

## Description

ATWINC1500A is a single chip IEEE 802.11 b/g/n Radio/Baseband/MAC network controller optimized for low-power mobile applications. ATWINC1500A supports single stream 1x1 802.11n mode providing up to 72Mbps PHY rate.

ATWINC1500A features fully integrated Power Amplifier, LNA, Switch, and Power Management. ATWINC1500A also features an on-chip microcontroller and integrated flash memory for system software. Implemented in 65nm CMOS technology, the ATWINC1500A offers very low power consumption while simultaneously providing high performance and minimal bill of materials.

The ATWINC1500A supports 2- and 3-wire Bluetooth coexistence protocols. The ATWINC1500A provides multiple peripheral interfaces including UART, SPI, I<sup>2</sup>C the only external clock source needed for the ATWINC1500A is a high-speed crystal or oscillator with a wide range of reference clock frequencies supported (12-40MHz). The ATWINC1500A is available in QFN packaging.

## Features

- IEEE 802.11 b/g/n 20MHz (1x1) solution
- Single spatial stream in 2.4GHz ISM band
- Integrated PA and T/R Switch
- Superior Sensitivity and Range via advanced PHY signal processing
- Advanced Equalization and Channel Estimation
- Advanced Carrier and Timing Synchronization
- Wi-Fi Direct and Soft-AP support
- Supports IEEE 802.11 WEP, WPA, WPA2 Security
- Supports China WAPI security
- Superior MAC throughput via hardware accelerated two-level A-MSDU/A-MPDU frame aggregation and block acknowledgement
- On-chip memory management engine to reduce host load
- Integrated Flash memory for system software
- SPI, UART, and I<sup>2</sup>C host interfaces
- 2/3 wire Bluetooth coexistence interface
- Operating temperature range of -40°C to +85°C

- Power save modes:
  - <4μA Deep Power Down mode typical @3.3V I/O
  - 280uA Doze mode with chip settings preserved (used for beacon monitoring)
  - On-chip low power sleep oscillator
  - Fast host wake-up from Doze mode by a pin or host I/O transaction
- Fast boot options:
  - On-Chip Boot ROM (firmware instant boot)
  - SPI flash boot (firmware patches and state variables)
  - Low-leakage on-chip memory for state variables
  - Fast AP re-association (150ms)
- On-Chip Network Stack to offload MCU:
  - Integrated Network IP stack to minimize host CPU requirements
  - Network features: TCP, UDP, DHCP, ARP, HTTP, SSL, and DNS

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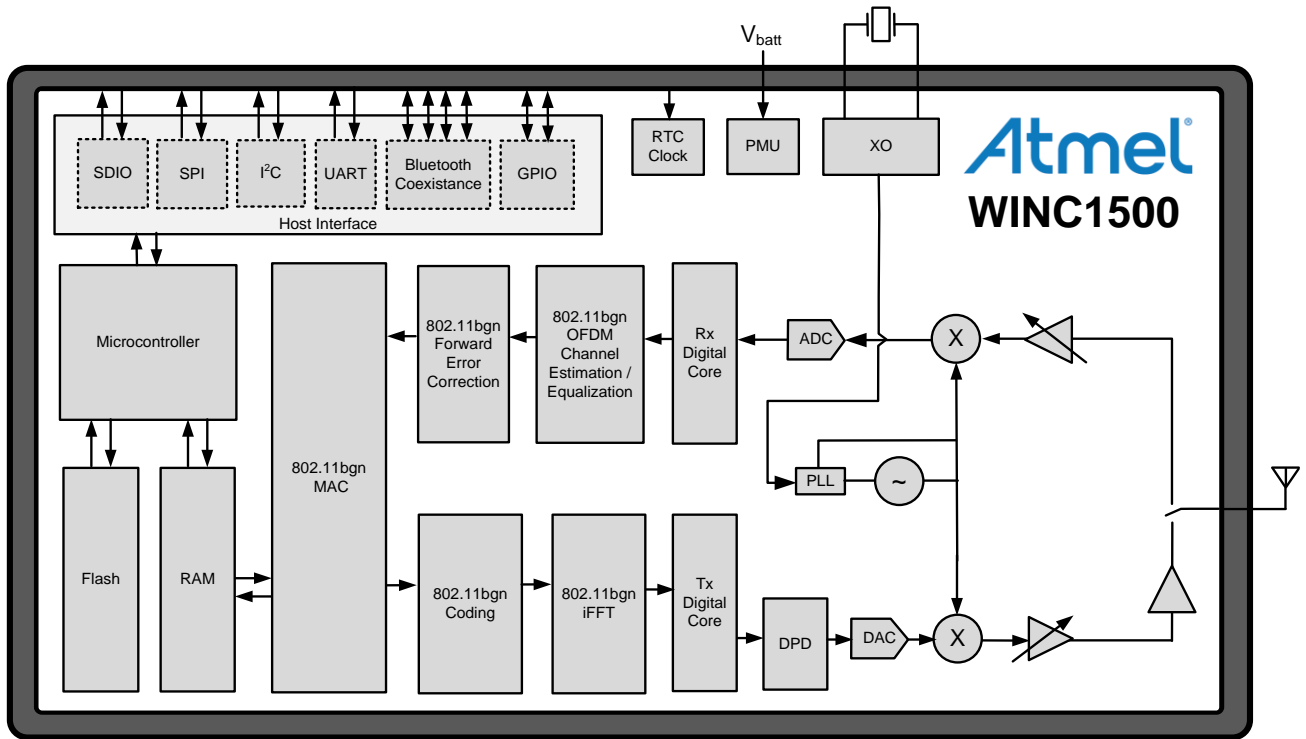
# 1    Ordering Information and IC Marking

Table 1-1.    Ordering Details

Atmel Official Part Number (for ordering)	Package Type	IC Marking
ATWINC1500A-MU	5x5 QFN in Tape and Reel	ATWINC1500A

# 2    Block Diagram

Figure 2-1.    ATWINC1500A Block Diagram

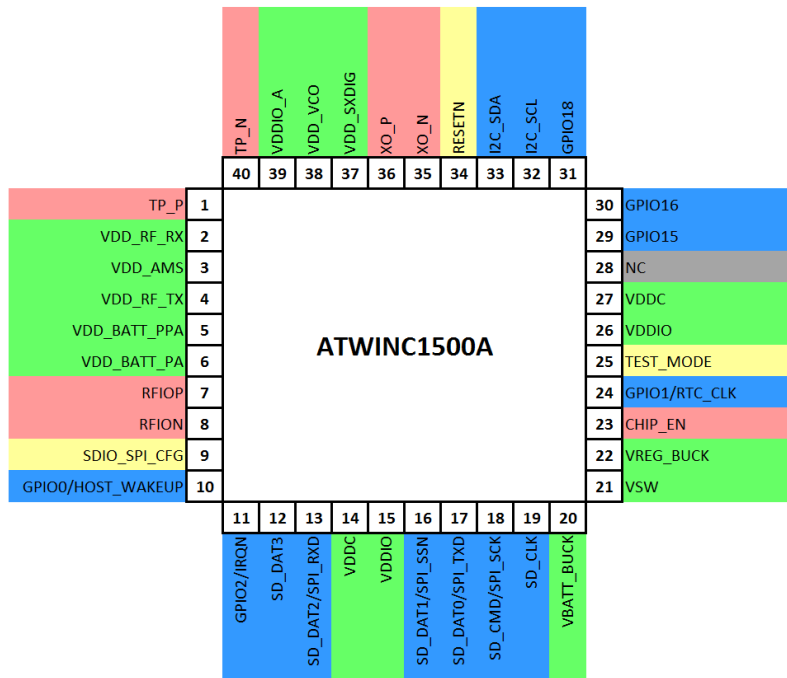


# 3    Pinout and Package Information

## 3.1    Pin Description

ATWINC1500A is offered in an exposed pad 40-pin QFN package. This package has an exposed paddle that must be connected to the system board ground. The QFN package pin assignment is shown in [Figure 3-1](#). The color shading is used to indicate the pin type as follows: green – power, red – analog, blue – digital I/O, yellow – digital input, grey – unconnected or reserved. The ATWINC1500A pins are described in [Table 3-1](#).

**Figure 3-1. Pin Assignment**



**Table 3-1. Pin Description**

Pin #	Pin Name	Pin Type	Description
1	TP_P	Analog	Test Pin/Customer No Connect
2	VDD_RF_RX	Power	Tuner RF Supply (see Section 9.1)
3	VDD_AMS	Power	Tuner BB Supply (see Section 9.1)
4	VDD_RF_TX	Power	Tuner RF Supply (see Section 9.1)
5	VDD_BATT_PPA	Power	PA 1 <sup>st</sup> Stage Supply (see Section 9.1)
6	VDD_BATT_PA	Power	PA 2 <sup>nd</sup> Stage Supply (see Section 9.1)
7	RFIO_P	Analog	Pos RF Differential I/O
8	RFIO_N	Analog	Neg RF Differential I/O
9	SDIO_SPI_CFG	Digital Input	Tie to 1 for SPI, 0 for SDIO
10	GPIO0/HOST_WAKE	Digital I/O, Programmable Pull-Up	GPIO0/SLEEP Mode Control
11	GPIO2/IRQN	Digital I/O, Programmable Pull-Up	GPIO2/Device Interrupt
12	SD_DAT3	Digital I/O, Programmable Pull-Up	SDIO Data3
13	SD_DAT2/SPI_RXD	Digital I/O, Programmable Pull-Up	SDIO Data2/SPI Data Rx
14	VDDC	Power	Digital Core Power Supply (see Section 9.1)
15	VDDIO	Power	Digital I/O Power Supply (see Section 9.1)
16	SD_DAT1/SPI_SSN	Digital I/O, Programmable Pull-Up	SDIO Data1/SPI Slave Select
17	SD_DAT0/SPI_TXD	Digital I/O, Programmable Pull-Up	SDIO Data0/SPI Data Tx
18	SD_CMD/SPI_SCK	Digital I/O, Programmable Pull-Up	SDIO Command/SPI Clock
19	SD_CLK	Digital I/O, Programmable Pull-Up	SDIO Clock

Pin #	Pin Name	Pin Type	Description
20	VBATT_BUCK	Power	Battery Supply for DC/DC Converter (see Section 9.1)
21	VSW	Power	Switching output of DC/DC Converter (see Section 9.1)
22	VREG_BUCK	Power	Core Power from DC/DC Converter (see Section 9.1)
23	CHIP_EN	Analog	PMU Enable
24	GPIO1/RTC_CLK	Digital I/O, Programmable Pull-Down	GPIO1/32kHz Clock Input
25	TEST_MODE	Digital Input	Test Mode – Customer Tie to GND
26	VDDIO	Power	Digital I/O Power Supply (see Section 9.1)
27	VDDC	Power	Digital Core Power Supply (see Section 9.1)
28	NC	None	Customer no connect
29	GPIO15	Digital I/O, Programmable Pull-Up	GPIO15
30	GPIO16	Digital I/O, Programmable Pull-Up	GPIO16
31	GPIO18	Digital I/O, Programmable Pull-Up	GPIO18
32	I2C_SCL <sup>1</sup>	Digital I/O, Programmable Pull-Up	I <sup>2</sup> C Slave Clock
33	I2C_SDA <sup>1</sup>	Digital I/O, Programmable Pull-Up	I <sup>2</sup> C Slave Data
34	RESETN	Digital Input	Active-Low Hard Reset
35	XO_N	Analog	Crystal Oscillator N
36	XO_P	Analog	Crystal Oscillator P
37	VDD_SXDIG	Power	SX Power Supply (see Section 9.1)
38	VDD_VCO	Power	VCO Power Supply (see Section 9.1)
39	VDDIO_A	Power	Tuner VDDIO Power Supply (see Section 9.1)
40	TP_N	Analog	Test Pin/Customer No Connect
41	PADDLE VSS	Power	Connect to System Board Ground

Note: 1. All digital IO have 2mA drive strength expect for I2C\_SCL/SDA which have 4mA.

## 3.2 Package Description

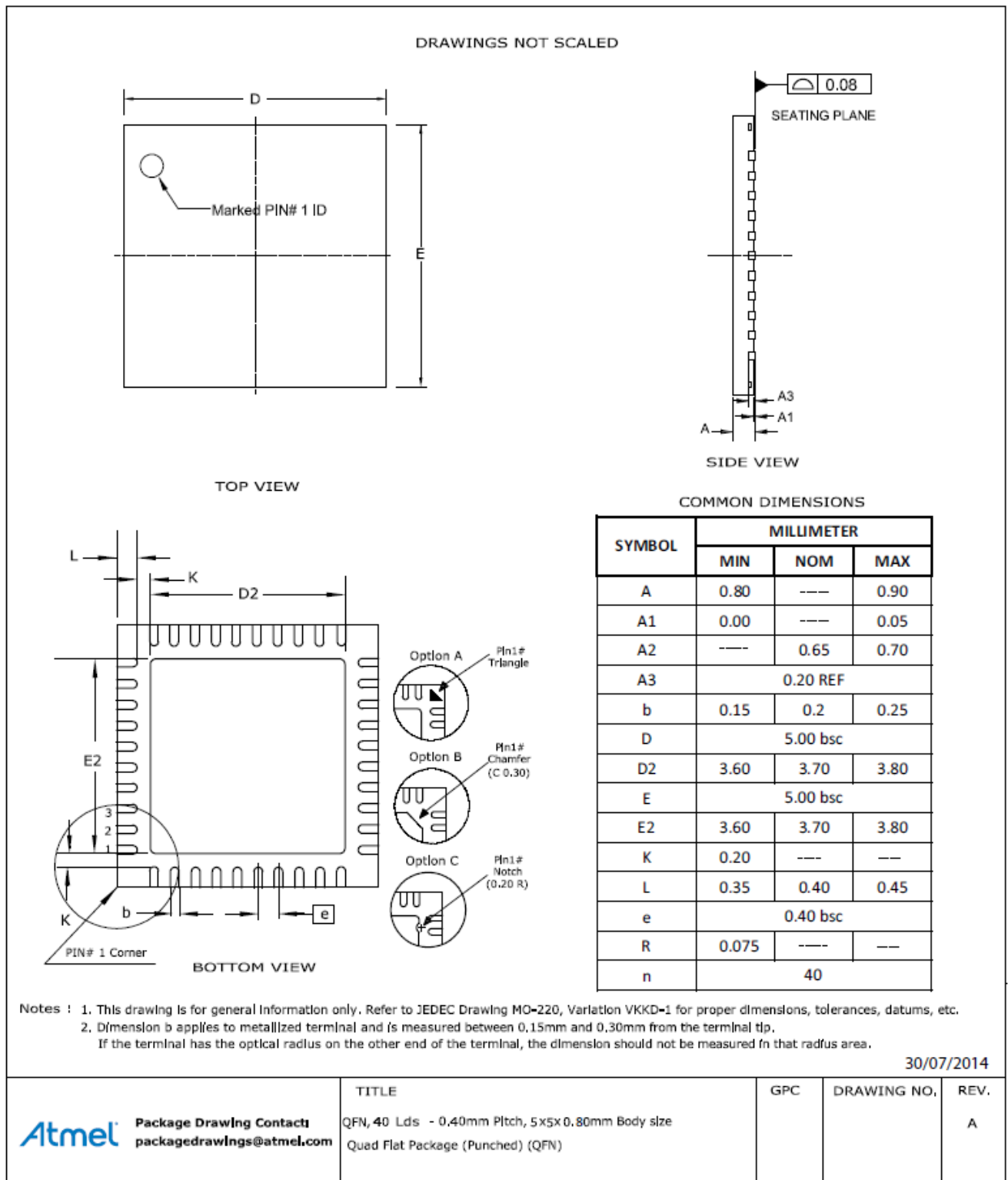
The ATWINC1500A QFN package information is provided in [Table 3-2](#).

**Table 3-2. QFN Package Information**

Parameter	Value	Units	
Package Size	5x5	mm	±0.1mm
QFN Pad Count	40		
Total Thickness	0.85	mm	±0.05mm
QFN Pad Pitch	0.40	mm	
Pad Width	0.20	mm	
Exposed Pad size	3.7x3.7	mm	

The ATWINC1500A 40L QFN package view is shown in Figure 3-2.

**Figure 3-2. QFN Package**



The QFN package is a qualified Green Package.



## 4 Electric Specifications

### 4.1 Absolute Ratings

Table 4-1. Absolute Maximum Ratings

Characteristic	Symbol	Min	Max	Unit
Core Supply Voltage	VDDC	-0.3	1.5	V
I/O Supply Voltage	VDDIO	-0.3	5.0	V
Battery Supply Voltage	VBATT	-0.3	5.0	V
Digital Input Voltage	V <sub>IN</sub>	-0.3	VDDIO	V
Analog Input Voltage	V <sub>ESDHBM</sub>	-0.3	1.5	V
ESD Human Body Model		-1000, -2000 (see notes below)	+1000, +2000 (see notes below)	V
Storage Temperature	T <sub>A</sub>	-65	150	°C
Junction Temperature			1225	°C
RF input power max			23	dBm

- Notes:
1. V<sub>IN</sub> corresponds to all the digital pins.
  2. V<sub>AIN</sub> corresponds to the following analog pins: VDD\_RF\_RX, VDD\_RF\_TX, VDD\_AMS, RFIO\_P, RFIO\_N, XO\_N, XO\_P, VDD\_SXDIG, VDD\_VCO.
  3. For V<sub>ESDHBM</sub>, each pin is classified as Class 1, or Class 2, or both:
    - The Class 1 pins include all the pins (both analog and digital)
    - The Class 2 pins are all digital pins only
    - V<sub>ESDHBM</sub> is ±1kV for Class1 pins. V<sub>ESDHBM</sub> is ±2kV for Class2 pins

### 4.2 Recommended Operating Conditions

Table 4-2. Recommended Operating Conditions

Characteristics	Symbol	Min	Typ	Max	Units
I/O Supply Voltage	VDDIO	2.7	3.3	3.6	V
Battery Supply Voltage	VBATT	3.0	3.6	4.2	
Operating Temperature		-40		85	°C

- Notes:
1. I/O supply voltage is applied to the following pins: VDDIO\_A, VDDIO.
  2. Battery supply voltage is applied to following pins: VDD\_BATT\_PPA, VDD\_BATT\_PA, VBATT\_BUCK.
  3. Refer to Sections 9.1 and Table 9-3 for the details of power connections.

## 4.3 DC Electric Characteristics

Table 4-3 provides the DC characteristics for the ATWINC1500A digital pads.

**Table 4-3. Electrical Characteristics**

VDDIO Condition	Characteristic	Min	Max	Unit
VDDIO <sub>L</sub>	Input Low Voltage V <sub>IL</sub>	-0.30	0.60	V
	Input High Voltage V <sub>IH</sub>	VDDIO-0.60	VDDIO+0.30	V
	Output Low Voltage V <sub>OL</sub>		0.45	V
	Output High Voltage V <sub>OH</sub>	VDDIO-0.50		V
VDDIO <sub>M</sub>	Input Low Voltage V <sub>IL</sub>	-0.30	0.63	V
	Input High Voltage V <sub>IH</sub>	VDDIO-0.60	VDDIO+0.30	V
	Output Low Voltage V <sub>OL</sub>		0.45	V
	Output High Voltage V <sub>OH</sub>	VDDIO-0.50		V
VDDIO <sub>H</sub>	Input Low Voltage V <sub>IL</sub>	-0.30	0.65	V
	Input High Voltage V <sub>IH</sub>	VDDIO-0.60	VDDIO+0.30 (up to 3.60)	V
	Output Low Voltage V <sub>OL</sub>		0.45	V
	Output High Voltage V <sub>OH</sub>	VDDIO-0.50		V
All	Output Loading		20	pF
All	Digital Input Load		6	pF

## 5 Clocking

### 5.1 Crystal Oscillator

**Table 5-1. Crystal Oscillator Parameters**

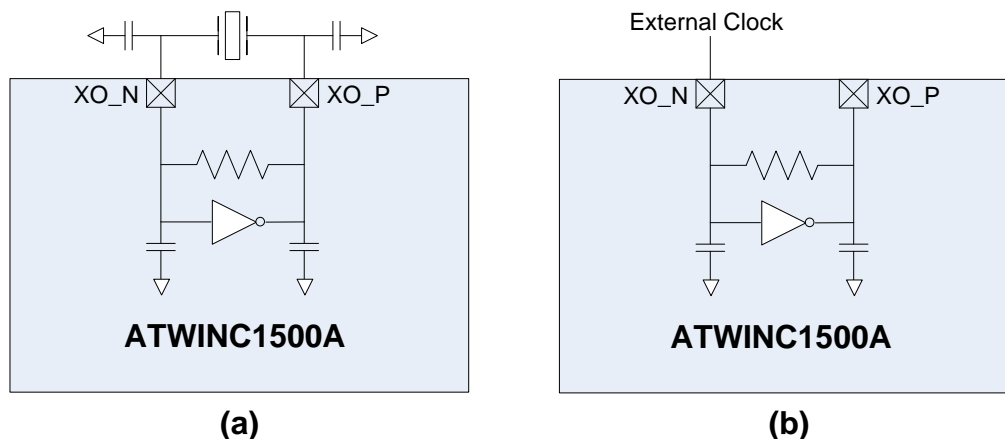
Parameter	Min	Typ	Max	Units
Crystal Resonant Frequency	12	26	40	MHz
Crystal Equivalent Series Resistance		50	150	Ω
Stability – Initial Off-set <sup>1</sup>	-100		100	ppm
Stability - Temperature and Aging	-25		25	ppm

Note: 1. Initial offset must be calibrated to maintain  $\pm 25$ ppm in all operating conditions. This calibration is performed during final production testing.

The block diagram in Figure 5-1(a) shows how the internal Crystal Oscillator (XO) is connected to the external crystal. The XO has 5pF internal capacitance on each terminal XO\_P and XO\_N. To bypass the crystal

oscillator with an external reference, an external signal capable of driving 5pF can be applied to the XO\_N terminal as shown [Figure 5-1\(b\)](#).

**Figure 5-1. XO Connections: (a) Crystal Oscillator is Used, (b) Crystal Oscillator is Bypassed**



[Table 5-2](#) specifies the electrical and performance requirements for the external clock.

**Table 5-2. Bypass Clock Specification**

Parameter	Min	Max	Unit	Comments
Oscillation frequency	12	32	MHz	Must be able to drive 5pF load @ desired frequency
Voltage swing	0.5	1.2	V <sub>pp</sub>	Must be AC coupled
Stability – Temperature and Aging	-25	+25	ppm	
Phase Noise		-130	dBc/Hz	At 10kHz offset
Jitter(RMS)		<1psec		Based on integrated phase noise spectrum from 1kHz to 1MHz

## 5.2 Low Power Oscillator

ATWINC1500A has an internally-generated 32kHz clock to provide timing information for various sleep functions. Alternatively, ATWINC1500A allows for an external 32kHz clock to be used for this purpose, which is provided through Pin 24 (RTC\_CLK). Software selects whether the internal clock or external clock is used.

The internal low-power clock is ring-oscillator based and has accuracy within 10,000ppm. When using the internal low-power clock, the advance wakeup time in beacon monitoring mode has to be increased by about 1% of the sleep time to compensate for the oscillator inaccuracy. For example, for the DTIM interval value of 1, wakeup time has to be increased by 1ms.

For any application targeting very low power consumption, an external 32kHz RTC clock should be used.

## 6 CPU and Memory Subsystems

### 6.1 Processor

ATWINC1500A has a Cortus APS3 32-bit processor. This processor performs many of the MAC functions, including but not limited to association, authentication, power management, security key management, and MSDU aggregation/de-aggregation. In addition, the processor provides flexibility for various modes of operation, such as STA and AP modes.

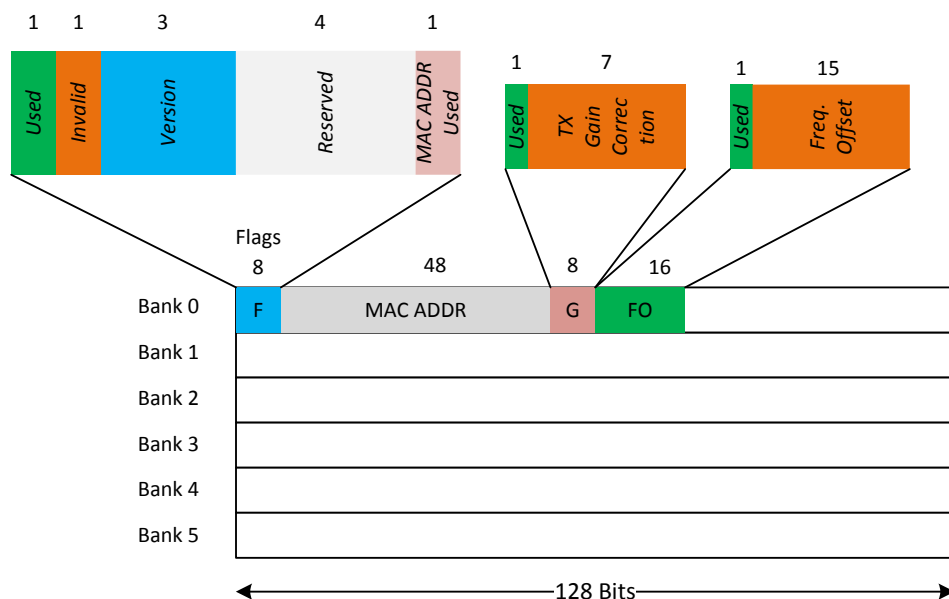
### 6.2 Memory Subsystem

The APS3 core uses a 128KB instruction/boot ROM along with a 128KB instruction RAM and a 64KB data RAM. ATWINC1500A also has 4Mb of flash memory, which can be used for system software. In addition, the device uses a 128KB shared RAM, accessible by the processor and MAC, which allows the APS3 core to perform various data management tasks on the TX and RX data packets.

### 6.3 Non-Volatile Memory (EFuse)

ATWINC1500A has 768 bits of non-volatile EFuse memory that can be read by the CPU after device reset. This non-volatile one-time-programmable (OTP) memory can be used to store customer-specific parameters, such as MAC address; various calibration information, such as TX power, crystal frequency offset, etc.; and other software-specific configuration parameters. The EFuse is partitioned into six 128-bit banks. Each bank has the same bit map, which is shown in Figure 6-1. The purpose of the first 80 bits in each bank is fixed, and the remaining 48 bits are general-purpose software dependent bits, or reserved for future use. Since each bank can be programmed independently, this allows for several updates of the device parameters following the initial programming, e.g. updating MAC address. Refer to ATWINC1500A Programming Guide for the EFuse programming instructions.

Figure 6-1. EFuse Bit Map



## 7 WLAN Subsystem

The WLAN subsystem is composed of the Media Access Controller (MAC) and the Physical Layer (PHY). The following two subsections describe the MAC and PHY in detail.

### 7.1 MAC

#### 7.1.1 Features

The ATWINC1500A IEEE802.11 MAC supports the following functions:

- IEEE 802.11b/g/n
- IEEE 802.11e WMM QoS EDCA/PCF multiple access categories traffic scheduling
- Advanced IEEE 802.11n features:
  - Transmission and reception of aggregated MPDUs (A-MPDU)
  - Transmission and reception of aggregated MSDUs (A-MSDU)
  - Immediate Block Acknowledgement
  - Reduced Interframe Spacing (RIFS)
- Support for IEEE802.11i and WPA security with key management
  - WEP 64/128
  - WPA-TKIP
  - 128-bit WPA2 CCMP (AES)
- Support for WAPI security
- Advanced power management
  - Standard 802.11 Power Save Mode
  - Wi-Fi Alliance WMM-PS (U-APSD)
- RTS-CTS and CTS-self support
- Supports either STA or AP mode in the infrastructure basic service set mode
- Supports independent basic service set (IBSS)

#### 7.1.2 Description

The ATWINC1500A MAC is designed to operate at low power while providing high data throughput. The IEEE 802.11 MAC functions are implemented with a combination of dedicated datapath engines, hardwired control logic, and a low-power, high-efficiency microprocessor. The combination of dedicated logic with a programmable processor provides optimal power efficiency and real-time response while providing the flexibility to accommodate evolving standards and future feature enhancements.

Dedicated datapath engines are used to implement data path functions with heavy computational. For example, an FCS engine checks the CRC of the transmitting and receiving packets, and a cipher engine performs all the required encryption and decryption operations for the WEP, WPA-TKIP, WPA2 CCMP-AES, and WAPI security requirements.

Control functions which have real-time requirements are implemented using hardwired control logic modules. These logic modules offer real-time response while maintaining configurability via the processor. Examples of hardwired control logic modules are the channel access control module (implements EDCA/HCCA, Beacon TX control, interframe spacing, etc.), protocol timer module (responsible for the Network Access Vector, back-off timing, timing synchronization function, and slot management), MPDU handling module, aggregation/de-aggregation module, block ACK controller (implements the protocol requirements for burst block communication), and TX/RX control FSMs (coordinate data movement between PHY-MAC interface, cipher engine, and the DMA interface to the TX/RX FIFOs).

The MAC functions implemented solely in software on the microprocessor have the following characteristics:

- Functions with high memory requirements or complex data structures. Examples are association table management and power save queuing.
- Functions with low computational load or without critical real-time requirements. Examples are authentication and association.
- Functions which need flexibility and upgradeability. Examples are beacon frame processing and QoS scheduling.

## 7.2 PHY

### 7.2.1 Features

The ATWINC1500A IEEE802.11 PHY supports the following functions:

- Single antenna 1x1 stream in 20MHz channels
- Supports IEEE 802.11b DSSS-CCK modulation: 1, 2, 5.5, 11Mbps
- Supports IEEE 802.11g OFDM modulation: 6, 9, 12, 18, 24, 36, 48, 54Mbps
- Supports IEEE 802.11n HT modulations MCS0-7, 20MHz, 800 and 400ns guard interval: 6.5, 7.2, 13.0, 14.4, 19.5, 21.7, 26.0, 28.9, 39.0, 43.3, 52.0, 57.8, 58.5, 65.0, 72.2Mbps
- IEEE 802.11n mixed mode operation
- Per packet TX power control
- Advanced channel estimation/equalization, automatic gain control, CCA, carrier/symbol recovery, and frame detection

### 7.2.2 Description

The ATWINC1500A WLAN PHY is designed to achieve reliable and power-efficient physical layer communication specified by IEEE 802.11 b/g/n in single stream mode with 20MHz bandwidth. Advanced algorithms have been employed to achieve maximum throughput in a real world communication environment with impairments and interference. The PHY implements all the required functions such as FFT, filtering, FEC (Viterbi decoder), frequency and timing acquisition and tracking, channel estimation and equalization, carrier sensing and clear channel assessment, as well as the automatic gain control.

## 7.3 Radio

### 7.3.1 Receiver Performance

Radio Performance under Typical Conditions: VBAT=3.6V; VDDIO=3.3V; Temp: 25°C.

**Table 7-1. Receiver Performance**

Parameter	Description	Unit	Minimum	Typical	Maximum
Frequency		MHz	2,412		2,484
Sensitivity 802.11b	1Mbps DSS	dBm		-98	
	2Mbps DSS	dBm		-94	
	5.5Mbps DSS	dBm		-92	
	11Mbps DSS	dBm		-88	
Sensitivity 802.11g	6Mbps OFDM	dBm		-90	
	9Mbps OFDM	dBm		-89	

Parameter	Description	Unit	Minimum	Typical	Maximum
	12Mbps OFDM	dBm		-88	
	18Mbps OFDM	dBm		-85	
	24Mbps OFDM	dBm		-83	
	36Mbps OFDM	dBm		-80	
	48Mbps OFDM	dBm		-76	
	54Mbps OFDM	dBm		-74	
Sensitivity 802.11n (BW=20MHz)	MCS 0	dBm		-89	
	MCS 1	dBm		-87	
	MCS 2	dBm		-85	
	MCS 3	dBm		-82	
	MCS 4	dBm		-77	
	MCS 5	dBm		-74	
	MCS 6	dBm		-72	
	MCS 7	dBm		-71	
Maximum Receive Signal Level	1-11Mbps DSS	dBm		0	
	6-54Mbps OFDM	dBm		0	
	MCS 0 – 7	dBm		0	
Adjacent Channel Re- jection	1Mbps DSS (30MHz offset)	dB		50	
	11Mbps DSS (25MHz offset)	dB		43	
	6Mbps OFDM (25MHz offset)	dB		40	
	54Mbps OFDM (25MHz offset)	dB		25	
	MCS 0 – 20MHz BW (25MHz offset)	dB		40	
	MCS 7 – 20MHz BW (25MHz offset)	dB		20	
Cellular Blocker Im- munity	776-794MHz CDMA	dBm		-14	
	824-849MHz GSM	dBm		-10	
	880-915MHz GSM	dBm		-10	
	1710-1785MHz GSM	dBm		-15	
	1850-1910MHz GSM	dBm		-15	
	1850-1910MHz WCDMA	dBm		-24	
	1920-1980MHz WCDMA	dBm		-24	

### 7.3.2 Transmitter Performance

Radio Performance under Typical Conditions: VBAT=3.6V; VDDIO=3.3V; Temp: 25°C.

**Table 7-2. Transmitter Performance**

Parameter	Description	Unit	Minimum	Typical <sup>3</sup>	Maximum
Frequency		MHz	2,412		2,484
Output Power	802.11b DSSS 1Mbps	dBm		20.6 <sup>1</sup>	
	802.11b DSSS 11Mbps	dBm		20.6 <sup>1</sup>	
	802.11g OFDM 6Mbps	dBm		20.5 <sup>1</sup>	
	802.11g OFDM 54Mbps	dBm		17.8 <sup>1</sup>	
	802.11n HT20 MCS 0	dBm		18.8 <sup>1</sup>	
	802.11n HT20 MCS 7	dBm		15.3 <sup>1</sup>	
Tx Power Accuracy		dB		±1.5 <sup>2</sup>	
Carrier Suppression		dBc		30.0	
Out of Band Transmit Power	76-108	dBm/Hz		-125	
	776-794	dBm/Hz		-125	
	869-960	dBm/Hz		-125	
	925-960	dBm/Hz		-125	
	1570-1580	dBm/Hz		-125	
	1805-1880	dBm/Hz		-125	
	1930-1990	dBm/Hz		-125	
	2110-2170	dBm/Hz		-125	
Harmonic Output Power	2 <sup>nd</sup>	dBm/MHz		-33	
	3 <sup>rd</sup>	dBm/MHz		-38	

- Notes: 1. Measured at 802.11 spec compliant EVM/Spectral Mask.  
2. Measured at RF Pin assuming 50Ω differential.  
3. RF performance guaranteed for Temp range -30 to 85deg. 1dB derating in performance at -40deg.

## 8 External Interfaces

ATWINC1500A external interfaces include I<sup>2</sup>C Slave for control, SPI Slave and SDIO Slave for control and data transfer, I<sup>2</sup>C Master for external EEPROM, UART for debug, control, and data transfer, General Purpose Input/Output (GPIO) pins, and a Wi-Fi/Bluetooth coexistence interface. With the exception of the SPI Slave and SDIO Slave host interfaces, which are selected using the dedicated SDIO\_SPI\_CFG pin, the other interfaces can be assigned to various pins by programming the corresponding pin muxing control register for each pin to a specific value between 0 and 6. The default values of these registers are 0, which is GPIO mode. The summary of the available interfaces and their corresponding pin mux settings is shown in [Table 8-1](#). For specific programming instructions refer to ATWINC1500A Programming Guide.



**Table 8-1. Pin-Mux Matrix of External Interfaces**

Pin Name	Mux 0	Mux 1	Mux 2	Mux3	Mux4	Mux6
GPIO0/HOST_WAKE	GPIO_0	I_HOST_WAKEUP		O_UART_TXD	IO_I2C_MASTER_SCL	IO_COE
GPIO2/IRQN	GPIO_2	O_IRQN		I_UART_RXD		IO_COE
SD_DAT3	GPIO_7	IO_SD_DAT3		O_UART_TXD		IO_COE
SD_DAT2/SPI_RXD		IO_SD_DA2	I_SPI_RXD			
SD_DAT1/SPI_SSN		IO_SD_DAT1	IO_SPI_SSN			
SD_DAT0/SPI_TXD		IO_SD_DAT0	O_SPI_TXD			
SD_CMD/SPI_SCK		IO_SD_CMD	IO_SPI_SCK			
SD_CLK	GPIO_8	I_SD_CLK		I_UART_RXD		IO_COE
GPIO1/RTC_CLK	GPIO_1	I_RTC_CLK		I_UART_RXD	IO_I2C_MASTER_SDA	IO_COE
GPIO15	GPIO_15					
GPIO16	GPIO_16					
GPIO18	GPIO_18					
I2C_SCL		IO_I2C_SCL		I_RTC_CLK	IO_I2C_MASTER_SCL	IO_COE
I2C_SDA		IO_I2C_SDA			IO_I2C_MASTER_SDA	IO_COE

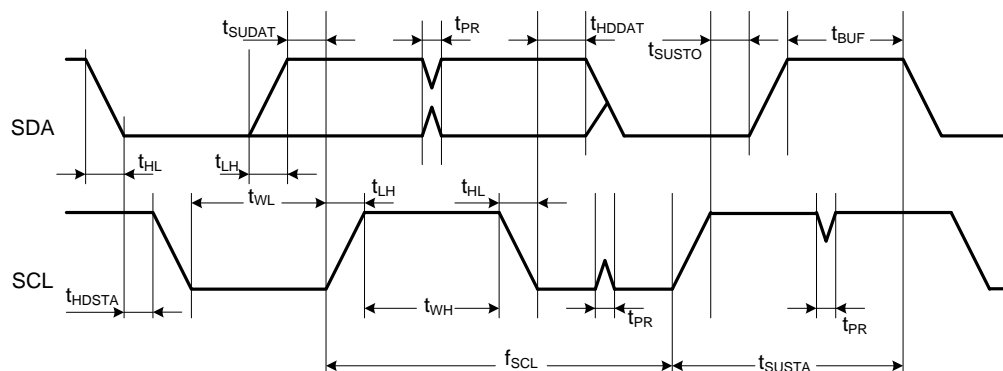
## 8.1 I<sup>2</sup>C Slave Interface

The I<sup>2</sup>C Slave interface, used primarily for control by the host processor, is a two-wire serial interface consisting of a serial data line (SDA, Pin 33) and a serial clock (SCL, Pin 32). It responds to the seven bit address value 0x60. The ATWINC1500A I<sup>2</sup>C supports I<sup>2</sup>C bus Version 2.1 - 2000 and can operate in standard mode (with data rates up to 100Kb/s) and fast mode (with data rates up to 400Kb/s).

The I<sup>2</sup>C Slave is a synchronous serial interface. The SDA line is a bidirectional signal and changes only while the SCL line is low, except for STOP, START, and RESTART conditions. The output drivers are open-drain to perform wire-AND functions on the bus. The maximum number of devices on the bus is limited by only the maximum capacitance specification of 400pF. Data is transmitted in byte packages.

For specific information, refer to the Philips Specification entitled “The I<sup>2</sup>C -Bus Specification, Version 2.1”.

The I<sup>2</sup>C Slave timing is provided in [Figure 8-1](#) and [0](#).

**Figure 8-1. I<sup>2</sup>C Slave Timing Diagram**

**Table 8-2. I<sup>2</sup>C Slave Timing Parameters**

Parameter	Symbol	Min	Max	Units	Remarks
SCL Clock Frequency	f <sub>SCL</sub>	0	400	kHz	
SCL Low Pulse Width	t <sub>WL</sub>	1.3		μs	
SCL High Pulse Width	t <sub>WH</sub>	0.6		μs	
SCL, SDA Fall Time	t <sub>HL</sub>		300	ns	
SCL, SDA Rise Time	t <sub>LH</sub>		300	ns	This is dictated by external components
START Setup Time	t <sub>SUSTA</sub>	0.6		μs	
START Hold Time	t <sub>HDSTA</sub>	0.6		μs	
SDA Setup Time	t <sub>SUDAT</sub>	100		ns	
SDA Hold Time	t <sub>HDDAT</sub>	0 40		ns ns	Slave and Master Default Master Programming Option
STOP Setup time	t <sub>SUSTO</sub>	0.6		μs	
Bus Free Time Between STOP and START	t <sub>BUF</sub>	1.3		μs	
Glitch Pulse Reject	t <sub>PR</sub>	0	50	ns	

## 8.2 I<sup>2</sup>C Master Interface

ATWINC1500A provides an I<sup>2</sup>C bus master, which is intended primarily for accessing an external EEPROM memory through a software-defined protocol. The I<sup>2</sup>C Master is a two-wire serial interface consisting of a serial data line (SDA) and a serial clock line (SCL). SDA can be configured on one of the following pins: GPIO1 (pin 24) or I2C\_SDA (pin 33). SCL can be configured on one of the following pins: GPIO0 (pin 10) or I2C\_SCL (pin 32). For more specific instructions refer to ATWINC1500A Programming Guide.

The I<sup>2</sup>C Master interface supports three speeds:

- Standard mode (100kb/s)
- Fast mode (400kb/s)
- High-speed mode (3.4Mb/s)

The timing diagram of the I<sup>2</sup>C Master interface is the same as that of the I<sup>2</sup>C Slave interface (see [Figure 8-1](#)). The timing parameters of I<sup>2</sup>C Master are shown in [Table 8-3](#).

**Table 8-3. I<sup>2</sup>C Master Timing Parameters**

Parameter	Symbol	Standard Mode		Fast Mode		High-Speed Mode		Units
		Min	Max	Min	Max	Min	Max	
SCL Clock Frequency	f <sub>SCL</sub>	0	100	0	400	0	3400	kHz
SCL Low Pulse Width	t <sub>WL</sub>	4.7		1.3		0.16		μs
SCL High Pulse Width	t <sub>WH</sub>	4		0.6		0.06		μs
SCL Fall Time	t <sub>HLSCL</sub>		300		300	10	40	ns
SDA Fall Time	t <sub>HLSDA</sub>		300		300	10	80	ns
SCL Rise Time	t <sub>LHSCL</sub>		1000		300	10	40	ns

Parameter	Symbol	Standard Mode		Fast Mode		High-Speed Mode		Units
		Min	Max	Min	Max	Min	Max	
SDA Rise Time	$t_{LHSDA}$		1000		300	10	80	ns
START Setup Time	$t_{SUSTA}$	4.7		0.6		0.16		$\mu$ s
START Hold Time	$t_{HSDTA}$	4		0.6		0.16		$\mu$ s
SDA Setup Time	$t_{SUDAT}$	250		100		10		ns
SDA Hold Time	$t_{HDDAT}$	5		40		0	70	ns
STOP Setup time	$t_{SUSTO}$	4		0.6		0.16		$\mu$ s
Bus Free Time Between STOP and START	$t_{BUF}$	4.7		1.3				$\mu$ s
Glitch Pulse Reject	$t_{PR}$			0	50			ns

### 8.3 SPI Slave Interface

ATWINC1500A provides a Serial Peripheral Interface (SPI) that operates as a SPI slave. The SPI Slave interface can be used for control and for serial I/O of 802.11 data. The SPI Slave pins are mapped as shown in [Table 8-4](#). The RXD pin is same as Master Output, Slave Input (MOSI), and the TXD pin is same as Master Input, Slave Output (MISO). The SPI Slave is a full-duplex slave-synchronous serial interface that is available immediately following reset when pin 9 (SDIO\_SPI\_CFG) is tied to VDDIO.

**Table 8-4. SPI Slave Interface Pin Mapping**

Pin #	SPI Function
9	CFG: Must be tied to VDDIO
16	SSN: Active Low Slave Select
18	SCK: Serial Clock
13	RXD: Serial Data Receive (MOSI)
17	TXD: Serial Data Transmit (MISO)

When the SPI is not selected, i.e., when SSN is high, the SPI interface will not interfere with data transfers between the serial-master and other serial-slave devices. When the serial slave is not selected, its transmitted data output is buffered, resulting in a high impedance drive onto the serial master receive line.

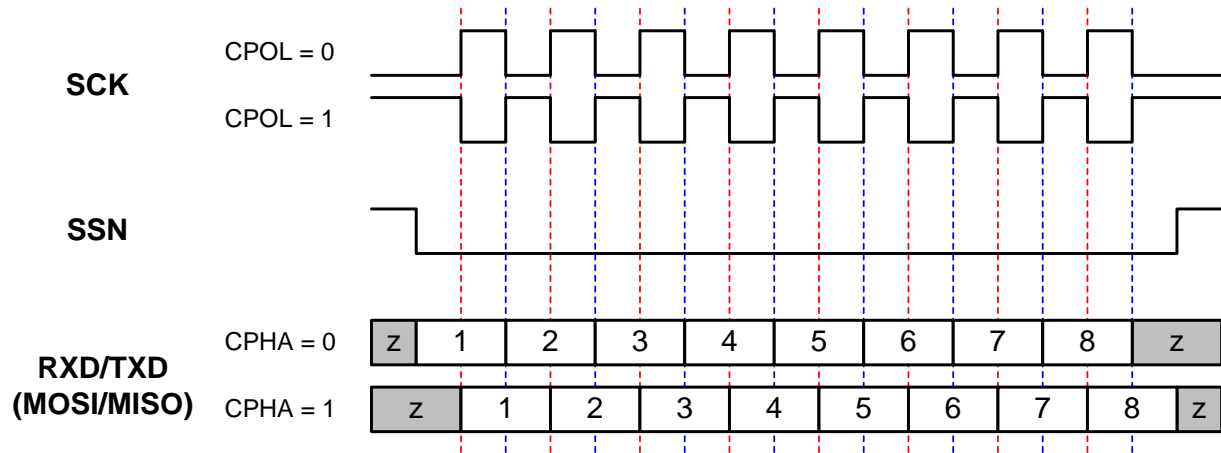
The SPI Slave interface responds to a protocol that allows an external host to read or write any register in the chip as well as initiate DMA transfers. For the details of the SPI protocol and more specific instructions refer to ATWINC1500A Programming Guide.

The SPI Slave interface supports four standard modes as determined by the Clock Polarity (CPOL) and Clock Phase (CPHA) settings. These modes are illustrated in [0](#) and [Figure 8-2](#). The red lines in [Figure 8-2](#) correspond to Clock Phase = 0 and the blue lines correspond to Clock Phase = 1.

**Table 8-5. SPI Slave Modes**

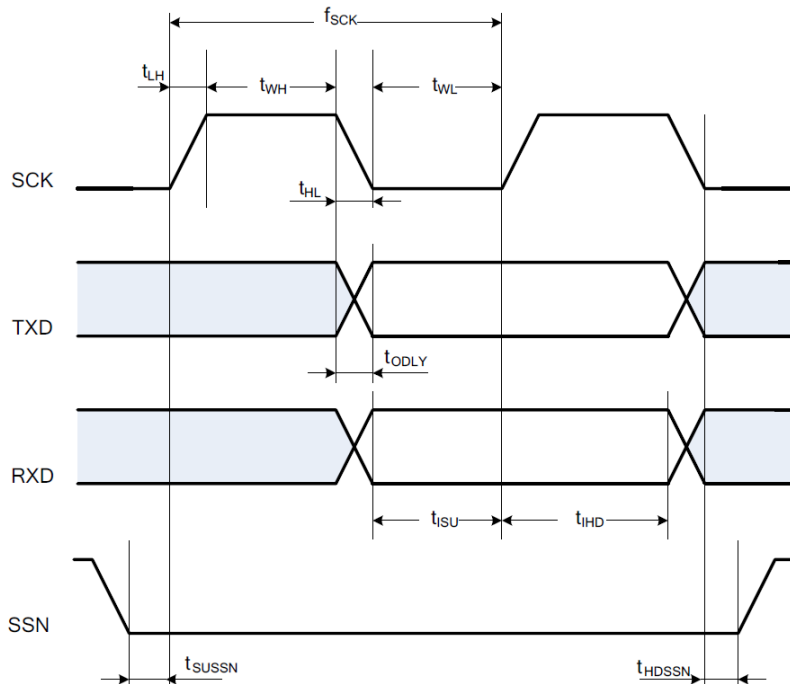
Mode	CPOL	CPHA
0	0	0
1	0	1
2	1	0
3	1	1

**Figure 8-2. SPI Slave Clock Polarity and Clock Phase Timing**



The SPI Slave timing is provided in [Figure 8-3](#) and [Table 8-6](#).

**Figure 8-3. SPI Slave Timing Diagram**



**Table 8-6. SPI Slave Timing Parameters**

Parameter	Symbol	Min	Max	Units
Clock Input Frequency	$f_{SCK}$		48	MHz
Clock Low Pulse Width	$t_{WL}$	15		ns
Clock High Pulse Width	$t_{WH}$	15		ns
Clock Rise Time	$t_{LH}$		10	ns
Clock Fall Time	$t_{HL}$		10	ns
Input Setup Time	$t_{ISU}$	5		ns
Input Hold Time	$t_{IHD}$	5		ns
Output Delay	$t_{ODLY}$	0	20	ns
Slave Select Setup Time	$t_{SUSSN}$	5		ns
Slave Select Hold Time	$t_{HDSSN}$	5		ns

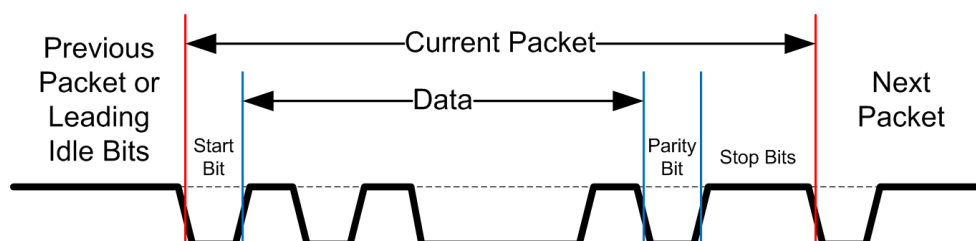
## 8.4 UART

ATWINC1500A has a Universal Asynchronous Receiver/Transmitter (UART) interface for serial communication. It is intended primarily for debugging, and it can also be used for control or data transfer if the baud rate is sufficient for a given application. The UART is compatible with the RS-232 standard, where ATWINC1500A operates as Data Terminal Equipment (DTE). It has a two-pin RXD/TXD interface, where RXD can be enabled on one of four alternative pins and TXD can be enabled on one of three alternative pins by programming their corresponding pin mux control registers to 3 (see [Table 8-1](#)). The UART features programmable baud rate generation with fractional clock division, which allows transmission and reception at a wide variety of standard and non-standard baud rates. The UART input clock is selectable between 10MHz, 5MHz, 2.5MHz, and 1.25MHz. The clock divider value is programmable as 13 integer bits and 3 fractional bits (with 8.0 being the smallest recommended value for normal operation). This results in the maximum supported baud rate of  $10\text{MHz}/8.0 = 1.25\text{MBd}$ .

The UART can be configured for seven or eight bit operation, with or without parity, with four different parity types (odd, even, mark, or space), and with one or two stop bits. It also has Rx and Tx FIFOs, which ensure reliable high speed reception and low software overhead transmission. FIFO size is 4x8 for both Rx and Tx direction. The UART also has status registers showing the number of received characters available in the FIFO and various error conditions, as well the ability to generate interrupts based on these status bits.

An example of UART receiving or transmitting a single packet is shown in [Figure 8-4](#). This example shows 7-bit data (0x45), odd parity, and two stop bits.

For more specific instructions refer to ATWINC1500A Programming Guide.

**Figure 8-4. Example of UART Rx or Tx Packet**

## 8.5 Wi-Fi/Bluetooth Coexistence

ATWILC1000A supports 2-wire and 3-wire Wi-Fi/Bluetooth Coexistence signaling conforming to the IEEE 802.15.2-2003 standard, Part 15.2. The type of coexistence interface used (2 or 3 wire) is chosen to be compatible with the specific Bluetooth device used in a given application. [Table 8-7](#) shows a usage example of the 2-wire interface using the GPIO3 and GPIO4 pins; 3-wire interface using the GPIO3, GPIO4, and GPIO5 pins; for more specific instructions on configuring Coexistence refer to ATWILC1000A Programming Guide.

**Table 8-7. Coexistence Pin Assignment Example**

Pin Name	Function	Target	Pin #	2-wire	3-wire
GPIO3	BT_Req	BT is requesting to access the medium to transmit or receive. Goes high on TX or RX slot.	28	Used	Used
GPIO4	BT_Pri	Priority of the BT packets in the requested slot. High to indicate high priority and low for normal.	29	Not Used	Used
GPIO5	WL_Act	Device response to the BT request. High - BT_req is denied and BT slot blocked.	30	Used	Used
GPIO6	Ant_SW	Direct control on Antenna (coex bypass).	31	Optional	Optional

## 8.6 GPIOs

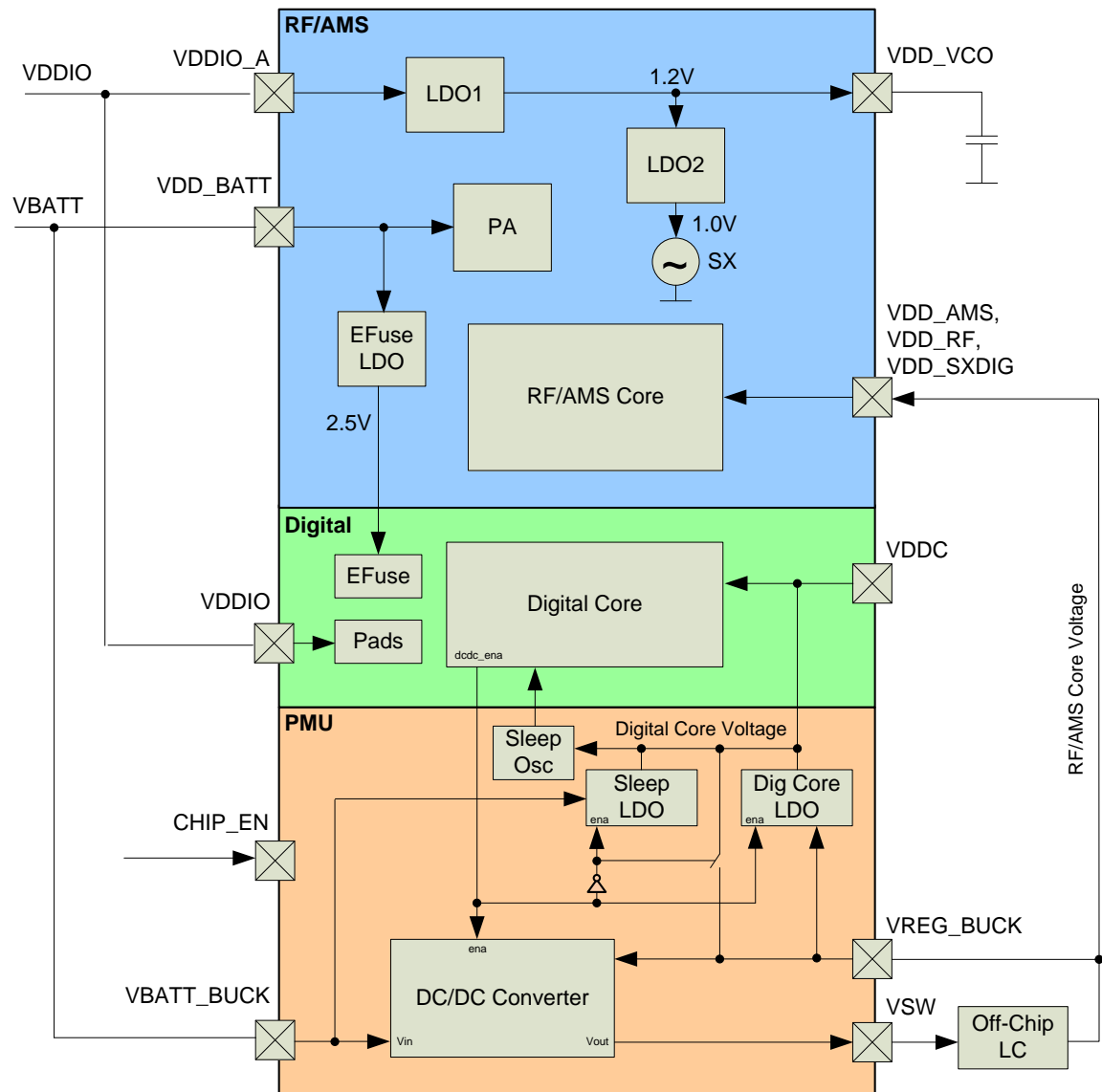
Eight General Purpose Input/Output (GPIO) pins, labeled GPIO0, GPIO1, GPIO2, GPIO7, GPIO8, GPIO15, GPIO16, and GPIO18, are available to allow for application specific functions. Each GPIO pin can be programmed as an input (the value of the pin can be read by the host or internal processor) or as an output (the output values can be programmed by the host or internal processor), where the default mode after power-up is input. GPIOs 7 and 8 are only available when the host does not use the SDIO interface, which shares two of its pins with these GPIOs. Therefore, for SDIO-based applications, six GPIOs are available. For more specific usage instructions refer to ATWILC1500A Programming Guide.

# 9 Power Management

## 9.1 Power Architecture

ATWILC1500A uses an innovative power architecture to eliminate the need for external regulators and reduce the number of off-chip components. This architecture is shown in [Figure 9-1](#). The Power Management Unit (PMU) has a DC/DC Converter that converts VBATT to the core supply used by the digital and RF/AMS blocks. [Table 9-1](#) shows the typical values for the digital and RF/AMS core voltages. The PA and EFuse are supplied by dedicated LDOs, and the VCO is supplied by a separate LDO structure.

**Figure 9-1. Power Architecture**



**Table 9-1. PMU Output Voltages**

Parameter	Typical
RF/AMS Core Voltage (VREG_BUCK)	1.35V
Digital Core Voltage (VDDC)	1.10V

The power connections in [Figure 9-1](#) provide a conceptual framework for understanding the ATWINC1500A power architecture. Refer to the reference design in [Chapter 10](#) for an example of power supply connections, including proper isolation of the supplies used by the digital and RF/AMS blocks.

## 9.2 Power Consumption

### 9.2.1 Description of Device States

ATWINC1500A has several Device States:

- ON\_Transmit – Device is actively transmitting an 802.11 signal
- ON\_Receive – Device is actively receiving an 802.11 signal
- ON\_Doze – Device is on but is neither transmitting nor receiving
- Power\_Down – Device core supply off (Leakage)
- IDLE connect – Device is connected with 1 DTIM beacon interval

### 9.2.2 Controlling the Device States

Table 9-2 shows how to switch between the device states using the following:

- CHIP\_EN – Device pin (pin #23) used to enable DC/DC Converter
- VDDIO – I/O supply voltage from external supply

Table 9-2. Device States

Device State	CHIP_EN	VDDIO	Power Consumption <sup>1</sup>	
			I <sub>VBATT</sub>	I <sub>VDDIO</sub>
ON_Transmit	VDDIO	On	230mA @ 18dBm	29mA
ON_Receive	VDDIO	On	68mA	29mA
ON_Doze	VDDIO	On	280μA	<10μA
Power_Down	GND	On	<0.5μA	<0.2μA

Note: 1. Conditions: VBAT @ 3.6v, IO@1.8V.

### 9.2.3 Restrictions for Power States

When no power supplied to the device, i.e., the DC/DC Converter output and VDDIO are both off (at ground potential). In this case, a voltage cannot be applied to the device pins because each pin contains an ESD diode from the pin to supply. This diode will turn on when voltage higher than one diode-drop is supplied to the pin.

If a voltage must be applied to the signal pads while the chip is in a low power state, the VDDIO supply must be on, so the SLEEP or Power\_Down state must be used.

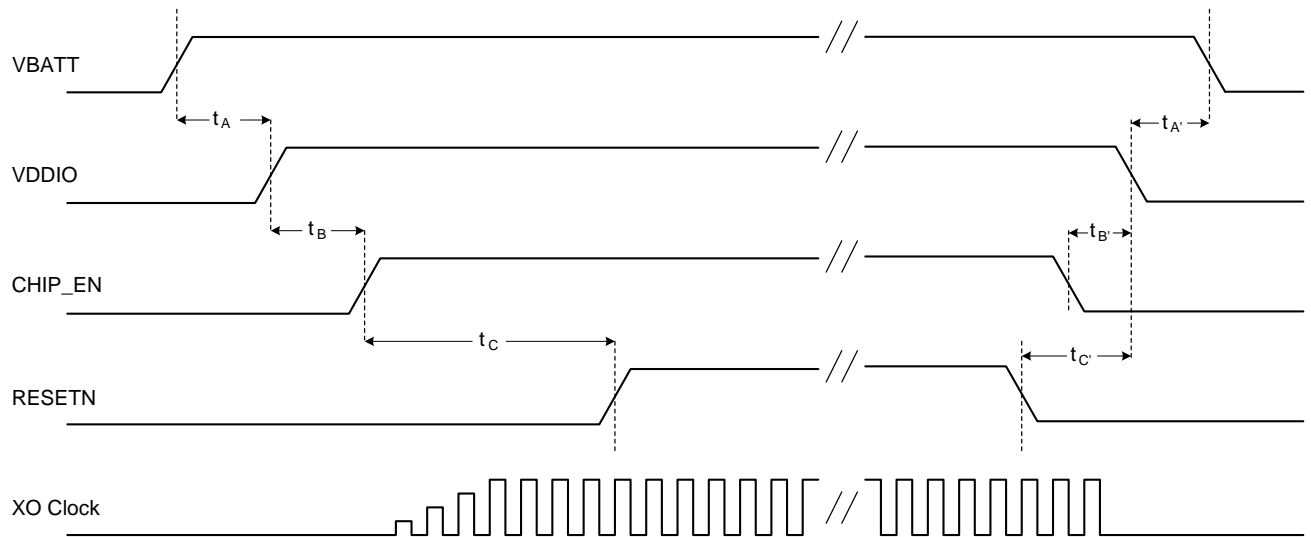
Similarly, to prevent the pin-to-ground diode from turning on, do not apply a voltage that is more than one diode-drop below ground to any pin.

## 9.3 Power-Up/Down Sequence

The power-up/down sequence for ATWILC1000A is shown in Figure 9-2. The timing parameters are provided in Table 9-3.



**Figure 9-2. Power Up/Down Sequence**



**Table 9-3. Power-Up/Down Sequence Timing**

Parameter	Min	Max	Units	Description	Notes
t <sub>A</sub>	0		ms	VBATT rise to VDDIO rise	VBATT and VDDIO can rise simultaneously or can be tied together. VDDIO must not rise before VBATT.
t <sub>B</sub>	0		ms	VDDIO rise to CHIP_EN rise	CHIP_EN must not rise before VDDIO. CHIP_EN must be driven high or low, not left floating.
t <sub>C</sub>	5		ms	CHIP_EN rise to RESETN rise	This delay is needed because XO clock must stabilize before RESETN removal. RESETN must be driven high or low, not left floating.
t <sub>A'</sub>	0		ms	VDDIO fall to VBATT fall	VBATT and VDDIO can fall simultaneously or can be tied together. VBATT must not fall before VDDIO.
t <sub>B'</sub>	0		ms	CHIP_EN fall to VDDIO fall	VDDIO must not fall before CHIP_EN. CHIP_EN and RESETN can fall simultaneously.
t <sub>C'</sub>	0		ms	RESETN fall to VDDIO fall	VDDIO must not fall before RESETN. RESETN and CHIP_EN can fall simultaneously.

## 9.4 Digital I/O Pin Behavior during Power-Up Sequences

Table 9-4 represents digital IO Pin states corresponding to device power modes.

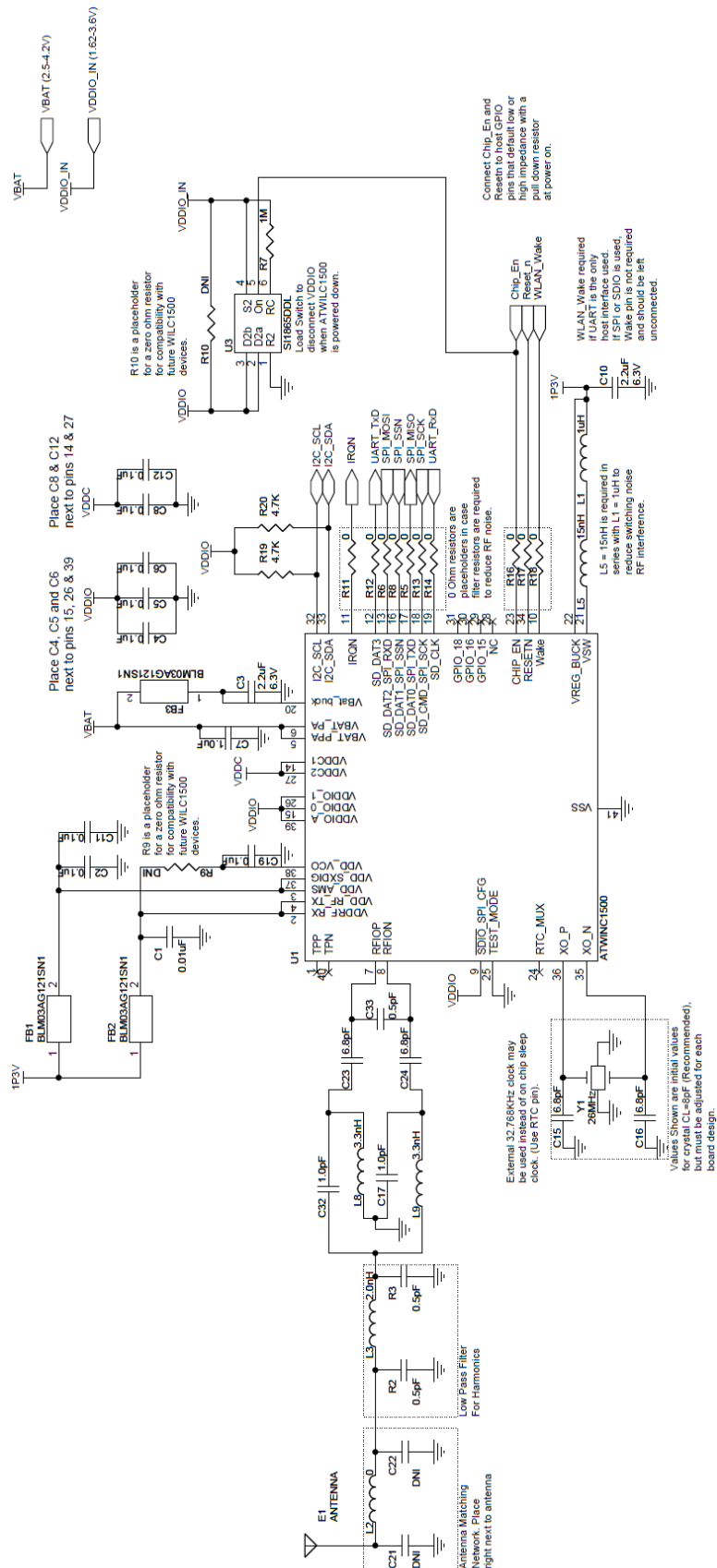
**Table 9-4. Digital I/O Pin Behavior in Different Device States**

Device State	VDDIO	CHIP_EN	RESETN	Output Driver	Input Driver	Pull Up/Down Resistor (96kΩ)
Power_Down: core supply off	High	Low	Low	Disabled (Hi-Z)	Disabled	Disabled
Power-On Reset: core supply on, hard reset on	High	High	Low	Disabled (Hi-Z)	Disabled	Enabled
Power-On Default: core supply on, device out of reset but not programmed yet	High	High	High	Disabled (Hi-Z)	Enabled	Enabled
On_Doze/ On_Transmit/ On_Receive: core supply on, device programmed by firmware	High	High	High	Programmed by firmware for each pin: Enabled or Disabled	Opposite of Output Driver state	Programmed by firmware for each pin: Enabled or Disabled

## 10 Reference Design

The ATWINC1500A reference design schematic is shown in [Figure 10-1](#).

Figure 10-1. ATWINC1500A Reference Schematic



## 11 Reference Documentation and Support

### 11.1 Reference Documents

Atmel offers a set of collateral documentation to ease integration and device ramp.

The following list of documents available on Atmel web or integrated into development tools.

Title	Content
Datasheet	This Document
Design Files Package	User Guide, Schematic, PCB layout, Gerber, BOM & System notes on: RF/Radio Full Test Report, radiation pattern, design guidelines, temperature performance, ESD.
Platform Getting Started Guide	How to use package: Out of the Box starting guide, HW limitations and notes, SW Quick start guidelines.
HW Design Guide	Best practices and recommendations to design a board with the product, Including: Antenna Design for Wi-Fi (layout recommendations, types of antennas, impedance matching, using a power amplifier etc), SPI/UART protocol between Wi-Fi SoC and the Host MCU.
SW Design Guide	Integration guide with clear description of: High level Arch, overview on how to write a networking application, list all API, parameters and structures. Features of the device, SPI/handshake protocol between device and host MCU, with flow/sequence/state diagram, timing.
SW Programmer Guide	Explain in details the flow chart and how to use each API to implement all generic use cases (e.g. start AP, start STA, provisioning, UDP, TCP, http, TLS, p2p, errors management, connection/transfer recovery mechanism/state diagram) - usage & sample App note

For a complete listing of development-support tools & documentation, visit <http://www.atmel.com/>, or contact the nearest Atmel field representative.

## 12 Revision History

Doc Rev.	Date	Comments
42353D	02/2015	New sections added, replaced text in most sections, new and updated drawings.
42353C	01/2015	Datasheet status changed from “Preliminary” to “Complete”. Updated “Ordering Information” on page 3. Major editing updates.
42353B	11/2014	Major document update, new sections added, replaced text in most sections, new and updated drawings.
42353A	09/2014	Initial document release.



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