SA58670A

2.1 W/channel stereo class-D audio amplifier

Rev. 02 — 23 October 2008

Product data sheet

1. General description

The SA58670A is a stereo, filter-free class-D audio amplifier which is available in an HVQFN20 package with the exposed Die Attach Paddle (DAP).

The SA58670A features independent shutdown controls for each channel. The gain may be set at 6 dB, 12 dB, 18 dB or 24 dB with gain select pins G0 and G1. Improved immunity to noise and RF rectification is increased by high PSRR and differential circuit topology. Fast start-up time and small package makes it an ideal choice for both cellular handsets and PDAs.

The SA58670A delivers 1.4 W/channel at 5.0 V and 720 mW/channel at 3.6 V into 8 Ω . It delivers 2.1 W/channel at 5.0 V into 4 Ω . The maximum power efficiency is excellent at 70 % to 74 % into 4 Ω and 84 % to 88 % into 8 Ω . The SA58670A provides thermal and short-circuit shutdown protection.

2. Features

- Output power:
 - 2.1 W/channel into 4 Ω at 5.0 V
 - 1.4 W/channel into 8 Ω at 5.0 V
 - ◆ 720 mW/channel into 8 Ω at 3.6 V
- Supply voltage: 2.5 V to 5.5 V
- Independent shutdown control for each channel
- Selectable gain: 6 dB, 12 dB, 18 dB and 24 dB
- High SVRR: -77 dB at 217 Hz
- Fast start-up time: 3.5 ms
- Low supply current
- Low shutdown current
- Short-circuit and thermal protection
- Space savings with 4 mm × 4 mm HVQFN20 package
- Low junction to ambient thermal resistance of 24 K/W with exposed DAP

3. Applications

- Wireless and cellular handset and PDA
- Portable DVD player
- USB speaker
- Notebook PC
- Portable radio and gaming



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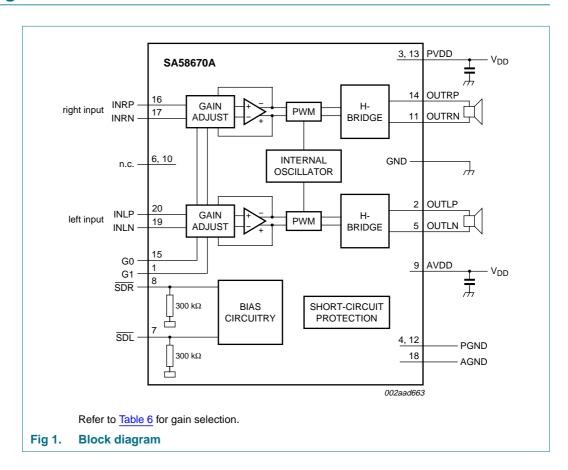
Educational toy

4. Ordering information

Table 1. Ordering information

Type number	mber Package					
	Name	Description	Version			
SA58670ABS	HVQFN20	plastic thermal enhanced very thin quad flat package; no leads; 20 terminals; body $4\times4\times0.85$ mm	SOT917-1			

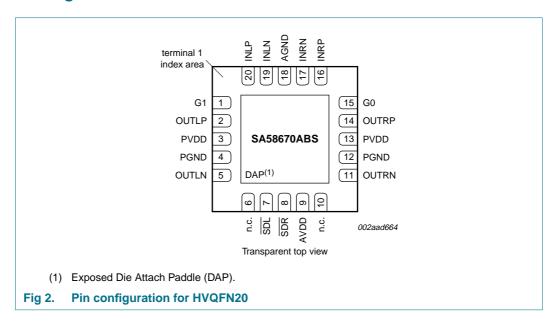
5. Block diagram



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6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
G1	1	gain select input 1
OUTLP	2	left channel positive output
PVDD	3	power supply voltage (level same as AVDD)
PGND	4	power ground
OUTLN	5	left channel negative output
n.c.	6	not connected
SDL	7	left channel shutdown input (active LOW)
SDR	8	right channel shutdown input (active LOW)
AVDD	9	analog supply voltage (level same as PVDD)
n.c.	10	not connected
OUTRN	11	right channel negative output
PGND	12	power ground
PVDD	13	power supply voltage (level same as AVDD)
OUTRP	14	right channel positive output
G0	15	gain select input 0
INRP	16	right channel positive input
INRN	17	right channel negative input
AGND	18	analog ground

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 Table 2.
 Pin description ...continued

Symbol	Pin	Description
INLN	19	left channel negative input
INLP	20	left channel positive input
-	(DAP)	exposed die attach paddle; connect to ground plane heat spreader

7. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).[1]

		<u> </u>			
Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage	Active mode	-0.3	+6.0	V
		Shutdown mode	-0.3	+7.0	V
VI	input voltage	pin SDL	GND	V_{DD}	V
		pin SDR	GND	V_{DD}	V
		other pins	-0.3	$V_{DD} + 0.3$	V
Р	power dissipation	derating factor 41.6 mW/K			
		T _{amb} = 25 °C	-	5.2	W
		T _{amb} = 75 °C	-	3.12	W
		T _{amb} = 85 °C	-	2.7	W
T _{amb}	ambient temperature	operating in free air	-40	+85	°C
Tj	junction temperature	operating	-40	+150	°C
T _{stg}	storage temperature		-65	+85	°C
V _{esd}	electrostatic discharge	human body model	±2000	-	V
	voltage	machine model	±200	-	V

^[1] V_{DD} is the supply voltage on pins PVDD and pin AVDD.GND is the voltage ground on pins PGND and pin AGND.

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8. Static characteristics

Table 4. Static characteristics

 $T_{amb} = 25 \,^{\circ}C$; unless otherwise specified [1].

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage	operating	2.5	-	5.5	V
I _{DD}	supply current	$V_{DD} = 2.5 \text{ V}$; no load	-	4	6	mΑ
		V _{DD} = 3.6 V; no load	-	5	7.5	mΑ
		V _{DD} = 5.5 V; no load	-	6	9	mΑ
$I_{DD(sd)}$	shutdown mode supply current	no input signal; V _{SDR} = V _{SDL} = GND	-	10	1000	nA
PSRR	power supply rejection ratio	$V_{DD} = 2.5 \text{ V to } 5.5 \text{ V}$	-	-75	- 55	dB
$V_{i(cm)}$	common-mode input voltage		0.5	-	$V_{DD}-0.8$	V
CMRR	common mode rejection ratio	inputs are shorted together; $V_{DD} = 2.5 \text{ V}$ to 5.5 V	-	-69	– 50	dB
V_{IH}	HIGH-level input voltage	$V_{DD} = 2.5 \text{ V to } 5.5 \text{ V};$ pins \overline{SDL} , \overline{SDR} , G0, G1	1.3	-	V_{DD}	V
V_{IL}	LOW-level input voltage	$V_{DD} = 2.5 \text{ V to } 5.5 \text{ V};$ pins \overline{SDL} , \overline{SDR} , G0, G1	0	-	0.35	V
I _{IH}	HIGH-level input current	$V_{DD} = 5.5 \text{ V}; V_{I} = V_{DD}$	-	-	50	μΑ
I _{IL}	LOW-level input current	$V_{DD} = 5.5 \text{ V}; V_{I} = 0 \text{ V}$	-	-	5	μΑ
f_{sw}	switching frequency	$V_{DD} = 2.5 \text{ V to } 5.5 \text{ V}$	250	300	350	kHz
$G_{v(cl)}$	closed-loop voltage gain	$V_{G0} = V_{G1} = 0.35 \text{ V}$	5.5	6	6.5	dB
		$V_{G0} = V_{DD}; V_{G1} = 0.35 V$	11.5	12	12.5	dB
		$V_{G0} = 0.35 \text{ V}; V_{G1} = V_{DD}$	17.5	18	18.5	dB
		$V_{G0} = V_{G1} = V_{DD}$	23.5	24	24.5	dB
Pins OUT	LP, OUTLN, OUTRP and OUTRN					
R_{DSon}	drain-source on-state resistance	$V_{DD} = 2.5 \text{ V}$	-	700	-	$m\Omega$
		$V_{DD} = 3.6 \text{ V}$	-	570	-	$m\Omega$
		V _{DD} = 5.5 V	-	500	-	$m\Omega$
V _{O(offset)}	output offset voltage	measured differentially; inputs AC grounded; $G_{V(cl)} = 6$ dB; $V_{DD} = 2.5$ V to 5.5 V	-	5	10	mV
Z _{o(sd)}	shutdown mode output impedance	$V_{SDR} = V_{SDL} = 0.35 \text{ V}$	-	2	-	kΩ

^[1] V_{DD} is the supply voltage on pins PVDD and pin AVDD.GND is the ground supply voltage on pins PGND and pin AGND.

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9. Dynamic characteristics

Table 5. Dynamic characteristics

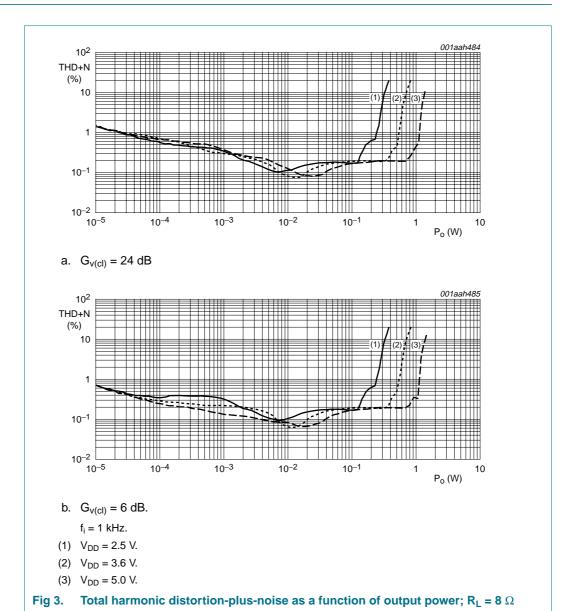
 $T_{amb} = 25 \,^{\circ}C$; $R_L = 8 \,\Omega$; unless otherwise specified^[1].

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Po	output power	per channel; f = 1 kHz; THD+N = 10 %				
		$R_L = 8 \Omega$; $V_{DD} = 3.6 V$	-	0.72	-	W
		$R_L = 8 \Omega; V_{DD} = 5.0 V$	-	1.4	-	W
		$R_L = 4 \Omega$; $V_{DD} = 5.0 V$	-	2.1	-	W
THD+N	total harmonic	$V_{DD} = 5.0 \text{ V}; G_{V(cl)} = 6 \text{ dB}; f = 1 \text{ kHz}$				
	distortion-plus-noise	$P_0 = 0.5 \text{ W}$	-	0.11	-	%
		$P_0 = 1.0 \text{ W}$	-	0.14	-	%
SVRR supply	supply voltage ripple	$G_{v(cl)} = 6 dB$; $f = 217 Hz$				
	rejection	V _{DD} = 3.6 V	-	-73	-	dB
		V _{DD} = 5.0 V	-	-77	-	dB
CMRR	common mode rejection ratio	$V_{DD} = 5.0 \text{ V}; G_{v(cl)} = 6 \text{ dB}; f = 217 \text{ Hz}$	-	-69	-	dB
Z _i	input impedance	$G_{v(cl)} = 6 dB$	-	28.1	-	$k\Omega$
		$G_{v(cl)} = 12 dB$	-	17.3	-	$k\Omega$
		G _{v(cl)} = 18 dB	-	9.8	-	kΩ
		$G_{v(cl)} = 24 dB$	-	5.2	-	$k\Omega$
t _{d(sd-startup)}	delay time from shutdown to start-up	$V_{DD} = 3.6 \text{ V}$	-	3.5	-	ms
$V_{n(o)}$	output noise voltage	V_{DD} = 3.6 V; f = 20 Hz to 20 kHz; inputs are AC grounded				
		no weighting	-	35	-	μV
		A weighting	-	27	-	μV

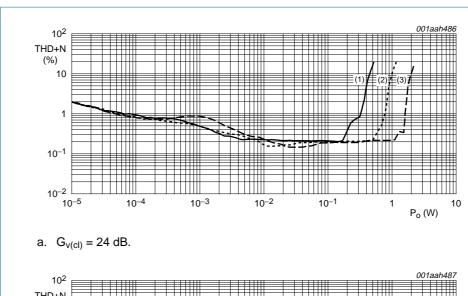
^[1] V_{DD} is the supply voltage on pins PVDD and pin AVDD.

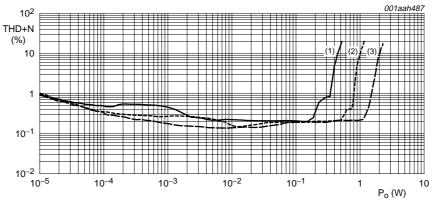
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10. Typical performance curves



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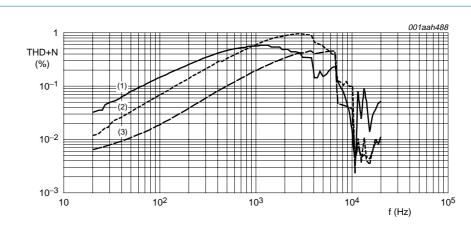
b. $G_{v(cl)} = 6 dB$.

 $f_i = 1 \text{ kHz}.$

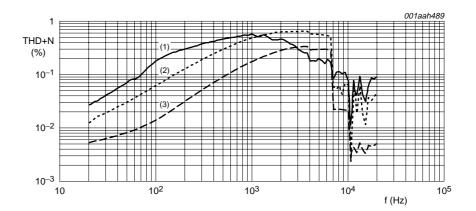
- (1) $V_{DD} = 2.5 \text{ V}.$
- (2) $V_{DD} = 3.6 \text{ V}.$
- (3) $V_{DD} = 5.0 \text{ V}.$

Fig 4. Total harmonic distortion-plus-noise as a function of output power; $R_L = 4 \Omega$

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- (1) $P_0 = 350 \text{ mW}$; $V_i = 590 \text{ mV}$ (RMS).
- (2) $P_0 = 240 \text{ mW}$; $V_i = 490 \text{ mV}$ (RMS).
- (3) $P_0 = 120 \text{ mW}$; $V_i = 346 \text{ mV}$ (RMS).
- a. $R_L = 4 \Omega$

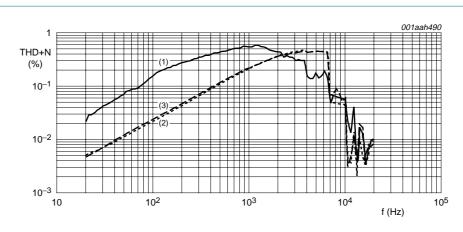


- (1) $P_0 = 260 \text{ mW}$; $V_i = 721.1 \text{ mV (RMS)}$.
- (2) $P_0 = 180 \text{ mW}$; $V_i = 600 \text{ mV}$ (RMS).
- (3) $P_0 = 90 \text{ mW}$; $V_i = 424.3 \text{ mV}$ (RMS).
- b. $R_L = 8 \Omega$

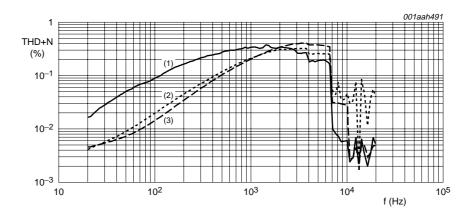
 $G_{v(cl)} = 6 \text{ dB}.$

Fig 5. Total harmonic distortion-plus-noise as a function of frequency; $V_{DD} = 2.5 \text{ V}$

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- (1) $P_0 = 825 \text{ mW}$; $V_i = 908.3 \text{ mV}$ (RMS).
- (2) $P_0 = 550 \text{ mW}$; $V_i = 741.6 \text{ mV (RMS)}$.
- (3) $P_o = 275 \text{ mW}$; $V_i = 524.4 \text{ mV}$ (RMS).
- a. $R_L = 4 \Omega$

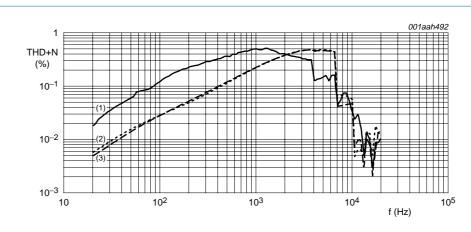


- (1) $P_o = 560 \text{ mW}$; $V_i = 1.058 \text{ V (RMS)}$.
- (2) $P_0 = 375 \text{ mW}$; $V_i = 866 \text{ mV}$ (RMS).
- (3) $P_0 = 190 \text{ mW}$; $V_i = 616.4 \text{ mV}$ (RMS).
- b. $R_L = 8 \Omega$

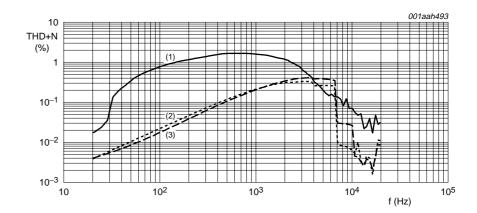
 $G_{v(cl)} = 6 \text{ dB}.$

Fig 6. Total harmonic distortion-plus-noise as a function of frequency; $V_{DD} = 3.6 \text{ V}$

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- (1) $P_0 = 1.65 \text{ W}$; $V_i = 1.285 \text{ V (RMS)}$.
- (2) $P_0 = 1.1 \text{ W}$; $V_i = 1.05 \text{ V (RMS)}$.
- (3) $P_o = 550 \text{ mW}$; $V_i = 741.6 \text{ mV}$ (RMS).
- a. $R_L = 4 \Omega$

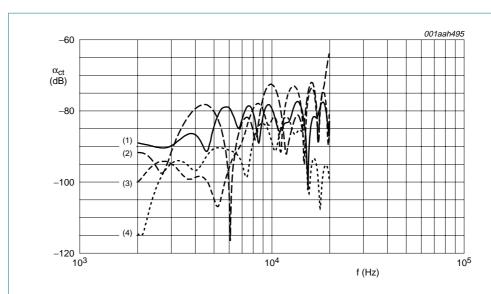


- (1) $P_0 = 1.16 \text{ W}$; $V_i = 1.523 \text{ V (RMS)}$.
- (2) $P_0 = 775 \text{ mW}$; $V_i = 1.245 \text{ V (RMS)}$.
- (3) $P_0 = 380 \text{ mW}$; $V_i = 871.8 \text{ mV}$ (RMS).
- b. $R_1 = 8 \Omega$

 $G_{v(cl)} = 6 \text{ dB}.$

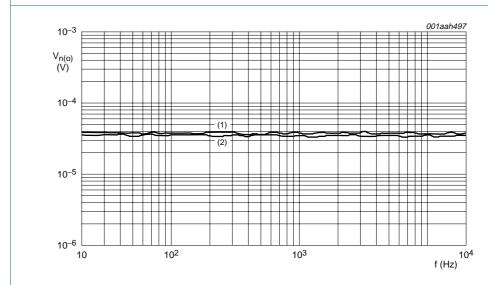
Fig 7. Total harmonic distortion-plus-noise as a function of frequency; $V_{DD} = 5.0 \text{ V}$

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- (1) $V_{DD} = 3.6 \text{ V}$; L channel to R channel.
- (2) $V_{DD} = 3.6 \text{ V}$; R channel to L channel.
- (3) $V_{DD} = 5.0 \text{ V}$; L channel to R channel.
- (4) $V_{DD} = 5.0 \text{ V}$; R channel to L channel.

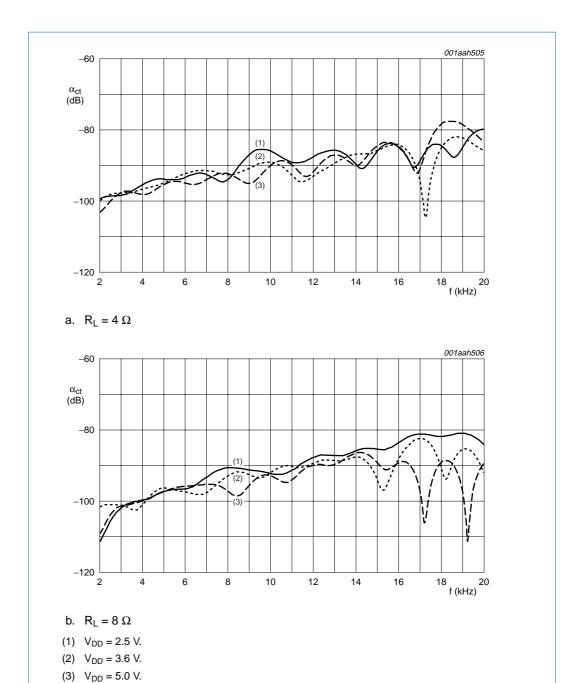
Fig 8. Crosstalk (stepped all-to-one) as a function of frequency



- (1) Left channel.
- (2) Right channel.

Fig 9. Noise output voltage (RMS value) as a function of frequency

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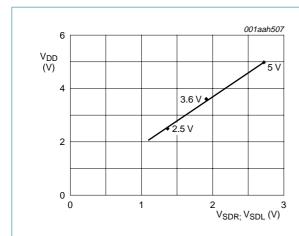
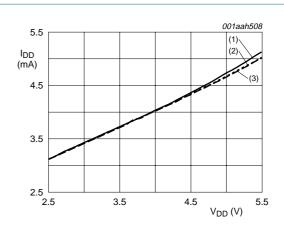
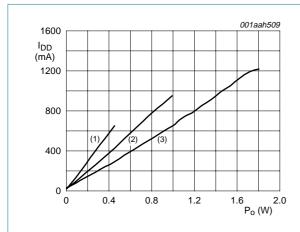


Fig 11. Supply voltage as a function of shutdown voltage



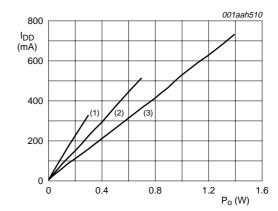
- (1) left channel; $R_L = 8 \Omega$.
- (2) right channel; $R_L = 4 \Omega$.
- (3) right channel; $R_L = 8 \Omega$.

Fig 12. Supply current as a function of supply voltage



- a. $R_L = 4 \Omega$
- (1) $V_{DD} = 2.5 \text{ V}.$
- (2) $V_{DD} = 3.6 \text{ V}.$
- (3) $V_{DD} = 5.0 \text{ V}.$

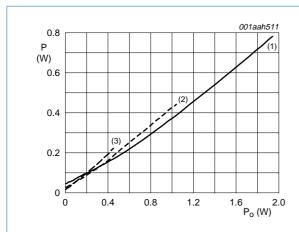
Fig 13. Supply current as a function of output power

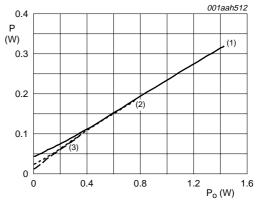


b. $R_L = 8 \Omega$

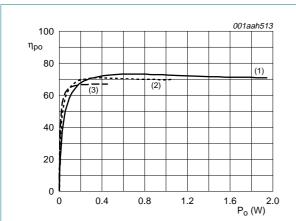
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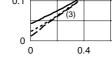
- a. $R_L = 4 \Omega$
- (1) $V_{DD} = 5.0 \text{ V}.$
- (2) $V_{DD} = 3.6 \text{ V}.$
- (3) $V_{DD} = 2.5 \text{ V}.$
- Fig 14. Power dissipation as a function of output power



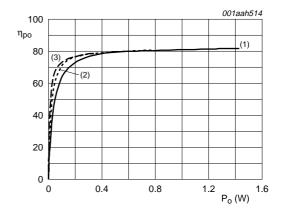


- (1) $V_{DD} = 5.0 \text{ V}.$
- (2) $V_{DD} = 3.6 \text{ V}.$
- (3) $V_{DD} = 2.5 \text{ V}.$

Fig 15. Output power efficiency as a function of output power



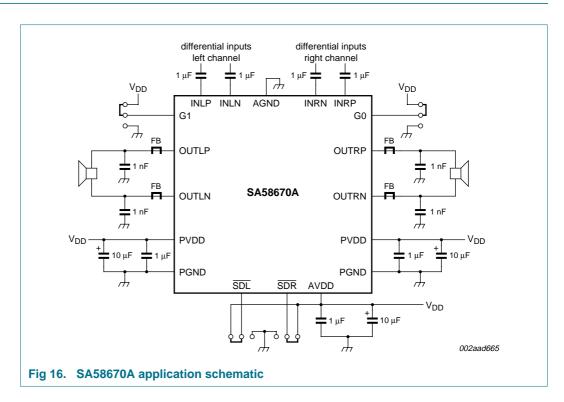
b. $R_L = 8 \Omega$



b. $R_L = 8 \Omega$

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11. Application information



11.1 Power supply decoupling considerations

The SA58670A is a stereo class-D audio amplifier that requires proper supply voltage decoupling to ensure the rated performance for THD+N and power efficiency. To decouple high frequency transients, supply voltage spikes and digital noise on the supply voltage bus line, a low Equivalent Series Resistance (ESR) capacitor of typically 1 μF is placed as close as possible to the PVDD pins of the SA58670A. It is important to place the decoupling capacitor at the supply voltage pins of the SA58670A because any resistance or inductance in the PCB trace between the SA58670A and the capacitor can cause a loss in efficiency. Additional decoupling using a larger capacitor, 4.7 μF or greater, may be done on the supply voltage connection on the PCB to filter low frequency signals. Usually this is not required due to high PSRR of the SA58670A.

11.2 Input capacitor selection

The SA58670A does not require input coupling capacitors when used with a differential audio source that is biased from 0.5 V to $V_{DD}-0.8$ V. In other words, the input signal must be biased within the common-mode input voltage ($V_{i(cm)}$) range. If high-pass filtering is required or if it is driven using a single-ended source, input coupling capacitors are required.

The 3 dB cut-off frequency created by the input coupling capacitor and the input resistors (see Table 6) is calculated by Equation 1:

$$f_{-3dB} = \frac{1}{2\pi \times R_i \times C_i} \tag{1}$$

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Table 6. Gai	in se	lection
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G1	G0	Gain (V/V)	Gain (dB)	Input impedance (kΩ)
LOW	LOW	2	6	28.1
LOW	HIGH	4	12	17.3
HIGH	LOW	8	18	9.8
HIGH	HIGH	16	24	5.2

Since the value of the input decoupling capacitor and the input resistance determined by the gain setting affects the low frequency performance of the audio amplifier, it is important to consider this during the system design. Small speakers in wireless and cellular phones usually do not respond well to low frequency signals, so the 3 dB cut-off frequency may be increased to block the low frequency signals to the speakers. Not using input coupling capacitors may increase the output offset voltage.

Equation 2 is solved for Ci:

$$C_i = \frac{1}{2\pi \times R_i \times f_{3dR}} \tag{2}$$

11.3 PCB layout considerations

Component location is very important for performance of the SA58670A. Place all external components very close to the SA58670A. Placing decoupling capacitors directly at the power supply voltage pins increases efficiency because the resistance and inductance in the trace between the SA58670A power supply voltage pins and the decoupling capacitor causes a loss in power efficiency.

The trace width and routing are also very important for power output and noise considerations.

For high current pins (PVDD, PGND and audio output), the trace widths should be maximized to ensure proper performance and output power. Use at least 500 μ m wide traces.

For the input pins (INRP, INRN, INLP and INLN), the traces must be symmetrical and run side-by-side to maximize common-mode cancellation.

11.4 Filter-free operation and ferrite bead filters

A ferrite bead low-pass filter can be used to reduce radio frequency emissions in applications that have circuits sensitive to frequencies greater than 1 MHz. A ferrite bead low-pass filter functions well for amplifiers that must pass FCC unintentional radiation requirements for frequencies greater than 30 MHz. Choose a bead with high-impedance at high frequencies and very low-impedance at low frequencies. In order to prevent distortion of the output signal, select a ferrite bead with adequate current rating.

For applications in which there are circuits that are EMI sensitive to low frequencies (< 1 MHz) and there are long leads from amplifier to speaker, it is necessary to use an LC output filter.

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11.5 Efficiency and thermal considerations

The maximum ambient operating temperature depends on the heat transferring ability of the heat spreader on the PCB layout. In <u>Table 3 "Limiting values"</u>, the power derating factor is given as 41.6 mW/K. The device thermal resistance, $R_{th(j-a)}$ is the reciprocal of the power derating factor. Convert the power derating factor to $R_{th(j-a)}$ by Equation 3:

$$R_{th(j-a)} = \frac{1}{derating\ factor} = \frac{1}{0.0416} = 24\ K/W \tag{3}$$

For a maximum allowable junction temperature $T_j = 150~^{\circ}C$ and $R_{th(j-a)} = 24~\text{K/W}$ and a maximum device dissipation of 1.5 W (750 mW per channel) and for 2.1 W per channel output power, 4 Ω load, 5 V supply, the maximum ambient temperature is calculated using Equation 4:

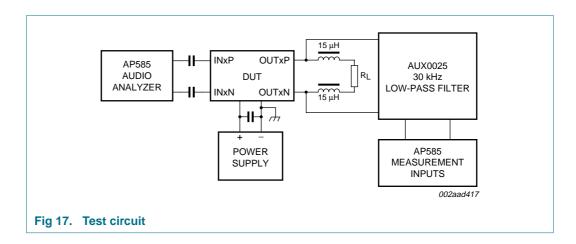
$$T_{amb(max)} = T_{j(max)} - (R_{th(j-a)} \times P_{max}) = 150 - (24 \times 1.5) = 114 \, ^{\circ}C$$
 (4)

The maximum ambient temperature is 114 °C at maximum power dissipation for 5 V supply and 4 Ω load. If the junction temperature of the SA58670A rises above 150 °C, the thermal protection circuitry turns the SA58670A off; this prevents damage to IC. Using speakers greater than 4 Ω further enhances thermal performance and battery lifetime by reducing the output load current and increasing amplifier efficiency.

11.6 Additional thermal information

The SA58670A HVQFN20 package incorporates an exposed DAP that is designed to solder the mount directly to the PCB heat spreader. By the use of thermal vias, the DAP may be soldered directly to a ground plane or special heat sinking layer designed into the PCB. The thickness and area of the heat spreader may be maximized to optimize heat transfer and achieve lowest package thermal resistance.

12. Test information



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13. Package outline

HVQFN20: plastic thermal enhanced very thin quad flat package; no leads; 20 terminals; body $4 \times 4 \times 0.85 \text{ mm}$

SOT917-1

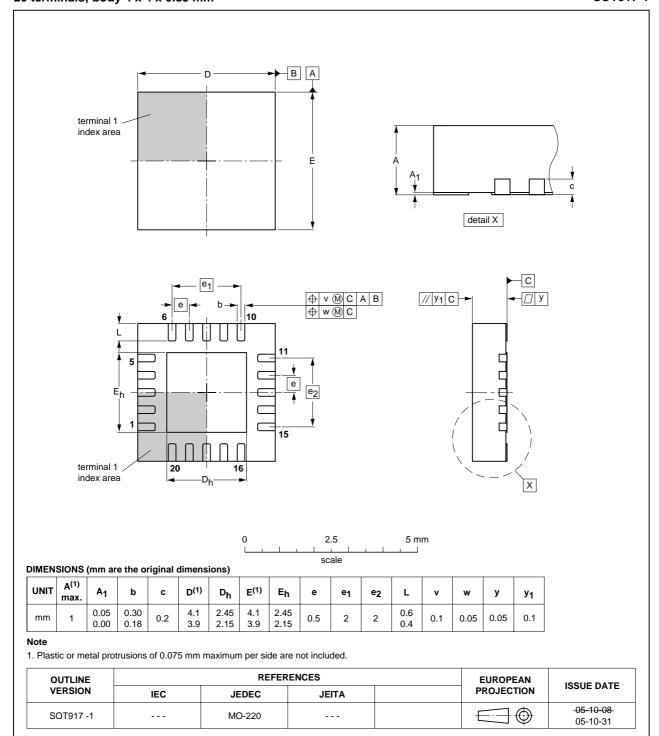


Fig 18. Package outline SOT917-1 (HVQFN20)

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14. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

14.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

14.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- · Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

14.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

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14.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 19</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 7 and 8

Table 7. SnPb eutectic process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C	3)	
	Volume (mm³)		
	< 350	≥ 350	
< 2.5	235	220	
≥ 2.5	220	220	

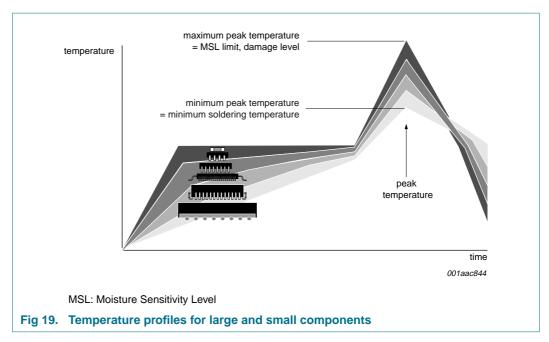
Table 8. Lead-free process (from J-STD-020C)

Package thickness (mm)	perature (°C)			
	Volume (mm ³)			
	< 350	350 to 2000	> 2000	
< 1.6	260	260	260	
1.6 to 2.5	260	250	245	
> 2.5	250	245	245	

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 19.

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For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

15. Abbreviations

Table 9. Abbreviations

Acronym	Description
DAP	Die Attach Paddle
DVD	Digital Video Disc
EMI	ElectroMagnetic Interference
ESR	Equivalent Series Resistance
LC	inductor-capacitor filter
PC	Personal Computer
PCB	Printed-Circuit Board
PDA	Personal Digital Assistant
PWM	Pulse Width Modulator
USB	Universal Serial Bus

16. Revision history

Table 10. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
SA58670A_2	20081023	Product data sheet	-	SA58670A_1
Modifications:		tic characteristics": D(sd) specification		
SA58670A_1	20080220	Product data sheet	-	-

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17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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