

K-No.: 25105
200 A Current-Sensor-Module

For the electronic measurement of currents:
DC, AC, pulsed, mixed ..., with a galvanic
Isolation between the primary circuit
(high power) and the secondary circuit

Date: 07.02.2008
Customer: Standard Type
Cutomers Part No.:
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Description

- Closed loop (compensation)
Current Sensor with magnetic
field probe
- Printed circuit board mounting
- Casing and materials UL-listed

Characteristics

- Excellent accuracy
- Very low offset current
- Very low temperature dependency and offset
current drift
- Very low hysteresis of offset current
- Short response time
- Wide frequency bandwidth
- Compact design

Applications

Mainly used for stationary operation in industrial
applications:

- AC variabel speed drives and servo motor
drives
- Static converters for for DC motor drives
- Battery supplied applications
- Switched Mode Power Supplies (SMPS)
- Power Supplies for welding applications
- Uninterruptable Power Supplies (UPS)

Electrical Data – Ratings

I_{PN}	Primary rated current, r.m.s	200	A
R_M	Load resistance	0 ... 200	Ω
I_{SN}	Output rated current, r.m.s	100	mA
K_N	Turns ratio	1 : 2000	

Accuracy – Dynamic performance data (with DRV401 @ $V_C = 5V \pm 5\%$)

		min.	typ	max.	Unit
$I_{P,max}$	Max. measuring range @ $R_M = 1,563 \Omega$	± 300			A
$X(T)$	Measuring accuracy @ $I_{PN}, T_A = -40... +85^\circ C$			0.5	%
ϵ_L	Linearity			0.1	%
$I_o(T)$	Offset current @ $I_P=0, T_A = -40... +85^\circ C$		0.02	0.05	mA
I_{oH}	Hysteresis		0.03	0.1	mA
t_r	Response time		1		μs
$\Delta t(I_{p,max})$	Delay time at $di/dt = 100 A/\mu s$		1		μs
f	Frequency range	DC...100			kHz

General Data

		min.	typ.	max.	Unit
T_A	Ambient temperature	-40		+85	$^\circ C$
T_S	Storage temperature	-40		+85	$^\circ C$
m	Mass		123		g
R_S	Secondary coil resistance @ $T_A=85^\circ C$			24	Ω
C_k	Coupling capacity		13		pF
	Mechanical Stress according to M3209/3			10g	
	Settings: 10 – 2000 Hz, 1 min/Decade, 2 hours				
	Constructed and manufactured and tested in accordance with EN 61800-5-1 (Pin 1 – 4 to innerhole)				
	Reinforced insulation, Insulation material group 1, Pollution degree 2				
S_{clear}	clearance (component without solder pad)	16			mm
S_{creep}	creepage (component without solder pad)	25			mm
V_{sys}	System voltage overvoltage category 3	RMS		1000	V
V_{work}	Working voltage (table 7 acc. to EN61800-5-1)	RMS		1700	V
U_{PD}	Rated discharge voltage	peak value		1700	V

Type Testing according to EN 61800-5-1 (Pin 1 – 4 to innerhole)

V_W	HV transient test according to M3064 (1,2 μs / 50 μs -wave form)		12	kV
V_d	Testing voltage to M3014	(5 s)	4.4	kV
V_e	Partial discharge voltage acc.M3024 (RMS)		1800	V
	with V_{vor} (RMS)		2250	V

Datum	Name	Index	Änderung
07.02.08	Le	81	Connections adjusted on actual conditions (Mechanical outline). Insignificant
Hrsg.: KB-E editor	Bearb: SA designer		KB-E: Le. check
			KB-PM IA: KRe. check
			freig.: Heu. released

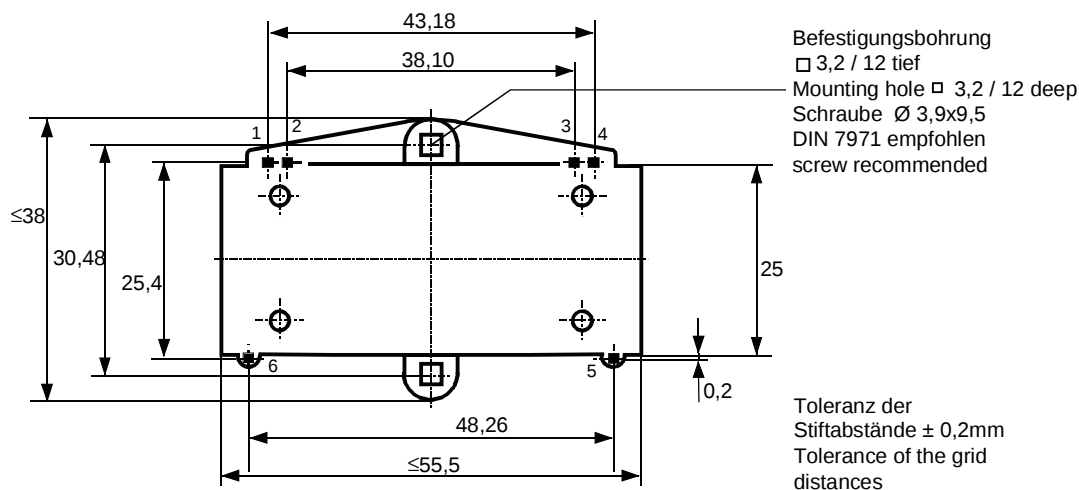
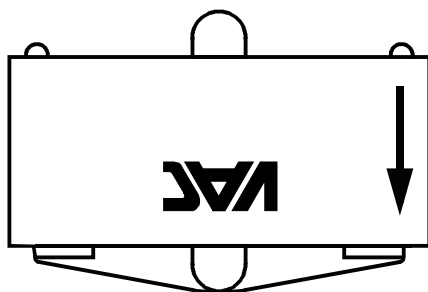
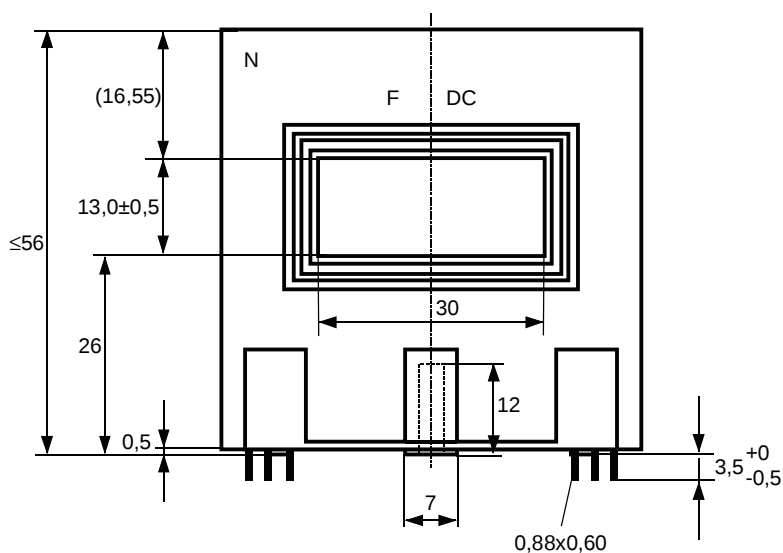
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Mechanical outline (mm):

General tolerances DIN ISO 2768-c

Connections:

 Pin1...6:
 0,88*0,60 mm

Marking:
VAC
 4645X080
 F DC

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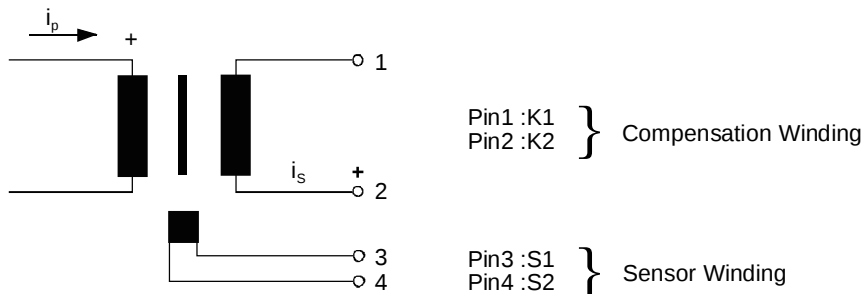
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Schematic diagram

Inspection (Measurements after temperature balance of the samples at room temperature.)

K_N (N1/N2)	(V)	M3011/6c:	Turns ratio ($I_P=200A$, 40...80 Hz)	$\approx 1 : 2000 \pm 0.5$	%
I_0		M3226:	Offset current	< 0.1	mA
$\Delta\Phi$ (K1-K2)	(V)	M3090:	Magnetic Flux compensation core	33...37	nVs
$\Delta\Phi$ (S1-S2)	(V)	M3090:	Magnetic Flux sensor	20...35	nVs
R_S (K1-K2)	(V)	M3011/5:	Winding resistance compensation coil	16.7...19.2	Ω
R (S1-S2)	(V)	M3011/5:	Winding resistance magnetic probe coil	2.5...3.5	Ω
V_d	(V)	M3014:	Testing voltage, rms, 1s Preliminary to secondary	2.2	kV
V_e	(AQL1/S4)	M3024:	Partial discharge voltage (RMS) with V_{vor} (RMS)	1800 2250	V V

Applicable documents

Current direction: A positive output current appears at point I_s , by primary current in direction of the arrow.
Temperature of the primary conductor should not exceed 110°C
Housing and bobbin material: UL-listed. Flammability class UL 94V-0.
Enclosures according to IEC 60529: IP50.

Additional data available on request.
This specification is no declaration of warranty acc. BGB §443.

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Explanation of several of the terms used in the tablets (in alphabetical order)

I_{0H} :	Zero variation of I_0 after overloading with a DC of tenfold the rated value ($R_M = R_{MN}$)
I_{0t} :	Long term drift of I_0 after 100 temperature cycles in the range -40 bis 85 °C.
t_r :	Response time (describe the dynamic performance for the specified measurement range), measured as delay time at $I_P = 0,9 \cdot I_{Pmax}$ between a rectangular current and the output current.
$\Delta t (I_{Pmax})$:	Delay time (describe the dynamic performance for the rapid current pulse rate e.g short circuit current) measured between I_{Pmax} and the output current i_a with a primary current rise of $di_1/dt = 100 \text{ A}/\mu\text{s}$.
U_{PD}	Rated discharge voltage (recurring peak voltage separated by the insulation) proved with a sinusoidal voltage V_e $U_{PD} = \sqrt{2} \cdot V_e / 1,5$
V_{vor}	Defined voltage is the RMS valve of a sinusoidal voltage with peak value of $1,875 \cdot U_{PD}$ required for partial discharge test in IEC 61800-5-1 $V_{vor} = 1,875 \cdot U_{PD} / \sqrt{2}$
V_{sys}	System voltage RMS value of rated voltage according to IEC 61800-5-1
V_{work}	Working voltage voltage according to IEC 61800-5-1 which occurs by design in a circuit or across insulation
$X_{ges}(I_{PN})$:	The sum of all possible errors over the temperature range by measuring a current I_{PN} : $X_{ges} = 100 \cdot \left \frac{I_S(I_{PN})}{K_N \cdot I_{PN}} - 1 \right \%$
X :	Permissible measurement error in the final inspection at RT, defined by $X = 100 \cdot \left \frac{I_{SB}}{I_{SN}} - 1 \right \%$ where I_{SB} is the output DC value of an input DC current of the same magnitude as the (positive) rated current ($I_0 = 0$)
X_{Ti} :	Temperature drift of the rated value orientated output term. I_{SN} (cf. Notes on F_i) in a specified temperature range, obtained by: $X_{Ti} = 100 \cdot \left \frac{I_{SB}(T_{A2}) - I_{SB}(T_{A1})}{I_{SN}} \right \%$
ϵ_L :	Linearity fault defined by $e_L = 100 \cdot \left \frac{I_P}{I_{PN}} - \frac{I_{Sx}}{I_{SN}} \right \%$ Where I_P is any input DC and I_{Sx} the corresponding output term. I_{SN}: see notes of F_i ($I_0 = 0$).

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