

TOSHIBA CMOS Digital Integrated Circuit Silicon Monolithic

TC4W66F, TC4W66FU

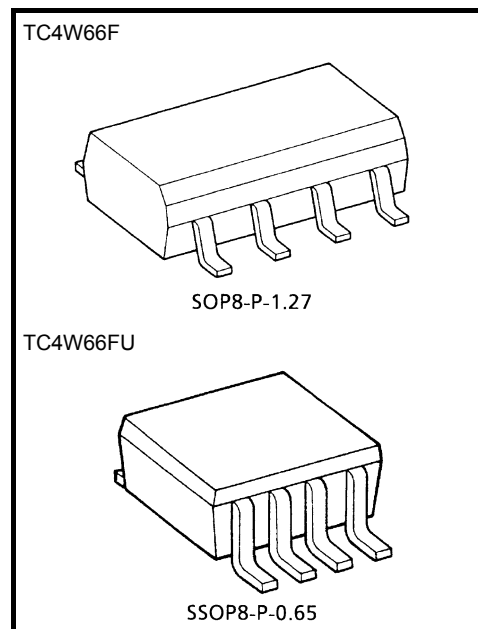
Dual Bilateral Switch

The TC4W66 contains two independence circuits of bidirectional switches.

When control input CONT is set to "H" level, the impedance between input and output of the switch becomes low and when it is set to "L" level, the switch becomes high. This can be applied for switching of analog signals and digital signals.

Features

- ON-resistance, R_{ON}
 $250\ \Omega$ (typ.) $V_{DD} - V_{SS} = 5\ V$
 $110\ \Omega$ (typ.) $V_{DD} - V_{SS} = 10\ V$
 $70\ \Omega$ (typ.) $V_{DD} - V_{SS} = 15\ V$
- OFF-resistance, R_{OFF}
 R_{OFF} (typ.) $> 10^9\ \Omega$



Weight
 SOP8-P-1.27: 0.05 g (typ.)
 SSOP8-P-0.65: 0.02 g (typ.)

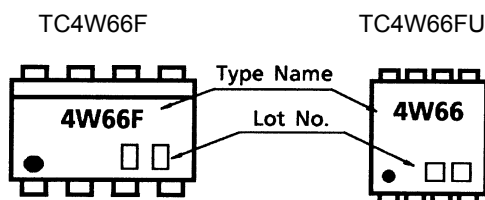
Absolute Maximum Ratings

Characteristics	Symbol	Rating	Unit
DC supply voltage	V_{DD}	$V_{SS} - 0.5$ to $V_{SS} + 20$	V
Control input voltage	$V_{C\ IN}$	$V_{SS} - 0.5$ to $V_{DD} + 0.5$	V
Switch I/O voltage	$V_{I/O}$	$V_{SS} - 0.5$ to $V_{DD} + 0.5$	V
Power dissipation	P_D	300	mW
Potential difference across I/O during ON	$V_I - V_O$	± 0.5	V
Control input current	$I_{C\ IN}$	± 10	mA
Operating temperature range	T_{opr}	-40 to 85	°C
Storage temperature	T_{stg}	-65 to 150	°C
Lead temp./time	T_L	260°C/10 s	

Note: Using continuously under heavy loads (e.g. the application of high temperature/current/voltage and the significant change in temperature, etc.) may cause this product to decrease in the reliability significantly even if the operating conditions (i.e. operating temperature/current/voltage, etc.) are within the absolute maximum ratings and the operating ranges.

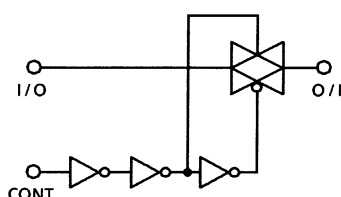
Please design the appropriate reliability upon reviewing the Toshiba Semiconductor Reliability Handbook ("Handling Precautions"/"Derating Concept and Methods") and individual reliability data (i.e. reliability test report and estimated failure rate, etc).

Marking

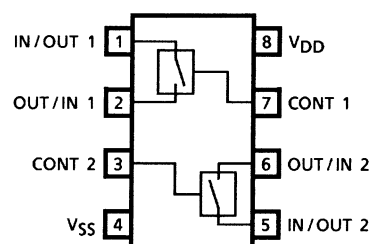


Logic Diagram

(1/2 TC4W66F)



Pin Assignment (top view)



Truth Table

Control	Impedance Between IN/OUT-OUT/IN (Note 1)
H	$0.5 \text{ to } 5 \times 10^2 \Omega$
L	$>10^9 \Omega$

Note 1: See static electrical characteristics.

Operating Ranges ($V_{SS} = 0 \text{ V}$)

Characteristics	Symbol	Test Condition	Min	Typ.	Max	Unit
DC supply voltage	V_{DD}	—	3	—	18	V
Input/output voltage	V_{DD}/V_{OUT}	—	0	—	V_{DD}	V

Static Electrical Characteristics (in case not specifically appointed, $V_{SS} = 0 \text{ V}$)

Characteristics	Symbol	Test Circuit	Test Condition	V_{DD} (V)	$T_a = -40^\circ\text{C}$		$T_a = 25^\circ\text{C}$			$T_a = 85^\circ\text{C}$		Unit
					Min	Max	Min	Typ.	Max	Min	Max	
Control input high voltage	V_{IH}	—	$ I_{IS} = 10 \mu\text{A}$	5	3.5	—	3.5	2.75	—	3.5	—	V
				10	7.0	—	7.0	5.50	—	7.0	—	
				15	11.0	—	11.0	8.25	—	11.0	—	
Control input low voltage	V_{IL}	—	$ I_{IS} = 10 \mu\text{A}$	5	—	1.5	—	2.25	1.5	—	1.5	V
				10	—	3.0	—	4.5	3.0	—	3.0	
				15	—	4.0	—	6.75	4.0	—	4.0	
On-state resistance	R_{ON}	—	$0 \leq V_{IS} \leq V_{DD}$ $R_L = 10 \text{ k}\Omega$	5	—	800	—	290	950	—	1200	Ω
				10	—	210	—	120	250	—	300	
				15	—	140	—	85	160	—	200	
Δ On-state resistance (between any 2 switches)	$R_{ON\Delta}$	—	—	5	—	—	—	10	—	—	—	Ω
				10	—	—	—	6	—	—	—	
				15	—	—	—	4	—	—	—	
Input/output leakage current	I_{OFF}	—	$V_{IN} = 18 \text{ V}, V_{OUT} = 0 \text{ V}$	18	—	± 100	—	± 0.1	± 100	—	± 1000	nA
			$V_{IN} = 0 \text{ V}, V_{OUT} = 18 \text{ V}$	18	—	± 100	—	± 0.1	± 100	—	± 1000	
Quiescent device current	I_{DD}	—	$V_{IN} = V_{DD}, V_{SS}^*$	5	—	0.25	—	0.001	0.25	—	7.5	μA
				10	—	0.5	—	0.001	0.5	—	15	
				15	—	1.0	—	0.002	1.0	—	30	
Input current	H level	I_{IH}	—	$V_{IH} = 18 \text{ V}$	18	—	0.1	—	10^{-5}	0.1	—	μA
	L level	I_{IL}	—	$V_{IL} = 0 \text{ V}$	18	—	-0.1	—	-10^{-5}	-0.1	—	

Dynamic Electrical Characteristics (Ta = 25°C, V_{SS} = 0 V, C_L = 50 pF)

Characteristics	Symbol	Test Circuit	Test Condition			Min	Typ.	Max	Unit
				V _{SS} (V)	V _{DD} (V)				
Phase difference between input to output	ϕ_{I-O}	—	C _L = 50 pF	0	5	—	15	40	ns
				0	10	—	8	20	
				0	15	—	5	15	
Propagation delay time (CONTROL-OUT)	t_{pZL} t_{pZH}	—	R _L = 1 k Ω C _L = 50 pF	0	5	—	55	120	ns
				0	10	—	25	40	
				0	15	—	20	30	
Propagation delay time (CONTROL-OUT)	t_{pLZ} t_{pHZ}	—	R _L = 1 k Ω C _L = 50 pF	0	5	—	45	80	ns
				0	10	—	30	70	
				0	15	—	25	60	
Max control input repetition Rate	f _{max} (C)	—	R _L = 1 k Ω C _L = 50 pF	0	5	—	10	—	MHz
				0	10	—	12	—	
				0	15	—	12	—	
–3dB cutoff frequency	f _{max} (I-O)	—	R _L = 1 k Ω C _L = 50 pF (Note 1)	–5	5	—	30	—	MHz
Total harmonic distortion	—	—	R _L = 10 k Ω f = 1 kHz (Note 2)	–5	5	—	0.03	—	%
–50dB feed through frequency	—	—	R _L = 1 k Ω (Note 3)	–5	5	—	600	—	kHz
–50dB crosstalk frequency	—	—	R _L = 1 k Ω (Note 4)	–5	5	—	1	—	MHz
Crosstalk (CONTROL-OUT)	—	—	R _{IN} = 1 k Ω R _{OUT} = 10 k Ω C _L = 15 pF	0	5	—	200	—	mV
				0	10	—	400	—	
				0	15	—	600	—	
Input capacitance	C _{IN}	—	Control input	—	—	—	5	7.5	pF
		—	Switch I/O	—	—	—	10	—	
Feed through capacitance	C _{IN-OUT}	—	—	—	—	—	0.5	—	pF

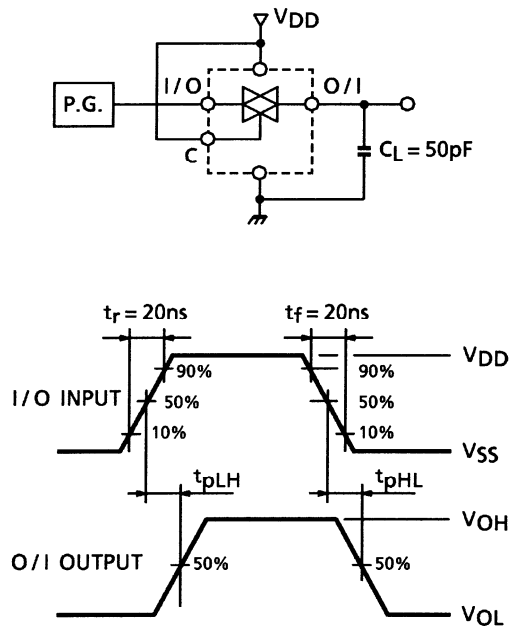
Note 1: Since wave of ± 2.5 V_{p-p} shall be used for V_{IS} and the frequency of $20 \log_{10} \frac{V_{OS}}{V_{IS}} = -3\text{dB}$ shall be f_{max}.

Note 2: V_{IS} shall be sine wave of ± 2.5 V_{p-p}.

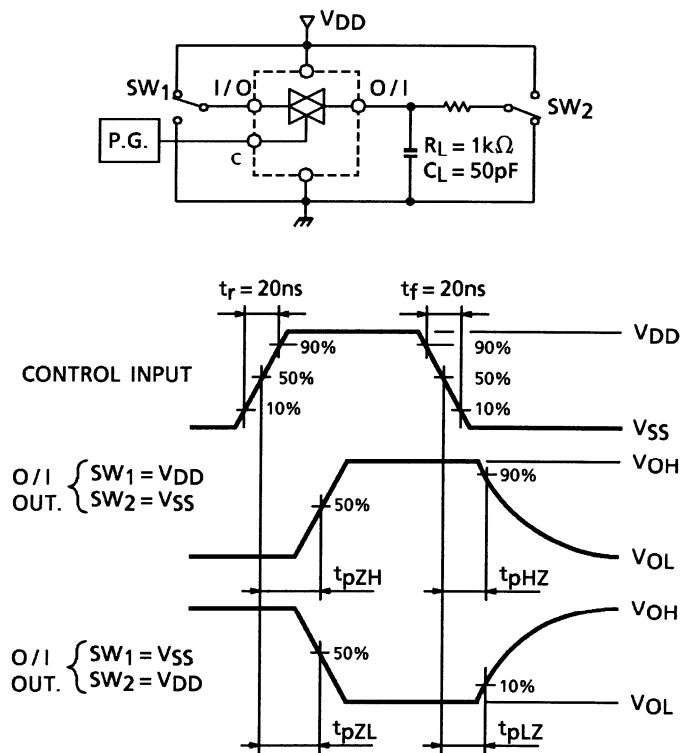
Note 3: Sine wave of ± 2.5 V_{p-p} shall be used for V_{IS} and the frequency of $20 \log_{10} \frac{V_{OUT}}{V_{IS}} = -50\text{dB}$ shall be feed-through.

Note 4: Sine wave of ± 2.5 V_{p-p} shall be used for V_{IS} and the frequency of $20 \log_{10} \frac{V_{OUT}}{V_{IS}} = -50\text{dB}$ shall be crosstalk.

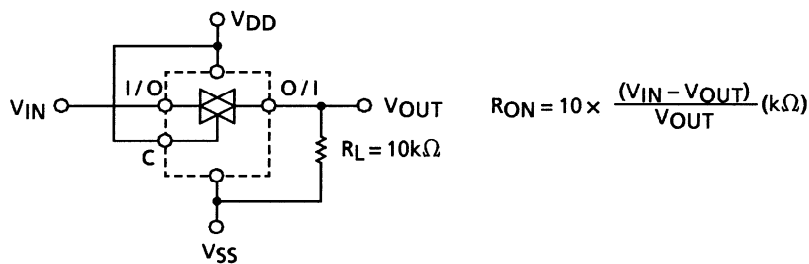
1. t_{pLH} , t_{pHL} I/O-O/I



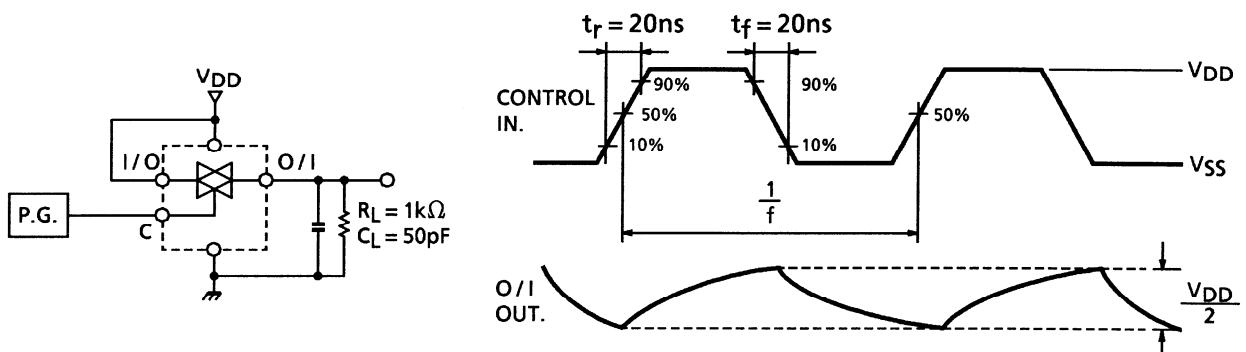
2. t_{pZL} , t_{pZH} , t_{pLZ} , t_{pHZ} Control-O/I



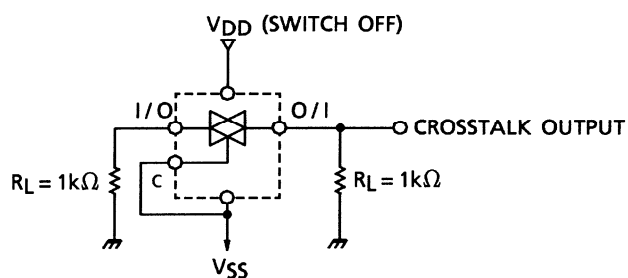
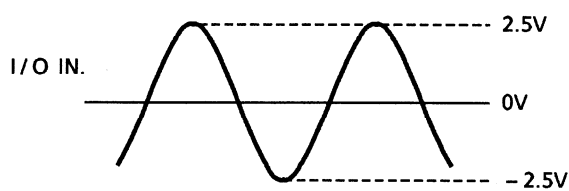
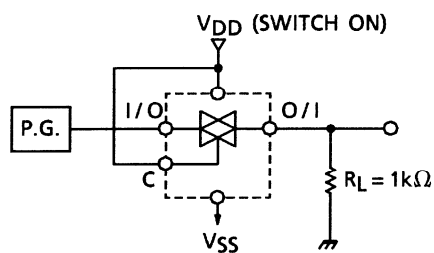
3. R_{ON}



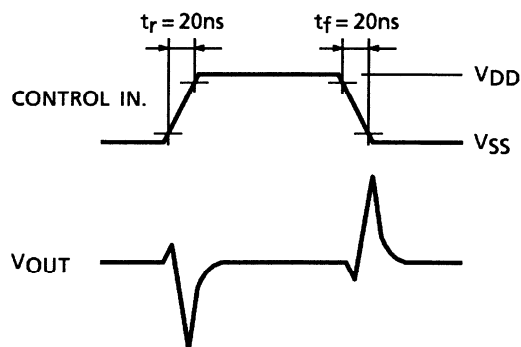
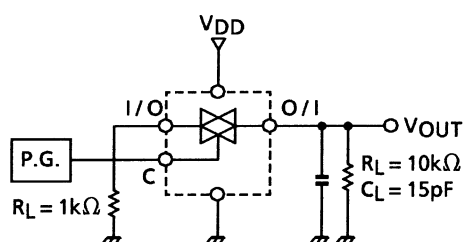
4. f_{max} (C)



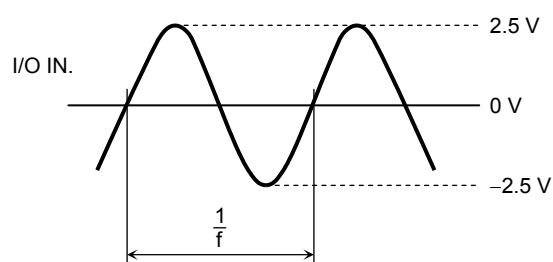
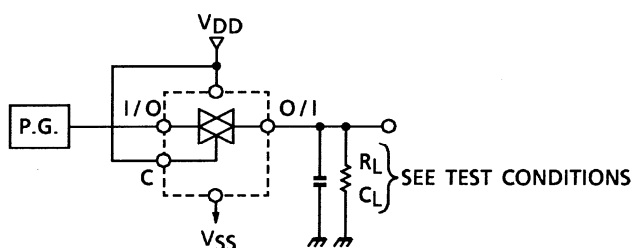
5. Crosstalk (switch I/O)



6. Crosstalk (control input)



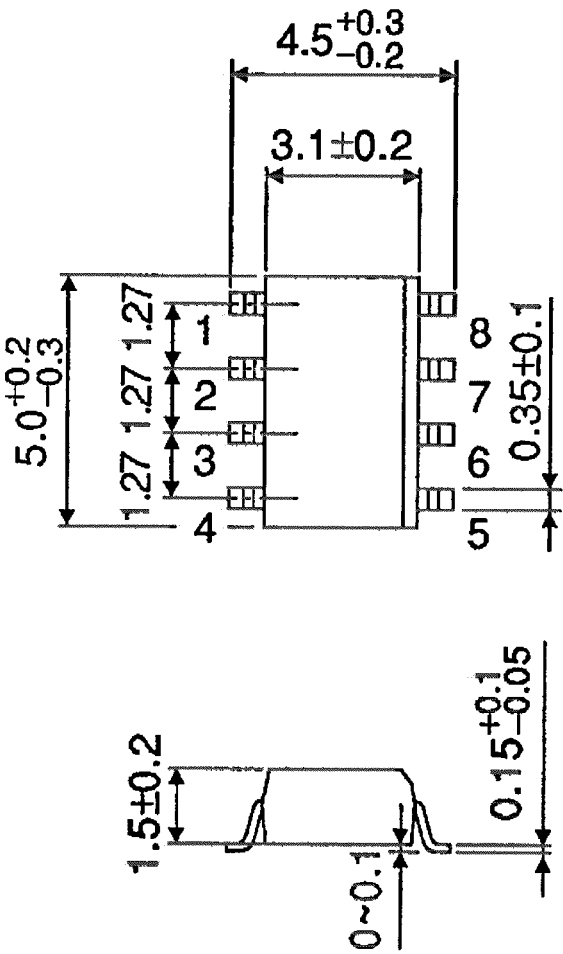
7. Total Harmonic Distortion, $f_{\max}$ (I/O-O/I), Feedthrough (switch OFF)



Package Dimensions

SOP8-P-1.27

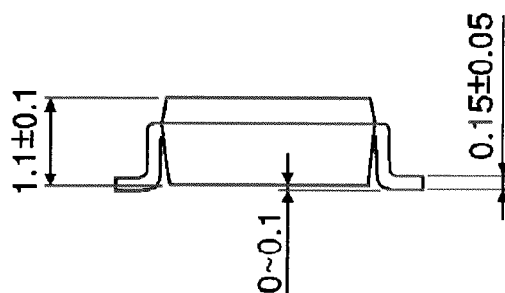
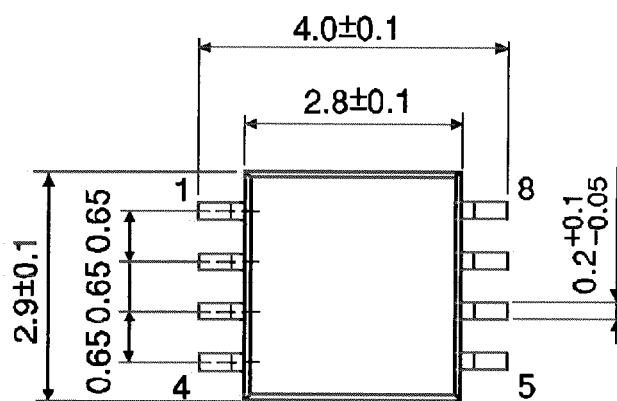
Unit : mm



Weight: 0.05 g (typ.)

SSOP8-P-0.65

Unit : mm



Weight: 0.02 g (typ.)

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