

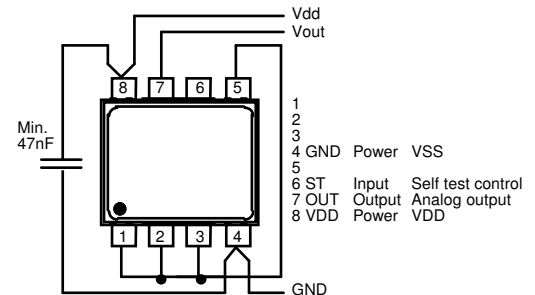
Inclination and Acceleration Sensors

SCA610 series

The sensors are based on an advanced "bulk micro machined" MEMS technology. The three dimensional structure (3D MEMS) of these sensors comprise a pendulum made of mono crystalline silicon. The pendulum is hermetically enclosed between two silicon discs. From this construction results a long term stable, high resolution und shock resistant sensor. A gas damping prevents overshooting and interfering resonance oscillation. The movement of the pendulum is measured capacitively by an ASIC.



- senses in positive and negative direction
- static and dynamic acceleration measured
- high repeatability up to 0,05% over range
- high resolution: up to 0,005% over range
- shock resistance of the pendulum min. 50'000g
- passive temperature compensation
- temperature range -40... +125°C
- small, solid brass housing with fixing holes
- rugged PVC cable
- large output span: 0.5 .. 4.5V output over measuring range
- 11x12x5 mm DIL 8- pin housing for SMD mounting



Other versions

- single and dual axis inclination and acceleration sensor chips in DIL-housing for SMD mounting
- single and dual axis sensors in IP67 housing with fixing holes, cable or connector and standardized signal output (4... 20mA, 2... 10V, digital output)

*) G and A are marks for technically identical device from different production series

Parameter	Remarks / Conditions	SCA610-CAHH1G	SCA610-CA1H1G	SCA610-C21H1A	SCA610-C13H1A	SCA610*) C28H1A(G)	SCA610-CC5H1A	Einheit
Measuring range (g) (angle) ⁴⁾		+/- 1,5 +/- 30	+/- 1 +/- 90	+/- 1 +/- 90	+/- 1,5 (+/- 90)	+/- 1,7 (+/- 90)	+/- 3	g (°)
Repeatability ¹⁾	0 .. 40°C on 0° angle	2 0,1	2 0,1	4 0,2	ca. 4 ca. 0,2	4 0,2	ca. 8	mg ° (angle)
Resolution (analogue output) ⁶⁾	0...50 Hz	0,2	0,2	0,2	0,2	0,2	0,4	mg
Longterm stability ⁵⁾	10 Jahren ⁵⁾	ca. 0,5	ca. 0,5	ca. 0,5	ca. 0,5	ca. 0,5	ca. 0,5	%
Measuring direction		horizontal	horizontal	horizontal	horizontal	horizontal	horizontal	
Cross axis sensitivity ²⁾	Max.	5	5	5	5	5	5	%
Damping / frequency response	-3dB, typ.	18	18	50	400	50	115	Hz
Operating temperature range		-40... +125	-40... +125	-40... +125	-40... +125	-40... +125	-40... +125	°C
Shock resistance		20'000	20'000	20'000	20'000	20'000	20'000	G
Output signal V _{out} Offset = V _{out} in 0° / rest position		0,5 .. 4,5 2,5 1,333	0,5 .. 4,5 2,5 1,333	0,5 .. 4,5 2,5 2	0,5 .. 4,5 2,5 1,333	0,5 .. 4,5 2,5 1,2	0,5 .. 4,5 2,5 0,75	V V V/g
Power supply ³⁾	max	4.75 ... 5.25	4.75 ... 5.25	4.75 ... 5.25	4.75 ... 5.25	4.75 ... 5.25	4.75 ... 5.25	V
Power consumption max.	on 5V on 3V ³⁾	2.0 approx. 0,3	2.0 approx. 0,3	2.0 approx. 0,3	2.0 approx. 0,3	2.0 approx. 0,3	2.0 approx. 0,3	mA mA

1) **Repeatability:** maximum offset occurring with position change after return to initial position (Corresponds to achievable precision including temperature hysteresis after temperature compensation and linearization).

2) **Cross axis sensitivity:** maximum error occurring with (additional) inclination or acceleration from another direction than the measuring plane

3) **Supply:** 5V DC stabilized; variations affect the measurement; (alternatively 3V, precision and resolution will be affected: 1g <> 1.5V, output ≈ 0.3 ... 2.7V)

4) **Measuring range:** Trigonometric function: $\text{angle} = \arcsin\left(\frac{V_{\text{out}} - 2,5(\text{Offset})}{\text{Sensitivity}}\right)$ (paste values without units)

5) **Long term stability:** calculated values from HTB tests. Test results available at request.

6) **Auflösung/Rauschen:** Averaging can improve very well the Resolution due to the noise of the sensing element (20..30 µg/Hz) which is 5...10x smaller the noise of the ASIC.: Test results available on request.