

I²C-Compatible (2-Wire) Serial EEPROM 64-Kbit (8,192 x 8)

DATASHEET

Features

- Low-voltage and standard-voltage operation
 - V_{CC} = 1.7V to 5.5V
- Internally organized as 8,192 x 8 (64K)
- I²C-compatible (2-Wire) serial interface
- Schmitt Trigger, filtered inputs for noise suppression
- Bidirectional data transfer protocol
- 400kHz (1.7V) and 1MHz (2.5V, 2.7V, 5.0V) compatibility
- Write Protect pin for hardware protection
- 32-byte Page Write mode
 - Partial Page Writes allowed
- Self-timed Write cycle (5ms max)
- High reliability
 - Endurance: 1,000,000 write cycles
 - Data retention: 100 years
- Lead-free/Halogen-free devices available
- Green package options (Pb/Halide-free/RoHS compliant)
 - 8-lead JEDEC SOIC, 8-lead TSSOP, 8-pad UDFN, 8-pad XDFN, 6-ball WLCSP,
 5-ball WLCSP, and 8-ball VFBGA packages
- Die sale options: wafer form, waffle pack, and bumped wafers

Description

The Atmel® AT24C64D provides 65,536-bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 8,192 words of eight bits each. The device's cascading feature allows up to eight devices to share a common 2-wire bus. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operation are essential. The devices are available in space-saving 8-lead JEDEC SOIC, 8-lead TSSOP, 8-pad UDFN, 8-pad XDFN, 6-ball WLCSP, 5-ball WLCSP, and 8-ball VFBGA packages. In addition, this device operates from 1.7V to 5.5V.

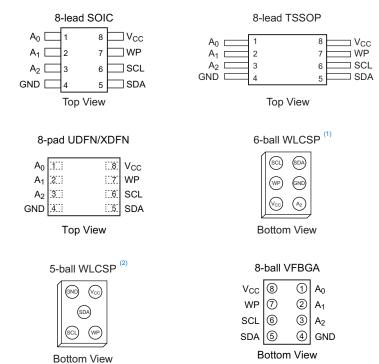
1. Pin Configurations and Pinouts

Table 1-1. Pin Configuration

| Pin | Function |
|-----------------|---------------------|
| A ₀ | Address Input |
| A ₁ | Address Input |
| A ₂ | Address Input |
| GND | Ground |
| SDA | Serial Data |
| SCL | Serial Clock Input |
| WP | Write Protect |
| V _{CC} | Device Power Supply |



- For use of the 6-ball WLCSP package, the software bits A1 and A0 in the device address word must be set to Logic 0 to properly communicate. See Section 7.
 Device Addressing on page 9 for more details.
- For use of the 5-ball WLCSP package, the three device address pins are not available. For proper comunication with the device, the software bits A2 and A1 must be set to Logic 0, while software bit



* Note: Drawings are not to scale

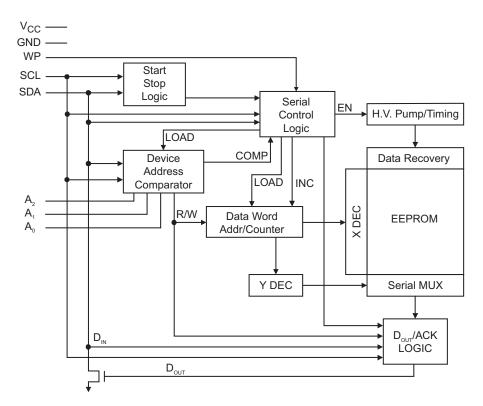
A0 must be set to Logic 1, resulting in a '001' string in the device address byte for bits 3, 2, and 1. See Section 7. Device Addressing on page 9 for more details.

2. Absolute Maximum Ratings*

| Operating Temperature | 55°C to +125°C |
|---|------------------|
| Storage Temperature | -65°C to + 150°C |
| Voltage on any pin with respect to ground | 1.0 V +7.0V |
| Maximum Operating Voltage | 6.25V |
| DC Output Current | 5.0mA |

*Notice: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

3. Block Diagram



4. Pin Descriptions

Serial Clock (SCL): The SCL input is used to positive-edge clock data into each EEPROM device and negative-edge clock data out of each device.

Serial Data (SDA): The SDA pin is bidirectional for serial data transfer. This pin is open drain driven and may be wire-ORed with any number of other open-drain or open-collector devices.

Device Addresses (A_2 , A_1 , A_0): The A_2 , A_1 , and A_0 pins are device address inputs that are hard wired (directly to GND or to V_{CC}) for compatibility with other Atmel AT24C devices. When the pins are hard wired, as many as eight 64K devices may be addressed on a single bus system. (Device addressing is discussed in detail in Section 7., "Device Addressing" on page 9). A device is selected when a corresponding hardware and software match is true. If these pins are left floating, the A_2 , A_1 , and A_0 pins will be internally pulled down to GND. However, due to capacitive coupling that may appear during customer applications, Atmel recommends always connecting the address pins to a known state. When using a pull-up resistor, Atmel recommends using $10k\Omega$ or less.

Write Protect (WP): The Write Protect input, when connected to GND, allows normal Write operations. When WP is connected directly to V_{CC} , all Write operations to the memory are inhibited. If the pin is left floating, the WP pin will be internally pulled down to GND: however, due to capacitive coupling that may appear during customer applications, Atmel recommends always connecting the WP pins to a known state. When using a pull-up resistor, Atmel recommends using $10k\Omega$ or less.

Table 4-1. Write Protect

| WP Pin Status | Part of the Array Protected |
|--------------------|------------------------------|
| At V _{CC} | Full Array |
| At GND | Normal Read/Write Operations |



5. Memory Organization

AT24C64D, **64K Serial EEPROM**: The 64K is internally organized as 256 pages of 32-bytes each. Random word addressing requires a 13-bit data word address.

Table 5-1. Pin Capacitance⁽¹⁾

Applicable over recommended operating range from: $T_A = 25$ °C, f = 1.0MHz, $V_{CC} = 5.5$ V

| Symbol | Test Condition | Max | Units | Conditions |
|------------------|--|-----|-------|-----------------------|
| C _{I/O} | Input/Output Capacitance (SDA) | 8 | pF | V _{I/O} = 0V |
| C _{IN} | Input Capacitance (A ₀ , A ₁ , A ₂ , and SCL) | 6 | pF | V _{IN} = 0V |

Note: 1. This parameter is characterized and is not 100% tested.

Table 5-2. DC Characteristics

Applicable over recommended operating range from: T_{AI} = -40°C to +85°C, V_{CC} = 1.7V to 5.5V (unless otherwise noted)

| Symbol | Parameter | Test Condition | 1 | Min | Тур | Max | Units |
|------------------|--|--|---|-----------------------|------|-----------------------|-------|
| V _{CC1} | Supply Voltage | | | 1.7 | | 5.5 | V |
| I _{CC1} | Supply Current | V _{CC} = 5.0V | Read at 400kHz | | 0.4 | 1.0 | mA |
| I _{CC2} | Supply Current | V _{CC} = 5.0V | Write at 400kHz | | 2.0 | 3.0 | mA |
| | Standby Current | V _{CC} = 1.7V | V _{CC} = 1.7V | | | 1.0 | μA |
| I _{SB1} | Standby Current | $V_{\rm CC} = 5.0 \text{V}$ $V_{\rm IN} = V_{\rm CC} \text{ or } V_{\rm SS}$ | | | | 6.0 | μA |
| I _{LI} | Input Leakage Current V _{CC} = 5.0V | $V_{IN} = V_{CC}$ or V_{S} | V _{IN} = V _{CC} or V _{SS} | | 0.10 | 3.0 | μΑ |
| I _{LO} | Output Leakage Current V _{CC} = 5.0V | V _{OUT} = V _{CC} or V | V _{OUT} = V _{CC} or V _{SS} | | 0.05 | 3.0 | μΑ |
| V _{IL} | Input Low Level ⁽¹⁾ | | | -0.6 | | V _{CC} x 0.3 | V |
| V _{IH} | Input High Level ⁽⁽¹⁾ | | | V _{CC} x 0.7 | | V _{CC} + 0.5 | V |
| V _{OL1} | Output Low Level | V _{CC} = 1.7V | I _{OL} = 0.15mA | | | 0.2 | V |
| V _{OL2} | Output Low Level | V _{CC} = 3.0V | I _{OL} = 2.1mA | | | 0.4 | V |

Note: 1. V_{IL} min and V_{IH} max are reference only and are not tested.

Table 5-3. AC Characteristics (Industrial Temperature)

Applicable over recommended operating range from: $T_{AI} = -40^{\circ}\text{C}$ to +85°C, $V_{CC} = 1.7\text{V}$ to 5.5V, CL = 100pF (unless otherwise noted). Test conditions are listed in Note 2.

| | | 1. | 7 V | 2.5V | , 5.0V | |
|--------------------------|--|------|------------|-------|--------|-----------------|
| Symbol | Parameter | Min | Max | Min | Max | Units |
| f _{SCL} | Clock Frequency, SCL | | 400 | | 1000 | kHz |
| t _{LOW} | Clock Pulse Width Low | 1300 | | 400 | | ns |
| t _{HIGH} | Clock Pulse Width High | 600 | | 400 | | ns |
| t _l | Noise Suppression Time ⁽¹⁾ | | 100 | | 50 | ns |
| t _{AA} | Clock Low to Data Out Valid | 50 | 900 | 50 | 550 | ns |
| t _{BUF} | Time the bus must be free before a new transmission can start ⁽¹⁾ | 1300 | | 500 | | ns |
| t _{HD.STA} | Start Hold Time | 600 | | 250 | | ns |
| t _{SU.STA} | Start Set-up Time | 600 | | 250 | | ns |
| t _{HD.DAT} | Data In Hold Time | 0 | | 0 | | ns |
| t _{SU.DAT} | Data In Set-up Time | 100 | | 100 | | ns |
| t _R | Inputs Rise Time ⁽¹⁾ | | 300 | | 300 | ns |
| t _F | Inputs Fall Time ⁽¹⁾ | | 300 | | 100 | ns |
| t _{SU.STO} | Stop Set-up Time | 600 | | 250 | | ns |
| t _{DH} | Data Out Hold Time | 50 | | 50 | | ns |
| t _{WR} | Write Cycle Time | | 5 | | 5 | ms |
| Endurance ⁽¹⁾ | 25°C, Page Mode, 3.3V | | 1,000 | 0,000 | | Write Cycles |

Notes: 1. This parameter is ensured by characterization and is not 100% tested.

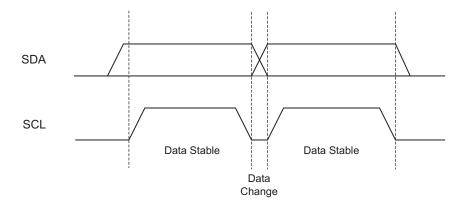
- 2. AC measurement conditions:
 - R_L (connects to V_{CC}): 1.3kΩ (2.5V, 5.5V), 10kΩ (1.7V)
 - Input pulse voltages: 0.3V_{CC} to 0.7V_{CC}
 - Input rise and fall times: ≤ 50ns
 - Input and output timing reference voltages: 0.5 x V_{CC}



6. Device Operation

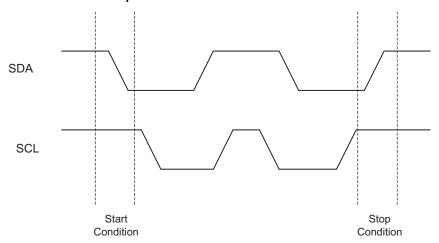
Clock and Data Transitions: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (See Figure 6-1). Data changes during SCL high periods will indicate a start or stop condition as defined below.

Figure 6-1. Data Validity



Start Condition: A high-to-low transition of SDA with SCL high is a Start condition that must precede every command (See Figure 6-2).

Figure 6-2. Start and Stop Definition



Stop Condition: A low-to-high transition of SDA with SCL high is a Stop condition. After a Read sequence, the Stop Condition will place the EEPROM in a standby power mode (See Figure 6-2).

Acknowledge: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The receiving device sends a zero during the ninth clock cycle to acknowledge that it has received each word. This zero response is referred to as an Acknowledge (See Figure 6-6).

Standby Mode: The AT24C64D features a low-power standby mode that is enabled upon power-up and after the receipt of the Stop condition and the completion of any internal operations.

Software Reset: After an interruption in protocol, power loss or system reset, any 2-wire part can be protocol reset by following these steps:

- 1. Create a Start condition,
- 2. Clock nine cycles,
- 3. Create another Start followed by Stop condition as shown below.

The device is ready for next communication after above steps has been completed.

Figure 6-3. Software Reset

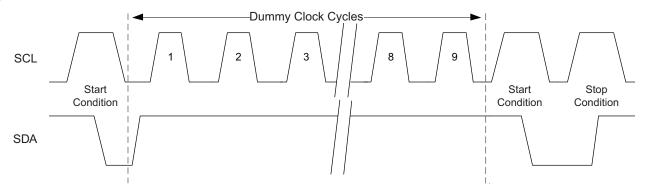


Figure 6-4. Bus Timing

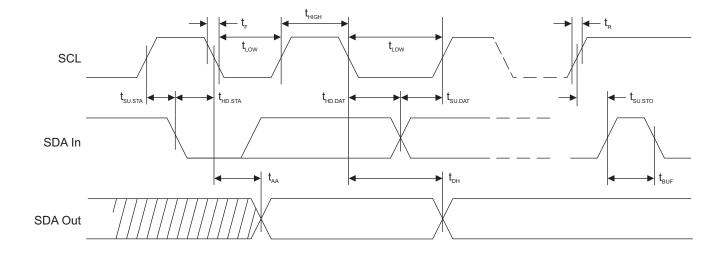
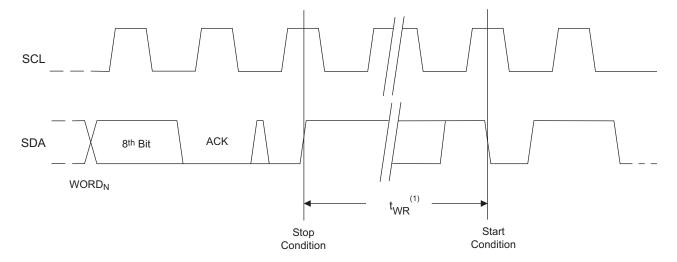


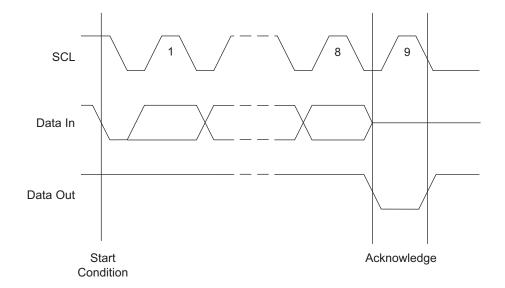


Figure 6-5. Write Cycle Timing



Note: 1. The write cycle time t_{WR} is the time from a valid stop condition of a write sequence to the end of the internal clear/write cycle.

Figure 6-6. Output Acknowledge



7. Device Addressing

The 64K EEPROM requires an 8-bit device address word following a start condition to enable the chip for a read or write operation. The device address word consists of a mandatory `1010' sequence for the first four most significant bits (bit 7, bit 6, bit 5, and bit 4 as seen in Figure 7-1). This is common to all 2-wire Serial EEPROM devices.

The next three bits are the A2, A1, and A0 device address bits to allow as many as eight devices on the same bus. These bits must compare to their corresponding hard wired input pins, where applicable. The A_2 , A_1 , and A_0 pins use an internal proprietary circuit that pulls them to GND if the pins are allowed to float.

When utilizing the 6-ball WLCSP package, the A_1 and A_0 pins are not available and are internally pulled to ground; therefore, the A1 and A0 device address bits must always be set to a Logic 0 condition to communicate with the device. This condition is depicted in Figure 7-1 below.

When utilizing the 5-ball WLCSP package, the A_2 , A_1 and A_0 pins are not available. The A_2 and A_1 pins are internally pulled to ground and thus the A2 and A1 device address bits must always be set to a Logic 0 condition to communicate with the device. The A_0 pin is internally connected to V_{CC} in this specific package only; therefore, the A0 software bit must be set to Logic 1 to communicate to the device. This condition is depicted in Figure 7-1 below.

The eighth bit of the device address is the Read/Write operation select bit. A Read operation is initiated if this bit is high, and a Write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a zero. If a compare is not made, the device will return to a standby state.

Figure 7-1. Device Addressing

| Package | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|---------------------------------------|-------|-------|-------|-------|-------|-------|-------|-------|
| SOIC, TSSOP, UDFN, XDFN, and VFBGA | 1 | 0 | 1 | 0 | A2 | A1 | A0 | R/W |
| 6-ball WLCSP | 1 | 0 | 1 | 0 | A2 | 0 | 0 | R/W |
| 5-ball WLCSP | 1 | 0 | 1 | 0 | 0 | 0 | 1 | R/W |
| | MSB | | | | | | | LSB |

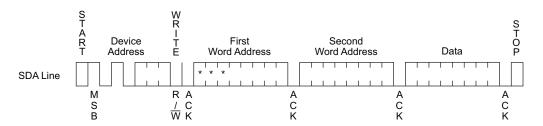
Data Security: AT24C64D has a hardware data protection scheme that allows the user to Write protect the whole memory when the WP pin is at V_{CC} .



8. Write Operations

Byte Write: A Write operation requires two 8-bit data word addresses following the device address word and acknowledgment. Upon receipt of this address, the EEPROM will again respond with a zero, and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a zero. The addressing device, such as a microcontroller, must then terminate the Write sequence with a Stop condition. At this time, the EEPROM enters an internally-timed Write cycle, t_{WR}, to the nonvolatile memory (See Figure 6-5). All inputs are disabled during this Write cycle and the EEPROM will not respond until the Write is complete (See Figure 8-1).

Figure 8-1. Byte Write

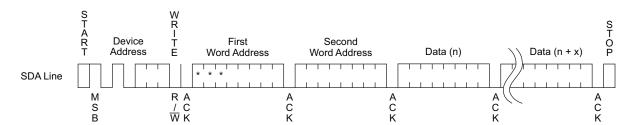


Note: * = Don't care bit.

Page Write: The 64K EEPROM is capable of 32-byte Page Writes.

A Page Write is initiated the same way as a Byte Write, but the microcontroller does not send a Stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to 31 more data words. The EEPROM will respond with a zero after each data word received. The microcontroller must terminate the Page Write sequence with a Stop condition (See Figure 8-2).

Figure 8-2. Page Write



Note: * = Don't care bit.

The data word address lower five bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than 32 data words are transmitted to the EEPROM, the data word address will roll-over and the previously loaded data will be altered. The address roll-over during Write is from the last byte of the current page to the first byte of the same page.

Acknowledge Polling: Once the internally-timed Write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a Start condition followed by the device address word. The Read/Write bit is representative of the operation desired. Only if the internal Write cycle has completed will the EEPROM respond with a zero, allowing the Read or Write sequence to continue.

9. Read Operations

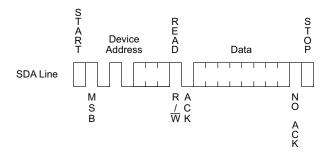
Read operations are initiated the same way as Write operations with the exception that the Read/Write select bit in the device address word is set to one. There are three Read operations:

- Current Address Read
- Random Address Read
- Sequential Read

Current Address Read: The internal data word address counter maintains the last address accessed during the last Read or Write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address roll-over during read is from the last byte of the last memory page, to the first byte of the first page.

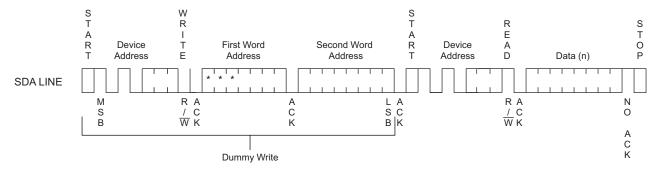
Once the device address with the Read/Write select bit set to one is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input zero but does generate a Stop condition (See Figure 9-1).

Figure 9-1. Current Address Read



Random Read: A Random Read requires a dummy Byte Write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another Start condition. The microcontroller now initiates a Current Address Read by sending a device address with the Read/Write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a zero but does generate a Stop condition. (See Figure 9-2)

Figure 9-2. Random Read

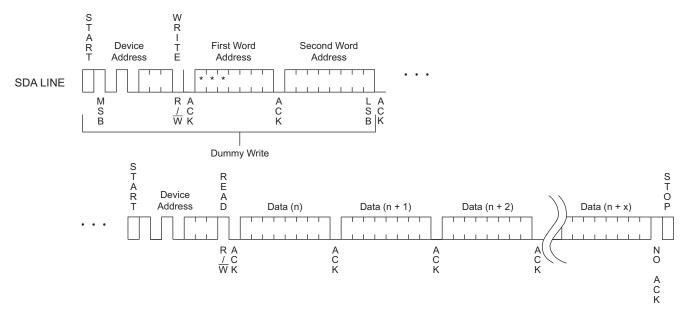


Note: * = Don't care bit.



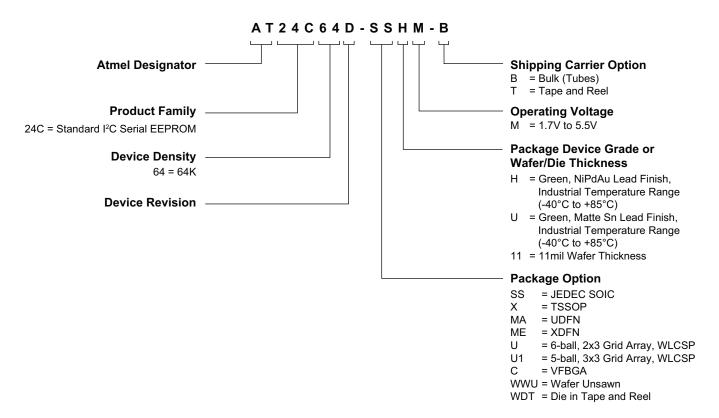
Sequential Read: Sequential Reads are initiated by either a Current Address Read or a Random Address Read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address maximum address is reached, the data word address will roll-over and the Sequential Read will continue from the beginning of the array. The Sequential Read operation is terminated when the microcontroller does not respond with a zero but does generate a Stop condition (See Figure 9-3).

Figure 9-3. Sequential Read



Note: * = Don't care bit.

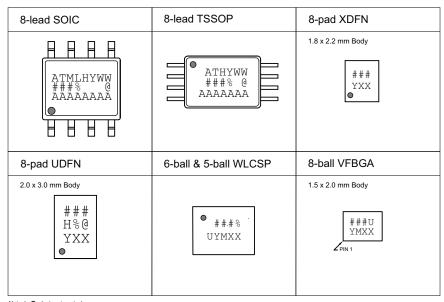
10. Ordering Code Detail





11. Part Markings

AT24C64D: Package Marking Information



Note 1: designates pin 1

Note 2: Package drawings are not to scale

| Catalog N | umber Trunca | tion | | | | |
|--|--|---------------------------------|--|--|----------------------------|--|
| AT24C64D | 1 | | | Truncation Code ###: 64D | | |
| Date Code | es | | | | Voltages | |
| Y = Year | | M = Month | | WW = Work Week of Assembly | % = Minimum Voltage | |
| 2: 2012 3: 2013 4: 2014 5: 2015 | 6: 2016 7: 2017 8: 2018 9: 2019 | A: January B: Februar L: Decemb | у | 02: Week 2 04: Week 4 52: Week 52 | M: 1.7V min | |
| Country o | f Assembly | | Lot Nu | mber | Grade/Lead Finish Material | |
| | | AAA/ | A = Atmel Wafer Lot Number | U: Industrial/Matte Tin/SnAo H: Industrial/NiPdAu | guCu | |
| Trace Cod | е | | | | Atmel Truncation | |
| XX = Trace Code (Atmel Lot Numbers Correspond Example: AA, AB YZ, ZZ | | d to Code) | AT: Atmel ATM: Atmel ATML: Atmel | | | |

3/8/13

| Atmel | TITLE | DRAWING NO. | REV. |
|--|--|-------------|------|
| Package Mark Contact: DL-CSO-Assy_eng@atmel.com | 24C64DSM, AT24C64D Package Marking Information | 24C64DSM | D |

12. Ordering Codes

12.1 Atmel AT24C64D Ordering Information

| Ordering Code | Lead Finish | Package | Voltage | Operating Range |
|--------------------------------|------------------------------------|------------|--------------|---|
| AT24C64D-SSHM-B ⁽¹⁾ | | 8S1 | | |
| AT24C64D-SSHM-T ⁽²⁾ | NiPdAu (Lead-free/Halogen-free) | 651 | | |
| AT24C64D-XHM-B ⁽¹⁾ | | 0.7 | | |
| AT24C64D-XHM-T ⁽²⁾ | | 8X | 1.7V to 5.5V | Industrial Temperature (-40°C to 85°C) |
| AT24C64D-MAHM-T ⁽²⁾ | | 8MA2 | | |
| AT24C64D-MEHM-T ⁽²⁾ | | 8ME1 | | |
| AT24C64D-UUM-T ⁽²⁾ | | 6U-1 | | |
| AT24C64D-U1UM-T ⁽²⁾ | SnAgCu (Lead-free/Halogen-free) | 5U-2 | | |
| AT24C64D-CUM-T ⁽²⁾ | | 8U2-1 | | |
| AT24C64D-WWU11M ⁽³⁾ | _ | Wafer Sale | | |

Notes: 1. Bulk delivery in tubes:

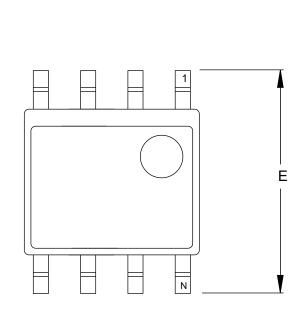
- SOIC and TSSOP = 100 per tube
- 2. Tape and reel delivery:
 - SOIC = 4k per reel
 - TSSOP, UDFN, XDFN, WLCSP, and VFBGA = 5k per reel
- 3. Contact Atmel Sales for Wafer sales.

| | Package Type |
|-------|---|
| 8S1 | 8-lead, 0.150" wide, Plastic Gull Wing Small Outline (JEDEC SOIC) |
| 8X | 8-lead, 4.40mm body, Plastic Thin Shrink Small Outline (TSSOP) |
| 8MA2 | 8-pad, 2.00mm x 3.00mm body, 0.50mm pitch, Dual No Lead (UDFN) |
| 8ME1 | 8-pad, 1.80mm x 2.20mm body, Extra Thin DFN (XDFN) |
| 6U-1 | 6-ball, 2x3 Grid Array, Wafer Level Chip Scale (WLCSP) |
| 5U-2 | 5-ball, 3x3 Grid Array, Wafer Level Chip Scale (WLCSP) |
| 8U2-1 | 8-ball, Die Ball Grid Array (VFBGA) |

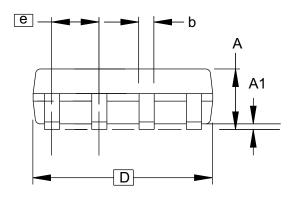


13. Packaging Information

13.1 8S1 — 8-lead JEDEC SOIC

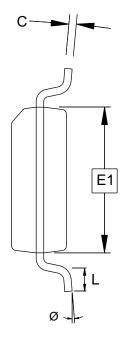


TOP VIEW



SIDE VIEW

Notes: This drawing is for general information only. Refer to JEDEC Drawing MS-012, Variation AA for proper dimensions, tolerances, datums, etc.



END VIEW

COMMON DIMENSIONS (Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|------|----------|------|------|
| Α | 1.35 | _ | 1.75 | |
| A1 | 0.10 | _ | 0.25 | |
| b | 0.31 | _ | 0.51 | |
| С | 0.17 | _ | 0.25 | |
| D | 4.80 | _ | 5.05 | |
| E1 | 3.81 | _ | 3.99 | |
| E | 5.79 | _ | 6.20 | |
| е | | 1.27 BSC | , | |
| L | 0.40 | _ | 1.27 | |
| Ø | 0° | _ | 8° | |

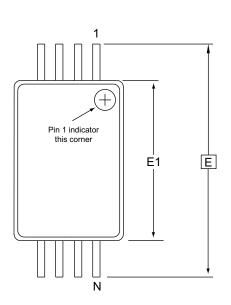
6/22/11

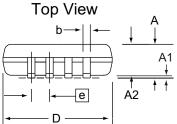
Package Drawing Contact: packagedrawings@atmel.com

TITLE8S1, 8-lead (0.150" Wide Body), Plastic Gull Wing Small Outline (JEDEC SOIC)

| GPC DRAWING NO | | REV |
|----------------|-----|-----|
| SWB | 8S1 | G |

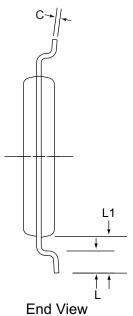
13.2 8X — 8-lead TSSOP





Side View

- Notes: 1. This drawing is for general information only. Refer to JEDEC Drawing MO-153, Variation AA, for proper dimensions, tolerances, datums, etc.
 - 2. Dimension D does not include mold Flash, protrusions or gate burrs. Mold Flash, protrusions and gate burrs shall not exceed 0.15mm (0.006in) per side.
 - 3. Dimension E1 does not include inter-lead Flash or protrusions. Inter-lead Flash and protrusions shall not exceed 0.25mm (0.010in) per side.
 - 4. Dimension b does not include Dambar protrusion. Allowable Dambar protrusion shall be 0.08mm total in excess of the b dimension at maximum material condition. Dambar cannot be located on the lower radius of the foot. Minimum space between protrusion and adjacent lead is 0.07mm.
 - 5. Dimension D and E1 to be determined at Datum Plane H.



COMMON DIMENSIONS (Unit of Measure = mm)

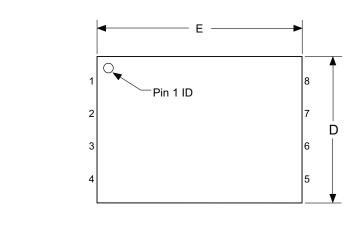
| (Cint of model of min) | | | | |
|------------------------|----------|----------|------|------|
| SYMBOL | MIN | NOM | MAX | NOTE |
| Α | - | - | 1.20 | |
| A1 | 0.05 | - | 0.15 | |
| A2 | 0.80 | 1.00 | 1.05 | |
| D | 2.90 | 3.00 | 3.10 | 2, 5 |
| E | | 6.40 BSC | | |
| E1 | 4.30 | 4.40 | 4.50 | 3, 5 |
| b | 0.19 | _ | 0.30 | 4 |
| е | | 0.65 BSC | | |
| L | 0.45 | 0.60 | 0.75 | |
| L1 | 1.00 REF | | | |
| С | | 0.09 | - | 0.20 |

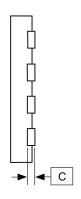
6/22/11

| Atmel | TITLE | GPC | DRAWING NO. | REV. |
|--|---|-----|-------------|------|
| Package Drawing Contact: packagedrawings@atmel.com | 8X, 8-lead 4.4mm Body, Plastic Thin Shrink Small Outline Package (TSSOP) | TNR | 8X | D |

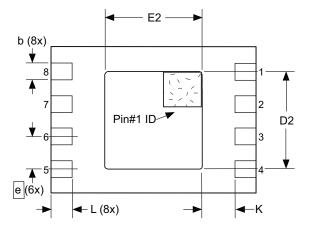


13.3 8MA2 — 8-pad UDFN









COMMON DIMENSIONS (Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|----------|-----------|------|------|
| D | 1.90 | 2.00 | 2.10 | |
| E | 2.90 | 3.00 | 3.10 | |
| D2 | 1.40 | 1.50 | 1.60 | |
| E2 | 1.20 | 1.30 | 1.40 | |
| А | 0.50 | 0.55 | 0.60 | |
| A1 | 0.0 | 0.02 | 0.05 | |
| A2 | _ | _ | 0.55 | |
| С | | 0.152 REF | | |
| L | 0.30 | 0.35 | 0.40 | |
| е | 0.50 BSC | | | |
| b | 0.18 | 0.25 | 0.30 | 3 |
| K | 0.20 | - | - | |

Notes: 1. This drawing is for general information only. Refer to JEDEC Drawing MO-229, for proper dimensions, tolerances, datums, etc.

- 2. The terminal #1 ID is a laser-marked feature.
- 3. Dimension b applies to metallized terminal and is measured between 0.15 mm and 0.30 mm from the terminal tip. If the terminal has the optional radius on the other end of the terminal, the dimension should not be measured in that radius area.

9/6/12

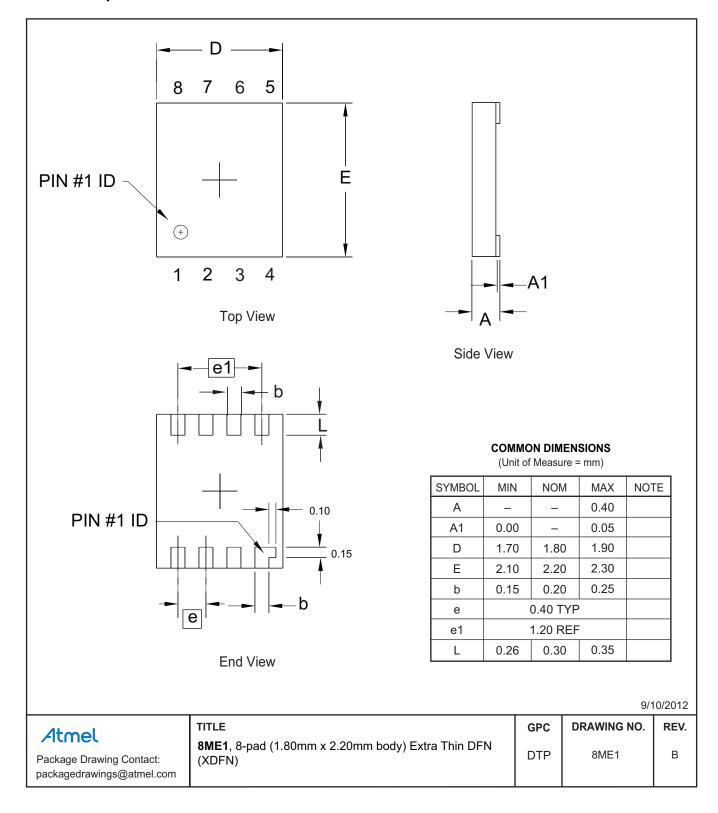
REV.

С

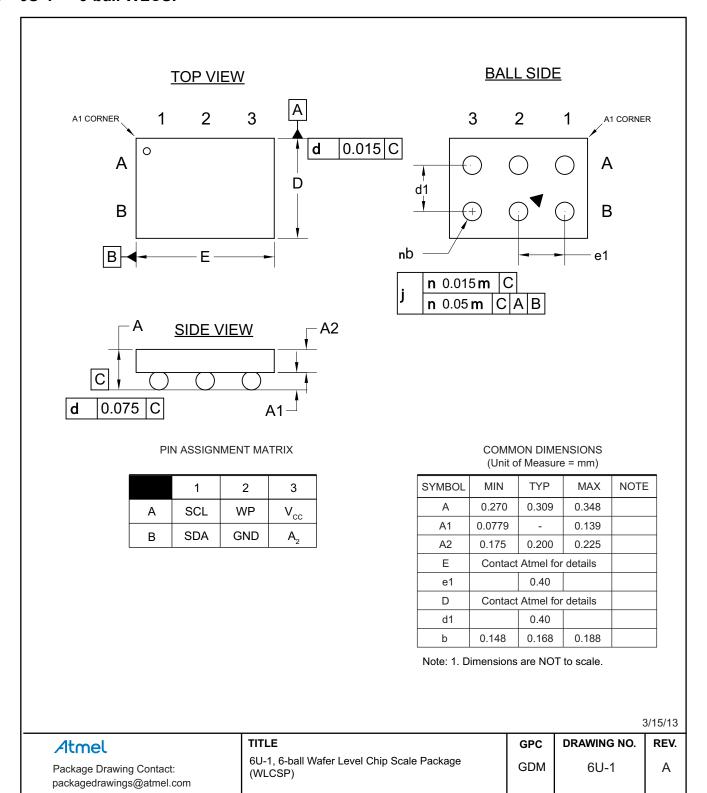
| Atmel | |
|---------------------------|---|
| Package Drawing Contact: | ı |
| packagedrawings@atmel.com | |

| TITLE | GPC | DRAWING NO. |
|---|-----|-------------|
| 8MA2, 8-pad, 2 x 3 x 0.6 mm Body, Thermally Enhanced Plastic Ultra Thin Dual Flat No | YNZ | 8MA2 |
| Lead Package (UDFN) | | |

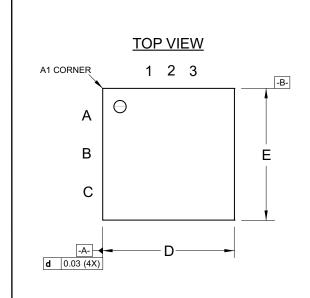
13.4 8ME1 — 8-pad XDFN

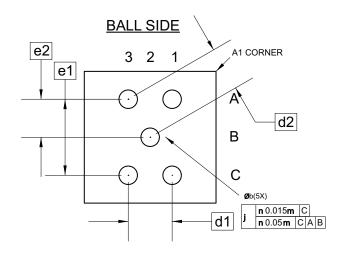


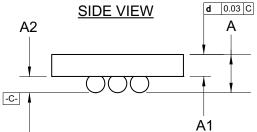
13.5 6U-1 — 6-ball WLCSP



13.6 5U-2 — 5-ball WLCSP







Note: Dimensions are NOT to scale.

PIN ASSIGNMENT MATRIX

| | 1 | 2 | 3 |
|---|-----------------|-----|-----|
| А | V _{cc} | n/a | GND |
| В | n/a | SDA | n/a |
| С | WP | n/a | SCL |

COMMON DIMENSIONS (Unit of Measure = mm)

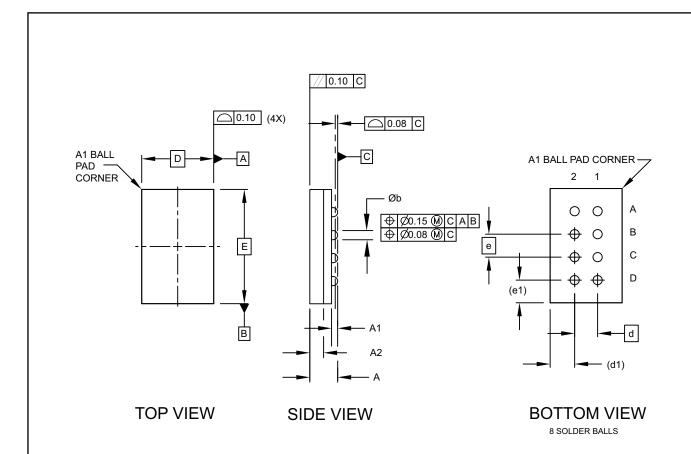
| SYMBOL | MIN | TYP | MAX | NOTE |
|--------|---------------------------|---------------------------|-------|------|
| Α | 0.270 | 0.309 | 0.348 | |
| A1 | 0.078 | - | 0.139 | |
| A2 | 0.175 | 0.200 | 0.225 | |
| E | Contact Atmel for details | | | |
| e1 | 0.693 | | | |
| e2 | | 0.3465 | | |
| D | Conta | Contact Atmel for details | | |
| d1 | 0.4 | | | |
| d2 | 0.4 | | | |
| b | 0.148 | 0.168 | 0.188 | |

7/30/13

| Atmel | TITLE | GPC | DRAWING NO. | REV. |
|--|--|-----|-------------|------|
| Package Drawing Contact: packagedrawings@atmel.com | 5U-2, 5-ball Wafer Level Chip Scale Package (WLCSP) | GPK | 5U-2 | А |



13.7 8U2-1 — 8-ball VFBGA



COMMON DIMENSIONS (Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|----------|----------|------|------|
| Α | 0.81 | 0.91 | 1.00 | |
| A1 | 0.15 | 0.20 | 0.25 | |
| A2 | 0.40 | 0.45 | 0.50 | |
| b | 0.25 | 0.30 | 0.35 | |
| D | 2 | 2.35 BSC | | |
| Е | 3 | .73 BSC |) | |
| е | 0 | 0.75 BSC | | |
| e1 | 0 | 0.74 REF | | |
| d | 0.75 BSC | | | |
| d1 | 0 | .80 REF | | |

Notes:

- 1. This drawing is for general information.
- 2. Dimension 'b' is measured at the maximum solder ball diameter.
- 3. Solder ball composition shall be 95.5Sn-4.0Ag-.5Cu.

3/20/12

| Atmel | TITLE | GPC | DRAWING NO. | REV. |
|---|--|-----|-------------|------|
| Package Drawing Contact: packagedrawings@atmel.com | 8U2-1, 8-ball, 2.35 x 3.73 mm Body, 0.75 mm pitch, VFBGA Package | GWW | 8U2-1 | F |

14. Revision History

| Doc. Rev. | Date | Comments |
|-----------|---------|--------------------------|
| 8850A | 08/2013 | Inital document release. |















Atmel Corporation 1600 Technology Drive, San Jose, CA 95110 USA **T:** (+1)(408) 441.0311

F: (+1)(408) 436.4200

www.atmel.com

© 2013 Atmel Corporation. / Rev.: Atmel-8850A-SEEPROM-AT24C64D-Datasheet_082013.

Atmel®, Atmel logo and combinations thereof, and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.

DISCLAIMER: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN THE ATMEL TERMS AND CONDITIONS OF SALES LOCATED ON THE ATMEL WEBSITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS AND PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and products descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

SAFETY-CRITICAL, MILITARY, AND AUTOMOTIVE APPLICATIONS DISCLAIMER: Atmel products are not designed for and will not be used in connection with any applications where the failure of such products would reasonably be expected to result in significant personal injury or death ("Safety-Critical Applications") without an Atmel officer's specific written consent. Safety-Critical Applications include, without limitation, life support devices and systems, equipment or systems for the operation of nuclear facilities and weapons systems. Atmel products are not designed nor intended for use in military or aerospace applications or environments unless specifically designated by Atmel as military-grade. Atmel products are not designed nor intended for use in automotive applications unless specifically designated by Atmel as automotive-grade.