

General Description

The MAX1420, +3.3V, 12-bit analog-to-digital converter (ADC) features a fully-differential input, pipelined, 12stage ADC architecture with wideband track-and-hold (T/H) and digital error correction, incorporating a fullydifferential signal path. The MAX1420 is optimized for low-power, high dynamic performance applications in imaging and digital communications. The converter operates from a single +3.3V supply, and consumes only 221mW. The fully-differential input stage has a small signal -3dB bandwidth of 400MHz and may be operated with single-ended inputs.

An internal +2.048V precision bandgap reference sets the full-scale range of the ADC. A flexible reference structure accommodates an internal reference, or externally applied buffered or unbuffered reference for applications that require increased accuracy and a different input voltage range.

In addition to low operating power, the MAX1420 features two power-down modes: reference power-down and shutdown mode. In reference power-down, the internal bandgap reference is deactivated, which results in a typical 2mA supply current reduction. A full shutdown mode is available to maximize power savings during idle periods.

The MAX1420 provides parallel, offset binary, CMOScompatible three-state outputs.

The MAX1420 is available in a 7mm × 7mm, 48-pin TQFP package, and is specified over the commercial (0°C to +70°C) and the extended industrial (-40°C to +85°C) temperature range.

Pin-compatible lower speed versions of the MAX1420 are also available. Please refer to the MAX1421 data sheet for 40Msps and the MAX1422 data sheet for 20Msps.

Applications

Medical Ultrasound Imaging **CCD Pixel Processing** IR Focal Plane Arrays Radar IF & Baseband Digitization

Functional diagram appears at end of data sheet.

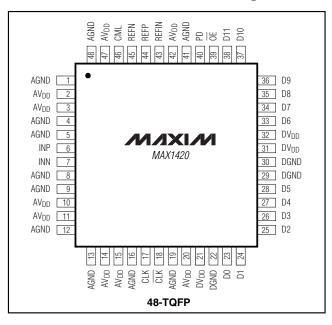
Features

- ♦ +3.3V Single Power Supply
- ♦ 67dB SNR at f_{IN} = 5MHz
- ♦ 66dB SNR at f_{IN} = 15MHz
- ♦ Internal +2.048V Precision Bandgap Reference
- ♦ Differential, Wideband Input T/H Amplifier
- ♦ Power-Down Modes:
 - 218mW (Reference Shutdown Mode) 10µW (Shutdown Mode)
- ♦ Space-Saving 48-Pin TQFP Package

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX1420CCM	0°C to +70°C	48 TQFP
MAX1420ECM	-40°C to +85°C	48 TQFP

Pin Configuration



Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

AVDD, DVDD to AGND	0.3V to +4V
DVDD, AVDD to DGND	0.3V to +4V
DGND to AGND	0.3V to +0.3V
INP, INN, REFP, REFN, REFIN,	
CML, CLK, <u>CLK</u> (AGND - 0.3V) to $(AV_{DD} + 0.3V)$
D0-D11, OE , PD(I	$DGND - 0.3V$) to $(DV_{DD} + 0.3V)$
Continuous Power Dissipation (T	$A = +70^{\circ}C$
48-Pin TQFP (derate 12.5mW/	°C above +70°C)1000mW

Operating Temperature Ranges	
MAX1420CCM	0°C to +70°C
MAX1420ECM	40°C to +85°C
Maximum Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 62.5MHz (50% duty cycle), digital output load C_L \approx 10pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DC ACCURACY						•
Resolution	RES			12		Bits
Differential Neplinearity	DNL	T _A = +25°C, no missing codes	-1		1	1.00
Differential Nonlinearity	DINL	$T_A = T_{MIN}$ to T_{MAX}		±0.5		LSB
Integral Nonlinearity	INL	$T_A = T_{MIN}$ to T_{MAX}		±2		LSB
Mid-scale Offset	MSO		-3	.75	3	%FSR
Mid-scale Offset Temperature Coefficient	MSOTC			3 x 10-4		%/°C
		Internal reference (Note 1)	-5	±0.1	5	
Gain Error	GE	External reference applied to REFIN (Note 2)	-5	±0.2	5	%FSR
		External reference applied to REFP, CML, and REFN (Note 3)	-1.5		1.5	
Gain Error Temperature Coefficient	GETC	External reference applied to REFP, CML, and REFN (Note 3)		100 x 106		%/°C
DYNAMIC PERFORMANCE (f _{CLK}	= 60MHz, 4096	S-point FFT)				•
Signal-to-Noise Ratio	SNR	f _{IN} = 5MHz		67		dB
Signal-to-Noise hatio	SIND	$f_{IN} = 15MHz$, $T_A = +25$ °C	62	66		UB
Spurious-Free Dynamic Range	SFDR	$f_{IN} = 5MHz$		72		dB
opunous rice Dynamic Hange	01 011	$f_{IN} = 15MHz$, $T_A = +25$ °C	64	72		QD.
Total Harmonic Distortion	THD	f _{IN} = 5MHz		-70		dB
Total Flamionio Diotoriion	1118	f _{IN} = 15MHz, T _A =+25°C	-69	-62	u.b	
Signal-to-Noise and Distortion	SINAD	f _{IN} = 5MHz		64.5		dB
		$f_{IN} = 15MHz, T_A = +25^{\circ}C$ 58.5 63				
Effective Number of Bits	ENOB	f _{IN} = 5MHz		10.4		Bits
		f _{IN} = 15MHz		10.2		
Two-Tone Intermodulation Distortion	IMD	$f_{IN1} = 11.566036MHz,$ $f_{IN2} = 13.4119138MHz$ (Note 4)		-74		dBc

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 62.5MHz (50% duty cycle), digital output load C_L \approx 10pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN TYP MAX	UNITS
Differential Gain	DG		±1	%
Differential Phase	DP		±0.25	degrees
ANALOG INPUTS (INP, INN, CML)				
Input Resistance	RIN	Either input to ground	22	kΩ
Input Capacitance	C _{IN}	Either input to ground	4	рF
Common-Mode Input Level (Note 5)	V _{CML}		Vavdd × 0.5	V
Common-Mode Input Voltage Range (Note 5)	VCMVR		V _{CML} ±5%	V
Differential Input Range	VIN	V _{INP} - V _{INN} (Note 6)	±V _{DIFF}	V
Small-Signal Bandwidth	BW _{-3dB}	(Note 7)	400	MHz
Large-Signal Bandwidth	FPBW-3dB	(Note 7)	150	MHz
Overvoltage Recovery	OVR	1.5 × FS input	1	Clock Cycle
INTERNAL REFERENCE (REFIN b	ypassed with 0	0.22µF in parallel with 1nF)		
Common-Mode Reference Voltage	VCML	At CML	VAVDD × 0.5	V
Positive Reference Voltage	VREFP	At REFP	V _{CML} + 0.512	V
Negative Reference Voltage	V _{REFN}	At REFN	V _{CML} - 0.512	V
Differential Reference Voltage	VDIFF	VDIFF = VREFP - VREFN	1.024 ±5%	V
Differential Reference Temperature Coefficient	REFTC		±100	ppm/°C
EXTERNAL REFERENCE (REFIN :	= +2.048V)			
REFIN Input Resistance	RIN	(Note 8)	5	kΩ
REFIN Input Capacitance	CIN		10	pF
REFIN Reference Input Voltage	VREFIN		2.048 ±10%	V
Differential Reference Voltage	V _{DIFF}	V _{DIFF} = (V _{REFP} - V _{REFN})	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	V
EXTERNAL REFERENCE (V _{REFIN} =	AGND, referen	nce voltage applied to REFP, REFN, and		
REFP, REFN, CML Input Current	I _{IN}		-200 200	μΑ
REFP, REFN, CML Input Capacitance	CIN		15	pF

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 62.5MHz (50% duty cycle), digital output load $C_L \approx 10pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Differential Reference Voltage Range	V _{DIFF}	V _{DIFF} = V _{REFP} - V _{REFN}		1.024 ±10%		V
CML Input Voltage Range	VCML			1.65 ±10%		V
REFP Input Voltage Range	V _{REFP}			V _{CML} + V _{DIFF} /2		V
REFN Input Voltage Range	VREFN			V _{CML} - V _{DIFF} /2		V
DIGITAL INPUTS (CLK, CLK, PD,	ŌĒ)	•	•			•
Input Logic High	V _{IH}		0.7 x V _{DVDD}			V
Input Logic Low	V _{IL}				0.3 x V _{DVDD}	V
		CLK, CLK		±330		_
Input Current		PD	-20		20	μA
		ŌĒ	-20		20	
Input Capacitance				10		рF
DIGITAL OUTPUTS (D0–D11)						
Output Logic High	VoH	I _{OH} = 200μA	V _{DVDD} - 0.5		V _{DVDD}	V
Output Logic Low	V _{OL}	$I_{OL} = -200 \mu A$	0		0.5	V
Three-State Leakage			-10		10	μΑ
Three-State Capacitance				2		рF
POWER REQUIREMENTS						
Analog Supply Voltage	V _A VDD		3.135	3.3	3.465	V
Digital Supply Voltage	V _D VDD		2.7	3.3	3.63	V
Analog Supply Current	lavdd			67	78	mA
Analog Supply Current with Internal Reference in Shutdown		REFIN = AGND		66	76	mA
Analog Shutdown Current		PD = D _{VDD}		10	20	μΑ
Digital Supply Current	IDVDD			8		mA
Digital Shutdown Current		PD = V _{DVDD}			20	μΑ
Power Dissipation	P _{DISS}	Analog power dissipation		221	258	mW
Power Dissipation with Internal Reference in Shutdown (Note 8)	PDISS	REFIN = AGND		218	251	mW

ELECTRICAL CHARACTERISTICS (continued)

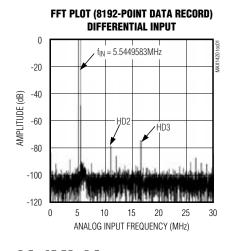
 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 62.5MHz (50% duty cycle), digital output load C_L <math>\approx$ 10pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)

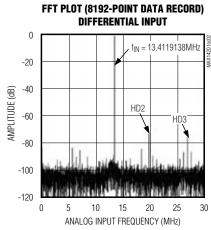
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Power Dissipation In Shutdown	P _{DISS}	PD = V _D VDD		10		μW
Power-Supply Rejection Ratio	PSRR	(Note 9)		±1		mV/V
TIMING CHARACTERISTICS						
Maximum Clock Frequency	fCLK		60			MHz
Clock High	tCH	Figure 6, clock period 16.667ns		8.33		ns
Clock Low	tCL	Figure 6, clock period 16.667ns		8.33		ns
Pipeline Delay (Latency)		Figure 6		7		f _{CLK} cycles
Aperture Delay	t _{AD}	Figure 10		2		ns
Aperture Jitter	taj	Figure 10		2		ps
Data Output Delay	top	Figure 6	5	10	14	ns
Bus Enable Time	tBE	Figure 5		5		ns
Bus Disable Time	t _{BD}	Figure 5		5		ns

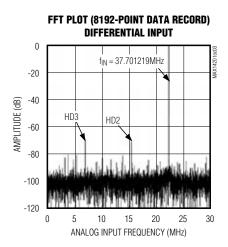
- Note 1: Internal reference, REFIN bypassed to AGND with a combination of 0.22µF in parallel with 1nF capacitor.
- Note 2: External +2.048V reference applied to REFIN.
- Note 3: Internal reference disabled. V_{REFIN} = 0, V_{REFP} = +2.162V, V_{CML} = +1.65V, and V_{REFN} = +1.138V.
- Note 4: IMD is measured with respect to either of the fundamental tones.
- Note 5: Specifies the common-mode range of the differential input signal supplied to the MAX1420.
- Note 6: V_{DIFF} = V_{REFP} V_{REFN}.
- Note 7: Input bandwidth is measured at a 3dB level.
- **Note 8:** V_{REFIN} is internally biased to +2.048V through a $10k\Omega$ resistor.
- Note 9: Measured as the ratio of the change in mid-scale offset voltage for a ±5% change in VAVDD, using the internal reference.

Typical Operating Characteristics

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, $f_{CLK} = 60.006MHz$ (50% duty cycle), digital output load $C_L = 10pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25$ °C.)

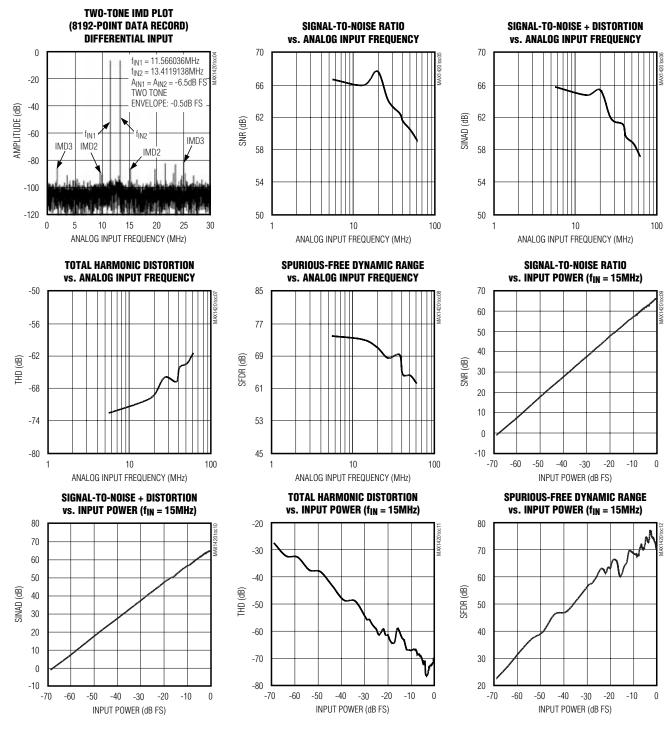






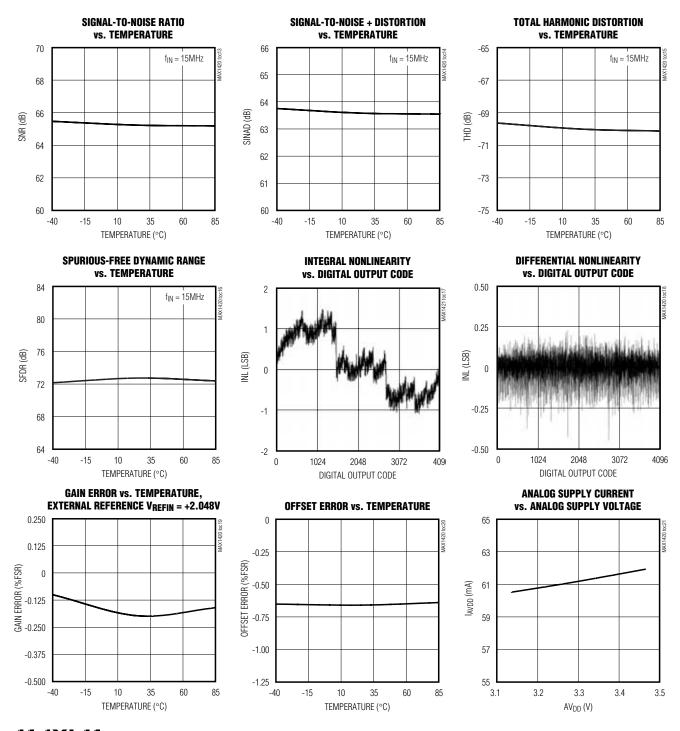
Typical Operating Characteristics (continued)

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, fCLK = 60.006MHz (50% duty cycle), digital output load CL = 10pF, TA = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at TA = +25°C.)



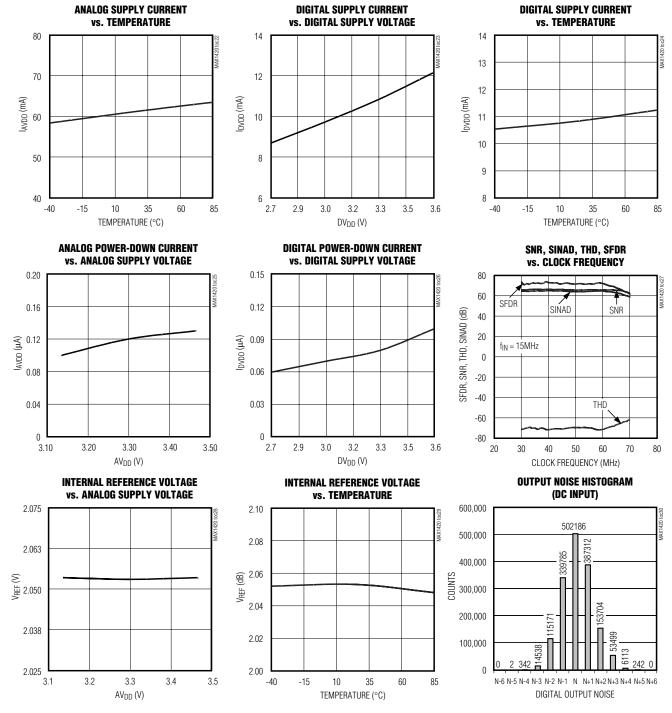
Typical Operating Characteristics (continued)

(VAVDD = VDVDD = +3.3V, AGND = DGND = 0, VIN = ±1.024V, differential input voltage at -0.5dB FS, fCLK = 60.006MHz (50% duty cycle), digital output load CL = 10pF, TA = TMIN to TMAX, unless otherwise noted. Typical values are at TA = +25°C.)



Typical Operating Characteristics (continued)

 $(V_{AVDD} = V_{DVDD} = +3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage at -0.5dB FS, fCLK = 60.006MHz (50% duty cycle), digital output load CL = 10pF, TA = TMIN to TMAX, unless otherwise noted. Typical values are at TA = +25°C.)$



___Pin Description

	I	
PIN	NAME	FUNCTION
1, 4, 5, 8, 9, 12, 13, 16, 19, 41, 48	AGND	Analog Ground. Connect all return paths for analog signals to AGND.
2, 3, 10, 11, 14, 15, 20, 42, 47	AV _{DD}	Analog Supply Voltage. For optimum performance, bypass to the closest AGND with a parallel combination of a 0.1µF and a 1nF capacitor. Connect a single 10µF and 1µF capacitor combination between A _{VDD} and A _{GND} .
6	INP	Positive Analog Signal Input
7	INN	Negative Analog Signal Input
17	CLK	Clock Frequency Input. Clock frequency input ranges from 100kHz to 60MHz.
18	CLK	Complementary Clock Frequency Input. This input is used for differential clock inputs. If the ADC is driven with a single-ended clock, bypass $\overline{\text{CLK}}$ with a 0.1µF capacitor to AGND.
21, 31, 32	DV _{DD}	Digital Supply Voltage. For optimum performance, bypass to the closest DGND with a parallel combination of a 0.1µF and a 1nF capacitor. Connect a single 10µF and 1µF capacitor combination between D _{VDD} and D _{GND} .
22, 29, 30	DGND	Digital Ground
23–28	D0-D5	Digital Data Outputs. Data bits D0 through D5, where D0 represents the LSB.
33–38	D6-D11	Digital Data Outputs. D6 through D11, where D11 represents the MSB.
39	ŌĒ	Output Enable Input. A logic "1" on \overline{OE} places the outputs D0–D11 into a high-impedance state. A logic "0" allows for the data bits to be read from the outputs.
40	PD	Shutdown Input. A logic "1" on PD places the ADC into shutdown mode.
43	REFIN	External Reference Input. Bypass to AGND with a capacitor combination of 0.22µF in parallel with 1nF. REFIN can be biased externally to adjust reference levels and calibrate full-scale errors. To disable the internal reference, connect REFIN to AGND.
44	REFP	Positive Reference I/O. Bypass to AGND with a capacitor combination of 0.22µF in parallel with 1nF. With the internal reference disabled (REFIN = AGND), REFP should be biased to V _{CML} + V _{DIFF} / 2.
45	REFN	Negative Reference I/O. Bypass to AGND with a capacitor combination of $0.22\mu F$ in parallel with 1nF. With the internal reference disabled (REFIN = AGND), REFN should be biased to V_{CML} - V_{DIFF} / 2.
46	CML	Common-Mode Level Input. Bypass to AGND with a capacitor combination of 0.22µF in parallel with 1nF.

Detailed Description

The MAX1420 uses a 12-stage, fully-differential, pipelined architecture (Figure 1) that allows for high-speed conversion while minimizing power consumption. Each sample moves through a pipeline stage every half-clock cycle, including the delay through the output latch. The latency is seven clock cycles.

A 2-bit (2-comparator) flash ADC converts the held-input voltage into a digital code. The following digital-to-analog converter (DAC) converts the digitized result back into an analog voltage, which is then subtracted from the original held-input signal. The resulting error signal is then multiplied by two, and the product is passed along to the next pipeline stage. This process is repeated until the signal has been processed by all 12 stages. Each stage provides a 1-bit resolution. Digital error correction compensates for ADC comparator offsets in each pipeline stage and ensures no missing codes.

Input Track-and-Hold Circuit

Figure 2 displays a simplified functional diagram of the input track-and-hold (T/H) circuit in both track-and-hold mode. In track mode, switches S1, S2a, S2b, S4a, S4b, S5a, and S5b are closed. The fully-differential circuit passes the input signal to the two capacitors C2a and C2b through switches S4a and S4b. Switches S2a and S2b set the common mode for the operational transcon-

ductance amplifier (OTA) input, and open simultaneously with S1, sampling the input waveform. The resulting differential voltage is held on capacitors C2a and C2b. Switches S4a and S4b are then opened before S3a, S3b, S4C are closed. The OTA is used to charge capacitors C1a and C1b to the same values originally held on C2a and C2b. This value is then presented to the first stage quantizer and isolates the pipeline from the fast-changing input. The wide input bandwidth T/H amplifier allows the MAX1420 to track and sample/hold analog inputs of high frequencies beyond Nyquist. The analog inputs INP to INN can be driven either differentially or single-ended. Match the impedance of INP and INN and set the common-mode voltage to midsupply (AVDD/2) for optimum performance.

Analog Input and Reference Configuration

The full-scale range of the MAX1420 is determined by the internally generated voltage difference between REFP (AVDD/2 + VREFIN/4) and REFN (AVDD/2 - VREFIN/4). The MAX1420's full-scale range is adjustable through REFIN, which provides high input impedance for this purpose. REFP, CML (AVDD/2), and REFN are internally buffered low impedance outputs.

An internal +2.048V precision bandgap reference sets the full-scale range of the ADC. A flexible reference structure accommodates an internal reference, or externally applied buffered or unbuffered reference for appli-

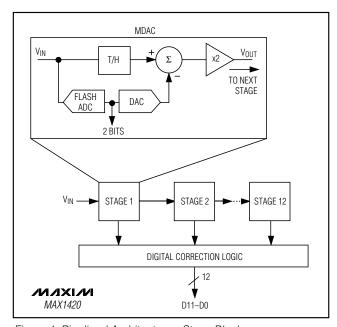


Figure 1. Pipelined Architecture—Stage Blocks

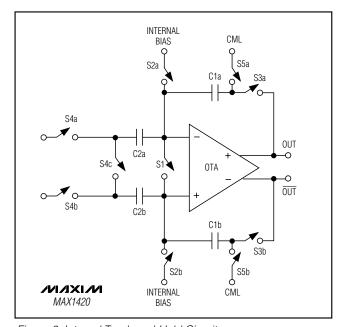


Figure 2. Internal Track-and-Hold Circuit

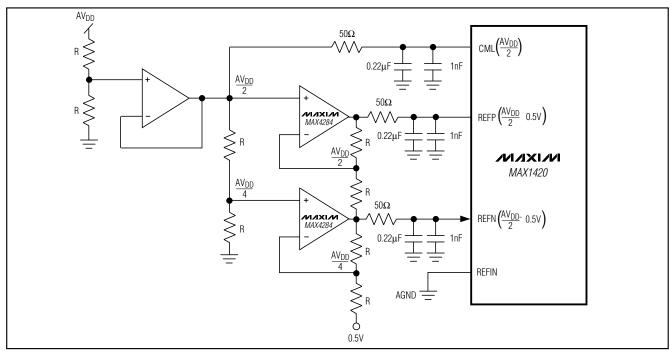


Figure 3. Unbuffered External Reference Drive-Internal Reference Disabled

cations that require increased accuracy and a different input voltage range.

The MAX1420 provides three modes of reference operation:

- Internal reference mode
- Buffered external reference mode
- Unbuffered external reference mode

In internal reference mode, the on-chip +2.048V bandgap reference is active and REFIN, REFP, CML, and REFN are left floating. For stability purposes, bypass REFIN, REFP, REFN and CML with a capacitor network of $0.22\mu F$ in parallel with a 1nF capacitor to AGND.

In buffered external reference mode, the reference voltage levels can be adjusted externally by applying a stable and accurate voltage at REFIN.

In unbuffered external reference mode, REFIN is connected to AGND, thereby deactivating the on-chip buffers of REFP, CML, and REFN. With their buffers shut down, these nodes become high impedance and can be driven by external reference sources, as shown in Figure 3.

Clock Inputs (CLK, CLK)

The MAX1420's CLK and CLK inputs accept both differential and single-ended input operation and accept CMOS-compatible clock signals. If CLK is driven with a single-ended clock signal, bypass CLK with a 0.1µF capacitor to AGND. Since the interstage conversion of the device depends on the repeatability of the rising and falling edges of the external clock, use a clock with low jitter and fast rise and fall times (< 2ns). Sampling occurs on the rising edge of the clock signal, requiring this edge to have the lowest possible jitter. Any significant aperture jitter would limit the SNR performance of the ADC according to the following relationship:

$$SNR_{dB} = 20 \times log_{10} \frac{1}{2\pi \times f_{|N} \times t_{AJ}}$$

where f_{IN} represents the analog input frequency and t_{AJ} is the aperture jitter. Clock jitter is especially critical for high input frequency applications. The clock input should always be considered as an analog signal and routed away from any analog or digital signal lines.

The MAX1420 clock input operates with a voltage threshold set to AV_{DD}/2. Clock inputs must meet the specifications for high and low periods as stated in the *Electrical Characteristics*.

12-Bit, 60Msps, +3.3V, Low-Power ADC

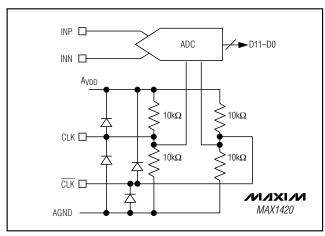


Figure 4. Simplified Clock Input Circuit

Figure 4 shows a simplified model of the clock input circuit. This circuit consists of two $10k\Omega$ resistors to bias the common-mode level of each input. This circuit may be used to AC-couple the system clock signal to the MAX1420 clock input.

Output Enable (OE), Power-Down (PD) and Output Data (D0-D11)

In addition to low operating power, the MAX1420 features two power-down modes: reference power-down and shutdown mode. In reference power-down, the in-

Table 1. MAX1420 Output Code for Differential Inputs

DIFFERENTIAL INPUT VOLTAGE*	DIFFERENTIAL INPUT	OFFSET BINARY
V _{REF} × 2047/2048	+FULL SCALE - 1LSB	1111 1111 1111
V _{REF} × 2046/2048	+FULL SCALE - 2LSB	1111 1111 1110
V _{REF} × 1/2048	+ 1 LSB	1000 0000 0001
0	Bipolar Zero	1000 0000 0000
-V _{REF} × 1/2048	- 1 LSB	0111 1111 1111
-V _{REF} × 2046/2048	-FULL SCALE + 1 LSB	0000 0000 0001
-V _{REF} × 2047/2048	-FULL SCALE	0000 0000 0000

^{*} VREF = VREFP - VREFN

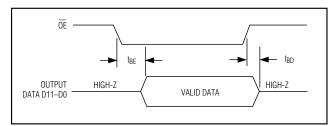


Figure 5. Output Enable Timing

ternal bandgap reference is deactivated, which results in a typical 2mA supply current reduction. A full shutdown mode is available to maximize power savings during idle periods.

The MAX1420 provides parallel, offset binary, CMOS-compatible three-state outputs.

With \overline{OE} high, the digital outputs enter a high-impedance state. If \overline{OE} is held low with PD high, the outputs are latched at the last digital output code prior to the power-down. All data outputs, D0 (LSB) through D11 (MSB), are TTL/CMOS logic-compatible. There is a seven clock-cycle latency between any particular sample and its valid output data. The output coding is in offset binary format (Table 1).

The capacitive load on the digital outputs D0 through D11 should be kept as low as possible (\leq 10pF), to avoid large digital currents that could feed back into the analog portion of the MAX1420, thereby degrading its performance. The use of buffers (e.g., 74LVCH16244) on the digital outputs of the ADC can further isolate the digital outputs from heavy capacitive loads. To further improve the dynamic performance of the MAX1420, add small-series resistors of 100Ω to the digital output paths, close to the ADC.

Figure 5 displays the timing relationship between output enable and data output.

System Timing Requirements

Figure 6 depicts the relationship between the clock input, analog input, and valid data output. The MAX1420 samples the analog input signal on the rising edge of CLK (falling edge of CLK) and output data is valid seven clock cycles (latency) later.

Applications Information

Figure 7 depicts a typical application circuit containing a single-ended to differential converter. The internal reference provides an AVDD/2 output voltage for level shifting purposes. The input is buffered and then split to a voltage follower and inverter. A lowpass filter at the input suppresses some of the wideband noise associated

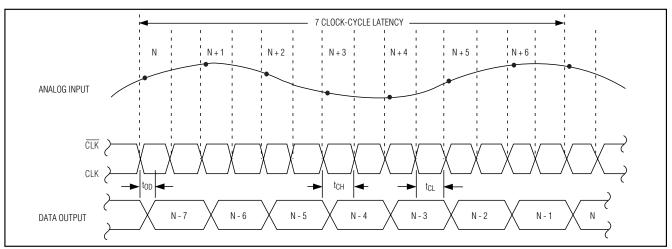


Figure 6. System and Output Timing Diagram

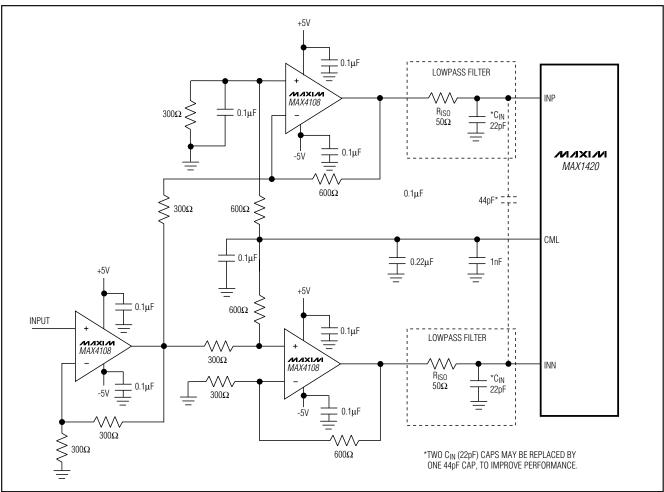


Figure 7. Typical Application Circuit for Single-Ended to Differential Conversion

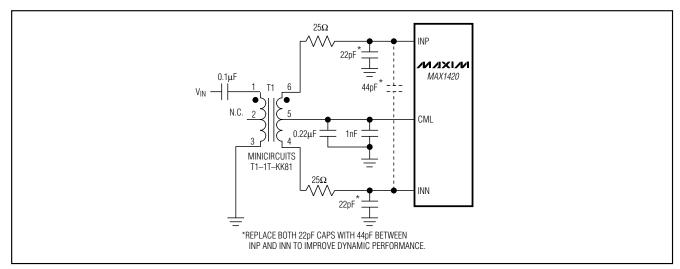


Figure 8. Using a Transformer for AC-Coupling

with high-speed op amps. Select the R_{ISO} and C_{IN} values to optimize the filter performance, to suit a particular application. For the application in Figure 7, an isolation resistor (R_{ISO}) of 50Ω is placed before the capacitive load to prevent ringing and oscillation. The 22pF C_{IN} capacitor acts as a small bypassing capacitor. Connecting C_{IN} from INN to INP may further improve dynamic performance.

Using Transformer Coupling

An RF transformer (Figure 8) provides an excellent solution to convert a single-ended signal to a fully differential signal, required by the MAX1420 for optimum performance. Connecting the center tap of the transformer to CML provides an AVDD/2 DC level shift to the input. Although a 1:1 transformer is shown, a 1:2 or 1:4 step-up transformer may be selected to reduce the drive requirements.

In general, the MAX1420 provides better SFDR and THD with fully differential input signals over single-ended input signals, especially for very high input frequencies. In differential input mode, even-order harmonics are suppressed and each input requires only half the signal swing compared to single-ended mode.

Single-Ended AC-Coupled Input Signal

Figure 9 shows an AC-coupled, single-ended application, using a MAX4108 op amp. This configuration provides high speed, high bandwidth, low noise, and low distortion to maintain the integrity of the input signal.

Grounding, Bypassing and Board Layout

The MAX1420 requires high-speed board layout design techniques. Locate all bypass capacitors as close to the device as possible, preferably on the same side of the board as the ADC, using surface-mount devices for minimum inductance. Bypass REFP, REFN, REFIN, and CML with a parallel network of 0.22µF capacitors and 1nF to AGND. AVDD should be bypassed with a similar network of a 10µF bipolar capacitor in parallel with two ceramic capacitors of 1nF and 0.1µF. Follow the same rules to bypass the digital supply DVDD to DGND. Multilayer boards with separate ground and power planes produce the highest level of signal integrity. Consider the use of a split ground plane arrangement to match the physical location of the analog ground (AGND) and the digital ground (DGND) on the ADCs package. Join the two ground planes at a single point, such that the noisy digital ground currents do not interfere with the analog ground plane. Alternatively, all ground pins could share the same ground plane, if the ground plane is sufficiently isolated from any noisy, digital systems ground plane (e.g., downstream output buffer or DSP ground plane). Route high-speed digital signal traces away from sensitive analog traces and remove digital ground and power planes from underneath digital outputs. Keep all signal lines short and free of 90 degree turns.

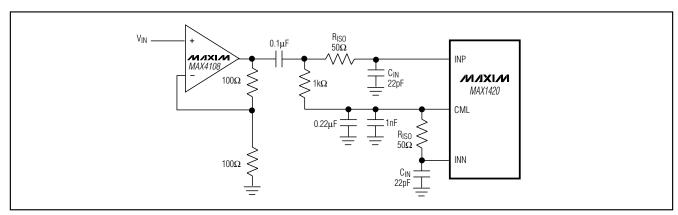


Figure 9. Single-Ended AC-Coupled Input Signal

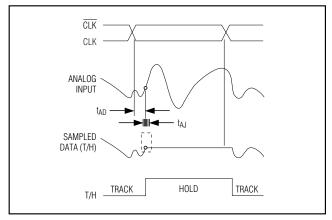


Figure 10. T/H Aperture Timing

Static Parameter Definitions

Integral Nonlinearity (INL)

Integral nonlinearity is the deviation of the values on an actual transfer function from a straight-line. This straight-line can be either a best straight-line fit or a line drawn between the endpoints of the transfer function once offset and gain errors have been nullified. The static linearity parameters for the MAX1420 are measured using the best straight-line fit method.

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between an actual step-width and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes.

Dynamic Parameter Definitions

Aperture Jitter

Figure 10 depicts the aperture jitter (t_{AJ}), which is the sample-to-sample variation in the aperture delay.

Aperture Delay

Aperture delay (t_{AD}) is the time defined between the falling edge of the sampling clock and the instant when an actual sample is taken (Figure 10).

Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADCs resolution (N-bits):

$$SNR_{MAX} = (6.02 \times N + 1.76)dB$$

In reality, there are other noise sources besides quantization noise, e.g., thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first four harmonics, and the DC offset.

Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to all spectral components minus the fundamental and the DC offset.

Effective Number of Bits (ENOB)

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB is computed from:

$$ENOB = \frac{SINADdB - 1.76dB}{6.02dB}$$

Total Harmonic Distortion (THD)

THD is typically the ratio of the RMS sum of the first four harmonics of the input signal to the fundamental itself. This is expressed as:

THDdB = 20 × log10
$$\left(\frac{\sqrt{(V2^2 + V3^2 + V4^2 + V5^2)}}{V_1} \right)$$

where V_1 is the fundamental amplitude, and V_2 through V_5 are the amplitudes of the 2nd- through 5th-order harmonics.

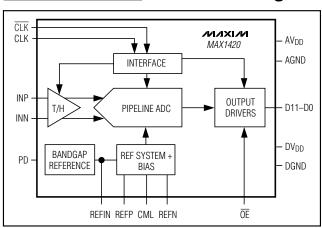
Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio expressed in decibels of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next largest spurious component, excluding DC offset.

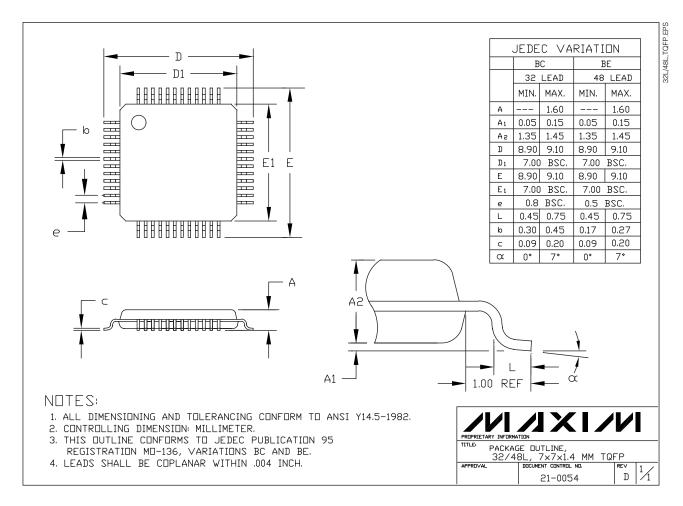
Intermodulation Distortion (IMD)

The two-tone IMD is the ratio expressed in decibels of either input tone to the worst 3rd-order (or higher) intermodulation products. The individual input tone levels are at -6.5dB full scale and their envelope is at -0.5dB full scale.

Functional Diagram



Package Information



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