



# High-Speed (10Mbps), Fail-Safe, RS-485/RS-422 Transceivers with Slew-Rate-Limiting and $\pm 15\text{kV}$ ESD Protection

## ADM3082/ADM3085/ADM3088

### FEATURES

- Enhanced Slew Rate Limiting for Error-Free Data Transmission
- Fail-Safe Receiver Operation while Maintaining EIA/TIA-485 compatibility
- Low-Current (1nA) Shutdown Mode
- High Input Impedance — Up to 256 Transceivers on Bus
- $\pm 15\text{kV}$  ESD Protection (Human Body Model) on RS-485 I/O pins
- Pin-Compatible with Industry Standard 75176

### APPLICATIONS

- Enhanced Replacement for Industry-Standard Parts
- EMI-Sensitive Systems
- Level Translation
- LANs for Industrial Control Applications

### GENERAL DESCRIPTION

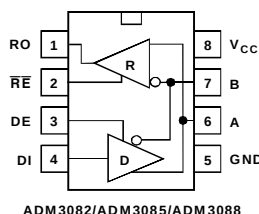
The ADM3082/ADM3085/ADM3088 are high-speed RS-485/RS-422 transceivers consisting of one driver and one receiver per package. The devices feature fail-safe operation, ensuring a logic-high receiver output when the receiver inputs are open-circuit or short-circuit. This guarantees that the receiver output will be high if all the transmitters on a terminated bus are disabled (high-impedance).

The ADM3082 has a slew-rate limited driver to minimize electromagnetic interference (EMI) and reduce reflections caused by incorrectly terminated cables. This allows error-free transmission at data rates up to 115kbps.

The ADM3085 offers a higher slew rate allowing data rates up to 500kbps, while the ADM3088 has a driver whose slew rate is not limited, allowing data rates up to 10Mbps.

All devices in the family feature  $\pm 15\text{kV}$  electrostatic discharge (ESD) protection and high receiver input impedance (1/8 unit load), allowing up to 256 transceivers on the bus. The devices have low current drain of  $375\mu\text{A}$  unloaded, or fully loaded with the drivers disabled, and feature an ultra-low power (1nA) shutdown mode.

### FUNCTIONAL BLOCK DIAGRAM



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## ADM3082/ADM3085/ADM3088

## ADM3082/ADM3085/ADM3088 SPECIFICATIONS

## DC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +5V ±5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and T<sub>A</sub> = +25°C.) (Note 1)

## DRIVER

| Parameter                                                                        | Min        | Typ | Max        | Units    | Test Conditions/Comments                                                                                                                 |
|----------------------------------------------------------------------------------|------------|-----|------------|----------|------------------------------------------------------------------------------------------------------------------------------------------|
| Differential Driver Output, V <sub>OD1</sub>                                     |            |     | 5          | V        | Figure 1 (No Load)                                                                                                                       |
| Differential Driver Output, V <sub>OD2</sub>                                     | 2.0<br>1.5 |     |            | V<br>V   | Figure 1, R = 50Ω (RS-422)<br>Figure 1, R = 27Ω (RS-485)                                                                                 |
| Change-in-Magnitude of Differential Common-Mode Output Voltage, ΔV <sub>OD</sub> |            |     | 0.2        | V        | Figure 1, R = 50Ω or R = 27Ω (Note 2)                                                                                                    |
| Driver Common-Mode Output Voltage, V <sub>OC</sub>                               |            |     | 3          | V        | Figure 1, R = 50Ω or R = 27Ω                                                                                                             |
| Change-in-Magnitude of Common-Mode Voltage, ΔV <sub>OC</sub>                     |            |     | 0.2        | V        | Figure 1, R = 50Ω or R = 27Ω (Note 2)                                                                                                    |
| Input High Voltage, V <sub>IH1</sub><br>(DE, DI, $\overline{RE}$ )               | 2.0        |     |            | V        |                                                                                                                                          |
| Input Low Voltage, V <sub>IL1</sub><br>(DE, DI, $\overline{RE}$ )                |            |     | 0.8        | V        |                                                                                                                                          |
| DI Input Hysteresis, V <sub>HYS</sub>                                            |            | 100 |            | mV       |                                                                                                                                          |
| Input Current, I <sub>IN1</sub> (DE, DI, $\overline{RE}$ )                       |            |     | ±2         | μA       |                                                                                                                                          |
| Input Current (A and B), I <sub>IN4</sub>                                        |            |     | 125<br>-75 | μA<br>μA | DE = GND, V <sub>CC</sub> = GND or 5.25V,<br>V <sub>IN</sub> = 12V<br>DE = GND, V <sub>CC</sub> = GND or 5.25V,<br>V <sub>IN</sub> = -7V |
| Output Leakage (Y and Z),<br>Full Duplex, I <sub>O</sub>                         | -100       |     | 125        | μA<br>μA | DE = GND, V <sub>CC</sub> = GND or 5.25V,<br>V <sub>IN</sub> = 12V<br>DE = GND, V <sub>CC</sub> = GND or 5.25V,<br>V <sub>IN</sub> = -7V |
| Driver Short-Circuit, V <sub>OD1</sub>                                           | -250       |     |            | mA       | -7V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub> (Note 3)                                                                                        |
| Output Current                                                                   | ±25        |     | 250        | mA<br>mA | 0V ≤ V <sub>OUT</sub> ≤ 12V (Note 3)<br>0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub> (Note 3)                                                 |

## ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

## DC ELECTRICAL CHARACTERISTICS

( $V_{CC} = +5V \pm 5\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^\circ C$ .) (Note 1)

## RECEIVER

| Parameter                                         | Min            | Typ  | Max      | Units      | Test Conditions/Comments        |
|---------------------------------------------------|----------------|------|----------|------------|---------------------------------|
| Receiver Differential Threshold Voltage, $V_{TH}$ | -200           | -125 | -50      | mV         | $-7V \leq V_{CM} \leq 12V$      |
| Receiver Input Hysteresis, $\Delta V_{TH}$        |                | 25   |          | mV         |                                 |
| Receiver Output High Voltage, $V_{OH}$            | $V_{CC} - 1.5$ |      |          | V          | $I_O = -4mA$ , $V_{ID} = -50mV$ |
| Receiver Output Low Voltage, $V_{OL}$             |                |      | 0.4      | V          | $I_O = 4mA$ , $V_{ID} = -200mV$ |
| Three-State Output Current at Receiver, $I_{OZR}$ |                |      | $\pm 1$  | $\mu A$    | $0.4V \leq V_O \leq 2.4V$       |
| Receiver Input Resistance, $R_{IN}$               | 96             |      |          | k $\Omega$ | $-7V \leq V_{CM} \leq 12V$      |
| Receiver Output Short-Circuit Current, $I_{OSR}$  | $\pm 7$        |      | $\pm 95$ | mA         | $0V \leq V_{RO} \leq V_{CC}$    |

## SUPPLY CURRENT

| Parameter                                   | Min | Typ      | Max | Units   | Test Conditions/Comments                                        |
|---------------------------------------------|-----|----------|-----|---------|-----------------------------------------------------------------|
| Supply Current, $I_{CC}$                    |     | 430      | 900 | $\mu A$ | No load, $\overline{RE} = DI = GND$ or $V_{CC}$ , $DE = V_{CC}$ |
|                                             |     | 375      | 600 | $\mu A$ | No load, $\overline{RE} = DI = GND$ or $V_{CC}$ , $DE = GND$    |
| Supply Current in Shutdown Mode, $I_{SHDN}$ |     | 0.001    | 10  | $\mu A$ | $DE = GND$ , $V_{\overline{RE}} = V_{CC}$                       |
| ESD Protection for Y, Z, A, B               |     | $\pm 15$ |     | kV      | Human Body Model                                                |

## NOTES

<sup>1</sup>All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

<sup>2</sup> $\Delta V_{DO}$  and  $\Delta V_{CC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

<sup>3</sup>Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

## ADM3082/ADM3085/ADM3088

## ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

## SWITCHING CHARACTERISTICS—ADM3082

(V<sub>CC</sub> = +5V ±5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and T<sub>A</sub> = +25°C.) (Note 1)

| Parameter                                                                               | Min | Typ  | Max  | Units | Test Conditions/Comments                     |
|-----------------------------------------------------------------------------------------|-----|------|------|-------|----------------------------------------------|
| Driver Input-to-Output, t <sub>DPLH</sub>                                               | 500 | 2030 | 2600 | ns    | Figures 2 and 3, R <sub>DIFF</sub> = 54Ω,    |
| Driver Input-to-Output, t <sub>DPHL</sub>                                               | 500 | 2030 | 2600 | ns    | C <sub>L1</sub> = C <sub>L2</sub> = 100pF    |
| Driver Output Skew,  t <sub>DPLH</sub> - t <sub>DPHL</sub>  , t <sub>DSKEW</sub>        |     | -3   | ±200 | ns    | Figures 2 and 3, R <sub>DIFF</sub> = 54Ω,    |
|                                                                                         |     |      |      |       | C <sub>L1</sub> = C <sub>L2</sub> = 100pF    |
| Driver Rise or Fall Time, t <sub>DR</sub> , t <sub>DF</sub>                             | 667 | 1320 | 2500 | ns    | Figures 2 and 3, R <sub>DIFF</sub> = 54Ω,    |
|                                                                                         |     |      |      |       | C <sub>L1</sub> = C <sub>L2</sub> = 100pF    |
| Maximum Data Rate, f <sub>MAX</sub>                                                     | 115 |      |      | kbps  |                                              |
| Driver Enable to Output High, t <sub>DZH</sub>                                          |     |      | 3500 | ns    | Figures 5 and 6, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Driver Enable to Output Low, t <sub>DZL</sub>                                           |     |      | 3500 | ns    | Figures 5 and 6, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S1 closed                                    |
| Driver Disable Time from Low, t <sub>DLZ</sub>                                          |     |      | 100  | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,      |
|                                                                                         |     |      |      |       | S1 closed                                    |
| Driver Disable Time from High, t <sub>DHZ</sub>                                         |     |      | 100  | ns    | Figures 4 and 5, C <sub>L</sub> = 15pF,      |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Receiver Input to Output, t <sub>RPLH</sub> , t <sub>RPHL</sub>                         |     | 127  | 200  | ns    | Figure 7;  V <sub>ID</sub>   ≥ 2.0V;         |
|                                                                                         |     |      |      |       | rise and fall time of V <sub>ID</sub> ≤ 15ns |
| Differential Receiver Skew, t <sub>RSKD</sub><br> t <sub>RPLH</sub> - t <sub>RPHL</sub> |     | 3    | ±30  | ns    | Figure 7;  V <sub>ID</sub>   ≥ 2.0V;         |
|                                                                                         |     |      |      |       | rise and fall time of V <sub>ID</sub> ≤ 15ns |
| Receiver Enable to Output Low, t <sub>RZL</sub>                                         |     | 20   | 50   | ns    | Figures 7 and 8; C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S1 closed                                    |
| Receiver Enable to Output High, t <sub>RZH</sub>                                        |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Receiver Disable Time from Low, t <sub>RLZ</sub>                                        |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S1 closed                                    |
| Receiver Disable Time from High, t <sub>RHZ</sub>                                       |     | 20   | 50   | ns    | Figures 7 and 8 C <sub>L</sub> = 100pF,      |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Time to Shutdown, t <sub>SHDN</sub>                                                     | 50  | 200  | 600  | ns    | (Note 5)                                     |
| Driver Enable from Shutdown to<br>Output High, t <sub>DZH(SHDN)</sub>                   |     |      | 6000 | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,      |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Driver Enable from Shutdown to<br>Output Low, t <sub>DZL(SHDN)</sub>                    |     |      | 6000 | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,      |
|                                                                                         |     |      |      |       | S1 closed                                    |
| Receiver Enable from Shutdown<br>to Output High, t <sub>RZH(SHDN)</sub>                 |     |      | 3500 | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S2 closed                                    |
| Receiver Enable from Shutdown<br>to Output Low, t <sub>RZL(SHDN)</sub>                  |     |      | 3500 | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,     |
|                                                                                         |     |      |      |       | S1 closed                                    |

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

## SWITCHING CHARACTERISTICS—ADM3085

( $V_{CC} = +5V \pm 5\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^\circ C$ .) (Note 1)

| Parameter                                                         | Min | Typ | Max       | Units | Test Conditions/Comments                                                     |
|-------------------------------------------------------------------|-----|-----|-----------|-------|------------------------------------------------------------------------------|
| Driver Input-to-Output, $t_{DPLH}$                                | 250 | 720 | 1000      | ns    | Figures 2 and 3 $R_{DIFF} = 54\Omega$ ,<br>$C_{L1} = C_{L2} = 100pF$         |
| Driver Input-to-Output, $t_{DPHL}$                                | 250 | 720 | 1000      | ns    |                                                                              |
| Driver Output Skew, $ t_{DPLH} - t_{DPHL} $ , $t_{DSKEW}$         |     | -3  | $\pm 100$ | ns    | Figures 2 and 3, $R_{DIFF} = 54\Omega$ ,<br>$C_{L1} = C_{L2} = 100pF$        |
| Driver Rise or Fall Time, $t_{DR}$ , $t_{DF}$                     | 200 | 530 | 750       | ns    | Figures 2 and 3, $R_{DIFF} = 54\Omega$ ,<br>$C_{L1} = C_{L2} = 100pF$        |
| Maximum Data Rate, $f_{MAX}$                                      | 500 |     |           | kbps  |                                                                              |
| Driver Enable to Output High, $t_{DZH}$                           |     |     | 2500      | ns    | Figures 5 and 6, $C_L = 100pF$ ,<br>S2 closed                                |
| Driver Enable to Output Low, $t_{DZL}$                            |     |     | 2500      | ns    | Figures 5 and 6, $C_L = 100pF$ ,<br>S1 closed                                |
| Driver Disable Time from Low, $t_{DLZ}$                           |     |     | 100       | ns    | Figures 5 and 6, $C_L = 15pF$ ,<br>S1 closed                                 |
| Driver Disable Time from High, $t_{DHZ}$                          |     |     | 100       | ns    | Figures 5 and 6, $C_L = 15pF$ ,<br>S2 closed                                 |
| Receiver Input to Output, $t_{RPLH}$ , $t_{RPHL}$                 |     | 127 | 200       | ns    | Figure 7; $ V_{ID}  \geq 2.0V$ ;<br>rise and fall time of $V_{ID} \leq 15ns$ |
| Differential Receiver Skew, $t_{RSKD}$<br>$ t_{RPLH} - t_{RPHL} $ |     | 3   | $\pm 30$  | ns    | Figure 7; $ V_{ID}  \geq 2.0V$ ;<br>rise and fall time of $V_{ID} \leq 15ns$ |
| Receiver Enable to Output Low, $t_{RZL}$                          |     | 20  | 50        | ns    | Figures 7 and 8 $C_L = 100pF$ ,<br>S1 closed                                 |
| Receiver Enable to Output High, $t_{RZH}$                         |     | 20  | 50        | ns    | Figures 7 and 8, $C_L = 100pF$ ,<br>S2 closed                                |
| Receiver Disable Time from Low, $t_{RLZ}$                         |     | 20  | 50        | ns    | Figures 7 and 8, $C_L = 100pF$ ,<br>S1 closed                                |
| Receiver Disable Time from High, $t_{RHZ}$                        |     | 20  | 50        | ns    | Figures 7 and 8, $C_L = 100pF$ ,<br>S2 closed                                |
| Time to Shutdown, $t_{SHDN}$                                      | 50  | 200 | 600       | ns    | (Note 5)                                                                     |
| Driver Enable from Shutdown<br>to Output High, $t_{DZH(SHDN)}$    |     |     | 4500      | ns    | Figures 5 and 6, $C_L = 15pF$ ,<br>S2 closed                                 |
| Driver Enable from Shutdown<br>to Output Low, $t_{OZL(SHDN)}$     |     |     | 4500      | ns    | Figures 5 and 6, $C_L = 15pF$ ,<br>S1 closed                                 |
| Receiver Enable from Shutdown<br>to Output High, $t_{RZH(SHDN)}$  |     |     | 3500      | ns    | Figures 7 and 8, $C_L = 100pF$ ,<br>S2 closed                                |
| Receiver Enable from Shutdown<br>to Output Low, $t_{RZL(SHDN)}$   |     |     | 3500      | ns    | Figures 7 and 8, $C_L = 100pF$ ,<br>S1 closed                                |

## ADM3082/ADM3085/ADM3088

## ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

## SWITCHING CHARACTERISTICS—ADM3088

(V<sub>CC</sub> = +5V ±5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and T<sub>A</sub> = +25°C.) (Note 1)

| Parameter                                                                               | Min | Typ  | Max  | Units | Test Conditions/Comments                                                               |
|-----------------------------------------------------------------------------------------|-----|------|------|-------|----------------------------------------------------------------------------------------|
| Driver Input-to-Output, t <sub>DPLH</sub>                                               |     | 34   | 60   | ns    | Figures 2 and 5, R <sub>DIFF</sub> = 54Ω,<br>C <sub>L1</sub> = C <sub>L2</sub> = 100pF |
| Driver Input-to-Output, t <sub>DPHL</sub>                                               |     | 34   | 60   | ns    |                                                                                        |
| Driver Output Skew,  t <sub>DPLH</sub> - t <sub>DPHL</sub>  , t <sub>DSKEW</sub>        |     | -2.5 | ±10  | ns    | Figures 2 and 5, R <sub>DIFF</sub> = 54Ω,<br>C <sub>L1</sub> = C <sub>L2</sub> = 100pF |
| Driver Rise or Fall Time, t <sub>DR</sub> , t <sub>DF</sub>                             |     | 14   | 25   | ns    | Figures 7 and 9, R <sub>DIFF</sub> = 54Ω,<br>C <sub>L1</sub> = C <sub>L2</sub> = 100pF |
| Maximum Data Rate, f <sub>MAX</sub>                                                     | 10  |      |      | Mbps  |                                                                                        |
| Driver Enable to Output High, t <sub>DZH</sub>                                          |     |      | 150  | ns    | Figures 5 and 6, C <sub>L</sub> = 100pF,<br>S2 closed                                  |
| Driver Enable to Output Low, t <sub>DZL</sub>                                           |     |      | 150  | ns    | Figures 5 and 6, C <sub>L</sub> = 100pF,<br>S1 closed                                  |
| Driver Disable Time from Low, t <sub>DLZ</sub>                                          |     |      | 100  | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,<br>S1 closed                                   |
| Driver Disable Time from High, t <sub>DHZ</sub>                                         |     |      | 100  | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,<br>S2 closed                                   |
| Receiver Input-to-Output, t <sub>RPLH</sub> , t <sub>RPHL</sub>                         |     | 106  | 150  | ns    | Figure 7;  V <sub>ID</sub>   ≥ 2.0V;<br>rise and fall time of V <sub>ID</sub> ≤ 15ns   |
| Differential Receiver Skew, t <sub>RSKD</sub><br> t <sub>RPLH</sub> - t <sub>RPHL</sub> |     | 0    | ±10  | ns    | Figures 7;  V <sub>ID</sub>   ≥ 2.0V;<br>rise and fall time of V <sub>ID</sub> ≤ 15ns  |
| Receiver Enable to Output Low, t <sub>RZL</sub>                                         |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S1 closed                                  |
| Receiver Enable to Output High, t <sub>RZH</sub>                                        |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S2 closed                                  |
| Receiver Disable Time from Low, t <sub>RLZ</sub>                                        |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S1 closed                                  |
| Receiver Disable Time from High, t <sub>RHZ</sub>                                       |     | 20   | 50   | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S2 closed                                  |
| Time to Shutdown, t <sub>SHDN</sub>                                                     | 50  | 200  | 600  | ns    | (Note 5)                                                                               |
| Driver Enable from Shutdown<br>to Output High, t <sub>DZH(SHDN)</sub>                   |     |      | 250  | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,<br>S2 closed                                   |
| Driver Enable from Shutdown<br>to Output Low, t <sub>DZL(SHDN)</sub>                    |     |      | 250  | ns    | Figures 5 and 6, C <sub>L</sub> = 15pF,<br>S1 closed                                   |
| Receiver Enable from Shutdown<br>to Output High, t <sub>RZH(SHDN)</sub>                 |     |      | 3500 | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S2 closed                                  |
| Receiver Enable from Shutdown<br>to Output Low, t <sub>RZL(SHDN)</sub>                  |     |      | 3500 | ns    | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S1 closed                                  |

## NOTES

<sup>5</sup>The device is put into shutdown by bringing  $\overline{RE}$  high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

## ADM3082/ADM3085/ADM3088 TEST CIRCUITS AND TIMING

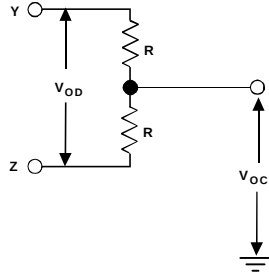


Figure 1. Driver DC Load Test Circuit

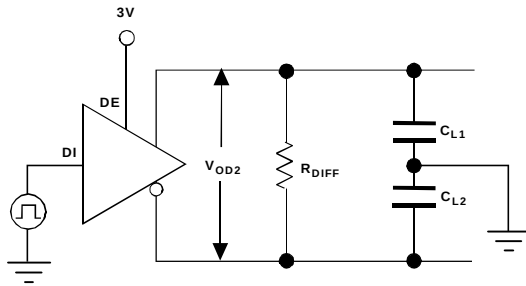


Figure 2. Test Load for Driver Timing Tests

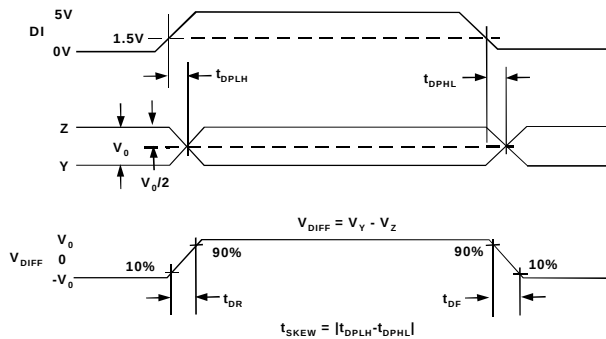


Figure 3. Driver Propagation Delays

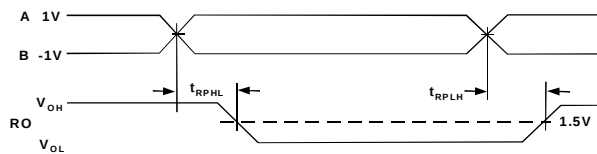


Figure 4. Receiver Propagation Delays

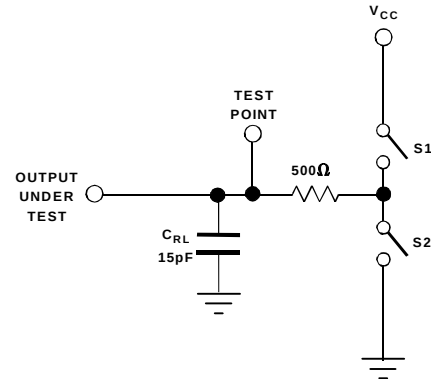


Figure 5. Test Load for Driver Enable/Disable Time Test

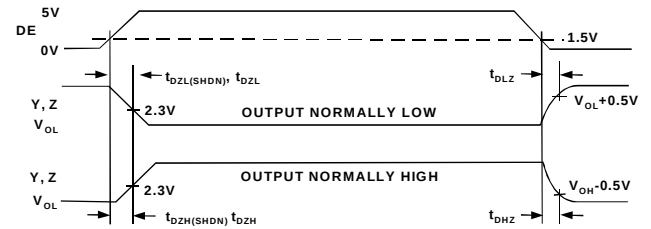


Figure 6. Driver Enable and Disable Times

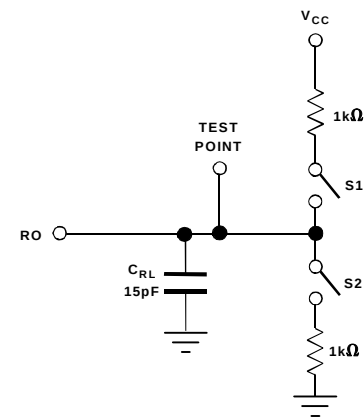


Figure 7. Test Load for Receiver Enable/Disable Time Test

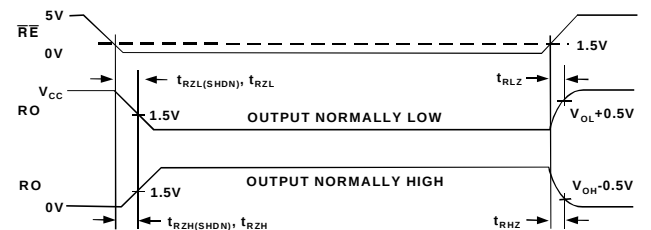


Figure 8. Receiver Enable and Disable Delay Times

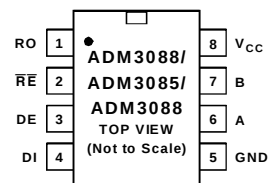
**ADM3082/ADM3085/ADM3088****ABSOLUTE MAXIMUM RATINGS**

Supply Voltage ( $V_{CC}$ ) ..... +7V  
 Logic Input Voltage ..... -0.3V to ( $V_{CC}+0.3V$ )  
 Driver Output Voltage (A, B) .....  $\pm 13V$   
 Receiver Input Voltage (A, B) .....  $\pm 13V$   
 Receiver Input Voltage, Full Duplex (A, B) .....  $\pm 13V$   
 Receiver Output Voltage (RO) ... -0.3V to ( $V_{CC}+0.3V$ )  
 Continuous Power Dissipation  
   8-Pin Plastic DIP  
     (derate 9.09mW/°C above +70°C) ..... 727mW  
   8-Pin Plastic SO  
     (derate 5.88mW/°C above +70°C) ..... 471mW  
 Maximum Junction Temperature ( $T_{Jmax}$ ) ..... 150 °C  
 Storage Temperature Range ..... -65°C to +150°C  
 Lead Temperature, Soldering  
   Vapor Phase 60 sec ..... +215°C  
   Infra-Red 15 sec ..... +200°C

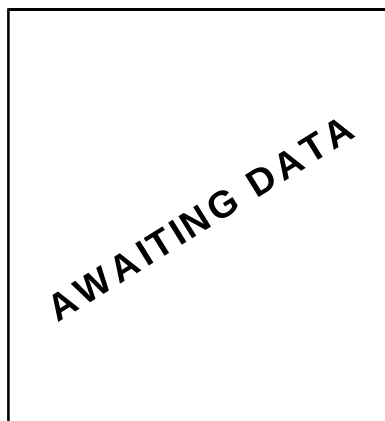
\*Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**THERMAL CHARACTERISTICS**

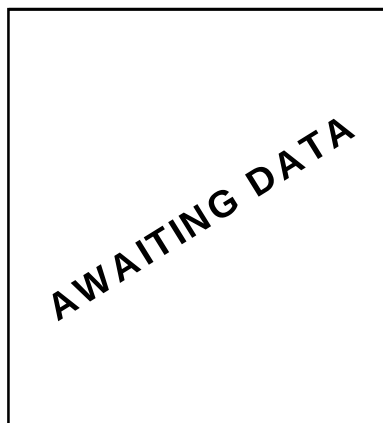
8-Pin Plastic DIP Package  
 $\theta_{JA}$  = tbd K/Watt,  $\theta_{JC}$  = tbd K/Watt  
 8-Pin Plastic SO Package  
 $\theta_{JA}$  = tbd K/Watt,  $\theta_{JC}$  = tbd K/Watt

**PIN CONFIGURATION****ORDERING INFORMATION**

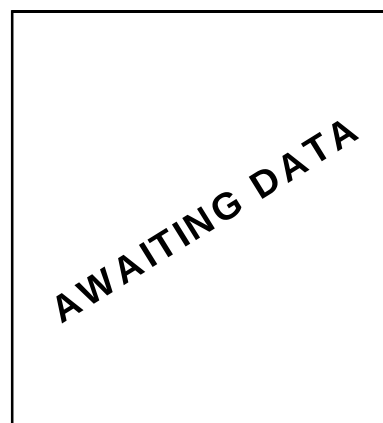
| Model     | Temperature Range | Package Option    |
|-----------|-------------------|-------------------|
| ADM3082JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3082JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3082AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3082AR | -40°C to +85°C    | 8 Pin SO          |
| ADM3085JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3085JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3085AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3085AR | -40°C to +85°C    | 8 Pin SO          |
| ADM3088JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3088JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3088AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3088AR | -40°C to +85°C    | 8 Pin SO          |

**ADM3082/ADM3085/ADM3088 TYPICAL PERFORMANCE CHARACTERISTICS**

TPC1. No-load Supply Current vs. Temperature

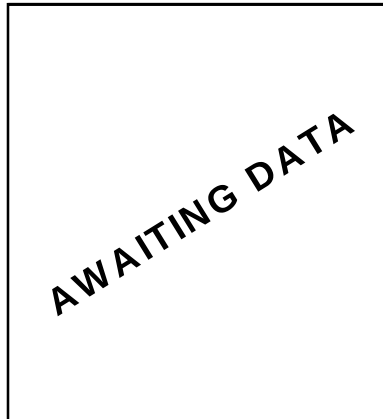


TPC2. Output Current vs. Receiver Output High Voltage

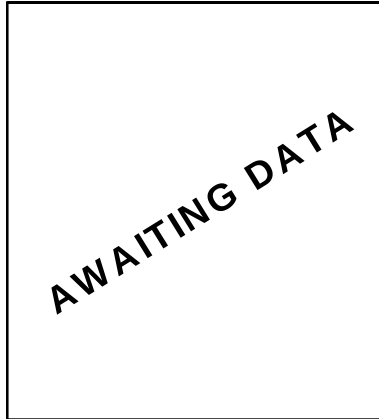


TPC3. Output Current vs. Receiver Output Low Voltage

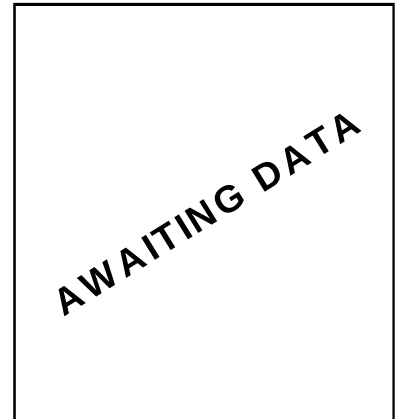
ADM3082/ADM3085/ADM3088 TYPICAL PERFORMANCE CHARACTERISTICS (continued)



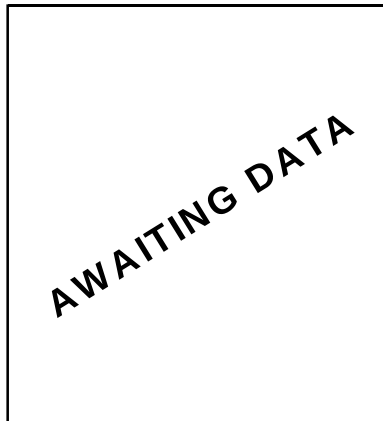
TPC4. Receiver Output High Voltage vs. Temperature



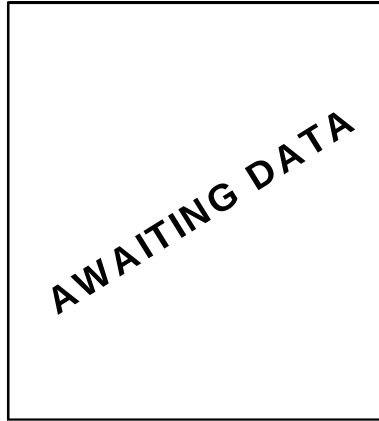
TPC5. Receiver Output Low Voltage vs. Temperature



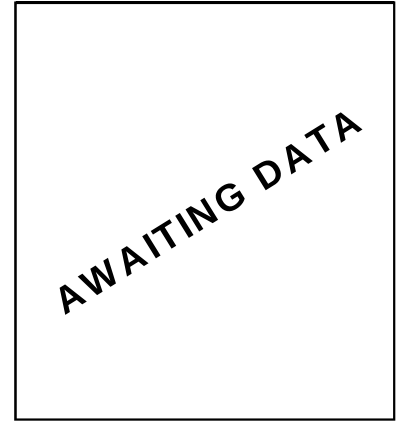
TPC6. Shutdown Current vs. Temperature



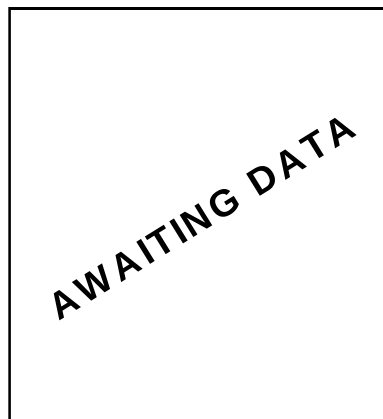
TPC7. ADM3082 Driver Propagation Delay vs. Temperature



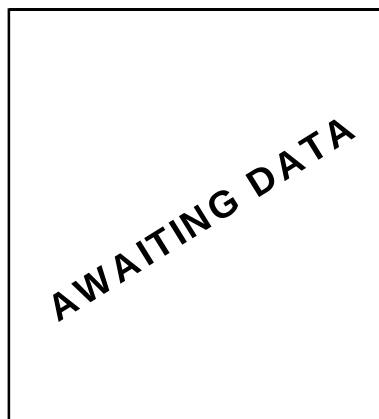
TPC8. ADM3085 Driver Propagation Delay vs. Temperature



TPC9. ADM3088 Driver Propagation Delay vs. Temperature



TPC10. ADM3082/5 Receiver Propagation Delay vs. Temperature



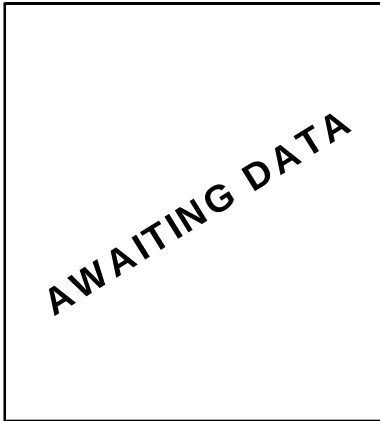
TPC11. ADM3088 Receiver Propagation Delay vs. Temperature



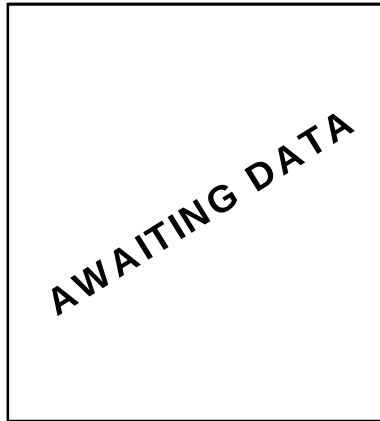
TPC12. Driver Differential Output Voltage vs. Temperature

ADM3082/ADM3085/ADM3088

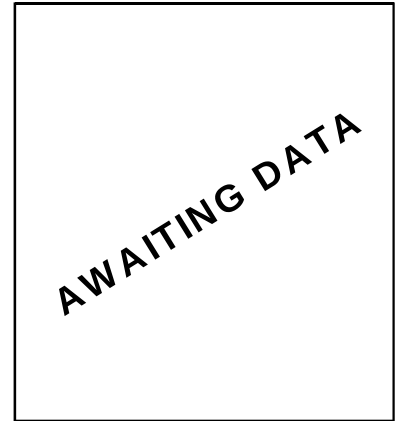
ADM3082/ADM3085/ADM3088 TYPICAL PERFORMANCE CHARACTERISTICS (continued)



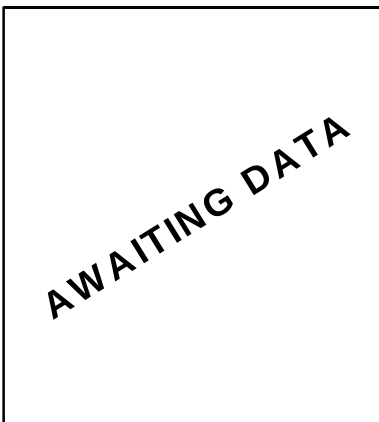
TPC13. Driver Output Current vs. Differential Output Voltage



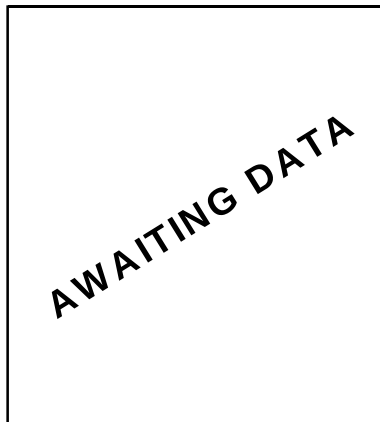
TPC14. Output Current vs. Driver Output High Voltage



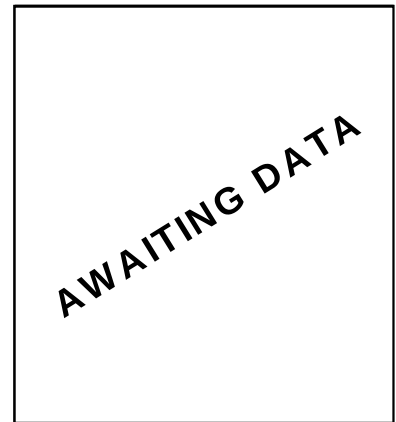
TPC15. Output Current vs. Driver Output Low Voltage



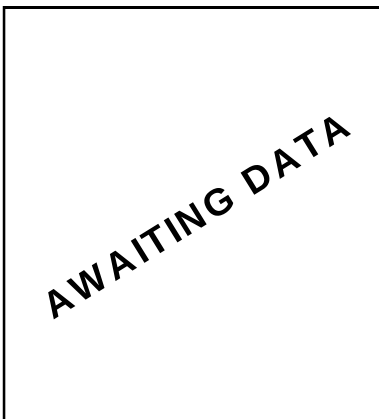
TPC16. ADM3082 Driver Propagation Delay



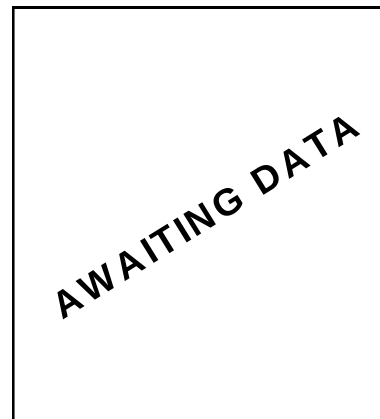
TPC17. ADM3085 Driver Propagation Delay



TPC18. ADM3088 Driver Propagation Delay



TPC19. ADM3082/5 Receiver Propagation Delay



TPC20. ADM3088 Receiver Propagation Delay

## PIN FUNCTION DESCRIPTION

| Pin | Mnemonic        | Description                                                                                                                                                                                                              |
|-----|-----------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1   | RO              | Receiver Output. When $\overline{RE}$ is low and $A - B \geq$ (more positive than) $-50\text{mV}$ , RO will be high. When $\overline{RE}$ is low and $A - B \leq$ (more negative than) $-200\text{mV}$ , RO will be low. |
| 2   | $\overline{RE}$ | Receiver Output Enable. Take $\overline{RE}$ low to enable RO; RO is high impedance when $\overline{RE}$ is high. Take $\overline{RE}$ high and DE low to enter low-power shutdown mode.                                 |
| 3   | DE              | Driver Output Enable. Take DE high to enable driver outputs. These outputs are high impedance when DE is low. Take RE high and DE low to enter low-power shutdown mode.                                                  |
| 4   | DI              | Driver Input. With DE high, a low on DI forces non-inverting output low and inverting output high. Similarly, a high on DI forces non-inverting output high and inverting output low.                                    |
| 5   | GND             | Ground                                                                                                                                                                                                                   |
| 6   | A               | Non-Inverting Receiver Input and Non-Inverting Driver Output                                                                                                                                                             |
| 7   | B               | Inverting Receiver Input and Inverting Driver Output                                                                                                                                                                     |
| 8   | $V_{CC}$        | Positive Supply $4.75\text{V} = V_{CC} = 5.25\text{V}$                                                                                                                                                                   |

## DEVICE TRUTH TABLES

## TRANSMITTING

| INPUTS          |    |    | OUTPUTS  |        |
|-----------------|----|----|----------|--------|
| $\overline{RE}$ | DE | DI | B/Z      | A/Y    |
| X               | 1  | 1  | 0        | 1      |
| X               | 1  | 0  | 1        | 0      |
| 0               | 0  | X  | High-Z   | High-Z |
| 1               | 0  | X  | Shutdown |        |

## RECEIVING

| INPUTS          |    |                      | OUTPUT   |
|-----------------|----|----------------------|----------|
| $\overline{RE}$ | DE | A-B                  | RO       |
| 0               | X  | $\geq -0.05\text{V}$ | 1        |
| 0               | X  | $\leq -0.2\text{V}$  | 0        |
| 0               | X  | Open/shorted         | 1        |
| 1               | 1  | X                    | High-Z   |
| 1               | 0  | X                    | Shutdown |

X = Don't care

Shutdown mode, driver and receiver outputs high impedance



**CURRENT LIMIT AND THERMAL SHUTDOWN**

The ADM3082/ADM3085/ADM3088 incorporate two protection mechanisms to guard the drivers against short-circuits, bus contention or other fault conditions. The first is a foldback current-limited output stage that protects the driver against short-circuits over the entire common-mode voltage range. The second is a thermal shutdown circuit that puts the driver outputs into a high-impedance state if the die temperature exceeds a safe limit.

**REDUCED EMI AND REFLECTIONS**

The ADM3082 and ADM3085 incorporate slew-rate limiting in the drivers. This reduces reflections due to incorrect cable termination and minimizes electromagnetic interference (EMI).

Figures 9 to 11 show driver output waveforms and Fourier analyses of 20kHz signals for the three different slew-rate settings. It can be seen that the harmonic content is greatly reduced for the ADM3085 and still further for the ADM3082 (Figures 10 and 9 respectively).

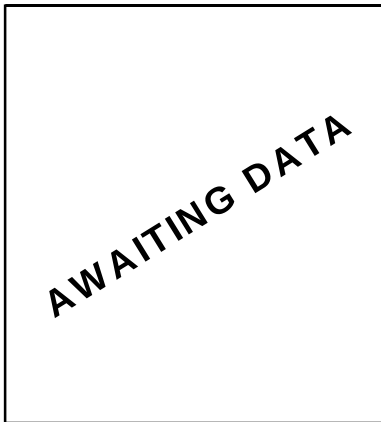


Figure 9 ADM3082 Driver Output Waveform and FFT Plot

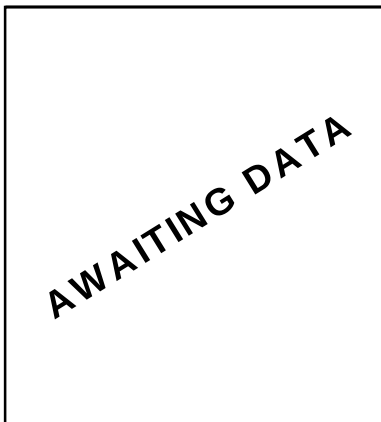


Figure 10. ADM3085 Driver Output Waveform and FFT Plot

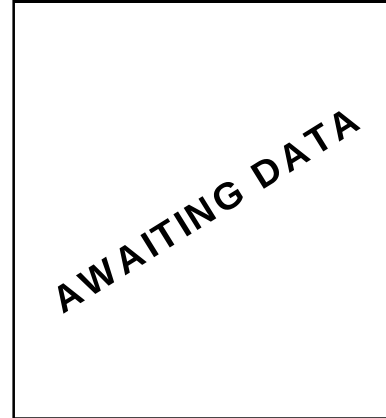


Figure 11. ADM3088 Driver Output Waveform and FFT Plot

The length of an unterminated stub that can be driven with only minor reflections depends on the rise time of the transmitter. A conservative estimate for this is given by the following equation:

$$L \text{ (metres)} = t_R / 49.2$$

where  $t_R$  is the transmitter's rise time in ns (multiply result by 3.28 for answer in feet).

For example, the rise time of the ADM3082 is typically 1320ns, which results in acceptable waveforms with stub lengths up to 27 metres. This is not the ultimate limit on unterminated stub length, as a system can still work if the waveform is allowed to settle before sampling the data.

The RS-485/RS-422 standard covers line lengths up to 4000 feet (1219 metres). Driver output and receiver output waveforms for the three slew rate settings, driving a 4000 foot cable, are shown in figures 12 to 14.

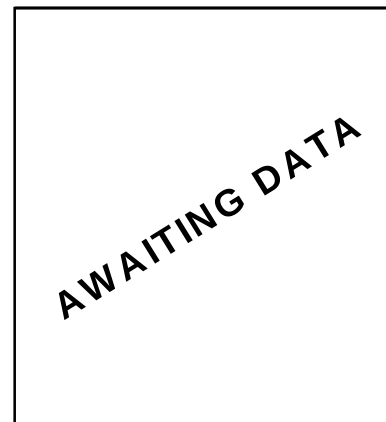


Figure 12. Driver Input, Driver Output and Receiver Output Waveforms of ADM3082, Driving 4000ft (1219m) of Cable at 50kHz

## ADM3082/ADM3085/ADM3088

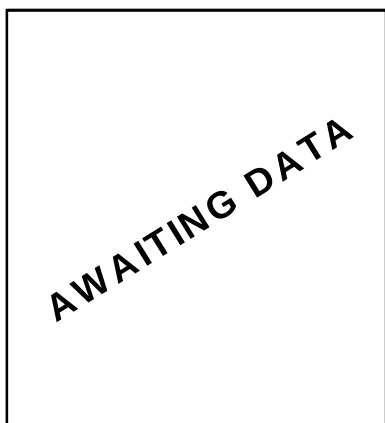


Figure 13. Driver Input, Driver Output and Receiver Output Waveforms of ADM3085, Driving 4000ft (1219m) of Cable at 50kHz

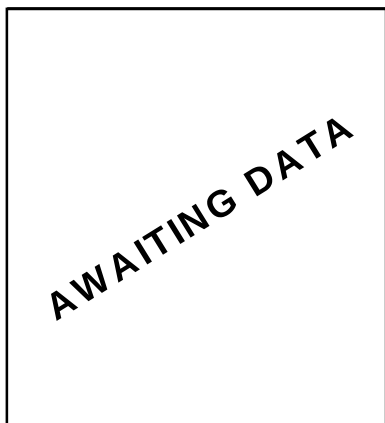


Figure 14. Driver Input, Driver Output and Receiver Output Waveforms of ADM3088, Driving 4000ft (1219m) of Cable at 200kHz

For line lengths in excess of 1220 metres the line should be split into smaller sections with intermediate repeaters.

## APPLICATIONS

Figure 15 shows a typical application of the device on a half-duplex network. The line should be terminated at both ends to minimize reflections and any stubs off the main line should be kept as short as possible.

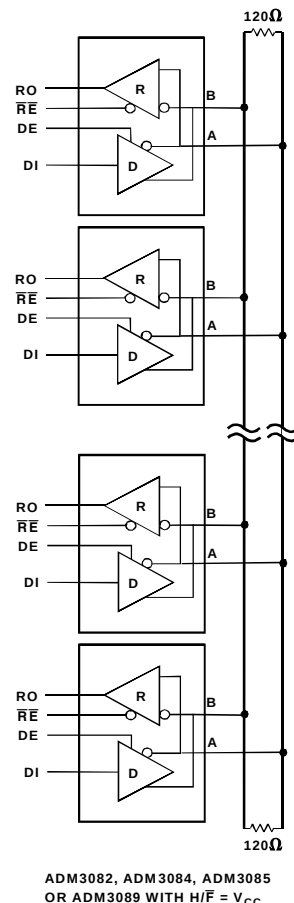
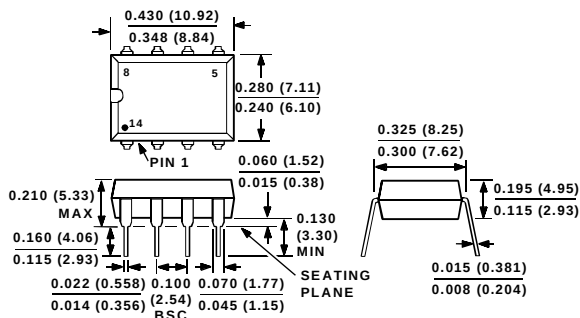


Figure 15. Typical Half-Duplex Network Application

## OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

### 8-Pin Plastic Dual-In-Line Package (N-8)



### 8-Pin SO Package (R-8)

