

### **SERIES 60AD**

Optical Encoder with integrated Joystick and Pushbutton

### **FEATURES**

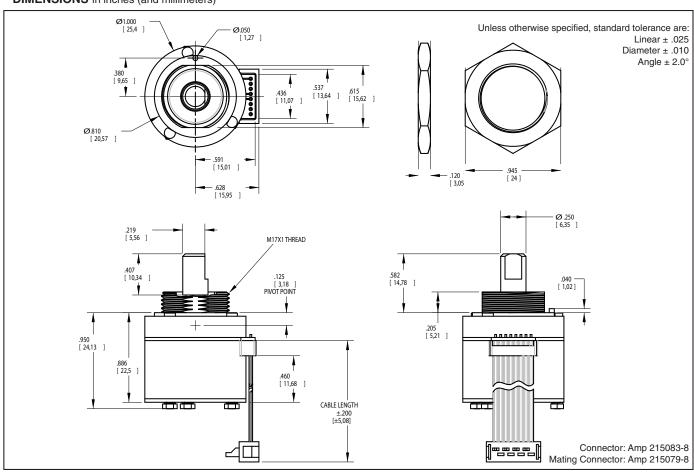
- Dome contacts provide excellent tactile feedback in all directions
- Choices of actuation force, cable length and termination
- Customized solutions available

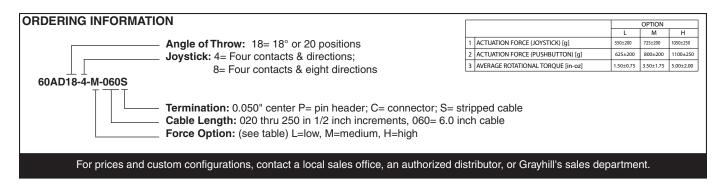
### **APPLICATIONS**

- Aerospace
- Automotive
- Medical devices

### **DIMENSIONS** in inches (and millimeters)

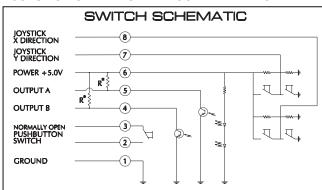






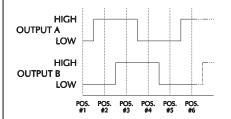


#### JOYSTICK OPERATION + ENCODER WAVEFORM AND TRUTH TABLE Standard Quadrature 2-Bit Code



\*EXTERNAL PULL-UP RESISTORS REQUIRED FOR OPERATION (2.2k $\Omega$ ).

### ENCODER WAVEFORM [C.W. ROTATION]

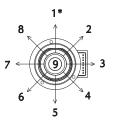


# ENCODER TRUTH TABLE [C.W. ROTATION]

POSITION	OUTPUT A	OUTPUT B
#1	0	0
#2		0
#3		0
#4	0	0

○ INDICATES LOGIC-HIGH
 ○ INDICATES LOGIC-LOW
 CODE REPEATS EVERY FOUR POSITIONS

## JOYSTICK POSITION DIAGRAM \* INDICATES DIRECTION OF D-FLAT ON BUSHING



### JOYSTICK TRUTH TABLE

POSITION	X OUTPUT	Y OUTPUT	
1	NEUTRAL	HIGH	
2	HIGH	HIGH	
3	HIGH	NEUTRAL	
4	HIGH	LOW	
5	NEUTRAL	LOW	
6	LOW	LOW	
7	LOW	NEUTRAL	
8	LOW	HIGH	
9	NEUTRAL	NEUTRAL	

### **SPECIFICATIONS**

**Rotary Specifications** 

Operating Voltage:  $5.00 \pm 0.25 \, \text{Vdc}$  Supply Current: 20 mA max at  $5 \, \text{Vdc}$  Minimum Sink Current: 2.0 mA at  $5 \, \text{Vdc}$  Power Consumption: 0.1 mW max at  $5 \, \text{Vdc}$  Output: Open collector phototransistor,  $2.2 \text{k} \, \Omega$  external pull-up resistors are required Output Code: 2-Bit quadrature, channel A leads channel B by  $90^\circ$  in clockwise rotation Logic Output Characteristics:

High: No less than 3.5 Vdc Low: No greater than 1.0 Vdc

**Mechanical Life:** 1 million rotational cycles (through all positions and a full return)

Rotational Torque: see table
Maximum Rotational Speed: 100 RPM
Mounting Torque: 15 in-lbs. maximum
Shaft Push/Pull Out Force: 45 lbs min.

**Shaft Side-Load Force:** 20 lbs. min. **Terminal Strength:** 15 lbs pull-out force min.

### **Pushbutton Specifications**

Rating: 10 mA at 5 Vdc resistive Contact Resistance: less than 10 ohms Contact Bounce: < 4ms make, <10 ms break Mechanical Life: 1 million actuations min.

Actuation Force: see table Pushbutton Travel: .027 ± .010 in.

Joystick Specifications Supply Current: 5mA max

Output Code: 2-Bit

**Logic Output Characteristics:** Neutral Position: 2.5 ± 0.5 Vdc

High-State Position: >4.5 Vdc
Low-State Position: <0.5 Vdc
Mechanical Life: 500k cycles min.
Actuation Force: see table
Angle of Throw: 3.5° +2°/-1°

### **Environmental Ratings**

Operating Temp. Range: -40°C to 85°C Storage Temp. Range: -55°C to 100°C Relative Humidity: 96 hours at 90-95%

humidity at 40°C

**Vibration:** Harmonic motion with amplitude of 15g, within 10 to 2000 Hz for 12 hours

**Mechanical Shock:** 

Test 1: 100g for 6ms half-sine wave with a

velocity change of 12.3 ft/s

Test 2: 100g for 6ms sawtooth wave with a

velocity change of 9.7 ft/s

### Materials and Finishes Detent Housing: Nylon 6/10

Shaft: Nylon 6/10

Shaft Insert: 303 stainless steel Joystick Housing: Nylon 6,10 Centering Plate: Nylon 6,10 Detent Balls: Carbon steel Detent Springs: Music wire Dome Contacts: Stainless steel

Dome Housings: Polycarbonate over brass-

lead frame

**Dome Retainers:** Nylon 6,0; 30% glass-filled **Joystick Actuators:** Polyphthalamide; 50%

glass filled

Pushbutton Dome Retainer: Polycarbonate Printed Circuit Board: NEMA grade FR-4. Glass-cloth epoxy, double clad with copper Infrared Emitter: Gallium arsenide

Phototransistor: Planar silicon

**Resistors:** Metal oxide on ceramic substrate **Solder:** 95.5% SN, 3% AG, 0.5% CU

### **OPTIONS**

Contact Grayhill for custom terminations, rotational torque, number of positions, shaft configurations, and resolutions.