

# PWM LED Driver and Boost, Flyback and SEPIC Controller

## FEATURES

- **True Color PWM™ Delivers Constant Color with 3000:1 Dimming Ratio**
- **Fully Integrated Load FET Driver for PWM Dimming Control of High Power LEDs**
- **100:1 Dimming from Analog Inputs**
- **Wide FB Voltage Range: 0V to 1.23V**
- **Constant Current or Constant Voltage Regulation**
- Low Shutdown Current:  $I_Q = 20\mu A$
- 1% 1.23V Internal Voltage Reference
- 2% RUN Pin Threshold with 100mV Hysteresis
- Programmable Operating Frequency (20kHz to 1MHz) with One External Resistor
- Synchronizable to an External Clock Up to  $1.3f_{OSC}$
- Internal 7V Low Dropout Voltage Regulator
- Programmable Output Overvoltage Protection
- Programmable Soft-Start
- Can be Used in a No  $R_{SENSE}^{\text{TM}}$  Mode for  $V_{DS} < 36V$
- 16-Lead DFN and TSSOP Packages

## APPLICATIONS

- High Voltage LED Arrays
- Telecom Power Supplies
- 42V Automotive Systems
- 24V Industrial Controls
- IP Phone Power Supplies

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## DESCRIPTION

The LTC®3783 is a current mode LED driver and boost, flyback and SEPIC controller that drives both an N-channel power MOSFET and an N-channel load PWM switch. When using an external load switch, the PWMIN input not only drives PWMOUT, but also enables controller GATE switching and error amplifier operation, allowing the controller to store load current information while PWMIN is low. This feature (patent pending) provides extremely fast, true PWM load switching with no transient overvoltage or undervoltage issues; LED dimming ratios of 3000:1 can be achieved digitally, avoiding the color shift normally associated with LED current dimming. The FBP pin allows analog dimming of load current, further increasing the effective dimming ratio by 100:1 over PWM alone.

In applications where output load current must be returned to  $V_{IN}$ , optional constant current/constant voltage regulation controls either output (or input) current or output voltage and provides a limit for the other.  $I_{LIM}$  provides a 10:1 analog dimming ratio.

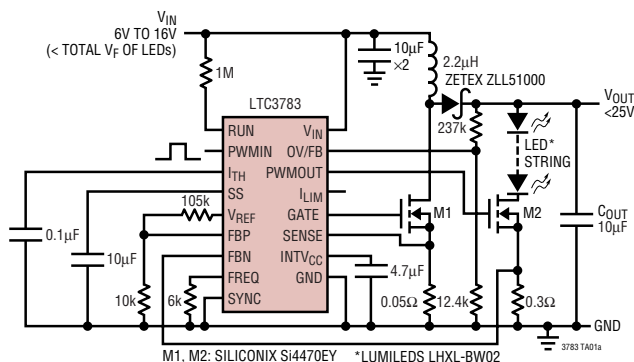
For low- to medium-power applications, No  $R_{SENSE}$  mode can utilize the power MOSFET's on-resistance to eliminate the current-sense resistor, thereby maximizing efficiency.

The IC's operating frequency can be set with an external resistor over a 20kHz to 1MHz range and can be synchronized to an external clock using the SYNC pin.

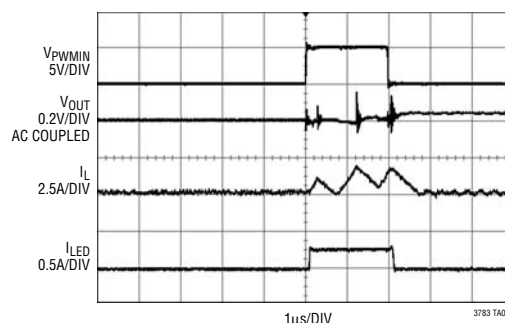
The LTC3783 is available in the 16-lead DFN and TSSOP packages.

## TYPICAL APPLICATION

### 350mA PWM LED Boost Application



## Typical Waveforms



**ABSOLUTE MAXIMUM RATINGS** (Note 1)

$V_{IN}$ , SENSE, FBP, FBN Voltages ..... -0.3V to 42V  
 $INTV_{CC}$  Voltage ..... -0.3V to 9V  
 $INTV_{CC}$  Output Current ..... 75mA  
 GATE Output Current ..... 50mA (RMS)  
 PWMOUT Output Current ..... 25mA (RMS)  
 $V_{REF}$  Output Current ..... 1mA  
 GATE, PWMOUT Voltages ..... -0.3V to ( $V_{INTVCC} + 0.3V$ )  
 $I_{TH}$ ,  $I_{LIM}$ , SS Voltages ..... -0.3V to 2.7V  
 RUN, SYNC, PWMIN Voltages ..... -0.3V to 7V

FREQ,  $V_{REF}$ , OV/FB Voltages ..... -0.3V to 1.5V  
 Operating Junction Temperature Range  
 (Note 2) ..... -40°C to 85°C  
 Junction Temperature (Note 3) ..... -40°C to 125°C  
 Storage Temperature Range  
 DFN Package ..... -65°C to 125°C  
 TSSOP Package ..... -65°C to 150°C  
 Lead Temperature (Soldering, 10sec)  
 TSSOP Package ..... 300°C

**PACKAGE/ORDER INFORMATION**

|                                                                                                                                                                                                                                            |                                                                                 |                                                                                                                                                                                                            |                                            |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------|
| <p>TOP VIEW</p> <p>DHD PACKAGE<br/>16-LEAD (5mm × 4mm) PLASTIC DFN<br/><math>T_{JMAX} = 125^{\circ}C</math>, <math>\theta_{JA} = 43^{\circ}C/W</math><br/>EXPOSED PAD (PIN 17) IS GND<br/>MUST BE SOLDERED TO PCB</p>                      | <p>ORDER PART NUMBER</p> <p>LTC3783EDHD</p> <p>DHD PART MARKING</p> <p>3783</p> | <p>TOP VIEW</p> <p>FE PACKAGE<br/>16-LEAD PLASTIC TSSOP<br/><math>T_{JMAX} = 125^{\circ}C</math>, <math>\theta_{JA} = 38^{\circ}C/W</math><br/>EXPOSED PAD (PIN 17) IS GND<br/>MUST BE SOLDERED TO PCB</p> | <p>ORDER PART NUMBER</p> <p>LTC3783EFE</p> |
| <p><b>Order Options</b> Tape and Reel: Add #TR<br/>         Lead Free: Add #PBF Lead Free Tape and Reel: Add #TRPBF<br/>         Lead Free Part Marking: <a href="http://www.linear.com/leadfree/">http://www.linear.com/leadfree/</a></p> |                                                                                 |                                                                                                                                                                                                            |                                            |

Consult LTC Marketing for parts specified with wider operating temperature ranges.

**ELECTRICAL CHARACTERISTICS**

The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are  $T_A = 25^{\circ}C$ .

$V_{IN} = 12V$ ,  $V_{RUN} = 1.5V$ ,  $V_{SYNC} = 0V$ ,  $V_{FBP} = V_{REF}$ ,  $R_T = 20k$ , unless otherwise specified.

| SYMBOL                                | PARAMETER                           | CONDITIONS                             | MIN   | TYP   | MAX   | UNITS   |
|---------------------------------------|-------------------------------------|----------------------------------------|-------|-------|-------|---------|
| <b>Main Control Loop/Whole System</b> |                                     |                                        |       |       |       |         |
| $V_{IN}$                              | Input Voltage Range                 |                                        | 3     |       | 36    | V       |
| $I_Q$                                 | Input Voltage Supply Current        | (Note 4)                               |       |       |       |         |
|                                       | Continuous Mode                     | $V_{OV/FB} = 1.5V$ , $V_{ITH} = 0.75V$ |       | 1.5   |       | mA      |
|                                       | Shutdown Mode                       | $V_{RUN} = 0V$                         |       | 20    |       | $\mu A$ |
| $V_{RUN}^{+}$                         | Rising RUN Input Threshold Voltage  |                                        |       | 1.348 |       | V       |
| $V_{RUN}^{-}$                         | Falling RUN Input Threshold Voltage |                                        | 1.223 | 1.248 | 1.273 | V       |
| $V_{RUN(HYST)}$                       | RUN Pin Input Threshold Hysteresis  |                                        |       | 100   |       | mV      |

## ELECTRICAL CHARACTERISTICS

The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are  $T_A = 25^\circ\text{C}$ .  
 $V_{IN} = 12\text{V}$ ,  $V_{RUN} = 1.5\text{V}$ ,  $V_{SYNC} = 0\text{V}$ ,  $V_{FBP} = V_{REF}$ ,  $R_T = 20\text{k}\Omega$ , unless otherwise specified.

| SYMBOL           | PARAMETER                       | CONDITIONS               | MIN | TYP | MAX | UNITS         |
|------------------|---------------------------------|--------------------------|-----|-----|-----|---------------|
| $I_{RUN}$        | RUN Pin Input Current           |                          |     | 5   |     | nA            |
| $V_{SENSE(MAX)}$ | Maximum Current Sense Threshold |                          | 125 | 150 | 180 | mV            |
| $I_{SENSE(ON)}$  | SENSE Pin Current (GATE High)   | $V_{SENSE} = 0\text{V}$  |     | 70  |     | $\mu\text{A}$ |
| $I_{SENSE(OFF)}$ | SENSE Pin Current (GATE Low)    | $V_{SENSE} = 36\text{V}$ |     | 0.2 |     | $\mu\text{A}$ |
| $I_{SS}$         | Soft-Start Pin Output Current   | $V_{SS} = 0\text{V}$     |     | -50 |     | $\mu\text{A}$ |

### Voltage/Temperature Reference

|                                 |                                     |                                             |                |       |                |                  |
|---------------------------------|-------------------------------------|---------------------------------------------|----------------|-------|----------------|------------------|
| $V_{REF}$                       | Reference Voltage                   | ●                                           | 1.218<br>1.212 | 1.230 | 1.242<br>1.248 | V<br>V           |
| $I_{REF}$                       | Max Reference Pin Output Current    |                                             | 0.5            |       |                | mA               |
| $\Delta V_{REF}/\Delta V_{IN}$  | Reference Voltage Line Regulation   | $3\text{V} \leq V_{IN} \leq 36\text{V}$     |                | 0.002 | 0.02           | %/V              |
| $\Delta V_{REF}/\Delta I_{REF}$ | Reference Voltage Load Regulation   | $0\text{mA} \leq I_{REF} \leq 0.5\text{mA}$ |                | 0.2   | 1.0            | %/mA             |
| $T_{MAX}$                       | Overtemperature SD Threshold Rising |                                             |                | 165   |                | $^\circ\text{C}$ |
| $T_{HYST}$                      | Overtemperature Hysteresis          |                                             |                | 25    |                | $^\circ\text{C}$ |

### Error Amplifier

|                        |                                         |                                                                                                                                                                                     |       |            |       |                                |
|------------------------|-----------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|------------|-------|--------------------------------|
| $I_{OV/FB}$            | OV/FB Pin Input Current                 |                                                                                                                                                                                     |       | 18         | 60    | nA                             |
| $\Delta V_{OV/FB(OV)}$ | OV/FB Overvoltage Lockout Threshold     | $V_{OV/FB(OV)} - V_{OV/FB(NOM)}$ in %, $V_{FBP} \leq V_{REF}$                                                                                                                       |       | 7          |       | %                              |
| $V_{OV/FB(FB)}$        | OV/FB Pin Regulation Voltage            | $2.5\text{V} < V_{FBP} < 36\text{V}$                                                                                                                                                | 1.212 | 1.230      | 1.248 | V                              |
| $I_{FBP}, I_{FBN}$     | Error Amplifier Input Current           | $0\text{V} \leq V_{FBP} \leq V_{REF}$<br>$2.5\text{V} < V_{FBP} < 36\text{V}$                                                                                                       |       | -0.4<br>50 |       | $\mu\text{A}$<br>$\mu\text{A}$ |
| $V_{FBP} - V_{FBN}$    | Error Amplifier Offset Voltage (Note 5) | $0\text{V} \leq V_{FBP} \leq V_{REF}$<br>$2.5\text{V} < V_{FBP} \leq 36\text{V}$ ( $V_{ILIM} = V_{REF}$ )<br>$2.5\text{V} < V_{FBP} \leq 36\text{V}$ ( $V_{ILIM} = 0.123\text{V}$ ) | -3    | 100<br>10  | 3     | mV<br>mV<br>mV                 |
| $g_m$                  | Error Amplifier Transconductance        | $V_{FBP} \leq V_{REF}$<br>$2.5\text{V} < V_{FBP} < 36\text{V}$                                                                                                                      |       | 1.7<br>14  |       | mmho<br>mmho                   |
| $A_{VOL}$              | Error Amplifier Open-Loop Gain          |                                                                                                                                                                                     | 500   |            |       | V/V                            |

### Oscillator

|                    |                                 |                                                            |     |               |      |                  |
|--------------------|---------------------------------|------------------------------------------------------------|-----|---------------|------|------------------|
| $f_{OSC}$          | Oscillator Frequency            | $R_{FREQ} = 20\text{k}\Omega$                              | 250 | 300           | 350  | kHz              |
|                    | Oscillator Frequency Range      |                                                            | 20  |               | 1000 | kHz              |
| $D_{MAX}$          | Maximum Duty Cycle              |                                                            | 85  | 90            | 97   | %                |
| $f_{SYNC}/f_{OSC}$ | Recommended Max SYNC Freq Ratio | $f_{OSC} = 300\text{kHz}$ (Note 6)                         |     | 1.25          | 1.3  |                  |
| $t_{SYNC(MIN)}$    | SYNC Minimum Input Pulse Width  | $V_{SYNC} = 0\text{V}$ to $5\text{V}$                      |     | 25            |      | ns               |
| $t_{SYNC(MAX)}$    | SYNC Maximum Input Pulse Width  | $V_{SYNC} = 0\text{V}$ to $5\text{V}$                      |     | $0.8/f_{OSC}$ |      | ns               |
| $V_{IH(SYNC)}$     | SYNC Input Voltage High Level   |                                                            | 1.2 |               |      | V                |
| $V_{HYST(SYNC)}$   | SYNC Input Voltage Hysteresis   |                                                            |     | 0.5           |      | V                |
| $R_{SYNC}$         | SYNC Input Pull-Down Resistance |                                                            |     | 100           |      | $\text{k}\Omega$ |
| $t_{ON(MIN)}$      | Minimum On-time                 | With Sense Resistor, 10mV Overdrive<br>No $R_{SENSE}$ Mode |     | 170<br>300    |      | ns<br>ns         |

## ELECTRICAL CHARACTERISTICS

The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are  $T_J = 25^\circ\text{C}$ .  
 $V_{IN} = 12\text{V}$ ,  $V_{RUN} = 1.5\text{V}$ ,  $V_{SYNC} = 0\text{V}$ ,  $V_{FBP} = V_{REF}$ ,  $R_T = 20\text{k}$ , unless otherwise specified.

| SYMBOL                                    | PARAMETER                                                    | CONDITIONS                                                            | MIN   | TYP               | MAX | UNITS                          |
|-------------------------------------------|--------------------------------------------------------------|-----------------------------------------------------------------------|-------|-------------------|-----|--------------------------------|
| <b>Low Dropout Regulator</b>              |                                                              |                                                                       |       |                   |     |                                |
| $V_{INTVCC}$                              | INTV <sub>CC</sub> Regulator Output Voltage                  | $V_{OV/FB} = 1.5\text{V}$                                             | ● 6.5 | 7                 | 7.5 | V                              |
| UVLO                                      | INTV <sub>CC</sub> Undervoltage Lockout Thresholds           | Rising INTV <sub>CC</sub><br>Falling INTV <sub>CC</sub><br>Hysteresis | 1.8   | 2.3<br>2.1<br>0.2 | 2.5 | V<br>V<br>V                    |
| $\frac{\Delta V_{INTVCC}}{\Delta V_{IN}}$ | INTV <sub>CC</sub> Line Regulation                           | $12\text{V} \leq V_{IN} \leq 36\text{V}$                              |       | 2                 | 6   | mV/V                           |
| $\Delta V_{LDO(LOAD)}$                    | INTV <sub>CC</sub> Load Regulation                           | $0 \leq I_{INTVCC} \leq 10\text{mA}$                                  | -1    | -0.1              |     | %                              |
| $V_{DROPOUT}$                             | INTV <sub>CC</sub> Dropout Voltage                           | $V_{IN} = 7\text{V}$ , $I_{INTVCC} = 10\text{mA}$                     |       | 300               | 500 | mV                             |
| $I_{INTVCC(SD)}$                          | Bootstrap Mode INTV <sub>CC</sub> Supply Current in Shutdown | $V_{SENSE} = 0\text{V}$<br>$V_{SENSE} = 7\text{V}$                    |       | 25<br>15          |     | $\mu\text{A}$<br>$\mu\text{A}$ |
| <b>GATE/PWMOUT Drivers</b>                |                                                              |                                                                       |       |                   |     |                                |
| $t_r(\text{GATE})$                        | GATE Driver Output Rise Time                                 | $C_L = 3300\text{pF}$ (Note 7)                                        |       | 15                |     | ns                             |
| $t_f(\text{GATE})$                        | GATE Driver Output Fall Time                                 | $C_L = 3300\text{pF}$ (Note 7)                                        |       | 8                 |     | ns                             |
| $I_{PK(\text{GATE,RISE})}$                | GATE Driver Peak Current Sourcing                            | $V_{GATE} = 0\text{V}$                                                |       | 0.5               |     | A                              |
| $I_{PK(\text{GATE,FALL})}$                | GATE Driver Peak Current Sinking                             | $V_{GATE} = 7\text{V}$                                                |       | 1                 |     | A                              |
| $V_{PWMIN}$                               | PWMIN Pin Input Threshold Voltages                           | Rising PWMIN<br>Falling PWMIN<br>Hysteresis                           |       | 1.6<br>0.8<br>0.8 |     | V<br>V<br>V                    |
| $R_{PWMIN}$                               | PWMIN Input Pull-Up Resistance                               |                                                                       |       | 100               |     | k $\Omega$                     |
| $t_r(\text{PWMOUT})$                      | PWMOUT Driver Output Rise Time                               | $C_L = 3300\text{pF}$ (Note 7)                                        |       | 30                |     | ns                             |
| $t_f(\text{PWMOUT})$                      | PWMOUT Driver Output Fall Time                               | $C_L = 3300\text{pF}$ (Note 7)                                        |       | 16                |     | ns                             |
| $I_{PK(\text{PWMOUT,RISE})}$              | PWMOUT Driver Peak Current Sourcing                          | $V_{PWMOUT} = 0\text{V}$                                              |       | 0.25              |     | A                              |
| $I_{PK(\text{PWMOUT,FALL})}$              | PWMOUT Driver Peak Current Sinking                           | $V_{PWMOUT} = 7\text{V}$                                              |       | 0.50              |     | A                              |

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of the device may be impaired.

**Note 2:** The LTC3783E is guaranteed to meet performance specifications from  $0^\circ\text{C}$  to  $85^\circ\text{C}$  junction temperature. Specifications over the  $-40^\circ\text{C}$  to  $85^\circ\text{C}$  operating temperature range are assured by design, characterization and correlation with statistical process controls.

**Note 3:**  $T_J$  is calculated from the ambient temperature  $T_A$  and power dissipation  $P_D$  according to the following formula:

$$T_J = T_A + (P_D \cdot 43^\circ\text{C/W}) \text{ for the DFN}$$

$$T_J = T_A + (P_D \cdot 38^\circ\text{C/W}) \text{ for the TSSOP}$$

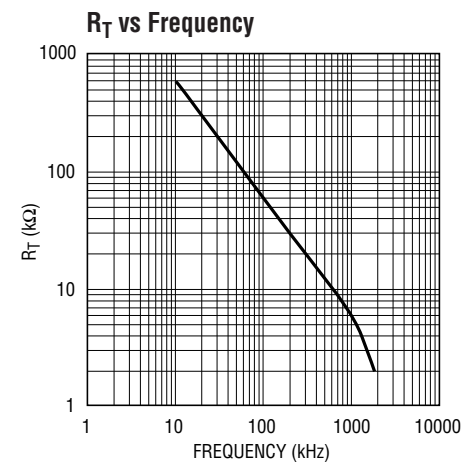
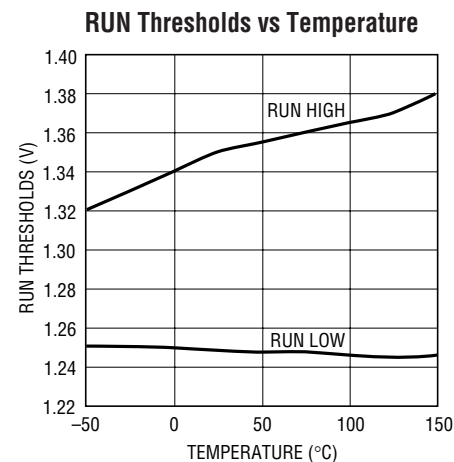
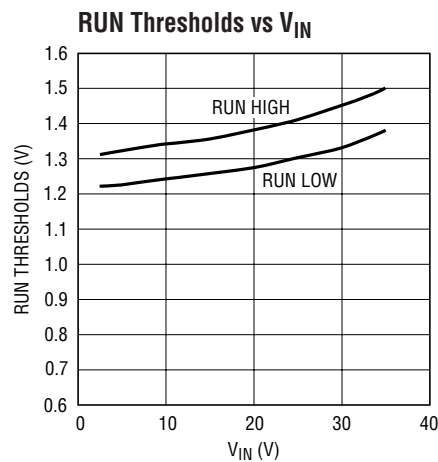
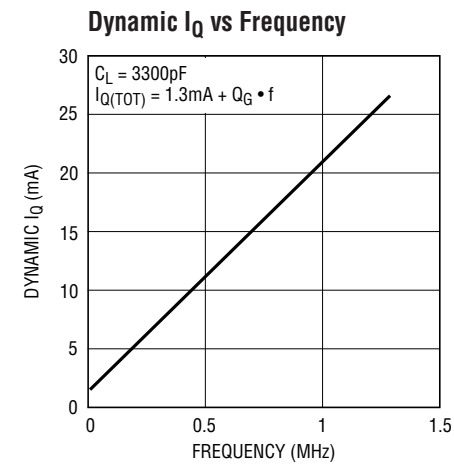
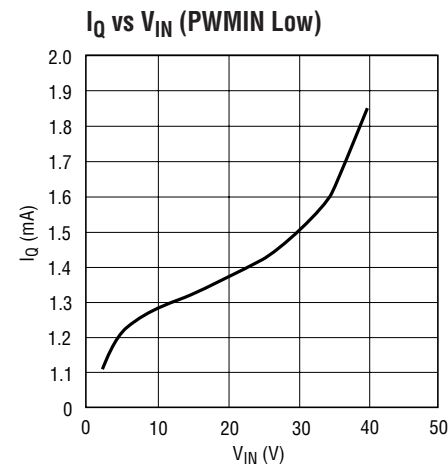
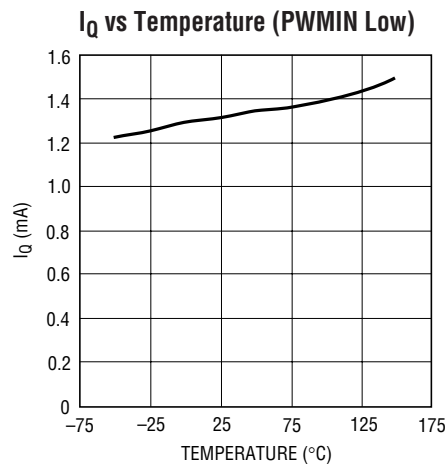
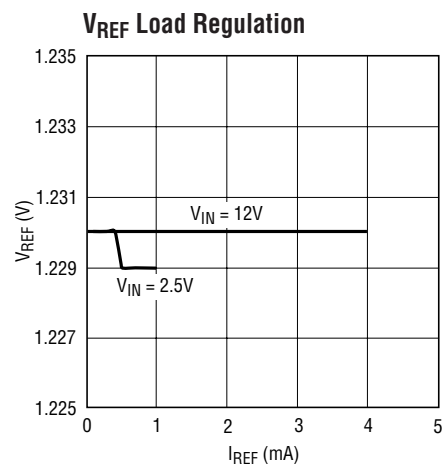
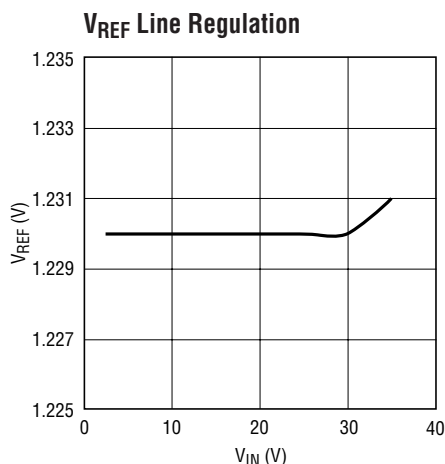
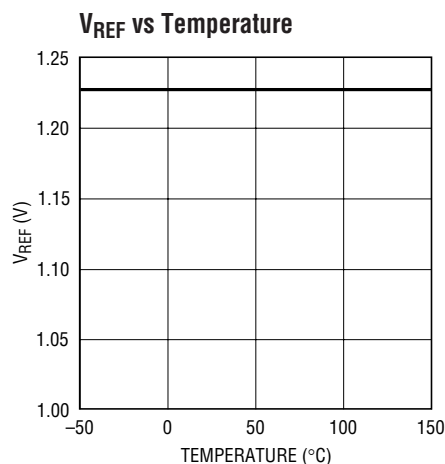
**Note 4:** The dynamic input supply current is higher due to power MOSFET gate charging ( $Q_G \cdot f_{OSC}$ ). See Operation section.

**Note 5:** The LTC3783 is tested in a feedback loop which serves  $V_{FBN}$  to  $V_{FBP} = V_{VREF}$  with the  $I_{TH}$  pin forced to the midpoint of its voltage range ( $0.3\text{V} \leq V_{ITH} \leq 1.2\text{V}$ ; midpoint =  $0.75\text{V}$ ).

**Note 6:** In a synchronized application, the internal slope compensation is increased by 25%. Synchronizing to a significantly higher ratio will reduce the effective amount of slope compensation, which could result in sub-harmonic oscillation for duty cycles greater than 50%.

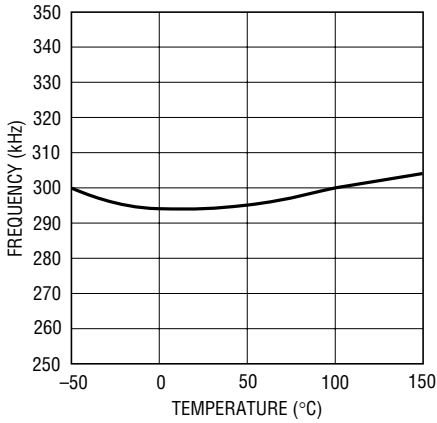
**Note 7:** Rise and fall times are measured at 10% and 90% levels.

# TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^\circ\text{C}$ unless otherwise specified



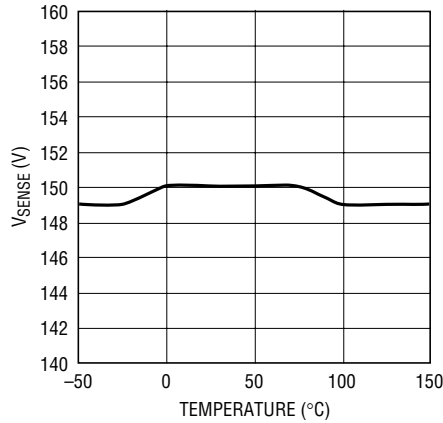
# TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^\circ\text{C}$ unless otherwise specified

Frequency vs Temperature



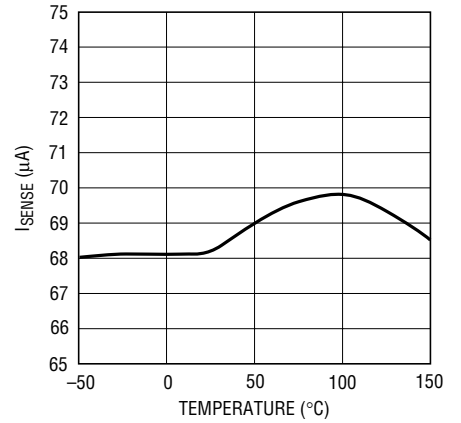
3783 G10

Maximum  $V_{\text{SENSE}}$  vs Temperature



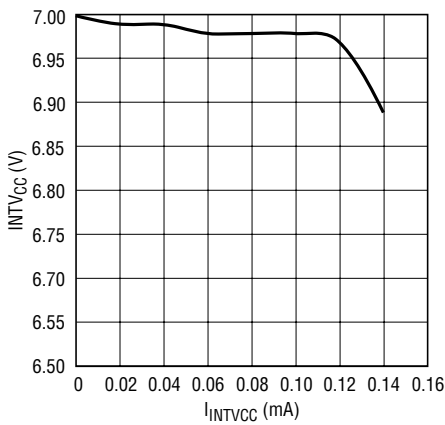
3783 G11

$I_{\text{SENSE}}$  vs Temperature



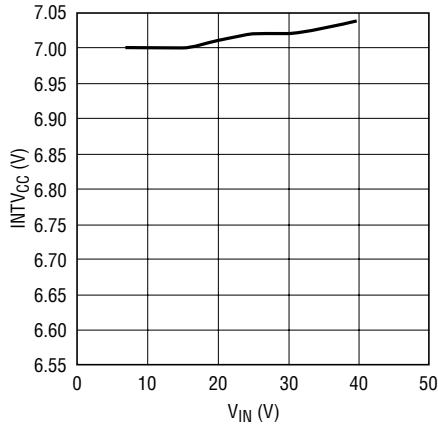
3783 G12

INTV<sub>CC</sub> Load Regulation



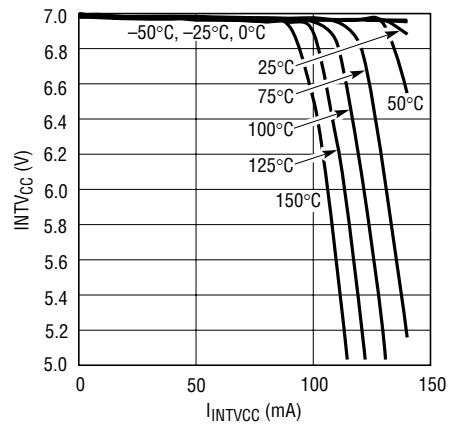
3783 G13

INTV<sub>CC</sub> Line Regulation



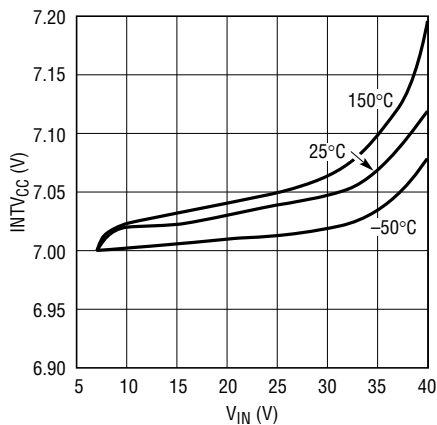
3783 G14

INTV<sub>CC</sub> Load Regulation Over Temperature



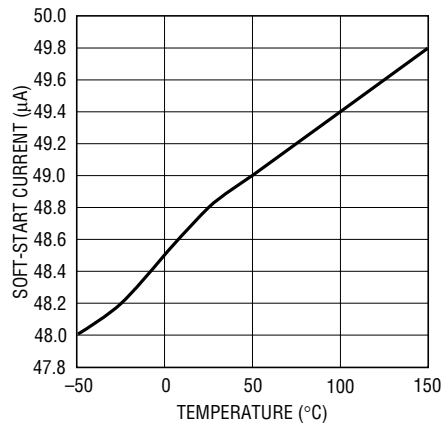
3783 G15

INTV<sub>CC</sub> Line Regulation vs Temperature



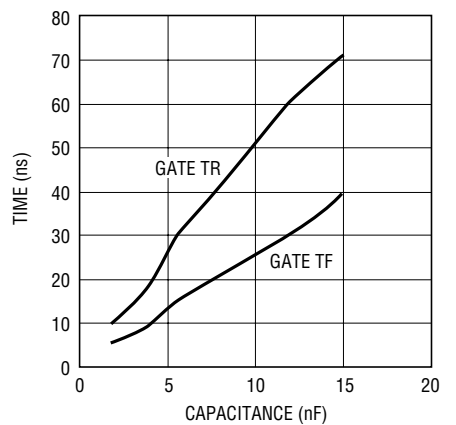
3783 G16

$I_{\text{SS}}$  Soft-Start Current vs Temperature



3783 G17

Gate Rise/Fall Time vs Capacitance



3783 G18

## PIN FUNCTIONS

**FBN (Pin 1):** Error Amplifier Inverting Input/Negative Current Sense Pin. In voltage mode ( $V_{FBP} \leq V_{VREF}$ ), this pin senses feedback voltage from either the external resistor divider across  $V_{OUT}$  for output voltage regulation, or the grounded sense resistor under the load for output current regulation. In constant current/constant voltage mode ( $V_{FBP} > 2.5V$ ), connect this pin to the negative side of the current-regulating resistor. Nominal voltage for this pin in regulation is either  $V_{FBP}$  or ( $V_{FBP} - 100mV$ ) for  $V_{ILIM} = 1.23V$ , depending on operational mode (voltage or constant current/constant voltage) set by the voltage at  $V_{FBP}$ .

**FBP (Pin 2):** Error Amplifier Noninverting Input/Positive Current Sense Pin. This pin voltage determines the control loop's feedback mode (voltage or constant current/constant voltage), the threshold of which is approximately 2V. In voltage mode ( $V_{FBP} \leq V_{REF}$ ), this pin represents the desired voltage which the regulated loop will cause FBN to follow. In constant current/constant voltage mode ( $V_{FBP} > 2.5V$ ), connect this pin to the positive side of the load current-sensing resistor. The acceptable input ranges for this pin are 0V to 1.23V (voltage mode) and 2.5V to 36V (constant current/constant voltage mode).

**$I_{LIM}$  (Pin 3):** Current Limit Pin. Sets current sense resistor offset voltage ( $V_{FBP} - V_{FBN}$ ) in constant current mode regulation (i.e., when  $V_{FBP} > 2.5V$ ). Offset voltage is 100mV when  $V_{ILIM} = 1.23V$  and decreases proportionally with  $V_{ILIM}$ . Nominal voltage range for this pin is 0.1V to 1.23V.

**$V_{REF}$  (Pin 4):** Reference Voltage Pin. Provides a buffered version of the internal bandgap voltage, which can be connected to FBP either directly or with attenuation. Nominal voltage for this pin is 1.23V. This pin should never be bypassed by a capacitor to GND. Instead, a 10k resistor to GND should be used to lower pin impedance in noisy systems.

**FREQ (Pin 5):** A resistor from the FREQ pin to ground programs the operating frequency of the chip. The nominal voltage at the FREQ pin is 0.615V.

**SYNC (Pin 6):** This input allows for synchronizing the operating frequency to an external clock and has an internal 100k pull-down resistor.

**PWMIN (Pin 7):** PWM Gate Driver Input. Internal 100k pull-up resistor. While PWMIN is low, PWMOUT is low, GATE stops switching and the external  $I_{TH}$  network is disconnected, saving the  $I_{TH}$  state.

**PWMOUT (Pin 8):** PWM Gate Driver Output. Used for constant current dimming (LED load) or for output disconnect (step-up power supply).

**GATE (Pin 9):** Main Gate Driver Output for the Boost Converter.

**INTV<sub>CC</sub> (Pin 10):** Internal 7V Regulator Output. The main and PWM gate drivers and control circuits are powered from this voltage. Decouple this pin locally to the IC ground with a minimum of 4.7 $\mu$ F low ESR ceramic capacitor.

**$V_{IN}$  (Pin 11):** Main Supply Pin. Must be closely decoupled to ground.

**SENSE (Pin 12):** Current Sense Input for the Control Loop. Connect this pin to the drain of the main power MOSFET for  $V_{DS}$  sensing and highest efficiency for  $V_{SENSE} \leq 36V$ . Alternatively, the SENSE pin may be connected to a resistor in the source of the main power MOSFET. Internal leading-edge blanking is provided for both sensing methods.

**SS (Pin 13):** Soft-Start Pin. Provides a 50 $\mu$ A pull-up current, enabled and reset by RUN, which charges an optional external capacitor. This voltage ramp translates into a corresponding current limit ramp through the main MOSFET.

**OV/FB (Pin 14):** Overvoltage Pin/Voltage Feedback Pin. In voltage mode ( $V_{FBP} \leq V_{REF}$ ), this input, connected to  $V_{OUT}$  through a resistor network, sets the output voltage at which GATE switching is disabled in order to prevent an overvoltage situation. Nominal threshold voltage for the OV pin is 1.32V ( $V_{REF} + 7\%$ ) with 20mV hysteresis. In current/voltage mode ( $V_{FBP} > 2.5V$ ), this pin senses  $V_{OUT}$  through a resistor divider and brings the loop into voltage regulation such that pin voltage approaches  $V_{REF} = 1.23V$ , provided the loop is not regulating the load current (e.g.,  $[V_{FBP} - V_{FBN}] < 100mV$  for  $I_{LIM} = 1.23V$ ).



## PIN FUNCTIONS

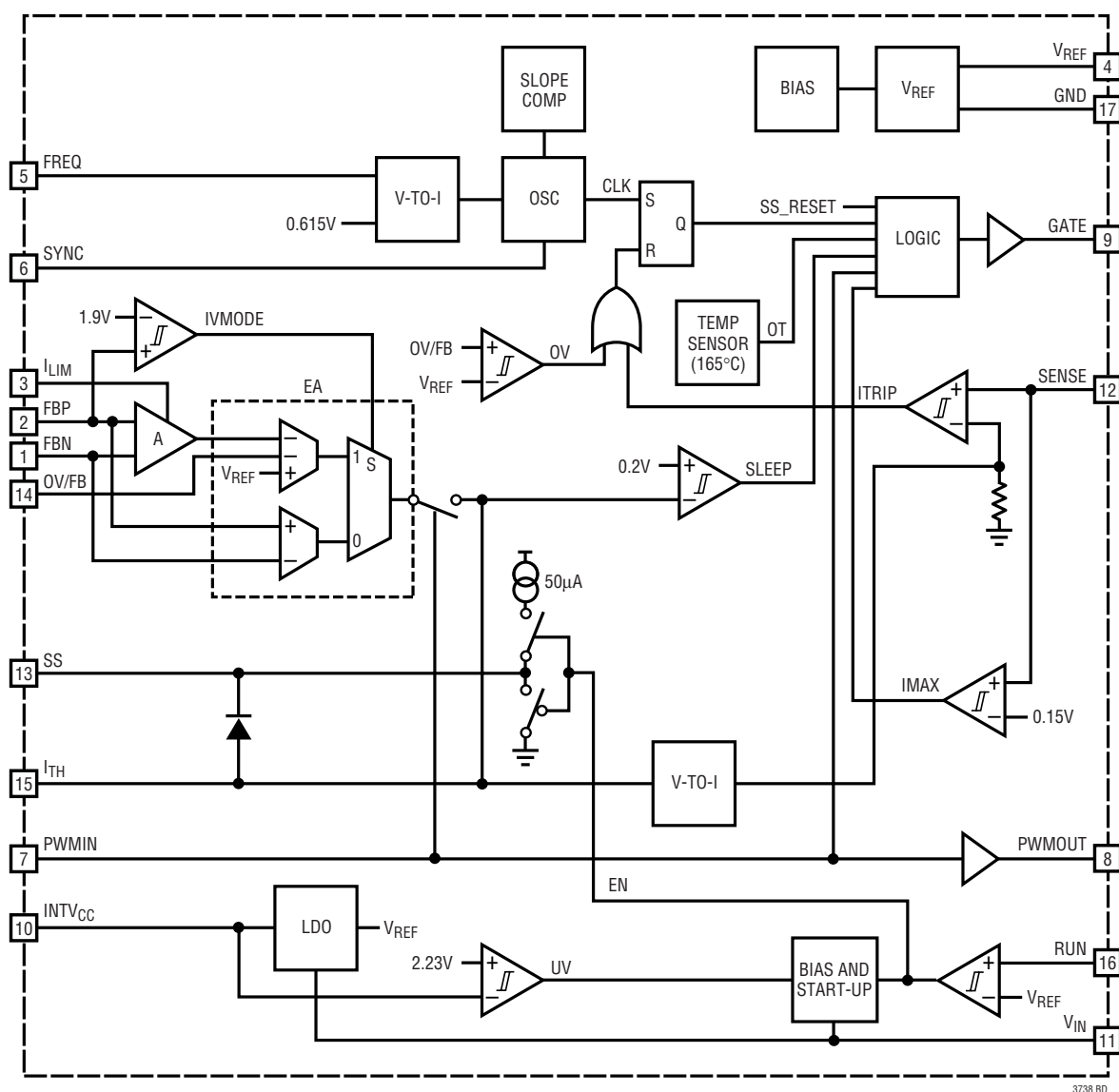
**I<sub>TH</sub> (Pin 15):** Error Amplifier Output/Compensation Pin. The current comparator input threshold increases with this control voltage, which is the output of the  $g_m$  type error amplifier. Nominal voltage range for this pin is 0V to 1.40V.

**RUN (Pin 16):** The RUN pin provides the user with an accurate means for sensing the input voltage and programming the start-up threshold for the converter. The

falling RUN pin threshold is nominally 1.248V and the comparator has 100mV hysteresis for noise immunity. When the RUN pin is grounded, the IC is shut down and the  $V_{IN}$  supply current is kept to a low value (20 $\mu$ A typ).

**Exposed Pad (Pin 17):** Ground Pin. Solder to PCB ground for electrical contact and rated thermal performance.

## BLOCK DIAGRAM





## OPERATION

### Main Control Loop

The LTC3783 is a constant frequency, current mode controller for PWM LED as well as DC/DC boost, SEPIC and flyback converter applications. In constant current LED applications, the LTC3783 provides an especially wide PWM dimming range due to its unique switching scheme, which allows PWM pulse widths as short as several converter switching periods.

For voltage feedback circuit operation (defined by  $V_{FBP} \leq 1.23V$ ), please refer to the Block Diagram of the IC and the Typical Application on the first page of this data sheet. In normal operation with PWMIN high, the power MOSFET is turned on (GATE goes high) when the oscillator sets the PWM latch, and is turned off when the ITRIP current comparator resets the latch. Based on the error voltage represented by  $(V_{FBP} - V_{FBN})$ , the error amplifier output signal at the  $I_{TH}$  pin sets the ITRIP current comparator input threshold. When the load current increases, a fall in the FBN voltage relative to the reference voltage at FBP causes the  $I_{TH}$  pin to rise, causing the ITRIP current comparator to trip at a higher peak inductor current value. The average inductor current will therefore rise until it equals the load current, thereby maintaining output regulation.

When PWMIN goes low, PWMOUT goes low, the  $I_{TH}$  switch opens and GATE switching is disabled. Lowering PWMOUT and disabling GATE causes the output capacitor  $C_{OUT}$  to hold the output voltage constant in the absence of load current. Opening the  $I_{TH}$  switch stores the correct load current value on the  $I_{TH}$  capacitor  $C_{ITH}$ . As a result, when PWMIN goes high again, both  $I_{TH}$  and  $V_{OUT}$  are instantly at the appropriate levels.

In voltage feedback operation, an overvoltage comparator, OV, senses when the OV/FB pin exceeds the reference voltage by 7% and provides a reset pulse to the main RS latch. Because this RS latch is reset-dominant, the power MOSFET is actively held off for the duration of an output overvoltage condition.

For constant current/constant voltage regulation operation (defined by  $V_{FBP} > 2.5V$ ), please refer to the Block Diagram of the IC and Figure 11. Loop operation is similar to the voltage feedback, except FBP and FBN now sense the voltage across sense resistor  $R_L$  in series with the load. The  $I_{TH}$  pin now represents the error from the desired differential set voltage, from 10mV to 100mV, for  $I_{LIM}$  values of 0.123V to 1.23V. That is, with  $V_{ILIM} = 1.23V$ , the loop will regulate such that  $V_{FBP} - V_{FBN} = 100mV$ ; lower values of  $I_{LIM}$  attenuate the difference proportionally. PWMIN is still functional as above, but will only work properly if load current can be disconnected by the PWMOUT signal.

In constant current/constant voltage operation, the OV/FB pin becomes a voltage feedback pin, which causes the loop to regulate such that  $V_{OV/FB} = 1.23V$ , provided the above current-sense voltage is not reached. In this way, the loop regulates either voltage or current, whichever parameter hits its preset limit first.

The nominal operating frequency of the LTC3783 is programmed using a resistor from the FREQ pin to ground and can be controlled over a 20kHz to 1MHz range. In addition, the internal oscillator can be synchronized to an external clock applied to the SYNC pin and can be locked to a frequency between 100% and 130% of its nominal value. When the SYNC pin is left open, it is pulled low by an internal 100k resistor. With no load, or an extremely light one, the controller will skip pulses in order to maintain regulation and prevent excessive output ripple.

The RUN pin controls whether the IC is enabled or is in a low current shutdown state. A micropower 1.248V reference and RUN comparator allow the user to program the supply voltage at which the IC turns on and off (the RUN comparator has 100mV of hysteresis for noise immunity). With the RUN pin below 1.248V, the chip is off and the input supply current is typically only 20 $\mu$ A.

## OPERATION

The SS pin provides a soft-start current to charge an external capacitor. Enabled by RUN, the soft-start current is  $50\mu\text{A}$ , which creates a positive voltage ramp on  $V_{\text{SS}}$  to which the internal  $I_{\text{TH}}$  is limited, avoiding high peak currents on start-up. Once  $V_{\text{SS}}$  reaches  $1.23\text{V}$ , the full  $I_{\text{TH}}$  range is established.

The LTC3783 can be used either by sensing the voltage drop across the power MOSFET or by connecting the SENSE pin to a conventional shunt resistor in the source of the power MOSFET, as shown in the Typical Application on the first page of this data sheet. Sensing the voltage across the power MOSFET maximizes converter efficiency and minimizes the component count, but limits the output voltage to the maximum rating for this pin ( $36\text{V}$ ). By connecting the SENSE pin to a resistor in the source of the power MOSFET, the user is able to program output voltages significantly greater than  $36\text{V}$ , limited only by other components' breakdown voltages.

### Externally Synchronized Operation

When an external clock signal drives the SYNC pin at a rate faster than the chip's internal oscillator, the oscillator will synchronize to it. When the oscillator's internal logic circuitry detects a synchronizing signal on the SYNC pin, the internal oscillator ramp is terminated early and the slope compensation is increased by approximately 25%. As a result, in applications requiring synchronization, it is recommended that the nominal operating frequency of the IC be programmed to be about 80% of the external clock frequency. Attempting to synchronize to too high an external frequency (above  $1.3f_{\text{OSC}}$ ) can result in inadequate slope compensation and possible subharmonic oscillation (or jitter).

The external clock signal must exceed  $2\text{V}$  for at least  $25\text{ns}$ , and should have a maximum duty cycle of 80%, as shown in Figure 1. The MOSFET turn-on will synchronize to the rising edge of the external clock signal.

### Programming the Operating Frequency

The choice of operating frequency and inductor value is a tradeoff between efficiency and component size. Low frequency operation improves efficiency by reducing

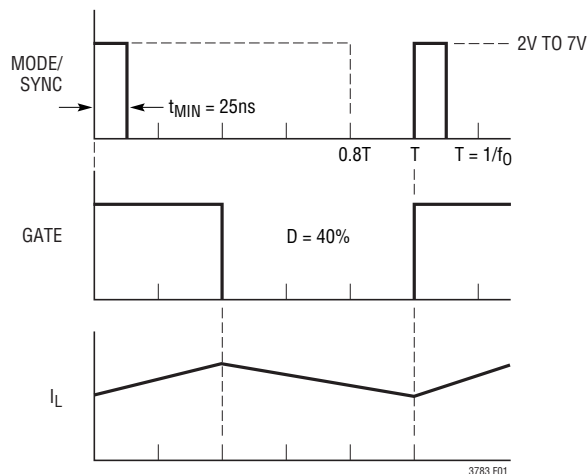


Figure 1. MODE/SYNC Clock Input and Switching Waveforms for Synchronized Operation

MOSFET and diode switching losses. However, lower frequency operation requires more inductance for a given amount of load current.

The LTC3783 uses a constant frequency architecture that can be programmed over a  $20\text{kHz}$  to  $1\text{MHz}$  range with a single external resistor from the FREQ pin to ground, as shown in the application on the first page of this data sheet. The nominal voltage on the FREQ pin is  $0.615\text{V}$ , and the current that flows out of the FREQ pin is used to charge and discharge an internal oscillator capacitor. The oscillator frequency is trimmed to  $300\text{kHz}$  with  $R_T = 20\text{k}$ . A graph for selecting the value of  $R_T$  for a given operating frequency is shown in Figure 2.

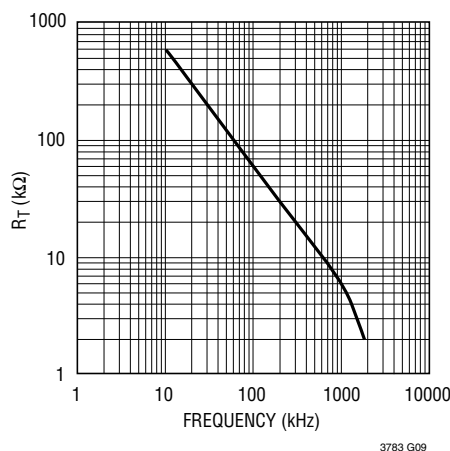


Figure 2. Timing Resistor ( $R_T$ ) Value



## OPERATION

maximum total gate charge of 35nC (the temperature coefficient of the gate charge is low).

$$I_{Q(TOT)} = 1.2\text{mA} + 35\text{nC} \cdot 300\text{kHz} = 12\text{mA}$$

$$P_{IC} = 12\text{V} \cdot 12\text{mA} = 144\text{mW}$$

$$T_J = 70^\circ\text{C} + 110^\circ\text{C/W} \cdot 144\text{mW} = 86^\circ\text{C}$$

This demonstrates how significant the gate charge current can be when compared to the static quiescent current in the IC.

To prevent the maximum junction temperature from being exceeded, the input supply current must be checked when operating in a continuous mode at high  $V_{IN}$ . A tradeoff between the operating frequency and the size of the power MOSFET may need to be made in order to maintain a reliable IC junction temperature. Prior to lowering the operating frequency, however, be sure to check with the power MOSFET manufacturers for the latest low  $Q_G$ , low  $R_{DS(ON)}$  devices. Power MOSFET manufacturing technologies are continually improving, with newer and better-performing devices being introduced almost monthly.

### Output Voltage Programming

In constant voltage mode, in order to regulate the output voltage, the output voltage is set by a resistor divider according to the following formula:

$$V_{OUT} = V_{FBP} \cdot \left(1 + \frac{R2}{R1}\right)$$

where  $0 \leq V_{FBP} \leq 1.23\text{V}$ . The external resistor divider is connected to the output as shown in Figure 4, allowing remote voltage sensing. The resistors R1 and R2 are typically chosen so that the error caused by the 500nA input bias current flowing out of the FBN pin during normal operation is less than 1%, which translates to a maximum R1 value of about 25k at  $V_{FBP} = 1.23\text{V}$ . For lower FBP voltages, R1 must be reduced accordingly to maintain accuracy, e.g.,  $R1 < 2\text{k}$  for 1% accuracy when  $V_{FBP} = 100\text{mV}$ . More accuracy can be achieved with lower resistances, at the expense of increased dissipation and decreased light load efficiency.

A similar analysis applies to the  $V_{FBP}$  resistive divider, if one is used:

$$V_{FBP} = V_{REF} \cdot \frac{R3}{R3 + R4}$$

where R3 is subject to a similar 500nA bias current.

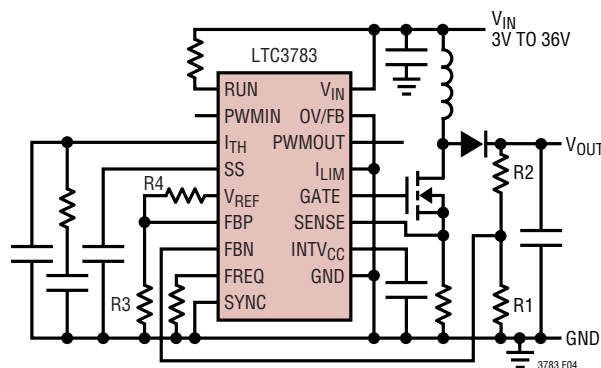


Figure 4. LTC3783 Boost Application

### Programming Turn-On and Turn-Off Thresholds with the RUN Pin

The LTC3783 contains an independent, micropower voltage reference and comparator detection circuit that remains active even when the device is shut down, as shown in Figure 5. This allows users to accurately program an input voltage at which the converter will turn on and off. The falling threshold on the RUN pin is equal to the internal reference voltage of 1.248V. The comparator has 100mV of hysteresis to increase noise immunity.

The turn-on and turn-off input voltage thresholds are programmed using a resistor divider according to the following formulas:

$$V_{IN(OFF)} = 1.248\text{V} \cdot \left(1 + \frac{R2}{R1}\right)$$

$$V_{IN(ON)} = 1.348\text{V} \cdot \left(1 + \frac{R2}{R1}\right)$$

The resistor R1 is typically chosen to be less than 1M.

## OPERATION

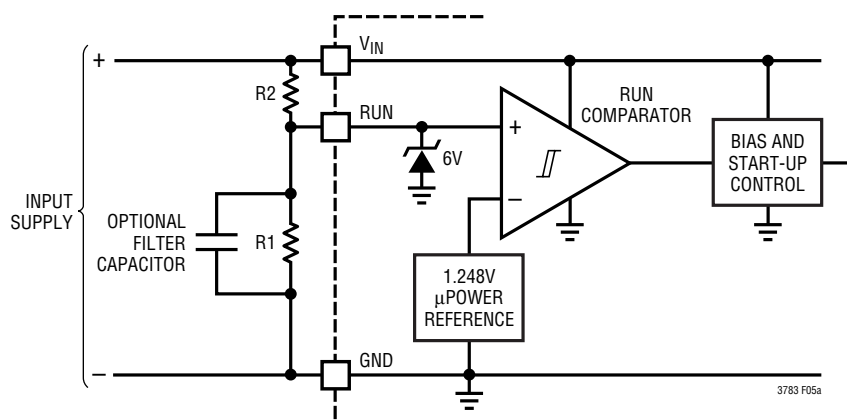


Figure 5a. Programming the Turn-On and Turn-Off Thresholds Using the RUN Pin

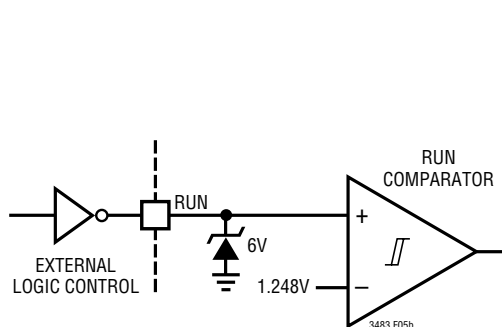


Figure 5b. On/Off Control Using External Logic

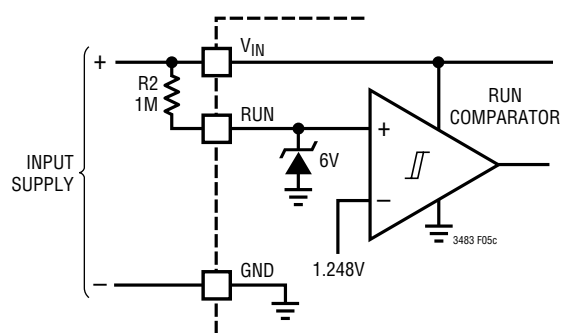


Figure 5c. External Pull-Up Resistor on RUN Pin for "Always On" Operation

For applications where the RUN pin is only to be used as a logic input, the user should be aware of the 7V Absolute Maximum Rating for this pin! The RUN pin can be connected to the input voltage through an external 1M resistor, as shown in Figure 5c, for "always on" operation.

### Soft-Start Capacitor Selection

For proper soft-start operation, the LTC3783 should have a sufficiently large soft-start capacitor,  $C_{SS}$ , attached to the SS pin. The minimum soft-start capacitor size can be estimated on the basis of output voltage, capacitor size and load current. In addition, PWM operation reduces the effective SS capacitor value by the dimming ratio.

$$C_{SS(MIN)} > \frac{2 \cdot \text{dimming ratio} \cdot 50\mu A \cdot C_{OUT} \cdot V_{OUT} \cdot R_{DS(ON)/SENSE}}{150mV \cdot 1.2V}$$

assuming 50% ripple current, where  $R_{DS(ON)/SENSE}$  represents either the  $R_{DS(ON)}$  of the switching MOSFET or  $R_{SENSE}$ , whichever is used on the SENSE pin. Dimming ratio is described by  $1/D_{PWM}$  as shown in Figure 6.

### Application Circuits

A basic LTC3783 PWM-dimming LED application is shown on the first page of this data sheet.

### Operating Frequency and PWM Dimming Ratio

The minimum operating frequency,  $f_{OSC}$ , required for proper operation of a PWM dimming application depends on the minimum PWM frequency,  $f_{PWM}$ , the dimming ratio  $1/D_{PWM}$ , and N, the number of  $f_{OSC}$  cycles per PWM cycle:

$$f_{OSC} > \frac{N \cdot f_{PWM}}{D_{PWM}}$$



## OPERATION

Figure 6 illustrates these various quantities in relation to one another.

Typically, in order to avoid visible flicker,  $f_{PWM}$  should be greater than 120Hz. Assuming inductor and capacitor sizing which is close to discontinuous operation,  $2 f_{OSC}$  cycles are sufficient for proper PWM operation. Thus, within the 1MHz rated maximum  $f_{OSC}$ , a dimming ratio of  $1/D_{PWM} = 3000$  is possible.

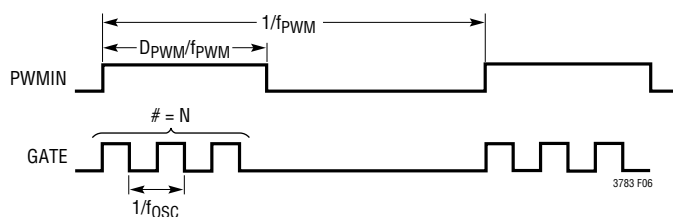


Figure 6. PWM Dimming Parameters

### Boost Converter: Duty Cycle Considerations

For a boost converter operating in a continuous conduction mode (CCM), the duty cycle of the main switch is:

$$D = \frac{V_{OUT} + V_D - V_{IN}}{V_{OUT} + V_D}$$

where  $V_D$  is the forward voltage of the boost diode. For converters where the input voltage is close to the output voltage, the duty cycle is low, and for converters that develop a high output voltage from a low input voltage, the duty cycle is high. The maximum output voltage for a boost converter operating in CCM is:

$$V_{OUT(MAX)} = \frac{V_{IN(MIN)}}{1 - D_{MAX}} - V_D$$

The maximum duty cycle capability of the LTC3783 is typically 90%. This allows the user to obtain high output voltages from low input supply voltages.

### Boost Converter: The Peak and Average Input Currents

The control circuit in the LTC3783 is measuring the input current (either by using the  $R_{DS(ON)}$  of the power MOSFET or by using a sense resistor in the MOSFET source), so the

output current needs to be reflected back to the input in order to dimension the power MOSFET properly. Based on the fact that, ideally, the output power is equal to the input power, the maximum average input current is:

$$I_{IN(MAX)} = \frac{I_{OUT(MAX)}}{1 - D_{MAX}}$$

The peak input current is:

$$I_{IN(PEAK)} = \left(1 + \frac{\chi}{2}\right) \cdot \frac{I_{OUT(MAX)}}{1 - D_{MAX}}$$

The maximum duty cycle,  $D_{MAX}$ , should be calculated at minimum  $V_{IN}$ .

### Boost Converter: Ripple Current $\Delta I_L$ and the 'χ' Factor

The constant 'χ' in the equation above represents the percentage peak-to-peak ripple current in the inductor, relative to its maximum value. For example, if 30% ripple current is chosen, then  $\chi = 0.3$ , and the peak current is 15% greater than the average.

For a current mode boost regulator operating in CCM, slope compensation must be added for duty cycles above 50% in order to avoid subharmonic oscillation. For the LTC3783, this ramp compensation is internal. Having an internally fixed ramp compensation waveform, however, does place some constraints on the value of the inductor and the operating frequency. If too large an inductor is used, the resulting current ramp ( $\Delta I_L$ ) will be small relative to the internal ramp compensation (at duty cycles above 50%), and the converter operation will approach voltage mode (ramp compensation reduces the gain of the current loop). If too small an inductor is used, but the converter is still operating in CCM (near critical conduction mode), the internal ramp compensation may be inadequate to prevent subharmonic oscillation. To ensure good current mode gain and to avoid subharmonic oscillation, it is recommended that the ripple current in the inductor fall in the range of 20% to 40% of the maximum average current. For example, if the maximum average input current is 1A, choose a  $\Delta I_L$  between 0.2A and 0.4A, and correspondingly a value 'χ' between 0.2 and 0.4.

## OPERATION

### Boost Converter: Inductor Selection

Given an operating input voltage range, and having chosen the operating frequency and ripple current in the inductor, the inductor value can be determined using the following equation:

$$L = \left( \frac{V_{IN(MIN)}}{\Delta I_L \cdot f} \right) \cdot D_{MAX}$$

where :

$$\Delta I_L = \frac{\chi \cdot I_{OUT(MAX)}}{1 - D_{MAX}}$$

Remember that most boost converters are not short-circuit protected. Under a shorted output condition, the inductor current is limited only by the input supply capability. For applications requiring a step-up converter that is short-circuit protected, please refer to the applications section covering SEPIC converters.

The minimum required saturation current of the inductor can be expressed as a function of the duty cycle and the load current, as follows:

$$I_{L(SAT)} > \left( 1 + \frac{\chi}{2} \right) \cdot \frac{I_{OUT(MAX)}}{1 - D_{MAX}}$$

The saturation current rating for the inductor should be checked at the minimum input voltage (which results in the highest inductor current) and maximum output current.

### Boost Converter: Operating in Discontinuous Mode

Discontinuous mode operation occurs when the load current is low enough to allow the inductor current to run out during the off-time of the switch, as shown in Figure 7. Once the inductor current is near zero, the switch and diode capacitances resonate with the inductance to form damped ringing at 1MHz to 10MHz. If the off-time is long enough, the drain voltage will settle to the input voltage.

Depending on the input voltage and the residual energy in the inductor, this ringing can cause the drain of the power MOSFET to go below ground where it is clamped by the body diode. This ringing is not harmful to the IC and it has

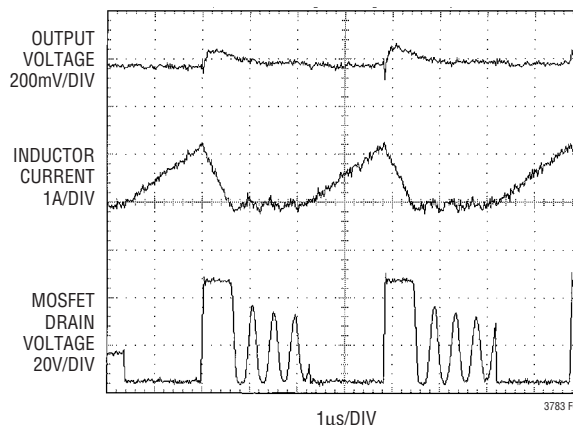


Figure 7. Discontinuous Mode Waveforms

not been shown to contribute significantly to EMI. Any attempt to damp it with a snubber will degrade the efficiency.

### Boost Converter: Power MOSFET Selection

The power MOSFET can serve two purposes in the LTC3783: it represents the main switching element in the power path, and its  $R_{DS(ON)}$  can represent the current sensing element for the control loop. Important parameters for the power MOSFET include the drain-to-source breakdown voltage  $BV_{DSS}$ , the threshold voltage  $V_{GS(TH)}$ , the on-resistance  $R_{DS(ON)}$  versus gate-to-source voltage, the gate-to-source and gate-to-drain charges  $Q_{GS}$  and  $Q_{GD}$ , respectively, the maximum drain current  $I_{D(MAX)}$  and the MOSFET's thermal resistances  $\theta_{JC}$  and  $\theta_{JA}$ .

The gate drive voltage is set by the 7V  $INTV_{CC}$  low drop regulator. Consequently, 6V rated MOSFETs are required in most high voltage LTC3783 applications. If low input voltage operation is expected (e.g., supplying power from a lithium-ion battery or a 3.3V logic supply), then sublogic-level threshold MOSFETs should be used. Pay close attention to the  $BV_{DSS}$  specifications for the MOSFETs relative to the maximum actual switch voltage in the application. Many logic-level devices are limited to 30V or less, and the switch node can ring during the turn-off of the MOSFET due to layout parasitics. Check the switching waveforms of the MOSFET directly across the drain and source terminals using the actual PC board layout for excessive ringing.



## OPERATION

During the switch on-time, the I<sub>MAX</sub> comparator limits the absolute maximum voltage drop across the power MOSFET to a nominal 150mV, regardless of duty cycle. The peak inductor current is therefore limited to 150mV/R<sub>DS(ON)</sub>. The relationship between the maximum load current, duty cycle, and the R<sub>DS(ON)</sub> of the power MOSFET is:

$$R_{DS(ON)} < 150\text{mV} \cdot \frac{1 - D_{MAX}}{\left(1 + \frac{\chi}{2}\right) \cdot I_{OUT(MAX)} \cdot \rho_T}$$

The  $\rho_T$  term accounts for the temperature coefficient of the R<sub>DS(ON)</sub> of the MOSFET, which is typically 0.4%/°C. Figure 8 illustrates the variation of normalized R<sub>DS(ON)</sub> over temperature for a typical power MOSFET.

Another method of choosing which power MOSFET to use is to check what the maximum output current is for a given R<sub>DS(ON)</sub>, since MOSFET on-resistances are available in discrete values.

$$I_{O(MAX)} = 150\text{mV} \cdot \frac{1 - D_{MAX}}{\left(1 + \frac{\chi}{2}\right) \cdot R_{DS(ON)} \cdot \rho_T}$$

It is worth noting that the 1 - D<sub>MAX</sub> relationship between I<sub>O(MAX)</sub> and R<sub>DS(ON)</sub> can cause boost converters with a wide input range to experience a dramatic range of maximum input and output currents. This should be taken into consideration in applications where it is important to limit

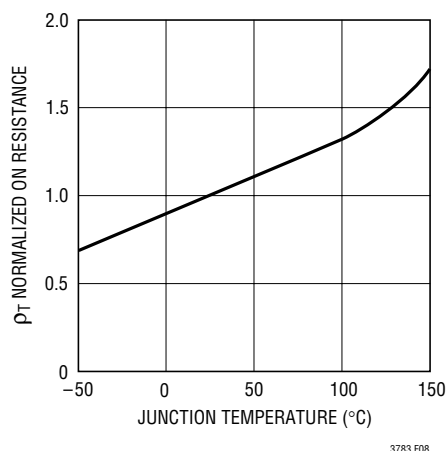


Figure 8. Normalized R<sub>DS(ON)</sub> vs Temperature

the maximum current drawn from the input supply, and also to avoid triggering the 150mV I<sub>MAX</sub> comparator, as this condition can result in excessive noise.

### Calculating Power MOSFET Switching and Conduction Losses and Junction Temperatures

In order to calculate the junction temperature of the power MOSFET, the power dissipated by the device must be known. This power dissipation is a function of the duty cycle, the load current, and the junction temperature itself (due to the positive temperature coefficient of its R<sub>DS(ON)</sub>). As a result, some iterative calculation is normally required to determine a reasonably accurate value. Since the controller is using the MOSFET as both a switching and a sensing element, care should be taken to ensure that the converter is capable of delivering the required load current over all operating conditions (line voltage and temperature), and for the worst-case specifications for V<sub>SENSE(MAX)</sub> and the R<sub>DS(ON)</sub> of the MOSFET listed in the manufacturer's data sheet.

The power dissipated by the MOSFET in a boost converter is:

$$P_{FET} = \left( \frac{I_{OUT(MAX)}}{1 - D_{MAX}} \right)^2 \cdot R_{DS(ON)} \cdot D_{MAX} \cdot \rho_T + k \cdot V_{OUT}^{1.85} \cdot \left( \frac{I_{OUT(MAX)}}{1 - D_{MAX}} \right) \cdot C_{RSS} \cdot f$$

The first term in the equation above represents the I<sup>2</sup>R losses in the device, and the second term, the switching losses. The constant k = 1.7 is an empirical factor inversely related to the gate drive current and has the dimension of 1/current.

From a known power dissipated in the power MOSFET, its junction temperature can be obtained using the following formula:

$$T_J = T_A + P_{FET} \cdot \theta_{JA}$$

The  $\theta_{JA}$  to be used in this equation normally includes the  $\theta_{JC}$  for the device plus the thermal resistance from the case to the ambient temperature ( $\theta_{CA}$ ). This value of T<sub>J</sub> can then be compared to the original, assumed value used in the iterative calculation process.

## OPERATION

### Boost Converter: Output Diode Selection

To maximize efficiency, a fast switching diode with low forward drop and low reverse leakage is desired. The output diode in a boost converter conducts current during the switch off-time. The peak reverse voltage that the diode must withstand is equal to the regulator output voltage. The average forward current in normal operation is equal to the output current, and the peak current is equal to the peak inductor current.

$$I_{D(PEAK)} = I_{L(PEAK)} = \left(1 + \frac{\chi}{2}\right) \cdot \frac{I_{OUT(MAX)}}{1 - D_{MAX}}$$

The power dissipated by the diode is:

$$P_D = I_{OUT(MAX)} \cdot V_D$$

and the diode junction temperature is:

$$T_J = T_A + P_D \cdot \theta_{JA}$$

The  $\theta_{JA}$  to be used in this equation normally includes the  $\theta_{JC}$  for the device plus the thermal resistance from the board to the ambient temperature in the enclosure.

Remember to keep the diode lead lengths short and to observe proper switch-node layout (see Board Layout Checklist) to avoid excessive ringing and increased dissipation.

### Boost Converter: Output Capacitor Selection

Contributions of ESR (equivalent series resistance), ESL (equivalent series inductance) and the bulk capacitance must be considered when choosing the correct component for a given output ripple voltage. The effects of these three parameters (ESR, ESL and bulk C) on the output voltage ripple waveform are illustrated in Figure 9 for a typical boost converter.

The choice of component(s) begins with the maximum acceptable ripple voltage (expressed as a percentage of the output voltage), and how this ripple should be divided between the ESR step and the charging/discharging  $\Delta V$ . For the purpose of simplicity we will choose 2% for the maximum output ripple, to be divided equally between the

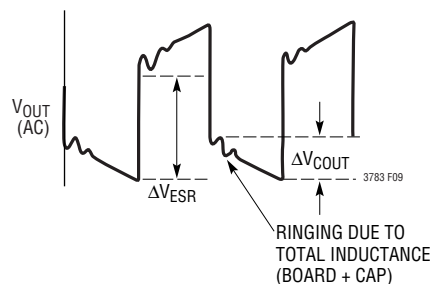


Figure 9. Output Ripple Voltage

ESR step and the charging/discharging  $\Delta V$ . This percentage ripple will change, depending on the requirements of the application, and the equations provided below can easily be modified.

For a 1% contribution to the total ripple voltage, the ESR of the output capacitor can be determined using the following equation:

$$ESR_{COUT} < 0.01 \cdot \frac{V_{OUT}}{I_{IN(PEAK)}}$$

where:

$$I_{IN(PEAK)} = \left(1 + \frac{\chi}{2}\right) \cdot \frac{I_{OUT(MAX)}}{1 - D_{MAX}}$$

For the bulk C component, which also contributes 1% to the total ripple:

$$C_{OUT} > \frac{I_{OUT(MAX)}}{0.01 \cdot V_{OUT} \cdot f}$$

For many designs it is possible to choose a single capacitor type that satisfies both the ESR and bulk C requirements for the design. In certain demanding applications, however, the ripple voltage can be improved significantly by connecting two or more types of capacitors in parallel. For example, using a low ESR ceramic capacitor can minimize the ESR setup, while an electrolytic capacitor can be used to supply the required bulk C.

Once the output capacitor ESR and bulk capacitance have been determined, the overall ripple voltage waveform should be verified on a dedicated PC board (see Board

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Layout section for more information on component placement). Lab breadboards generally suffer from excessive series inductance (due to inter-component wiring), and these parasitics can make the switching waveforms look significantly worse than they would be on a properly designed PC board.

The output capacitor in a boost regulator experiences high RMS ripple currents. The RMS output capacitor ripple current is:

$$I_{\text{RMS(COUT)}} \approx I_{\text{OUT(MAX)}} \cdot \sqrt{\frac{V_{\text{OUT}} - V_{\text{IN(MIN)}}}{V_{\text{IN(MIN)}}}}$$

Note that the ripple current ratings from capacitor manufacturers are often based on only 2000 hours of life. This makes it advisable to further derate the capacitor or to choose a capacitor rated at a higher temperature than required. Several capacitors may also be placed in parallel to meet size or height requirements in the design.

### Boost Converter: Input Capacitor Selection

The input capacitor of a boost converter is less critical than the output capacitor, due to the fact that the inductor is in series with the input, and hence, the input current waveform is continuous (see Figure 10). The input voltage source impedance determines the size of the input capacitor, which is typically in the range of 10μF to 100μF. A low ESR capacitor is recommended, although it is not as critical as for the output capacitor.

The RMS input capacitor ripple current for a boost converter is:

$$I_{\text{RMS(CIN)}} \approx 0.3 \cdot \frac{V_{\text{IN(MIN)}}}{L \cdot f} \cdot D_{\text{MAX}}$$

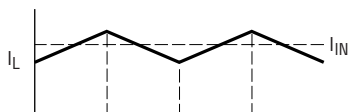


Figure 10. Inductor and Input Currents

Please note that the input capacitor can see a very high surge current when a battery is suddenly connected to the input of the converter, and solid tantalum capacitors can fail catastrophically under these conditions. Be sure to specify surge-tested capacitors!

### Boost Converter Design Example

The design example given here will be for the circuit shown in Figure 1. The input voltage is 12V, and the output voltage is 25V at a maximum load current of 0.7A (1A peak).

1. The duty cycle is:

$$D = \frac{V_{\text{OUT}} + V_D - V_{\text{IN}}}{V_{\text{OUT}} + V_D} = \frac{25 + 0.4 - 12}{25 + 0.4} = 53\%$$

2. The operating frequency is chosen to be 1MHz to maximize the PWM dimming range. From Figure 2, the resistor from the FREQ pin to ground is 6k.

3. An inductor ripple current of 40% of the maximum load current is chosen, so the peak input current (which is also the minimum saturation current) is:

$$I_{\text{IN(PEAK)}} = \left(1 + \frac{\chi}{2}\right) \cdot \frac{I_{\text{OUT(MAX)}}}{1 - D_{\text{MAX}}} = 1.2 \cdot \frac{0.7}{1 - 0.53} = 1.8\text{A}$$

The inductor ripple current is:

$$\Delta I_L = \chi \cdot \frac{I_{\text{OUT(MAX)}}}{1 - D_{\text{MAX}}} = 0.4 \cdot \frac{0.7}{1 - 0.53} = 0.6\text{A}$$

And so the inductor value is:

$$L = \frac{V_{\text{IN(MIN)}}}{\Delta I_L \cdot f} \cdot D_{\text{MAX}} = \frac{12\text{V}}{0.6\text{A} \cdot 1\text{MHz}} \cdot 0.53 = 11\mu\text{H}$$

4.  $R_{\text{SENSE}}$  should be:

$$R_{\text{SENSE}} = \frac{0.5 \cdot V_{\text{SENSE(MAX)}}}{I_{\text{IN(PEAK)}}} = \frac{0.5 \cdot 150\text{mV}}{1.8\text{A}} = 42\text{m}\Omega$$

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5. The diode for this design must handle a maximum DC output current of 0.7A and be rated for a minimum reverse voltage of  $V_{OUT}$ , or 25V. A 1A, 40V diode from Zetex was chosen for its specifications, especially low leakage at higher temperatures, which is important for maintaining dimming range.

6. Voltage and value permitting, the output capacitor usually consists of some combination of low ESR ceramics. Based on a maximum output ripple voltage of 1%, or 250mV, the bulk C needs to be greater than:

$$C_{OUT} > \frac{I_{OUT(MAX)}}{0.01 \cdot V_{OUT} \cdot f} = \frac{0.7A}{0.01 \cdot 25V \cdot 1MHz} = 3\mu F$$

The RMS ripple current rating for this capacitor needs to exceed:

$$I_{RMS(COUT)} = I_{OUT(MAX)} \cdot \sqrt{\frac{V_{OUT} - V_{IN(MIN)}}{V_{IN(MIN)}}}$$

$$= 0.7A \cdot \sqrt{\frac{25V - 12V}{12V}} = 0.7A$$

Based on value and ripple current, and taking physical size into account, a surface mount ceramic capacitor is a good choice. A 4.7 $\mu$ F TDK C5750X7R1H475M will satisfy all requirements in a compact package.

7. The soft-start capacitor should be:

$$C_{SS(MIN)} > \frac{2 \cdot \text{dimming ratio} \cdot 50\mu A \cdot C_{OUT} \cdot V_{OUT} \cdot R_{DS(ON)}/SENSE}{150mV \cdot 1.2V}$$

$$> \frac{2 \cdot 3000 \cdot 50\mu A \cdot 4.7\mu F \cdot 25V \cdot 42m\Omega}{150mV \cdot 1.2V} = 8\mu F$$

8. The choice of an input capacitor for a boost converter depends on the impedance of the source supply and the amount of input ripple the converter will safely tolerate. For this particular design and lab setup, 20 $\mu$ F was found to be satisfactory.

### PC Board Layout Checklist

1. In order to minimize switching noise and improve output load regulation, the GND pad of the LTC3783 should be connected directly to 1) the negative terminal of

the INTV<sub>CC</sub> decoupling capacitor, 2) the negative terminal of the output decoupling capacitors, 3) the bottom terminals of the sense resistors or the source of the power MOSFET, 4) the negative terminal of the input capacitor, and 5) at least one via to the ground plane immediately under the exposed pad. The ground trace on the top layer of the PC board should be as wide and short as possible to minimize series resistance and inductance.

2. Beware of ground loops in multiple layer PC boards. Try to maintain one central ground node on the board and use the input capacitor to avoid excess input ripple for high output current power supplies. If the ground plane is to be used for high DC currents, choose a path away from the small-signal components.

3. Place the C<sub>VCC</sub> capacitor immediately adjacent to the INTV<sub>CC</sub> and GND pins on the IC package. This capacitor carries high di/dt MOSFET gate-drive currents. A low ESR and ESL 4.7 $\mu$ F ceramic capacitor works well here.

4. The high di/dt loop from the bottom terminal of the output capacitor, through the power MOSFET, through the boost diode and back through the output capacitors should be kept as tight as possible to reduce inductive ringing. Excess inductance can cause increased stress on the power MOSFET and increase HF noise on the output. If low ESR ceramic capacitors are used on the output to reduce output noise, place these capacitors close to the boost diode in order to keep the series inductance to a minimum.

5. Check the stress on the power MOSFET by measuring its drain-to-source voltage directly across the device terminals (reference the ground of a single scope probe directly to the source pad on the PC board). Beware of inductive ringing which can exceed the maximum specified voltage rating of the MOSFET. If this ringing cannot be avoided and exceeds the maximum rating of the device, either choose a higher voltage device or specify an avalanche-rated power MOSFET.

6. Place the small-signal components away from high frequency switching nodes. All of the small-signal components should be placed on one side of the IC and all of the power components should be placed on the other. This also allows the use of a pseudo-Kelvin connection for the signal ground, where high di/dt gate driver currents flow

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out of the IC ground pad in one direction (to bottom plate of the  $INTV_{CC}$  decoupling capacitor) and small-signal currents flow in the other direction.

7. If a sense resistor is used in the source of the power MOSFET, minimize the capacitance between the SENSE pin trace and any high frequency switching nodes. The LTC3783 contains an internal leading-edge blanking time of approximately 160ns, which should be adequate for most applications.

8. For optimum load regulation and true remote sensing, the top of the output resistor should connect independently to the top of the output capacitor (Kelvin connection), staying away from any high dV/dt traces. Place the divider resistors near the LTC3783 in order to keep the high impedance FBN node short.

9. For applications with multiple switching power converters connected to the same input supply, make sure that the input filter capacitor for the LTC3783 is not shared with any other converters. AC input current from another converter could cause substantial input voltage ripple, and this could interfere with the operation of the LTC3783. A few inches of PC trace or wire ( $L \sim 100\text{nH}$ ) between the  $C_{IN}$  of the LTC3783 and the actual source  $V_{IN}$  should be sufficient to prevent current-sharing problems.

### Returning the Load to $V_{IN}$ : A Single Inductor Buck-Boost Application

As shown in Figure 11, due to its available high side current sensing mode, the LTC3783 is also well-suited to a boost converter in which the load current is returned to  $V_{IN}$ , hence providing a load voltage ( $V_{OUT} - V_{IN}$ ) which can be greater or less than the input voltage  $V_{IN}$ . This configuration allows for complete overlap of input and output voltages, with the disadvantages that only the load current, and not the load voltage, can be tightly regulated. The switch must be rated for a  $V_{DS(MAX)}$  equal to  $V_{IN} + V_{LOAD}$ .

The design of this circuit resembles that of the boost converter above, and the procedure is much the same, except  $V_{OUT}$  is now  $(V_{IN} + V_{LOAD})$ , and the duty cycles and voltages must be adjusted accordingly.

Similar to the boost converter, which can be dimmed via the digital PWMIN input or the analog FBP pin, the buck-boost can be dimmed via the PWMIN pin or the analog  $I_{LIM}$  pin, which adjusts the offset voltage to which the loop will drive ( $V_{FBP} - V_{FBN}$ ). In the case of the buck-boost, however, the dimming ratio cannot be as high as in the boost converter, since there is no load switch to preserve the  $V_{OUT}$  level while PWMIN is low.

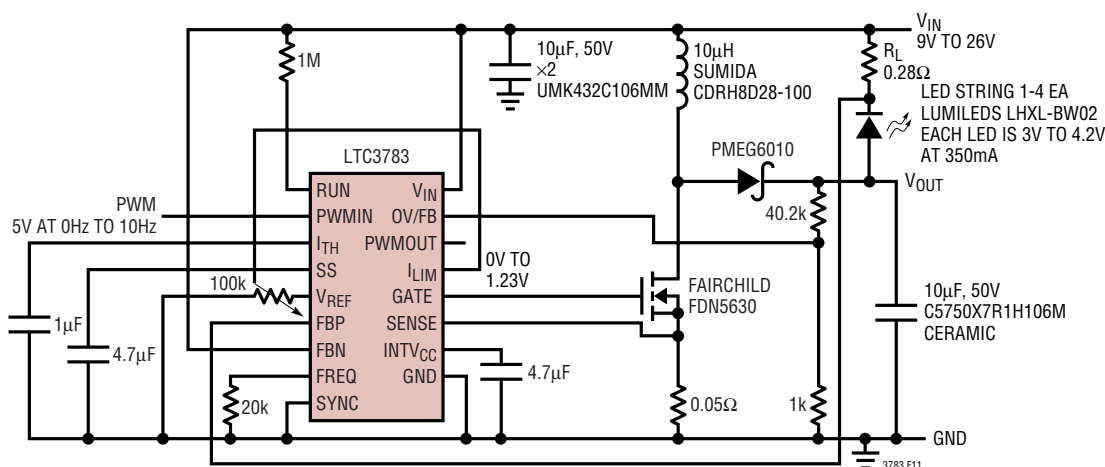


Figure 11. Single Inductor Buck-Boost Application with Analog Dimming and Low Frequency PWM Dimming

As shown in Figure 12, high side current sensing also allows the LTC3783 to control a functional buck converter when load voltage is always sufficiently less than

The schematic diagram illustrates the LTC3783 LED driver circuit. The input voltage  $V_{IN}$  ranges from 6V to 36V. The circuit includes a feedback network with resistors and capacitors, a current sense resistor ( $R_{CS}$ ), and an LED string. The LTC3783 is configured with various pins connected to  $V_{IN}$ , GND, and the feedback network. The output is connected to the LED string through a diode and a resistor.





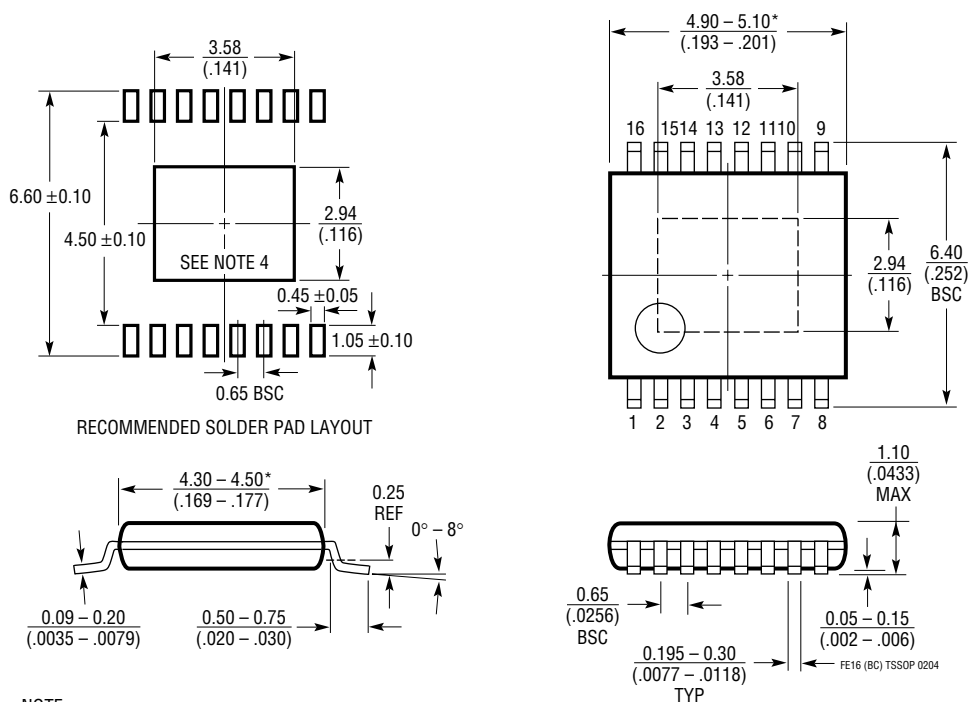
Diagram illustrating the top view of a package with dimensions and pin layout:

- Overall width:  $4.50 \pm 0.05$
- Distance from top edge to top of package body:  $3.10 \pm 0.05$
- Distance from top edge to top of package body (2 SIDES):  $2.44 \pm 0.05$
- Distance from top edge to top of package body (2 SIDES):  $0.70 \pm 0.05$
- Distance from bottom edge to bottom of package body:  $4.34 \pm 0.05$  (2 SIDES)
- Distance from bottom edge to bottom of package body:  $0.25 \pm 0.05$
- Distance from bottom edge to bottom of package body:  $0.50$  BSC
- Pin layout: 10 pins on the top edge and 10 pins on the bottom edge.
- Label: PACKAGE OUTLINE

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# PACKAGE DESCRIPTION

## FE Package 16-Lead Plastic TSSOP (4.4mm) (Reference LTC DWG # 05-08-1663) Exposed Pad Variation BC



### NOTE:

1. CONTROLLING DIMENSION: MILLIMETERS
2. DIMENSIONS ARE IN  $\frac{\text{MILLIMETERS}}{\text{INCHES}}$
3. DRAWING NOT TO SCALE

4. RECOMMENDED MINIMUM PCB METAL SIZE FOR EXPOSED PAD ATTACHMENT

\*DIMENSIONS DO NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED  $0.150\text{mm}$  ( $.006$ " ) PER SIDE

**RELATED PARTS**

| PART NUMBER          | DESCRIPTION                                         | COMMENTS                                                                                 |
|----------------------|-----------------------------------------------------|------------------------------------------------------------------------------------------|
| LT <sup>®</sup> 1618 | Monolithic 1.4MHz Boost Regulator                   | Constant-Current/Constant-Voltage, 1A Switch                                             |
| LTC1871              | Boost, Flyback, SEPIC Controller                    | No R <sub>SENSE</sub> , 2.5V ≤ V <sub>IN</sub> ≤ 36V, 92% Duty Cycle                     |
| LT3477               | 3A DC/DC LED Driver with Rail-to-Rail Current Sense | 2.5V ≤ V <sub>IN</sub> ≤ 25V: Buck, Buck-Boost and Boost Topologies                      |
| LTC3780              | High Power Buck-Boost Controller                    | 4-Switch, 4V ≤ V <sub>IN</sub> ≤ 36V, 0.8V ≤ V <sub>OUT</sub> ≤ 30V                      |
| LTC3782              | 2-Phase Boost Controller                            | High Power, 6V ≤ V <sub>IN</sub> ≤ 40V, 150kHz to 500kHz                                 |
| LTC3827/LTC3827-1    | Low I <sub>Q</sub> Current Dual Controllers         | 2-Phase, 80μA I <sub>Q</sub> , 0.8V ≤ V <sub>OUT</sub> ≤ 10V, 4V ≤ V <sub>IN</sub> ≤ 36V |
| LTC4002              | Standalone 2A Li-Ion Battery Charger                | 1- and 2-Cell, 4.7V ≤ V <sub>IN</sub> ≤ 22V, 3 Hour Timer                                |