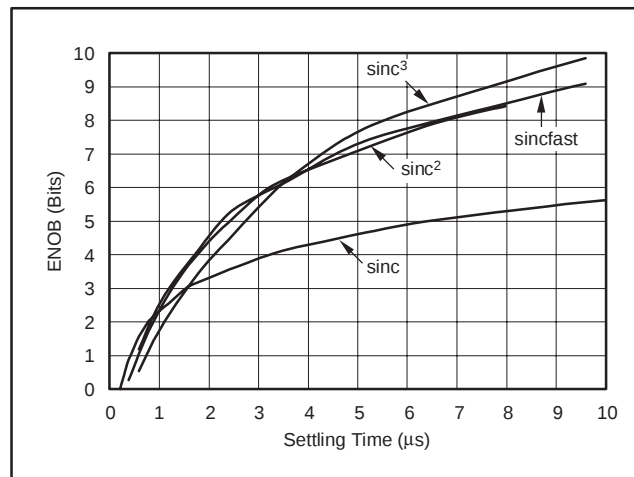


Figure 13. Measured ENOB vs Settling Time

For more information, see application note SBAA094, *Combining the ADS1202 with an FPGA Digital Filter for Current Measurement in Motor Control Applications*, available for download at www.ti.com.

APPLICATIONS

Operating the ADS1203 in a typical application using mode 0 is shown in Figure 14. Measurement of the motor phase current is done through the shunt resistor. For better performance, both signals are filtered. R_2 and C_2 filter noise on the noninverting input signal, R_3 and C_3 filter noise on the inverting input signal, and C_4 in combination with R_2 and R_3 filter the differential input signal. In this configuration, the shunt resistor is connected via three wires with the ADS1203.

The power supply is taken from the upper gate driver power supply. A decoupling capacitor of $0.1\mu\text{F}$ is recommended for filtering the power supply. If better filtering is required, an additional $1\mu\text{F}$ to $10\mu\text{F}$ capacitor can be added.

The control lines M0 and M1 are both low while the part is operating in mode 0. Two output signals, MCLK and MDAT, are connected directly to the optocoupler. The optocoupler can be connected to transfer a direct or inverse signal because the output stage has the capacity to source and sink the same current. The discharge resistor is not needed in parallel with optocoupler diodes because the output driver has push-pull capability to keep the LED diode out of the charge.

The DSP (such as a C28x or C24x) can be directly connected at the output of two channels of the optocoupler. In this configuration, the signals arriving at C28x or C24x are standard delta-sigma modulator signals and are connected directly to the SPICLK and SPISIMO pins. Being a delta-sigma converter, there is no need to have word sync on the serial data, so an SPI is ideal for connection. McBSP would work as well in SPI mode.

When component reduction is necessary, the ADS1203 can operate in mode 2, as shown in Figure 15. M1 is high and M0 is low. Only the noninverting input signal is filtered. R_2 and C_2 filter noise on the input signal. The inverting input is directly connected to the GND pin, which is simultaneously connected to the shunt resistor.

The output signal from the ADS1203 is Manchester-encoded. In this case, only one signal is transmitted. For that reason, one optocoupler channel is used instead of two channels, as in the previous example of Figure 14. Another advantage of this configuration is that the DSP will use only one line per channel instead of two. That permits the use of smaller DSP packages in the application.

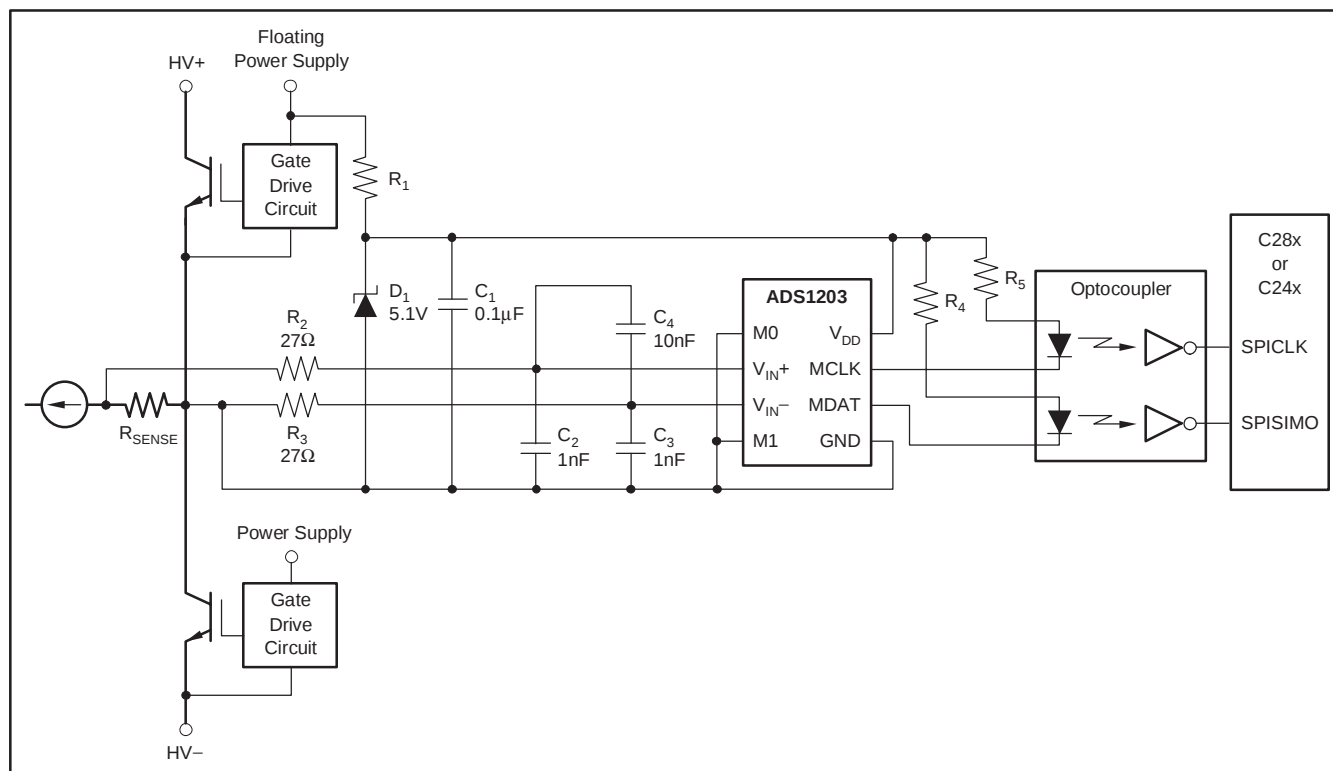


Figure 14. Application Diagram in Mode 0

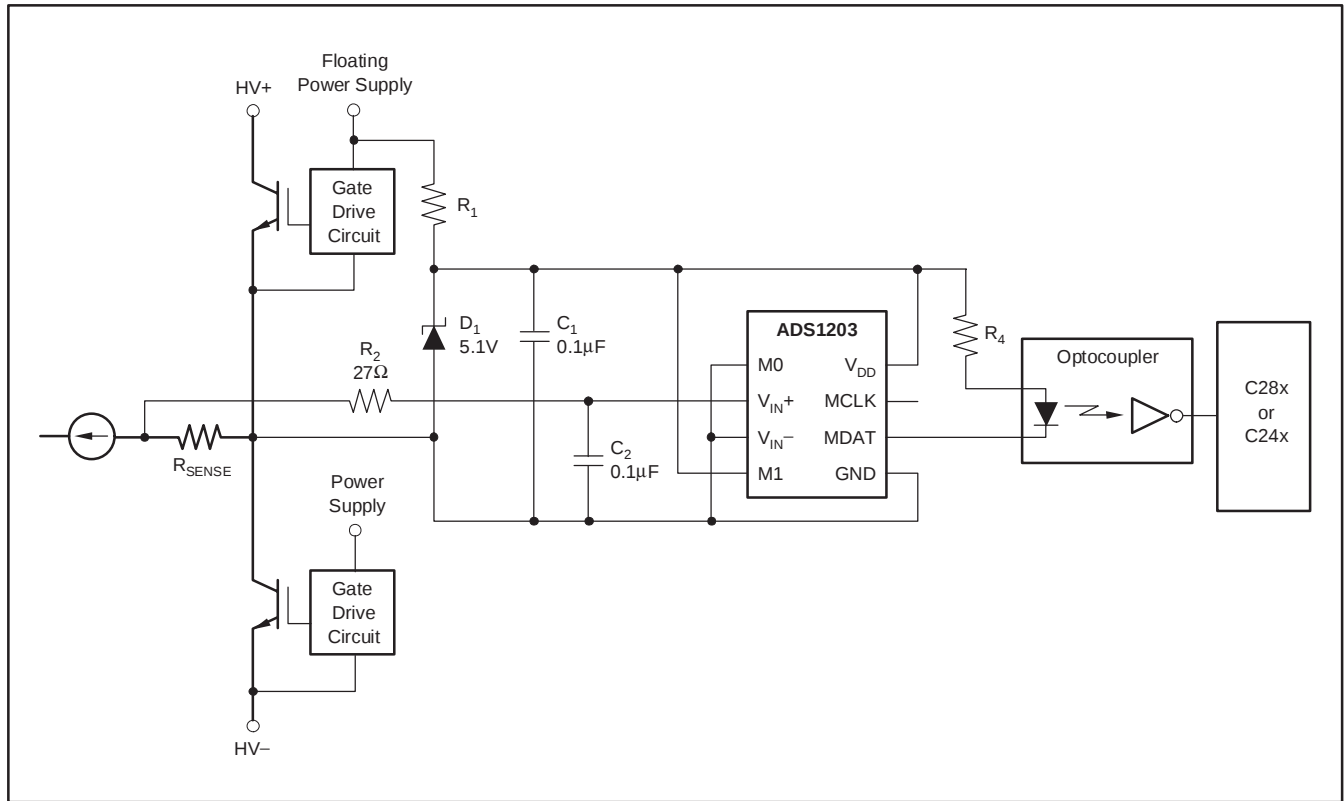


Figure 15. Application Diagram in Mode 2

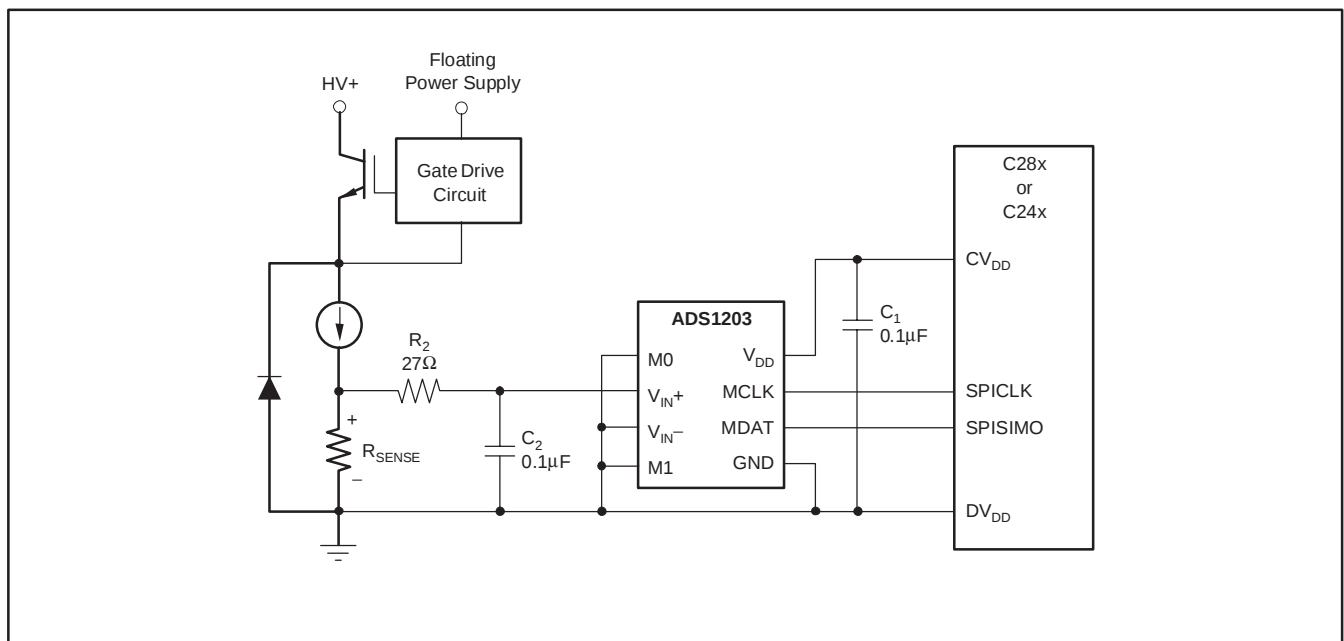


Figure 16. Application Diagram without Galvanic Isolation in Mode 0

22

LAYOUT CONSIDERATIONS

Power Supplies

The ADS1203 requires only one power supply (V_{DD}). If there are separate analog and digital power supplies on the board, a good design approach is to have the ADS1203 connected to the analog power supply. Another possible approach to control noise is the use of a resistor on the power supply. The connection can be made between the ADS1203 power-supply pins via a 10Ω resistor. The combination of this resistor and the decoupling capacitors between the power-supply pins on the ADS1203 provide some filtering. The analog supply that is used must be well-regulated and generate low noise. For designs requiring higher resolution from the ADS1203, power-supply rejection will be a concern. The digital power supply has high-frequency noise that can be capacitively coupled into the analog portion of the ADS1203. This noise can originate from switching power supplies, microprocessors, or DSPs. High-frequency noise will generally be rejected by the external digital filter at integer multiples of MCLK. Just below and above these frequencies, noise will alias back into the passband of the digital filter, affecting the conversion result. Inputs to the ADS1203, such as V_{IN+} , V_{IN-} , and MCLK should not be present before the power supply is on. Violating this condition could cause latch-up. If these signals are present before the supply

is on, series resistors should be used to limit the input current. Experimentation may be the best way to determine the appropriate connection between the ADS1203 and different power supplies.

Grounding

Analog and digital sections of the design must be carefully and cleanly partitioned. Each section should have its own ground plane with no overlap between them. Do not join the ground planes; instead, connect the two with a moderate signal trace underneath the converter. For multiple converters, connect the two ground planes as close as possible to one central location for all of the converters. In some cases, experimentation may be required to find the best point to connect the two planes together.

Decoupling

Good decoupling practices must be used for the ADS1203 and for all components in the design. All decoupling capacitors, specifically the $0.1\mu\text{F}$ ceramic capacitors, must be placed as close as possible to the pin being decoupled. A $1\mu\text{F}$ and $10\mu\text{F}$ capacitor, in parallel with the $0.1\mu\text{F}$ ceramic capacitor, can be used to decouple V_{DD} to GND. At least one $0.1\mu\text{F}$ ceramic capacitor must be used to decouple V_{DD} to GND, as well as for the digital supply on each digital component.

Revision History

DATE	REV	PAGE	SECTION	DESCRIPTION
1/08	C	1	Features	Changed upper Operating Temperature Range from +85°C to +125°C.
		2	Absolute Maximum Ratings	Changed upper Operating Free-Air Temperature Range from +85°C to +125°C.
			Recommended Operating Conditions	Changed upper Operating Junction Temperature Range from +105°C to +150°C.
			Dissipation Ratings	Deleted R _{θJA} column.
				Changed values.
		3	Electrical Characteristics	Changed condition; upper temperature range from +85°C to +125°C.
				Added rows with values for updated temperature range.
				Changed values throughout table.
				Changed notes 5, 7, and 8.
		7, 8	Parameter Measurement Information	Changed upper temperature range for all four timing characteristics tables from +85°C to +125°C.
8/07	B	5	Equivalent Input Circuit	Moved Equivalent Input Circuit figure to bottom of page 5.
		6	Pin Assignments	Added note to QFN package.

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
ADS1203IPWT	Active	Production	TSSOP (PW) 8	250 SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AZ1203
ADS1203IPWT.B	Active	Production	TSSOP (PW) 8	250 SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AZ1203
ADS1203IRGTR.B	Active	Production	VQFN (RGT) 16	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	A03I
ADS1203IRGTT	Active	Production	VQFN (RGT) 16	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	A03I
ADS1203IRGTT.B	Active	Production	VQFN (RGT) 16	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	A03I
ADS1203IRGTTG4	Active	Production	VQFN (RGT) 16	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	A03I
ADS1203IRGTTG4.B	Active	Production	VQFN (RGT) 16	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	A03I

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS1203IPWT	TSSOP	PW	8	250	180.0	12.4	7.0	3.6	1.6	8.0	12.0	Q1
ADS1203IRGTT	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
ADS1203IRGTTG4	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

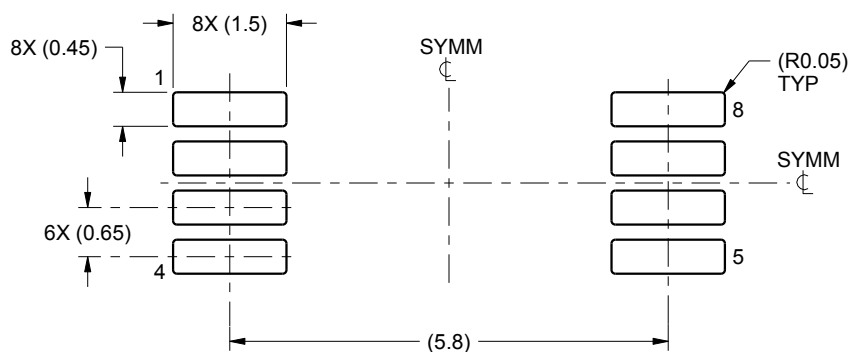
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS1203IPWT	TSSOP	PW	8	250	210.0	185.0	35.0
ADS1203IRGTT	VQFN	RGT	16	250	210.0	185.0	35.0
ADS1203IRGTTG4	VQFN	RGT	16	250	210.0	185.0	35.0

EXAMPLE BOARD LAYOUT

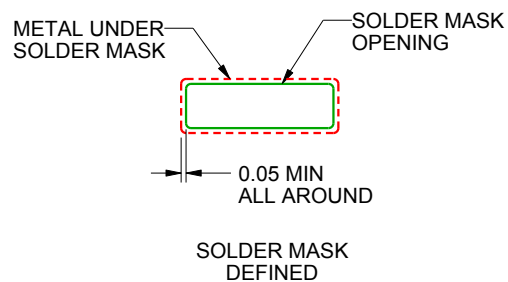
PW0008A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE
SCALE:10X



SOLDER MASK DETAILS
NOT TO SCALE

4221848/A 02/2015

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

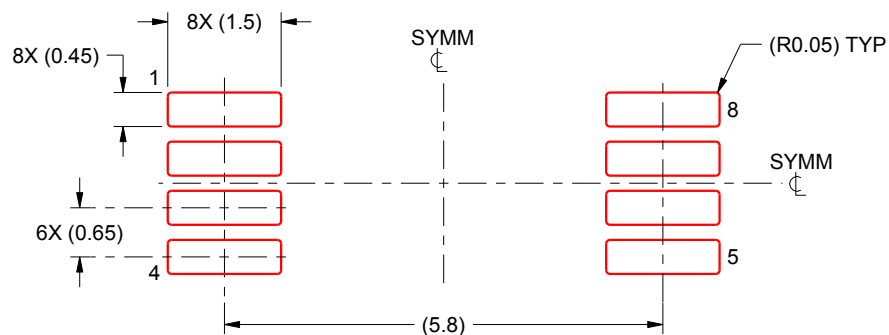
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

PW0008A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:10X

4221848/A 02/2015

NOTES: (continued)

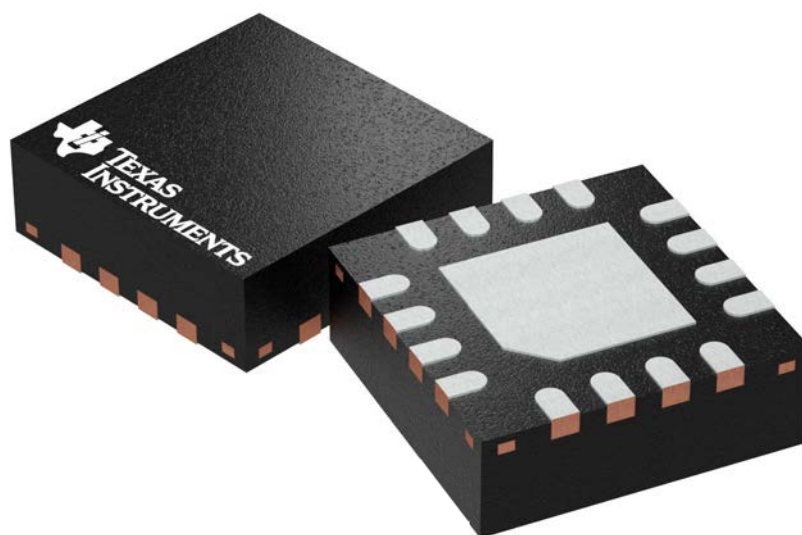
8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

RGT 16

GENERIC PACKAGE VIEW

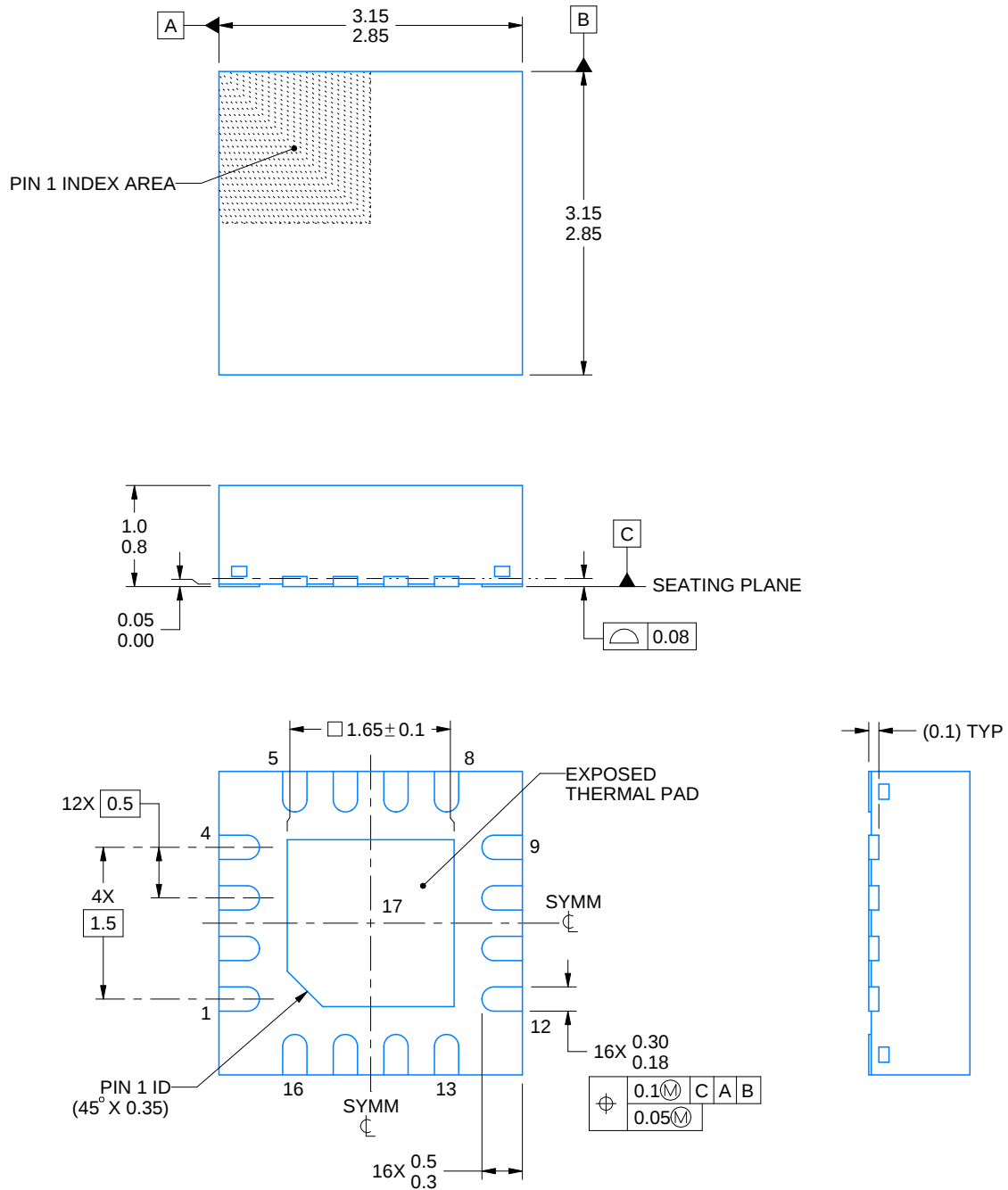
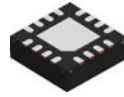
VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4203495/1



4230572/A 07/2025

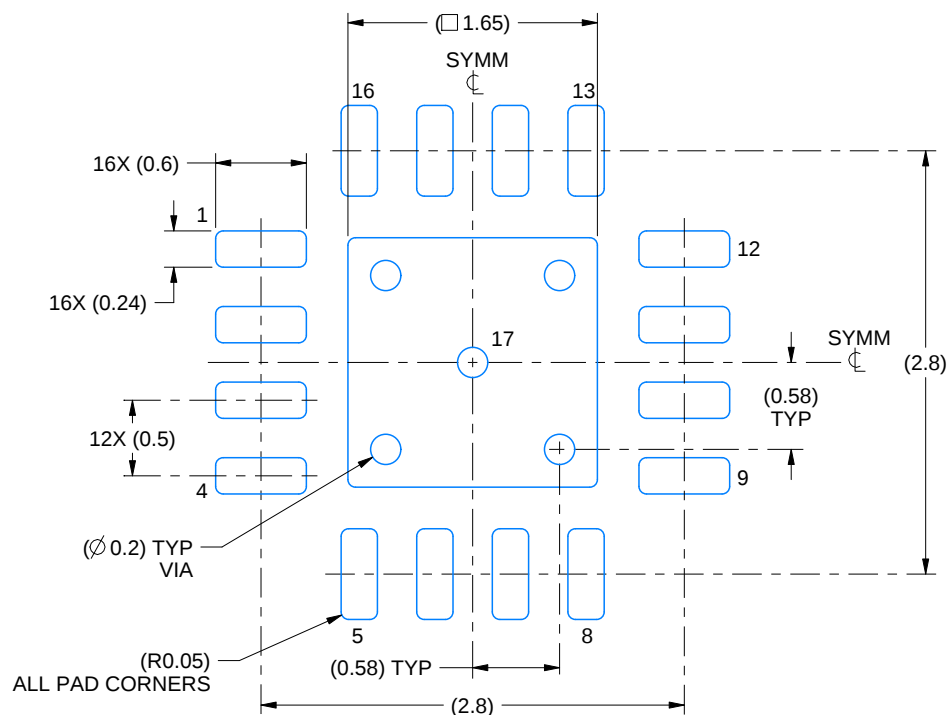
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

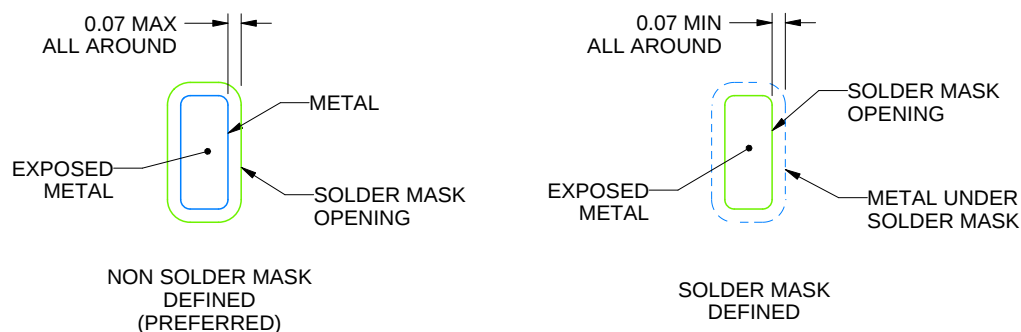
RG T0016F

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:20X



SOLDER MASK DETAILS

4230572/A 07/2025

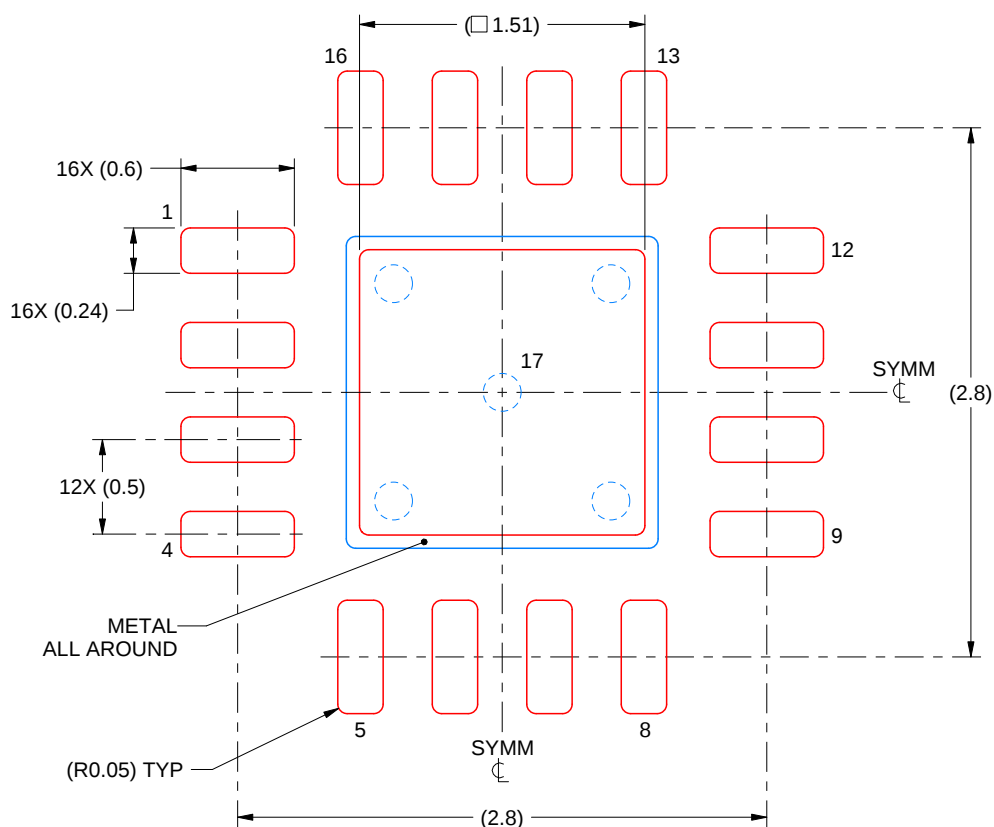
NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

RG T0016F

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 17:
84% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE
SCALE:25X

4230572/A 07/2025

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated