



DLP7000 DLP® 0.7 XGA 2x LVDS Type A DMD

1 Features

- 0.7-Inch Diagonal Micromirror Array
 - 1024 × 768 Array of Aluminum, Micrometer-Sized Mirrors
 - 13.68-μm Micromirror Pitch
 - ±12° Micromirror Tilt Angle (Relative to Flat State)
 - Designed for Corner Illumination
- Designed for Use with Broadband Visible Light (400 to 700 nm):
 - Window Transmission 97% (Single Pass, Through Two Window Surfaces)
 - Micromirror Reflectivity 88%
 - Array Diffraction Efficiency 86%
 - Array Fill Factor 92%
- Two 16-Bit, Low Voltage Differential Signaling (LVDS) Double Data Rate (DDR) Input Data Buses
- Up to 400 MHz Input Data Clock Rate
- 40.64-mm by 31.75-mm by 6.0-mm Package Footprint
- Hermetic Package

2 Applications

- Industrial
 - Digital Imaging Lithography
 - Laser Marking
 - LCD and OLED Repair
 - Computer-to-Plate Printers
 - SLA 3D Printers
 - 3D Scanners for Machine Vision and Factory Automation
 - Flat Panel Lithography
- Medical
 - Phototherapy Devices
 - Ophthalmology
 - Direct Manufacturing
 - Hyperspectral Imaging
 - 3D Biometrics
 - Confocal Microscopes
- Display
 - 3D Imaging Microscopes
 - Adaptive Illumination
 - Augmented Reality and Information Overlay

3 Description

The DLP7000 XGA Chipset is part of the DLP® Discovery™ 4100 platform, which enables high resolution and high performance spatial light modulation. The DLP7000 is the digital micromirror device (DMD) fundamental to the 0.7 XGA chipset, and currently supports the fastest pattern rates in the DLP catalog portfolio. The DLP Discovery 4100 platform also provides the highest level of individual micromirror control with the option for random row addressing. Combined with a hermetic package, the unique capability and value offered by DLP7000 makes it well suited to support a wide variety of industrial, medical, and advanced display applications.

In addition to the DLP7000 DMD, the 0.7 XGA Chipset includes these components:

- Dedicated DLPC410 controller for high speed pattern rates of >32000 Hz (1-bit binary) and >1900 Hz (8-bit gray)
- One unit DLPR410 (DLP Discovery 4100 Configuration PROM)
- One unit DLPA200 (DMD Micromirror Driver)

Device Information⁽¹⁾

| PART NUMBER | PACKAGE | BODY SIZE (NOM) |
|-------------|------------|---------------------|
| DLP7000 | LCCC (203) | 40.64 mm × 31.75 mm |

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

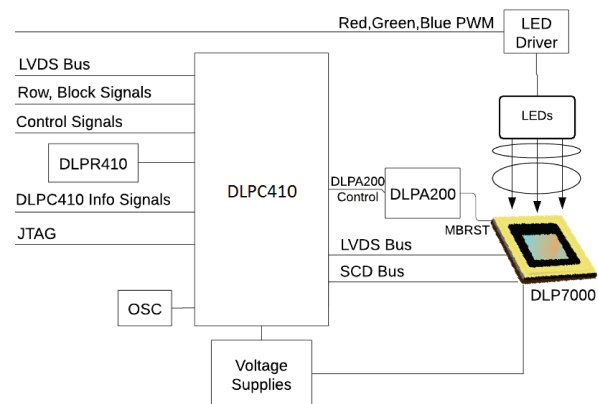


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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| Changes from Revision D (November 2015) to Revision E | Page |
|--|------|
| • Clarified T_{GRADIENT} footnote | 11 |
| • Changed T_{stg} to T_{DMD} | 11 |
| • Changed Environmental sections of Recommended Operating Conditions table - Simplified to one Environmental section with Illumination power densities in a single group | 12 |
| • Changed 400 to 420 nm illumination power density max from 2.5 to 11 W/cm ² and added 16.2 W max optical power in Recommended Operating Conditions | 12 |
| • Collapsed Operating case temperature points 1 & 2 with point 3 & array to one entry - identical specifications in Recommended Operating Conditions | 12 |
| • Changed TC2 to TP1 to follow latest thermal test point nomenclature convention in Thermal Information | 13 |
| • Changed Micromirror active border from 10 to correct value of 6 | 19 |
| • Changed micromirror crossover to mean transition time and renamed previous crossover to micromirror switching time typical micromirror crossover time typ (16 μ s to 13 μ s) | 20 |
| • Added typical micromirror switching time - 13 μ s | 20 |
| • Changed "Micromirror switching time" to "Array switching time" for clarity | 20 |
| • Added clarification to Micromirror switching time at 400 MHz with global reset | 20 |
| • Changed references to D4100 Discovery to DPC410 | 22 |
| • Changed Thermal Test Point Location drawing to current numbering convention | 34 |
| • Updated Figure 22 | 44 |
| • Removed link to DLP Discovery 4100 chipset datasheet | 44 |
| • Added DLPR410 to Related Links table | 45 |

| Changes from Revision C (April 2014) to Revision D | Page |
|---|--------------------|
| • Updated Figure 21 | 44 |
| • Updated Figure 22 | 44 |

| Changes from Revision B (June 2013) to Revision C | Page |
|---|--------------------|
| • Added <i>Pin Configuration and Functions</i> section, <i>ESD Rating</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i> , <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section | 1 |
| • Deleted / DLPR4101 Enhanced PROM from Chipset List | 1 |
| • Corrected VCC2 max to 8 V | 11 |
| • Added array temperature vs duty cycle graph..... | 13 |
| • Replaced serial communications bus timing parameters | 17 |
| • Converted interface loads to Newtons..... | 18 |
| • Grayed out LVDS buses that are unused on DLP7000 | 26 |
| • Added micromirror landed duty cycle section..... | 35 |
| • Changed to DLP7000 | 38 |
| • Deleted / DLPR4101 Enhanced PROM from Related Documentation..... | 45 |

| Changes from Revision A (September 2012) to Revision B | Page |
|--|--------------------|
| • Added / DLPR4101 Enhanced PROM to DLPR410 in Chipset List | 1 |
| • Changed pin number of DCLK_AN From: D19 To: B22 | 8 |
| • Changed pin number of DCLK_AP From: E19 To: B24 | 8 |
| • Changed pin number of DCLK_BN From: M19 To: AB22 | 8 |
| • Changed pin number of DCLK_BP From: N19 To: AB24 | 8 |
| • Added / DLPR4101 Enhanced PROM to DLPR410 in Related Documentation | 45 |

| Changes from Original (August 2012) to Revision A | Page |
|---|-------------------|
| • Changed the device from 'Product Preview' to 'Production' | 1 |

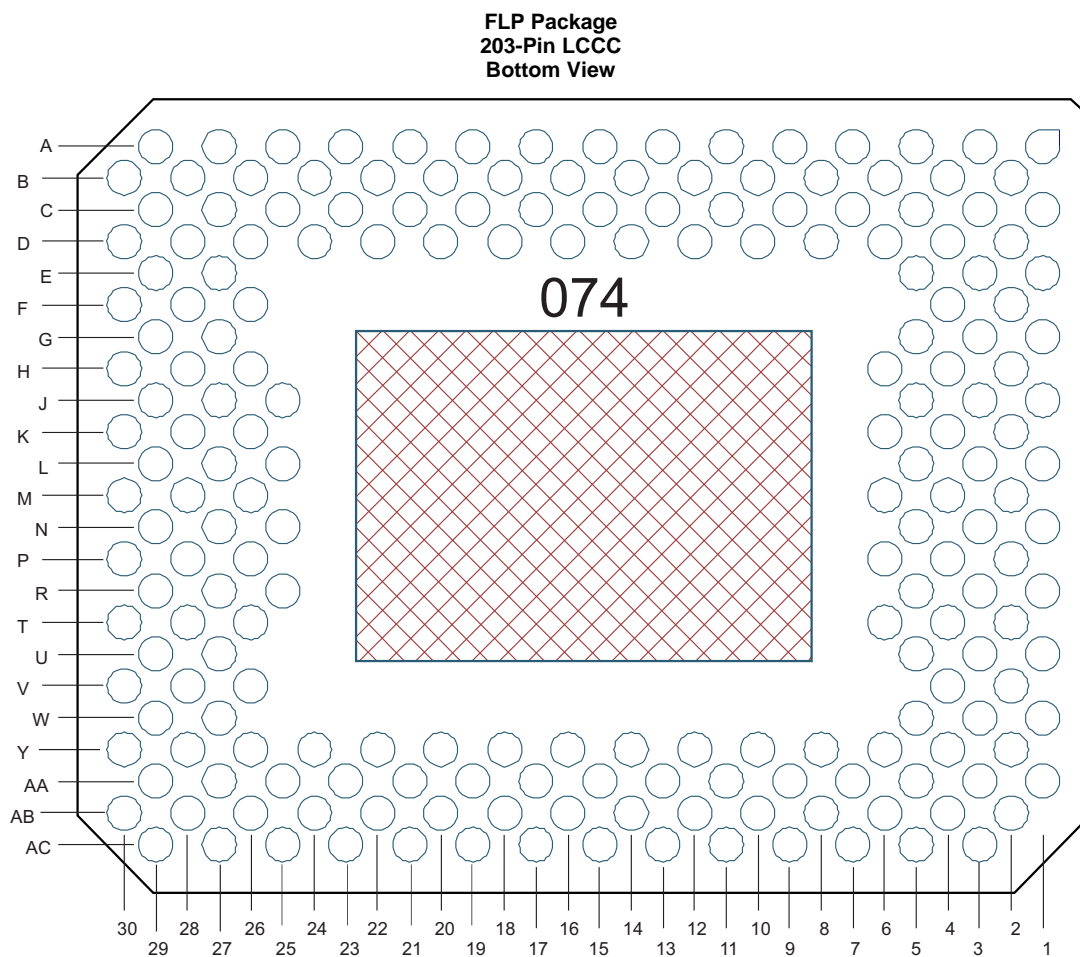
5 Description (continued)

Reliable function and operation of the DLP7000 requires that it be used in conjunction with the other components of the chipset. A dedicated chipset provides developers easier access to the DMD as well as high speed, independent micromirror control.

DLP7000 is a digitally controlled micro-electromechanical system (MEMS) spatial light modulator (SLM). When coupled to an appropriate optical system, the DLP7000 can be used to modulate the amplitude, direction, and/or phase of incoming light.

Electrically, the DLP7000 consists of a two-dimensional array of 1-bit CMOS memory cells, organized in a grid of 1024 memory cell columns by 768 memory cell rows. The CMOS memory array is addressed on a row-by-row basis, over two 16-bit low voltage differential signaling (LVDS) double data rate (DDR) buses. Addressing is handled via a serial control bus. The specific CMOS memory access protocol is handled by the DLPC410 digital controller.

6 Pin Configuration and Functions



Pin Functions

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|--------------------|-----|-----------------|---------|-----------------------------|---------------------------------|--------|-------------------------------|--------|
| NAME | NO. | | | | | | | |
| DATA INPUT | | | | | | | | |
| D_AN(0) | B10 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | Input data bus A (2x LVDS) | 368.72 |
| D_AN(1) | A13 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 424.61 |
| D_AN(2) | D16 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 433.87 |
| D_AN(3) | C17 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 391.39 |
| D_AN(4) | B18 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 438.57 |
| D_AN(5) | A17 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 391.13 |
| D_AN(6) | A25 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 563.26 |
| D_AN(7) | D22 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 411.62 |
| D_AN(8) | C29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 595.11 |
| D_AN(9) | D28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 543.07 |
| D_AN(10) | E27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 455.98 |
| D_AN(11) | F26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 359.5 |
| D_AN(12) | G29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 542.67 |
| D_AN(13) | H28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 551.51 |
| D_AN(14) | J27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 528.04 |
| D_AN(15) | K26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 484.38 |
| D_AP(0) | B12 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 366.99 |
| D_AP(1) | A11 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 417.47 |

(1) The following power supplies are required to operate the DMD: VCC, VCC1, VCC2. VSS must also be connected.

(2) DDR = Double Data Rate. SDR = Single Data Rate. Refer to the [LVDS Timing Requirements](#) for specifications and relationships.

(3) Refer to [Electrical Characteristics](#) for differential termination specification.

DLP7000

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Pin Functions (continued)

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|--------------------|------|-----------------|---------|-----------------------------|---------------------------------|--------|--|--------|
| NAME | NO. | | | | | | | |
| D_AP(2) | D14 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | Input data bus A - continued (2x LVDS) | 434.89 |
| D_AP(3) | C15 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 394.67 |
| D_AP(4) | B16 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 437.3 |
| D_AP(5) | A19 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 389.01 |
| D_AP(6) | A23 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 562.92 |
| D_AP(7) | D20 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 410.34 |
| D_AP(8) | A29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 594.61 |
| D_AP(9) | B28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 539.88 |
| D_AP(10) | C27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 456.78 |
| D_AP(11) | D26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 360.68 |
| D_AP(12) | F30 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 543.97 |
| D_AP(13) | H30 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 570.85 |
| D_AP(14) | J29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 527.18 |
| D_AP(15) | K28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 481.02 |
| D_BN(0) | AB10 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | Input data bus B (2x LVDS) | 368.72 |
| D_BN(1) | AC13 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 424.61 |
| D_BN(2) | Y16 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 433.87 |
| D_BN(3) | AA17 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 391.39 |
| D_BN(4) | AB18 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 438.57 |

Pin Functions (continued)

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|--------------------|------|-----------------|---------|-----------------------------|---------------------------------|--------|--|--------|
| NAME | NO. | | | | | | | |
| D_BN(5) | AC17 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | Input data bus B - continued (2x LVDS) | 391.13 |
| D_BN(6) | AC25 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 563.26 |
| D_BN(7) | Y22 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 411.62 |
| D_BN(8) | AA29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 595.11 |
| D_BN(9) | Y28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 543.07 |
| D_BN(10) | W27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 455.98 |
| D_BN(11) | V26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 360.94 |
| D_BN(12) | T30 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 575.85 |
| D_BN(13) | R29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 519.37 |
| D_BN(14) | R27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 532.59 |
| D_BN(15) | N27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 441.14 |
| D_BP(0) | AB12 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 366.99 |
| D_BP(1) | AC11 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 417.47 |
| D_BP(2) | Y14 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 434.89 |
| D_BP(3) | AA15 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 394.67 |
| D_BP(4) | AB16 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 437.3 |
| D_BP(5) | AC19 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 389.01 |
| D_BP(6) | AC23 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 562.92 |
| D_BP(7) | Y20 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 410.34 |

Pin Functions (continued)

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|--|------|-----------------|---------|-----------------------------|---------------------------------|--------|---|--------|
| NAME | NO. | | | | | | | |
| D_BP(8) | AC29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | Input data bus B - continued (2x LVDS) | 594.61 |
| D_BP(9) | AB28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 539.88 |
| D_BP(10) | AA27 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 456.78 |
| D_BP(11) | Y26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 360.68 |
| D_BP(12) | U29 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 578.46 |
| D_BP(13) | T28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 509.74 |
| D_BP(14) | P28 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 534.59 |
| D_BP(15) | P26 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 440 |
| DATA CLOCK | | | | | | | | |
| DCLK_AN | B22 | Input | LVC MOS | – | Differential Terminated - 100 Ω | – | DCLK for data bus A (2x LVDS) | 477.1 |
| DCLK_AP | B24 | Input | LVC MOS | – | Differential Terminated - 100 Ω | – | | 477.14 |
| DCLK_BN | AB22 | Input | LVC MOS | – | Differential Terminated - 100 Ω | – | DCLK for data bus B (2x LVDS) | 477.07 |
| DCLK_BP | AB24 | Input | LVC MOS | – | Differential Terminated - 100 Ω | – | | 477.14 |
| DATA CONTROL INPUTS | | | | | | | | |
| SCTRL_AN | C21 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | Serial control for data bus A (2x LVDS) | 477.07 |
| SCTRL_AP | C23 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_A | | 477.14 |
| SCTRL_BN | AA21 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | Serial control for data bus B (2x LVDS) | 477.07 |
| SCTRL_BP | AA23 | Input | LVC MOS | DDR | Differential Terminated - 100 Ω | DCLK_B | | 477.14 |
| SERIAL COMMUNICATION AND CONFIGURATION | | | | | | | | |
| SCPCLK | E3 | Input | LVC MOS | – | Pull-down | – | Serial port clock | 379.29 |
| SCPDO | B2 | Output | LVC MOS | – | – | SCPCLK | Serial port output | 480.91 |
| SCPDI | F4 | Input | LVC MOS | – | Pull-down | SCPCLK | Serial port input | 323.56 |
| SCPENZ | D4 | Input | LVC MOS | – | Pull-down | SCPCLK | Serial port enable | 326.99 |
| PWRDNZ | C3 | Input | LVC MOS | – | Pull-down | – | Device Reset | 406.28 |

Pin Functions (continued)

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|---------------------------------|--|-----------------|---------|-----------------------------|---------------------------------|-------|---|--------|
| NAME | NO. | | | | | | | |
| MODE_A | D8 | Input | LVC MOS | – | Pull-down | – | Data bandwidth mode select A | 396.05 |
| MODE_B | C11 | Input | LVC MOS | – | Pull-down | – | Data bandwidth mode select B | 208.86 |
| MICROMIRROR BIAS CLOCKING PULSE | | | | | | | | |
| MBRST(0) | P2 | Input | Analog | – | – | – | Micromirror Bias Clocking Pulse "MBRST" signals "clock" micromirrors into state of LVC MOS memory cell associated with each mirror. | |
| MBRST(1) | AB4 | Input | Analog | – | – | – | | |
| MBRST(2) | AA7 | Input | Analog | – | – | – | | |
| MBRST(3) | N3 | Input | Analog | – | – | – | | |
| MBRST(4) | M4 | Input | Analog | – | – | – | | |
| MBRST(5) | AB6 | Input | Analog | – | – | – | | |
| MBRST(6) | AA5 | Input | Analog | – | – | – | | |
| MBRST(7) | L3 | Input | Analog | – | – | – | | |
| MBRST(8) | Y6 | Input | Analog | – | – | – | | |
| MBRST(9) | K4 | Input | Analog | – | – | – | | |
| MBRST(10) | L5 | Input | Analog | – | – | – | | |
| MBRST(11) | AC5 | Input | Analog | – | – | – | | |
| MBRST(12) | Y8 | Input | Analog | – | – | – | | |
| MBRST(13) | J5 | Input | Analog | – | – | – | | |
| MBRST(14) | K6 | Input | Analog | – | – | – | | |
| MBRST(15) | AC7 | Input | Analog | – | – | – | | |
| POWER | | | | | | | | |
| V _{CC} | A7, A15, C1, E1, U1, W1, AB2, AC9, AC15 | Power | Analog | – | – | – | Power for LVC MOS Logic | – |
| V _{CC1} | A21, A27, D30, M30, Y30, AC21, AC27 | Power | Analog | – | – | – | Power supply for LVDS Interface | – |
| V _{CC2} | G1, J1, L1, N1, R1 | Power | Analog | – | – | – | Power for High Voltage CMOS Logic | – |

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Pin Functions (continued)

| PIN ⁽¹⁾ | | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE |
|---|--|-----------------|---------|-----------------------------|---------------------------------|-------|--|-------|
| NAME | NO. | | | | | | | |
| V _{SS} | A1, A3, A5, A9, B4, B8, B14, B20, B26, B30, C7, C13, C19, C25, D6, D12, D18, D24, E29, F2, F28, G3, G27, H2, H4, H26, J3, J25, K2, K30, L25, L27, L29, M2, M6, M26, M28, N5, N25, N29, P4, P30, R3, R5, R25, T2, T26, U27, V28, V30, W5, W29, Y4, Y12, Y18, Y24, AA3, AA9, AA13, AA19, AA25, AB8, AB14, AB20, AB26, AB30 | Power | Analog | – | – | – | Common return for all power inputs | – |
| RESERVED SIGNALS (NOT FOR USE IN SYSTEM) | | | | | | | | |
| RESERVED _AA1 | AA1 | Input | LVC MOS | – | Pull-down | – | Pins should be connected to VSS | – |
| RESERVED _B6 | B6 | Input | LVC MOS | – | Pull-down | – | – | – |
| RESERVED _T4 | T4 | Input | LVC MOS | – | Pull-down | – | – | – |
| RESERVED _U5 | U5 | Input | LVC MOS | – | Pull-down | – | – | – |
| NO_CONN ECT | AA11, AC3, C5, C9, D10, D2, E5, G5, H6, P6, T6, U3, V2, V4, W3, Y10, Y2 | – | – | – | – | – | Do not connect | – |

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | MIN | MAX | UNIT |
|------------------------------------|---|------|-----------------------|------|
| ELECTRICAL | | | | |
| V _{CC} | Voltage applied to V _{CC} ^{(2) (3)} | –0.5 | 4 | V |
| V _{CCI} | Voltage applied to V _{CCI} ^{(2) (3)} | –0.5 | 4 | V |
| V _{CC2} | Voltage applied to V _{VCC2} ^{(2) (3) (4)} | –0.5 | 8 | V |
| V _{MBRST} | Micromirror Clocking Pulse Waveform Voltage applied to MBRST[15:0] Input Pins (supplied by DLPA200) | –28 | 28 | V |
| V _{CC} – V _{CCI} | Supply voltage delta (absolute value) ⁽⁴⁾ | | 0.3 | V |
| | Voltage applied to all other input pins ⁽²⁾ | –0.5 | V _{CC} + 0.3 | V |
| V _{ID} | Maximum differential voltage, damage can occur to internal termination resistor if exceeded, see Figure 3 | | 700 | mV |
| I _{OH} | Current required from a high-level output V _{OH} = 2.4 V | | –20 | mA |
| I _{OL} | Current required from a low-level output V _{OL} = 0.4 V | | 15 | mA |
| ENVIRONMENTAL | | | | |
| T _C | Case temperature: operational ⁽⁵⁾ | 10 | 65 | °C |
| | Case temperature: non-operational ⁽⁵⁾ | –40 | 80 | °C |
| T _{GRADIENT} | Device temperature gradient - operational ⁽⁶⁾ | | 10 | °C |
| RH | Operating relative humidity (non-condensing) | 0 | 95 | %RH |

- (1) Stresses beyond those listed under [Absolute Maximum Ratings](#) may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under [Recommended Operating Conditions](#). Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages referenced to V_{SS} (ground).
- (3) V_{OFFSET} supply transients must fall within specified max voltages.
- (4) To prevent excess current, the supply voltage delta |V_{CC} – V_{CCI}| must be less than specified limit.
- (5) DMD Temperature is the worst-case of any test point shown in [Figure 18](#), or the active array as calculated by the [Micromirror Array Temperature Calculation](#).
- (6) As either measured, predicted, or both between any two points -- measured on the exterior of the package, or as predicted at any point inside the micromirror array cavity. Refer to [Thermal Information](#) and [Micromirror Array Temperature Calculation](#).

7.2 Storage Conditions

Applicable before the DMD is installed in the final product

| | | MIN | MAX | UNIT |
|------------------|----------------------------------|-----|-----|------|
| T _{DMD} | Storage temperature | –40 | 80 | °C |
| RH | Storage humidity, non-condensing | 0 | 95 | %RH |

7.3 ESD Ratings

| | | | | VALUE | UNIT |
|--------------------|-------------------------|---|-----------------------------|-------|------|
| V _(ESD) | Electrostatic discharge | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾ | All pins except MBRST[15:0] | ±2000 | V |
| | | | Pins MBRST[15:0] | ±250 | |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

7.4 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

| | | MIN | NOM | MAX | UNIT |
|---|--|------------------------------|-------|----------------------------------|--------------------|
| SUPPLY VOLTAGES ^{(2) (3)} | | | | | |
| V _{CC} | Supply voltage for LVCMOS core logic | 3 | 3.3 | 3.6 | V |
| V _{CCI} | Supply voltage for LVDS receivers | 3 | 3.3 | 3.6 | V |
| V _{CC2} | Mirror electrode and HVCMOS supply voltage | 7.25 | 7.5 | 7.75 | V |
| V _{MBRST} | Clocking Pulse Waveform Voltage applied to MBRST[29:0] Input Pins (supplied by DLPA200) | –27 | | 26.5 | V |
| V _{CC} – V _{CCI} | Supply voltage delta (absolute value) ⁽⁴⁾ | | | 0.3 | V |
| ENVIRONMENTAL ⁽⁵⁾ | | | | | |
| Illumination power density ⁽⁶⁾ | | <400 nm ⁽⁷⁾ | | 0.68 | mW/cm ² |
| | | 400 to 420 nm ⁽⁸⁾ | | 11 | W/cm ² |
| | | | | 16.2 | W |
| | | 420 to 700 nm | | Thermally limited ⁽⁸⁾ | W/cm ² |
| | | >700 nm | | 10 | mW/cm ² |
| T _C | Operating Case Temperature ⁽⁹⁾ : Thermal Test Points 1, 2, 3, and Array ⁽¹⁰⁾ | 10 | 25–45 | 65 ⁽¹⁰⁾ | °C |
| T _{GRADIENT} | Device temperature gradient – operational ⁽¹¹⁾ | | | 10 | °C |
| RH | Operating relative humidity (non-condensing) | 0 | | 95 | %RH |

- (1) The functional performance of the device specified in this data sheet is achieved when operating the device within the limits defined by the *Recommended Operating Conditions*. No level of performance is implied when operating the device above or below the *Recommended Operating Conditions* limits.
- (2) Supply voltages V_{CC}, V_{CC2}, V_{CCI}, V_{OFFSET}, V_{BIAS}, and V_{RESET} are all required for proper DMD operation. V_{SS} must also be connected.
- (3) All voltages are referenced to common ground V_{SS}.
- (4) To prevent excess current, the supply voltage delta |V_{CCI} – V_{CC}| must be less than the specified limit.
- (5) Optimal, long-term performance and optical efficiency of the digital micromirror device (DMD) can be affected by various application parameters, including illumination spectrum, illumination power density, micromirror landed duty-cycle (refer to [Figure 1](#)), ambient temperature (storage and operating), DMD temperature, ambient humidity (storage and operating), and power on or off duty cycle. TI recommends that application-specific effects be considered as early as possible in the design cycle.
- (6) Total integrated illumination power density, above or below the indicated wavelength threshold or in the indicated wavelength range.
- (7) The maximum operating conditions for operating temperature and illumination power density for wavelengths <400 nm should not be implemented simultaneously.
- (8) Also limited by the resulting micromirror array temperature. Refer to [Case Temperature](#) and [Micromirror Array Temperature Calculation](#) for information related to calculating the micromirror array temperature.
- (9) In some applications, the total DMD heat load can be dominated by the amount of incident light energy absorbed. See the [Thermal Information](#) for further details.
- (10) See the [Thermal Information](#) and the [Micromirror Array Temperature Calculation](#) for Thermal Test Point Locations, Package Thermal Resistance, and Device Temperature Calculation.
- (11) As either measured, predicted, or both between any two points -- measured on the exterior of the package, or as predicted at any point inside the micromirror array cavity. Refer to [Thermal Information](#) and [Micromirror Array Temperature Calculation](#).

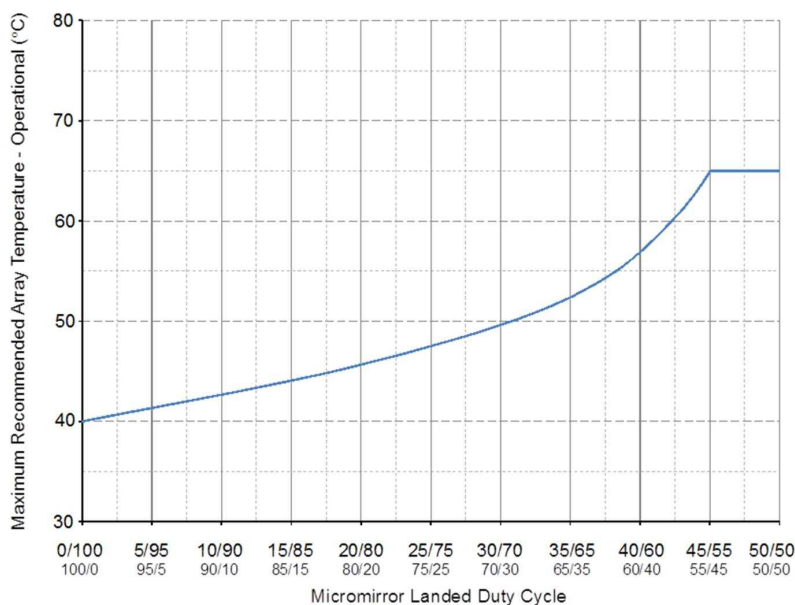


Figure 1. Max Recommended DMD Temperature – Derating Curve

7.5 Thermal Information

| THERMAL METRIC ⁽¹⁾ | DLP7000 | UNIT |
|--|------------|------|
| | FLP (LCCC) | |
| | 203 PINS | |
| Active micromirror array resistance to TP1 | 0.90 | °C/W |

- (1) The DMD is designed to conduct absorbed and dissipated heat to the back of the package where it can be removed by an appropriate heat sink. The heat sink and cooling system must be capable of maintaining the package within the temperature range specified in the [Recommended Operating Conditions](#). The total heat load on the DMD is largely driven by the incident light absorbed by the active area; although other contributions include light energy absorbed by the window aperture and electrical power dissipation of the array. Optical systems should be designed to minimize the light energy falling outside the window clear aperture since any additional thermal load in this area can significantly degrade the reliability of the device.

DLP7000

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7.6 Electrical Characteristics

over the range of recommended supply voltage and recommended case operating temperature (unless otherwise noted).

| PARAMETERS | | TEST CONDITIONS | MIN | NOM | MAX | UNIT |
|-------------|---|---|------|-----|---------------|---------------|
| V_{OH} | High-level output voltage ⁽¹⁾ , See Figure 11 | $V_{CC} = 3.0\text{ V}$, $I_{OH} = -20\text{ mA}$ | 2.4 | | | V |
| V_{OL} | Low-level output voltage ⁽¹⁾ , See Figure 11 | $V_{CC} = 3.6\text{ V}$, $I_{OH} = 15\text{ mA}$ | | | 0.4 | V |
| V_{MBRST} | Clocking Pulse Waveform applied to MBRST[29:0] Input Pins (supplied by DLPA200) | | -27 | | 26.5 | V |
| I_{OZ} | High impedance output current ⁽¹⁾ | $V_{CC} = 3.6\text{ V}$ | | | 10 | μA |
| I_{OH} | High-level output current ⁽¹⁾ | $V_{OH} = 2.4\text{ V}$, $V_{CC} \geq 3\text{ V}$ | | | -20 | mA |
| | | $V_{OH} = 1.7\text{ V}$, $V_{CC} \geq 2.25\text{ V}$ | | | -15 | |
| I_{OL} | Low-level output current ⁽¹⁾ | $V_{OL} = 0.4\text{ V}$, $V_{CC} \geq 3\text{ V}$ | | | 15 | mA |
| | | $V_{OL} = 0.4\text{ V}$, $V_{CC} \geq 2.25\text{ V}$ | | | 14 | |
| V_{IH} | High-level input voltage ⁽¹⁾ | | 1.7 | | $V_{CC} + .3$ | V |
| V_{IL} | Low-level input voltage ⁽¹⁾ | | -0.3 | | 0.7 | V |
| I_{IL} | Low-level input current ⁽¹⁾ | $V_{CC} = 3.6\text{ V}$, $V_I = 0\text{ V}$ | | | -60 | μA |
| I_{IH} | High-level input current ⁽¹⁾ | $V_{CC} = 3.6\text{ V}$, $V_I = V_{CC}$ | | | 200 | μA |
| I_{CC} | Current into V_{CC} pin | $V_{CC} = 3.6\text{ V}$ | | | 1475 | mA |
| I_{CCI} | Current into V_{CCI} pin ⁽²⁾ | $V_{CCI} = 3.6\text{ V}$ | | | 450 | mA |
| I_{CC2} | Current into V_{CC2} pin | $V_{CC2} = 8.75\text{ V}$ | | | 25 | mA |
| Z_{IN} | Internal Differential Impedance | | 95 | | 105 | Ω |
| Z_{LINE} | Line Differential Impedance (PWB, Trace) | | 90 | 100 | 110 | Ω |
| C_I | Input capacitance ⁽¹⁾ | $f = 1\text{ MHz}$ | | | 10 | pF |
| C_O | Output capacitance ⁽¹⁾ | $f = 1\text{ MHz}$ | | | 10 | pF |
| C_{IM} | Input capacitance for MBRST[29:0] pins | $f = 1\text{ MHz}$ | 220 | | 270 | pF |

(1) Applies to LVCMOS pins only.

(2) Exceeding the maximum allowable absolute voltage difference between V_{CC} and V_{CCI} may result in excess current draw. See the [Absolute Maximum Ratings](#) for details.

7.7 LVDS Timing Requirements

over operating free-air temperature range (unless otherwise noted). See [Figure 2](#)

| | | MIN | NOM | MAX | UNIT |
|--------------|---|-------|------|------|------|
| $f_{DCLK_}$ | DCLK_ _* clock frequency {where * = [A, or B]} | 200 | | 400 | MHz |
| t_c | Clock Cycle - DCLK_ _* | 2.5 | | | ns |
| t_w | Pulse Width - DCLK_ _* | | 1.25 | | ns |
| t_s | Setup Time - D_ _* [15:0] and SCTRL_ _* before DCLK_ _* | 0.35 | | | ns |
| t_h | Hold Time, D_ _* [15:0] and SCTRL_ _* after DCLK_ _* | 0.35 | | | ns |
| t_{skew} | Skew between bus A and B | -1.25 | | 1.25 | ns |

7.8 LVDS Waveform Requirements

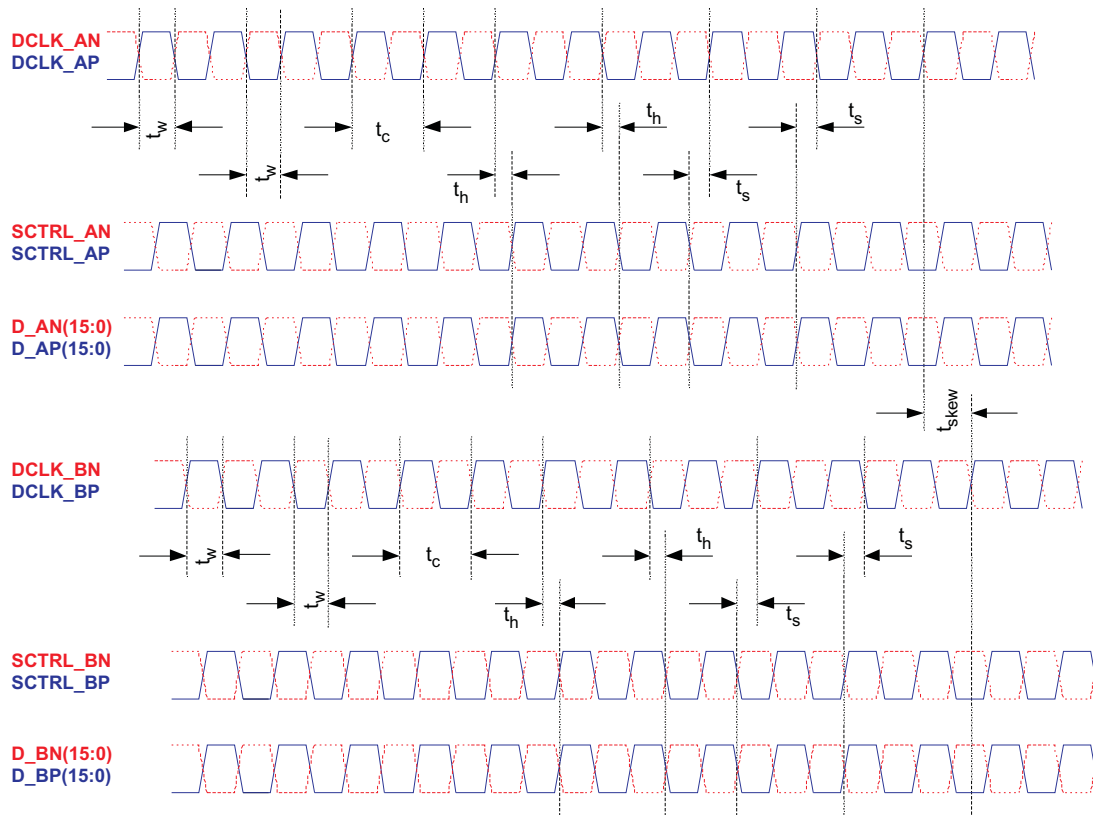
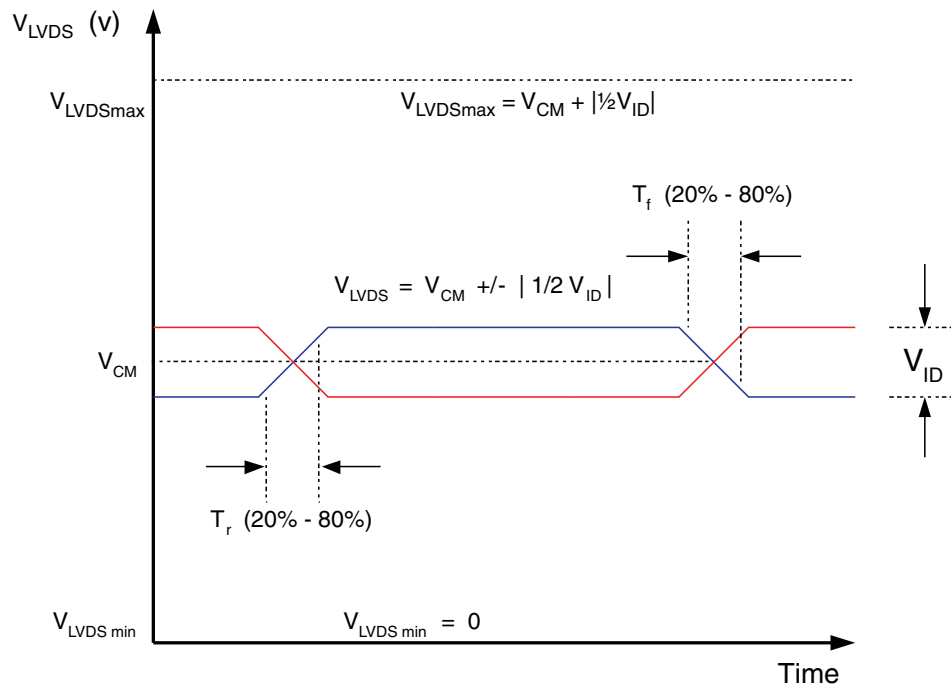
over operating free-air temperature range (unless otherwise noted). See [Figure 3](#)

| | | MIN | NOM | MAX | UNIT |
|------------|--|-----|------|------|------|
| $ V_{ID} $ | Input Differential Voltage (absolute difference) | 100 | 400 | 600 | mV |
| V_{CM} | Common Mode Voltage | | 1200 | | mV |
| V_{LVDS} | LVDS Voltage | 0 | | 2000 | mV |
| t_r | Rise Time (20% to 80%) | 100 | | 400 | ps |
| t_f | Fall Time (80% to 20%) | 100 | | 400 | ps |

7.9 Serial Control Bus Timing Requirements

over operating free-air temperature range (unless otherwise noted). See [Figure 4](#) and [Figure 5](#)

| | | MIN | NOM | MAX | UNIT |
|------------------|--|------|-----|-----|------|
| f_{SCP_CLK} | SCP Clock Frequency | 50 | | 500 | kHz |
| t_{SCP_SKEW} | Time between valid SCP_DI and rising edge of SCP_CLK | -300 | | 300 | ns |
| t_{SCP_DELAY} | Time between valid SCP_DO and rising edge of SCP_CLK | | | 960 | ns |
| t_{SCP_EN} | Time between falling edge of SCP_EN and the first rising edge of SCP_CLK | 30 | | | ns |
| t_{SCP} | Rise time for SCP signals | | | 200 | ns |
| t_{f_SCP} | Fall time for SCP signals | | | 200 | ns |


Figure 2. LVDS Timing Waveforms

Figure 3. LVDS Waveform Requirements

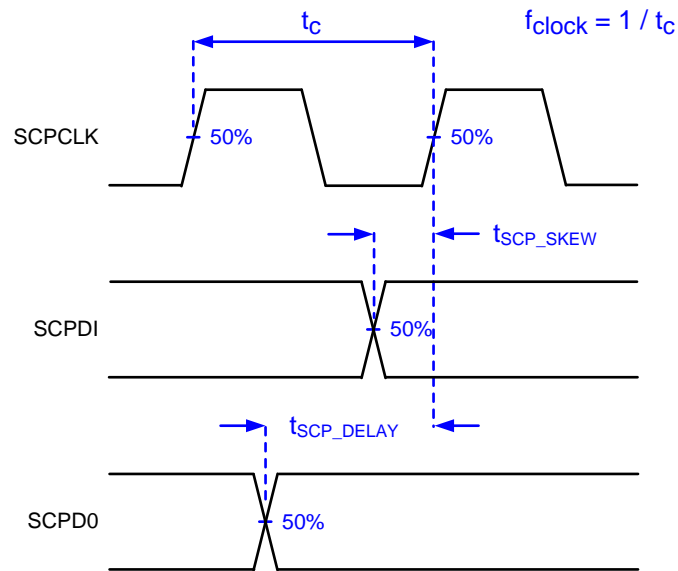


Figure 4. Serial Communications Bus Timing Parameters

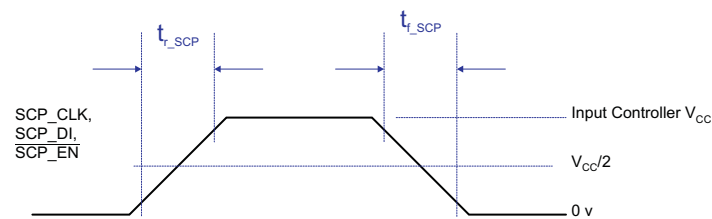


Figure 5. Serial Communications Bus Waveform Requirements

7.10 Systems Mounting Interface Loads

| | | | MIN | NOM | MAX | UNIT |
|--|---|----------------|-----|-----|-----|------|
| Maximum system mounting interface load to be applied to the: | Thermal Interface area | (See Figure 6) | | | 111 | N |
| | Electrical Interface area | | | | 423 | N |
| | Datum "A" Interface area ⁽¹⁾ | | | | 400 | N |

(1) Combined loads of the thermal and electrical interface areas in excess of Datum "A" load shall be evenly distributed outside the Datum "A" area ($425 + 111 - \text{Datum "A"}$).

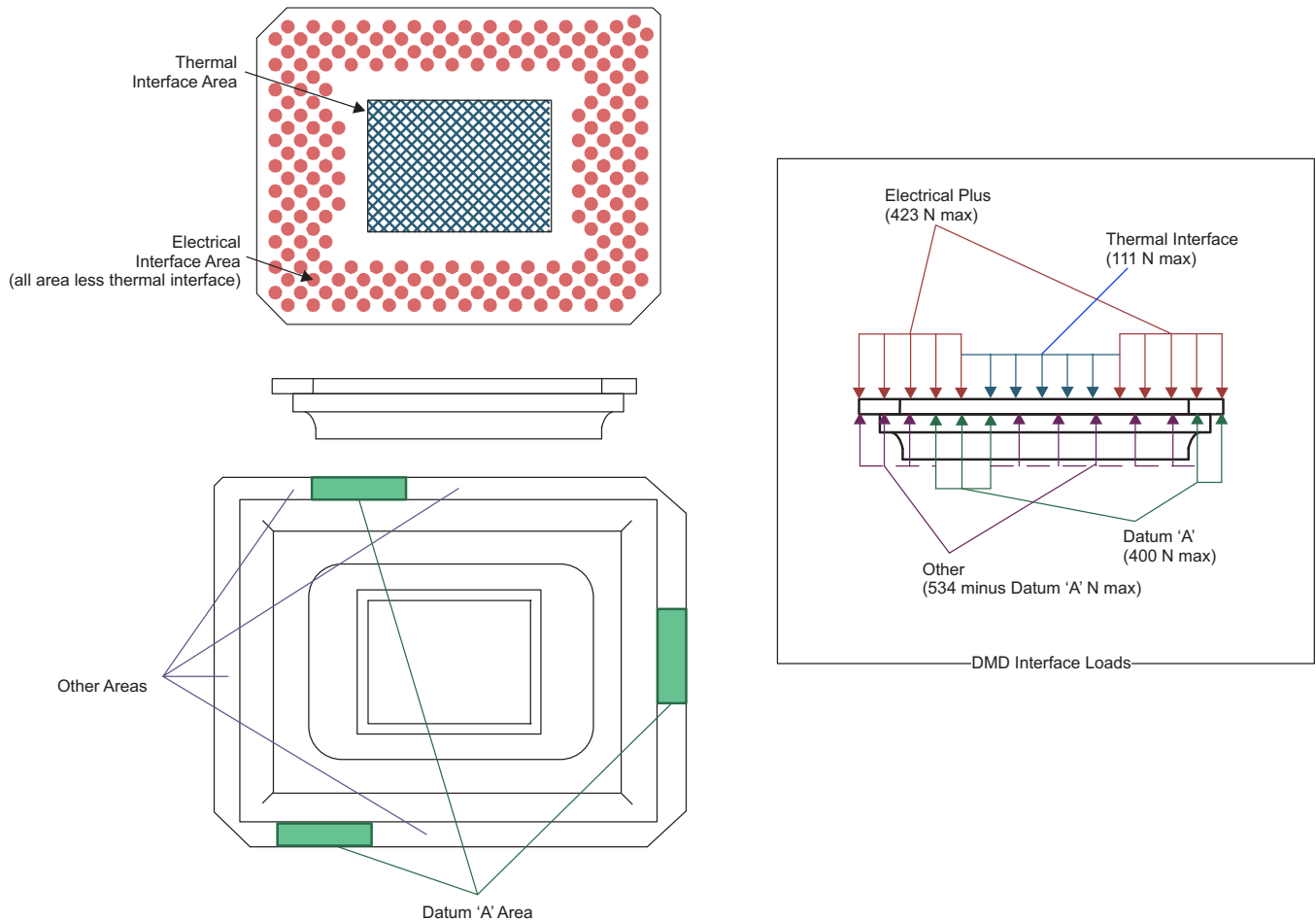
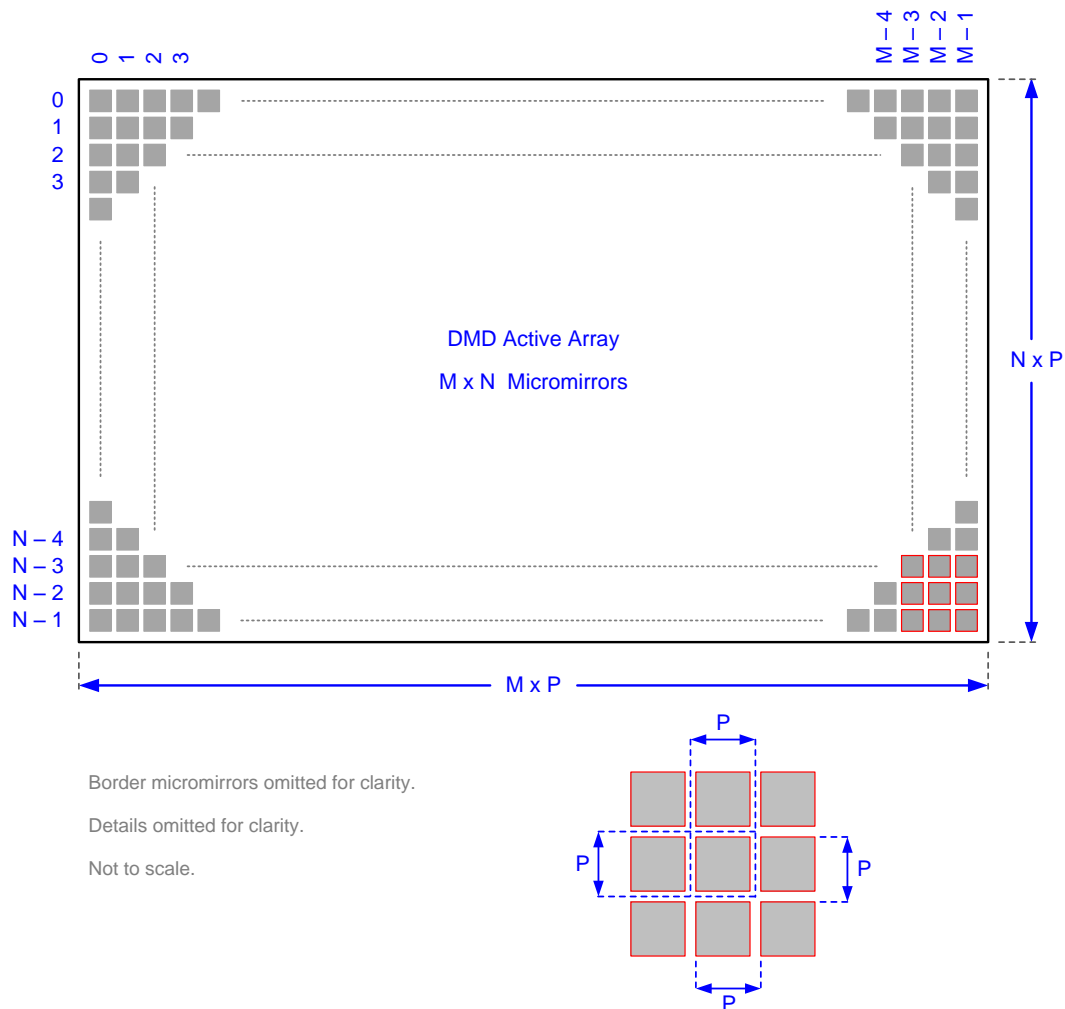


Figure 6. System Interface Loads

7.11 Micromirror Array Physical Characteristics

| PARAMETER | | | | VALUE | UNIT |
|-----------|---------------------------------|--|--------------|--------|-------------------|
| M | Number of active columns | | See Figure 7 | 1024 | micromirrors |
| N | Number of active rows | | | 768 | micromirrors |
| P | Micromirror (pixel) pitch | | | 13.68 | μm |
| | Micromirror active array width | M × P | | 14.008 | mm |
| | Micromirror active array height | N × P | | 10.506 | mm |
| | Micromirror active border | Pond of micromirror (POM) ⁽¹⁾ | | 6 | micromirrors/side |

- (1) The structure and qualities of the border around the active array includes a band of partially functional micromirrors called the POM. These micromirrors are structurally and/or electrically prevented from tilting toward the bright or ON state, but still require an electrical bias to tilt toward OFF.



Refer to [Micromirror Array Physical Characteristics](#) table for M, N, and P specifications.

Figure 7. Micromirror Array Physical Characteristics

7.12 Micromirror Array Optical Characteristics

TI assumes no responsibility for end-equipment optical performance. Achieving the desired end-equipment optical performance involves making trade-offs between numerous component and system design parameters.

| PARAMETER | CONDITIONS | MIN | NOM | MAX | UNIT |
|---|---|-----|-----|-----|--------------|
| a Micromirror tilt angle | DMD “parked” state ^{(1) (2) (3)} , see Figure 13 | | 0 | | degrees |
| | DMD “landed” state ^{(1) (4) (5)} see Figure 13 | | 12 | | |
| β Micromirror tilt angle tolerance ^{(1) (4) (6) (7) (8)} | See Figure 13 | –1 | | 1 | degrees |
| Micromirror crossover time ⁽⁹⁾ | | | 4 | | μ s |
| Micromirror switching time ⁽¹⁰⁾ | | | 13 | 22 | μ s |
| Array switching time at 400 MHz with global reset ⁽¹¹⁾ | | 43 | | | μ s |
| Non-operating micromirrors ⁽¹²⁾ | Non-adjacent micromirrors | | | 10 | micromirrors |
| | adjacent micromirrors | | | 0 | |
| Orientation of the micromirror axis-of-rotation ⁽¹³⁾ | See Figure 12 | 44 | 45 | 46 | degrees |
| Micromirror array optical efficiency ^{(14) (15)} | 400 nm to 700 nm, with all micromirrors in the ON state | | 68% | | |

- (1) Measured relative to the plane formed by the overall micromirror array.
- (2) “Parking” the micromirror array returns all of the micromirrors to an essentially flat (0°) state (as measured relative to the plane formed by the overall micromirror array).
- (3) When the micromirror array is “parked”, the tilt angle of each individual micromirror is uncontrolled.
- (4) Additional variation exists between the micromirror array and the package datums, as shown in the [Mechanical, Packaging, and Orderable Information](#).
- (5) When the micromirror array is “landed”, the tilt angle of each individual micromirror is dictated by the binary contents of the CMOS memory cell associated with each individual micromirror. A binary value of “1” will result in a micromirror “landing” in an nominal angular position of “+12°”. A binary value of 0 results in a micromirror “landing” in an nominal angular position of “–12°”.
- (6) Represents the “landed” tilt angle variation relative to the Nominal “landed” tilt angle.
- (7) Represents the variation that can occur between any two individual micromirrors, located on the same device or located on different devices.
- (8) For some applications, it is critical to account for the micromirror tilt angle variation in the overall System Optical Design. With some System Optical Designs, the micromirror tilt angle variation within a device may result in perceivable non-uniformities in the light field reflected from the micromirror array. With some System Optical Designs, the micromirror tilt angle variation between devices may result in colorimetry variations and/or system contrast variations.
- (9) Micromirror crossover time is primarily a function of the natural response time of the micromirrors and is the time it takes for the micromirror to crossover to the other state, but does not include mechanical settling time.
- (10) Micromirror switching time is the time before a micromirror may be addressed again. Crossover time plus mechanical settling time.
- (11) Array switching is controlled and coordinated by the DLPC410 ([DLPS024](#)) and DLP4200 ([DLPS015](#)). Nominal Switching time depends on the system implementation and represents the time for the entire micromirror array to be refreshed (array loaded plus reset and mirror settling time).
- (12) Non-operating micromirror is defined as a micromirror that is unable to transition nominally from the –12° position to +12° or vice versa.
- (13) Measured relative to the package datums “B” and “C”, shown in [Mechanical, Packaging, and Orderable Information](#).
- (14) The minimum or maximum DMD optical efficiency observed depends on numerous application-specific design variables, such as:
 - Illumination wavelength, bandwidth/line-width, degree of coherence
 - Illumination angle, plus angle tolerance
 - Illumination and projection aperture size, and location in the system optical path
 - Illumination overfill of the DMD micromirror array
 - Aberrations present in the illumination source and/or path
 - Aberrations present in the projection path

The specified nominal DMD optical efficiency is based on the following use conditions:

- Visible illumination (400 nm – 700 nm)
- Input illumination optical axis oriented at 24° relative to the window normal
- Projection optical axis oriented at 0° relative to the window normal
- f/3.0 illumination aperture
- f/2.4 projection aperture

Based on these use conditions, the nominal DMD optical efficiency results from the following four components:

- Micromirror array fill factor: nominally 92%
- Micromirror array diffraction efficiency: nominally 86%
- Micromirror surface reflectivity: nominally 88%
- Window transmission: nominally 97% (single pass, through two surface transitions)

- (15) Does not account for the effect of micromirror switching duty cycle, which is application dependent. Micromirror switching duty cycle represents the percentage of time that the micromirror is actually reflecting light from the optical illumination path to the optical projection path. This duty cycle depends on the illumination aperture size, the projection aperture size, and the micromirror array update rate.

7.13 Window Characteristics

| PARAMETER ⁽¹⁾ | CONDITIONS | MIN | TYP | MAX | UNIT |
|--|--|-----|-------|-----|---------|
| Window material designation | Corning 7056 | | | | |
| Window refractive index | at wavelength 589 nm | | 1.487 | | |
| Window flatness ⁽²⁾ | Per 25 mm | | | 4 | fringes |
| Window artifact size | Within the Window Aperture ⁽³⁾ | | | 400 | μm |
| Window aperture | See ⁽⁴⁾ | | | | |
| Illumination overfill | Refer to Illumination Overfill | | | | |
| Window transmittance, single-pass through both surfaces and glass ⁽⁵⁾ | At wavelength 405 nm. Applies to 0° and 24° AOI only. | 95% | | | |
| | Minimum within the wavelength range 420 nm to 680 nm. Applies to all angles 0° to 30° AOI. | 97% | | | |
| | Average over the wavelength range 420 nm to 680 nm. Applies to all angles 30° to 45° AOI. | 97% | | | |

(1) See [Window Characteristics and Optics](#) for more information.

(2) At a wavelength of 632.8 nm.

(3) See the [Mechanical, Packaging, and Orderable Information](#) section at the end of this document for details regarding the size and location of the window aperture.

(4) For details regarding the size and location of the window aperture, see the package mechanical characteristics listed in the Mechanical ICD in the [Mechanical, Packaging, and Orderable Information](#).

(5) See the TI application report [DLPA031](#), *Wavelength Transmittance Considerations for DLP DMD Window*.

7.14 Chipset Component Usage Specification

The DLP7000 is a component of one or more DLP chipsets. Reliable function and operation of the DLP7000 requires that it be used in conjunction with the other components of the applicable DLP chipset, including those components that contain or implement TI DMD control technology. TI DMD control technology is the TI technology and devices for operating or controlling a DLP DMD.

8 Detailed Description

8.1 Overview

Optically, the DLP7000 consists of 786,432 highly reflective, digitally switchable, micrometer-sized mirrors ("micromirrors"), organized in a two-dimensional array of 1024 micromirror columns by 768 micromirror rows (Figure 12). Each aluminum micromirror is approximately 13.68 microns in size (see the "Micromirror Pitch" in Figure 12), and is switchable between two discrete angular positions: -12° and $+12^\circ$. The angular positions are measured relative to a 0° "flat state", which is parallel to the array plane (see Figure 13). The tilt direction is perpendicular to the hinge-axis which is positioned diagonally relative to the overall array. The "On State" landed position is directed towards "Row 0, Column 0" (upper left) corner of the device package (see the "Micromirror Hinge-Axis Orientation" in Figure 12). In the field of visual displays, the 1024 by 768 "pixel" resolution is referred to as "XGA".

Each individual micromirror is positioned over a corresponding CMOS memory cell. The angular position of a specific micromirror is determined by the binary state (logic 0 or 1) of the corresponding CMOS memory cell contents, after the micromirror "clocking pulse" is applied. The angular position (-12° or $+12^\circ$) of the individual micromirrors changes synchronously with a micromirror "clocking pulse", rather than being synchronous with the CMOS memory cell data update. Therefore, writing a logic 1 into a memory cell followed by a micromirror "clocking pulse" will result in the corresponding micromirror switching to a $+12^\circ$ position. Writing a logic 0 into a memory cell followed by a micromirror "clocking pulse" will result in the corresponding micromirror switching to a -12° position.

Updating the angular position of the micromirror array consists of two steps. First, updating the contents of the CMOS memory. Second, application of a Micromirror Clocking Pulse to all or a portion of the micromirror array (depending upon the configuration of the system). Micromirror Clocking Pulses are generated externally by a DLPA200, with application of the pulses being coordinated by the DLPC410 controller.

Around the perimeter of the 1024 by 768 array of micromirrors is a uniform band of "border" micromirrors. The border micromirrors are not user-addressable. The border micromirrors land in the -12° position once power has been applied to the device. There are 10 border micromirrors on each side of the 1024 by 768 active array.

Figure 8 shows a DLPC410 and DLP7000 Chipset Block Diagram. The DLPC410 and DLPA200 control and coordinate the data loading and micromirror switching for reliable DLP7000 operation. The DLPR410 is the programmed PROM required to properly configure the DLPC410 controller. For more information on the chipset components, see [Application and Implementation](#). For a typical system application using the DLPC410 chipset including the DLP7000, see Figure 19.

8.2 Functional Block Diagram

Figure 8 is a simplified system block diagram showing the use of the following components:

- DLPC410 – Xilinx [XC5VLX30] FPGA configured to provide high-speed DMD data and control, and DLPA200 timing and control
- DLPR410 – [XCF16PFGS48C] serial flash PROM contains startup configuration information (EEPROM)
- DLPA200 – DMD micromirror driver for the DLP7000 DMD
- DLP7000 – Spatial Light Modulator (DMD)

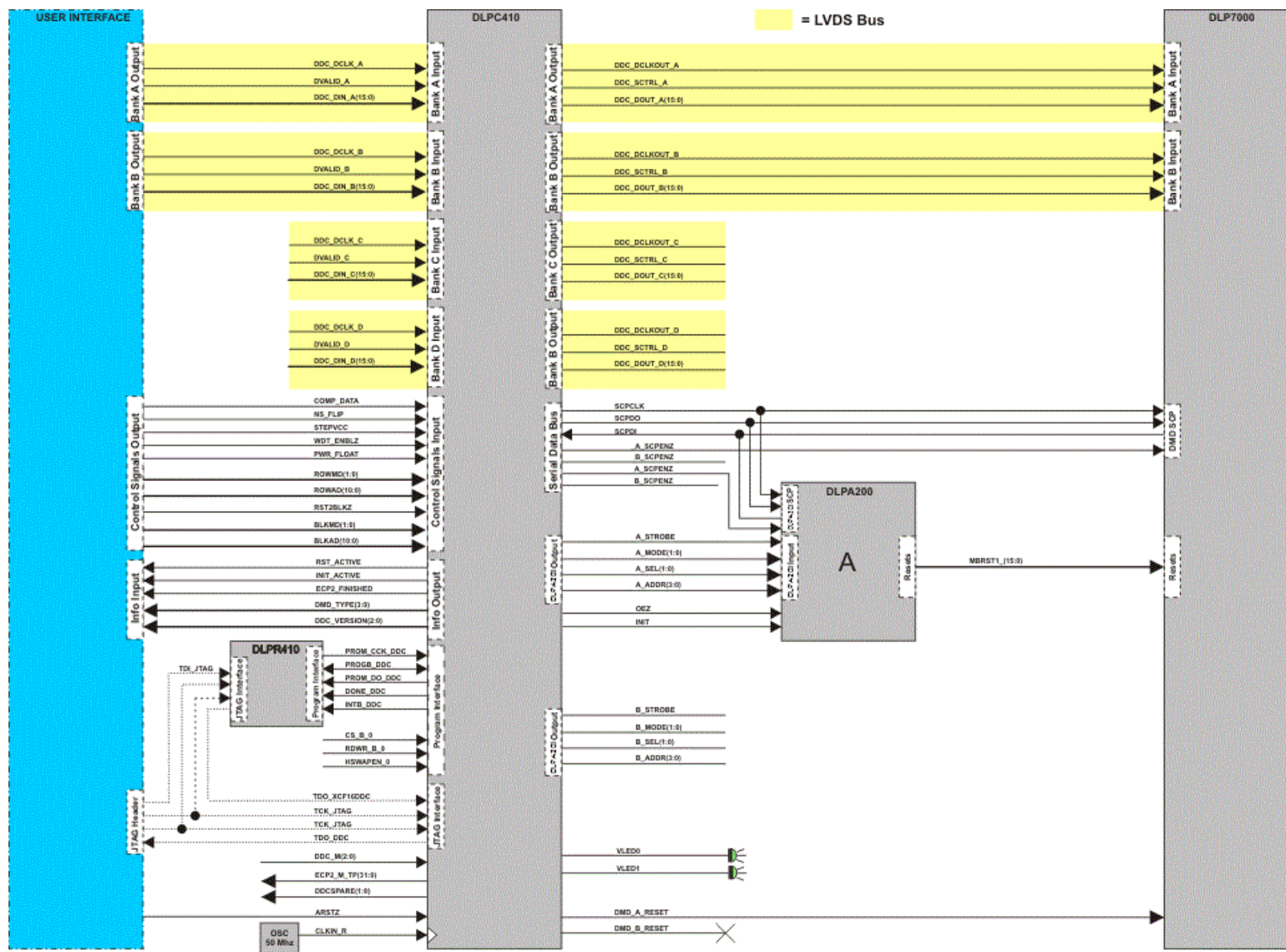


Figure 8. DLPC410 and DLP7000 Chipset Block Diagram

8.3 Feature Description

8.3.1 DLPC410 Chipset DMD Features

Table 1. DLP7000 Overview

| DMD | ARRAY | PATTERNS/s | DATA RATE (Gbps) | MIRROR PITCH |
|-------------------|------------|------------|------------------|--------------|
| DLP7000 - 0.7"XGA | 1024 × 768 | 32552 | 25.6 | 13.6 μm |

8.3.1.1 DLPC410 - Digital Controller for DLP Discovery 4100 Chipset

The DLP7000 chipset includes the DLPC410 controller which provides a high-speed LVDS data and control interface for DMD control. This interface is also connected to a second FPGA used to drive applications (not included in the chipset). The DLPC410 generates DMD and DLPA200 initialization and control signals in response to the inputs on the control interface.

For more information, see the DLPC410 data sheet [DLPS024](#).

8.3.1.2 DLPA200 - DMD Micromirror Driver

DLPA200 micromirror driver provides the micromirror clocking pulse driver functions for the DMD. One DLPA200 is required for DLP7000.

For more information on the DLPA200, see the DLPA200 data sheet [DLPS015](#).

8.3.1.3 DLPR410 - PROM for DLP Discovery 4100 Chipset

The DLPC410 is configured at startup from the serial flash PROM. The contents of this PROM can not be altered. For more information, see the DLPR410 data sheet ([DLPS027](#)) and the DLPC410 data sheet ([DLPS024](#)).

8.3.1.4 DLP7000 - DLP 0.7 XGA 2xLVDS Type-A DMD

8.3.1.4.1 DLP7000 XGA Chip Set Interfaces

This section will describe the interface between the different components included in the chipset. For more information on component interfacing, see [Application and Implementation](#).

8.3.1.4.1.1 DLPC410 Interface Description

8.3.1.4.1.1.1 DLPC410 IO

[Table 2](#) describes the inputs and outputs of the DLPC410 to the user. For more details on these signals, see the DLPC410 data sheet ([DLPS024](#)).

Table 2. Input/Output Description

| PIN NAME | DESCRIPTION | I/O |
|---------------------|--|-----|
| ARST | Asynchronous active low reset | I |
| CLKIN_R | Reference clock, 50 MHz | I |
| DIN_[A,B,C,D](15:0) | LVDS DDR input for data bus A,B,C,D (15:0) | I |
| DCLKIN[A,B,C,D] | LVDS inputs for data clock (200 - 400 MHz) on bus A, B, C, and D | I |
| DVALID[A,B,C,D] | LVDS input used to start write sequence for bus A, B, C, and D | I |
| ROWMD(1:0) | DMD row address and row counter control | I |
| ROWAD(10:0) | DMD row address pointer | I |
| BLK_AD(3:0) | DMD mirror block address pointer | I |
| BLK_MD(1:0) | DMD mirror block reset and clear command modes | I |
| PWR_FLOAT | Used to float DMD mirrors before complete loss of power | I |
| DMD_TYPE(3:0) | DMD type in use | O |
| RST_ACTIVE | Indicates DMD mirror reset in progress | O |
| INIT_ACTIVE | Initialization in progress. | O |

Table 2. Input/Output Description (continued)

| PIN NAME | DESCRIPTION | I/O |
|----------|---------------------------------|-----|
| VLED0 | System “heartbeat” signal | O |
| VLED1 | Denotes initialization complete | O |

8.3.1.4.1.1.2 Initialization

The *INIT_ACTIVE* (Table 2) signal indicates that the DLP7000, DLPA200, and DLPC410 are in an initialization state after power is applied. During this initialization period, the DLPC410 is initializing the DLP7000 and DLPA200 by setting all internal registers to their correct states. When this signal goes low, the system has completed initialization. System initialization takes approximately 220 ms to complete. Data and command write cycles should not be asserted during the initialization.

During initialization the user must send a training pattern to the DLPC410 on all data and DVALID lines to correctly align the data inputs to the data clock. For more information about the interface training pattern, see the DLPC410 data sheet (DLPS024).

8.3.1.4.1.1.3 DMD Device Detection

The DLPC410 automatically detects the DMD type and device ID. *DMD_TYPE* (Table 2) is an output from the DLPC410 that contains the DMD information. Only DMDs sold with the chipset or kit are recognized by the automatic detection function. All other DMDs do not operate with the DLPC410.

8.3.1.4.1.1.4 Power Down

To ensure long term reliability of the DLP7000, a shutdown procedure must be executed. Prior to power removal, assert the *PWR_FLOAT* (Table 2) signal and allow approximately 300 μs for the procedure to complete. This procedure assures the mirrors are in a flat state.

8.3.1.4.2 DLPC410 to DMD Interface

8.3.1.4.2.1 DLPC410 to DMD IO Description

Table 3 lists the available controls and status pin names and their corresponding signal type, along with a brief functional description.

Table 3. DLPC410 to DMD I/O Pin Descriptions

| PIN NAME | DESCRIPTION | I/O |
|--------------------------|--|-----|
| DDC_DOUT_[A,B,C,D](15:0) | LVDS DDR output to DMD data bus A,B,C,D (15:0) | O |
| DDC_DCLKOUT_[A,B,C,D] | LVDS output to DMD data clock A,B,C,D | O |
| DDC_SCTRL_[A,B,C,D] | LVDS DDR output to DMD data control A,B,C,D | O |

8.3.1.4.2.2 Data Flow

Figure 9 shows the data traffic through the DLPC410. Special considerations are necessary when laying out the DLPC410 to allow best signal flow.

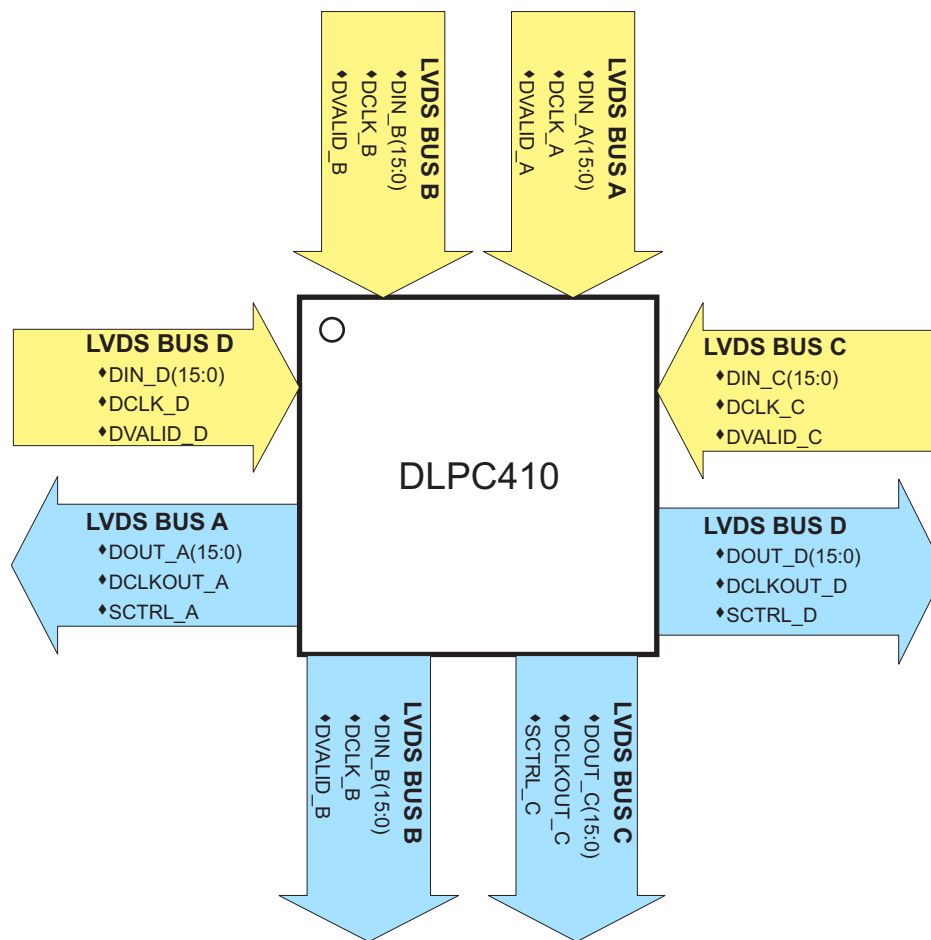


Figure 9. DLPC410 Data Flow

Two LVDS buses transfer the data from the user to the DLPC410. Each bus has its data clock that is input edge aligned with the data (DCLK). Each bus also has its own validation signal that qualifies the data input to the DLPC410 (DVALID).

Output LVDS buses transfer data from the DLPC410 to the DLP7000. Output buses LVDS A and LVDS B are used as highlighted in Figure 9.

8.3.1.4.3 DLPC410 to DLPA200 Interface

8.3.1.4.3.1 DLPA200 Operation

The DLPA200 DMD Micromirror Driver is a mixed-signal Application Specific Integrated Circuit (ASIC) that combines the necessary high-voltage power supply generation and Micromirror Clocking Pulse functions for a family of DMDs. The DLPA200 is programmable and controllable to meet all current and anticipated DMD requirements.

The DLPA200 operates from a 12-V power supply input. For more detailed information on the DLPA200, see the DLPA200 data sheet.

8.3.1.4.3.2 DLPC410 to DLPA200 IO Description

The Serial Communications Port (SCP) is a full duplex, synchronous, character-oriented (byte) port that allows exchange of commands from the DLPC410 to the DLPA200. One SCP bus is used for the DLP7000.

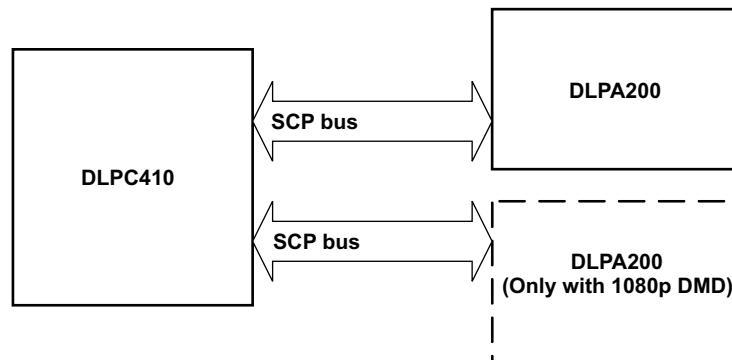


Figure 10. Serial Port System Configuration

There are five signal lines associated with the SCP bus: $\overline{\text{SCPEN}}$, SCPCK, SCPDI, SCPDO, and $\overline{\text{IRQ}}$.

Table 4 lists the available controls and status pin names and their corresponding signal type, along with a brief functional description.

Table 4. DLPC410 to DLPA200 I/O Pin Descriptions

| PIN NAME | DESCRIPTION | I/O |
|-------------|---|-----|
| A_SCPEN | Active low chip select for DLPA200 serial bus | O |
| A_STROBE | DLPA200 control signal strobe | O |
| A_MODE(1:0) | DLPA200 mode control | O |
| A_SEL(1:0) | DLPA200 select control | O |
| A_ADDR(3:0) | DLPA200 address control | O |
| B_SCPEN | Active low chip select for DLPA200 serial bus (2) | O |
| B_STROBE | DLPA200 control signal strobe (2) | O |
| B_MODE(1:0) | DLPA200 mode control | O |
| B_SEL(1:0) | DLPA200 select control | O |
| B_ADDR(3:0) | DLPA200 address control | O |

The DLPA200 provides a variety of output options to the DMD by selecting logic control inputs: MODE[1:0], SEL[1:0] and reset group address A[3:0] (Table 4). The MODE[1:0] input determines whether a single output, two outputs, four outputs, or all outputs, will be selected. Output levels (VBIAS, VOFFSET, or VRESET) are selected by SEL[1:0] pins. Selected outputs are tri-stated on the rising edge of the STROBE signal and latched to the selected voltage level after a break-before-make delay. Outputs will remain latched at the last Micromirror Clocking Pulse waveform level until the next Micromirror Clocking Pulse waveform cycle.

8.3.1.4.4 DLPA200 to DLP7000 Interface

8.3.1.4.4.1 DLPA200 to DLP7000 Interface Overview

The DLPA200 generates three voltages: VBIAS, VRESET, and VOFFSET that are supplied to the DMD MBRST lines in various sequences through the Micromirror Clocking Pulse driver function. VOFFSET is also supplied directly to the DMD as DMDVCC2. A fourth DMD power supply, DMDVCC, is supplied directly to the DMD by regulators.

The function of the Micromirror Clocking Pulse driver is to switch selected outputs in patterns between the three voltage levels (VBIAS, VRESET and VOFFSET) to generate one of several Micromirror Clocking Pulse waveforms. The order of these Micromirror Clocking Pulse waveform events is controlled externally by the logic control inputs and timed by the STROBE signal. DLPC410 automatically detects the DMD type and then uses the DMD type to determine the appropriate Micromirror Clocking Pulse waveform.

A direct Micromirror Clocking Pulse operation causes a mirror to transition directly from one latched state to the next. The address must already be set up on the mirror electrodes when the Micromirror Clocking Pulse is initiated. Where the desired mirror display period does not allow for time to set up the address, a Micromirror Clocking Pulse with release can be performed. This operation allows the mirror to go to a relaxed state regardless of the address while a new address is set up, after which the mirror can be driven to a new latched state.

A mirror in the relaxed state typically reflects light into a system collection aperture and can be thought of as “off” although the light is likely to be more than a mirror latched in the “off” state. System designers should carefully evaluate the impact of relaxed mirror conditions on optical performance.

8.3.1.5 Measurement Conditions

The data sheet provides timing at the device pin. For output timing analysis, the tester pin electronics and its transmission line effects must be taken into account. [Figure 11](#) shows an equivalent test load circuit for the output under test. The load capacitance value stated is only for characterization and measurement of AC timing signals. This load capacitance value does not indicate the maximum load the device is capable of driving. All rise and fall transition timing parameters are referenced to V_{IL} MAX and V_{IH} MIN for input clocks, V_{OL} MAX and V_{OH} MIN for output clocks.

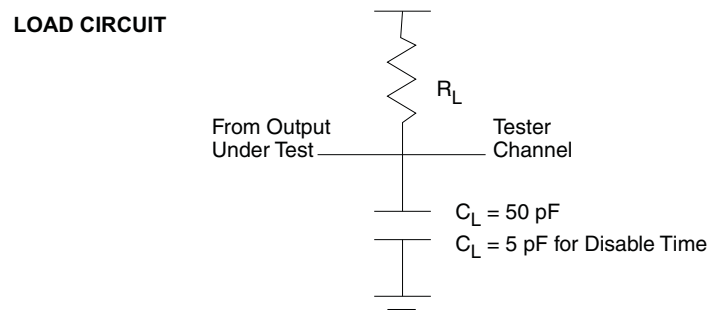


Figure 11. Test Load Circuit for AC Timing Measurements

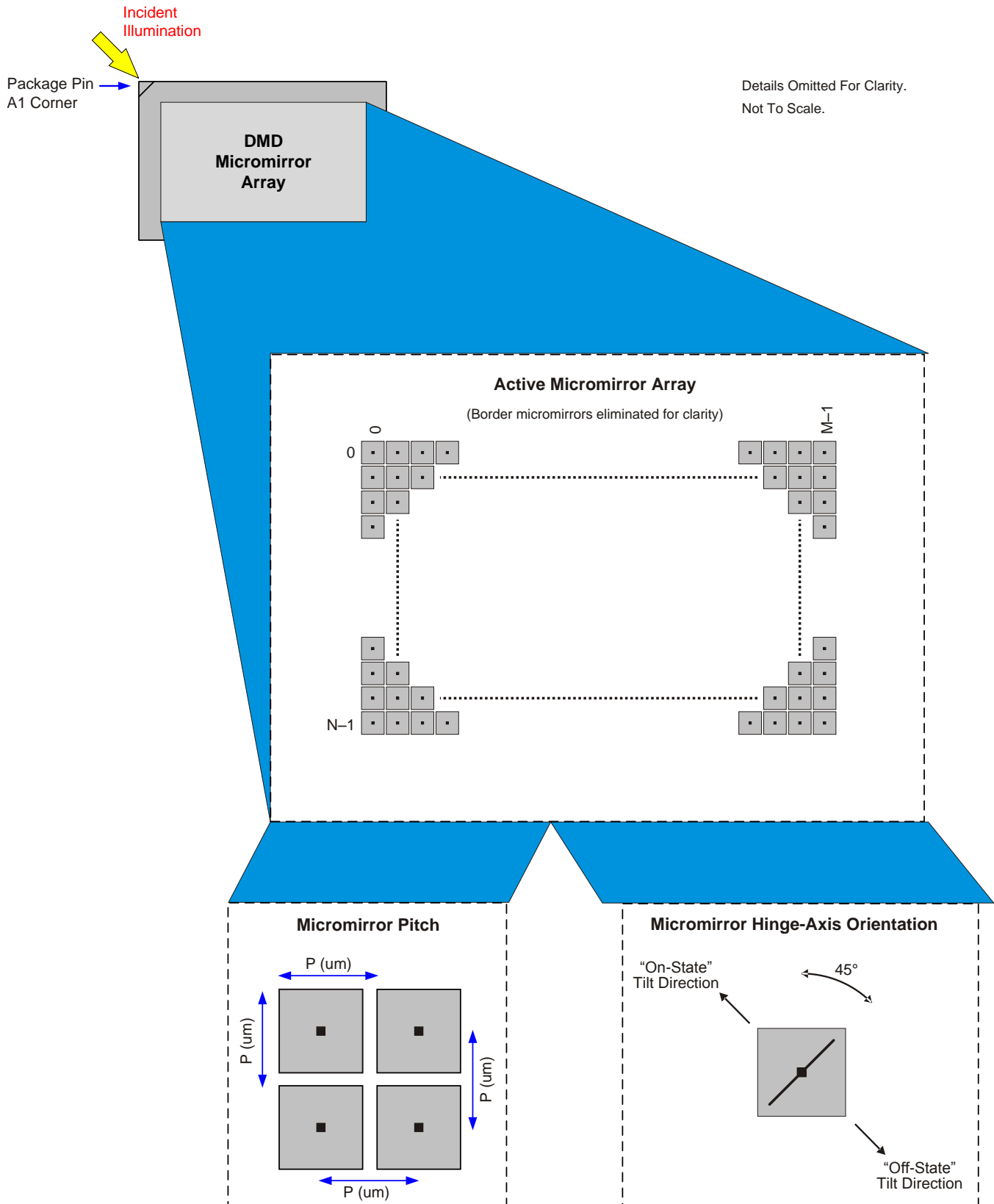


Figure 12. DMD Micromirror Array, Pitch, and Hinge-Axis Orientation

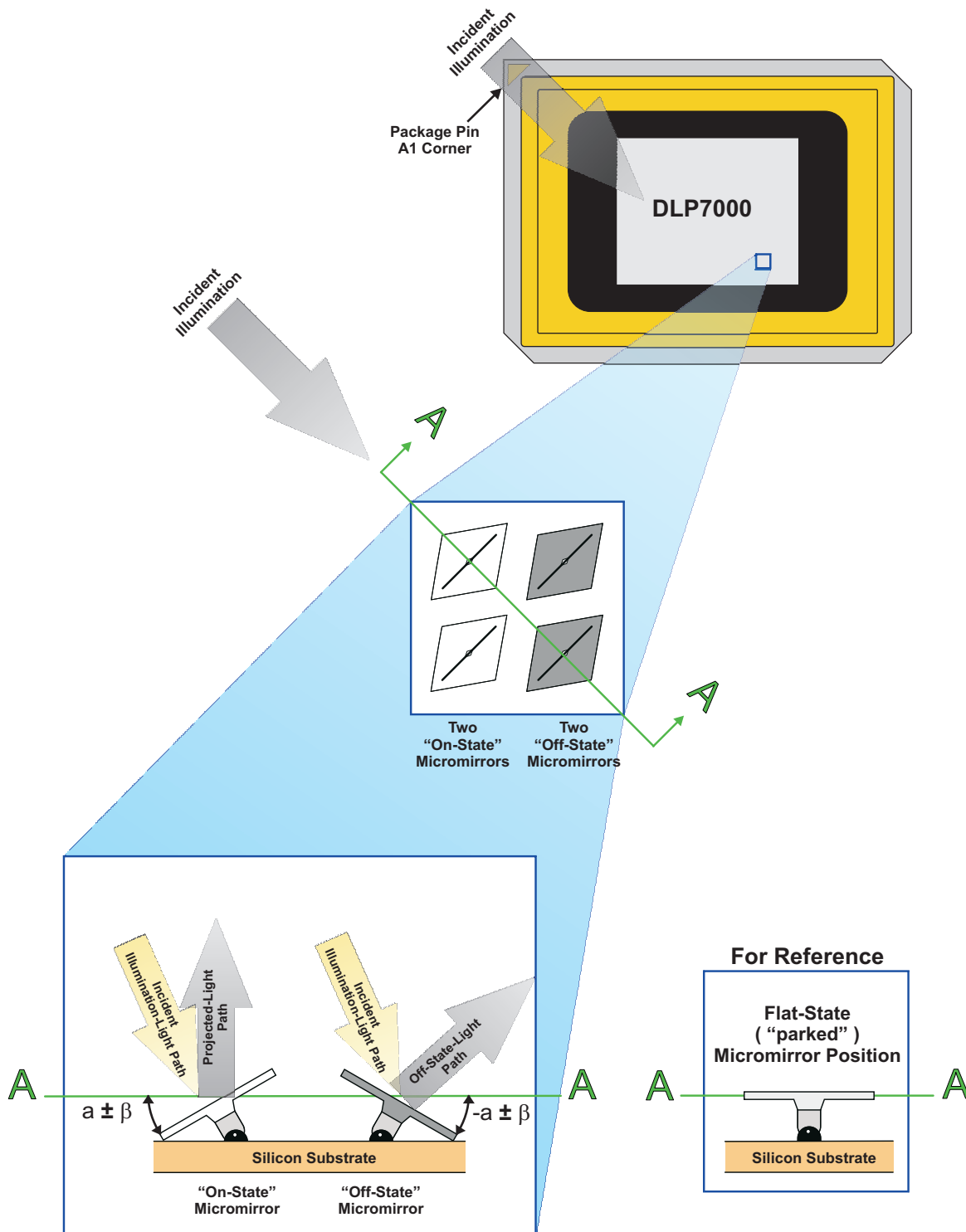


Figure 13. Micromirror Landed Positions and Light Paths

8.4 Device Functional Modes

8.4.1 DMD Operation

The DLP7000 has only one functional mode, it is set to be highly optimized for low latency and high speed in generating mirror clocking pulses and timings.

When operated with the DLPC410 controller in conjunction with the DLPA200 driver, the DLP7000 can be operated in several display modes. The DLP7000 is loaded as 16 blocks of 48 rows each. Figure 14, Figure 15, Figure 16, and Figure 17 show how the image is loaded by the different Micromirror Clocking Pulse modes.

There are four Micromirror Clocking Pulse modes that determine which blocks are "reset" when a Micromirror Clocking Pulse command is issued:

- Single block mode
- Dual block mode
- Quad block mode
- Global mode

8.4.1.1 Single Block Mode

In single block mode, a single block can be loaded and reset in any order. After a block is loaded, it can be reset to transfer the information to the mechanical state of the mirrors.



Figure 14. Single Block Mode Diagram

8.4.1.2 Dual Block Mode

In dual block mode, reset blocks are paired together as follows (0-1), (2-3), (4-5) . . . (14-15). These pairs can be reset in any order. After data is loaded a pair can be reset to transfer the information to the mechanical state of the mirrors.

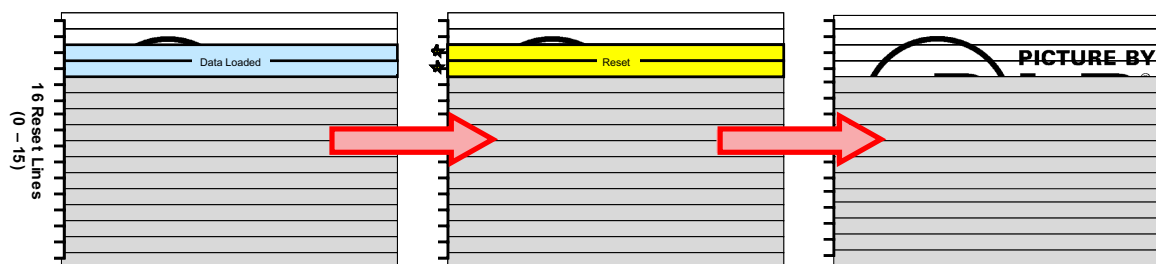


Figure 15. Dual Block Mode Diagram

Device Functional Modes (continued)

8.4.1.3 Quad Block Mode

In quad block mode, reset blocks are grouped together in fours as follows (0-3), (4-7), (8-11) and (12-15). Each quad group can be randomly addressed and reset. After a quad group is loaded, it can be reset to transfer the information to the mechanical state of the mirrors.

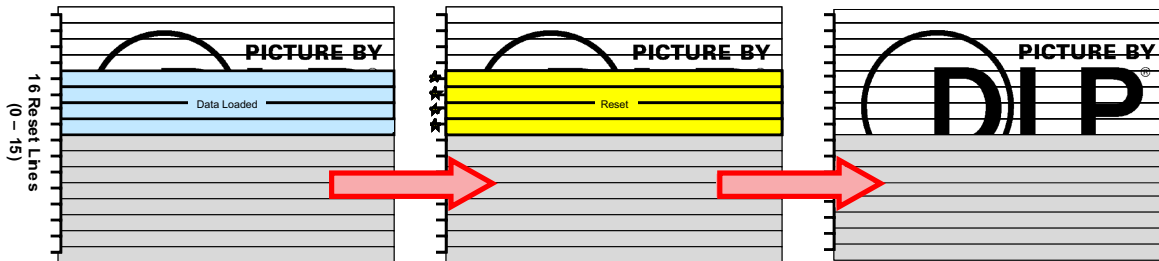


Figure 16. Quad Block Mode Diagram

8.4.1.4 Global Mode

In global mode, all reset blocks are grouped into a single group and reset together. The entire DMD must be loaded with the desired data before issuing a Global Reset to transfer the information to the mechanical state of the mirrors.

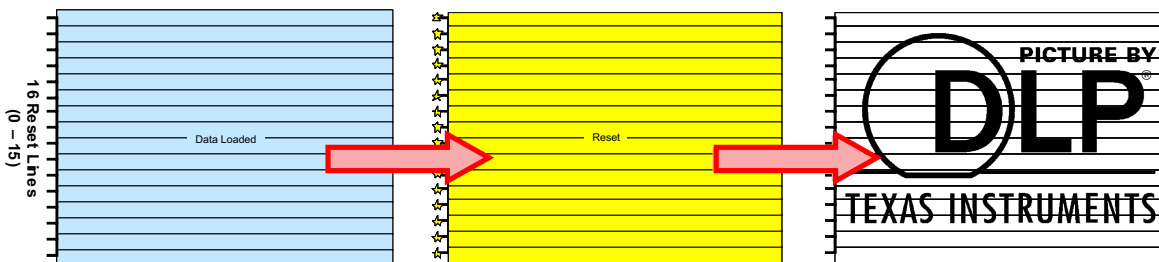


Figure 17. Global Mode Diagram

8.5 Window Characteristics and Optics

NOTE

TI assumes no responsibility for image quality artifacts or DMD failures caused by optical system operating conditions exceeding limits described previously.

8.5.1 Optical Interface and System Image Quality

TI assumes no responsibility for end-equipment optical performance. Achieving the desired end-equipment optical performance involves making trade-offs between numerous component and system design parameters. Optimizing system optical performance and image quality strongly relate to optical system design parameter trades. Although it is not possible to anticipate every conceivable application, projector image quality and optical performance is contingent on compliance to the optical system operating conditions described in the following sections.

8.5.2 Numerical Aperture and Stray Light Control

The angle defined by the numerical aperture of the illumination and projection optics at the DMD optical area should be the same. This angle should not exceed the nominal device mirror tilt angle unless appropriate apertures are added in the illumination and/or projection pupils to block out flat-state and stray light from the projection lens. The mirror tilt angle defines DMD capability to separate the "ON" optical path from any other light path, including undesirable flat-state specular reflections from the DMD window, DMD border structures, or other system surfaces near the DMD such as prism or lens surfaces. If the numerical aperture exceeds the mirror tilt angle, or if the projection numerical aperture angle is more than two degrees larger than the illumination numerical aperture angle, objectionable artifacts in the display's border and/or active area could occur.

8.5.3 Pupil Match

TI recommends the exit pupil of the illumination is nominally centered within 2° of the entrance pupil of the projection optics. Misalignment of pupils can create objectionable artifacts in the display's border and/or active area, which may require additional system apertures to control, especially if the numerical aperture of the system exceeds the pixel tilt angle.

8.5.4 Illumination Overfill

The active area of the device is surrounded by an aperture on the inside DMD window surface that masks structures of the DMD device assembly from normal view. The aperture is sized to anticipate several optical operating conditions. Overfill light illuminating the window aperture can create artifacts from the edge of the window aperture opening and other surface anomalies that may be visible on the screen. The illumination optical system should be designed to limit light flux incident anywhere on the window aperture from exceeding approximately 10% of the average flux level in the active area. Depending on the particular system's optical architecture, overfill light may have to be further reduced below the suggested 10% level in order to be acceptable.

8.6 Micromirror Array Temperature Calculation

Achieving optimal DMD performance requires proper management of the maximum DMD case temperature, the maximum temperature of any individual micromirror in the active array, the maximum temperature of the window aperture, and the temperature gradient between case temperature and the predicted micromirror array temperature. (see [Figure 18](#)).

See the [Recommended Operating Conditions](#) for applicable temperature limits.

8.6.1 Package Thermal Resistance

The DMD is designed to conduct absorbed and dissipated heat to the back of the Type A package where it can be removed by an appropriate heat sink. The heat sink and cooling system must be capable of maintaining the package within the specified operational temperatures, refer to [Figure 18](#). The total heat load on the DMD is typically driven by the incident light absorbed by the active area; although other contributions include light energy absorbed by the window aperture and electrical power dissipation of the array.

8.6.2 Case Temperature

The temperature of the DMD case can be measured directly. For consistency, a Thermal Test Point locations 1 and 2 are defined, as shown in [Figure 18](#).

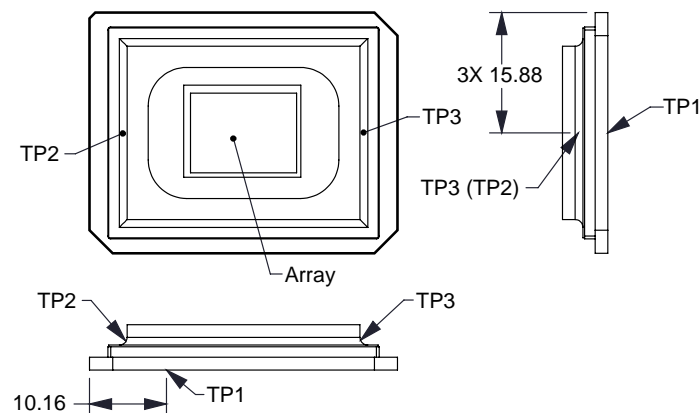


Figure 18. Thermal Test Point Location

Micromirror Array Temperature Calculation (continued)

8.6.3 Micromirror Array Temperature Calculation

Micromirror array temperature cannot be measured directly; therefore, it must be computed analytically from measurement points (Figure 18), the package thermal resistance, the electrical power, and the illumination heat load. The relationship between micromirror array temperature and the reference ceramic temperature (test point number 1 in Figure 18) are provided by Equation 1 and Equation 2:

$$T_{\text{Array}} = T_{\text{Ceramic}} + (Q_{\text{Array}} \times R_{\text{Array-To-Ceramic}}) \quad (1)$$

$$Q_{\text{Array}} = Q_{\text{ELE}} + Q_{\text{ILL}}$$

Where the following elements are defined as:

- T_{Array} = computed micromirror array temperature (°C)
- T_{Ceramic} = Ceramic temperature (°C) (TP1 Location Figure 18)
- Q_{Array} = Total DMD array power (electrical + absorbed) (measured in Watts)
- $R_{\text{Array-To-Ceramic}}$ = thermal resistance of DMD package from array to TC2 (°C/W) (see [Package Thermal Resistance](#))
- Q_{ELE} = Nominal electrical power (W)
- Q_{ILL} = Absorbed illumination energy (W) (2)

An example calculation is provided below based on a traditional DLP Video projection system. The electrical power dissipation of the DMD is variable and depends on the voltages, data rates, and operating frequencies. The nominal electrical power dissipation to be used in the calculation is 2 Watts. Thus, $Q_{\text{ELE}} = 2$ Watts. The absorbed power from the illumination source is variable and depends on the operating state of the mirrors and the intensity of the light source. Based on modeling and measured data from DLP projection system

$$Q_{\text{ILL}} = C_{\text{L2W}} \times \text{SL}$$

where

- C_{L2W} is a Lumens to Watts constant, and can be estimated at 0.00274 W/lm
- SL = Screen Lumens nominally measured to be 2000 lm
- $Q_{\text{array}} = 2.0 + (0.00274 \times 2000) = 7.48$ W, Estimated total power on micromirror Array
- $T_{\text{Ceramic}} = 55^\circ\text{C}$, assumed system measurement
- Finally, T_{Array} (micromirror active array temperature) is
- $T_{\text{Array}} = 55^\circ\text{C} + (7.48 \text{ W} \times 0.9^\circ\text{C/W}) = 61.7^\circ\text{C}$ (3)

8.7 Micromirror Landed-On/Landed-Off Duty Cycle

8.7.1 Definition of Micromirror Landed-On/Landed-Off Duty Cycle

The micromirror landed-on/landed-off duty cycle (landed duty cycle) denotes the amount of time (as a percentage) that an individual micromirror is landed in the On-state versus the amount of time the same micromirror is landed in the Off-state.

As an example, a landed duty cycle of 100/0 indicates that the referenced pixel is in the On-state 100% of the time (and in the Off-state 0% of the time); whereas 0/100 would indicate that the pixel is in the Off-state 100% of the time. Likewise, 50/50 indicates that the pixel is On 50% of the time and Off 50% of the time.

Note that when assessing landed duty cycle, the time spent switching from one state (ON or OFF) to the other state (OFF or ON) is considered negligible and is thus ignored.

Since a micromirror can only be landed in one state or the other (On or Off), the two numbers (percentages) always add to 100.

8.7.2 Landed Duty Cycle and Useful Life of the DMD

Knowing the long-term average landed duty cycle (of the end product or application) is important because subjecting all (or a portion) of the DMD's micromirror array (also called the active array) to an asymmetric landed duty cycle for a prolonged period of time can reduce the DMD's usable life.

Micromirror Landed-On/Landed-Off Duty Cycle (continued)

Note that it is the symmetry/asymmetry of the landed duty cycle that is of relevance. The symmetry of the landed duty cycle is determined by how close the two numbers (percentages) are to being equal. For example, a landed duty cycle of 50/50 is perfectly symmetrical whereas a landed duty cycle of 100/0 or 0/100 is perfectly asymmetrical.

8.7.3 Landed Duty Cycle and Operational DMD Temperature

Operational DMD Temperature and Landed Duty Cycle interact to affect the DMD's usable life, and this interaction can be exploited to reduce the impact that an asymmetrical Landed Duty Cycle has on the DMD's usable life. This is quantified in the de-rating curve shown in [Figure 1](#). The importance of this curve is that:

- All points along this curve represent the same usable life.
- All points above this curve represent lower usable life (and the further away from the curve, the lower the usable life).
- All points below this curve represent higher usable life (and the further away from the curve, the higher the usable life).

In practice, this curve specifies the Maximum Operating DMD Temperature that the DMD should be operated at for a give long-term average Landed Duty Cycle.

8.7.4 Estimating the Long-Term Average Landed Duty Cycle of a Product or Application

During a given period of time, the Landed Duty Cycle of a given pixel follows from the image content being displayed by that pixel.

For example, in the simplest case, when displaying pure-white on a given pixel for a given time period, that pixel will experience a 100/0 Landed Duty Cycle during that time period. Likewise, when displaying pure-black, the pixel will experience a 0/100 Landed Duty Cycle.

Between the two extremes (ignoring for the moment color and any image processing that may be applied to an incoming image), the Landed Duty Cycle tracks one-to-one with the gray scale value, as shown in [Table 5](#).

Table 5. Grayscale Value and Landed Duty Cycle

| GRAYSCALE VALUE | LANDED DUTY CYCLE |
|-----------------|-------------------|
| 0% | 0/100 |
| 10% | 10/90 |
| 20% | 20/80 |
| 30% | 30/70 |
| 40% | 40/60 |
| 50% | 50/50 |
| 60% | 60/40 |
| 70% | 70/30 |
| 80% | 80/20 |
| 90% | 90/10 |
| 100% | 100/0 |

Accounting for color rendition (but still ignoring image processing) requires knowing both the color intensity (from 0% to 100%) for each constituent primary color (red, green, and/or blue) for the given pixel as well as the color cycle time for each primary color, where "color cycle time" is the total percentage of the frame time that a given primary must be displayed in order to achieve the desired white point.

During a given period of time, the landed duty cycle of a given pixel can be calculated as follows:

$$\text{Landed Duty Cycle} = (\text{Red_Cycle_}\% \times \text{Red_Scale_Value}) + (\text{Green_Cycle_}\% \times \text{Green_Scale_Value}) + (\text{Blue_Cycle_}\% \times \text{Blue_Scale_Value})$$

where

- Red_Cycle_%, Green_Cycle_%, and Blue_Cycle_%, represent the percentage of the frame time that Red, Green, and Blue are displayed (respectively) to achieve the desired white point. (4)

For example, assume that the red, green and blue color cycle times are 50%, 20%, and 30% respectively (in order to achieve the desired white point), then the Landed Duty Cycle for various combinations of red, green, blue color intensities would be as shown in [Table 6](#).

Table 6. Example Landed Duty Cycle for Full-Color

| RED CYCLE PERCENTAGE 50% | GREEN CYCLE PERCENTAGE 20% | BLUE CYCLE PERCENTAGE 30% | LANDED DUTY CYCLE |
|-----------------------------|-------------------------------|------------------------------|-------------------|
| RED SCALE VALUE | GREEN SCALE VALUE | BLUE SCALE VALUE | |
| 0% | 0% | 0% | 0/100 |
| 100% | 0% | 0% | 50/50 |
| 0% | 100% | 0% | 20/80 |
| 0% | 0% | 100% | 30/70 |
| 12% | 0% | 0% | 6/94 |
| 0% | 35% | 0% | 7/93 |
| 0% | 0% | 60% | 18/82 |
| 100% | 100% | 0% | 70/30 |
| 0% | 100% | 100% | 50/50 |
| 100% | 0% | 100% | 80/20 |
| 12% | 35% | 0% | 13/87 |
| 0% | 35% | 60% | 25/75 |
| 12% | 0% | 60% | 24/76 |
| 100% | 100% | 100% | 100/0 |

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The DLP7000 devices require they be coupled with the DLPC410 controller to provide a reliable solution for many different applications. The DMDs are spatial light modulators which reflect incoming light from an illumination source to one of two directions, with the primary direction being into a projection collection optic. Each application is derived primarily from the optical architecture of the system and the format of the data coming into the DLPC410. Applications of interest include 3D measurement systems, lithography, medical systems, and compressive sensing.

9.1.1 Device Description

The DLP7000 XGA chipset offers developers a convenient way to design a wide variety of industrial, medical, telecom and advanced display applications by delivering maximum flexibility in formatting data, sequencing data, and light patterns.

The DLP7000 XGA chipset includes the following four components: DMD Digital Controller (DLPC410), EEPROM (DLPR410), DMD Micromirror Driver (DLPA200), and a DMD (DLP7000).

DLPC410 Digital Controller for DLP Discovery 4100 chipset

- Provides high speed LVDS data and control interface to the DLP7000.
- Drives mirror clocking pulse and timing information to the DLPA200.
- Supports random row addressing.

DLPR410 PROM for DLP Discovery 4100 chipset

- Contains startup configuration information for the DLPC410.

DLPA200 DMD Micromirror Driver

- Generates Micromirror Clocking Pulse control (sometimes referred to as a "Reset") of DMD mirrors.

DLP7000 DLP 0.7 XGA 2xLVDS Type-A DMD

- Steers light in two digital positions (+12° and -12°) using 1024 x 768 micromirror array of aluminum mirrors.

Table 7. DLPC410 Chipset Configuration for 0.7 XGA Chipset

| QUANTITY | TI PART | DESCRIPTION |
|----------|---------|---|
| 1 | DLP7000 | DLP 0.7 XGA 2xLVDS Type-A DMD |
| 1 | DLPC410 | Digital Controller for DLP Discovery 4100 chipset |
| 1 | DLPR410 | PROM for DLP Discovery 4100 chipset |
| 1 | DLPA200 | DMD Micromirror Driver |

Reliable function and operation of DLP7000 XGA chipsets require the components be used in conjunction with each other. This document describes the proper integration and use of the DLP7000 XGA chipset components.

The DLP7000 XGA chipset can be combined with a user programmable Application FPGA (not included) to create high performance systems.

9.2 Typical Application

A typical embedded system application using the DLPC410 controller and DLP7000 is shown in Figure 19. In this configuration, the DLPC410 controller supports input from an FPGA. The FPGA sends low-level data to the controller, enabling the system to be highly optimized for low latency and high speed.

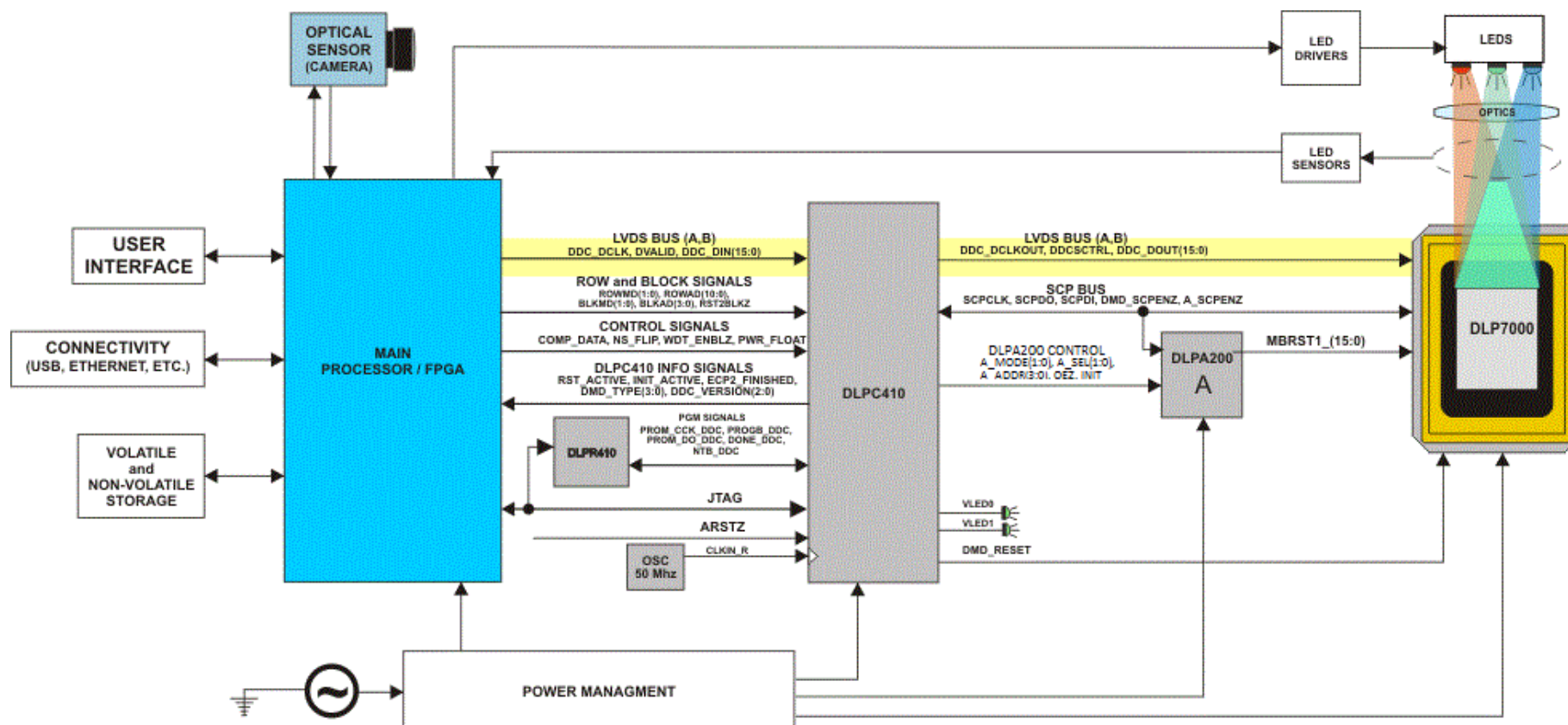


Figure 19. DLPC410 and DLP7000 Embedded Example Block Diagram

9.2.1 Design Requirements

All applications using the DLP7000 XGA chipset require both the controller and the DMD components for operation. The system also requires an external parallel flash memory device loaded with the DLPC410 Configuration and Support Firmware. The chipset has several system interfaces and requires some support circuitry. The following interfaces and support circuitry are required:

- DLPC410 System Interfaces:
 - Control Interface
 - Trigger Interface
 - Input Data Interface
 - Illumination Interface
 - Reference Clock
- DLP7000 Interfaces:
 - DLPC410 to DLP7000 Digital Data
 - DLPC410 to DLP7000 Control Interface
 - DLPC410 to DLP7000 Micromirror Reset Control Interface
 - DLPC410 to DLPA200 Micromirror Driver
 - DLPA200 to DLP7000 Micromirror Reset

9.2.2 Detailed Design Procedure

The DLP7000 DMD is well suited for visible light applications requiring fast, spatially programmable light patterns using the micromirror array. See the [Functional Block Diagram](#) to see the connections between the DLP7000 DMD, the DLPC410 digital controller, the DLPR410 EEPROM, and the DLPA200 DMD micromirror drivers. See the [Figure 19](#) for an application example. Follow the [Layout Guidelines](#) for reliability.

10 Power Supply Recommendations

10.1 DMD Power-Up and Power-Down Procedures

Repeated failure to adhere to the prescribed power-up and power-down procedures may affect device reliability. The DLP7000 power-up and power-down procedures are defined by the DLPC410 data sheet ([DLPS024](#)). These procedures must be followed to ensure reliable operation of the device.

11 Layout

11.1 Layout Guidelines

The DLP7000 is part of a chipset that is controlled by the DLPC410 in conjunction with the DLPA200. These guidelines are targeted at designing a PCB board with these components.

A target impedance of 50 Ω for single ended signals and 100 Ω between LVDS signals is specified for all signal layers.

11.1.1 Impedance Requirements

Signals should be routed to have a matched impedance of 50 $\Omega \pm 10\%$ except for LVDS differential pairs (DMD_DAT_Xnn, DMD_DCKL_Xn, and DMD_SCTRL_Xn), which should be matched to 100 $\Omega \pm 10\%$ across each pair.

11.1.2 PCB Signal Routing

When designing a PCB for the DLP7000 controlled by the DLPC410 in conjunction with the DLPA200, the following are recommended:

Signal trace corners should be no sharper than 45°. Adjacent signal layers should have the predominate traces routed orthogonal to each other. TI recommends that critical signals be hand routed in the following order: DDR2 Memory, DMD (LVDS signals), then DLPA200 signals.

TI does not recommend signal routing on power or ground planes.

TI does not recommend ground plane slots.

High speed signal traces should not cross over slots in adjacent power and/or ground planes.

Table 8. Important Signal Trace Constraints

| SIGNAL | CONSTRAINTS |
|---|--|
| LVDS (DMD_DAT_xnn, DMD_DCKL_xn, and DMD_SCTRL_xn) | P-to-N data, clock, and SCTRL: <10 mils (0.25 mm); Pair-to-pair <10 mils (0.25 mm); Bundle-to-bundle <2000 mils (50 mm, for example DMD_DAT_Ann to DMD_DAT_Bnn) Trace width: 4 mil (0.1 mm) Trace spacing: In ball field – 4 mil (0.11 mm); PCB etch – 14 mil (0.36 mm) Maximum recommended trace length <6 inches (150 mm) |

Table 9. Power Trace Widths and Spacing

| SIGNAL NAME | MINIMUM TRACE WIDTH | MINIMUM TRACE SPACING | LAYOUT REQUIREMENTS |
|-------------|---------------------|-----------------------|---|
| GND | Maximize | 5 mil (0.13 mm) | Maximize trace width to connecting pin as a minimum |
| VCC, VCC2 | 20 mil (0.51 mm) | 10 mil (0.25 mm) | |
| MBRST[15:0] | 11 mil (0.23 mm) | 15 mil (0.38 mm) | |

11.1.3 Fiducials

Fiducials for automatic component insertion should be 0.05-inch copper with a 0.1-inch cutout (antipad). Fiducials for optical auto insertion are placed on three corners of both sides of the PCB.

11.1.4 DMD Interface

The digital interface from the DLPC410 to the DMD are LVDS signals that run at clock rates up to 400 MHz. Data is clocked into the DMD on both the rising and falling edge of the clock, so the data rate is 800 MHz. The LVDS signals should have 100 Ω differential impedance. The differential signals should be matched but kept as short as possible. Parallel termination at the LVDS receiver is in the DMD; therefore, on board termination is not necessary.

11.1.4.1 Trace Length Matching

The DLPC410 DMD data signals require precise length matching. Differential signals should have impedance of 100 Ω (with 5% tolerance). It is important that the propagation delays are matched. The maximum differential pair uncoupled length is 100 mils with a relative propagation delay of ± 25 mil between the p and n. Matching all signals exactly will maximize the channel margin. The signal path through all boards, flex cables and internal DMD routing must be considered in this calculation.

11.1.5 DLP7000 Decoupling

General decoupling capacitors for the DLP7000 should be distributed around the PCB and placed to minimize the distance from IC voltage and ground pads. Each decoupling capacitor (0.1 μ F recommended) should have vias directly to the ground and power planes. Via sharing between components (discrete or integrated) is discouraged. The power and ground pads of the DLP7000 should be tied to the voltage and ground planes with their own vias.

11.1.5.1 Decoupling Capacitors

Decoupling capacitors should be placed to minimize the distance from the decoupling capacitor to the supply and ground pin of the component. It is recommended that the placement of and routing for the decoupling capacitors meet the following guidelines:

- The supply voltage pin of the capacitor should be located close to the device supply voltage pin(s). The decoupling capacitor should have vias to ground and voltage planes. The device can be connected directly to the decoupling capacitor (no via) if the trace length is less than 0.1 inch. Otherwise, the component should be tied to the voltage or ground plane through separate vias.
- The trace lengths of the voltage and ground connections for decoupling capacitors and components should be less than 0.1 inch to minimize inductance.
- The trace width of the power and ground connection to decoupling capacitors and components should be as wide as possible to minimize inductance.
- Connecting decoupling capacitors to ground and power planes through multiple vias can reduce inductance and improve noise performance.
- Decoupling performance can be improved by utilizing low ESR and low ESL capacitors.

11.1.6 VCC and VCC2

The VCC pins of the DMD should be connected directly to the DMD VCC plane. Decoupling for the VCC should be distributed around the DMD and placed to minimize the distance from the voltage and ground pads. Each decoupling capacitor should have vias directly connected to the ground and power planes. The VCC and GND pads of the DMD should be tied to the VCC and ground planes with their own vias.

The VCC2 voltage can be routed to the DMD as a trace. Decoupling capacitors should be placed to minimize the distance from the DMD's VCC2 and ground pads. Using wide etch from the decoupling capacitors to the DMD connection will reduce inductance and improve decoupling performance.

11.1.7 DMD Layout

See the respective sections in this data sheet for package dimensions, timing and pin out information.

11.1.8 DLPA200

The DLPA200 generates the micromirror clocking pulses for the DMD. The DMD-drive outputs from the DLPA200 (MBRST[15:0]) should be routed with minimum trace width of 11 mil and a minimum spacing of 15 mil. The VCC and VCC2 traces from the output capacitors to the DLPA200 should also be routed with a minimum trace width and spacing of 11 mil and 15 mil, respectively. See the DLPA200 customer data sheet for mechanical package and layout information.

11.2 Layout Example

For LVDS (and other differential signal) pairs and groups, it is important to match trace lengths. In the area of the dashed lines, [Figure 20](#) shows correct matching of signal pair lengths with serpentine sections to maintain the correct impedance.

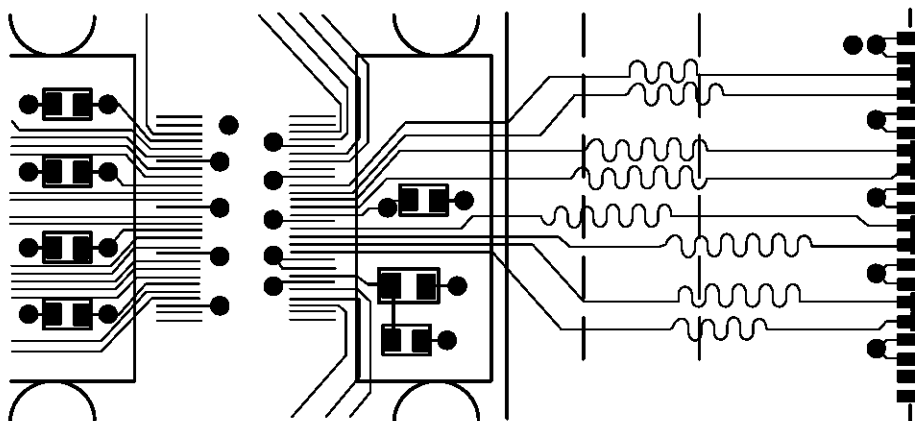


Figure 20. Mitering LVDS Traces to Match Lengths

12 Device and Documentation Support

12.1 Device Support

12.1.1 Device Nomenclature

Figure 21 provides a legend of reading the complete device name for any DLP device.

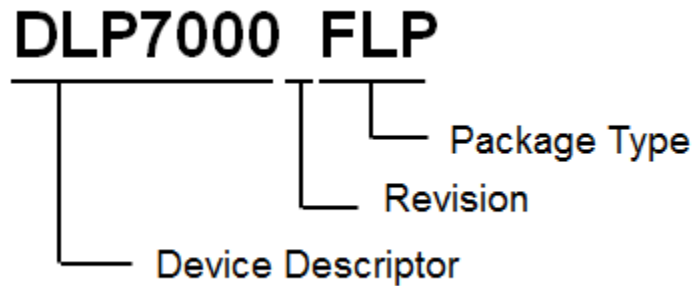


Figure 21. Device Nomenclature

12.1.2 Device Marking

The device marking consists of the fields shown in Figure 22.

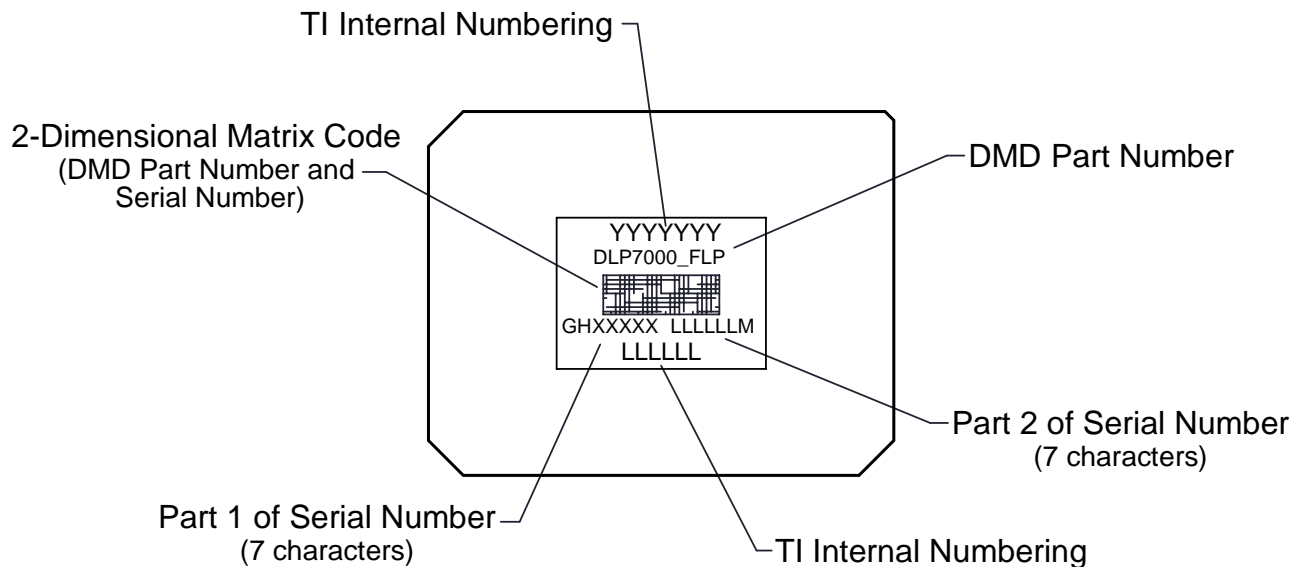


Figure 22. Device Marking

12.2 Documentation Support

12.2.1 Related Documents

The following documents contain additional information related to the use of the DLP7000 device:

- DLPC410 Digital Controller for DLP Discovery 4100 chipset data sheet, [DLPS024](#)
- DLPA200 DMD Micromirror Driver data sheet, [DLPS015](#)

Documentation Support (continued)

- DLPR410 PROM for DLP Discovery 4100 chipset data sheet, [DLPS027](#)

12.3 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 10. Related Links

| PARTS | PRODUCT FOLDER | SAMPLE & BUY | TECHNICAL DOCUMENTS | TOOLS & SOFTWARE | SUPPORT & COMMUNITY |
|---------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|
| DLP7000 | Click here | Click here | Click here | Click here | Click here |
| DLPA200 | Click here | Click here | Click here | Click here | Click here |
| DLPC410 | Click here | Click here | Click here | Click here | Click here |
| DLPR410 | Click here | Click here | Click here | Click here | Click here |

12.4 Trademarks

Discovery is a trademark of Texas Instruments.

DLP is a registered trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

12.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead/Ball Finish (6) | MSL Peak Temp (3) | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|--------------------|------|----------------|-----------------|-------------------------|----------------------|--------------|-------------------------|-------------------------|
| DLP7000BFLP | ACTIVE | CLGA | FLP | 203 | 3 | RoHS & Green | NI-PD-AU | N / A for Pkg Type | | | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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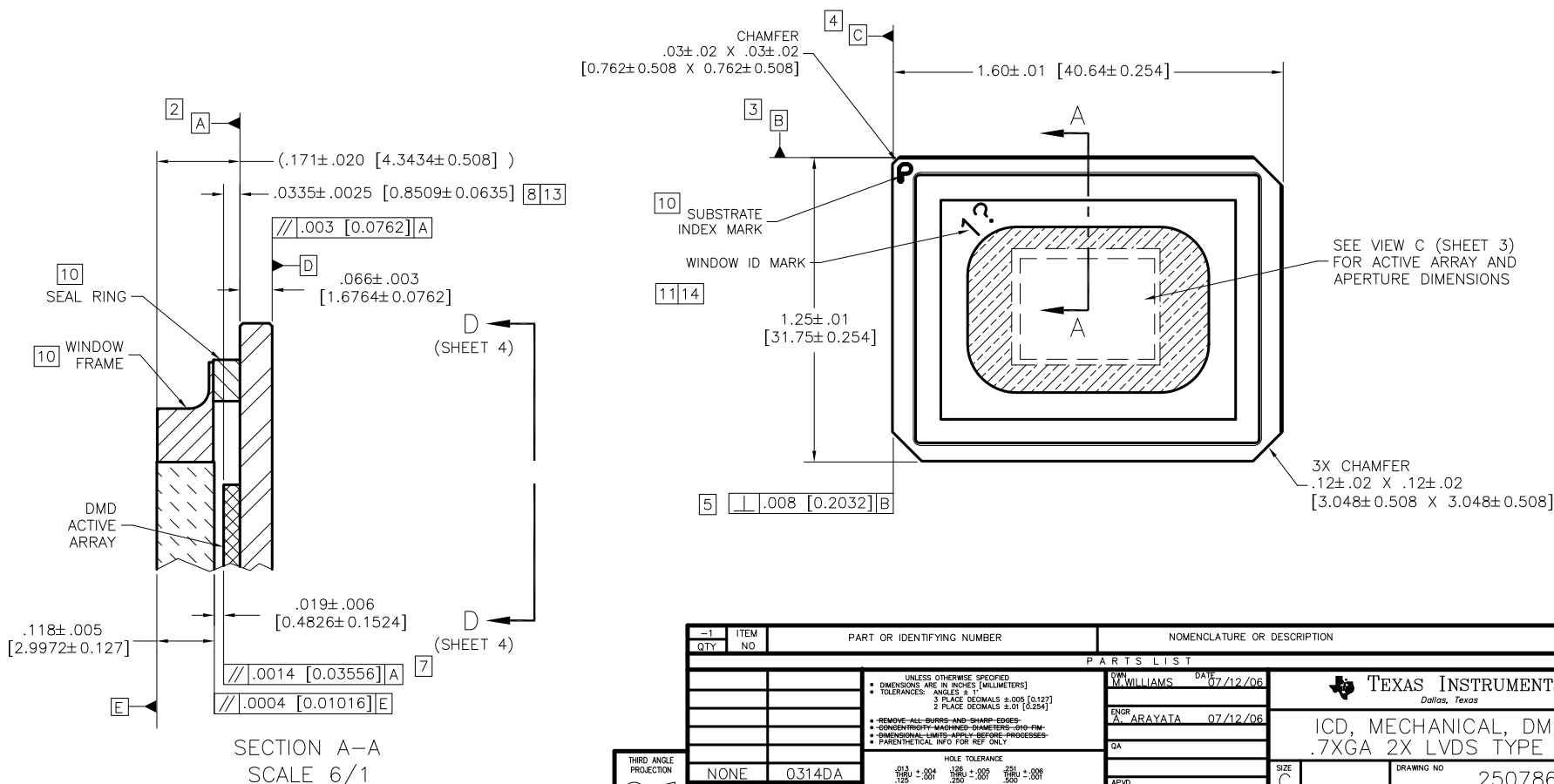
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| REVISIONS | | | |
|-----------|-------------------------------|----------|----------|
| REV | DESCRIPTION | DATE | APPROVED |
| A | ECO 2071155, INITIAL RELEASE | 07/24/06 | MRW |
| B | ECO 2077187, CHG DESG FROM 29 | 02/19/07 | MRW |

1. INTERPRET DIMENSIONS IN ACCORDANCE WITH ASME Y14.5M—1994.
2. DATUM A (SYSTEM INTERFACE PLANE) ESTABLISHED BY THREE DATUM AREAS SHOWN IN VIEW B (SHEET 2).
3. DATUM B ESTABLISHED BY TWO DATUM AREAS SHOWN IN VIEW B (SHEET 2).
4. DATUM C ESTABLISHED BY DATUM AREA SHOWN IN VIEW B (SHEET 2).
5. SUBSTRATE EDGE PERPENDICULARITY TOLERANCE APPLIES TO ENTIRE SURFACE
6. LOCALIZED BACKSIDE SURFACE FLATNESS APPLIES TO ENTIRE CERAMIC SURFACE.
7. DIE PARALLELISM TOLERANCE APPLIES TO DMD ACTIVE ARRAY ONLY.
8. DIE HEIGHT TOLERANCE APPLIES TO CENTER OF DMD ACTIVE ARRAY ONLY.
9. ROTATION ANGLE OF DMD ACTIVE ARRAY IS A REFINEMENT OF THE LOCATION TOLERANCE AND IS THE MAXIMUM VALUE ALLOWED.
10. SUBSTRATE INDEX MARK, SYMBOLIZATION PAD, SEAL RING, AND WINDOW FRAME TO BE ELECTRICALLY CONNECTED TO VSS PLANE IN SUBSTRATE.
11. WINDOW SHALL BE ORIENTED SUCH THAT WINDOW ID MARK ALIGNS WITH SUBSTRATE INDEX MARK AS SHOWN.
12. THE OUTER DIMENSIONS OF THE SYMBOLIZATION PAD REPRESENT THE APPROXIMATE SIZE AND LOCATION OF THE RECOMMENDED THERMAL INTERFACE AREA.
13. DMD ACTIVE ARRAY DIMENSIONS ARE RELATED TO DATUM A (PRIMARY), DATUM B (SECONDARY), AND DATUM C (TERTIARY).
14. ? IS A WILD CARD CHARACTER AND CAN BE ANY LETTER.



ACEC1q

THIRD ANGLE
PROJECTION

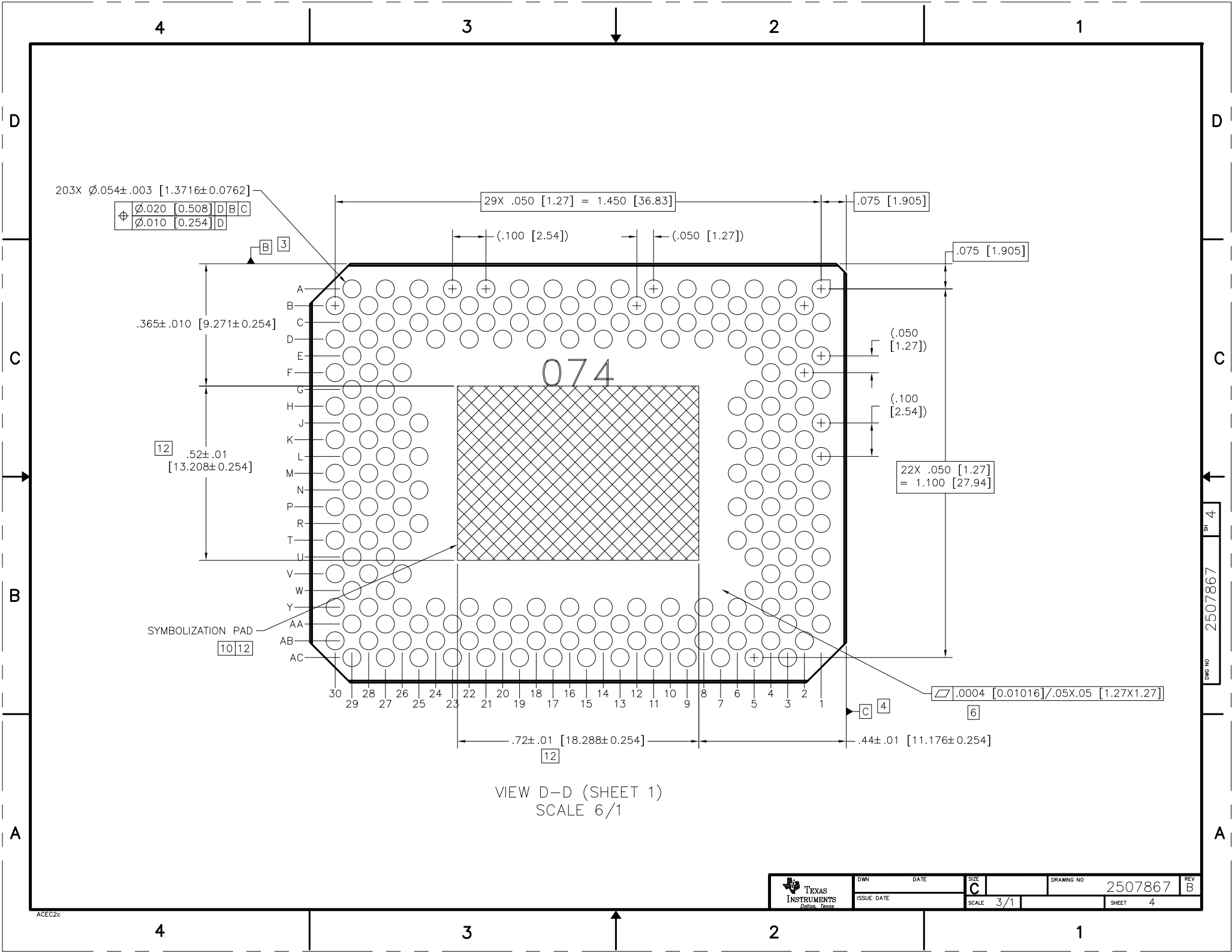
| | | | | | |
|--|------------|----------------------------|--------------------------------|-------------------------|--|
| -1 QTY | ITEM NO | PART OR IDENTIFYING NUMBER | NOMENCLATURE OR DESCRIPTION | | NOTES |
| PARTS LIST | | | | | |
| UNLESS OTHERWISE SPECIFIED: • DIMENSIONS ARE IN INCHES, [MILLIMETERS] • TOLERANCES: ANGLES ± 1 PLACES DECIMALS ±.005 [0.127] 2 PLACE DECIMALS ±.01 [0.254] | | | DRAWN BY M. WILLIAMS | DATE 07/12/06 |  TEXAS INSTRUMENTS <i>Dallas, Texas</i> ICD, MECHANICAL, DMD .7XGA 2X LVDS TYPE A |
| • REMOVE ALL BURRS AND SHARP EDGES. • CONCENTRICITY-MACHINED-DIMETERS-Ø&F.M. • DIMENSIONAL LIMITS APPLY BEFORE FINISHES. • PARENTHERTICAL INFO FOR REF ONLY. | | | ENG'D A. ARAYATA | DATE 07/12/06 | |
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