

## Features

- **ZERO POWER E<sup>2</sup>CMOS TECHNOLOGY**
  - 100µA Standby Current
  - Input Transition Detection on GAL16V8Z
  - Dedicated Power-down Pin on GAL16V8ZD
  - Input and Output Latching During Power Down
- **HIGH PERFORMANCE E<sup>2</sup>CMOS TECHNOLOGY**
  - 12 ns Maximum Propagation Delay
  - F<sub>max</sub> = 83.3 MHz
  - 8 ns Maximum from Clock Input to Data Output
  - TTL Compatible 16 mA Output Drive
  - UltraMOS<sup>®</sup> Advanced CMOS Technology
- **E<sup>2</sup> CELL TECHNOLOGY**
  - Reconfigurable Logic
  - Reprogrammable Cells
  - 100% Tested/100% Yields
  - High Speed Electrical Erasure (<100ms)
  - 20 Year Data Retention
- **EIGHT OUTPUT LOGIC MACROCELLS**
  - Maximum Flexibility for Complex Logic Designs
  - Programmable Output Polarity
  - Architecturally Similar to Standard GAL16V8
- **PRELOAD AND POWER-ON RESET OF ALL REGISTERS**
  - 100% Functional Testability
- **APPLICATIONS INCLUDE:**
  - Battery Powered Systems
  - DMA Control
  - State Machine Control
  - High Speed Graphics Processing
- **ELECTRONIC SIGNATURE FOR IDENTIFICATION**

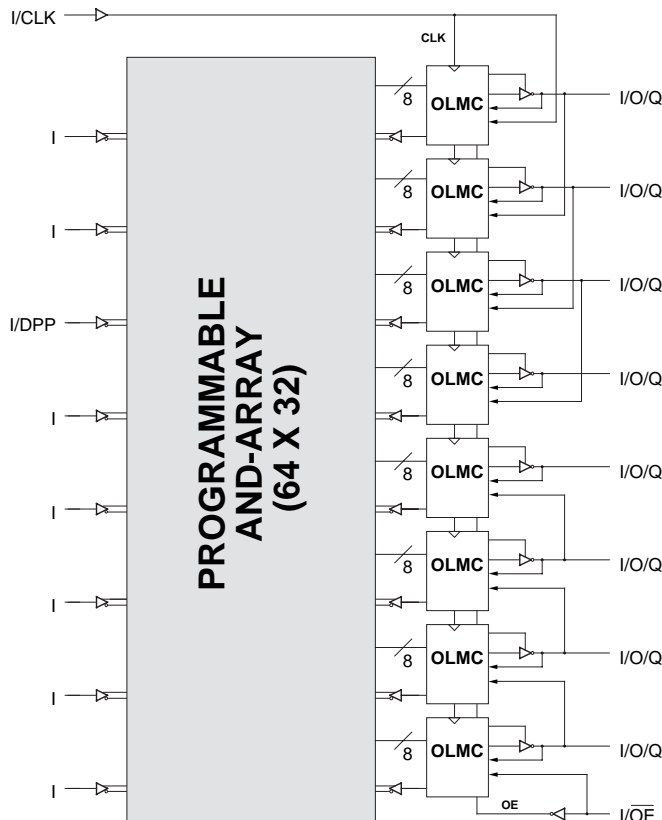
## Description

The GAL16V8Z and GAL16V8ZD, at 100 µA standby current and 12ns propagation delay provides the highest speed and lowest power combination PLD available in the market. The GAL16V8Z/ZD is manufactured using Lattice Semiconductor's advanced zero power E<sup>2</sup>CMOS process, which combines CMOS with Electrically Erasable (E<sup>2</sup>) floating gate technology.

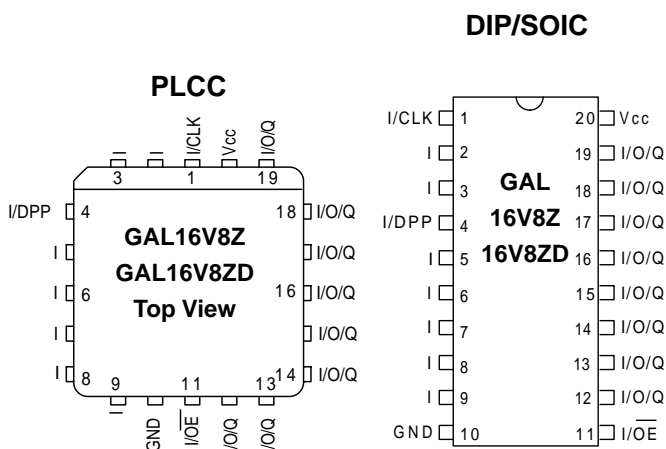
The GAL16V8Z uses Input Transition Detection (ITD) to put the device in standby mode and is capable of emulating the full functionality of the standard GAL16V8. The GAL16V8ZD utilizes a dedicated power-down pin (DPP) to put the device in standby mode. It has 15 inputs available to the AND array.

Unique test circuitry and reprogrammable cells allow complete AC, DC, and functional testing during manufacture. As a result, Lattice Semiconductor delivers 100% field programmability and functionality of all GAL products. In addition, 100 erase/write cycles and data retention in excess of 20 years are specified.

## Functional Block Diagram



## Pin Configuration



## GAL16V8Z/ZD ORDERING INFORMATION

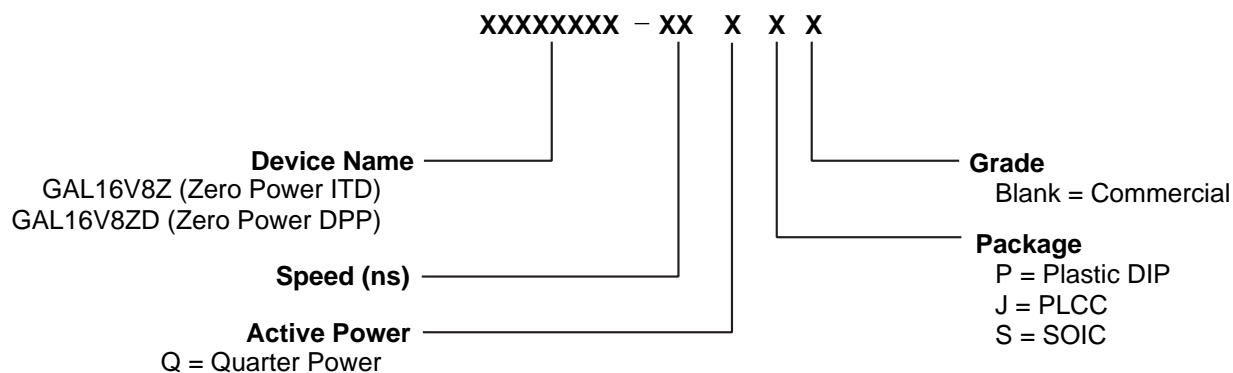
### GAL16V8Z: Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	I <sub>sb</sub> (μA)	Ordering #	Package
12	10	8	55	100	GAL16V8Z-12QP	20-Pin Plastic DIP
			55	100	GAL16V8Z-12QJ	20-Lead PLCC
			55	100	GAL16V8Z-12QS	20-Lead SOIC
15	15	10	55	100	GAL16V8Z-15QP	20-Pin Plastic DIP
			55	100	GAL16V8Z-15QJ	20-Lead PLCC
			55	100	GAL16V8Z-15QS	20-Lead SOIC

### GAL16V8ZD: Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	I <sub>sb</sub> (μA)	Ordering #	Package
12	10	8	55	100	GAL16V8ZD-12QP	20-Pin Plastic DIP
			55	100	GAL16V8ZD-12QJ	20-Lead PLCC
15	15	10	55	100	GAL16V8ZD-15QP	20-Pin Plastic DIP
			55	100	GAL16V8ZD-15QJ	20-Lead PLCC

## PART NUMBER DESCRIPTION



## OUTPUT LOGIC MACROCELL (OLMC)

The following discussion pertains to configuring the output logic macrocell. It should be noted that actual implementation is accomplished by development software/hardware and is completely transparent to the user.

There are three global OLMC configuration modes possible: **simple**, **complex**, and **registered**. Details of each of these modes is illustrated in the following pages. Two global bits, SYN and AC0, control the mode configuration for all macrocells. The

XOR bit of each macrocell controls the polarity of the output in any of the three modes, while the AC1 bit of each of the macrocells controls the input/output configuration. These two global and 16 individual architecture bits define all possible configurations in a GAL16V8Z/ZD. The information given on these architecture bits is only to give a better understanding of the device. Compiler software will transparently set these architecture bits from the pin definitions, so the user should not need to directly manipulate these architecture bits.

## COMPILER SUPPORT FOR OLMC

Software compilers support the three different global OLMC modes as different device types. Most compilers also have the ability to automatically select the device type, generally based on the register usage and output enable (OE) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with OE controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without OE control. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode.

In **registered mode** pin 1 and pin 11 are permanently configured as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In **complex mode** pin 1 and pin 11 become dedicated inputs and use the feedback paths of pin 19 and pin 12 respectively. Because of this feedback path usage, pin 19 and pin 12 do not have the feedback option in this mode.

In **simple mode** all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins (pins 15 and 16) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

When using the standard GAL16V8 JEDEC fuse pattern generated by the logic compilers for the GAL16V8ZD, special attention must be given to pin 4 (DPP) to make sure that it is not used as one of the functional inputs.

## Registered Mode

In the Registered mode, macrocells are configured as dedicated registered outputs or as I/O functions.

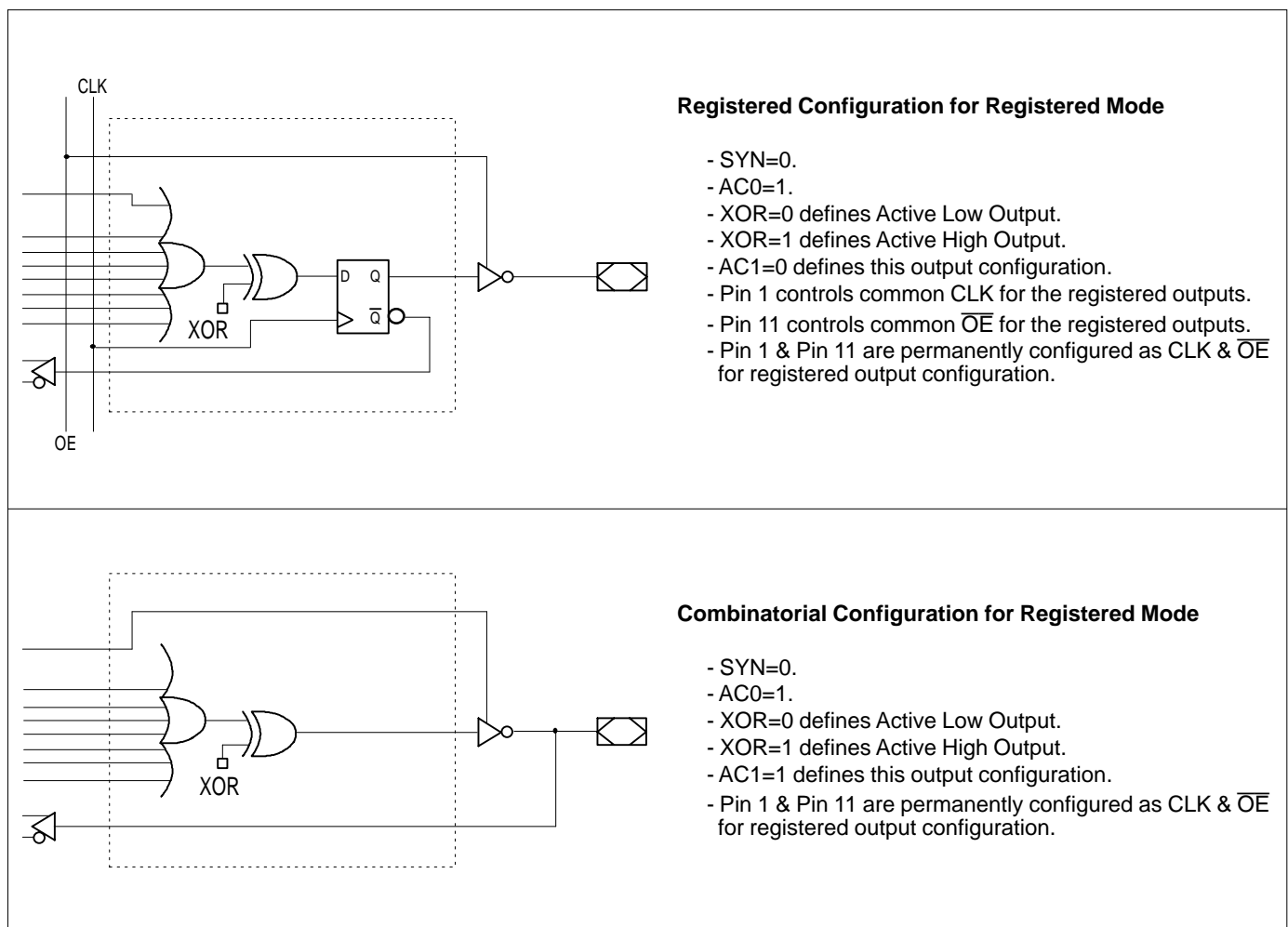
Architecture configurations available in this mode are similar to the common 16R8 and 16RP4 devices with various permutations of polarity, I/O and register placement.

All registered macrocells share common clock and output enable control pins. Any macrocell can be configured as registered or I/O. Up to eight registers or up to eight I/Os are possible in this mode. Dedicated input or output functions can be implemented as subsets of the I/O function.

Registered outputs have eight product terms per output. I/Os have seven product terms per output.

Pin 4 is used as dedicated power-down pin on GAL16V8ZD. It cannot be used as functional input.

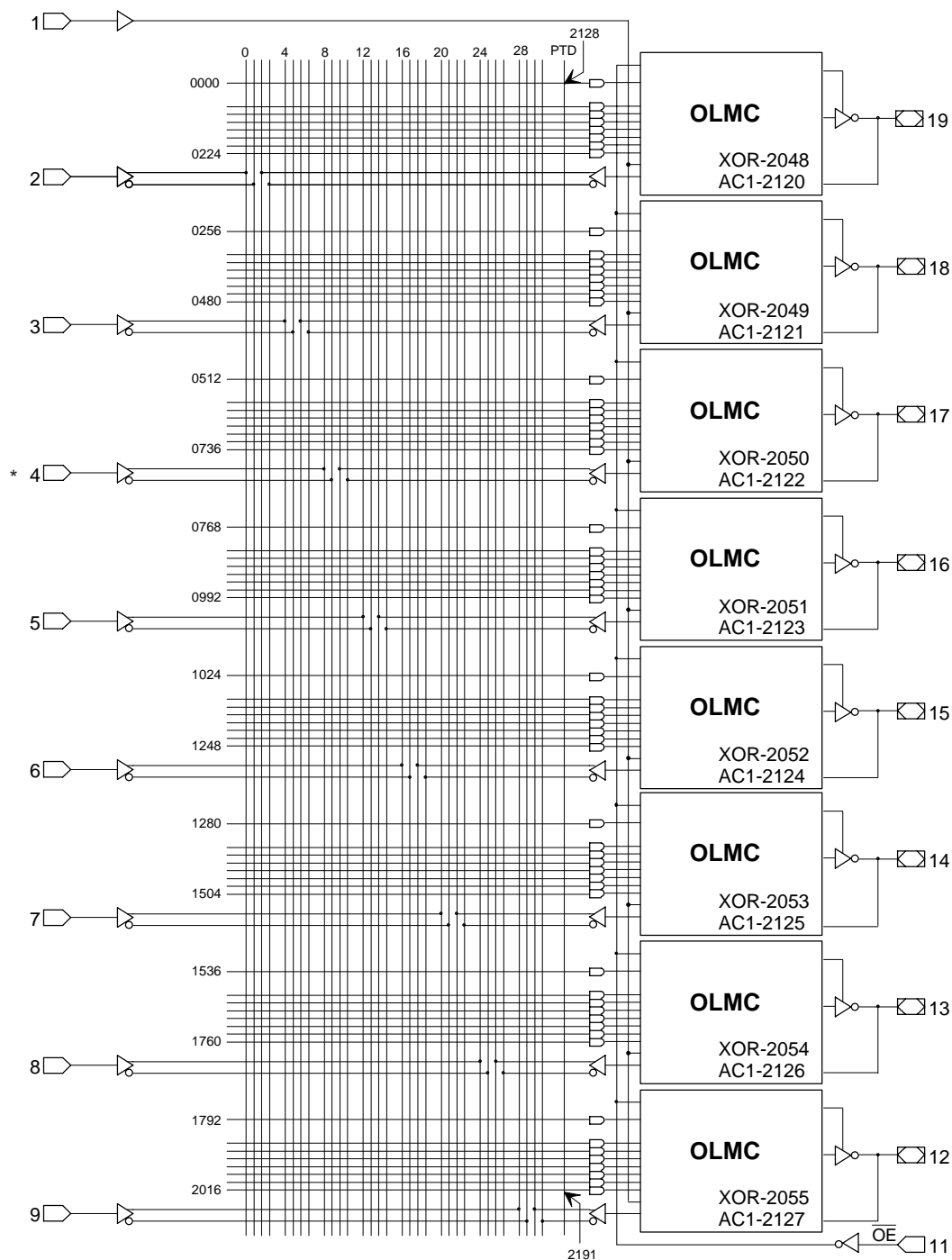
The JEDEC fuse numbers, including the User Electronic Signature (UES) fuses and the Product Term Disable (PTD) fuses, are shown on the logic diagram on the following page.



Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.

**REGISTERED MODE LOGIC DIAGRAM**

DIP, SOIC & PLCC Package Pinouts



64-USER ELECTRONIC SIGNATURE FUSES

2056, 2057, .... 2118, 2119

Byte7 Byte6 .... Byte1 Byte0

MSB

LSB

SYN-2192

AC0-2193

\* Note: Input not available on GAL16V8ZD

## COMPLEX MODE

In the Complex mode, macrocells are configured as output only or I/O functions.

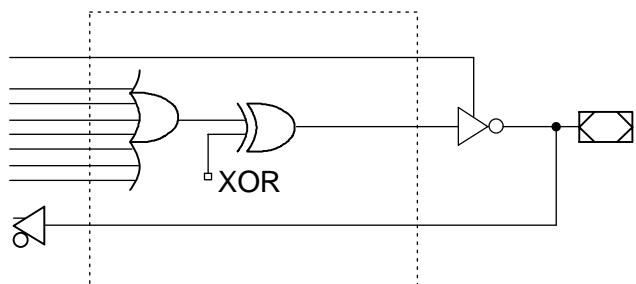
Architecture configurations available in this mode are similar to the common 16L8 and 16P8 devices with programmable polarity in each macrocell.

Up to six I/Os are possible in this mode. Dedicated inputs or outputs can be implemented as subsets of the I/O function. The two outer most macrocells (pins 12 & 19) do not have input capability. Designs requiring eight I/Os can be implemented in the Registered mode.

All macrocells have seven product terms per output. One product term is used for programmable output enable control. Pins 1 and 11 are always available as data inputs into the AND array.

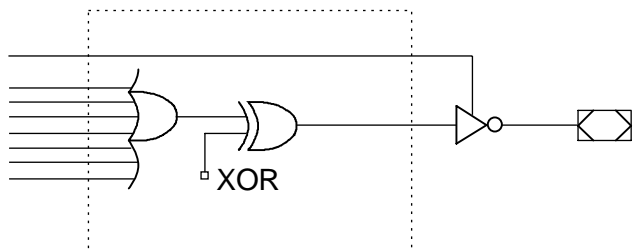
Pin 4 is used as dedicated power-down pin on GAL16V8ZD. It cannot be used as functional input.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram on the following page.



### Combinatorial I/O Configuration for Complex Mode

- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1 has no effect on this mode.
- Pin 13 through Pin 18 are configured to this function.



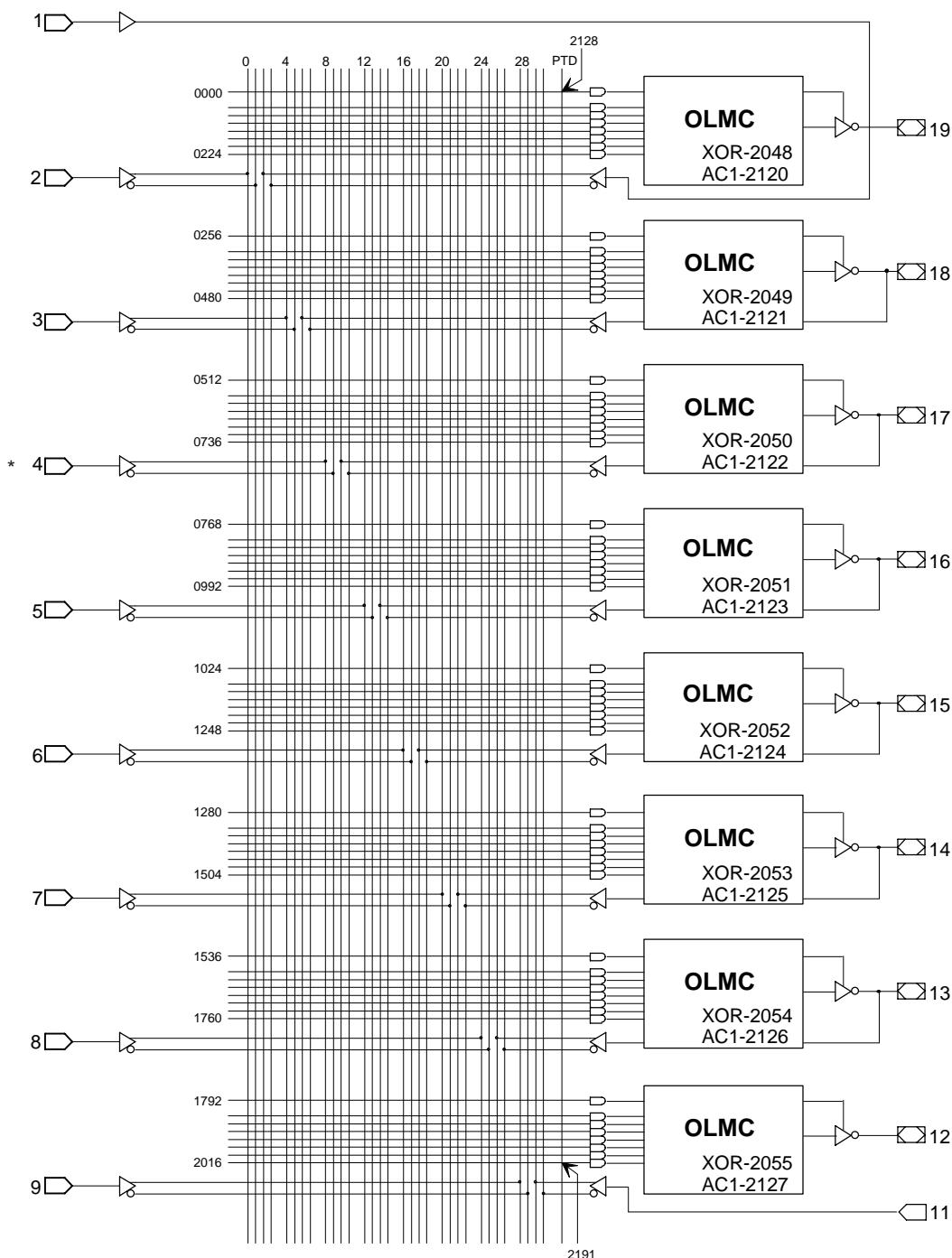
### Combinatorial Output Configuration for Complex Mode

- SYN=1.
- AC0=1.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1 has no effect on this mode.
- Pin 12 and Pin 19 are configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.

**COMPLEX MODE LOGIC DIAGRAM**

DIP, SOIC & PLCC Package Pinouts



64-USER ELECTRONIC SIGNATURE FUSES			
2056, 2057, ....	.... 2118, 2119	Byte7	Byte6 ....
.... Byte1	Byte0	MSB	LSB

SYN-2192  
AC0-2193

\* Note: Input not available on GAL16V8ZD

## SIMPLE MODE

In the Simple mode, macrocells are configured as dedicated inputs or as dedicated, always active, combinatorial outputs.

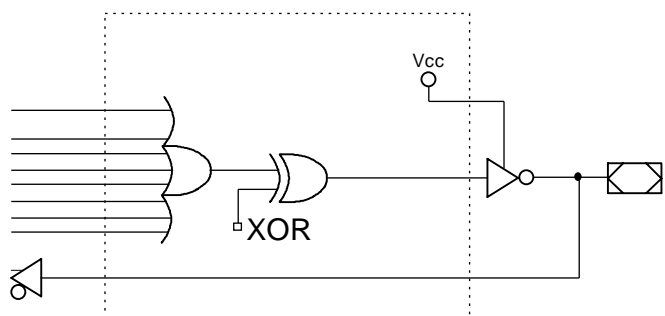
Architecture configurations available in this mode are similar to the common 10L8 and 12P6 devices with many permutations of generic output polarity or input choices.

All outputs in the simple mode have a maximum of eight product terms that can control the logic. In addition, each output has programmable polarity.

Pins 1 and 11 are always available as data inputs into the AND array. The center two macrocells (pins 15 & 16) cannot be used in the input configuration.

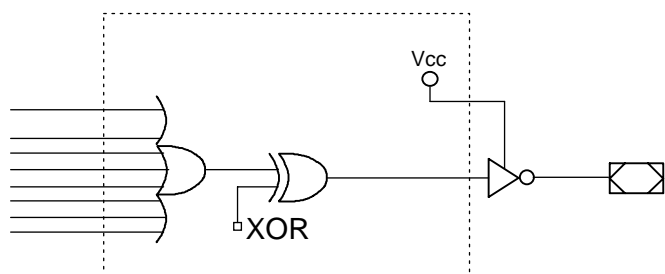
Pin 4 is used as dedicated power-down pin on GAL16V8ZD. It cannot be used as functional input.

The JEDEC fuse numbers including the UES fuses and PTD fuses are shown on the logic diagram.



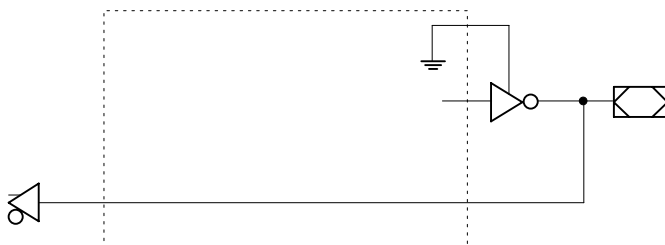
### Combinatorial Output with Feedback Configuration for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- All OLMC **except** pins 15 & 16 can be configured to this function.



### Combinatorial Output Configuration for Simple Mode

- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=0 defines this configuration.
- Pins 15 & 16 are permanently configured to this function.



### Dedicated Input Configuration for Simple Mode

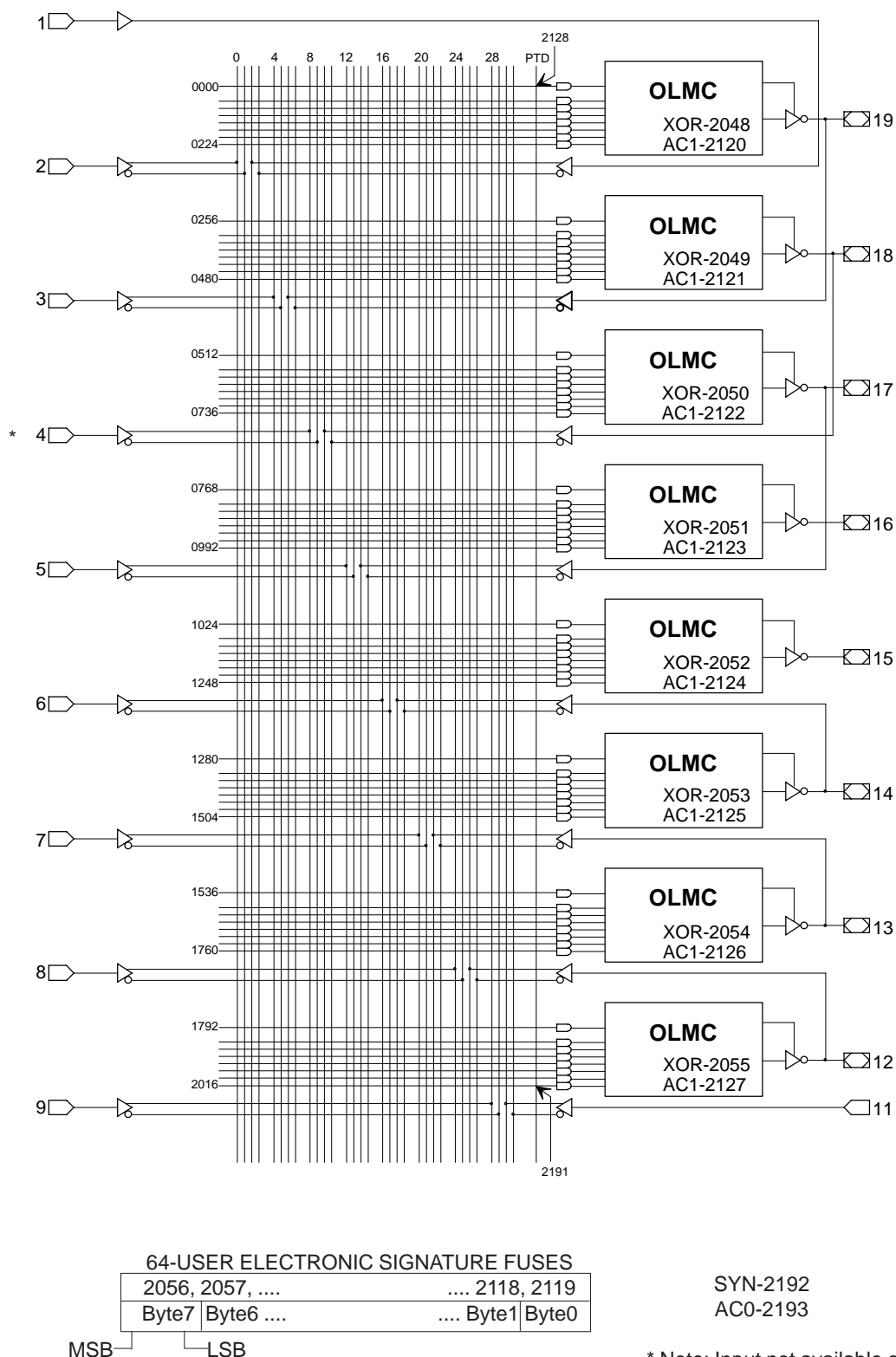
- SYN=1.
- AC0=0.
- XOR=0 defines Active Low Output.
- XOR=1 defines Active High Output.
- AC1=1 defines this configuration.
- All OLMC **except** pins 15 & 16 can be configured to this function.

Note: The development software configures all of the architecture control bits and checks for proper pin usage automatically.



**SIMPLE MODE LOGIC DIAGRAM**

DIP, SOIC & PLCC Package Pinouts



## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

Supply voltage  $V_{CC}$  ..... -5 to +7V  
 Input voltage applied ..... -2.5 to  $V_{CC} + 1.0V$   
 Off-state output voltage applied ..... -2.5 to  $V_{CC} + 1.0V$   
 Storage Temperature ..... -65 to 150°C  
 Ambient Temperature with  
 Power Applied ..... -55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

## RECOMMENDED OPERATING COND.

### Commercial Devices:

Ambient Temperature ( $T_A$ ) ..... 0 to 75°C  
 Supply voltage ( $V_{CC}$ )  
 with Respect to Ground ..... +4.75 to +5.25V

## DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP. <sup>2</sup>	MAX.	UNITS
<b>V<sub>IL</sub></b>	Input Low Voltage		$V_{SS} - 0.5$	—	0.8	V
<b>V<sub>IH</sub></b>	Input High Voltage		2.0	—	$V_{CC} + 1$	V
<b>I<sub>IL</sub></b>	Input or I/O Low Leakage Current	$0V \leq V_{IN} \leq V_{IL} (MAX.)$	—	—	-10	μA
<b>I<sub>IH</sub></b>	Input or I/O High Leakage Current	$3.5V \leq V_{IN} \leq V_{CC}$	—	—	10	μA
<b>V<sub>OL</sub></b>	Output Low Voltage	$I_{OL} = MAX. \quad V_{IN} = V_{IL} \text{ or } V_{IH}$	—	—	0.5	V
<b>V<sub>OH</sub></b>	Output High Voltage	$I_{OH} = MAX. \quad V_{IN} = V_{IL} \text{ or } V_{IH}$	2.4	—	—	V
		$I_{OH} = -100 \mu A \quad V_{IN} = V_{IL} \text{ or } V_{IH}$	$V_{CC} - 1$	—	—	V
<b>I<sub>OL</sub></b>	Low Level Output Current		—	—	16	mA
<b>I<sub>OH</sub></b>	High Level Output Current		—	—	-3.2	mA
<b>I<sub>OS</sub><sup>1</sup></b>	Output Short Circuit Current	$V_{CC} = 5V \quad V_{OUT} = 0.5V \quad T_A = 25^\circ C$	-30	—	-150	mA

## COMMERCIAL

<b>I<sub>SB</sub></b>	Stand-by Power Supply Current	$V_{IL} = GND \quad V_{IH} = V_{CC} \quad \text{Outputs Open}$	Z-12/-15 ZD-12/-15	—	50	100	μA
<b>I<sub>CC</sub></b>	Operating Power Supply Current	$V_{IL} = 0.5V \quad V_{IH} = 3.0V$ $f_{toggle} = 15 \text{ MHz} \quad \text{Outputs Open}$	Z-12/-15 ZD-12/-15	—	—	55	mA

1) One output at a time for a maximum duration of one second.  $V_{out} = 0.5V$  was selected to avoid test problems by tester ground degradation. Characterized but not 100% tested.

2) Typical values are at  $V_{CC} = 5V$  and  $T_A = 25^\circ C$

## CAPACITANCE ( $T_A = 25^\circ C, f = 1.0 \text{ MHz}$ )

SYMBOL	PARAMETER	MAXIMUM*	UNITS	TEST CONDITIONS
<b>C<sub>I</sub></b>	Input Capacitance	10	pF	$V_{CC} = 5.0V, V_I = 2.0V$
<b>C<sub>I/O</sub></b>	I/O Capacitance	10	pF	$V_{CC} = 5.0V, V_{IO} = 2.0V$

\*Characterized but not 100% tested.

## AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

			COM		COM		
PARAMETER	TEST COND <sup>1</sup> .	DESCRIPTION	-12		-15		UNITS
			MIN.	MAX.	MIN.	MAX.	
t <sub>pd</sub>	A	Input or I/O to Combinational Output	3	12	3	15	ns
t <sub>co</sub>	A	Clock to Output Delay	2	8	2	10	ns
t <sub>cf</sub> <sup>2</sup>	—	Clock to Feedback Delay	—	6	—	7	ns
t <sub>su</sub>	—	Setup Time, Input or Feedback before Clock↑	10	—	15	—	ns
t <sub>h</sub>	—	Hold Time, Input or Feedback after Clock↑	0	—	0	—	ns
f <sub>max</sub> <sup>3</sup>	A	Maximum Clock Frequency with External Feedback, 1/(t <sub>su</sub> + t <sub>co</sub> )	55	—	40	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(t <sub>su</sub> + t <sub>cf</sub> )	62.5	—	45.5	—	MHz
	A	Maximum Clock Frequency with No Feedback	83.3	—	62.5	—	MHz
t <sub>wh</sub>	—	Clock Pulse Duration, High	6	—	8	—	ns
t <sub>wl</sub>	—	Clock Pulse Duration, Low	6	—	8	—	ns
t <sub>en</sub>	B	Input or I/O to Output Enabled	—	12	—	15	ns
	B	$\overline{\text{OE}}$ to Output Enabled	—	12	—	15	ns
t <sub>dis</sub>	C	Input or I/O to Output Disabled	—	15	—	15	ns
	C	$\overline{\text{OE}}$ to Output Disabled	—	12	—	15	ns
t <sub>as</sub>	—	Last Active Input to Standby	60	140	50	150	ns
t <sub>sa</sub> <sup>4</sup>	—	Standby to Active Output	6	13	5	15	ns

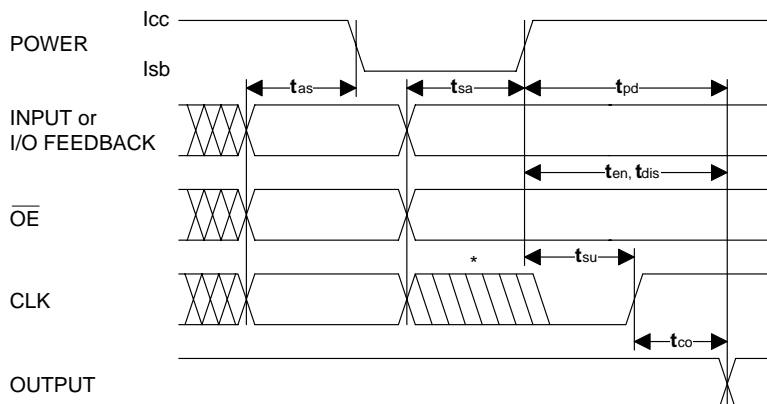
1) Refer to **Switching Test Conditions** section.

2) Calculated from f<sub>max</sub> with internal feedback. Refer to **f<sub>max</sub> Specification** section.

3) Refer to **f<sub>max</sub> Specification** section.

4) Add t<sub>sa</sub> to t<sub>pd</sub>, t<sub>su</sub>, t<sub>en</sub> and t<sub>dis</sub> when the device is coming out of standby state.

## STANDBY POWER TIMING WAVEFORMS



\* Note: Rising clock edges are allowed during t<sub>sa</sub> but outputs are not guaranteed.

## AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

			COM		COM		
PARAMETER	TEST COND <sup>1</sup> .	DESCRIPTION	-12		-15		UNITS
			MIN.	MAX.	MIN.	MAX.	
<b>t<sub>pd</sub></b>	A	Input or I/O to Combinational Output	3	12	3	15	ns
<b>t<sub>co</sub></b>	A	Clock to Output Delay	2	8	2	10	ns
<b>t<sub>cf</sub><sup>2</sup></b>	—	Clock to Feedback Delay	—	6	—	7	ns
<b>t<sub>su</sub></b>	—	Setup Time, Input or Feedback before Clock↑	10	—	15	—	ns
<b>t<sub>h</sub></b>	—	Hold Time, Input or Feedback after Clock↑	0	—	0	—	ns
<b>f<sub>max</sub><sup>3</sup></b>	A	Maximum Clock Frequency with External Feedback, 1/(t <sub>su</sub> + t <sub>co</sub> )	55	—	40	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(t <sub>su</sub> + t <sub>cf</sub> )	62.5	—	45.5	—	MHz
	A	Maximum Clock Frequency with No Feedback	83.3	—	62.5	—	MHz
<b>t<sub>wh</sub></b>	—	Clock Pulse Duration, High	6	—	8	—	ns
<b>t<sub>wl</sub></b>	—	Clock Pulse Duration, Low	6	—	8	—	ns
<b>t<sub>en</sub></b>	B	Input or I/O to Output Enabled	—	12	—	15	ns
	B	$\overline{\text{OE}}$ to Output Enabled	—	12	—	15	ns
<b>t<sub>dis</sub></b>	C	Input or I/O to Output Disabled	—	15	—	15	ns
	C	$\overline{\text{OE}}$ to Output Disabled	—	12	—	15	ns

1) Refer to **Switching Test Conditions** section.

2) Calculated from f<sub>max</sub> with internal feedback. Refer to **f<sub>max</sub> Specification** section.

3) Refer to **f<sub>max</sub> Specification** section.

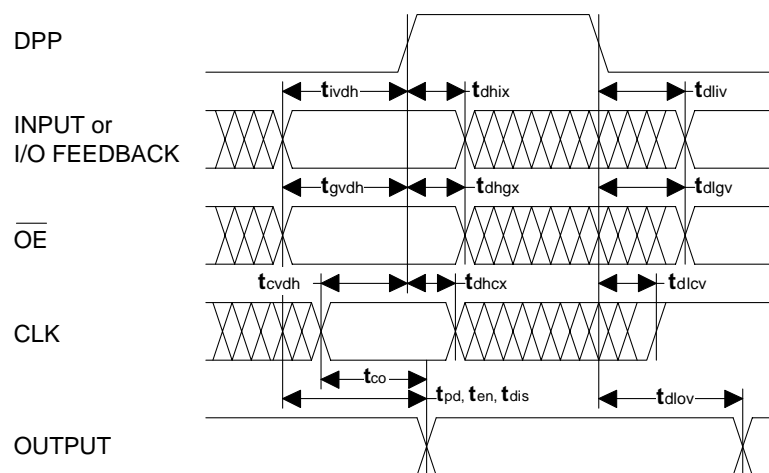
## DEDICATED POWER-DOWN PIN SPECIFICATIONS

Over Recommended Operating Conditions

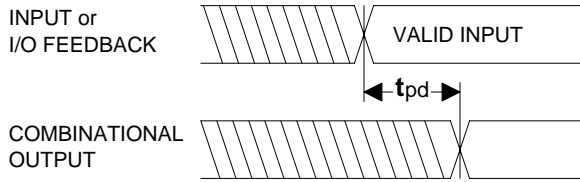
			COM		COM		UNITS
PARAMETER	TEST COND <sup>1</sup> .	DESCRIPTION	-12		-15		
			MIN.	MAX.	MIN.	MAX.	
<b>t</b> whd	—	DPP Pulse Duration High	12	—	15	—	ns
<b>t</b> wld	—	DPP Pulse Duration Low	25	—	30	—	ns
ACTIVE TO STANDBY							
<b>t</b> ivdh	—	Valid Input before DPP High	5	—	8	—	ns
<b>t</b> gvdh	—	Valid OE before DPP High	0	—	0	—	ns
<b>t</b> cvdh	—	Valid Clock Before DPP High	0	—	0	—	ns
<b>t</b> dhix	—	Input Don't Care after DPP High	—	2	—	5	ns
<b>t</b> dhgx	—	$\overline{\text{OE}}$ Don't Care after DPP High	—	6	—	9	ns
<b>t</b> dhcx	—	Clock Don't Care after DPP High	—	8	—	11	ns
STANDBY TO ACTIVE							
<b>t</b> dliv	—	DPP Low to Valid Input	12	—	15	—	ns
<b>t</b> dlgv	—	DPP Low to Valid $\overline{\text{OE}}$	16	—	20	—	ns
<b>t</b> dlcv	—	DPP Low to Valid Clock	18	—	20	—	ns
<b>t</b> dlov	A	DPP Low to Valid Output	5	24	5	30	ns

1) Refer to **Switching Test Conditions** section.

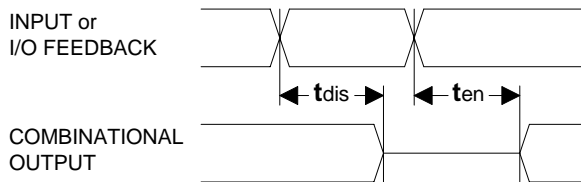
## DEDICATED POWER-DOWN PIN (DPP) TIMING WAVEFORMS



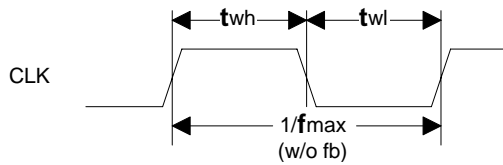
## SWITCHING WAVEFORMS



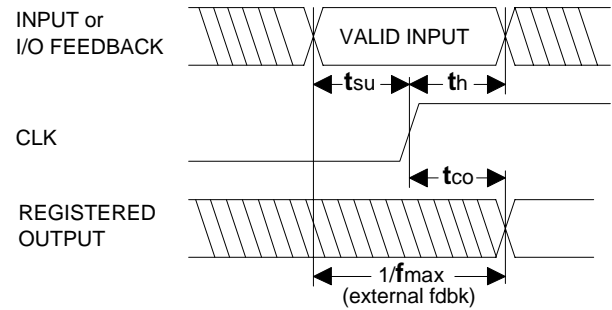
**Combinatorial Output**



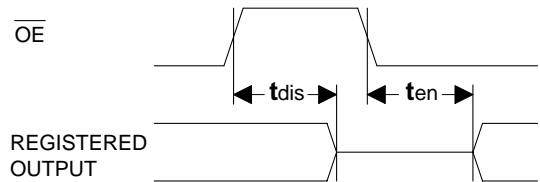
**Input or I/O to Output Enable/Disable**



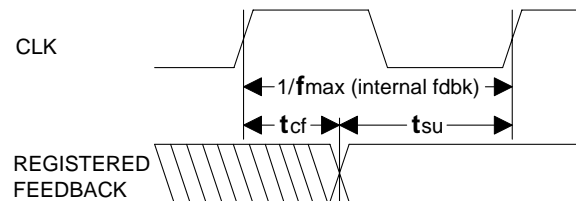
**Clock Width**



**Registered Output**

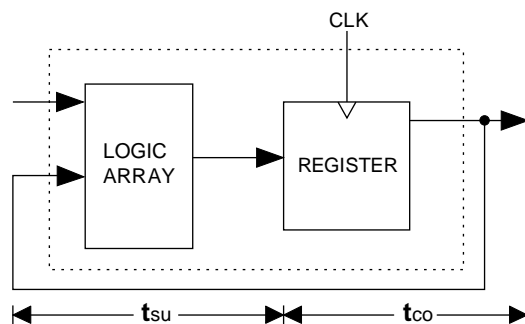


**OE to Output Enable/Disable**



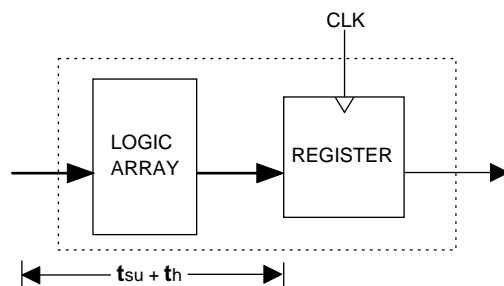
**$f_{max}$  with Feedback**

## f<sub>max</sub> SPECIFICATIONS



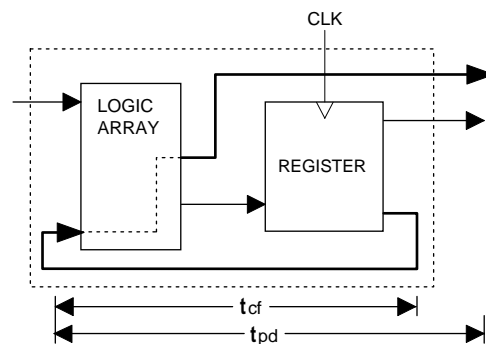
### f<sub>max</sub> with External Feedback 1/(tsu+tco)

**Note:** f<sub>max</sub> with external feedback is calculated from measured tsu and tco.



### f<sub>max</sub> with No Feedback

**Note:** f<sub>max</sub> with no feedback may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.



### f<sub>max</sub> with Internal Feedback 1/(tsu+tcf)

**Note:** tcf is a calculated value, derived by subtracting tsu from the period of f<sub>max</sub> w/internal feedback (tcf = 1/f<sub>max</sub> - tsu). The value of tcf is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to tcf + tpd.

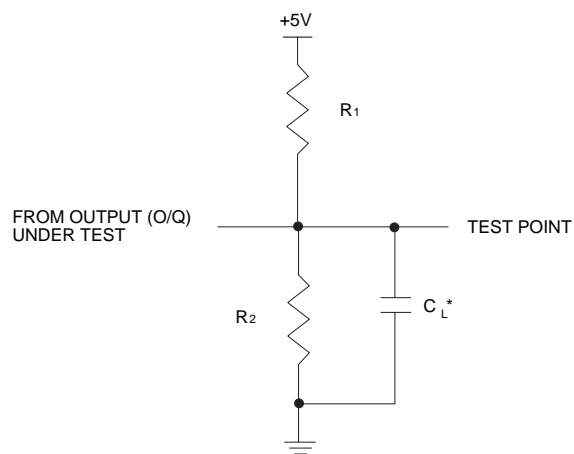
## SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	3ns 10% – 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active level.

### Output Load Conditions (see figure)

Test Condition	R1	R2	CL
A	300Ω	390Ω	50pF
B	∞	390Ω	50pF
C	∞	390Ω	5pF



\*C<sub>L</sub> INCLUDES TEST FIXTURE AND PROBE CAPACITANCE

## ELECTRONIC SIGNATURE

An electronic signature word is provided in every GAL16V8Z/ZD device. It contains 64 bits of reprogrammable memory that can contain user defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

NOTE: The electronic signature is included in checksum calculations. Changing the electronic signature will alter checksum.

## SECURITY CELL

A security cell is provided in the GAL16V8Z/ZD devices to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The electronic signature data is always available to the user, regardless of the state of this security cell.

## DEVICE PROGRAMMING

GAL devices are programmed using a Lattice Semiconductor-approved Logic Programmer, available from a number of manufacturers (see the Development Tools Section of the Data Book). Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.

## INPUT TRANSITION DETECTION (ITD)

The GAL16V8Z relies on its internal input detection circuitry to put the device in to power down mode. If there is no input transition for the specified period of time, the device will go into the power down state. Any valid input transition will put the device back into the active state. The first rising clock transition from power-down state only acts as a wake up signal to the device and will not clock the data input through to the output (refer to standby power timing waveform for more detail). Any input pulse widths greater than 5ns at input voltage level of 1.5V will be detected as input transition. The device will not detect any input pulse widths less than 1ns measured at input voltage level of 1.5V as an input transition.

## DEDICATED POWER-DOWN PIN (DPP)

The GAL16V8ZD uses pin 4 as the dedicated power-down signal to put the device in to the power-down state. DPP is an active high signal where a logic high driven on this signal puts the device into power-down state. Input pin 4 cannot be used as a functional input on this device.

## OUTPUT REGISTER PRELOAD

When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because, in system operation, certain events occur that may throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

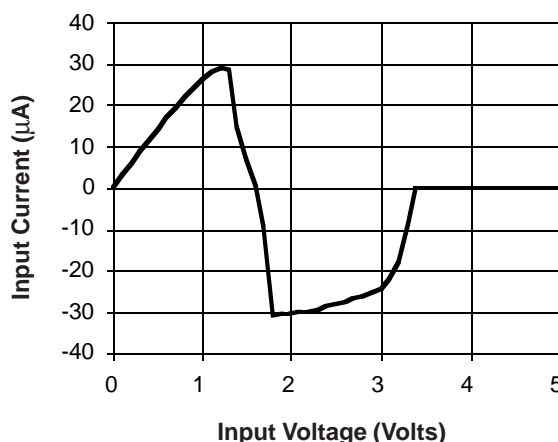
The GAL16V8Z/ZD devices includes circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing test vectors perform output register preload automatically.

## INPUT BUFFERS

GAL16V8Z/ZD devices are designed with TTL level compatible input buffers. These buffers, with their characteristically high impedance, load driving logic much less than traditional bipolar devices. This allows for a greater fan out from the driving logic.

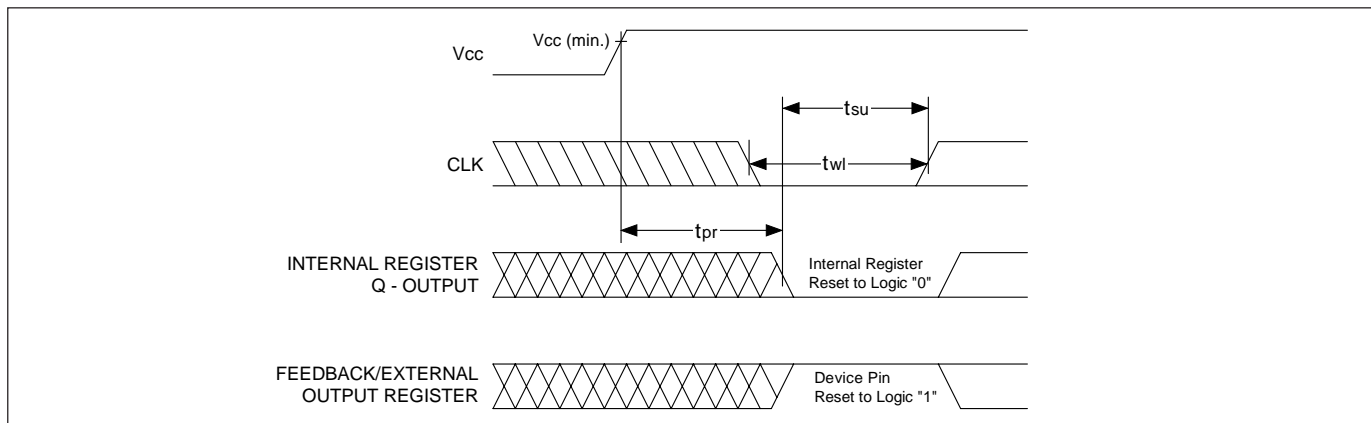
GAL16V8Z/ZD input buffers have latches within the buffers. As a result, when the device goes into standby mode the inputs will be latched to its values prior to standby. In order to overcome the input latches, they will have to be driven by an external source. Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins for both devices be connected to another active input,  $V_{CC}$ , or GND. Doing this will tend to improve noise immunity and reduce  $I_{CC}$  for the device.

Typical Input Characteristic





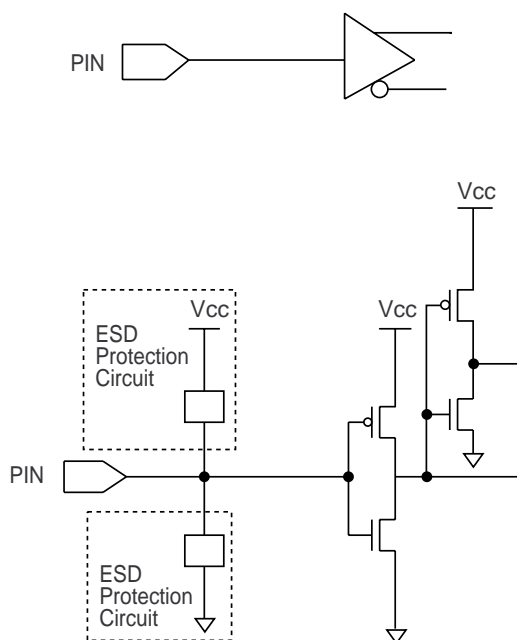
## POWER-UP RESET



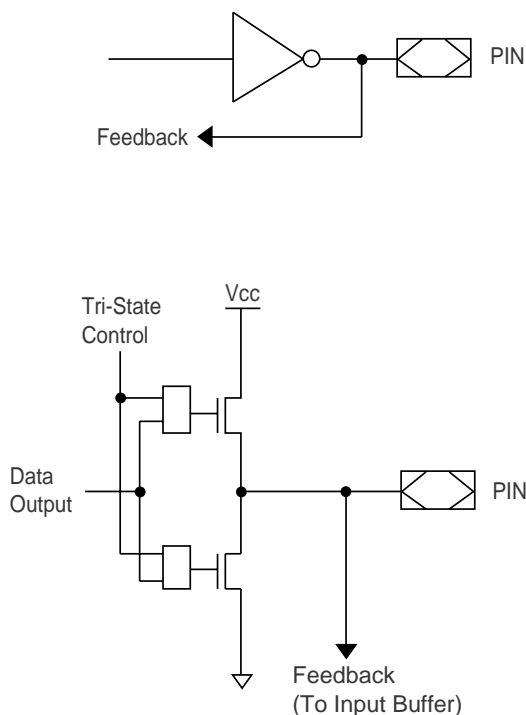
Circuitry within the GAL16V8Z/ZD provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time ( $t_{pr}$ , 1 $\mu$ s MAX). As a result, the state on the registered output pins (if they are enabled) will always be high on power-up, regardless of the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. The timing diagram for power-up is shown below. Because of the

asynchronous nature of system power-up, some conditions must be met to provide a valid power-up reset of the GAL16V8Z/ZD. First, the  $V_{CC}$  rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of  $t_{pr}$  time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.

## INPUT/OUTPUT EQUIVALENT SCHEMATICS



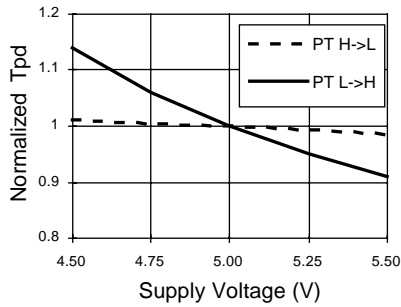
Typical Input



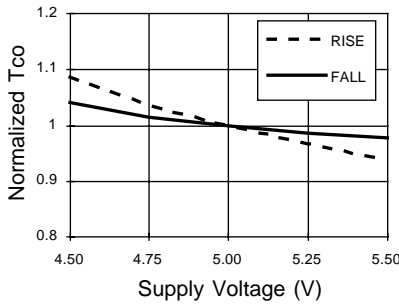
Typical Output

**TYPICAL AC AND DC CHARACTERISTICS**

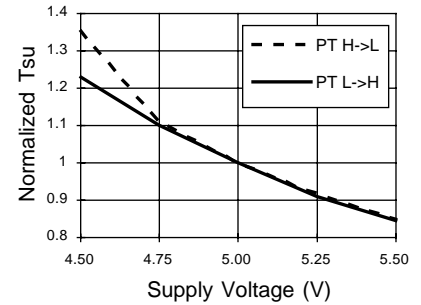
**Normalized Tpd vs Vcc**



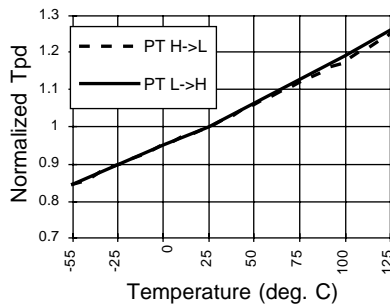
**Normalized Tco vs Vcc**



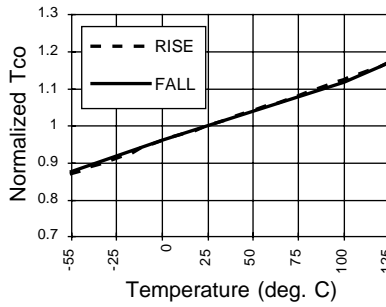
**Normalized Tsu vs Vcc**



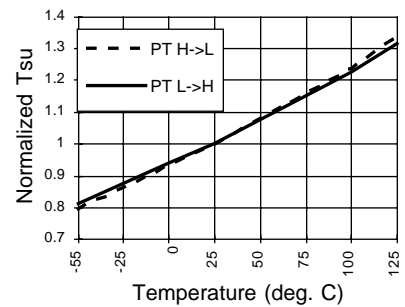
**Normalized Tpd vs Temp**



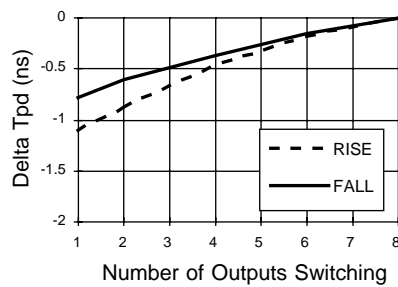
**Normalized Tco vs Temp**



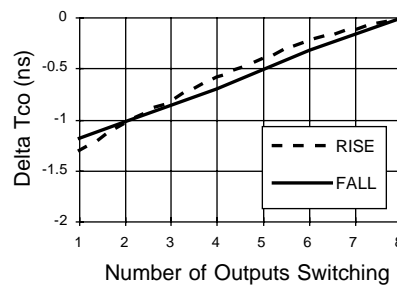
**Normalized Tsu vs Temp**



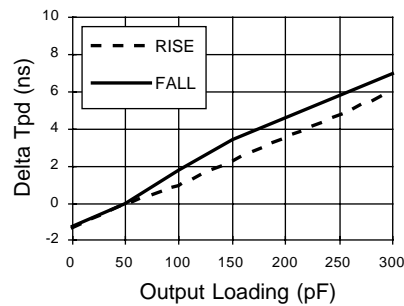
**Delta Tpd vs # of Outputs Switching**



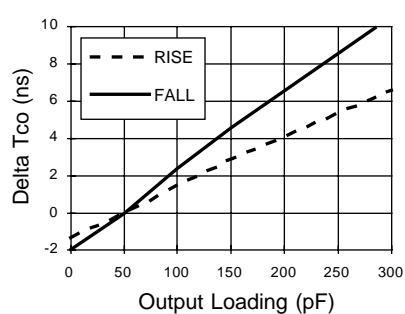
**Delta Tco vs # of Outputs Switching**



**Delta Tpd vs Output Loading**

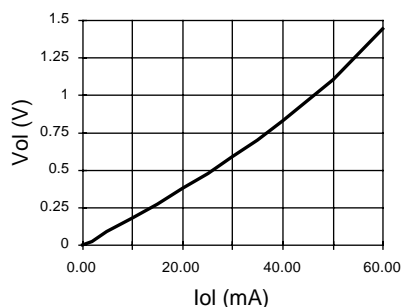


**Delta Tco vs Output Loading**

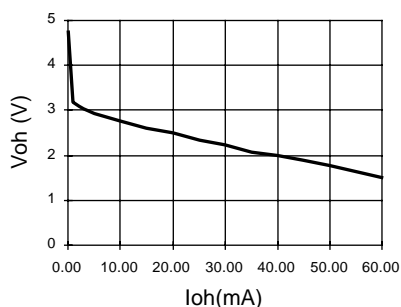


**TYPICAL AC AND DC CHARACTERISTICS**

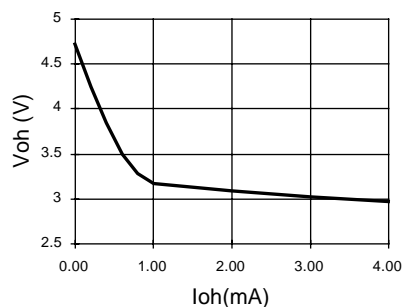
**Vol vs Iol**



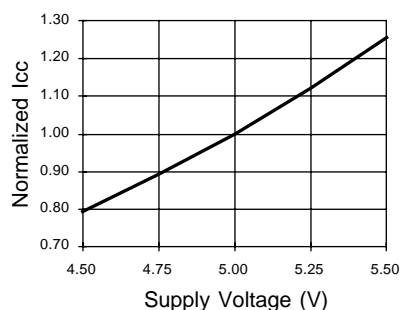
**Voh vs Ioh**



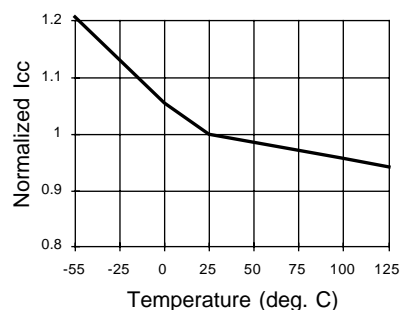
**Voh vs Ioh**



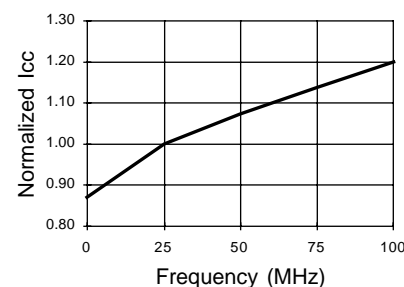
**Normalized Icc vs Vcc**



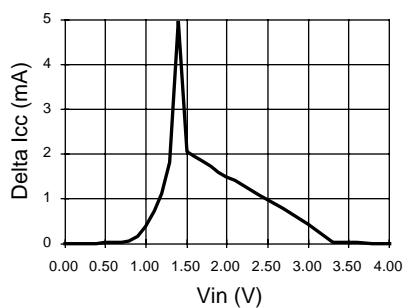
**Normalized Icc vs Temp**



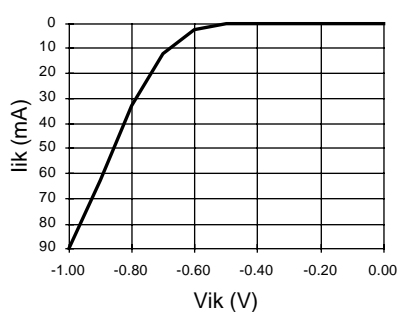
**Normalized Icc vs Freq. (DPP & ITD > 10MHz)**



**Delta Icc vs Vin (1 input)**



**Input Clamp (Vik)**



**Normalized Icc vs Freq. (ITD)**

