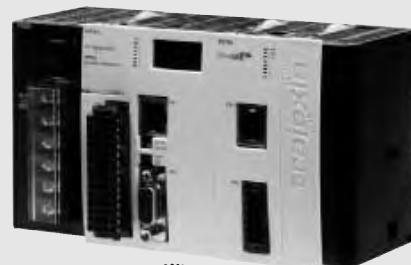


Trajexia stand-alone

Trajexia motion controller

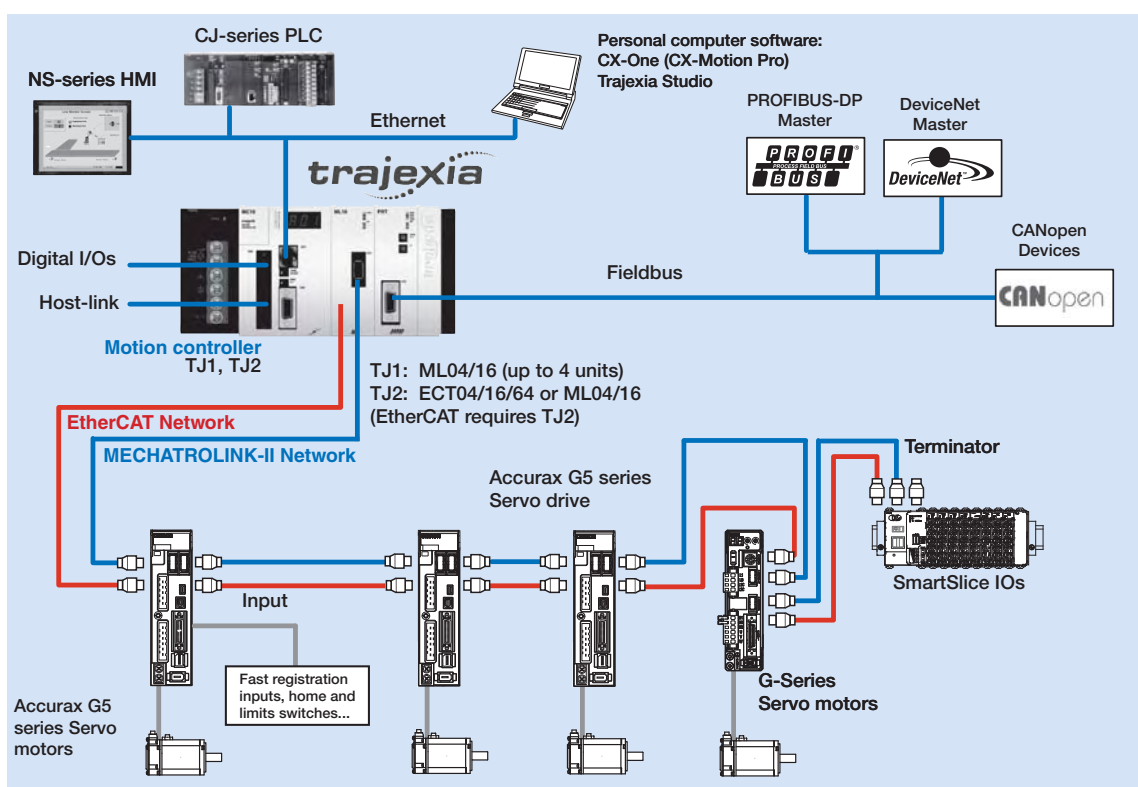
Stand-alone advanced motion controller over EtherCAT

- Perfect motion control of up to 64 axes. Scalability with EtherCAT masters for 4, 16 and 64 axes.
- Supports position, speed and torque control
- Multi-tasking controller capable of running up to 22 tasks simultaneously
- Advanced motion control such as linear, circular, helical or spherical interpolation, electronic cams and gearboxes via simple motion commands.
- Control of servos, inverters, vision systems and distributed I/Os over a single EtherCAT network
- Support for EtherNet/IP communications
- Advanced debugging tools including data trace and oscilloscope functions
- Open communication: Serial and EtherNet/IP built-in, PROFIBUS-DP, DeviceNet and CANopen



trajexia

System configuration



Specifications

Trajexia general specifications

Item	Details
Model	TJ□
Ambient operating temperature	0 to 55°C
Ambient operating humidity	10 to 90%RH
Ambient storage temperature	-20 to 70°C
Ambient storage humidity	90% max. (with no condensation)
Atmosphere	No corrosive gases
Vibration resistance	10 to 57 Hz: (0.075 mm amplitude) 57 to 100 Hz Acceleration: 9,8 m/s ² , in X, Y and Z directions for 80 minutes.
Shock resistance	143 m/s ² , 3 times each X, Y and Z directions.
Insulation resistance	20 MOhm
Dielectric strength	500 Volt
Protective structure	IP20
International standards	CE, EN 61131-2, cULus, Lloyds, RoHS compliant

Trajexia motion control units

Item	Details
Model	TJ2-MC64 TJ1-MC16 TJ1-MC04
Number of axes	64 16 4 (+1 using TJ1-FL02 unit)
Number of inverters and I/O modules	Up to 64 (Inverters in position, speed or torque mode) 8 maximum (Inverters in position, speed or torque mode) 8 maximum (Max. 4 Inverters in position mode)
Motion bus	Number of EtherCAT master units ^{*1} 1 EtherCAT master is allowed per controller (see below TJ2-ECT64/ECT16/ECT04 for detailed info) not supported
	Number of ML2 master units Up to 4 MECHATROLINK-II master units per controller (see below TJ1-ML16/ML04 for detailed info)
Cycle time	Selectable 0.25 ms, 0.5 ms, 1 ms or 2 ms Selectable 0.5 ms, 1 ms or 2 ms
Programming language	BASIC-like motion language
Multi-tasking	Up to 22 tasks running simultaneously Up to 14 tasks running simultaneously
Built-in digital I/O	16 inputs and 8 outputs, for general purpose
Measurement units	User definable
Available memory for user programs	8 MB 500 KB
Data storage capacity	Up to 32 MB Flash data storage Up to 2 MB Flash data storage
Saving program data, motion controller	Flash-ROM SRAM with battery backup and Flash-ROM
Saving program data, personal computer	Via CX-Motion Pro/Trajexia Studio software
Communication ports	1 Ethernet port and 2 serial ports
Firmware update	Via CX-Motion Pro/Trajexia Studio software
Ethernet port	Electrical characteristics Conform to IEEE 802.3 (100BaseT)
	Connector RJ45 Ethernet connector
	Transmission protocol Modbus TCP slave
	TELNET
	FINS server and client
Serial port	EtherNet/IP slave not supported
	Electrical characteristics Conform 1 port to RS232C and 1 port to RS485/RS422A (selectable by switch)
	Connector SUB-D9 connector (Counterpart included in the package)
	Synchronization Start-stop synchronization (asynchronous)
	Baud rate 1200 / 2400 / 4800 / 9600 / 19200 / 38400 bps
	Transmission format Databit length (7 or 8 bit)
	Stop bit (1 or 2 bit)
	Parity bit (Even/Odd/None)
	Transmission mode Point-to-multipoint (1:N)
	Transmission protocol RS-232C (1:1) Host Link master protocol, Host Link slave protocol, ASCII general-purpose, Modbus RTU slave
	RS-485 (1:N) RS-422A (1:N) Host Link master protocol, Host Link slave protocol, ASCII general-purpose, Modbus RTU slave
	Galvanic isolation RS422A port
	Communication buffers 254 bytes
	Flow control None
	Terminator Yes, selectable by switch
	Cable length 15 m for RS232 and 500 meter for RS422/485

*1. The EtherCAT master unit cannot be used in combination with a MECHATROLINK master unit when using TJ2-MC64 motion controller unit with firmware 2.0132.

Trajexia EtherCAT master units

Item	Specifications		
Model	TJ2-ECT64	TJ2-ECT16	TJ2-ECT04
Controlled devices with EtherCAT interface	Accurax G5 servo drive, MX2 inverter and SmartSlice IOs		
Electrical characteristics	Conform to Ethernet (IEEE 802.3), 100Base Tx		
Communications port	1 EtherCAT communication connector (to connect the EtherCAT twisted-pair cable)		
Transmission speed	100 Mbps		
Topology	Daisy chain, line or drop line		
Communications media	STP Category 5		
Communication cycle	0.5 ms, 1 ms or 2 ms		
Stations slave types ^{*1}	Servo drives (axis)		
	Frequency inverters (axis)		
	I/O modules (devices)		
Number of axes per master / Cycle time ^{*2}	Max.64 axes/2 ms	Max. 16 axes/2 ms	Max. 4 axes/2 ms
	Max.32 axes/1 ms	Max. 16 axes/1 ms	Max. 4 axes/1 ms
	Max. 16 axes/0.5 ms	Max. 16 axes/0.5 ms	Max. 4 axes/0.5 ms
Transmission distance	Up to 100 meters between nodes		
Auxiliary I/Os	8 fast registration inputs		

*1. The TJ2-MC64 CPU supports a total of 1024 digital I/O points and 36 analogue I/O points.

*2. The number of axes per master/ cycle time is currently (TJ2-MC64 motion controller with firmware 2.01.32) limited to:

Max. 32 axes @ 2ms

Max. 16 axes @ 1 ms

Max. 8 axes @ 0.5 ms

Trajexia MECHATROLINK-II master units

Item	Specifications	
Model	TJ1-ML16	TJ1-ML04
Controlled devices with MECHATROLINK-II interface	Accurax G5, G-Series, MX2 inverter and SmartSlice IOs	
Electrical characteristics	Conforms to MECHATROLINK standard	
Communication ports	1 MECHATROLINK-II master	
Transmission speed	10 Mbps	
Communication cycle	0.5 ms, 1 ms or 2 ms	
Stations slave types	Axes or servo drives	
	Frequency inverters	
	I/O modules	
Number of stations per master / Cycle time	Max.16 Stations/2 ms	Max. 4 Stations/2 ms
	Max. 8 Stations/1 ms	Max. 4 Stations/1 ms
Transmission distance	Max. 50 meters without using repeater	

Trajexia PROFIBUS slave unit

Items	Specifications
Model	TJ1-PRT
PROFIBUS standard	Conforms to PROFIBUS-DP standard EN50170 (DP-V0)
Communication ports	1 PROFIBUS-DP slave
Transmission speed	9.6, 19.2, 45.45, 93.75, 187.5, 500, 1500, 3000, 6000 and 12000 kbps
Node numbers	0 to 99
I/O size	0 to 122 words (16 bit), configurable, for both directions
Galvanic isolation	Yes

Trajexia DeviceNet slave unit

Items	Specifications
Model	TJ1-DRT
DeviceNet standard	Conforms to DeviceNet standard of CIP edition 1
Communication ports	1 DeviceNet slave
Transmission speed	125, 250 and 500 Kbps, auto-detect
Node numbers	0 to 63
I/O size	0 to 32 words (16 bit), configurable, for both directions
Galvanic isolation	Yes

Trajexia CANopen unit

Items	Specifications
Model	TJ1-CORT
Electrical Characteristics	Conforms to CAN 2.0 B
Communication ports	1 CANopen
Transmission speed	20, 50, 125 and 500 Kbps
Implemented CiA Standards	DS301, DS302
PDO Support	8 TPDO and 8 RPDO
PDO Mapping	Each PDO can be mapped into TJ1-MC16/04 VR, table, analogue and digital IO. BASIC commands assign mapping and start address ^{*1}
CANopen slave configuration	Any SDO message can be sent using BASIC during start-up and operation
CANopen network states	CANopen network can be set to pre-operational and operational using BASIC
CANopen slave emergencies	Available using BASIC command
Galvanic isolation	Yes

*1. The TJ1-MC16/04 CPUs support a total of 256 digital I/O points and 36 analogue I/O points. The TJ2-MC64 CPU supports a total of 1024 digital I/O points and 36 analogue I/O points.

Trajexia flexible axis unit

Items		Specifications
Model		TJ1-FL02
Number of axes		2. Every axis has 1 analog output, 1 encoder in/out -software configurable - and several digital I/O
Control methods (independent per axis)		±10 V analogue output + encoder input (closed loop) Line driver AB output Stepper pulse output in closed loop or pulse train output in open loop
Encoder	Encoder protocols	Abs SSI 200 kHz, Abs EnDat 1 MHz, Abs Tamagawa and Incremental Line driver AB
	Encoder Input maximum frequency	6 MHz
	Encoder/pulse output max. frequency	2 MHz
Auxiliary I/Os		2 fast registration inputs, 2 definable inputs, 2 enable output, 4 position switch outputs or axes reset
Galvanic isolation		Yes

SmartSlice EtherCAT interface unit

Item	Specifications
Model	GRT1-ECT
Electrical characteristics	Conform to Ethernet (IEEE 802.3), 100Base-TX
Communication cycle	0.25 ms min.
Power supply	24 VDC
Number of connectable Slices	Up to 64 slices with a maximum amount of 128 bytes ^{*1}
IO mapping	Automatic analogue and digital IO mapping into TJ2-MC64 CPU
Slice unit configuration	Not supported
Supported slice units	See ordering information section

*1. The TJ2-MC64 CPU supports a total of 1024 digital I/O points and 36 analogue I/O points.

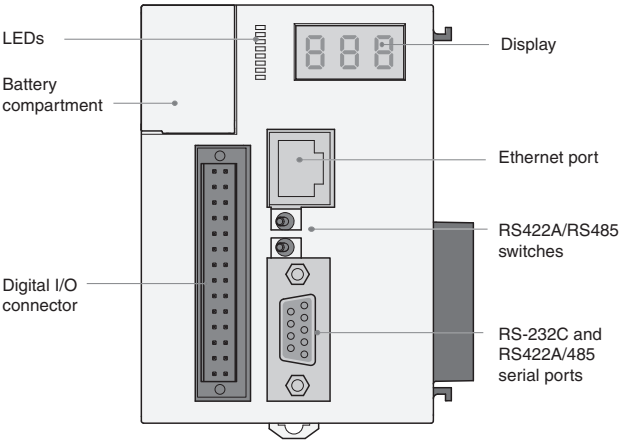
SmartSlice MECHATROLINK-II interface unit

Item	Specifications
Model	GRT1-ML2
Electrical characteristics	Conform to MECHATROLINK standard
Communication cycle	0.5, 1 or 2 ms
Power supply	24 VDC
Number of connectable Slices	Up to 64 slices with a maximum amount of 128 bytes ^{*1}
IO mapping	Automatic analogue and digital IO mapping into TJ1-MC16/04 and TJ2-MC64 CPUs
Slice unit configuration	Not supported
Supported slice units	See ordering information section

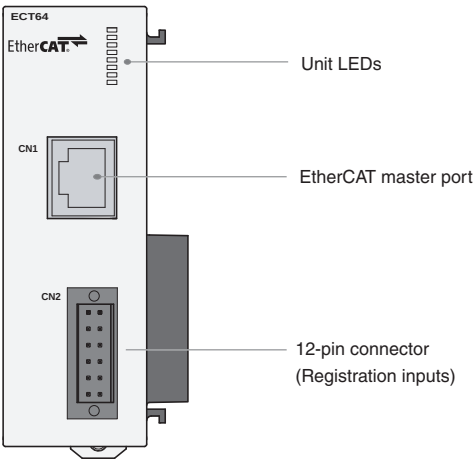
*1. The TJ1-MC16/04 CPUs support a total of 256 digital I/O points and 36 analogue I/O points.
The TJ2-MC64 CPU supports a total of 1024 digital I/O points and 36 analogue I/O points.

Nomenclature

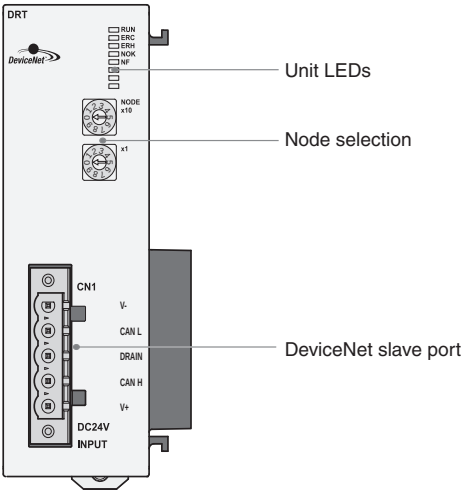
Trajexia motion controller unit - TJ2-MC64, TJ1MC-16/04



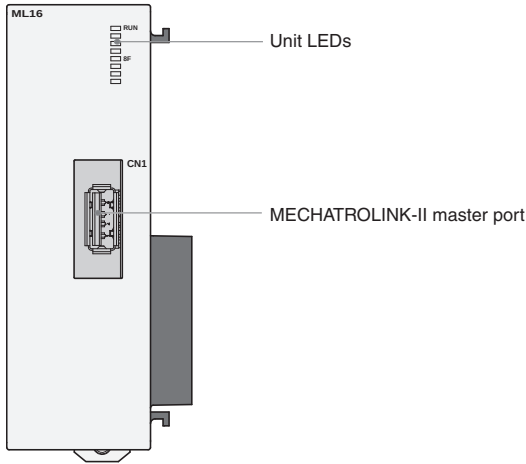
Trajexia EtherCAT master unit - TJ2-ECT04/16/64



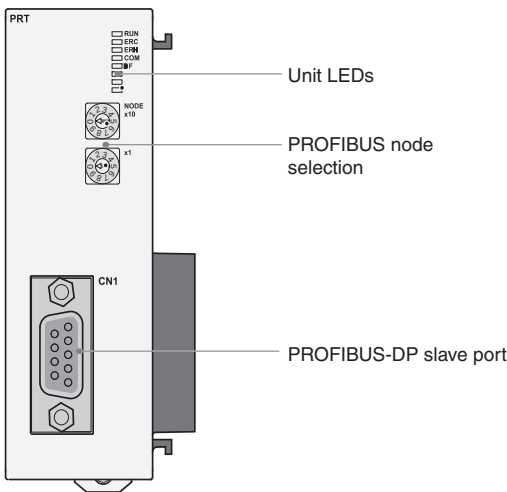
Trajexia DeviceNet slave unit - TJ1-DRT



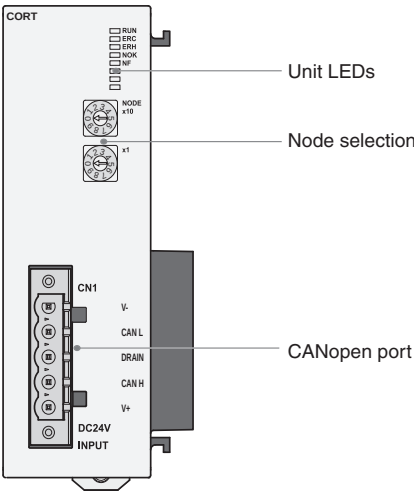
Trajexia MECHATROLINK-II master unit - TJ1-ML16/04



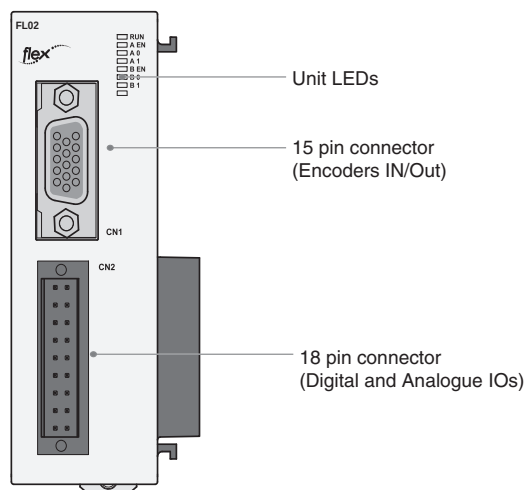
Trajexia PROFIBUS-DP unit - TJ1-PRT



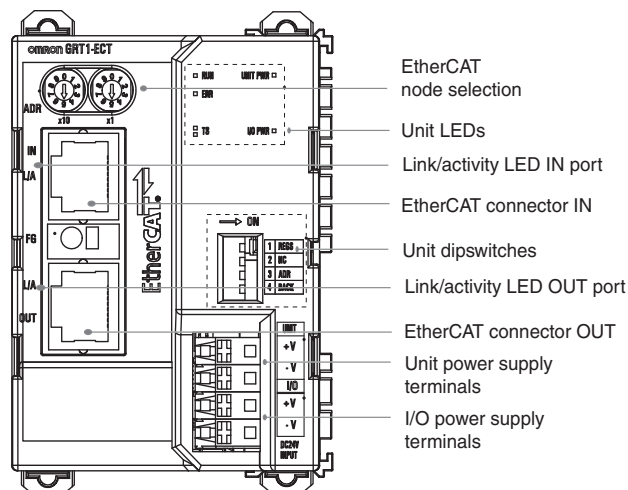
Trajexia CANopen unit - TJ1-CORT



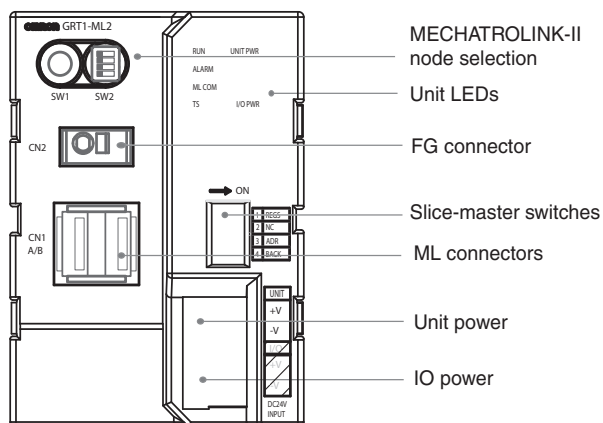
Trajexia Flex axis unit - TJ1-FL02



SmartSlice EtherCAT interface unit - GRT1-ECT

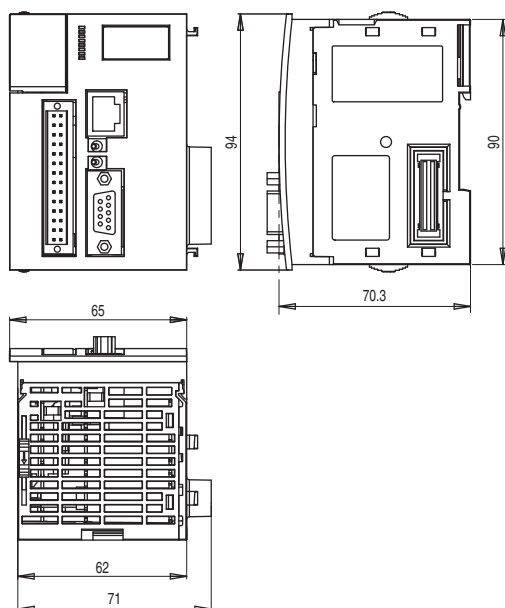


SmartSlice MECHATROLINK-II interf. unit - GRT1-ML2

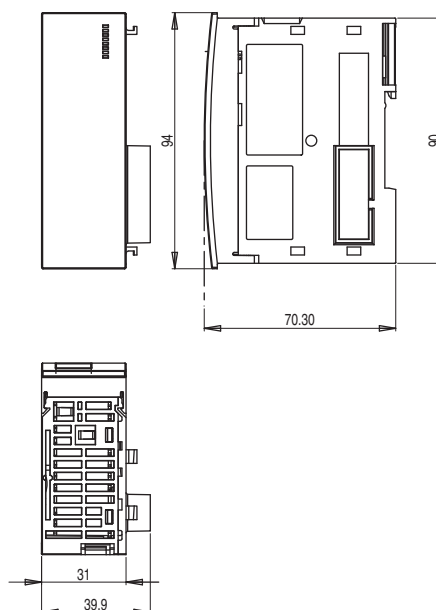


Dimensions

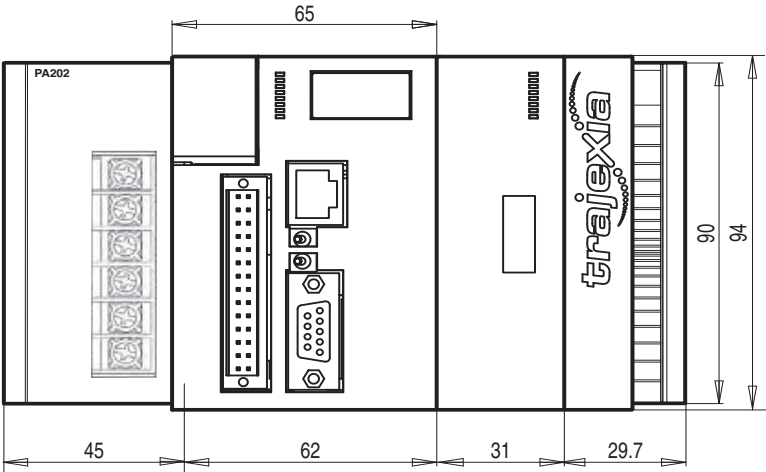
Trajexia motion controller - TJ2-MC64, TJ1-MC16/04



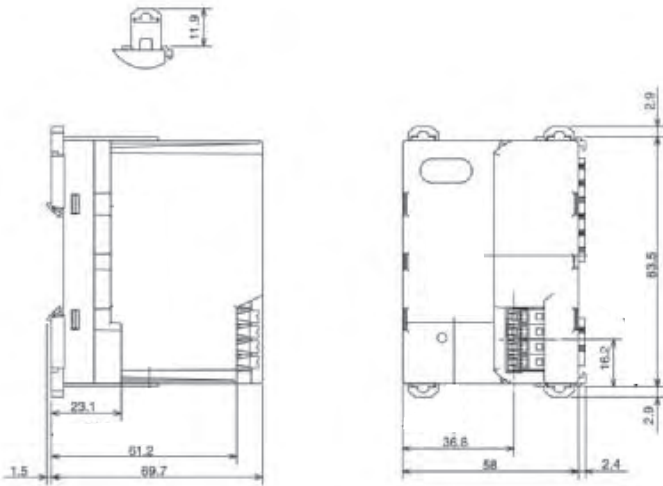
Trajexia units - TJ1-ML16/04, -PRT, -DRT, -CORT, -FL02, TJ2-ECT64/16/04



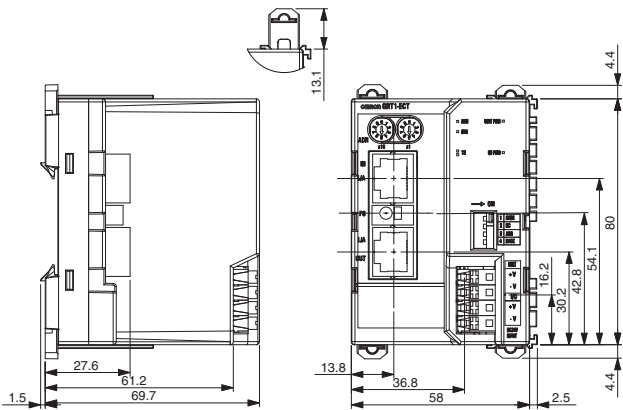
Trajexia system - CJ1W-PA202 + TJ1-MC16 + one module + TJ1-TER



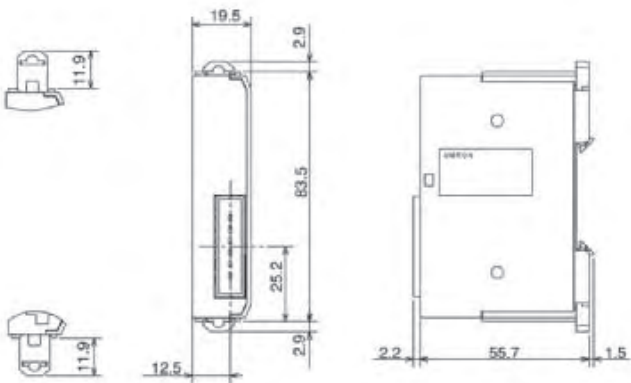
SmartSlice interface unit - GRT1-ML2



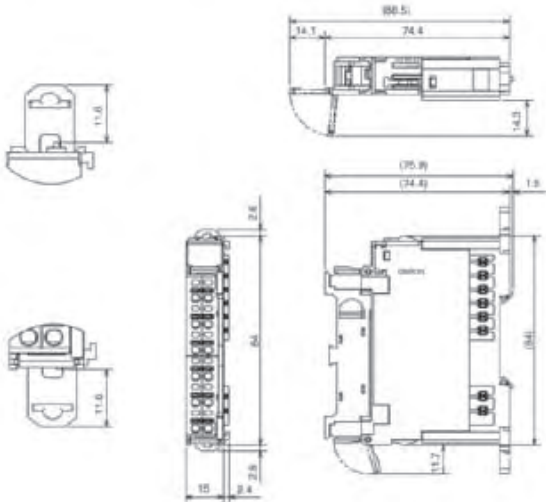
SmartSlice interface unit - GRT1-ECT



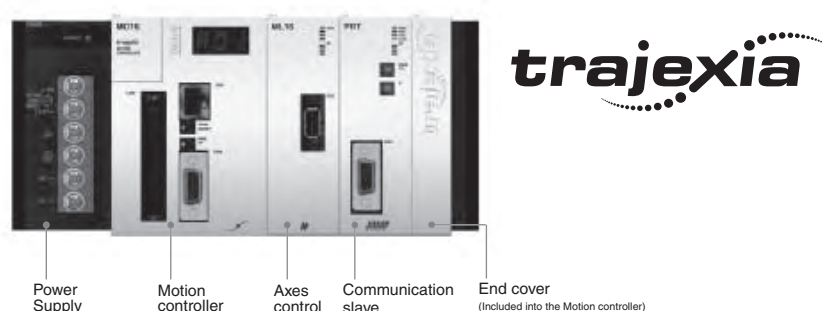
SmartSlice end unit - GRT1-END



SmartSlice I/O units - GRT1-__



Ordering information



Trajexia motion controller

Name	Model
Trajexia motion controller Unit, up to 64 axes. (Trajexia end cover unit TJ1-TER is included)	TJ2-MC64
Trajexia motion controller unit, up to 16 axes. (Trajexia end cover unit TJ1-TER is included)	TJ1-MC16
Trajexia motion controller unit, up to 4 axes. (Trajexia end cover unit TJ1-TER is included)	TJ1-MC04
Power supply for Trajexia system, 100-240 VAC	CJ1W-PA202
Power supply for Trajexia system, 24 VDC	CJ1W-PD022

Trajexia - axes control modules

Name	Model
Trajexia EtherCAT master unit (up to 64 servo drives) ^{*1}	TJ2-ECT64
Trajexia EtherCAT master unit (up to 16 servo drives)	TJ2-ECT16
Trajexia EtherCAT master unit (up to 4 servo drives)	TJ2-ECT04
Trajexia MECHATROLINK-II master unit (up to 16 stations)	TJ1-ML16
Trajexia MECHATROLINK-II master unit (up to 4 stations)	TJ1-ML04
Trajexia flexible axis unit (for 2 stations)	TJ1-FL02

*1. The number of servo drives is currently limited to 32 when using TJ2-MC64 motion controller with firmware 2.0132.

Note: The TJ1-ML04 and TJ1-ML16 supported by the TJ2-MC64 motion controller are V2 (Version 2) and lot number equal or above Lot. No.091019 (YYMMDD).

Trajexia - communication modules

Name	Model
Trajexia DevicNet slave unit	TJ1-DRT
Trajexia PROFIBUS-DP slave unit	TJ1-PRT
Trajexia CANopen unit	TJ1-CORT

EtherCAT - related devices

Servo system & frequency inverters

Name	Model
Accurax G5 servo drive EtherCAT built-in	R88D-KN□□□-ECT
MX2 inverter with EtherCAT option board	Frequency inverter
	EtherCAT option board
	3G3MX2-A□
	3G3AX-MX2-ECT

Note: Refer to servo systems and frequency inverter sections for detailed specs and ordering information

SmartSlice IOs system

Function	Specification	Model
SmartSlice Interface unit	SmartSlice EtherCAT interface unit	GRT1-ECT
End plate, one unit required per bus interface		GRT1-END
4 NPN inputs	24 VDC, 6 mA, 3-wire connection	GRT1-ID4
4 PNP inputs	24 VDC, 6 mA, 3-wire connection	GRT1-ID4-1
8 NPN inputs	24 VDC, 4 mA, 1-wire connection + 4xG	GRT1-ID8
8 PNP inputs	24 VDC, 4 mA, 1-wire connection + 4xV	GRT1-ID8-1
4 AC inputs	110 VAC, 2-wire connection	GRT1-IA4-1
4 AC inputs	230 VAC, 2-wire connection	GRT1-IA4-2
4 NPN outputs	24 VDC, 500 mA, 2-wire connection	GRT1-OD4
4 PNP outputs	24 VDC, 500 mA, 2-wire connection	GRT1-OD4-1
4 PNP outputs with short-circuit protection	24 VDC, 500 mA, 3-wire connection	GRT1-OD4G-1
4 PNP outputs with short-circuit protection	24 VDC, 2 A, 2-wire connection	GRT1-OD4G-3
8 NPN outputs	24 VDC, 500 mA, 1-wire connection + 4xV	GRT1-OD8
8 PNP outputs	24 VDC, 500 mA, 1-wire connection + 4xG	GRT1-OD8-1
8 PNP outputs with short-circuit protection	24 VDC, 500 mA, 1-wire connection + 4xG	GRT1-OD8G-1
2 relay outputs	240 VAC, 2 A, normally-open contacts	GRT1-ROS2
2 analogue inputs, current/voltage	±10 V, 0-10 V, 0-5 V, 1-5 V, 0-20 mA, 4-20 mA	GRT1-AD2
2 analogue outputs, voltage	± 10 V, 0-10 V, 0-5 V, 1-5 V	GRT1-DA2V
2 analogue outputs, current	0-20 mA, 4-20 mA	GRT1-DA2C
2 Pt100 inputs	Pt100, 2-wire or 3-wire connection	GRT1-TS2P
2 Pt1000 inputs	Pt1000, 2-wire or 3-wire connection	GRT1-TS2K
2 Thermocouple inputs	Types B, E, J, K, N, R, S, T, U, W, PL2, with cold junction compensation	GRT1-TS2T

Note: Refer to Automation systems catalogue for detailed specs and accessories information

GX-Series I/O Blocks

Name	Specification	Model
16 NPN inputs	24 VDC, 6 mA, 1-wire connection, expandable	GX-ID1611
16 PNP inputs	24 VDC, 6 mA, 1-wire connection, expandable	GX-ID1621
16 NPN outputs	24 VDC, 500 mA, 1-wire connection, expandable	GX-OD1611
16 PNP outputs	24 VDC, 500 mA, 1-wire connection, expandable	GX-OD1621
8 inputs and 8 outputs, NPN	24 VDC, 6 mA input, 500 mA output, 1-wire connection	GX-MD1611
8 inputs and 8 outputs, PNP	24 VDC, 6 mA input, 500 mA output, 1-wire connection	GX-MD1621
16 NPN inputs	24 VDC, 6 mA, 3-wire connection	GX-ID1612
16 PNP inputs	24 VDC, 6 mA, 3-wire connection	GX-ID1622
16 NPN outputs	24 VDC, 500 mA, 3-wire connection	GX-OD1612
16 PNP outputs	24 VDC, 500 mA, 3-wire connection	GX-OD1622
8 inputs and 8 outputs, NPN	24 VDC, 6 mA input, 500 mA output, 3-wire connection	GX-MD1612
8 inputs and 8 outputs, PNP	24 VDC, 6 mA input, 500 mA output, 3-wire connection	GX-MD1622
16 relay outputs	250 VAC, 2 A, 1-wire connection, expandable	GX-OC1601
4 analogue inputs, current/voltage	±10 V, 0-10 V, 0-5 V, 1-5 V, 4-20 mA	GX-AD0471
2 analogue outputs, current/voltage	±10 V, 0-10 V, 0-5 V, 1-5 V, 4-20 mA	GX-DA0271
2 encoder open collector inputs	500 kHz Open collector input	GX-EC0211
2 encoder line-driver inputs	4 MHz Line driver input	GX-EC0241

Note: The GX-Series I/O blocks are only supported by the T2-MC64 motion controller and with official firmware release above 2.0132.

Vision system

Name	Specification	Model
Vision system with EtherCAT interface	NPN	FZM1-350-ECT
	PNP	FZM1-355-ECT
Smart camera with EtherCAT interface	NPN/ Color camera	FQ-MS120-ECT
	NPN/ Monochrome camera	FQ-MS120-M-ECT
	PNP/ Color camera	FQ-MS125-ECT
	PNP/ Monochrome camera	FQ-MS125-M-ECT

Note: The vision systems are only supported by the T2-MC64 motion controller and with official firmware release above 2.0132.

MECHATROLINK-II - related devices

Servo system & frequency inverters

Name	Specification	Model
Accurax G5 servo drive ML-II built-in		R88D-KN□□□-ML2
G-Series servo drive ML-II built-in		R88D-GN□□□H-ML2
MX2 inverter with MECHATROLINK-II option board	Frequency inverter	3G3MX2-A□
	ML2 option board	3G3AX-MX2-MRT

Note: Refer to servo systems and frequency inverter sections for detailed specs and ordering information

SmartSlice IOs system

Function	Specification	Model
SmartSlice Interface unit	SmartSlice MECHATROLINK-II interface unit	GRT1-ML2 ^{*1}
End plate, one unit required per bus interface		GRT1-END
4 NPN inputs	24 VDC, 6 mA, 3-wire connection	GRT1-ID4
4 PNP inputs	24 VDC, 6 mA, 3-wire connection	GRT1-ID4-1
8 NPN inputs	24 VDC, 4 mA, 1-wire connection + 4xG	GRT1-ID8
8 PNP inputs	24 VDC, 4 mA, 1-wire connection + 4xV	GRT1-ID8-1
4 AC inputs	110 VAC, 2-wire connection	GRT1-IA4-1
4 AC inputs	230 VAC, 2-wire connection	GRT1-IA4-2
4 NPN outputs	24 VDC, 500 mA, 2-wire connection	GRT1-OD4
4 PNP outputs	24 VDC, 500 mA, 2-wire connection	GRT1-OD4-1
4 PNP outputs with short-circuit protection	24 VDC, 500 mA, 3-wire connection	GRT1-OD4G-1
4 PNP outputs with short-circuit protection	24 VDC, 2 A, 2-wire connection	GRT1-OD4G-3
8 NPN outputs	24 VDC, 500 mA, 1-wire connection + 4xV	GRT1-OD8
8 PNP outputs	24 VDC, 500 mA, 1-wire connection + 4xG	GRT1-OD8-1
8 PNP outputs with short-circuit protection	24 VDC, 500 mA, 1-wire connection + 4xG	GRT1-OD8G-1
2 relay outputs	240 VAC, 2 A, normally-open contacts	GRT1-ROS2
2 analogue inputs, current/voltage	±10 V, 0-10 V, 0-5 V, 1-5 V, 0-20 mA, 4-20 mA	GRT1-AD2
2 analogue outputs, voltage	± 10 V, 0-10 V, 0-5 V, 1-5 V	GRT1-DA2V
2 analogue outputs, current	0-20 mA, 4-20 mA	GRT1-DA2C
2 Pt100 inputs	Pt100, 2-wire or 3-wire connection	GRT1-TS2P
2 Pt1000 inputs	Pt1000, 2-wire or 3-wire connection	GRT1-TS2K
2 Thermocouple inputs	Types B, E, J, K, N, R, S, T, U, W, PL2, with cold junction compensation	GRT1-TS2T

*1. The GRT1-ML2 supports the GRT1-IA4-1, GRT1-IA4-2, GRT1-OD4G-3, GRT1-TS2P, GRT1-TS2K and GRT1-TS2T slice units only in combination with TJ2-MC64 motion controller. They are not supported in combination with TJ1-MC16/04.

Refer to Automation systems catalogue for detailed specs and accessories information

MECHATROLINK-II cables

Name	Remarks	Model
MECHATROLINK-II cables	0.5 meter	FNY-W6003-A5
	1 meter	FNY-W6003-01
	3 meters	FNY-W6003-03
	5 meters	FNY-W6003-05
	10 meters	FNY-W6003-10
	20 meters	FNY-W6003-20
	30 meters	FNY-W6003-30
MECHATROLINK-II terminator	Terminating resistor	FNY-W6022
MECHATROLINK-II repeater	Network repeater	FNY-REP2000

Computer software

Specifications	Model
CX-Motion Pro V1.3.3 or higher	CX-One
Trajexia Studio ^{*1} V1.3.3 or higher	TJ1-Studio

*1. When the Trajexia Studio software is included in CX-One, then it is called CX-Motion Pro.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Terms and Conditions of Sale

1. **Offer; Acceptance.** These terms and conditions (these "Terms") are deemed part of all quotes, agreements, purchase orders, acknowledgments, price lists, catalogs, manuals, brochures and other documents, whether electronic or in writing, relating to the sale of products or services (collectively, the "Products") by Omron Electronics LLC and its subsidiary companies ("Omron"). Omron objects to any terms or conditions proposed in Buyer's purchase order or other documents which are inconsistent with, or in addition to, these Terms.
2. **Prices; Payment Terms.** All prices stated are current, subject to change without notice by Omron. Omron reserves the right to increase or decrease prices on any unshipped portions of outstanding orders. Payments for Products are due net 30 days unless otherwise stated in the invoice.
3. **Discounts.** Cash discounts, if any, will apply only on the net amount of invoices sent to Buyer after deducting transportation charges, taxes and duties, and will be allowed only if (i) the invoice is paid according to Omron's payment terms and (ii) Buyer has no past due amounts.
4. **Interest.** Omron, at its option, may charge Buyer 1-1/2% interest per month or the maximum legal rate, whichever is less, on any balance not paid within the stated terms.
5. **Orders.** Omron will accept no order less than \$200 net billing.
6. **Governmental Approvals.** Buyer shall be responsible for, and shall bear all costs involved in, obtaining any government approvals required for the importation or sale of the Products.
7. **Taxes.** All taxes, duties and other governmental charges (other than general real property and income taxes), including any interest or penalties thereon, imposed directly or indirectly on Omron or required to be collected directly or indirectly by Omron for the manufacture, production, sale, delivery, importation, consumption or use of the Products sold hereunder (including customs duties and sales, excise, use, turnover and license taxes) shall be charged to and remitted by Buyer to Omron.
8. **Financial.** If the financial position of Buyer at any time becomes unsatisfactory to Omron, Omron reserves the right to stop shipments or require satisfactory security or payment in advance. If Buyer fails to make payment or otherwise comply with these Terms or any related agreement, Omron may (without liability and in addition to other remedies) cancel any unshipped portion of Products sold hereunder and stop any Products in transit until Buyer pays all amounts, including amounts payable hereunder, whether or not then due, which are owing to it by Buyer. Buyer shall in any event remain liable for all unpaid accounts.
9. **Cancellation; Etc.** Orders are not subject to rescheduling or cancellation unless Buyer indemnifies Omron against all related costs or expenses.
10. **Force Majeure.** Omron shall not be liable for any delay or failure in delivery resulting from causes beyond its control, including earthquakes, fires, floods, strikes or other labor disputes, shortage of labor or materials, accidents to machinery, acts of sabotage, riots, delay in or lack of transportation or the requirements of any government authority.
11. **Shipping; Delivery.** Unless otherwise expressly agreed in writing by Omron:
 - a. Shipments shall be by a carrier selected by Omron; Omron will not drop ship except in "break down" situations.
 - b. Such carrier shall act as the agent of Buyer and delivery to such carrier shall constitute delivery to Buyer;
 - c. All sales and shipments of Products shall be FOB shipping point (unless otherwise stated in writing by Omron), at which point title and risk of loss shall pass from Omron to Buyer; provided that Omron shall retain a security interest in the Products until the full purchase price is paid;
 - d. Delivery and shipping dates are estimates only; and
 - e. Omron will package Products as it deems proper for protection against normal handling and extra charges apply to special conditions.
12. **Claims.** Any claim by Buyer against Omron for shortage or damage to the Products occurring before delivery to the carrier must be presented in writing to Omron within 30 days of receipt of shipment and include the original transportation bill signed by the carrier noting that the carrier received the Products from Omron in the condition claimed.
13. **Warranties.** (a) **Exclusive Warranty.** Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied. (b) **Limitations.** OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right. (c) **Buyer Remedy.** Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty. See <http://www.omron247.com> or contact your Omron representative for published information.
14. **Limitation on Liability; Etc.** OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY. Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.
15. **Indemnities.** Buyer shall indemnify and hold harmless Omron Companies and their employees from and against all liabilities, losses, claims, costs and expenses (including attorney's fees and expenses) related to any claim, investigation, litigation or proceeding (whether or not Omron is a party) which arises or is alleged to arise from Buyer's acts or omissions under these Terms or in any way with respect to the Products. Without limiting the foregoing, Buyer (at its own expense) shall indemnify and hold harmless Omron and defend or settle any action brought against such Companies to the extent based on a claim that any Product made to Buyer specifications infringed intellectual property rights of another party.
16. **Property; Confidentiality.** Any intellectual property in the Products is the exclusive property of Omron Companies and Buyer shall not attempt to duplicate it in any way without the written permission of Omron. Notwithstanding any charges to Buyer for engineering or tooling, all engineering and tooling shall remain the exclusive property of Omron. All information and materials supplied by Omron to Buyer relating to the Products are confidential and proprietary, and Buyer shall limit distribution thereof to its trusted employees and strictly prevent disclosure to any third party.
17. **Export Controls.** Buyer shall comply with all applicable laws, regulations and licenses regarding (i) export of products or information; (ii) sale of products to "forbidden" or other proscribed persons; and (iii) disclosure to non-citizens of regulated technology or information.
18. **Miscellaneous.** (a) **Waiver.** No failure or delay by Omron in exercising any right and no course of dealing between Buyer and Omron shall operate as a waiver of rights by Omron. (b) **Assignment.** Buyer may not assign its rights hereunder without Omron's written consent. (c) **Law.** These Terms are governed by the law of the jurisdiction of the home office of the Omron company from which Buyer is purchasing the Products (without regard to conflict of law principles). (d) **Amendment.** These Terms constitute the entire agreement between Buyer and Omron relating to the Products, and no provision may be changed or waived unless in writing signed by the parties. (e) **Severability.** If any provision hereof is rendered ineffective or invalid, such provision shall not invalidate any other provision. (f) **Setoff.** Buyer shall have no right to set off any amounts against the amount owing in respect of this invoice. (g) **Definitions.** As used herein, "including" means "including without limitation"; and "Omron Companies" (or similar words) mean Omron Corporation and any direct or indirect subsidiary or affiliate thereof.

Certain Precautions on Specifications and Use

1. **Suitability of Use.** Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases but the following is a non-exhaustive list of applications for which particular attention must be given:
 - (i) Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.
 - (ii) Use in consumer products or any use in significant quantities.
 - (iii) Energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
 - (iv) Systems, machines and equipment that could present a risk to life or property. Please know and observe all prohibitions of use applicable to this Product.
 NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON'S PRODUCT IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.
2. **Programmable Products.** Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.
3. **Performance Data.** Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.
4. **Change in Specifications.** Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.
5. **Errors and Omissions.** Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

OMRON INDUSTRIAL AUTOMATION • THE AMERICAS HEADQUARTERS • Schaumburg, IL USA • 847.843.7900 • 800.556.6766 • www.omron247.com

OMRON CANADA, INC. • HEAD OFFICE

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OMRON ELECTRONICS DE MEXICO • HEAD OFFICE

México DF • 52.55.59.01.43.00 • 001.800.556.6766 • mela@omron.com

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São Paulo, SP, Brasil • 55.11.2101.6300 • www.omron.com.br

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OMRON EUROPE B.V. • Wegalaan 67-69, NL-2132 JD, Hoofddorp, The Netherlands. • Tel: +31 (0) 23 568 13 00 • Fax: +31 (0) 23 568 13 88 • www.industrial.omron.eu

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