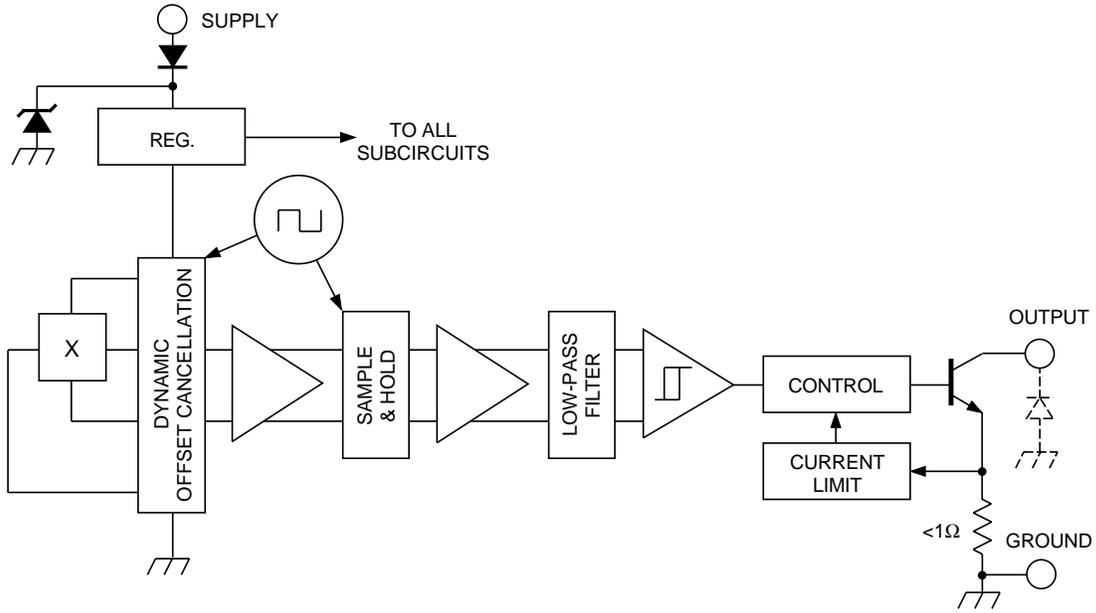


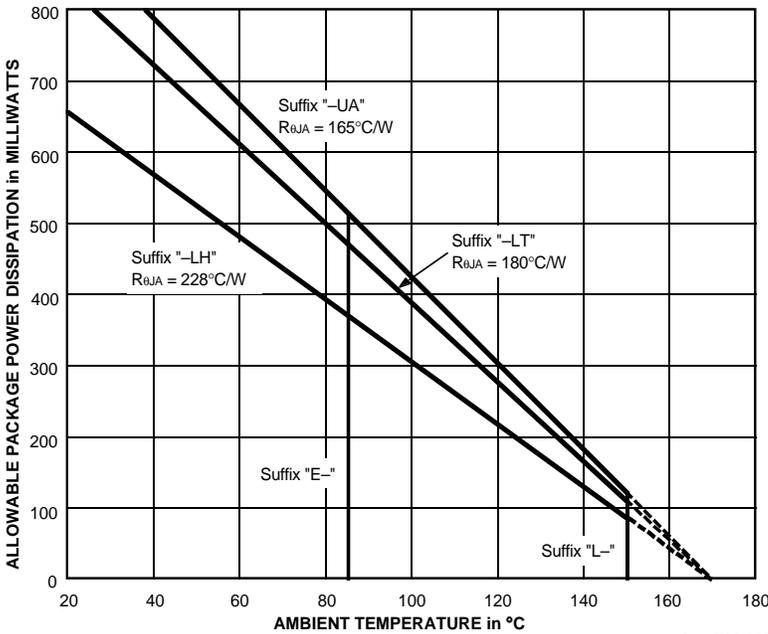


# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

## FUNCTIONAL BLOCK DIAGRAM

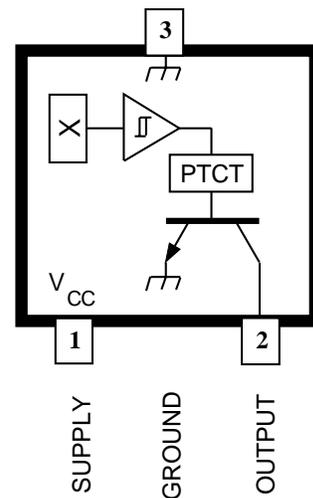


Dwg. FH-020-1



Dwg. GH-046-2D

## Suffix '-LH' Pinning (SOT23W)



Dwg. PH-003-4

**3240**  
**CHOPPER-STABILIZED,**  
**PRECISION**  
**HALL-EFFECT SWITCH**

**ELECTRICAL CHARACTERISTICS over operating temperature range.**

Characteristic	Symbol	Test Conditions	Limits			
			Min.	Typ.	Max.	Units
Supply Voltage Range	$V_{CC}$	Operating, $T_J < 165^\circ\text{C}^1$	4.2	–	24	V
Output Leakage Current	$I_{OFF}$	$V_{OUT} = 24\text{ V}$ , $B < B_{RP}$	–	–	10	$\mu\text{A}$
Output Saturation Voltage	$V_{OUT(SAT)}$	$I_{OUT} = 20\text{ mA}$ , $B > B_{OP}$	–	185	500	mV
Output Current Limit	$I_{OM}$	$B > B_{OP}$	30	–	60	mA
Power-On Time	$t_{po}$	$V_{CC} > 4.2\text{ V}$	–	–	50	$\mu\text{s}$
Chopping Frequency	$f_C$		–	340	–	kHz
Output Rise Time	$t_r$	$R_L = 820\ \Omega$ , $C_L = 20\ \text{pF}$	–	0.2	2.0	$\mu\text{s}$
Output Fall Time	$t_f$	$R_L = 820\ \Omega$ , $C_L = 20\ \text{pF}$	–	0.1	2.0	$\mu\text{s}$
Supply Current	$I_{CC}$	$B < B_{RP}$ , $V_{CC} = 12\text{ V}$	–	3.0	6.0	mA
		$B > B_{OP}$ , $V_{CC} = 12\text{ V}$	–	4.0	6.0	mA
Reverse Battery Current	$I_{CC}$	$V_{RCC} = -30\text{ V}$	–	–	-5.0	mA
Zener Voltage	$V_Z + V_D$	$I_{CC} = 15\text{ mA}$ , $T_A = 25^\circ\text{C}$	28	32	37	V
Zener Impedance	$Z_Z + Z_D$	$I_{CC} = 15\text{ mA}$ , $T_A = 25^\circ\text{C}$	–	50	–	$\Omega$

- NOTES: 1. Maximum voltage must be adjusted for power dissipation and junction temperature.  
 2.  $B_{OP}$  = operate point (output turns on);  $B_{RP}$  = release point (output turns off).  
 3. Typical Data is at  $T_A = +25^\circ\text{C}$  and  $V_{CC} = 12\text{ V}$  and is for design information only.

**MAGNETIC CHARACTERISTICS over operating supply voltage and temperature ranges.**

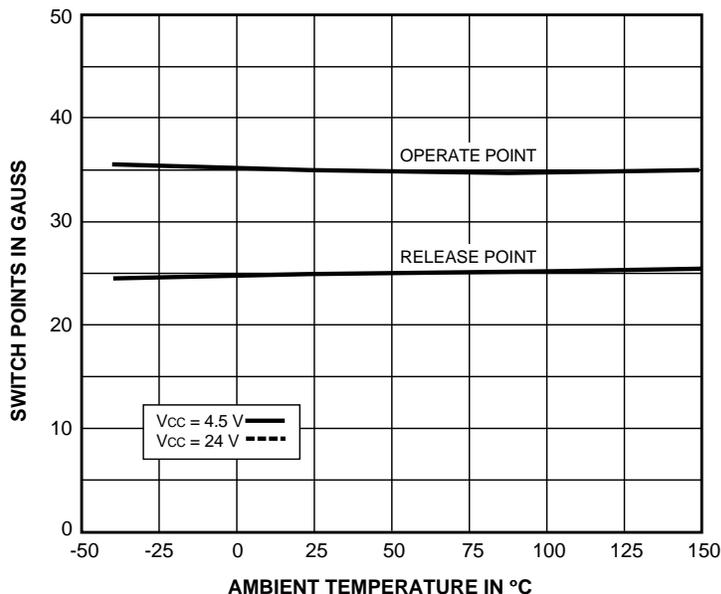
Characteristic	Symbol	Test Conditions	Limits			
			Min.	Typ.	Max.	Units
Operate Point	$B_{OP}$		–	35	50	G
Release Point	$B_{RP}$		5.0	25	–	G
Hysteresis	$B_{hys}$	$B_{OP} - B_{RP}$	–	10	–	G

- NOTES: 1. Typical Data is at  $T_A = +25^\circ\text{C}$  and  $V_{CC} = 12\text{ V}$  and is for design information only.  
 2. 1 gauss (G) is exactly equal to 0.1 millitesla (mT).

# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

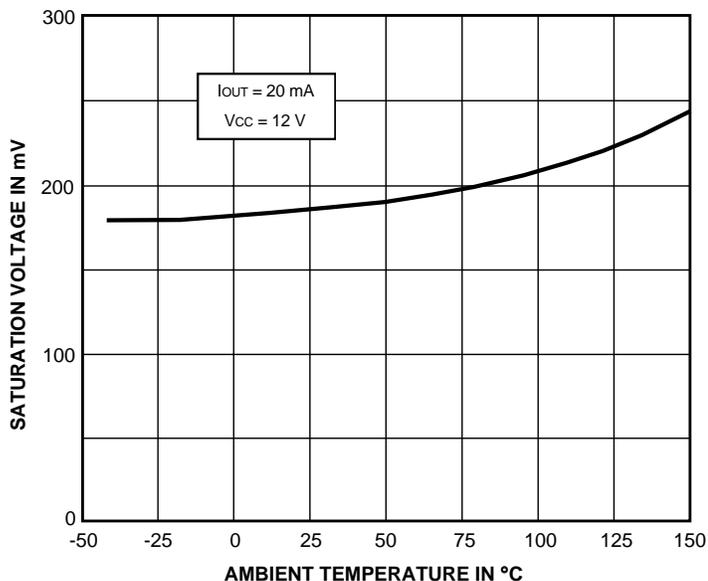
## TYPICAL OPERATING CHARACTERISTICS as a function of temperature

### SWITCH POINTS



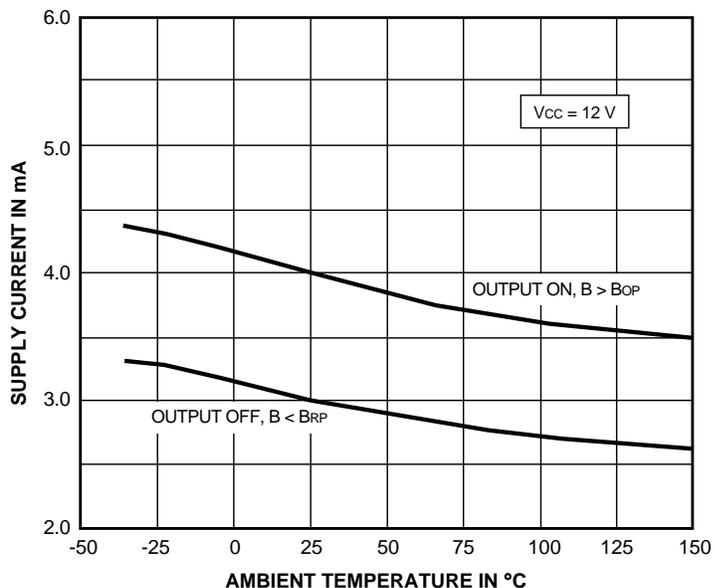
Dwg. GH-026-5

### OUTPUT SATURATION VOLTAGE



Dwg. GH-029-4

### SUPPLY CURRENT

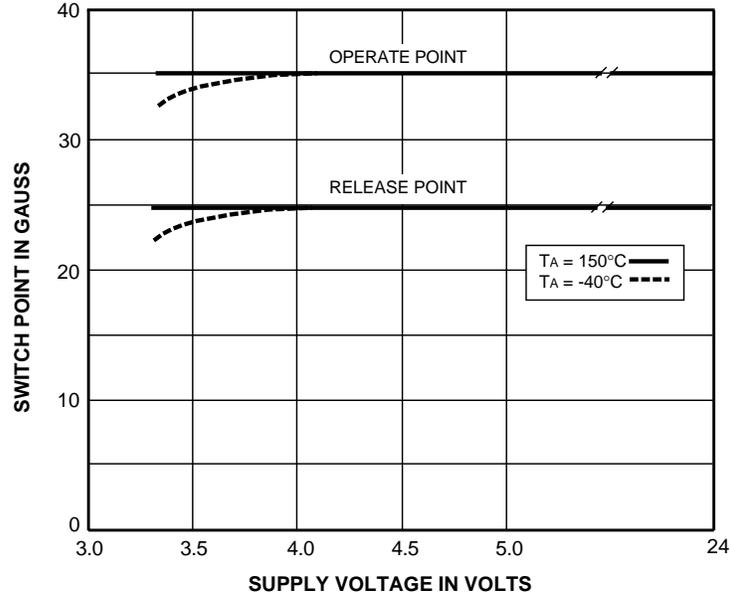


Dwg. GH-028-5

# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

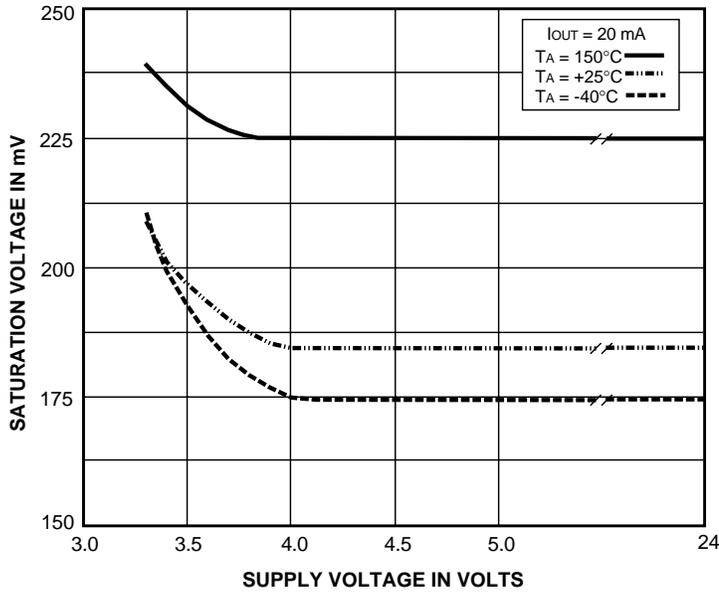
## TYPICAL OPERATING CHARACTERISTICS as a function of supply voltage

### SWITCH POINTS



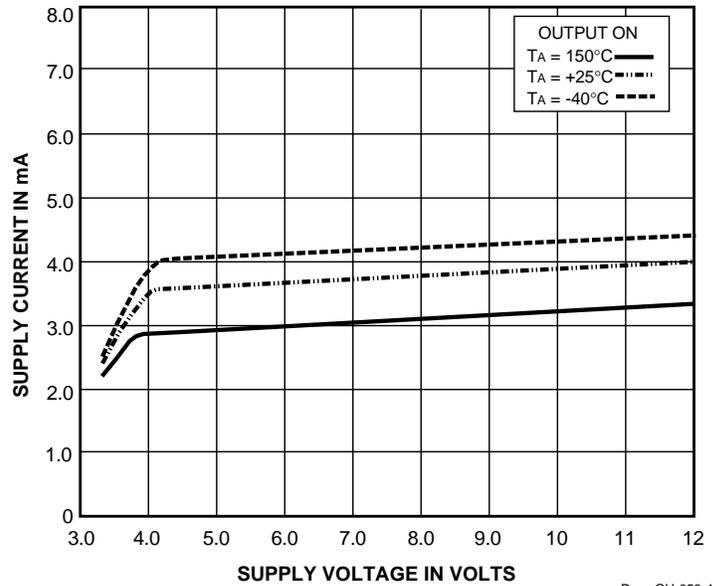
Dwg. GH-021-2

### OUTPUT SATURATION VOLTAGE



Dwg. GH-055-1

### SUPPLY CURRENT

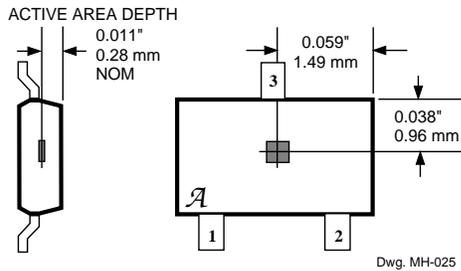


Dwg. GH-058-4

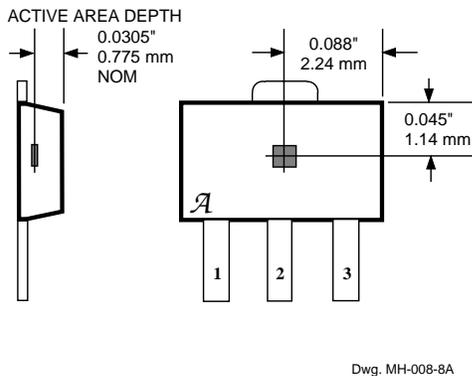
# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

## SENSOR LOCATIONS

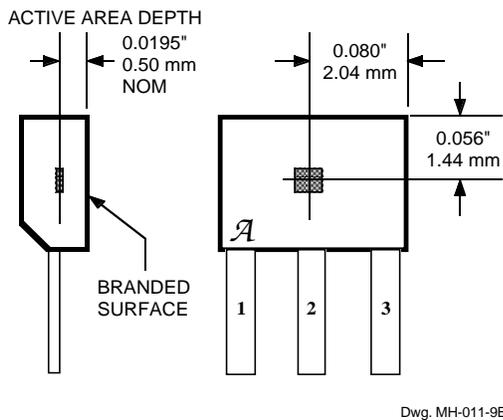
### Package Designator 'LH'



### Package Designator 'LT'



### Package Designator 'UA'



The products described herein are manufactured under one or more of the following U.S. patents: 5,045,920; 5,264,783; 5,442,283; 5,389,889; 5,581,179; 5,517,112; 5,619,137; 5,621,319; 5,650,719; 5,686,894; 5,694,038; 5,729,130; 5,917,320; and other patents pending.

Allegro MicroSystems, Inc. reserves the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the performance, reliability, or manufacturability of its products. Before placing an order, the user is cautioned to verify that the information being relied upon is current.

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# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

## FUNCTIONAL DESCRIPTION

**Chopper-Stabilized Technique.** The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistor circuit by changing the direction of the current flowing through the Hall plate using CMOS switches and Hall voltage measurement taps, while maintaining the Hall-voltage signal that is induced by the external magnetic flux. The signal is then captured by a sample-and-hold circuit and further processed using low-offset bipolar circuitry. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique will also slightly degrade the device output repeatability. A relatively high sampling frequency is used in order that faster signals can be processed.

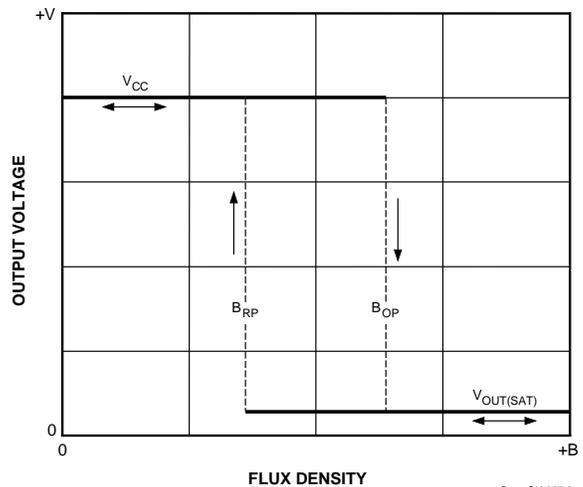
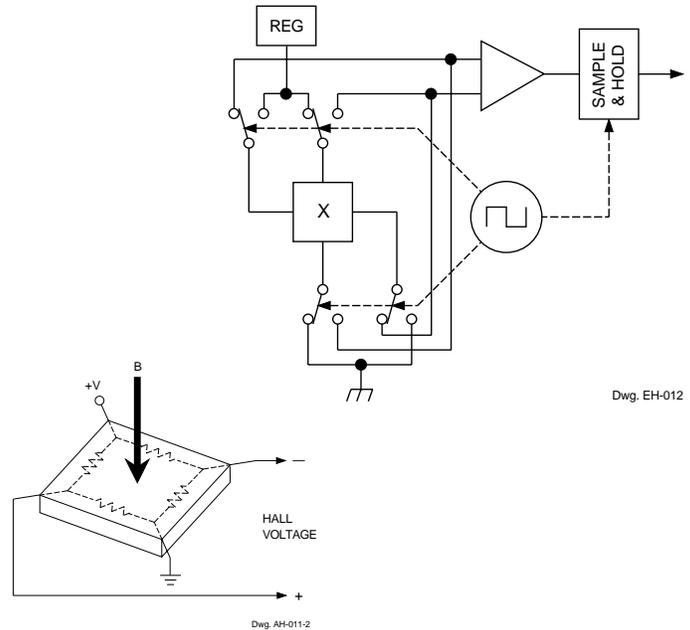
More detailed descriptions of the circuit operation can be found in: Technical Paper STP 97-10, *Monolithic Magnetic Hall Sensor Using Dynamic Quadrature Offset Cancellation* and Technical Paper STP 99-1, *Chopper-Stabilized Amplifiers With A Track-and-Hold Signal Demodulator*.

**Operation.** The output of these devices switches low (turns on) when a magnetic field (south pole) perpendicular to the Hall sensor exceeds the operate point threshold ( $B_{OP}$ ). After turn-on, the output is capable of sinking 25 mA and the output voltage is  $V_{OUT(SAT)}$ . When the magnetic field is reduced below the release point ( $B_{RP}$ ), the device output goes high (turns off). The difference in the magnetic operate and release points is the hysteresis ( $B_{HYS}$ ) of the device. This built-in hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise.

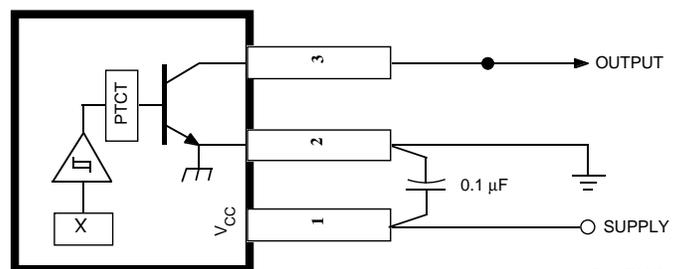
**Applications.** It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique.

The simplest form of magnet that will operate these devices is a ring magnet. Other methods of operation, such as linear magnets, are possible. Extensive applications information on magnets and Hall-effect sensors is also available in *Application Note 27701*, or at

[www.allegromicro.com](http://www.allegromicro.com)



○ SUPPLY

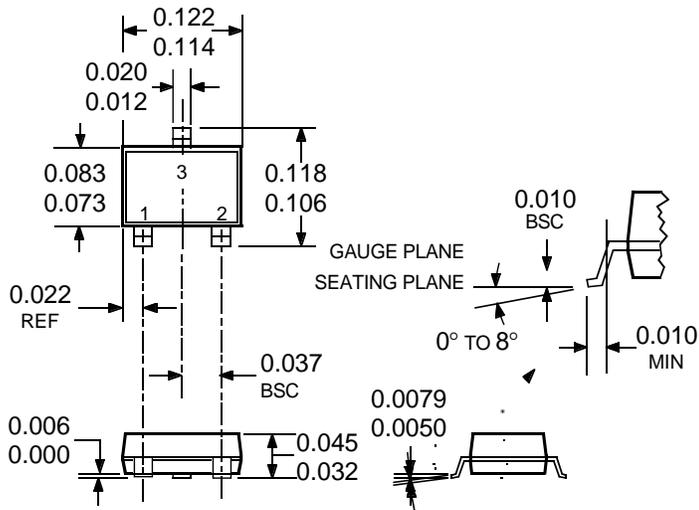


**3240**  
**CHOPPER-STABILIZED,**  
**PRECISION**  
**HALL-EFFECT SWITCH**

**PACKAGE DESIGNATOR 'LH'**

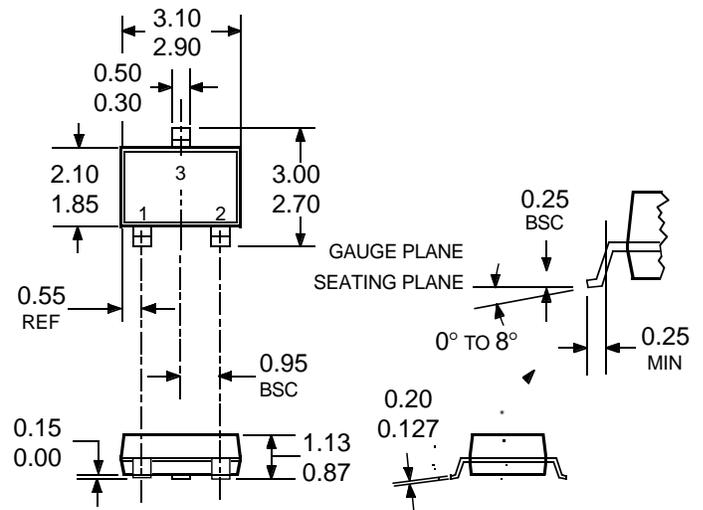
(fits SC-59A solder-pad layout)

**Dimensions in Inches**  
(for reference only)

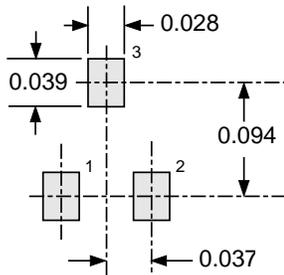


Dwg. MA-010-3D in

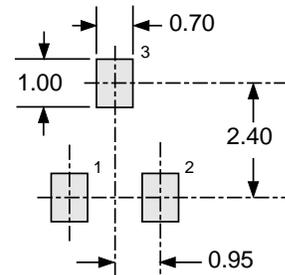
**Dimensions in Millimeters**  
(controlling dimensions)



Dwg. MA-010-3D mm



Dwg. MA-011-3 in



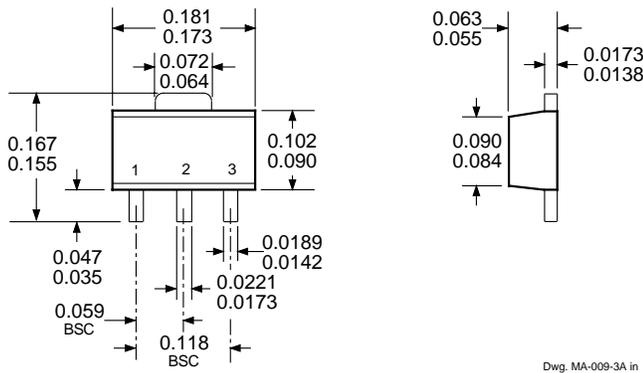
Dwg. MA-011-3 mm

- NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).  
2. Exact body and lead configuration at vendor's option within limits shown.  
3. Height does not include mold gate flash.  
4. Where no tolerance is specified, dimension is nominal.  
5. Add "LT" to part number for tape and reel.

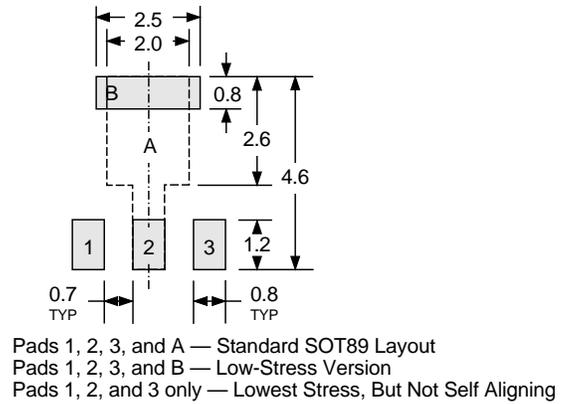
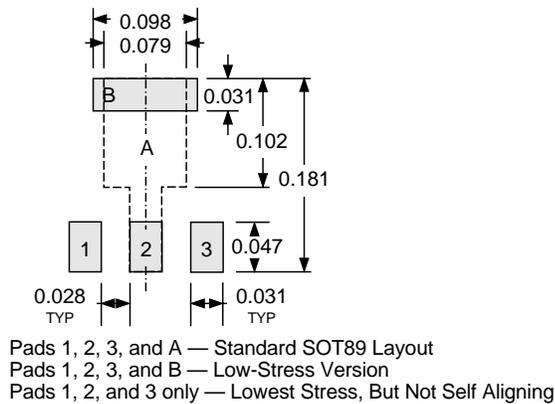
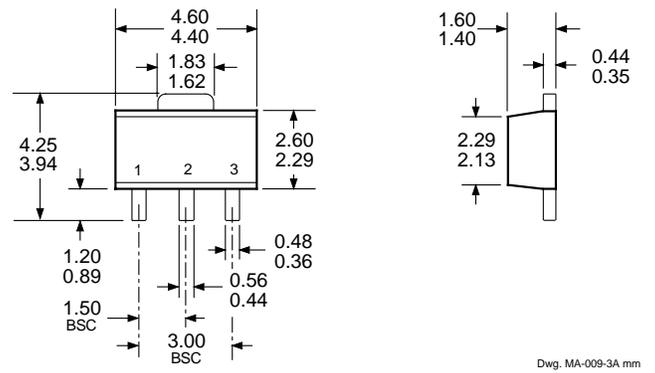
# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

## PACKAGE DESIGNATOR 'LT' (SOT89/TO-243AA)

**Dimensions in Inches**  
(for reference only)



**Dimensions in Millimeters**  
(controlling dimensions)

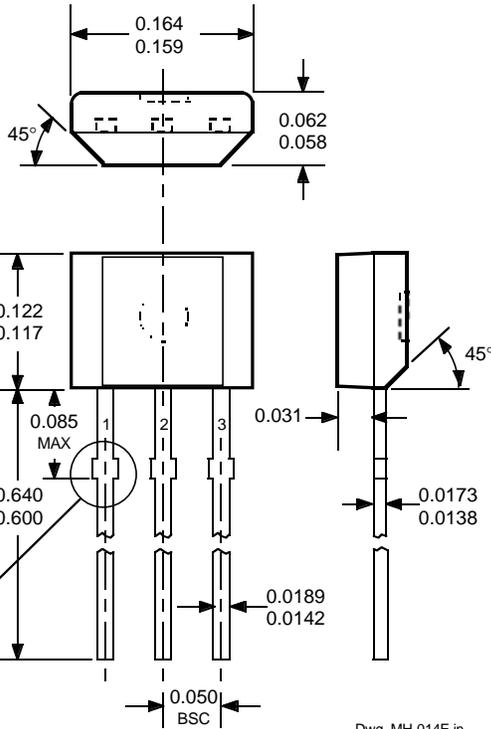


- NOTES:
1. Exact body and lead configuration at vendor's option within limits shown.
  2. Supplied in bulk pack (500 pieces per bag) or add "TR" to part number for tape and reel.
  3. Only low-temperature ( $\leq 240^{\circ}\text{C}$ ) reflow-soldering techniques are recommended for SOT89 devices.

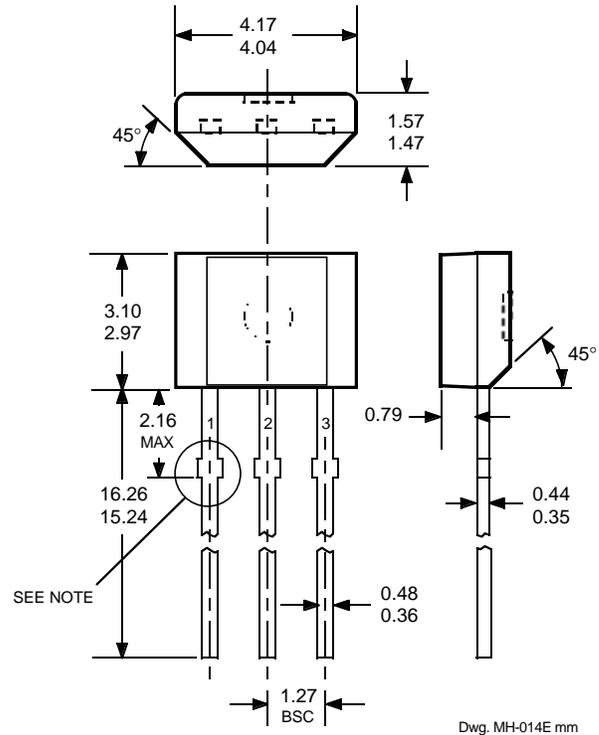
# 3240 CHOPPER-STABILIZED, PRECISION HALL-EFFECT SWITCH

## PACKAGE DESIGNATOR 'UA'

Dimensions in Inches  
(controlling dimensions)

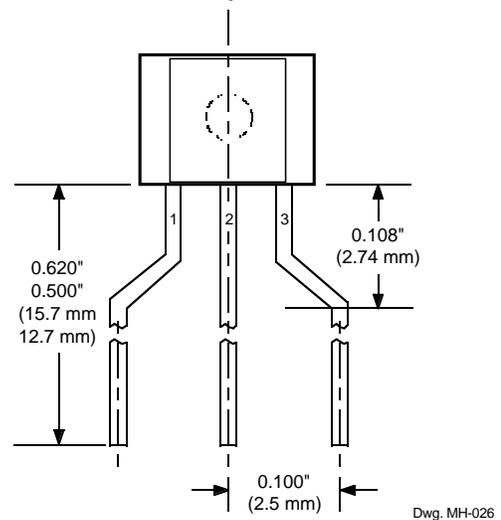


Dimensions in Millimeters  
(for reference only)



- NOTES:
1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).
  2. Exact body and lead configuration at vendor's option within limits shown.
  3. Height does not include mold gate flash.
  4. Recommended minimum PWB hole diameter to clear transition area is 0.035" (0.89 mm).
  5. Where no tolerance is specified, dimension is nominal.
  6. Supplied in bulk pack (500 pieces per bag).

## Radial Lead Form (order A3240xUA-LC)



NOTE: Lead-form dimensions are the nominals produced on the forming equipment. No dimensional tolerance is implied or guaranteed for bulk packaging (500 pieces per bag).