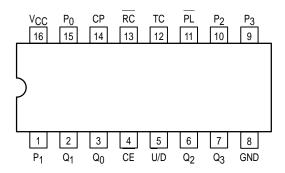


# **Up/Down Counter with Preset and Ripple Clock**

The MC74AC190 is a reversible BCD (8421) decade counter which features synchronous counting and asynchronous presetting. The preset feature allows the MC74AC190 to be used in programmable dividers. The Count Enable input, the Terminal Count output and the Ripple Clock output make possible a variety of methods of implementing multistage counters. In the counting modes, state changes are initiated by the rising edge of the clock.

- High-Speed 120 MHz Typical Count Frequency
- · Synchronous Counting
- Asynchronous Parallel Load
- Cascadable
- · Outputs Source/Sink 24 mA



## **PIN NAMES**

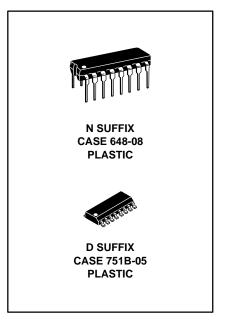
CE Count Enable Input
CP Clock Pulse Input
P0-P3 Parallel Data Inputs

PL Asynchronous Parallel Load Input U/D Up/Down Count Control Input

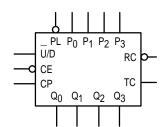
Q<sub>0</sub>-Q<sub>3</sub> Flip-Flop Outputs
RC Ripple Clock Output
TC Terminal Count Output

# MC74AC190

UP/DOWN COUNTER WITH PRESET AND RIPPLE CLOCK



#### LOGIC SYMBOL



### **FUNCTIONAL DESCRIPTION**

The MC74AC190 is a synchronous up/down BCD decade counter. It contains four edge-triggered flip-flops with internal gating and steering logic to provide individual preset, count-up and count-down operations.

Each circuit has an asynchronous parallel load capability permitting the counter to be preset to any desired number. When the Parallel Load (PL) input is LOW, information present on the Parallel Load inputs (Po-P3) is loaded into the counter and appears on the Q outputs. This operation overrides the counting functions, as indicated in the Mode Select Table.

A HIGH signal on the CE input inhibits counting. When CE is LOW, internal state changes are initiated synchronously by the LOW-to-HIGH transition of the clock input. The direction of counting is determined by the U/D input signal, as indicated in the Mode Select Table. CE and U/D can be changed with the clock in either state, provided only that the recommended setup and hold times are observed.

Two types of outputs are provided as overflow/underflow indicators. The terminal count (TC) output is normally LOW. It goes HIGH when the circuits reach zero in the count down mode or 9 in the count up mode. The TC output will then remain HIGH until a state change occurs, whether by counting or presetting or until U/D is changed. The TC output should not be used as a clock signal because it is subject to decoding spikes.

The TC signal is also used internally to enable the Ripple Clock (RC) output. The RC output is normally HIGH. When CE is LOW and TC is HIGH, RC output will go LOW when the clock next goes LOW and will stay LOW until the clock goes HIGH again. This feature simplifies the design of multistage counters, as indicated in Figures a and b. In Figure a, each RC output is used as the clock input for the next higher stage. This configuration is particularly advantageous when the clock source has a limited drive capability, since it drives only the first stage. To prevent counting in all stages it is only necessary to inhibit the first stage, since a HIGH signal on CE inhibits the RC output pulse, as indicated in the RC Truth Table. A disadvantage of this configuration, in some applications, is the timing skew between state changes in the first and lost stages. This represents the cumulative delay of the clock as it ripples through the preceding stages.

A method of causing state changes to occur simultaneously in all stages is shown in Figure b. All clock inputs are driven in parallel and the RC outputs propagate the carry/borrow signals in ripple fashion. In this configuration the LOW state duration of the clock must be long enough to allow the negative-going edge of the carry/borrow signal to ripple through to the last stage before the clock goes HIGH. There is no such restriction on the HIGH state duration of the clock, since the RC output of any device goes HIGH shortly after its CP input goes HIGH.

The configuration shown in Figure cavoids ripple delays and their associated restrictions. The CE input for a given stage is formed by combining the TC signals from all the preceding stages. Note that in order to inhibit counting an enable signal must be included in each carry gate. The simple inhibit scheme of Figures a and b doesn't apply, because the TC output of a given stage is not affected by its own CE.

#### MODE SELECT TABLE

Inputs				Mode
PL	CE	U/D	CP	Wode
Н	L	L	7	Count Up
Н	L	Н	丁	Count Down
L	Х	Х	Х	Preset (Asyn.)
Н	Н	Х	Х	No Change (Hold)

## **RC TRUTH TABLE**

	Inp	uts		Output
PL	CE	TC*	СР	RC
Н	L	Н	4	7
Н	Н	Х	Х	Н
Н	Χ	L	Х	Н
L	Х	Х	Х	Н

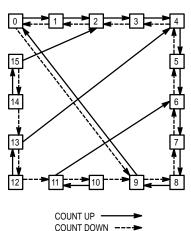
\*TC is generated internally

H = HIGH Voltage Level L = LOW Voltage Level

X = Immaterial

\_ = LOW-to-HIGH Transition

#### STATE DIAGRAM



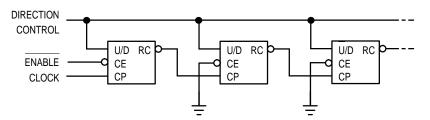


Figure a: N-Stage Counter Using Ripple Clock

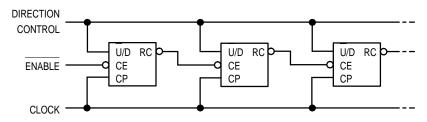


Figure b: Synchronous N-Stage Counter Using Ripple Carry/Borrow

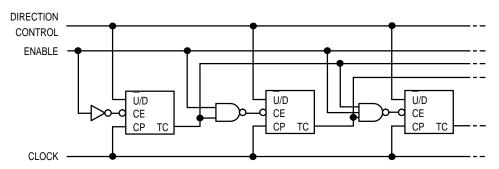
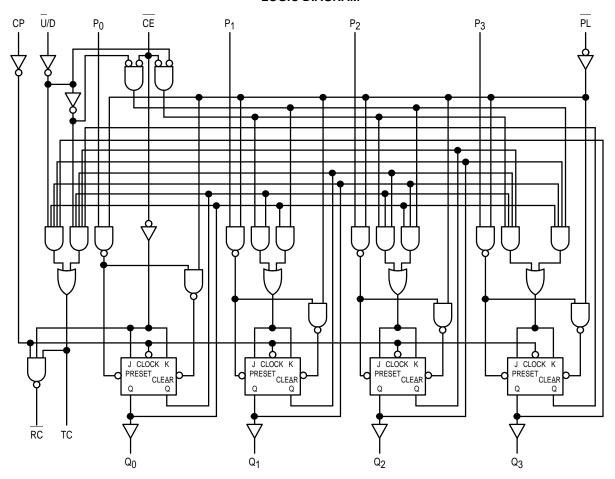


Figure c: Synchronous N-Stage Counter With Parallel Gated Carry/Borrow

## **LOGIC DIAGRAM**



Please note that this diagram is provided only for the understanding of logic operations and should not be used to estimate propagation delays.

## **MAXIMUM RATINGS\***

Symbol	Parameter	Value	Unit
VCC	DC Supply Voltage (Referenced to GND)	-0.5 to +7.0	V
V <sub>in</sub>	DC Input Voltage (Referenced to GND)	–0.5 to V <sub>CC</sub> +0.5	V
V <sub>out</sub>	DC Output Voltage (Referenced to GND)	-0.5 to V <sub>CC</sub> +0.5	V
I <sub>in</sub>	DC Input Current, per Pin	±20	mA
l <sub>out</sub>	DC Output Sink/Source Current, per Pin	±50	mA
Icc	DC V <sub>CC</sub> or GND Current per Output Pin	±50	mA
T <sub>stg</sub>	Storage Temperature	-65 to +150	°C

<sup>\*</sup> Maximum Ratings are those values beyond which damage to the device may occur. Functional operation should be restricted to the Recommended Operating Conditions.

### **RECOMMENDED OPERATING CONDITIONS**

Symbol	Parameter		Min	Тур	Max	Unit
Vac	Supply Voltage	′AC	2.0	5.0	6.0	٧
Vcc	Зирріў Уонаде	'ACT	4.5	5.0	5.5	V
V <sub>in</sub> , V <sub>out</sub>	DC Input Voltage, Output Voltage (Ref. to GND)	0		Vcc	V	
	Input Rise and Fall Time (Note 1) 'AC Devices except Schmitt Inputs	V <sub>CC</sub> @ 3.0 V		150		ns/V
t <sub>r</sub> , t <sub>f</sub>		V <sub>CC</sub> @ 4.5 V		40		
		V <sub>CC</sub> @ 5.5 V		25		
	Input Rise and Fall Time (Note 2)	V <sub>CC</sub> @ 4.5 V		10		ns/V
t <sub>r</sub> , t <sub>f</sub>	'ACT Devices except Schmitt Inputs	V <sub>CC</sub> @ 5.5 V		8.0		
TJ	Junction Temperature (PDIP)				140	°C
TA	Operating Ambient Temperature Range	-40	25	85	°C	
loн	Output Current — High			-24	mA	
loL	Output Current — Low				24	mA

<sup>1.</sup>  $V_{in}$  from 30% to 70%  $V_{CC}$ ; see individual Data Sheets for devices that differ from the typical input rise and fall times. 2.  $V_{in}$  from 0.8 V to 2.0 V; see individual Data Sheets for devices that differ from the typical input rise and fall times.

## **DC CHARACTERISTICS**

			74AC T <sub>A</sub> = +25°C		74AC		
Symbol	Parameter	V <sub>CC</sub>			T <sub>A</sub> = -40°C to +85°C	Unit	Conditions
			Тур	Guar	anteed Limits		
VIH	Minimum High Level Input Voltage	3.0 4.5 5.5	1.5 2.25 2.75	2.1 3.15 3.85	2.1 3.15 3.85	V	V <sub>OUT</sub> = 0.1 V or V <sub>CC</sub> – 0.1 V
V <sub>IL</sub>	Maximum Low Level Input Voltage	3.0 4.5 5.5	1.5 2.25 2.75	0.9 1.35 1.65	0.9 1.35 1.65	V	V <sub>OUT</sub> = 0.1 V or V <sub>CC</sub> – 0.1 V
VOH	Minimum High Level Output Voltage	3.0 4.5 5.5	2.99 4.49 5.49	2.9 4.4 5.4	2.9 4.4 5.4	V	I <sub>OUT</sub> = -50 μA
		3.0 4.5 5.5		2.56 3.86 4.86	2.46 3.76 4.76	V	*V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> -12 mA I <sub>OH</sub> -24 mA -24 mA
VOL	Maximum Low Level Output Voltage	3.0 4.5 5.5	0.002 0.001 0.001	0.1 0.1 0.1	0.1 0.1 0.1	V	Ι <sub>ΟUT</sub> = 50 μΑ
		3.0 4.5 5.5		0.36 0.36 0.36	0.44 0.44 0.44	V	*V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> 12 mA I <sub>OL</sub> 24 mA 24 mA
I <sub>IN</sub>	Maximum Input Leakage Current	5.5		±0.1	±1.0	μΑ	V <sub>I</sub> = V <sub>CC</sub> , GND
lold	†Minimum Dynamic	5.5			75	mA	V <sub>OLD</sub> = 1.65 V Max
IOHD	Output Current				<del>-</del> 75	mA	V <sub>OHD</sub> = 3.85 V Min
ICC	Maximum Quiescent Supply Current	5.5		8.0	80	μΑ	V <sub>IN</sub> = V <sub>CC</sub> or GND

 $<sup>^{\</sup>star}$  All outputs loaded; thresholds on input associated with output under test.

<sup>†</sup> Maximum test duration 2.0 ms, one output loaded at a time. Note:  $I_{IN}$  and  $I_{CC}$  @ 3.0 V are guaranteed to be less than or equal to the respective limit @ 5.5 V V<sub>CC</sub>.

## AC CHARACTERISTICS (For Figures and Waveforms — See Section 3)

			74AC190		74AC190 T <sub>A</sub> = -40°C to +85°C C <sub>L</sub> = 50 pF				
Symbol	Parameter	V <sub>CC</sub> *	T <sub>A</sub> = +25°C C <sub>L</sub> = 50 pF				Unit	Fig. No.	
			Min	Тур	Max	Min	Max		
f <sub>max</sub>	Maximum Count Frequency	3.3 5.0	80 110					MHz	3-3
<sup>t</sup> PLH	Propagation Delay CP to Q <sub>n</sub>	3.3 5.0	2.0 1.5		1.4 9.5	2.0 2.0	15.5 11.0	ns	3-6
<sup>t</sup> PHL	Propagation Delay CP to Q <sub>n</sub>	3.3 5.0	2.5 1.5		14.5 10.0	2.0 2.0	16.0 11.5	ns	3-6
<sup>t</sup> PLH	Propagation Delay CP to TC	3.3 5.0	3.5 2.5		17.0 11.5	2.0 2.0	18.5 13.0	ns	3-6
<sup>t</sup> PHL	Propagation Delay CP to TC	3.3 5.0	3.5 2.5		17.0 12.5	2.0 2.0	18.5 13.0	ns	3-6
<sup>t</sup> PLH	Propagation Delay CP to RC	3.3 5.0	2.5 2.0		11.5 7.5	2.0 2.0	13.0 9.5	ns	3-6
<sup>t</sup> PHL	Propagation Delay CP to RC	3.3 5.0	2.5 1.5		11.0 8.0	2.0 2.0	12.5 9.5	ns	3-6
<sup>t</sup> PLH	Propagation Delay CE to RC	3.3 5.0	2.5 1.5		12.0 8.0	2.0 2.0	13.0 9.0	ns	3-6
<sup>t</sup> PHL	Propagation Delay CE to RC	3.3 5.0	2.0 1.5		13.0 8.0	2.0 2.0	14.5 9.0	ns	3-6
<sup>t</sup> PLH	Propagation Delay U/D to RC	3.3 5.0	2.5 1.5		14.0 8.5	2.0 2.0	15.5 10.0	ns	3-6
<sup>t</sup> PHL	Propagation Delay U/D to RC	3.3 5.0	2.5 2.5		13.0 8.5	2.0 2.0	14.5 10.0	ns	3-6
<sup>t</sup> PLH	Propagation Delay U/D to TC	3.3 5.0	3.0 3.0		12.0 8.0	2.0 2.0	13.0 9.0	ns	3-6
<sup>t</sup> PHL	Propagation Delay U/D to TC	3.3 5.0	3.0 3.0		12.0 8.0	2.0 2.0	13.0 9.0	ns	3-6
<sup>t</sup> PLH	Propagation Delay P <sub>n</sub> to Q <sub>n</sub>	3.3 5.5	2.0 2.0		15.0 10.0	1.5 1.5	17.0 11.5	ns	3-6
<sup>t</sup> PHL	Propagation Delay P <sub>n</sub> to Q <sub>n</sub>	3.3 5.0	2.0 2.0		14.0 9.5	1.5 1.5	16.0 11.0	ns	3-6
<sup>t</sup> PLH	Propagation Delay PL to Qn	3.3 5.0	3.0 3.0		18.0 10.5	2.0 2.0	19.5 12.5	ns	3-6
tPHL	Propagation Delay PL to Q <sub>n</sub>	3.3 5.0	2.5 2.0		15.0 10.5	2.0 2.0	17.0 12.0	ns	3-6

 $<sup>^*</sup>$  Voltage Range 3.3 V is 3.3 V  $\pm 0.3$  V. Voltage Range 5.0 V is 5.0 V  $\pm 0.5$  V.

## **AC OPERATING REQUIREMENTS**

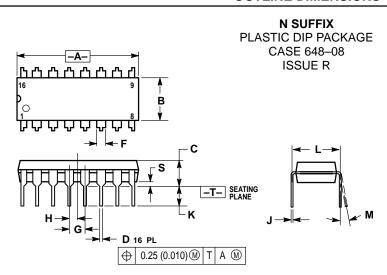
			7	74AC190	74AC190		
Symbol	Parameter	V <sub>CC</sub> *	T <sub>A</sub> = +25°C C <sub>L</sub> = 50 pF		T <sub>A</sub> = -40°C to +85°C C <sub>L</sub> = 50 pF	Unit	Fig. No.
			Тур	Guarantee	d Minimum		
t <sub>S</sub>	Setup <u>Time</u> , HIGH or LOW P <sub>n</sub> to PL	3.3 5.0		0.5 0	0.5 0	ns	3-9
th	Hold <u>Time</u> , HIGH or LOW P <sub>n</sub> to PL	3.3 5.0		0 0	0 0	ns	3-9
t <sub>S</sub>	Setup Time, LOW CE to CP	3.3 5.0		6.5 4.5	7.5 5.0	ns	3-9
th	Hold Time, LOW CE to CP	3.3 5.0		0 0	0 0	ns	3-9
t <sub>S</sub>	Setup Time, HIGH or LOW U/D to CP	3.3 5.0		8.5 5.0	9.5 6.0	ns	3-9
t <sub>h</sub>	Hold Time HIGH or LOW U/D to CP	3.3 5.0		0 0	0 0	ns	3-9
t <sub>W</sub>	PL Pulse Width, LOW	3.3 5.0		5.0 3.5	5.5 4.0	ns	3-6
t <sub>W</sub>	CP Pulse Width, LOW	3.3 5.0		5.0 3.5	5.5 4.0	ns	3-6
t <sub>rec</sub>	Recovery Time PL to CP	3.3 5.0		0.5 0	0.5 0	ns	3-9

 $<sup>^*</sup>$  Voltage Range 3.3 V is 3.3 V  $\pm 0.3$  V. Voltage Range 5.0 V is 5.0 V  $\pm 0.5$  V.

## **CAPACITANCE**

Symbol	Parameter	Value Typ	Unit	Test Conditions
C <sub>IN</sub>	Input Capacitance	4.5	pF	V <sub>CC</sub> = 5.0 V
C <sub>PD</sub>	Power Dissipation Capacitance	75	pF	V <sub>CC</sub> = 5.0 V

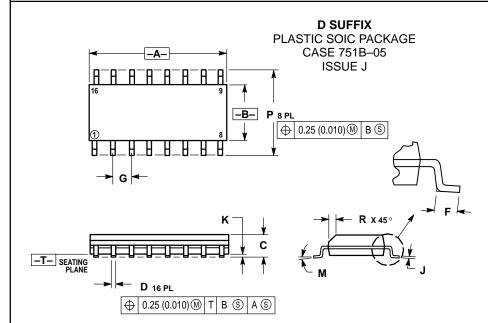
#### **OUTLINE DIMENSIONS**



#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: INCH.
  DIMENSION L TO CENTER OF LEADS WHEN 3 FORMED PARALLEL.
  DIMENSION B DOES NOT INCLUDE MOLD FLASH.
- ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIN	IETERS			
DIM	MIN	MAX	MIN	MAX			
Α	0.740	0.770	18.80	19.55			
В	0.250	0.270	6.35	6.85			
C	0.145	45 0.175 3.69		4.44			
D	0.015	0.021	0.39	0.53			
F	0.040	0.70	1.02	1.77			
G	0.100	BSC	2.54 BSC				
Η	0.050	BSC	1.27 BSC				
7	0.008	0.015	0.21	0.38			
K	0.110	0.130	2.80	3.30			
L	0.295	0.305	7.50	7.74			
М	0°	10 °	0 °	10 °			
S	0.020	0.040	0.51	1.01			



#### NOTES

- 1. DIMENSIONING AND TOLERANCING PER
- ANSI Y14.5M, 1982.
  CONTROLLING DIMENSION: MILLIMETER.
  DIMENSIONS A AND B DO NOT INCLUDE
  MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE
- DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	METERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	9.80	10.00	0.386	0.393
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27	BSC	0.050	BSC
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
Р	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

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