

3-PHASE DC BRUSHLESS MOTOR CONTROL IC

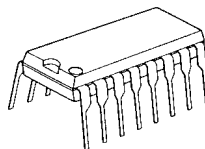
■ GENERAL DESCRIPTION

The NJM2627 is a 3-phase DC brush less motor control pre-driver IC.

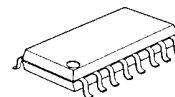
Output pre-driver is optimized to work with external power MOS FET for better power handling.

The NJM2627 can easily implement speed control by input of PWM signal to ON/ OFF terminal.

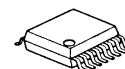
■ PACKAGE OUTLINE



NJM2627D



NJM2627M

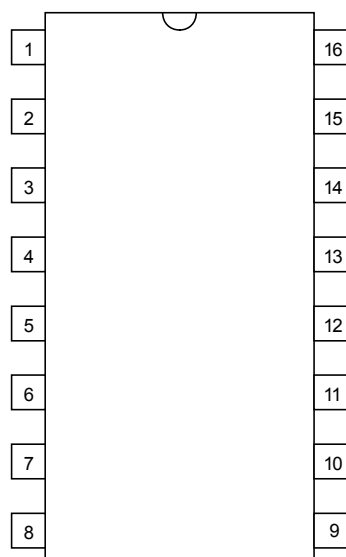


NJM2627V

■ FEATURES

- Operating Voltage 4.5 to 14V
- Pre-driver circuit
 - Lower arm : Totem-pole
 - Upper arm : Open-collector
- Forward or Reverse direction
- Internal ON/OFF Circuit (No-output is Verr pin to GND)
- Bipolar Technology
- Package Outline DIP16,DMP16,SSOP16

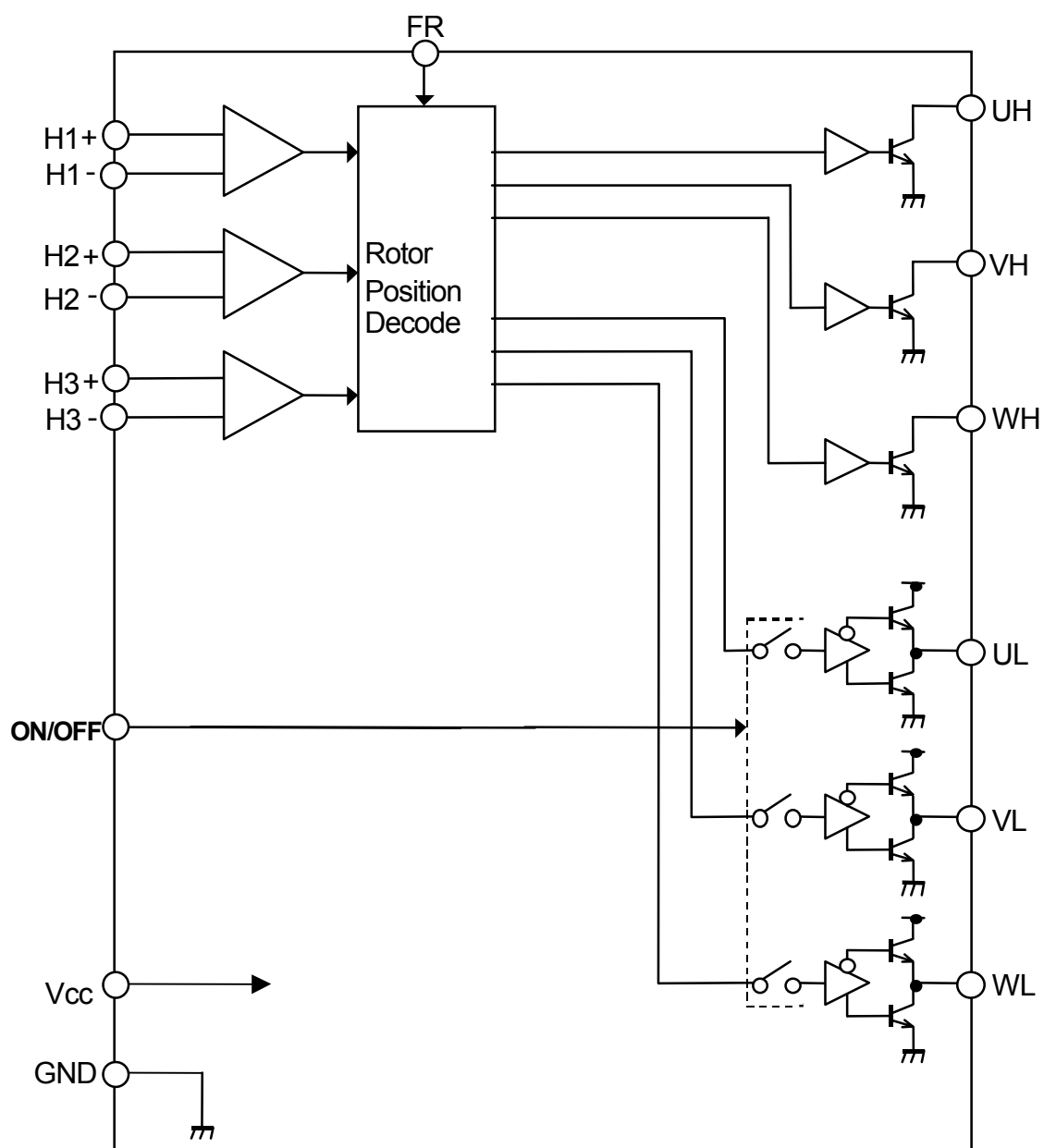
■ PIN CONNECTION



NJM2627V

1.H1-	9.GND
2.H1+	10.ON/OFF
3.H2-	11.WL
4.H2+	12.VL
5.H3-	13.UL
6.H3+	14.WH
7.FR	15.VH
8.VCC	16.UH

■ BLOCK DIAGRAM



■ABSOLUTE MAXIMUM RATINGS

(Ta=25°C)

PARAMETER	SYMBOL	RATINGS	UNIT	REMARKS
Maximum Supply Voltage	V _{CC}	15	V	
Hall Input Differential Voltage	V _{IHD}	2	V	
Hall Input Voltage	V _{IH}	-0.3~V _{DD}	V	
ON/OFF Terminal Input Voltage	V _{ON/OFF}	-0.3~V _{DD}	V	
F/R Terminal Input Voltage	V _{FR}	-0.3~V _{DD}	V	
Maximum Output Current	I _{out}	30	mA	Under Arm Source Current
		50		Upper Arm Sink Current Under Arm Sink Current
Power Dissipation	P _D	700 (DIP device itself)	mW	
		350 (DMP device itself)		
		300 (SSOP16 device itself)		
Operating Temperature Range	T _{opr}	-40 ~ +85	°C	
Storage Temperature range	T _{stg}	-50 ~ +150	°C	

■ELECTRICAL CHARACTERISTICS

(V_{CC}=12V, Ta=25°C)

Total Device

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Operation Supply Voltage	V _{CC}	-	4.5	-	14.0	V
Supply Current	I _{CC}	RL=∞	-	8.0	10.0	mA

Hall Amplifier Section

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Input Offset Voltage	V _{ID}	-	-5	-	5	mV
Input Common Mode Voltage Range	V _{ICM}	-	1.5	-	10.5	V
Input Bias Voltage	I _B	-	-	-	600	nA

Output Section

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Under Arm Output Voltage 1	V _{OH-D1}	Is _{source} =20mA	10	10.3	-	V
Under Arm Output Voltage 2	V _{OL-D2}	Is _{sink} =10mA	-	0.5	0.8	V
Under Arm Output Voltage 3	V _{OL-D3}	Is _{sink} =50mA	-	1.6	2.0	V
Upper Arm Output Voltage	V _{OL-U}	Is _{sink} =10mA	-	0.5	0.8	V
Output Leak Current	I _{O-LEAK}		-	-	1.0	uA

ON/OFF Section

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Output ON Voltage	V _{ON}	-	1/2V _{CC} +0.5	-	-	V
Output OFF Voltage	V _{OFF}	-	-	-	1/2V _{CC} -0.5	V
Output Voltage Undefined Area	V _{O-undef}	-	1/2V _{CC} -0.5	1/2V _{CC}	1/2V _{CC} +0.5	V
Source Current 1	I _{ON1}	ON/OFF terminal=GND	-	250	400	μA
Pull-Up Resistance	R _{pu-of}	-	-	50	-	kΩ

Forward or Reverse Direction Section (FR input terminal)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Output Forward Direction	V_F	-	$1/2V_{CC}+0.5$	-	-	V
Output Reverse Direction	V_R	-	-	-	$1/2V_{CC}-0.5$	V
F/R Logic Undefined Area	$V_{SW-undef}$	-	$1/2V_{CC}-0.5$	$1/2V_{CC}$	$1/2V_{CC}+0.5$	V
Source Current 2	I_{ON2}	F/R terminal=GND	-	250	400	μA
Pull-Up Resistance	R_{pu-FR}	-	-	50	-	k Ω

■ HALL INPUT vs HALL OUTPUT TRUTH TABLE

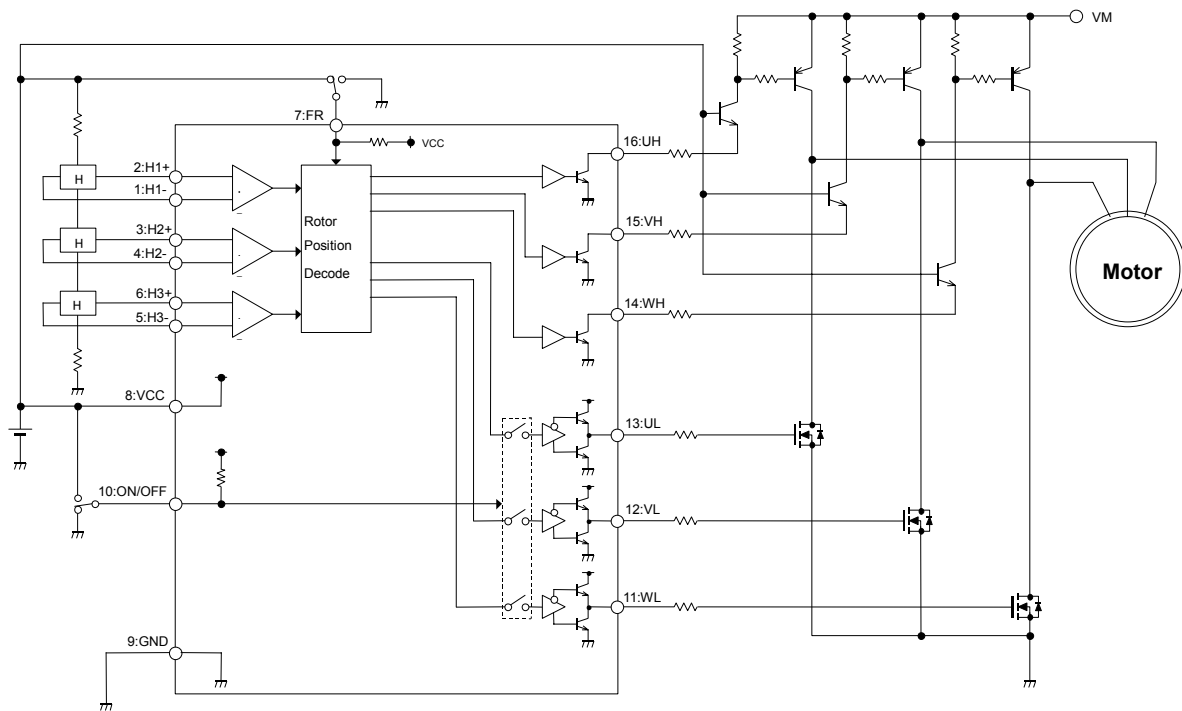
H1:"H"=H1+>H1-,"L"=H1+<H1- H2:"H"=H2+>H2-,"L"=H2+<H2- H3:"H"=H3+>H3-,"L"=H3+<H3-

FR=H			FR=L			ON/ OFF	H:Source,L:Sink,X:Hi-Z					
H1	H2	H3	H1	H2	H3		UH	VH	WH	UL	VL	WL
H	L	H	L	H	L	H	X	L	X	H	L	L
H	L	L	L	H	H	H	X	X	L	H	L	L
H	H	L	L	L	H	H	X	X	L	L	H	L
L	H	L	H	L	H	H	L	X	X	L	H	L
L	H	H	H	L	L	H	L	X	X	L	L	H
L	L	H	H	H	L	H	X	L	X	L	L	H
H	L	H	L	H	L	L	X	L	X	L	L	L
H	L	L	L	H	H	L	X	X	L	L	L	L
H	H	L	L	L	H	L	X	X	L	L	L	L
L	H	L	H	L	H	L	L	X	X	L	L	L
L	H	H	H	L	L	L	L	X	X	L	L	L
L	L	H	H	H	L	L	X	L	X	L	L	L

■ FR INPUT TERMINAL

Terminal Voltage	Direction
L input	F
H input	R

■ TYPICAL APPLICATION



[CAUTION]
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