

Using the TPS51116EVM

The TPS51116EVM evaluation module (EVM) is a dual-output converter for DDR, DDR2 and DDR3 memory modules. It uses a 10-A synchronous buck converter to provide the core voltage (VDDQ) for DDR memory modules. The EVM is designed to use a 4.5-V to 28-V supply voltage and a 4.75-V to 5.25-V controller bias supply. This allows the EVM to start up from a single 5-V supply or operate from a wide range of supply voltages with low power 5-V bias supply. The TPS51116EVM provides several jumpers and switches to allow the user to evaluate all of the TPS51116's configurations including lossless $R_{DS(on)}$ or resistive current sensing, current mode or D-CAP™ semi-hysteretic operation, DDR, DDR2 or DDR3 voltage standards and the S3 and S5 sleep states.

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1 Description

The TPS51116 is designed to be a complete power supply solution for dual data rate (DDR) memory modules covering DDR (2.5 V/1.25 V), and DDR2 (1.8 V/0.9 V) and DDR3 (1.5 V/ 0.75 V) specifications. By combining a high-efficiency synchronous buck switching regulator and a high-current fixed ratio sink/source LDO regulator, the TPS51116 provides high-efficiency generation of the DDR memory cell's core and I/O voltages as well as providing an accurate, high-speed termination voltage. While the TPS51116 is designed to use the VDDQ output to power the termination voltage LDO, another power source can be used, allowing for more control and efficient operation of the termination voltage if lower voltages are available in the system. Powerful, efficient and flexible, the TPS51116 is a single device that can meet all DDR memory power needs.

1.1 Applications

- Dual Data Rate (DDR) High-Speed RAM Supply
- High Performance AGP Video Cards
- Notebook, Desktop and Server Motherboards
- High Performance Computer
- High Memory Content Consumer Electronics

1.2 Features

- Up to 85% efficiency on the V_{DDQ} switching regulator output
- Dual switching regulator / LDO output for both DDR core and termination voltages
- 3-A sink/source termination voltage LDO regulator
- 10-mA termination reference voltage for DDR input reference
- User selectable DDR, DDR2, DDR3 or externally referenced supply voltages
- User selectable switching regulator or external supply source for LDO termination regulator
- Switches available for testing S3 and S5 sleep states

2 Electrical Performance Specifications

Table 1. Electrical Performance Specifications

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
V_{VIN}	Supply voltage		4.5		28	V
V_{V5IN}	Logic supply voltage		4.75		5.25	
V_{VDDQ}	Switching output voltage	DDR mode	2.45	2.50	2.55	
		DDR2 mode	1.75	1.80	1.85	
		DDR3 mode	1.45	1.50	1.55	
$V_{VDDQ(RIP-p)}$	Switching output voltage ripple	DDR2 mode, $I_{DDQ} = 10\text{ A}$	10		40	mV
I_{VDDQ}	Switching output current	$I_{VTT} = 0\text{ A}$	0		10	A
V_{VTT}	Termination voltage output	$V_{VDDQSNS} = V_{VDDQ}$	$V_{VDDQ}/2$			V
$V_{tt(tol)}$	VTT output voltage tolerance to VTTREF		-40		40	mV
$V_{ttripple(p-p)}$	Termination voltage ripple		0		20	
V_{tt_Ref}	Reference voltage	$V_{VDDQSNS} = V_{VDDQ}$	$V_{VDDQ}/2$			V
$V_{tt_Ref(tol)}$	Reference voltage tolerance	$I_{VTTREF} < 10\text{ mA}$	-10		10	mV
η	Switching output efficiency	$I_{VTTREF} = 0\text{ mA}$, DDR2 mode, $I_{VDDQ} = 10\text{ mA}$, $V_{IN} = 12\text{ V}$	78%			
		$I_{VTTREF} = 0\text{ mA}$, DDR2 mode, $I_{VDDQ} = 1\text{ A}$	88%			
		$I_{VTTREF} = 0\text{ mA}$, DDR2 mode, $I_{VDDQ} = 7\text{ A}$	90%			
		$I_{VTTREF} = 0\text{ mA}$, DDR2 mode, $I_{VDDQ} = 10\text{ A}$	88%			

3 Schematic

The TPS51116EVM schematic is shown in [Figure 1](#).

3.1 Jumpers

Standard 100-mil spacing headers JP1 through JP4 provide user configuration settings for the TPS51116EVM. Each jumper bank of three or six pins is provided with a single 100-mil shunt to allow the user to select the desired operation mode.

Table 2. Jumper Functions

JUMPER	SELECTION	DEFAULT
JP1	TPS51116 VDDQ discharge scheme, tracking, non-tracking or no discharge.	Tracking
JP2	Current sensing mode used by the TPS51116.	$R_{DS(on)}$
JP3	Control scheme used by the TPS51116.	D-CAP mode
JP4	Output levels DDR, DDR2, DDR3, or externally adjustable.	DDR2

3.2 Sleep State Switches

Switches SW1 and SW2 select the S5 and S3 sleep states respectively allowing the user to examine the reaction of the TPS51116 controller to these memory sleep states

3.3 Resistors and Shorts

Resistor R8 and short R9 allow the user to select between lossless $R_{DS(on)}$ and conventional resistive current sense. If resistive sensing is selected by JP2, R8 must be in place and R9 removed. If $R_{DS(on)}$ sensing is chosen by JP2, R9 must be in place, but since R9 and R8 are in parallel, R8 can be left on the PCB.

3.4 MOSFETs

The values of the MOSFETs Q1 and Q2 used on the TPS51116EVM are selected to optimize operation of the switching regulator over the 3-V to 28-V operating range for notebook power systems.

In applications with a regulated supply voltage available, it is possible to optimize the MOSFETs used to reduce losses and improve efficiency. For systems running from a fixed 12-V supply, the low duty cycle of the high-side MOSFET favors a higher $R_{DS(on)}$ for lower gate charge and faster switching times. For a regulated 12-V supply voltage, TI recommends Vishay SI4390 for Q1 and SI4378 for Q2 or equivalent MOSFETs.

For applications using a single 5-V supply rail for both the switching regulator and the TPS51116's VDD voltage, the high-side MOSFET duty cycles are higher, and thus favor a lower $R_{DS(on)}$ and somewhat higher gate charge. If a single 5-V supply voltage is used, TI recommends the Vishay SI4378 for both Q1 and Q2.

The use of these MOSFET pairs improves the high-load efficiency of the switching regulator by reducing MOSFET losses, however they may adversely effect lighter load efficiencies with increased switching and gate charge losses. Other MOSFET pairs are possible and even greater performance improvements can be realized by using PowerPak, LFPack or DirectFET MOSFETs at the increased cost of these customized power MOSFET packages. As each application's power needs are unique, each design may require the evaluation of several MOSFET pairs to determine the best MOSFET selection.

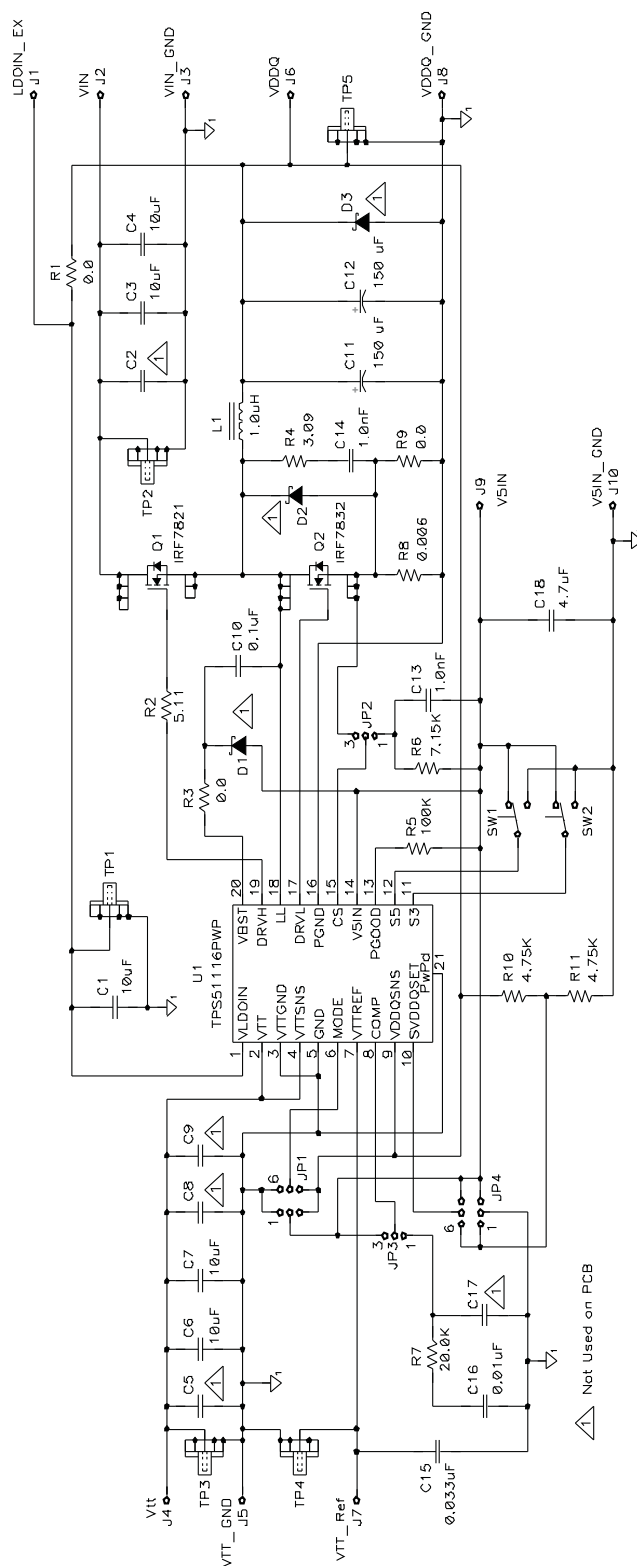


Figure 1. TPS51116 Schematic

4 Configuration

4.1 User Selectable Configuration Modes

Figure 2 shows the location of the four jumper blocks, two switches and three resistors used to adjust the configuration of TPS51116EVM. Refer to the specific configuration settings sections regarding how to set each jumper, switch or resistor for the specific configuration desired.

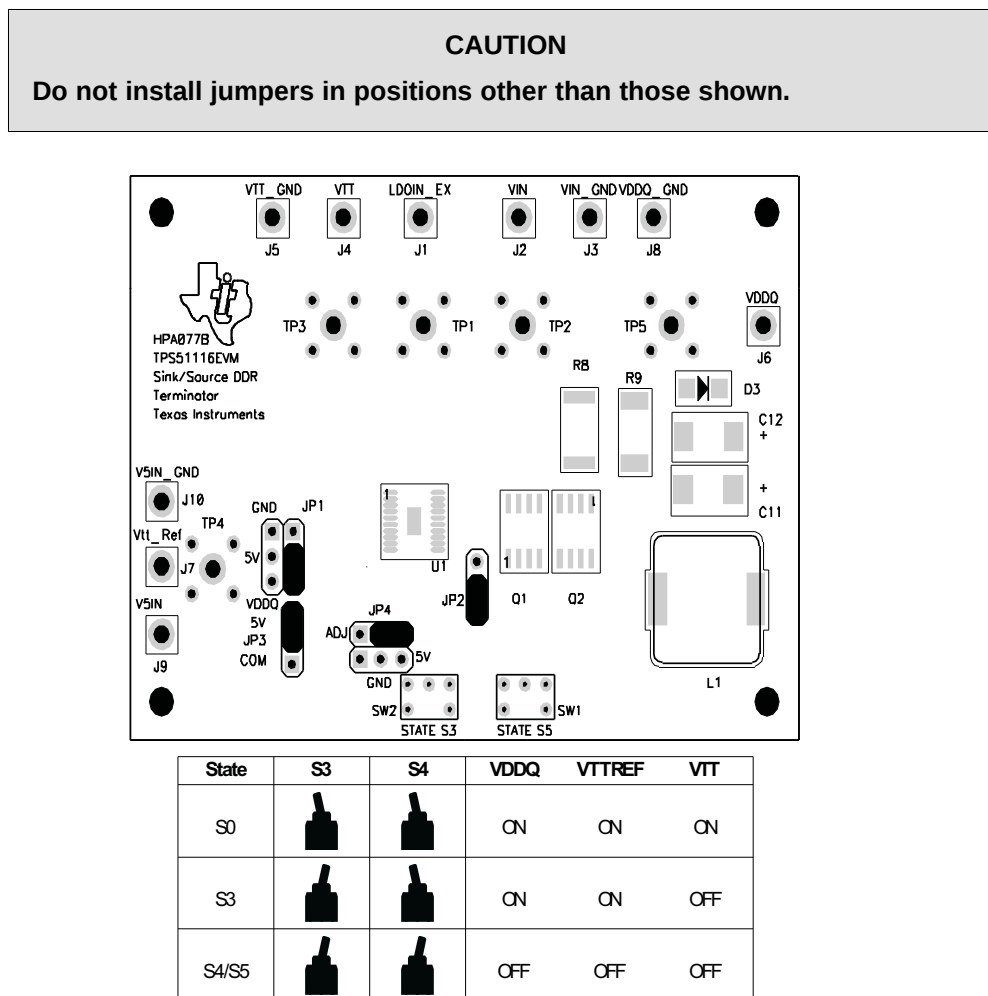


Figure 2. TPS51116EVM Jumper/Switch Locations and Default Positions

4.2 JP1 Tracking Discharge Mode

The TPS51116EVM comes preconfigured in tracking discharge mode. In tracking discharge mode, when the TPS51116 is set to discharge by turning on both S3 and S5 switches, the TPS51116 turns off both MOSFETs and sinks current slowly from the VDDQ output through an internal MOSFET. Because the resistance of this MOSFET is fairly high, the VDDQ level discharges slowly unless a heavy load is placed externally.

To program the EVM for tracking discharge mode set the JP1 jumper to the lower vertical position.

4.3 JP1 **Non-Tracking Discharge Mode**

The TPS51116EVM can be configured to operate in non-tracking discharge mode. To operate in non-tracking discharge mode the TPS51116 must be set in self-driven LDO supply voltage mode because the TPS51116 sinks up to 3 A from the VDDQ output until V_{VDDQ} discharges to 300 mV. If an external LDO supply is used, selecting non-tracking discharge mode can damage the TPS51116EVM as the LDO attempts to discharge this external supply and sink up to 3 A.

To program the EVM for non-tracking discharge mode set the JP1 jumper to the upper vertical position.

4.4 JP1 **No Discharge Mode**

The TPS51116EVM can be configured to operate in no discharge mode. In no discharge mode, the TPS51116 simply turns off the supply MOSFETs and leaves the output to be discharged by the load or self-discharge of the output capacitors.

To program the EVM for no discharge mode set the JP1 jumper to the center horizontal position.

4.5 JP2 **$R_{DS(on)}$ Current Sensing**

The TPS51116EVM comes preconfigured in a lossless $R_{DS(on)}$ current sensing mode. In this mode the TPS51116EVM uses the forward voltage drop of the low-side MOSFET (Q2) to monitor inductor current. If a fault is detected, the output voltage droops as output current rises. If a severe over current fault is detected, it trips the undervoltage comparator. When configured to use $R_{DS(on)}$ overcurrent sensing, the TPS51116 compensates for thermal shift in the $R_{DS(on)}$ of the MOSFET.

For $R_{DS(on)}$ overcurrent sensing, place a 0- Ω resistor or short at R9 and set the JP2 jumper in the lower position.

4.6 JP2 **Resistive Current Sensing**

The TPS51116EVM can be configured into a resistive current sense mode. In this mode the TPS51116EVM senses inductor current by the voltage drop across R8. As with the $R_{DS(on)}$ current sensing mode, the TPS51116 limits the output current allowing V_{VDDQ} to droop and trip the undervoltage comparator output.

To program the EVM for resistive current sensing, ensure the 2-W, 6 m Ω resistor is installed in position R8, remove any resistor from the R9 position, and set JP2 to the upper position.

4.7 JP3 **D-CAP Control Mode**

The TPS51116EVM is preconfigured to operate in TI's D-CAP mode. This adaptive constant on-time semi-hysteretic control scheme combines the benefits of fixed frequency steady-state operation with the fast transient response of hysteretic control and a minimum off time to prevent inductor saturation or 100% duty cycle operation. For more information on D-CAP mode, see *D-CAP Mode and Transient Load Response* section. Electrolytic output capacitors should always be used when operating in D-CAP mode. See Appendix A for more information about D-CAP mode.

To program the EVM for D-CAP control mode, set JP3 into the upper position.

4.8 JP3 **Current Mode Control**

The TPS51116EVM can be configured to operate in a more conventional current mode control. In this mode, the transconductance amplifier's output is connected to the compensation network.

To program the EVM for current mode control, set JP3 into the lower position.

4.9 JP4 **DDR Mode**

The TPS51116EVM can be configured to operate in DDR mode, setting the switching regulator output voltage (V_{VDDQ}) to 2.5 V and the LDO termination voltage (V_{VTT}) to 1.25 V.

To program the EVM for DDR mode, place the JP4 jumper in the center vertical position.

4.10 JP4 **DDR2 Mode**

The TPS51116EVM comes preconfigured in DDR2 mode, setting the switching regulator output voltage (V_{VDDQ}) to 1.8 V and the LDO termination voltage (V_{VTT}) to 0.9 V.

To program the EVM for DDR2 mode, place the JP4 jumper in the right horizontal position.

4.11 JP4 **DDR3 or Adjustable Output Voltage**

The TPS51116EVM can be configured to operate in DDR3 or adjustable output mode, allowing the user to set V_{VDDQ} between 1.5 V and 3.0 V by selecting the R10 and R11 voltage divider and using the internal 750-mV reference. The V_{VTT} output voltage tracks at of this adjustable voltage. The default values for R10 and R11 provide DDR3 voltage levels. These set the switching regulator voltage (V_{VDDQ}) to 1.5 V and the LDO termination voltage (V_{VTT}) to 0.75 V.

To program the EVM for adjustable output voltage mode, place the JP4 jumper in the left horizontal position.

Table 3. Adjustable Output Voltage Resistor Values⁽¹⁾

V_{VDDQ} (V)	V_{VTT} (V)	R10 (k Ω)	R11 (k Ω)
3.0	1.50	14.3	4.75
2.7	1.35	12.4	4.75
2.0	1.00	8.06	4.75

⁽¹⁾ For adjustable output voltage mode, place the JP4 jumper in the left horizontal position.

4.12 **Self-Driven LDO Supply Voltage**

The TPS51116EVM comes preconfigured in self-driven LDO supply voltage mode. In this mode, the LDO is supplied directly from the V_{VDDQ} switching regulator's output, eliminating the need for an external supply voltage.

To program the EVM for self-driven LDO supply voltage, place a short in the R1 position.

4.13 **External LDO Supply Voltage**

The TPS51116EVM can be configured in an external LDO supply voltage mode. In this mode the LDO is supplied by an external voltage source not produced by the TPS51116, allowing the user to select another power rail to provide power to the VLDOIN by removing the 0- Ω resistor from the R1 position and applying an external supply to the LDOIN_EX pin (J1) on the EVM board.

5 Test Set-Up

Figure 3 shows the basic test set up recommended to evaluate the TPS51116EVM. Please note that although all grounds are common, their connections should remain separate as noted in Figure 3.

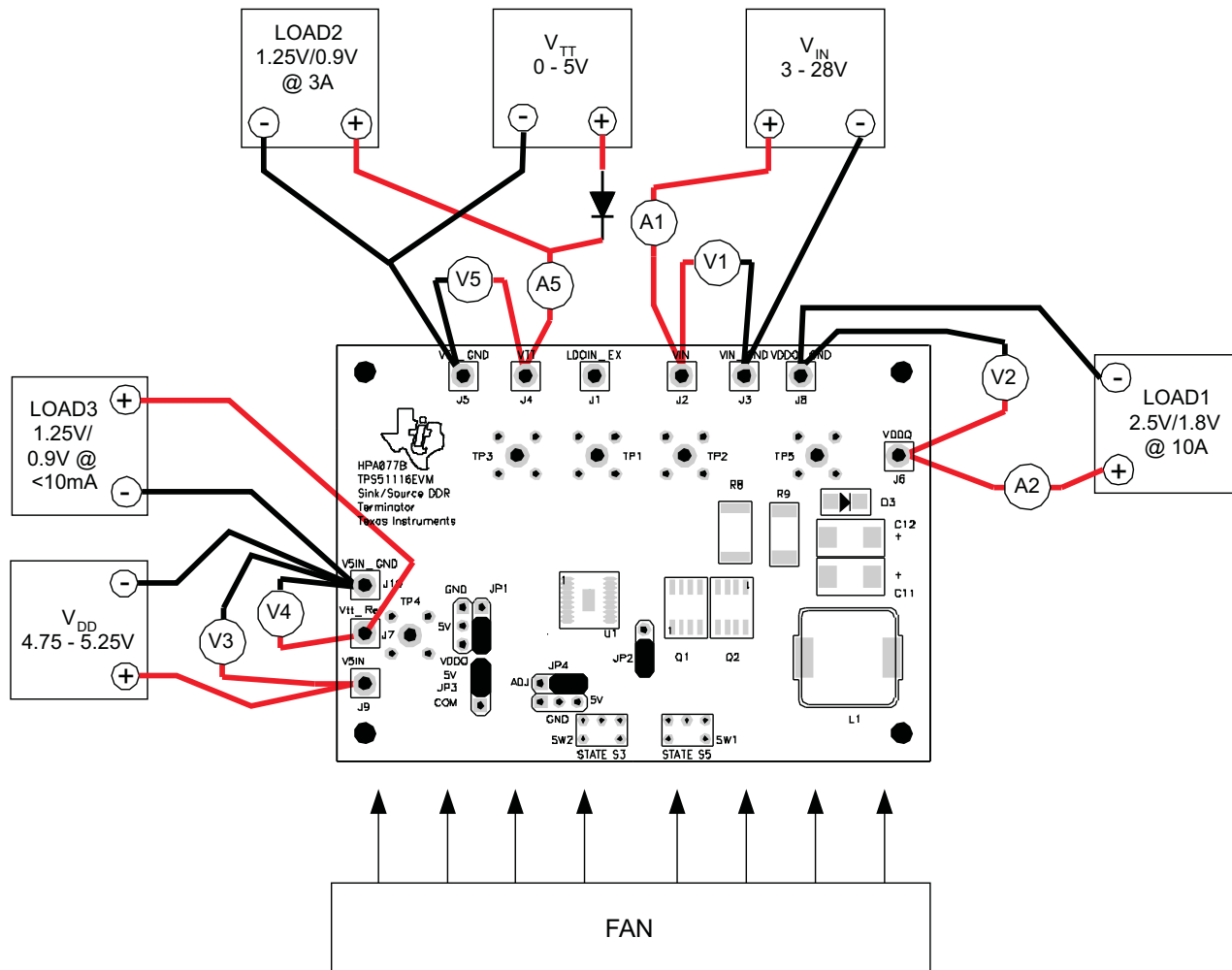


Figure 3. TPS51116EVM Test and Evaluation Setup

5.1 DC Power Source (V_{IN})

V_{IN} should be a DC voltage source capable of delivering between 0 VDC and 30 VDC and between 0 A and 10A with a power handling capability of at least 35 W. V_{IN} should be connected between pins VIN and VIN_GND. V_{IN} supplies power to the switching regulator.

5.2 5-V DC Power Source (V_{DD})

V_{DD} should be a DC voltage source capable of delivering 5 V at 500 mA with a power handling capability of at least 2.5 W. V_{DD} should be connected between pins V5IN and V5IN_GND. VDD supplies the TPS51116 operating current, powers the S3 and S5 sleep state switches and the JP1 through JP4 configuration jumpers.

5.3 Termination Voltage Source (V_{TT})

V_{TT} source is used to test the sink capability of the VTT LDO. V_{TT} must be able to source 3 A of current at 5 V. A diode should be placed in series with V_{TT} to prevent current from flowing into V_{TT} . V_{TT} should be connected between pins Vtt and Vtt_GND. V_{TT} and LOAD3 should never be powered on at the same time.

5.4 Core Voltage Load (LOAD1)

LOAD1 should be an electronic load set in constant current mode capable of sinking between 0 A and 10A at 2.5 V (DDR Mode) or 1.8 V (DDR2 Mode). LOAD1 should be connected between pins VDDQ and VDDQ_GND.

5.5 Termination Voltage Load (LOAD2)

LOAD2 should be an electronic load set in constant current mode capable of sinking between 0 A and 3 A of current at 1.25 V (DDR Mode) or 0.9 V (DDR2 Mode). LOAD2 should be connected between pins Vtt and Vtt_GND. LOAD2 and V_{TT} should never be powered on at the same time.

5.6 Memory Cell Reference Voltage Load (LOAD3)

LOAD3 should be an electronic or resistive load sinking less than 10 mA from the V_{VTTREF} of 1.25 V (DDR Mode) or 0.9 V (DDR2 Mode). LOAD3 should be connected between pins Vtt_Ref and V5IN_GND.

5.7 Fan

This converter includes components that can get hot to the touch. Because this EVM is not enclosed to allow probing of circuit nodes, a small fan capable of between 200 LFM and 400 LFM is recommended to reduce component temperatures when operating the evaluation module.

6 Power-Up/Power-Down Test Procedures

The following test procedure is recommended primarily for powering up and shutting down the EVM. Whenever the EVM is running the fan should be turned on. Also, never walk away from a powered EVM for extended periods of time.

1. Working at an ESD workstation, make sure that any wrist straps, boot straps or mats are connected referencing the user to earth ground before power is applied to the EVM. Electrostatic smock and safety glasses should also be worn.
2. Connect power supplies, loads, voltage meters and current meters as shown in [Figure 3](#)
3. Set 100-mil shunt jumpers as described in the *User Configuration Jumper Settings* for desired operational configuration. (**Note: Do not attempt to change jumper settings during operation**)
4. Ensure S3 and S5 are set to the S4/S5 state to ensure the outputs initially disabled before applying the input voltage. See Figure 2 for details.
5. Increase V_{DD} from 0 VDC to 5 VDC. Using V3, verify V_{DD} voltage between 4.75 V and 5.25 V.
6. Increase V_{IN} from 0 VDC to 12 VDC. Using V1, verify V_{IN} voltage between 11 V and 13 V.
7. Switch S3 and S5 to the S0 state to enable the outputs. See Figure 2 for details.
8. Vary LOAD1 from 0 ADC to 10 ADC.
9. Ensure that V_{TT} is off before starting LOAD2.
10. Vary LOAD2 from 0 A to 3 A (0 A to -3A on meter A5) to test LDO source capability.
11. Set LOAD2 to 0 A before turning on V_{TT} .
12. Vary V_{TT} to obtain A5 between 0 A to +3 A. to test LDO sink capability. (Note: Running both V_{TT} and LOAD2 at the same time causes V_{TT} to source additional current through LOAD2. A5 reads the summation of the LOAD2 current and LDO sink current)
13. Vary LOAD3 from 0 mA to 10mA. (Note: Do not exceed 10 mA on LOAD3)
14. Vary V_{IN} from 4.5 V to 28 V.
15. Vary V_{DD} from 4.75 V to 5.25 V.
16. Use state S3 and state S5 switches to test sleep states.
17. Increase V_{IN} to 12 VDC
18. Decrease LOAD3 to 0 mA.
19. Decrease LOAD2 to 0 A.
20. Decrease LOAD3 to 0 A.
21. Decrease V_{IN} to 0 V.
22. Decrease V_{DD} to 0V.

7 Performance Data and Characteristic Curves

The TPS51116EVM is design to provide high efficiency over a very wide range of load currents from maximum load of 10 A down to very light loads less than 100 mA. It is important to achieve high efficiency at very light loads because memory modules consume very little current when waiting for instructions in an idle state.

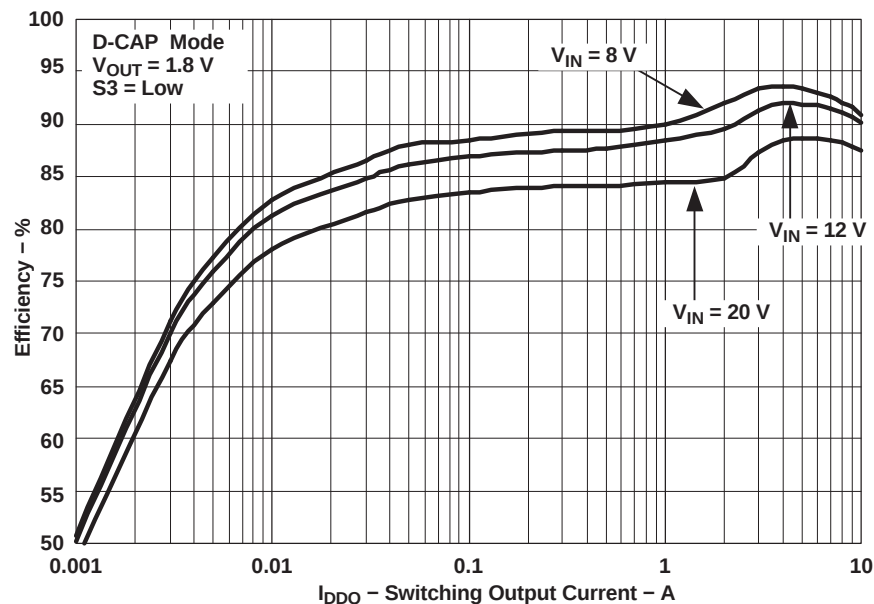


Figure 4. TPS51116EVM Efficiency

The efficiency of the TPS51116EVM is shown in Figure 4. At less than 2-A of load current the TPS51116 is operating in PFM mode as the low-side MOSFET is turned off when inductor current reaches zero to prevent sinking current from the output capacitor. Because the semi-hysteretic valley comparator threshold does not change, output ripple voltage does not increase while in PFM mode. In addition to requiring very good light load efficiency, memory module power supplies must have very good transient responses. As the module goes from idle state to computational state, they may go from very light load to full load and back again in a very short period of time. In order to achieve this fast transient response without requiring large bulk output capacitance, the TPS51116EVM used the TI's D-CAP control mode discussed in detail in the Appendix. In D-CAP mode, the TPS51116EVM is able to immediately respond to a load transient, going from nominal duty cycle to maximum duty cycle in a single switching cycle and return to nominal duty cycle as soon as the output voltage has returned to its regulated value.

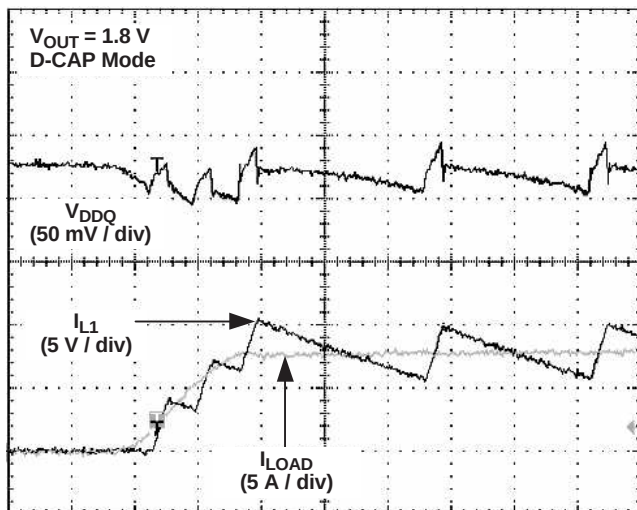


Figure 5. TPS51116EVM 0-A to 8-A Load Transient Response

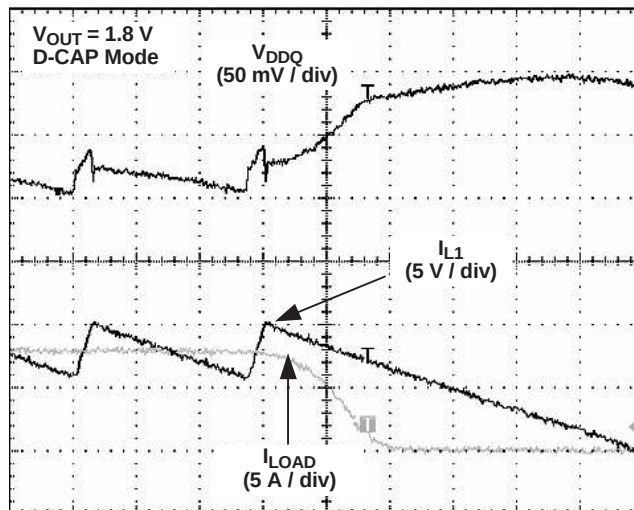


Figure 6. TPS51116EVM - 8-A to 0-A Load Transient Response

Figure 5 shows the switching output ripple voltage, the inductor current and the output load current. The advantage of the semi-hysteretic D-CAP mode is clearly visible. Here an 8-A load transient of 5 A/s causes less than 30 mV of voltage drop and nominal operation is recovered in less than 2 s, that's a single switching cycle at the normal 400 kHz switching frequency.

Figure 6, with the same channel designations of Figure 5 shows the falling transient. As soon as the first main switching pulse is terminated normally, the TPS51116EVM turns on the lowside FET and immediately begins dropping the inductor current as fast as possible by shorting the switch node to ground. The low-side MOSFET is then turned OFF when the inductor current reaches zero and the high-side MOSFET is held off until the output voltage drops below the valley comparator and nominal operation is immediately restored.

8 EVM Assembly Drawing and Layout

TPS51116 is built on a 4-layer copper clad FR4 PCB 2.25" x 3.2" and 0.062 thick with all components on a single side. [Figure 7](#) through [Figure 11](#) detail the PCB assembly, silk screen and copper layers for TPS51116EVM. These figures are provided for reference and evaluation purposes only.

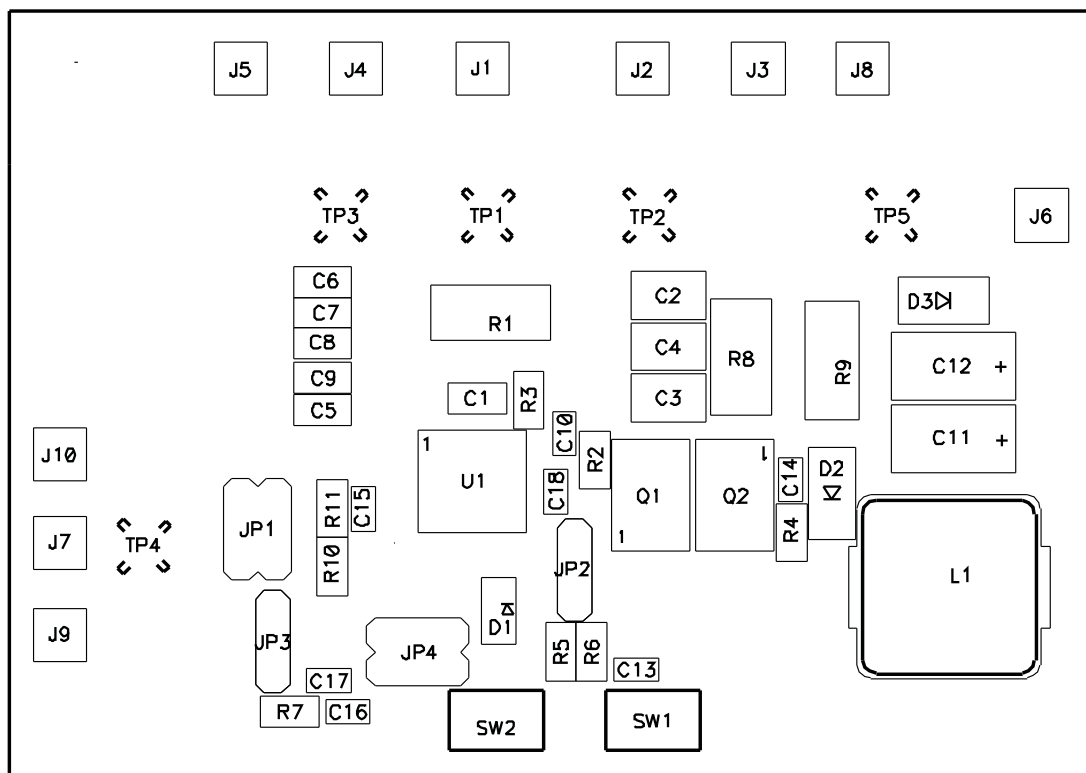


Figure 7. Component Outlines

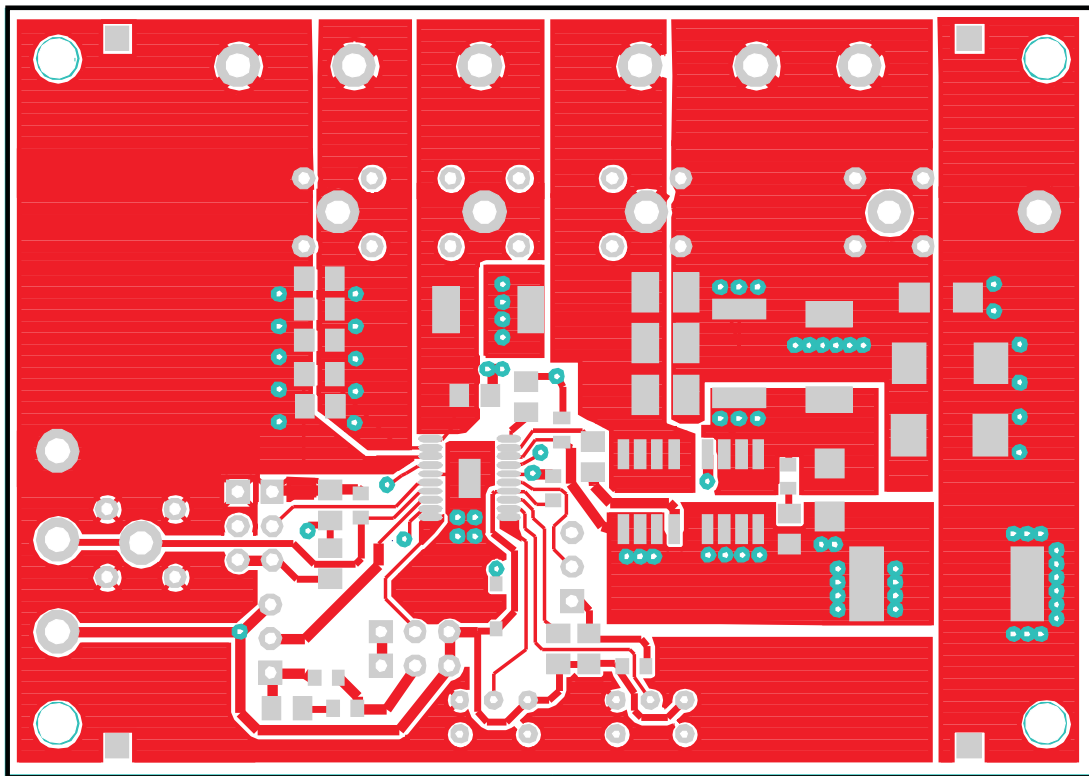


Figure 8. Top Copper Layer (Top View)

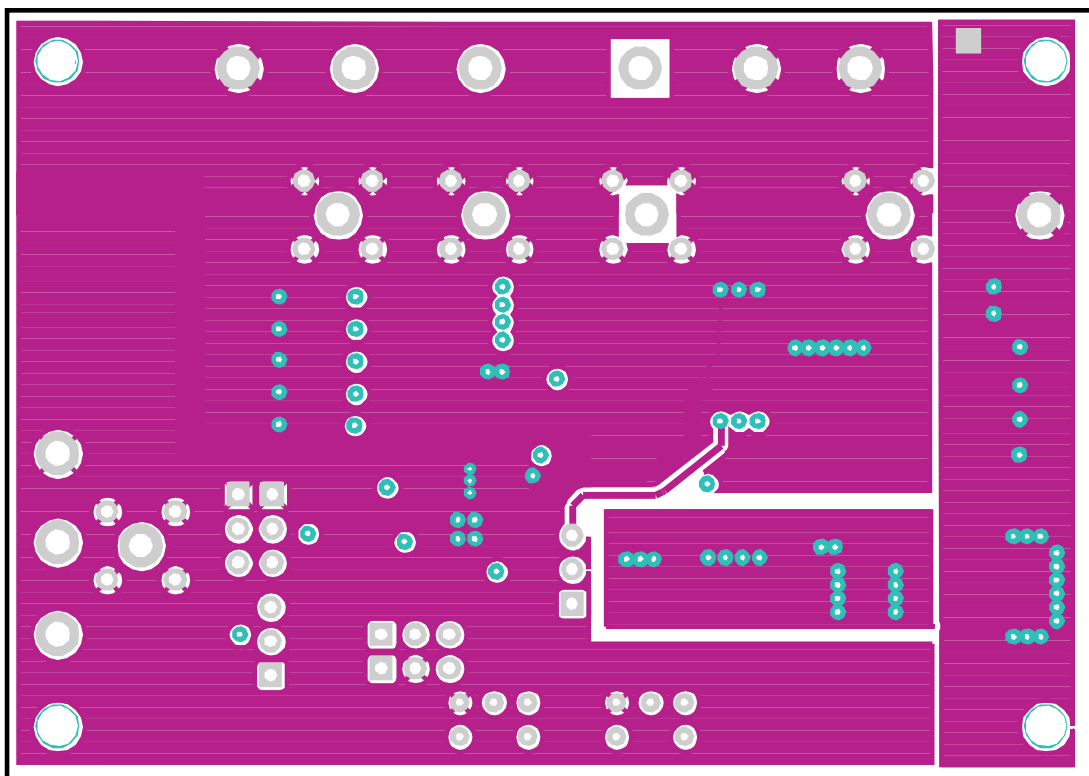


Figure 9. Internal Layer 1 (Top View)

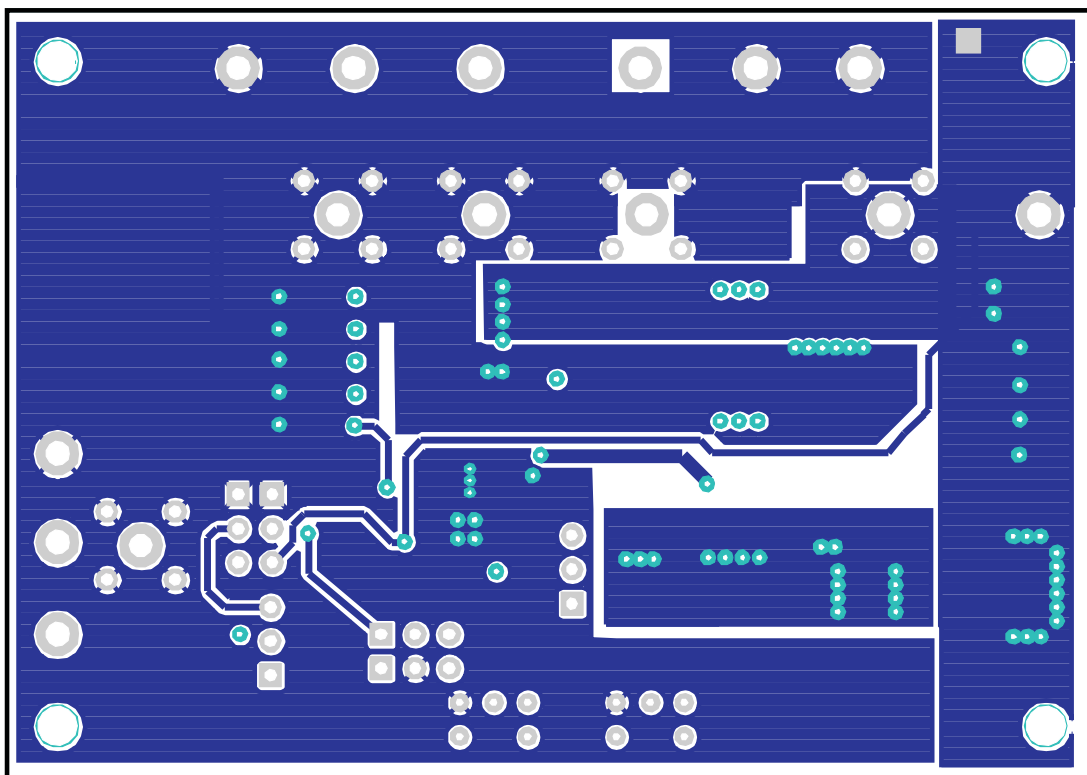


Figure 10. Internal Layer 2 (Top View)

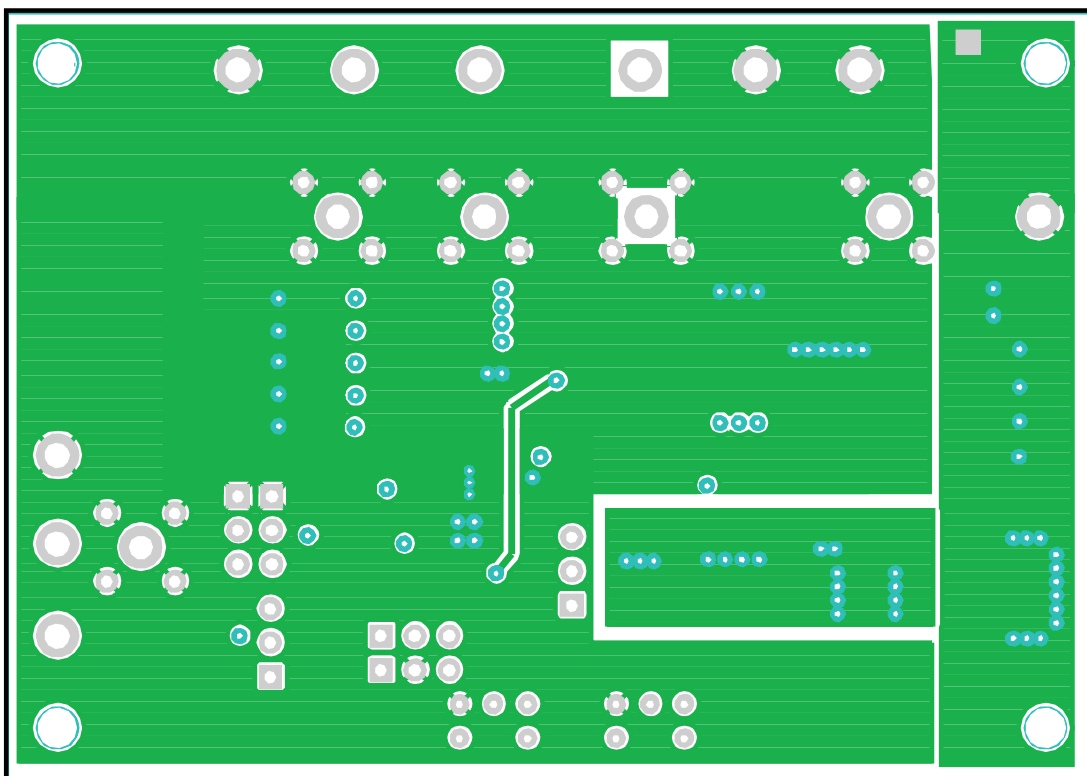


Figure 11. Bottom Copper (Top View)

9 List of Materials

Table 4. List of Materials

QTY	REFERENCE DESIGNATOR	DESCRIPTION	SIZE	MRF	PART NUMBER
2	C3, C4	Capacitor, ceramic, 10 μ F, 25 V, X5R, 20%	1210	Vishay	C3225X5R1E106M
3	C1, C6, C7	Capacitor, ceramic, 10 μ F, 6.3 V, X5R, 10%	805	TDK	C2012X5R0J106K
1	C10	Capacitor, ceramic, 0.10 μ F, 50 V, X75, 10%	603	Standard	Standard
2	C11, C12	Capacitor, POSCAP, 150 μ F, 4 V, 45 m Ω , 20%	7343(D)	Sanyo	4TPC150M
2	C13, C14	Capacitor, ceramic, 1.0 nF, 50 V, X7R, 10%	603	Standard	Standard
1	C15	Capacitor, ceramic, 0.033 μ F, 50 V, X7R, 10%	603	Standard	Standard
1	C16	Capacitor, ceramic, 0.01 μ F, X7R, 50 V, 20%	603	Standard	Standard
1	C18	Capacitor, ceramic, 4.7 μ F, 6.3 V, X5R, 10%	603	TDK	C1608X5R0J475K
1	L1	Inductor, SMT, 1.0 μ H, 29 A, 2.3 m Ω	0.51 $\times$ 0.51	Vishay	IHLP5050-01
1	Q1	MOSFET, N-channel, 30 V, 11 A, 9.1 m Ω	SO-8	Int'l Rectifier	IRF7821
1	Q2	MOSFET, N-channel, 30 V, 16-A, 4.0 m Ω	SO-8	Int'l Rectifier	IRF7832
2	R1, R9	Resistor, chip, 0 Ω , 1 W, 1%	1225	TYEE	Standard
1	R2	Resistor, chip, 5.11 Ω , 1/10 W, 1%	805	Standard	Standard
1	R3	Resistor, chip, 0 Ω , 1/10 W, 1%	805	Standard	Standard
1	R4	Resistor, chip, 3.09 Ω , 1/10 W, 1%	805	Standard	Standard
1	R5	Resistor, chip, 100 k Ω , 1/10 W, 1%	805	Standard	Standard
1	R6	Resistor, chip, 7.15 k Ω , 1/10 W, 1%	805	Standard	Standard
1	R7	Resistor, chip, 20.0 k Ω , 1/10 W, 1%	805	Standard	Standard
1	R8	Resistor, current sense, 0.006 Ω	2512	Standard	Standard
2	R11, R10	Resistor, chip, 4.75 k Ω , 1/10 W, 1%	805	Standard	Standard
1	U1	High-Voltage Synchronous Switcher with VTT Regulator	PWP-20	Texas Instruments	TPS51116PWP

Appendix A

A.1 D-CAP Mode and Transient Response

TI's adaptive constant ON-time semi-hysteretic control scheme or D-CAP technology uses V_{IN} and V_{OUT} to determine an ON-time. After this ON-time, the controller waits a minimum off time, then detects a valley in the output voltage, and turns back on after the output voltage has dropped below a threshold voltage. By using a variant of voltage feed-forward, the constant ON-time is adapted to maintain a near constant switching frequency during steady state operation, but allows for the advantages of hysteretic control during a load transient.

Turning a positive load transient, the output voltage drops below the threshold and the OFF-time comparator reacts as soon as the minimum OFF-time has elapsed, increasing the switching frequency and immediately driving the output to its maximum duty cycle. Once the output has charged above the valley threshold, the OFF-time is again set by the decay of the output voltage. Since there is no compensation capacitor to charge or discharge, the TPS51116 is able to immediately react to load transient without recovery ringing. (See [Figure 5](#) and [Figure 6](#)).

In [Figure 5](#), a 0 A to 8 A load transient with the output voltage and the inductor ripple current. On the positive transient edge, the TPS51116 has reacted to the 8-A transient load and returned to steady state operation within 2 ms. Despite the transient, there has been less than 50 mV of overshoot and no ringing on the output. On the negative transient edge (as shown in [Figure 6](#)), the synchronous MOSFET has been turned on within one switching cycle and held on until the output voltage recovers from the output transient, at which point it immediately recovers its steady state operation since the ON-time is fixed by the input to output voltage ratio and is not a function of the voltage across a compensation capacitor. This allows the TPS51116 to react to sever load transients extremely quickly, allowing the use of less bulk capacitance while maintaining tighter control of the sensitive output voltage.

It is important to note that the D-CAP mode depends on the output voltage relating directly to the inductor current. This dictates that at the switching frequency, approximately 400 kHz during steady state operation, the output capacitors should approximate a resistive load. Ceramic and ultra-low ESR capacitors can impose a significant phase shift and interfere with D-CAP mode operation. Thus, it is not recommended that one use ceramic capacitors when operating in D-CAP mode.

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Exceeding the specified input range may cause unexpected operation and/or irreversible damage to the EVM. If there are questions concerning the input range, please contact a TI field representative prior to connecting the input power.

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During normal operation, some circuit components may have case temperatures greater than 60°C. The EVM is designed to operate properly with certain components above 60°C as long as the input and output ranges are maintained. These components include but are not limited to linear regulators, switching transistors, pass transistors, and current sense resistors. These types of devices can be identified using the EVM schematic located in the EVM User's Guide. When placing measurement probes near these devices during operation, please be aware that these devices may be very warm to the touch.

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