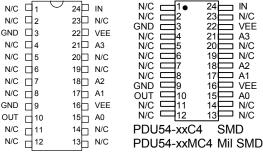
4-BIT, ECL-INTERFACED PROGRAMMABLE DELAY LINE (SERIES PDU54)



FEATURES PACKAGES

- Digitally programmable in 16 delay steps
- Monotonic delay-versus-address variation
- Precise and stable delays
- Input & outputs fully 100K-ECL interfaced & buffered
- Available in 24-pin DIP (600 mil) socket or SMD

PDU54-xx DIP PDU54-xxM Military DIP



FUNCTIONAL DESCRIPTION

The PDU54-series device is a 4-bit digitally programmable delay line. The delay, TD_A , from the input pin (IN) to the output pin (OUT) depends on the address code (A3-A0) according to the following formula:

$$TD_A = TD_0 + T_{INC} * A$$

PIN DESCRIPTIONS

IN Signal Input
OUT Signal Output
A3-A0 Address Bits
VEE -5 Volts
GND Ground

where A is the address code, T_{INC} is the incremental delay of the device, and TD_0 is the inherent delay of the device. The incremental delay is specified by the dash number of the device and can range from 100ps through 3000ps, inclusively. The address is not latched and must remain asserted during normal operation.

SERIES SPECIFICATIONS

- Total programmed delay tolerance: 5% or 40ps, whichever is greater
- Inherent delay (TD₀): 3.3ns typical
- Address to input setup (T_{AIS}): 2.9ns
 Operating temperature: 0° to 85° C
- Temperature coefficient: 100PPM/°C (excludes TD₀)
- Supply voltage V_{EE}: -5VDC ± 0.7V
- Power Supply Current: -300ma typical (50Ω to -2V)
- Minimum pulse width: 3ns or 10% of total delay,

whichever is greater

• **Minimum period:** 8ns or 2 x pulse width, whichever is greater

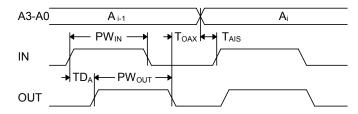


Figure 1: Timing Diagram

DASH NUMBER SPECIFICATIONS

Part Number	Incremental Delay Per Step (ps)	Total Delay Change (ns)	
PDU54-100	100 ± 50	1.50	
PDU54-200	200 ± 60	3.00	
PDU54-250	250 ± 60	3.75	
PDU54-400	400 ± 80	6.00	
PDU54-500	500 ± 100	7.50	
PDU54-750	750 ± 100	11.25	
PDU54-1000	1000 ± 200	15.00	
PDU54-1200	1200 ± 200	18.00	
PDU54-1500	1500 ± 200	22.50	
PDU54-2000	2000 ± 400	30.00	
PDU54-2500	2500 ± 400	37.50	
PDU54-3000	3000 ± 500	45.00	

NOTE: Any dash number between 100 and 3000 not shown is also available.

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APPLICATION NOTES

ADDRESS UPDATE

The PDU54 is a memory device. As such, special precautions must be taken when changing the delay address in order to prevent spurious output signals. The timing restrictions are shown in Figure 1.

After the last signal edge to be delayed has appeared on the OUT pin, a minimum time, T_{OAX}, is required before the address lines can change. This time is given by the following relation:

$$T_{OAX} = max \{ (A_i - A_{i-1}) * T_{INC}, 0 \}$$

where A_{i-1} and A_i are the old and new address codes, respectively. Violation of this constraint may, depending on the history of the input signal, cause spurious signals to appear on the OUT pin. The possibility of spurious signals persists until the required T_{OAX} has elapsed.

INPUT RESTRICTIONS

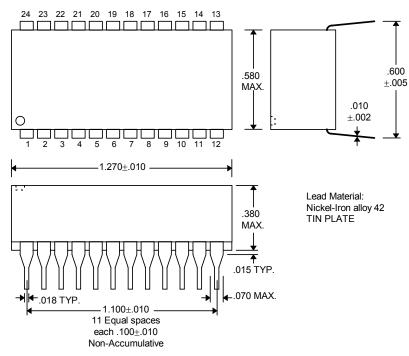
There are three types of restrictions on input pulse width and period listed in the **AC Characteristics** table. The **recommended**

conditions are those for which the delay tolerance specifications and monotonicity are guaranteed. The **suggested** conditions are those for which signals will propagate through the unit without significant distortion. The **absolute** conditions are those for which the unit will produce some type of output for a given input.

When operating the unit between the recommended and absolute conditions, the delays may deviate from their values at low frequency. However, these deviations will remain constant from pulse to pulse if the input pulse width and period remain fixed. In other words, the delay of the unit exhibits frequency and pulse width dependence when operated beyond the recommended conditions. Please consult the technical staff at Data Delay Devices if your application has specific high-frequency requirements.

Please note that the increment tolerances listed represent a design goal. Although most delay increments will fall within tolerance, they are not guaranteed throughout the address range of the unit. Monotonicity is, however, guaranteed over all addresses.

PACKAGE DIMENSIONS



PDU54-xx (Commercial DIP) PDU54-xxM (Military DIP)

.882

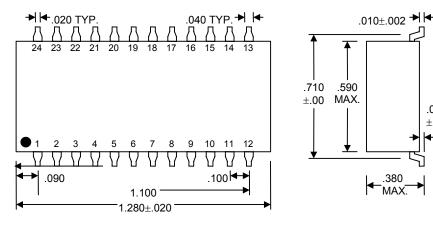
 $\pm .00$

.050

±.01

.007 ±.00

PACKAGE DIMENSIONS (cont'd)



PDU54-xxC4 (Commercial SMD) PDU54-xxMC4 (Military SMD)

DEVICE SPECIFICATIONS

TABLE 1: AC CHARACTERISTICS

PARAMETER		SYMBOL	MIN	TYP	UNITS
Total Programmable Delay		TD_T		7	T_{INC}
Inherent Delay		TD_0		3.3	ns
Address to Input Setup Time		T _{AIS}	2.9		ns
Output to Address Change		T _{OAX}	See Text		
Input Period	Absolute	PERIN	20		% of TD_{T}
	Suggested	PERIN	40		% of TD_{T}
	Recommended	PERIN	200		% of TD_{T}
Input Pulse Width	Absolute	PW _{IN}	10		% of TD_{T}
	Suggested	PW _{IN}	20		% of TD_T
	Recommended	PW _{IN}	100		% of TD _⊤

TABLE 2: ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	MIN	MAX	UNITS	NOTES
DC Supply Voltage	V_{EE}	-7.0	0.3	V	
Input Pin Voltage	V_{IN}	V _{EE} - 0.3	0.3	V	
Storage Temperature	T _{STRG}	-65	150	С	
Lead Temperature	T_{LEAD}		300	С	10 sec

TABLE 3: DC ELECTRICAL CHARACTERISTICS

(0C to 85C)

PARAMETER	SYMBOL	MIN	MAX	UNITS	NOTES
High Level Output Voltage	V_{OH}	-1.025	-0.880	V	V_{IH} = MAX,50 Ω to -2V
Low Level Output Voltage	V_{OL}	-1.810	-1.620	V	V_{IL} = MIN, 50Ω to -2V
High Level Input Voltage	V_{IH}	-1.165	-0.880	V	
Low Level Input Voltage	V_{IL}	-1.810	-1.475	V	
High Level Input Current	I _{IH}		340	μΑ	V _{IH} = MAX
Low Level Input Current	I _{IL}	0.5		μΑ	V _{IL} = MIN

DELAY LINE AUTOMATED TESTING

TEST CONDITIONS

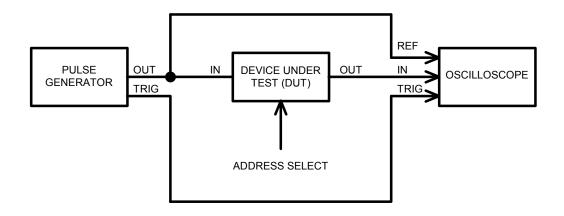
INPUT: OUTPUT:

Source Impedance: 50Ω Max.

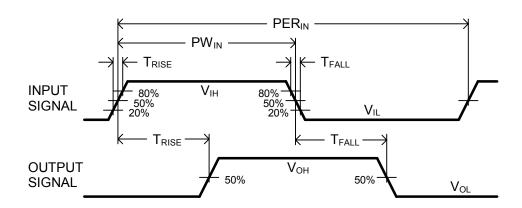
Rise/Fall Time: 1.0 ns Max. (measured between 20% and 80%)

Pulse Width: $PW_{IN} = 10ns$ Period: $PER_{IN} = 100ns$

NOTE: The above conditions are for test only and do not in any way restrict the operation of the device.



Test Setup



Timing Diagram For Testing