



## 2.5V LVDS 1:16 GLITCHLESS CLOCK BUFFER TERABUFFER™ II

**IDT5T93GL16**

### FEATURES:

- Guaranteed Low Skew < 25ps (max)
- Very low duty cycle distortion < 100ps (max)
- High speed propagation delay < 2ns (max)
- Up to 650MHz operation
- Glitchless input clock switching
- Selectable inputs
- Hot insertable and over-voltage tolerant inputs
- 3.3V / 2.5V LVTTTL, HSTL, eHSTL, LVEPECL (2.5V), LVPECL (3.3V), CML, or LVDS input interface
- Selectable differential inputs to sixteen LVDS outputs
- Power-down mode
- 2.5V V<sub>DD</sub>
- Available in VFQFPN package

### APPLICATIONS:

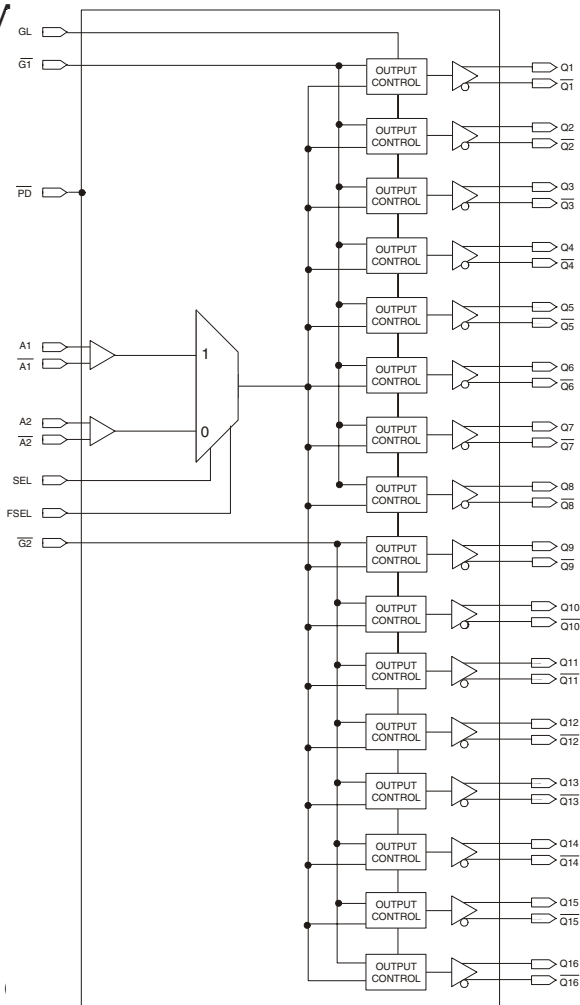
- Clock distribution

### DESCRIPTION:

The IDT5T93GL16 2.5V differential clock buffer is a user-selectable differential input to sixteen LVDS outputs. The fanout from a differential input to sixteen LVDS outputs reduces loading on the preceding driver and provides an efficient clock distribution network. The IDT5T93GL16 can act as a translator from a differential HSTL, eHSTL, LVEPECL (2.5V), LVPECL (3.3V), CML, or LVDS input to LVDS outputs. A single-ended 3.3V / 2.5V LVTTTL input can also be used to translate to LVDS outputs. The redundant input capability allows for a glitchless change-over from a primary clock source to a secondary clock source. Selectable inputs are controlled by SEL. During the switchover, the output will disable low for up to three clock cycles of the previously-selected input clock. The outputs will remain low for up to three clock cycles of the newly-selected clock, after which the outputs will start from the newly-selected input. A FSEL pin has been implemented to control the switchover in cases where a clock source is absent or is driven to DC levels below the minimum specifications.

The IDT5T93GL16 outputs can be asynchronously enabled/disabled. When disabled, the outputs will drive to the value selected by the GL pin. Multiple power and grounds reduce noise.

### FUNCTIONAL BLOCK DIAGRAM

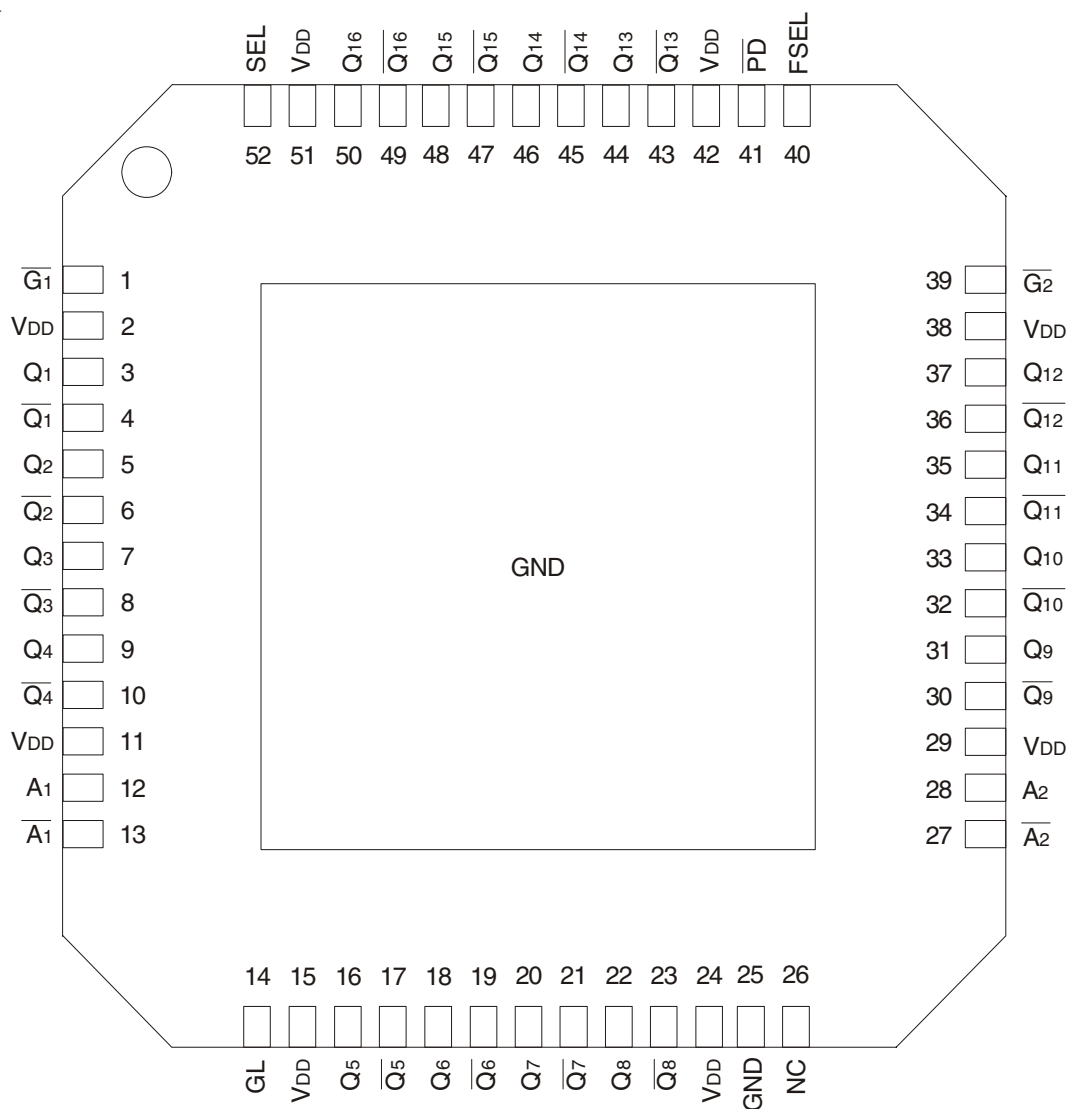


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INDUSTRIAL TEMPERATURE RANGE

JANUARY 2007

## PIN CONFIGURATION



VFQFPN  
TOP VIEW

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

| Symbol           | Description                   | Max                           | Unit |
|------------------|-------------------------------|-------------------------------|------|
| V <sub>DD</sub>  | Power Supply Voltage          | −0.5 to +3.6                  | V    |
| V <sub>I</sub>   | Input Voltage                 | −0.5 to +3.6                  | V    |
| V <sub>O</sub>   | Output Voltage <sup>(2)</sup> | −0.5 to V <sub>DD</sub> + 0.5 | V    |
| T <sub>STG</sub> | Storage Temperature           | −65 to +150                   | °C   |
| T <sub>J</sub>   | Junction Temperature          | 150                           | °C   |

### NOTES:

- Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- Not to exceed 3.6V.

## CAPACITANCE<sup>(1)</sup> (T<sub>A</sub> = +25°C, F = 1.0MHz)

| Symbol          | Parameter         | Min | Typ. | Max. | Unit |
|-----------------|-------------------|-----|------|------|------|
| C <sub>IN</sub> | Input Capacitance | —   | —    | 3    | pF   |

### NOTE:

- This parameter is measured at characterization but not tested

## RECOMMENDED OPERATING RANGE

| Symbol          | Description                   | Min. | Typ. | Max. | Unit |
|-----------------|-------------------------------|------|------|------|------|
| T <sub>A</sub>  | Ambient Operating Temperature | −40  | +25  | +85  | °C   |
| V <sub>DD</sub> | Internal Power Supply Voltage | 2.3  | 2.5  | 2.7  | V    |

## PIN DESCRIPTION

| Symbol             | I/O | Type                        | Description                                                                                                                                                                                                                                                                                                 |
|--------------------|-----|-----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| A <sub>[1:2]</sub> | I   | Adjustable <sup>(1,4)</sup> | Clock input. A <sub>[1:2]</sub> is the "true" side of the differential clock input.                                                                                                                                                                                                                         |
| $\bar{A}_{[1:2]}$  | I   | Adjustable <sup>(1,4)</sup> | Complementary clock inputs. $\bar{A}_{[1:2]}$ is the complementary side of A <sub>[1:2]</sub> . For LVTTTL single-ended operation, $\bar{A}_{[1:2]}$ should be set to the desired toggle voltage for A <sub>[1:2]</sub> :<br>3.3V LVTTTL V <sub>REF</sub> = 1650mV<br>2.5V LVTTTL V <sub>REF</sub> = 1250mV |
| $\bar{G}_1$        | I   | LVTTTL                      | Gate control for differential outputs Q <sub>1</sub> and $\bar{Q}_1$ through Q <sub>8</sub> and $\bar{Q}_8$ . When $\bar{G}_1$ is LOW, the differential outputs are active. When $\bar{G}_1$ is HIGH, the differential outputs are asynchronously driven to the level designated by GL <sup>(2)</sup> .     |
| $\bar{G}_2$        | I   | LVTTTL                      | Gate control for differential outputs Q <sub>9</sub> and $\bar{Q}_9$ through Q <sub>16</sub> and $\bar{Q}_{16}$ . When $\bar{G}_2$ is LOW, the differential outputs are active. When $\bar{G}_2$ is HIGH, the differential outputs are asynchronously driven to the level designated by GL <sup>(2)</sup> . |
| GL                 | I   | LVTTTL                      | Specifies output disable level. If HIGH, "true" outputs disable HIGH and "complementary" outputs disable LOW. If LOW, "true" outputs disable LOW and "complementary" outputs disable HIGH.                                                                                                                  |
| Q <sub>n</sub>     | O   | LVDS                        | Clock outputs                                                                                                                                                                                                                                                                                               |
| $\bar{Q}_n$        | O   | LVDS                        | Complementary clock outputs                                                                                                                                                                                                                                                                                 |
| SEL                | I   | LVTTTL                      | Reference clock select. When LOW, selects A <sub>2</sub> and $\bar{A}_2$ . When HIGH, selects A <sub>1</sub> and $\bar{A}_1$ .                                                                                                                                                                              |
| $\bar{PD}$         | I   | LVTTTL                      | Power-down control. Shuts off entire chip. If LOW, the device goes into low power mode. Inputs and outputs are disabled. Both "true" and "complementary" outputs will pull to V <sub>DD</sub> . Set HIGH for normal operation. <sup>(3)</sup>                                                               |
| FSEL               | I   | LVTTTL                      | At a rising edge, FSEL forces select to the input designated by SEL. Set LOW for normal operation.                                                                                                                                                                                                          |
| V <sub>DD</sub>    |     | PWR                         | Power supply for the device core and inputs                                                                                                                                                                                                                                                                 |
| GND                |     | PWR                         | Ground                                                                                                                                                                                                                                                                                                      |

### NOTES:

- Inputs are capable of translating the following interface standards:  
Single-ended 3.3V and 2.5V LVTTTL levels  
Differential HSTL and eHSTL levels  
Differential LVEPECL (2.5V) and LVPECL (3.3V) levels  
Differential LVDS levels  
Differential CML levels
- Because the gate controls are asynchronous, runt pulses are possible. It is the user's responsibility to either time the gate control signals to minimize the possibility of runt pulses or be able to tolerate them in down stream circuitry.
- It is recommended that the outputs be disabled before entering power-down mode. It is also recommended that the outputs remain disabled until the device completes power-up after asserting  $\bar{PD}$ .
- The user must take precautions with any differential input interface standard being used in order to prevent instability when there is no input signal.

## DC ELECTRICAL CHARACTERISTICS OVER RECOMMENDED OPERATING RANGE FOR LVTTTL<sup>(1)</sup>

| Symbol                | Parameter                                     | Test Conditions                                 | Min. | Typ. <sup>(2)</sup> | Max  | Unit |
|-----------------------|-----------------------------------------------|-------------------------------------------------|------|---------------------|------|------|
| Input Characteristics |                                               |                                                 |      |                     |      |      |
| I <sub>IH</sub>       | Input HIGH Current                            | V <sub>DD</sub> = 2.7V                          | —    | —                   | ±5   | μA   |
| I <sub>IL</sub>       | Input LOW Current                             | V <sub>DD</sub> = 2.7V                          | —    | —                   | ±5   |      |
| V <sub>IK</sub>       | Clamp Diode Voltage                           | V <sub>DD</sub> = 2.3V, I <sub>IN</sub> = -18mA | —    | -0.7                | -1.2 | V    |
| V <sub>IN</sub>       | DC Input Voltage                              |                                                 | -0.3 |                     | +3.6 | V    |
| V <sub>IH</sub>       | DC Input HIGH                                 |                                                 | 1.7  |                     | —    | V    |
| V <sub>IL</sub>       | DC Input LOW                                  |                                                 | —    |                     | 0.7  | V    |
| V <sub>THI</sub>      | DC Input Threshold Crossing Voltage           |                                                 |      | V <sub>DD</sub> /2  |      | V    |
| V <sub>REF</sub>      | Single-Ended Reference Voltage <sup>(3)</sup> | 3.3V LVTTTL                                     | —    | 1.65                | —    | V    |
|                       |                                               | 2.5V LVTTTL                                     | —    | 1.25                | —    |      |

### NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. Typical values are at V<sub>DD</sub> = 2.5V, +25°C ambient.
3. For A<sub>[1:2]</sub> single-ended operation,  $\bar{A}_{[1:2]}$  is tied to a DC reference voltage.

## DC ELECTRICAL CHARACTERISTICS OVER RECOMMENDED OPERATING RANGE FOR DIFFERENTIAL INPUTS<sup>(1)</sup>

| Symbol                | Parameter                                   | Test Conditions                                 | Min. | Typ. <sup>(4)</sup> | Max             | Unit |
|-----------------------|---------------------------------------------|-------------------------------------------------|------|---------------------|-----------------|------|
| Input Characteristics |                                             |                                                 |      |                     |                 |      |
| I <sub>IH</sub>       | Input HIGH Current                          | V <sub>DD</sub> = 2.7V                          | —    | —                   | ±5              | μA   |
| I <sub>IL</sub>       | Input LOW Current                           | V <sub>DD</sub> = 2.7V                          | —    | —                   | ±5              |      |
| V <sub>IK</sub>       | Clamp Diode Voltage                         | V <sub>DD</sub> = 2.3V, I <sub>IN</sub> = -18mA | —    | -0.7                | -1.2            | V    |
| V <sub>IN</sub>       | DC Input Voltage                            |                                                 | -0.3 |                     | +3.6            | V    |
| V <sub>DIF</sub>      | DC Differential Voltage <sup>(2)</sup>      |                                                 | 0.1  |                     | —               | V    |
| V <sub>CM</sub>       | DC Common Mode Input Voltage <sup>(3)</sup> |                                                 | 0.05 |                     | V <sub>DD</sub> | V    |

### NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. V<sub>DIF</sub> specifies the minimum input differential voltage (V<sub>TR</sub> - V<sub>CP</sub>) required for switching where V<sub>TR</sub> is the "true" input level and V<sub>CP</sub> is the "complement" input level. The DC differential voltage must be maintained to guarantee retaining the existing HIGH or LOW input. The AC differential voltage must be achieved to guarantee switching to a new state.
3. V<sub>CM</sub> specifies the maximum allowable range of (V<sub>TR</sub> + V<sub>CP</sub>) / 2.
4. Typical values are at V<sub>DD</sub> = 2.5V, +25°C ambient.

## DC ELECTRICAL CHARACTERISTICS OVER RECOMMENDED OPERATING RANGE FOR LVDS<sup>(1)</sup>

| Symbol                 | Parameter                                                     | Test Conditions                                | Min.  | Typ. <sup>(2)</sup> | Max   | Unit |
|------------------------|---------------------------------------------------------------|------------------------------------------------|-------|---------------------|-------|------|
| Output Characteristics |                                                               |                                                |       |                     |       |      |
| V <sub>OT</sub> (+)    | Differential Output Voltage for the True Binary State         |                                                | 247   | —                   | 454   | mV   |
| V <sub>OT</sub> (-)    | Differential Output Voltage for the False Binary State        |                                                | 247   | —                   | 454   | mV   |
| ΔV <sub>OT</sub>       | Change in V <sub>OT</sub> Between Complementary Output States |                                                | —     | —                   | 50    | mV   |
| V <sub>OS</sub>        | Output Common Mode Voltage (Offset Voltage)                   |                                                | 1.125 | 1.2                 | 1.375 | V    |
| ΔV <sub>OS</sub>       | Change in V <sub>OS</sub> Between Complementary Output States |                                                | —     | —                   | 50    | mV   |
| I <sub>OS</sub>        | Outputs Short Circuit Current                                 | V <sub>OUT</sub> + and V <sub>OUT</sub> - = 0V | —     | 12                  | 24    | mA   |
| I <sub>OSD</sub>       | Differential Outputs Short Circuit Current                    | V <sub>OUT</sub> + = V <sub>OUT</sub> -        | —     | 6                   | 12    | mA   |

### NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. Typical values are at V<sub>DD</sub> = 2.5V, +25°C ambient.

## DIFFERENTIAL INPUT AC TEST CONDITIONS FOR HSTL

| Symbol                          | Parameter                                               | Value          | Units |
|---------------------------------|---------------------------------------------------------|----------------|-------|
| V <sub>DIF</sub>                | Input Signal Swing <sup>(1)</sup>                       | 1              | V     |
| V <sub>X</sub>                  | Differential Input Signal Crossing Point <sup>(2)</sup> | 750            | mV    |
| D <sub>H</sub>                  | Duty Cycle                                              | 50             | %     |
| V <sub>THI</sub>                | Input Timing Measurement Reference Level <sup>(3)</sup> | Crossing Point | V     |
| t <sub>R</sub> , t <sub>F</sub> | Input Signal Edge Rate <sup>(4)</sup>                   | 2              | V/ns  |

### NOTES:

1. The 1V peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>DIF</sub> (AC) specification under actual use conditions.
2. A 750mV crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>X</sub> specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

## DIFFERENTIAL INPUT AC TEST CONDITIONS FOR eHSTL

| Symbol                          | Parameter                                               | Value          | Units |
|---------------------------------|---------------------------------------------------------|----------------|-------|
| V <sub>DIF</sub>                | Input Signal Swing <sup>(1)</sup>                       | 1              | V     |
| V <sub>X</sub>                  | Differential Input Signal Crossing Point <sup>(2)</sup> | 900            | mV    |
| D <sub>H</sub>                  | Duty Cycle                                              | 50             | %     |
| V <sub>THI</sub>                | Input Timing Measurement Reference Level <sup>(3)</sup> | Crossing Point | V     |
| t <sub>R</sub> , t <sub>F</sub> | Input Signal Edge Rate <sup>(4)</sup>                   | 2              | V/ns  |

### NOTES:

1. The 1V peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>DIF</sub> (AC) specification under actual use conditions.
2. A 900mV crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>X</sub> specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

## DIFFERENTIAL INPUT AC TEST CONDITIONS FOR LVEPECL (2.5V) AND LVPECL (3.3V)

| Symbol                          | Parameter                                               | Value          | Units |
|---------------------------------|---------------------------------------------------------|----------------|-------|
| V <sub>DIF</sub>                | Input Signal Swing <sup>(1)</sup>                       | 732            | mV    |
| V <sub>X</sub>                  | Differential Input Signal Crossing Point <sup>(2)</sup> | LVEPECL        | mV    |
|                                 |                                                         | LVPECL         |       |
| D <sub>H</sub>                  | Duty Cycle                                              | 50             | %     |
| V <sub>THI</sub>                | Input Timing Measurement Reference Level <sup>(3)</sup> | Crossing Point | V     |
| t <sub>R</sub> , t <sub>F</sub> | Input Signal Edge Rate <sup>(4)</sup>                   | 2              | V/ns  |

### NOTES:

1. The 732mV peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>DIF</sub> (AC) specification under actual use conditions.
2. 1082mV LVEPECL (2.5V) and 1880mV LVPECL (3.3V) crossing point levels are specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V<sub>X</sub> specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

## DIFFERENTIAL INPUT AC TEST CONDITIONS FOR LVDS

| Symbol     | Parameter                                               | Value          | Units |
|------------|---------------------------------------------------------|----------------|-------|
| $V_{DIF}$  | Input Signal Swing <sup>(1)</sup>                       | 400            | mV    |
| $V_X$      | Differential Input Signal Crossing Point <sup>(2)</sup> | 1.2            | V     |
| $D_H$      | Duty Cycle                                              | 50             | %     |
| $V_{THI}$  | Input Timing Measurement Reference Level <sup>(3)</sup> | Crossing Point | V     |
| $t_R, t_F$ | Input Signal Edge Rate <sup>(4)</sup>                   | 2              | V/ns  |

### NOTES:

1. The 400mV peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the  $V_{DIF}$  (AC) specification under actual use conditions.
2. A 1.2V crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the  $V_X$  specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

## AC DIFFERENTIAL INPUT SPECIFICATIONS<sup>(1)</sup>

| Symbol    | Parameter                                      | Min. | Typ. | Max      | Unit |
|-----------|------------------------------------------------|------|------|----------|------|
| $V_{DIF}$ | AC Differential Voltage <sup>(2)</sup>         | 0.1  | —    | 3.6      | V    |
| $V_{IX}$  | Differential Input Crosspoint Voltage          | 0.05 | —    | $V_{DD}$ | V    |
| $V_{CM}$  | Common Mode Input Voltage Range <sup>(3)</sup> | 0.05 | —    | $V_{DD}$ | V    |
| $V_{IN}$  | Input Voltage                                  | -0.3 |      | +3.6     | V    |

### NOTES:

1. The output will not change state until the inputs have crossed and the minimum differential voltage defined by  $V_{DIF}$  has been met or exceeded.
2.  $V_{DIF}$  specifies the minimum input voltage ( $V_{TR} - V_{CP}$ ) required for switching where  $V_{TR}$  is the "true" input level and  $V_{CP}$  is the "complement" input level. The AC differential voltage must be achieved to guarantee switching to a new state.
3.  $V_{CM}$  specifies the maximum allowable range of  $(V_{TR} + V_{CP}) / 2$ .

## POWER SUPPLY CHARACTERISTICS FOR LVDS OUTPUTS<sup>(1)</sup>

| Symbol    | Parameter                               | Test Conditions                                                                   | Typ. | Max | Unit |
|-----------|-----------------------------------------|-----------------------------------------------------------------------------------|------|-----|------|
| $I_{DDQ}$ | Quiescent $V_{DD}$ Power Supply Current | $V_{DD} = \text{Max.}$ , All Input Clocks = LOW <sup>(2)</sup><br>Outputs enabled | —    | 350 | mA   |
| $I_{TOT}$ | Total Power $V_{DD}$ Supply Current     | $V_{DD} = 2.7V$ , REFERENCE CLOCK = 650MHz                                        | —    | 360 | mA   |
| $I_{PD}$  | Total Power Down Supply Current         | $\overline{PD} = \text{LOW}$                                                      | —    | 5   | mA   |

### NOTES:

1. These power consumption characteristics are for all the valid input interfaces and cover the worst case conditions.
2. The true input is held LOW and the complementary input is held HIGH.

## AC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE<sup>(1,5)</sup>

| Symbol | Parameter | Min. | Typ. | Max | Unit |
|--------|-----------|------|------|-----|------|
|--------|-----------|------|------|-----|------|

### Skew Parameters

|              |                                                   |   |   |     |    |
|--------------|---------------------------------------------------|---|---|-----|----|
| $t_{sk(o)}$  | Same Device Output Pin-to-Pin Skew <sup>(2)</sup> | — | — | 25  | ps |
| $t_{sk(p)}$  | Pulse Skew <sup>(3)</sup>                         | — | — | 100 | ps |
| $t_{sk(pp)}$ | Part-to-Part Skew <sup>(4)</sup>                  | — | — | 300 | ps |

### Propagation Delay

|                        |                                                                             |   |     |     |     |
|------------------------|-----------------------------------------------------------------------------|---|-----|-----|-----|
| $t_{PLH}$<br>$t_{PHL}$ | Propagation Delay A, $\bar{A}$ Crosspoint to $Q_n$ , $\bar{Q}_n$ Crosspoint | — | 1.5 | 2   | ns  |
| $f_o$                  | Frequency Range <sup>(6)</sup>                                              | — | —   | 650 | MHz |

### Output Gate Enable/Disable Delay

|           |                                                                                                    |   |   |     |    |
|-----------|----------------------------------------------------------------------------------------------------|---|---|-----|----|
| $t_{PGE}$ | Output Gate Enable Crossing $V_{THI}$ to $Q_n/\bar{Q}_n$ Crosspoint                                | — | — | 3.5 | ns |
| $t_{PGD}$ | Output Gate Disable Crossing $V_{THI}$ to $Q_n/\bar{Q}_n$ Crosspoint Driven to GL Designated Level | — | — | 3.5 | ns |

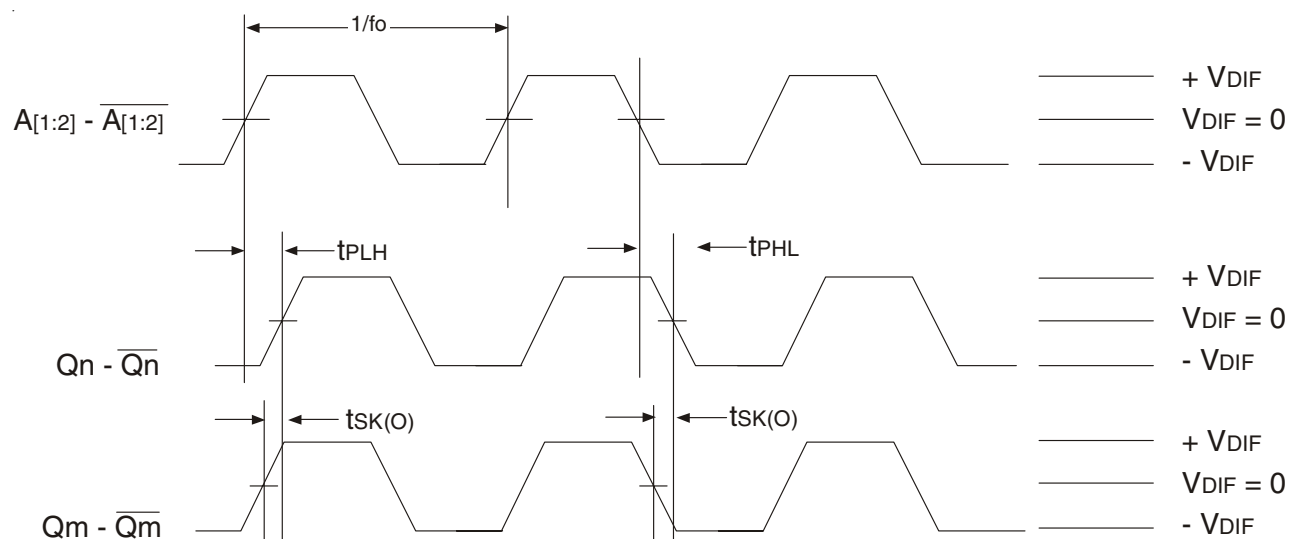
### Power Down Timing

|             |                                                                                         |   |   |     |         |
|-------------|-----------------------------------------------------------------------------------------|---|---|-----|---------|
| $t_{PWRDN}$ | $\bar{PD}$ Crossing $V_{THI}$ to $Q_n = V_{DD}$ , $\bar{Q}_n = V_{DD}$                  | — | — | 100 | $\mu$ S |
| $t_{PWRUP}$ | Output Gate Disable Crossing $V_{THI}$ to $Q_n/\bar{Q}_n$ Driven to GL Designated Level | — | — | 100 | $\mu$ S |

### NOTES:

1. AC propagation measurements should not be taken within the first 100 cycles of startup.
2. Skew measured between crosspoints of all differential output pairs under identical input and output interfaces, transitions and load conditions on any one device.
3. Skew measured is the difference between propagation delay times  $t_{PHL}$  and  $t_{PLH}$  of any single differential output pair under identical input and output interfaces, transitions and load conditions on any one device.
4. Skew measured is the magnitude of the difference in propagation times between any single differential output pair of two devices, given identical transitions and load conditions at identical  $V_{DD}$  levels and temperature.
5. All parameters are tested with a 50% input duty cycle.
6. Guaranteed by design but not production tested.

## DIFFERENTIAL AC TIMING WAVEFORMS



*Output Propagation and Skew Waveforms*

### NOTES:

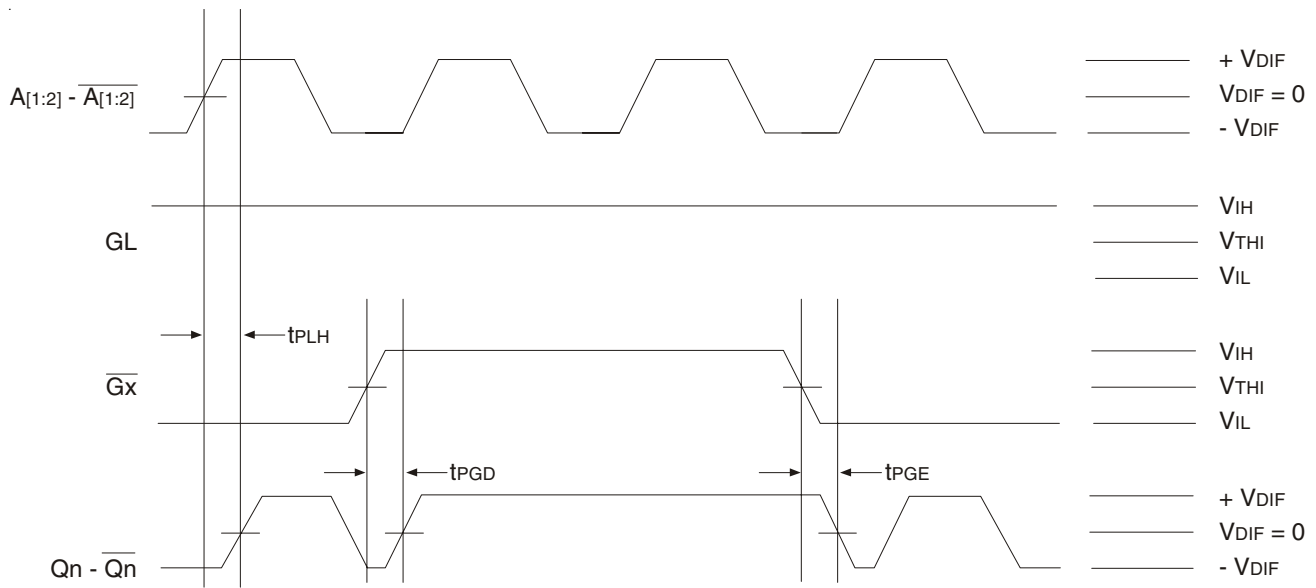
1. Pulse skew is calculated using the following expression:

$$tsk(p) = |t_{PHL} - t_{PLH}|$$

Note that the  $t_{PHL}$  and  $t_{PLH}$  shown above are not valid measurements for this calculation because they are not taken from the same pulse.

2. AC propagation measurements should not be taken within the first 100 cycles of startup.

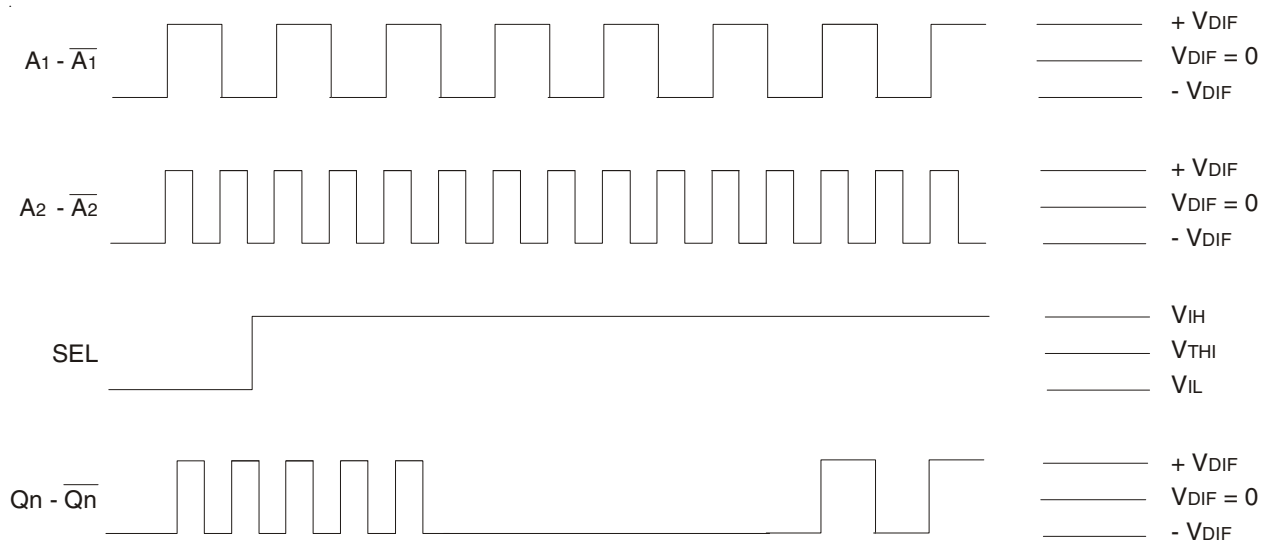




#### Differential Gate Disable/Enable Showing Runt Pulse Generation

##### NOTE:

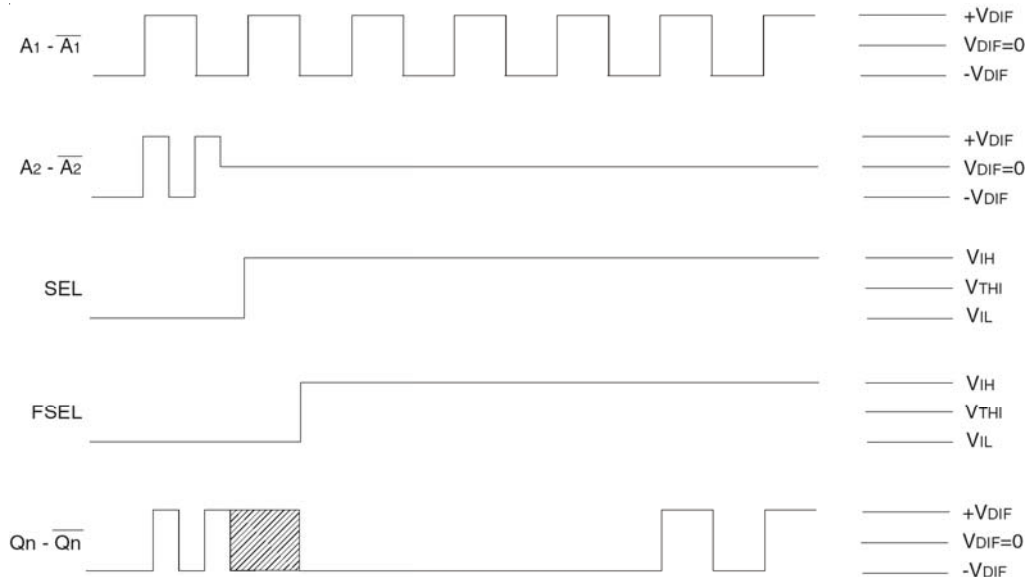
- As shown, it is possible to generate runt pulses on gate disable and enable of the outputs. It is the user's responsibility to time their  $\overline{Gx}$  signals to avoid this problem.



#### Glitchless Output Operation with Switching Input Clock Selection

##### NOTES:

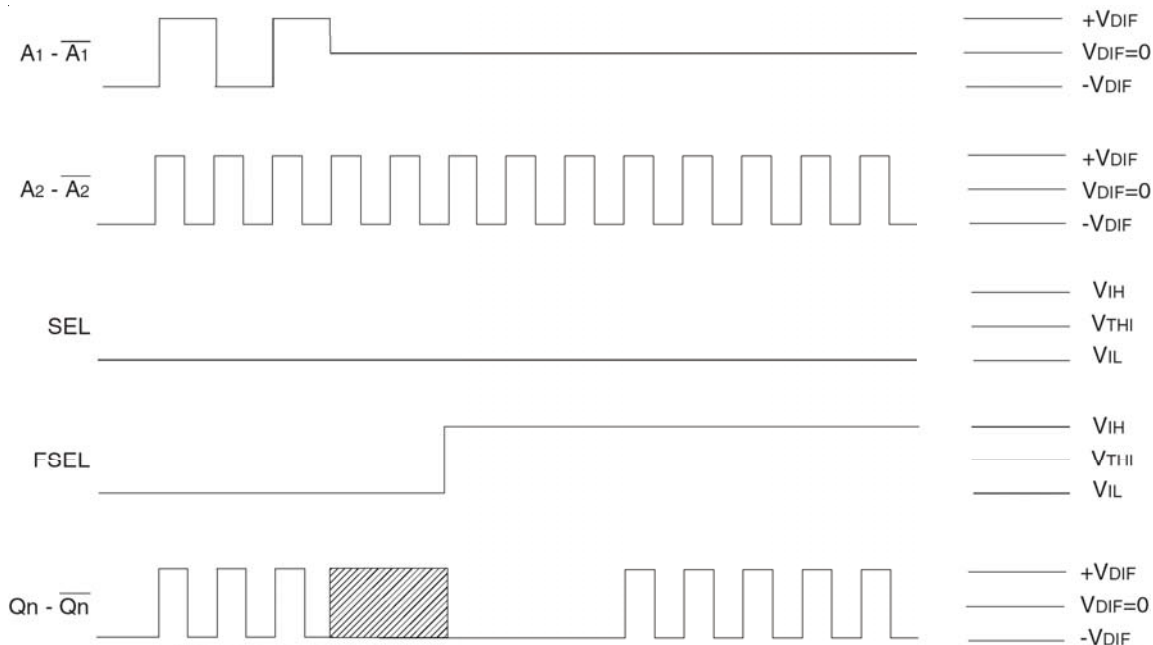
- When  $SEL$  changes, the output clock goes LOW on the falling edge of the output clock up to three cycles later. The output then stays LOW for up to three clock cycles of the new input clock. After this, the output starts with the rising edge of the new input clock.
- AC propagation measurements should not be taken within the first 100 cycles of startup.



*FSEL Operation for When Current Clock Dies*

NOTES:

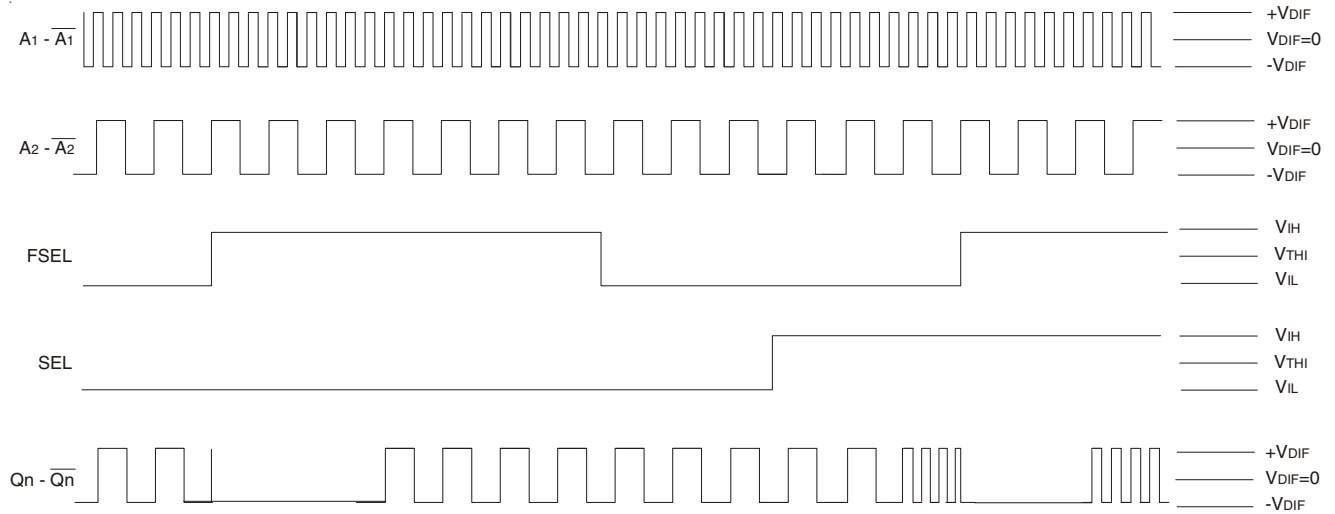
1. When the differential on the selected clock goes below the minimum DC differential, the outputs clock goes to an unknown state. When this happens, the SEL pin should be toggled and FSEL asserted in order to force selection of the new input clock. The output clock will start up after a number of cycles of the newly-selected input clock.
2. The FSEL pin should stay asserted until the problem with the dead clock can be fixed in the system.
3. It is recommended that the FSEL be tied HIGH for systems that use only one input. If this is not possible, the user must guarantee that the unused input have a differential greater than or equal to the minimum DC differential specified in the datasheet.



*FSEL Operation for When Opposite Clock Dies*

NOTES:

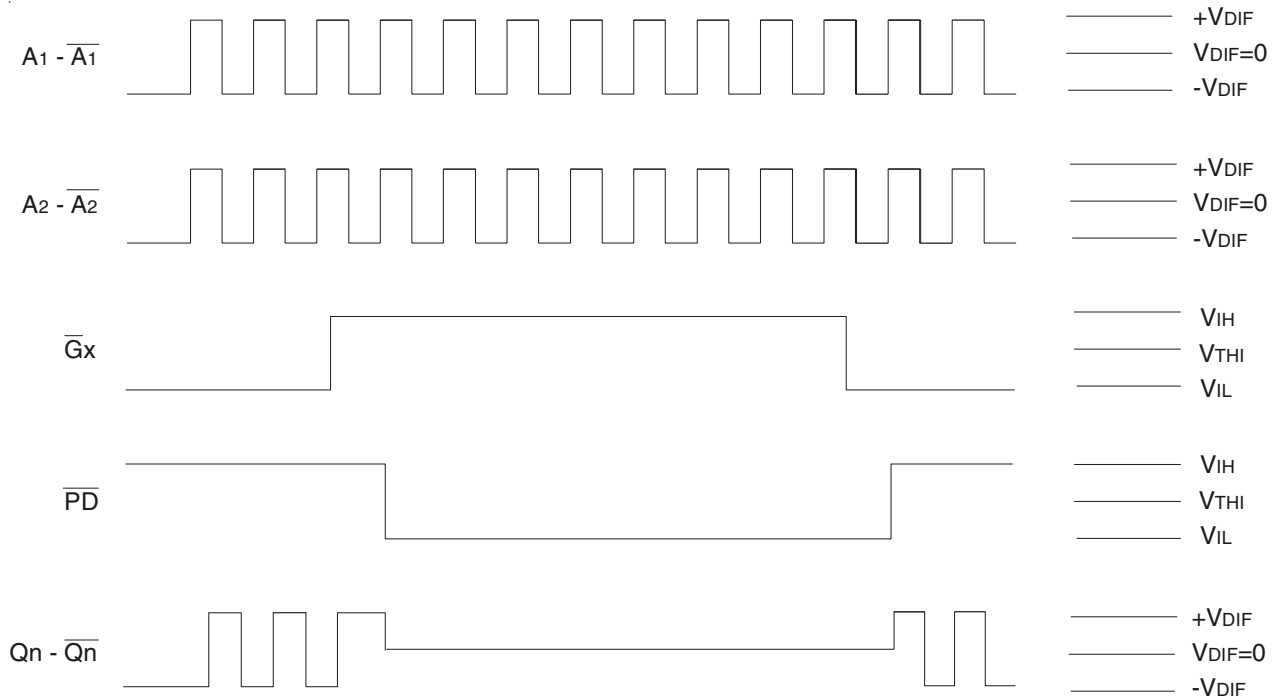
1. When the differential on the non-selected clock goes below the minimum DC differential, the outputs clock goes to an unknown state. When this happens, the FSEL pin should be asserted in order to force selection of the new input clock. The output clock will start up after a number of cycles of the newly-selected input clock.
2. The FSEL pin should stay asserted until the problem with the dead clock can be fixed in the system.
3. It is recommended that the FSEL be tied HIGH for systems that use only one input. If this is not possible, the user must guarantee that the unused input have a differential greater than or equal to the minimum DC differential specified in the datasheet.



### Selection of Input While Protecting Against When Opposite Clock Dies

#### NOTES:

1. If the user holds FSEL HIGH, the output will not be affected by the deselected input clock.
2. The output will immediately be driven to LOW once FSEL is asserted. This may cause glitching on the output. The output will restart with the input clock selected by the SEL pin.
3. If the user decides to switch input clocks, the user must de-assert FSEL, then assert FSEL after toggling the SEL input pin. The output will be driven LOW and will restart with the input clock selected by the SEL pin.

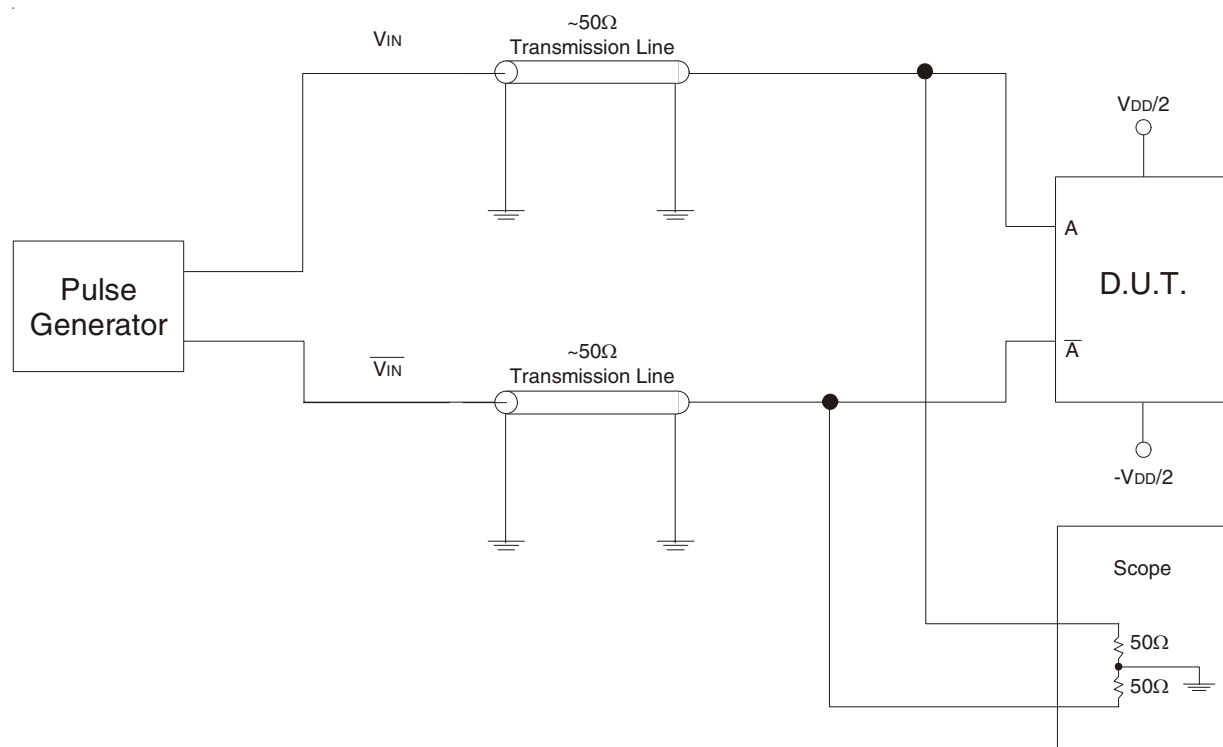


### Power Down Timing

#### NOTES:

1. It is recommended that outputs be disabled before entering power-down mode. It is also recommended that the outputs remain disabled until the device completes power-up after asserting PD.
2. The POWER DOWN TIMING diagram assumes that GL is HIGH.
3. It should be noted that during power-down mode, the outputs are both pulled to  $V_{DD}$ . In the POWER DOWN TIMING diagram this is shown when  $Q_n - \overline{Q}_n$  goes to  $V_{DIF} = 0$ .

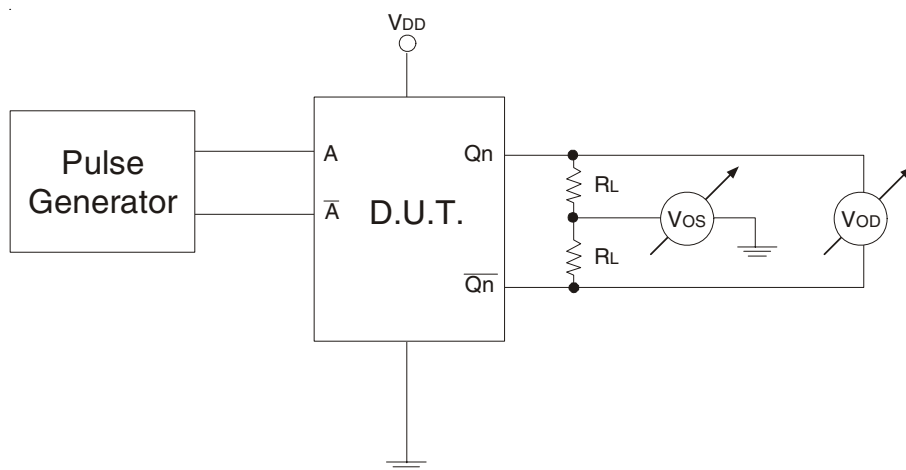
## TEST CIRCUITS AND CONDITIONS



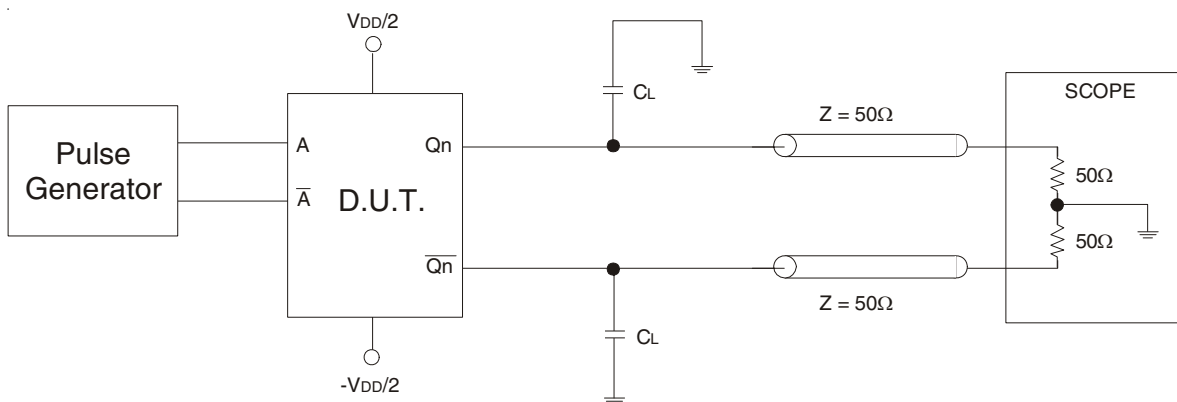
*Test Circuit for Differential Input*

## DIFFERENTIAL INPUT TEST CONDITIONS

| Symbol    | $V_{DD} = 2.5V \pm 0.2V$         | Unit |
|-----------|----------------------------------|------|
| $V_{THI}$ | Crossing of A and $\overline{A}$ | V    |



Test Circuit for DC Outputs and Power Down Tests



Test Circuit for Propagation, Skew, and Gate Enable/Disable Timing

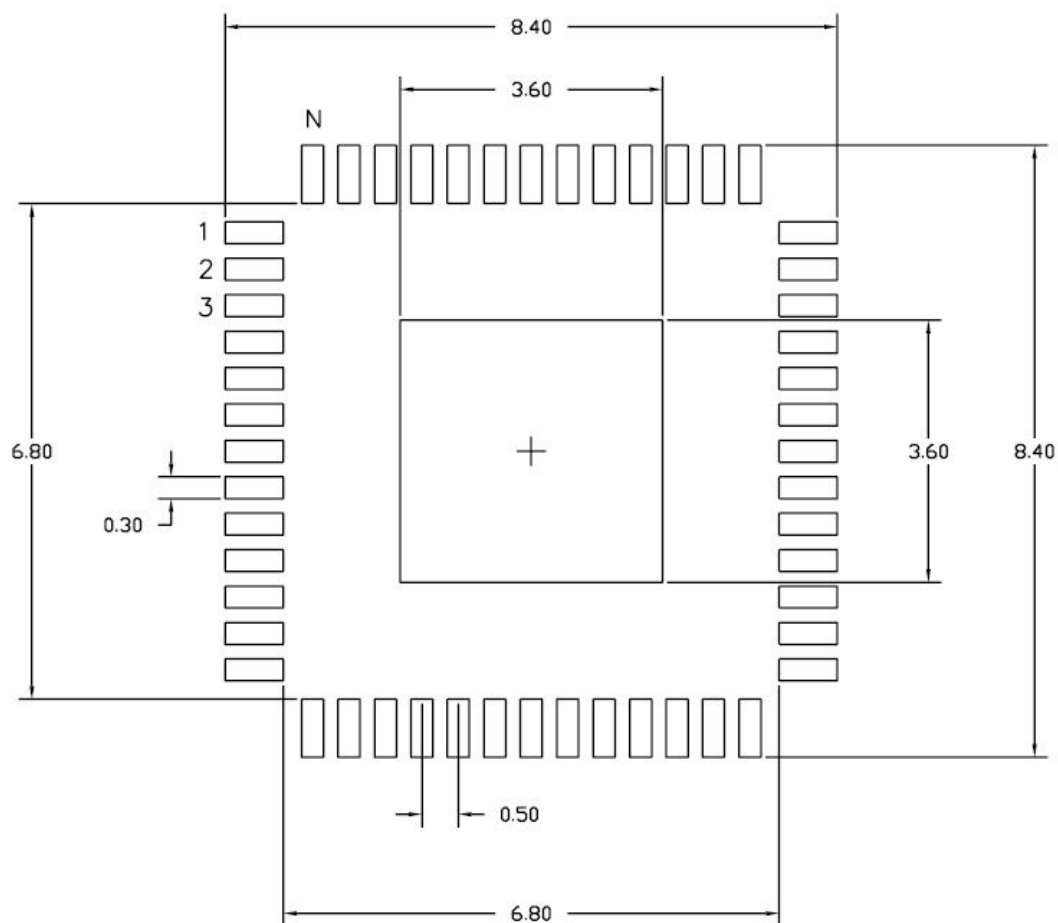
### LVDS OUTPUT TEST CONDITION

| Symbol | $V_{DD} = 2.5V \pm 0.2V$ | Unit     |
|--------|--------------------------|----------|
| $C_L$  | $0^{(1)}$                | pF       |
|        | $8^{(1,2)}$              |          |
| $R_L$  | 50                       | $\Omega$ |

NOTES:

- Specifications only apply to "Normal Operations" test condition. The  $T_{IA}/E_{IA}$  specification load is for reference only.
- The scope inputs are assumed to have a 2pF load to ground.  $T_{IA}/E_{IA}$  - 644 specifies 5pF between the output pair. With  $C_L = 8pF$ , this gives the test circuit appropriate 5pF equivalent load.

## RECOMMENDED LANDING PATTERN



NL 52 pin

NOTE: All dimensions are in millimeters.

## ORDERING INFORMATION

| IDT         | XXXXX   | XX      | X        |  |                                                                      |
|-------------|---------|---------|----------|--|----------------------------------------------------------------------|
| Device Type | Package | Process |          |  |                                                                      |
|             |         |         | I        |  | -40°C to +85°C (Industrial)                                          |
|             |         |         | NL       |  | Thermally Enhanced Plastic Very Fine Pitch Quad Flat No Lead Package |
|             |         |         | NLG      |  | VFQFPN - Green                                                       |
|             |         |         | 5T93GL16 |  | 2.5V LVDS 1:16 Glitchless Clock Buffer Terabuffer™ II                |



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