

Monolithic 1A Step-Down Regulator

The EL7536 is a synchronous, integrated FET 1A step-down regulator with internal compensation. It operates with an input voltage range from 2.5V to 5.5V, which accommodates supplies of 3.3V, 5V, or a Li-Ion battery source. The output can be externally set from 0.8V to V_{IN} with a resistive divider.

The EL7536 features PWM mode control. The operating frequency is typically 1.4MHz. Additional features include a 100ms Power-On-Reset output, <1μA shut-down current, short-circuit protection, and over-temperature protection.

The EL7536 is available in the 10 Ld MSOP package, making the entire converter occupy less than 0.15in² of PCB area with components on one side only. Both packages are specified for operation over the full -40°C to +85°C temperature range.

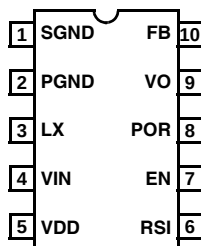
Ordering Information

PART NUMBER (BRAND)	PART MARKING	TAPE & REEL	PACKAGE	PKG. DWG. #
EL7536IY	BDAAA	-	10 Ld MSOP	MDP0043
EL7536IY-T7	BDAAA	7"	10 Ld MSOP	MDP0043
EL7536IY-T13	BDAAA	13"	10 Ld MSOP	MDP0043
EL7536IYZ (Note)	BFAAA	-	10 Ld MSOP (Pb-free)	MDP0043
EL7536IYZ-T7 (Note)	BFAAA	7"	10 Ld MSOP (Pb-free)	MDP0043
EL7536IYZ-T13 (Note)	BFAAA	13"	10 Ld MSOP (Pb-free)	MDP0043

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

Pinout

EL7536 (10 LD MSOP)
TOP VIEW



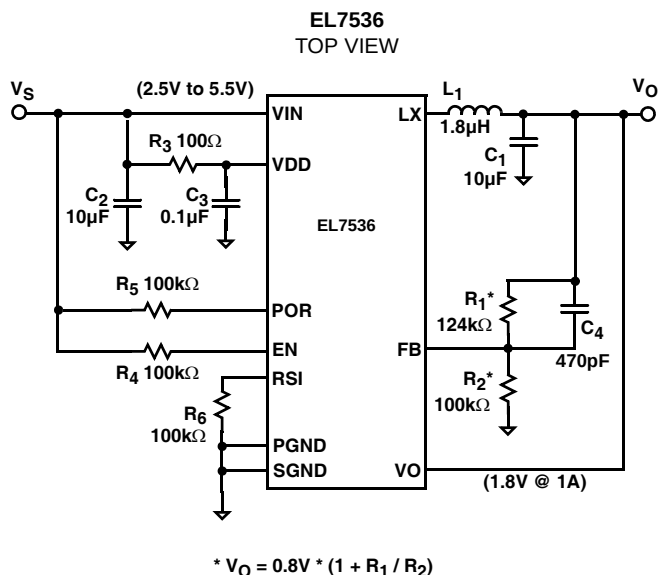
Features

- Less than 0.15in² (0.97cm²) footprint for the complete 1A converter
- Components on one side of PCB
- Max height 1.1mm MSOP10
- 100ms Power-On-Reset output (POR)
- Internally-compensated voltage mode controller
- Up to 94% efficiency
- <1μA shut-down current
- Overcurrent and over-temperature protection
- Pb-free plus anneal available (RoHS compliant)

Applications

- PDA and pocket PC computers
- Bar code readers
- Cellular phones
- Portable test equipment
- Li-Ion battery powered devices
- Small form factor (SFP) modules

Typical Application Diagram



Absolute Maximum Ratings ($T_A = 25^\circ\text{C}$)

V_{IN} , V_{DD} , POR to SGND -0.3V to +6.5V
 LX to PGND -0.3V to ($V_{IN} + 0.3\text{V}$)
 RSI, EN, V_O , FB to SGND -0.3V to ($V_{IN} + 0.3\text{V}$)
 PGND to SGND -0.3V to +0.3V
 Peak Output Current 1.2A

Operating Ambient Temperature -40°C to $+85^\circ\text{C}$
 Storage Temperature -65°C to $+150^\circ\text{C}$
 Junction Temperature $+125^\circ\text{C}$

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typ values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore: $T_J = T_C = T_A$

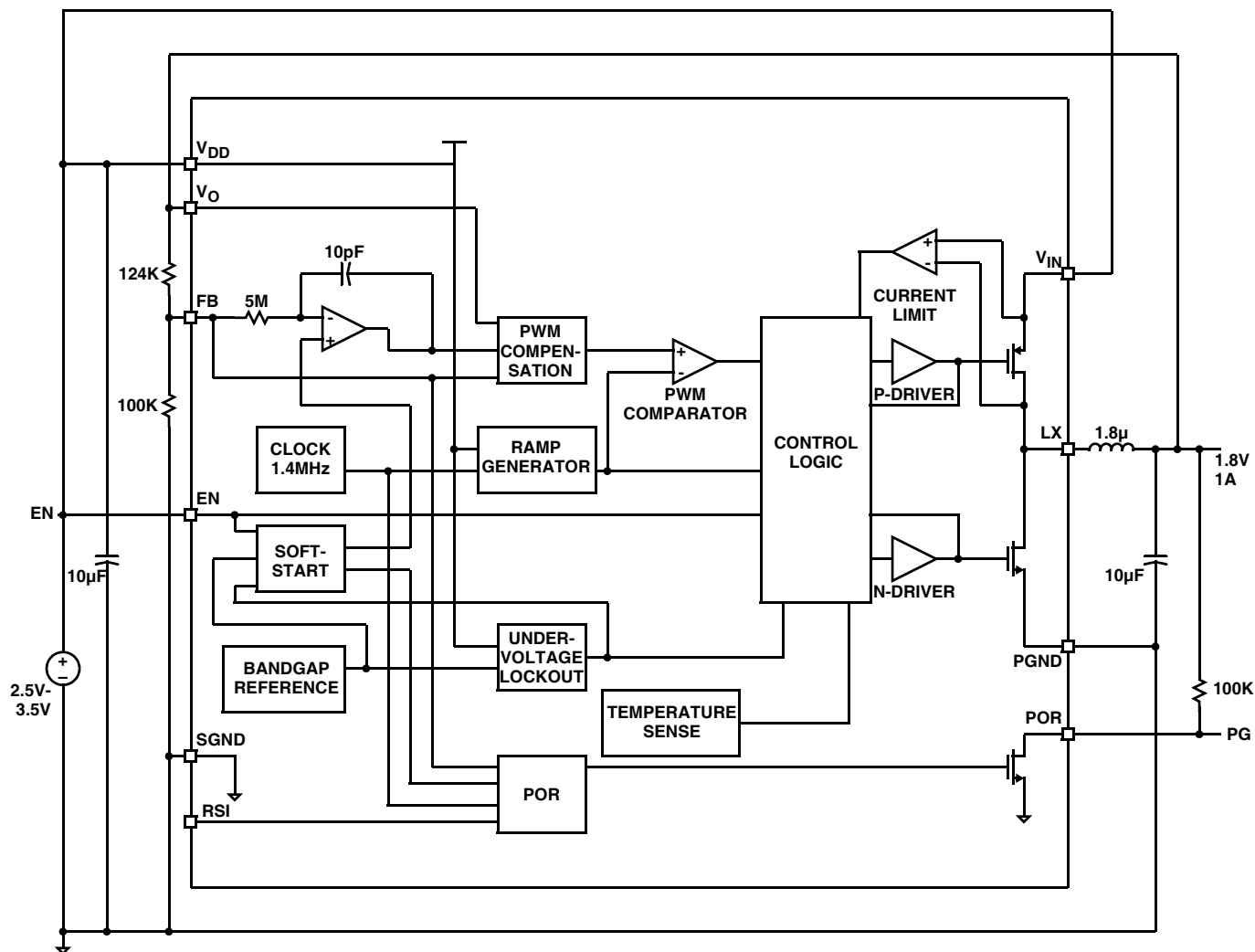
Electrical Specifications $V_{DD} = V_{IN} = V_{EN} = 3.3\text{V}$, $C_1 = C_2 = 10\mu\text{F}$, $L = 1.8\mu\text{H}$, $V_O = 1.8\text{V}$, unless otherwise specified.

PARAMETER	DESCRIPTION	CONDITIONS	MIN	TYP	MAX	UNIT
DC CHARACTERISTICS						
V_{FB}	Feedback Input Voltage		790	800	810	mV
I_{FB}	Feedback Input Current				250	nA
V_{IN} , V_{DD}	Input Voltage		2.5		5.5	V
$V_{IN,OFF}$	Minimum Voltage for Shutdown	V_{IN} falling	2		2.2	V
$V_{IN,ON}$	Maximum Voltage for Startup	V_{IN} rising	2.2		2.4	V
I_{DD}	Supply Current	PWM, $V_{IN} = V_{DD} = 5\text{V}$		400	500	μA
		EN = 0, $V_{IN} = V_{DD} = 5\text{V}$		0.1	1	μA
$R_{DS(ON)-PMOS}$	PMOS FET Resistance	$V_{DD} = 5\text{V}$, wafer test only		70	100	$\text{m}\Omega$
$R_{DS(ON)-NMOS}$	NMOS FET Resistance	$V_{DD} = 5\text{V}$, wafer test only		45	75	$\text{m}\Omega$
I_{LMAX}	Current Limit			1.5		A
$T_{OT,OFF}$	Over-temperature Threshold	T rising		145		$^\circ\text{C}$
$T_{OT,ON}$	Over-temperature Hysteresis	T falling		130		$^\circ\text{C}$
I_{EN} , I_{RSI}	EN, RSI Current	V_{EN} , $V_{RSI} = 0\text{V}$ and 3.3V	-1		1	V
V_{EN1} , V_{RSI1}	EN, RSI Rising Threshold	$V_{DD} = 3.3\text{V}$			2.4	V
V_{EN2} , V_{RSI2}	EN, RSI Falling Threshold	$V_{DD} = 3.3\text{V}$	0.8			V
V_{POR}	Minimum V_{FB} for POR, WRT Targeted V_{FB} Value	V_{FB} rising			95	%
		V_{FB} falling	86			%
V_{OLPOR}	POR Voltage Drop	$I_{SINK} = 5\text{mA}$		35	70	mV
AC CHARACTERISTICS						
F_{PWM}	PWM Switching Frequency		1.4	1.5	1.75	MHz
t_{RSI}	Minimum RSI Pulse Width	Guaranteed by design		25	50	ns
t_{SS}	Soft-start Time			650		μs
t_{POR}	Power On Reset Delay Time		80	100	120	ms

Pin Descriptions

PIN NUMBER	PIN NAME	PIN FUNCTION
1	SGND	Negative supply for the controller stage
2	PGND	Negative supply for the power stage
3	LX	Inductor drive pin; high current digital output with average voltage equal to the regulator output voltage
4	VIN	Positive supply for the power stage
5	VDD	Power supply for the controller stage
6	RSI	Resets POR timer
7	EN	Enable
8	POR	Power on reset open drain output
9	VO	Output voltage sense
10	FB	Voltage feedback input; connected to an external resistor divider between V_O and SGND for variable output

Block Diagram



Performance Curves and Waveforms

All waveforms are taken at $V_{IN} = 3.3V$, $V_O = 1.8V$, $I_O = 1A$ with component values shown on page 1 at room ambient temperature, unless otherwise noted.

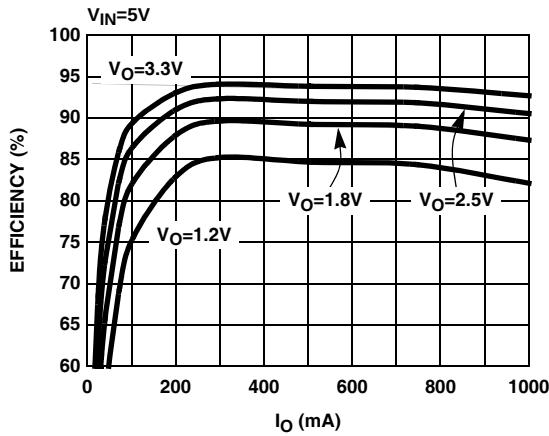


FIGURE 1. EFFICIENCY

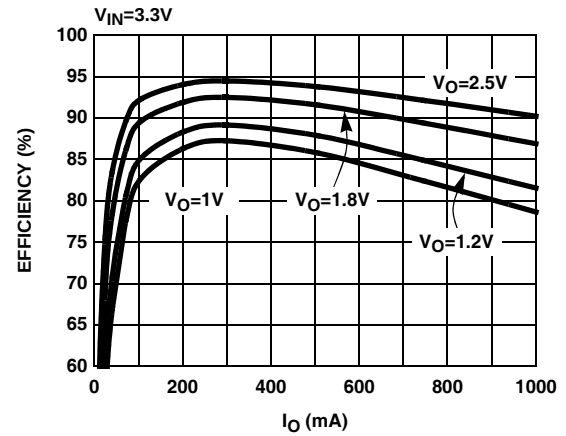


FIGURE 2. EFFICIENCY

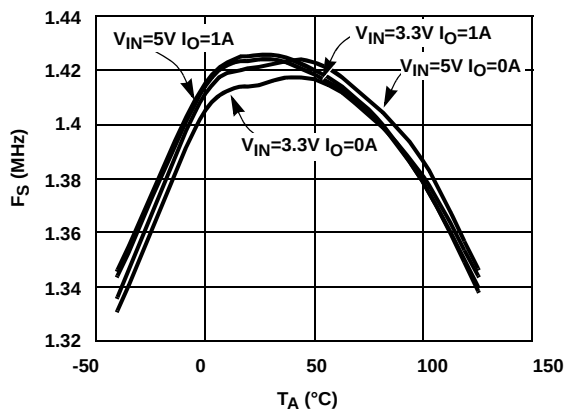
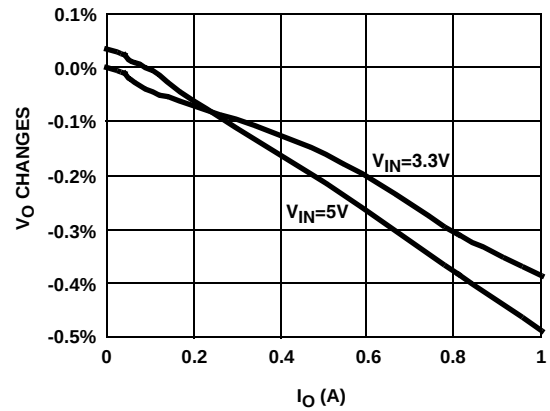
FIGURE 3. F_S vs JUNCTION TEMPERATURE

FIGURE 4. LOAD REGULATIONS

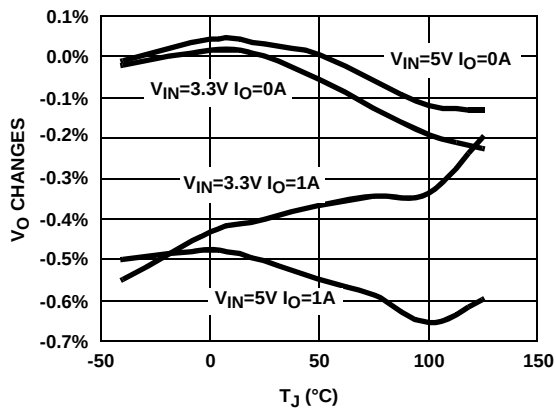


FIGURE 5. LOAD/LINE REGULATIONS vs JUNCTION TEMPERATURE

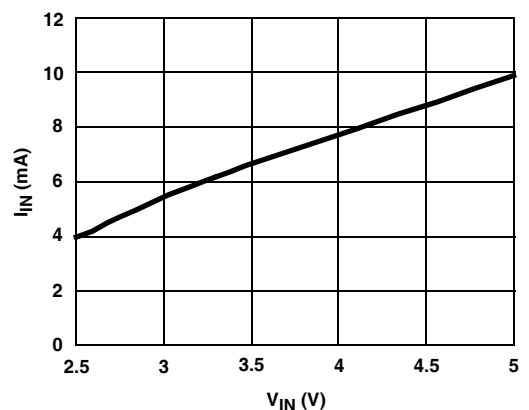


FIGURE 6. NO LOAD INPUT CURRENT

Performance Curves and Waveforms (Continued)

All waveforms are taken at $V_{IN} = 3.3V$, $V_O = 1.8V$, $I_O = 1A$ with component values shown on page 1 at room ambient temperature, unless otherwise noted.

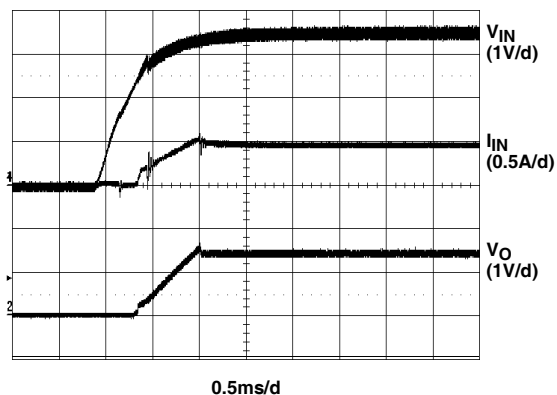


FIGURE 7. START-UP 1

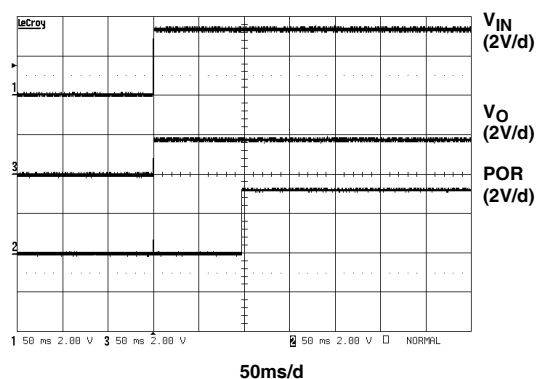


FIGURE 8. START-UP 2

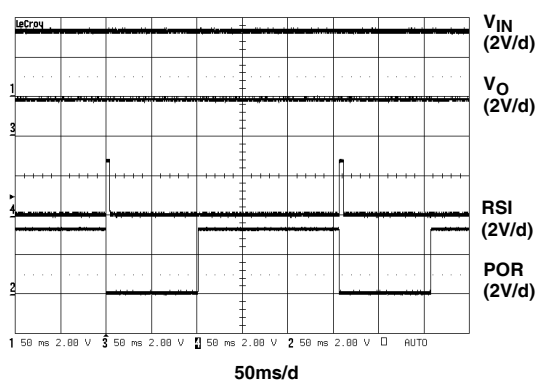


FIGURE 9. POR FUNCTION

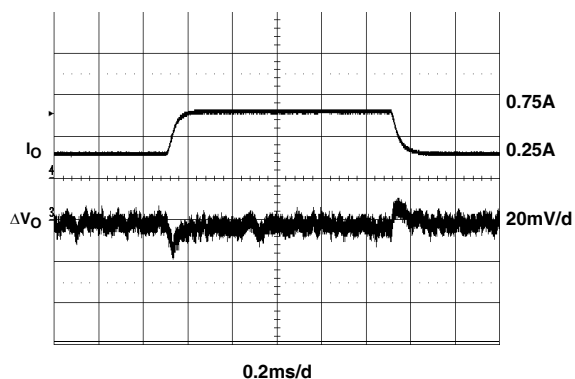


FIGURE 10. TRANSIENT RESPONSE

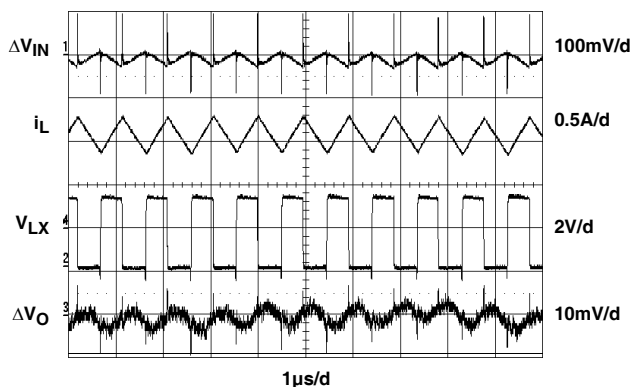


FIGURE 11. STEADY-STATE

Performance Curves and Waveforms (Continued)

All waveforms are taken at $V_{IN} = 3.3V$, $V_O = 1.8V$, $I_O = 1A$ with component values shown on page 1 at room ambient temperature, unless otherwise noted.

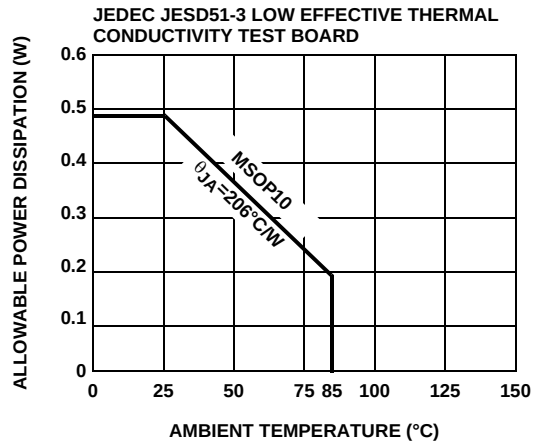


FIGURE 12. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

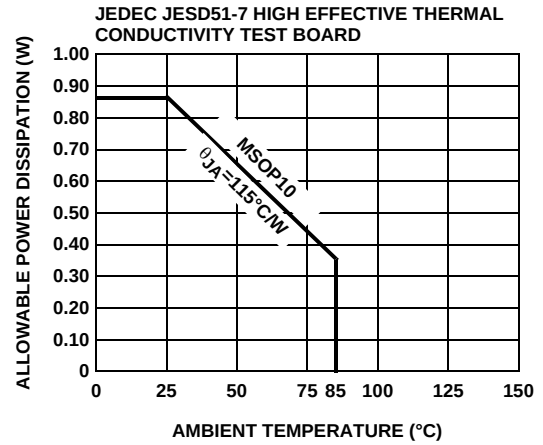


FIGURE 13. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

Applications Information

Product Description

The EL7536 is a synchronous, integrated FET 1A step-down regulator which operates from an input of 2.5V to 6V. The output voltage is user-adjustable with a pair of external resistors.

The internally-compensated controller makes it possible to use only two ceramic capacitors and one inductor to form a complete, very small footprint 1A DC:DC converter.

Start-Up and Shut-Down

When the EN pin is tied to V_{IN} , and V_{IN} reaches approximately 2.4V, the regulator begins to switch. The output voltage is gradually increased to ensure proper soft-start operation.

When the EN pin is connected to a logic low, the EL7536 is in the shut-down mode. All the control circuitry and both MOSFETs are off, and V_{OUT} falls to zero. In this mode, the total input current is less than 1 μ A.

When the EN reaches logic HI, the regulator repeats the start-up procedure, including the soft-start function.

PWM Operation

In the PWM mode, the P channel MOSFET and N channel MOSFET always operate complementary. When the PMOSFET is on and the NMOSFET off, the inductor current increases linearly. The input energy is transferred to the output and also stored in the inductor. When the P channel MOSFET is off and the N channel MOSFET on, the inductor current decreases linearly, and energy is transferred from the inductor to the output. Hence, the average current through the inductor is the output current. Since the inductor and the output capacitor act as a low pass filter, the duty cycle ratio is approximately equal to V_O divided by V_{IN} .

The output LC filter has a second order effect. To maintain the stability of the converter, the overall controller must be compensated. This is done with the fixed internally compensated error amplifier and the PWM compensator. Because the compensations are fixed, the values of input and output capacitors are 10 μ F to 22 μ F ceramic. The inductor is nominally 1.8 μ H, but 1.5 μ A to 2.2 μ H can be used.

100% Duty Ratio Operation

EL7536 utilizes CMOS power FET's as the internal synchronous power switches. The upper switch is a PMOS and lower switch a NMOS. This not only saves a boot capacitor, it also allows 100% turn-on of the upper PFET switch, achieving V_O close to V_{IN} . The maximum achievable V_O is,

$$V_O = V_{IN} - (R_L + R_{DS(ON)1}) \times I_O$$

Where R_L is the DC resistance on the inductor and $R_{DS(ON)1}$ the PFET on-resistance, nominal 70m Ω at room temperature with tempco of 0.2m Ω /°C.

As the input voltage drops gradually close or even below the preset V_O , the converter gets into 100% duty ratio. At this condition, the upper PFET needs some minimum turn-off time if it is turned off. This off-time is related to input/output conditions. This makes the duty ratio appears randomly and increases the output ripple somewhat until the 100% duty ratio is reached. Larger output capacitor could reduce the random-looking ripple. Users need to verify if this condition has adverse effect on overall circuit if close to 100% duty ratio is expected.

RSI/POR Function

When powering up, the open-collector Power-On-Reset output holds low for about 100ms after V_O reaches the preset voltage. When the active-HI reset signal RSI is issued, POR goes to low immediately and holds for the same period of time after RSI comes back to LOW. The output voltage is unaffected. (Please refer to the timing diagram). When the function is not used, connect RSI to ground and leave open the pull-up resistor R_4 at POR pin.

The POR output also serves as a 100ms delayed Power Good signal when the pull-up resistor R_4 is installed. The RSI pin needs to be directly (or indirectly through a resistor R_6) connected to Ground for this to function properly.

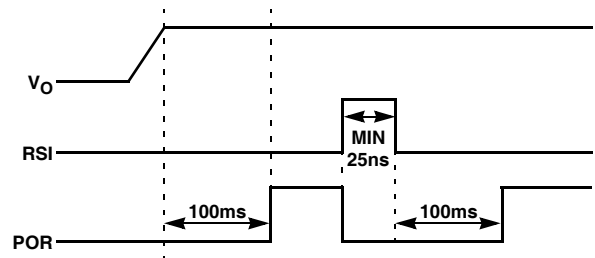


FIGURE 14. RSI & POR TIMING DIAGRAM

Output Voltage Selection

Users can set the output voltage of the converter with a resistor divider, which can be chosen based on the following formula:

$$V_O = 0.8 \times \left(1 + \frac{R_2}{R_1} \right)$$

Component Selection

Because of the fixed internal compensation, the component choice is relatively narrow. We recommend 10 μ F to 22 μ F multi-layer ceramic capacitors with X5R or X7R rating for both the input and output capacitors, and 1.5 μ H to 2.2 μ H inductance for the inductor.

At extreme conditions ($V_{IN} < 3V$, $I_O > 0.7A$, and junction temperature higher than $75^{\circ}C$), input cap C_1 is recommended to be $22\mu F$. Otherwise, if any of the above 3 conditions is not true, C_1 can remain as low as $10\mu F$.

The RMS current present at the input capacitor is decided by the following formula:

This is about half of the output current I_O for all the V_O . This input capacitor must be able to handle this current.

The inductor peak-to-peak ripple current is given as:

- L is the inductance
- f_S the switching frequency (nominally 1.4MHz)

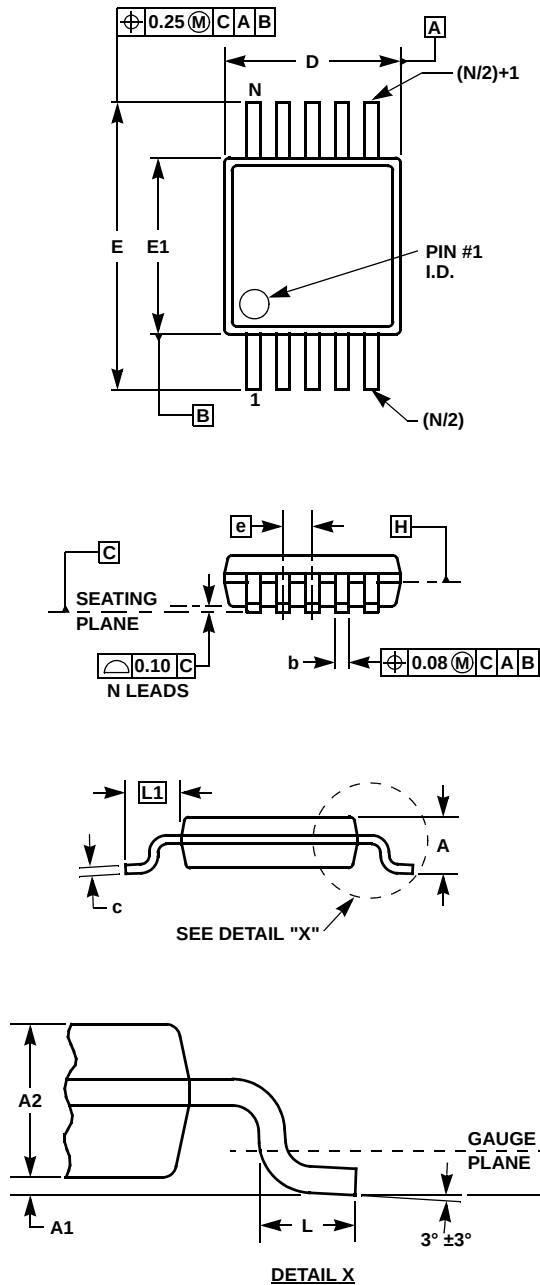
The inductor must be able to handle I_O for the RMS load current, and to assure that the inductor is reliable, it must handle the 1.5A surge current that can occur during a current limit condition.

In addition to decoupling capacitors and inductor value, it is important to properly size the phase-lead capacitor C_4 (Refer to the Typical Application Diagram). The phase-lead capacitor creates additional phase margin in the control loop by generating a zero and a pole in the transfer function. As a general rule of thumb, C_4 should be sized to start the phase-lead at a frequency of $\sim 2.5kHz$. The zero will always appear at lower frequency than the pole and follow the equation below:

Over a normal range of R_2 ($\sim 10-100k$), C_4 will range from $\sim 470-4700pF$. The pole frequency cannot be set once the zero frequency is chosen as it is dictated by the ratio of R_1 and R_2 , which is solely determined by the desired output set point. The equation below shows the pole frequency relationship:

Current Limit and Short-Circuit Protection

Mini SO Package Family (MSOP)



MDP0043

MINI SO PACKAGE FAMILY

SYMBOL	MSOP8	MSOP10	TOLERANCE	NOTES
A	1.10	1.10	Max.	-
A1	0.10	0.10	±0.05	-
A2	0.86	0.86	±0.09	-
b	0.33	0.23	+0.07/-0.08	-
c	0.18	0.18	±0.05	-
D	3.00	3.00	±0.10	1, 3
E	4.90	4.90	±0.15	-
E1	3.00	3.00	±0.10	2, 3
e	0.65	0.50	Basic	-
L	0.55	0.55	±0.15	-
L1	0.95	0.95	Basic	-
N	8	10	Reference	-

Rev. C 6/99

NOTES:

1. Plastic or metal protrusions of 0.15mm maximum per side are not included.
2. Plastic interlead protrusions of 0.25mm maximum per side are not included.
3. Dimensions "D" and "E1" are measured at Datum Plane "H".
4. Dimensioning and tolerancing per ASME Y14.5M-1994.

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